# Satellite Communication Assignment 2 EEE F472



Sai Kartik (2020A3PS0435P) Rajeev Rajagopal (2020A3PS1237P) Kshitij Merchant (2020A3PS0436P)

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## Problem 1

- Write the algorithm to compute position of the Friendship 7 spacecraft in the form of pseudocode (or present a flowchart)
- Write a computer program (in MATLAB) to compute position of the Friendship 7 spacecraft

#### Pseudocode

- 1. Declare constants
- 2. Input date, time (precisely)
- 3. convert into fractional day with the value of time (fractional day = hh/24+mm/1440+ss/86400)
- 4. if month  $\leq 2$ , year = year -1; month = month + 12
- 5. Calculate Julian date with obtained params
- 6. Calculate various orbital parameters
- 7. Convert to cartesian co-ordinates from obtained angular orbital parameters. Alpha and Delta is obtained from here
- 8. Compute GST with its empirical formula
- 9. Make sure GST is in the range [0,360)
- 10. Calculate L=GST Alpha
- 11. L = wrapTo180(L)
- 12. Print Delta and L (lat. and long.)

#### MATLAB Code

```
1 clear
2 close all
3 clc
6 %Required constants%
9 a = 6589116;
10 e = 0.007589;
11 i = 32.54;
12 Omega = 235.2;
13 omega = 181.2;
14 \quad M0 = 228.5;
15 TO = 2437716.11642;
16
17 GMe = 3.986004415 *10^(14);
18
20 %Taking required input from the user%
22
23 disp("Enter the precise date and time needed to find latitiude and longitude of the ...
      Friendship 7 spacecraft")
24
25 date = input("Enter the required date: ");
26 month = input ("Enter the required month(in number format): ");
27 Y = input ("Enter the required year: ");
28 hh = input("Enter the required hour of the day (24h format): ");
29 mm = input("Enter the required minute of the hour: ");
  ss = input("Enter the required second of the minute: ");
31
d = ((hh/24) + (mm/1440) + (ss/86400));
33 D = date + d;
34
  if month<2
      month = month+12;
35
      Y = Y -1;
36
37 end
38
40 % Calculation of the Julian day
42
43 A = floor(Y/100);
44 B = 2 - A + floor(A/4);
45
46 t = (floor(365.25*(Y+4716))+floor(30.6001*(month+1))+D+B-1524.5);
47 % t = 2459580;
48
50 %Calculating required orbital parameters
n = (86400/(2*pi))*sqrt(GMe/a^3);
M = deg2rad(M0) + 2*pi*n*(t-T0);
55
56 syms E_sym
so eqn = M == E_sym - e*sin(E_sym);
E_r = solve(eqn, E_sym);
E = rad2deg(double(E_r));
60 f = double(2*atand(sqrt((1+e)/(1-e)) * tan (E/2)));
u = omega + f;
62
```

```
63 r = a*(1-e*cosd(E));
64
  65
66 %Converting orbital parameters to Latitude and Longitude
69 %cartesian conversion
70
x = r*((cosd(u)*cosd(Omega)) - (sind(u)*sind(Omega)*cosd(i)));
y = r*((cosd(u)*sind(Omega))+(sind(u)*cosd(Omega)*cosd(i)));
z = r*sind(u)*sind(i);
74
75 Alpha = atan2d(y,x);
76 Delta = asind(z/r);
78 T = ((t-2451545)/36525);
79
   \texttt{GST\_d} = (280.46061837 + (360.98564736629*(t-2451545)) + (0.000387933*T^2) - \dots 
80
      ((T<sup>3</sup>)/38710000));
  GST = mod(GST_d, 360);
81
83 L = wrapTo180(alpha - GST);
84 psi = Delta;
85
86 psi_s = angl2str(psi, "ns", "degrees2dms");
87 L_s = angl2str(L,"ew","degrees2dms");
88
89 sprintf("The latitude of the spacecraft at this time is %s ",psi_s)
90 sprintf("The longitude of the spacecraft at this time is: sn'', L_s
```

### Problem 2

• Consider a satellite non-linear power amplifier (e.g., TWTA) with the following voltage transfer characteristic:

$$v_{out} = b_1 v_{in} + b_3 v_{in}^3$$

Where  $v_{in}(t) = \cos(2\pi f_1 t) + \cos(2\pi f_2 t) + \cos(2\pi f_3 t)$ . Here,  $f_1 = 3.8$ GHz,  $f_2 = 3.9$ 5GHz, and  $f_3 = 4.0$ 5GHz.

- Assume that the satellite transponder bandwidth is from  $f_{\ell} = 3.7 \text{GHz}$  to  $f_u = 4.2 \text{GHz}$
- Determine the amplitude and location of all intermodulation (IM) products within the transponder bandwidth resulting from the power amplifier action on the input signal  $v_{in}$ . **Note:** Present your final answers in the form of a table

#### Solution

Given

$$v_{out} = b_1 v_{in} + b_3 v_{in}^3 \tag{1}$$

We have:

$$v_{in} = \cos(\omega_1 t) + \cos(\omega_2 t) + \cos(\omega_3 t)$$
 where  $\omega_1 = 2\pi f_1$ ,  $\omega_2 = 2\pi f_2$ ,  $\omega_3 = 2\pi f_3$  (2)

We know that:

$$(a+b+c)^3 = a^3 + 3a^2b + 3a^2c + 6abc + 3ac^2 + b^3 + 3b^2c + 3bc^2 + c^3$$
(3)

Using 3 we have  $v_{in}^3$  to be:

$$v_{in}^{3} = \cos^{3}(\omega_{1}t) + 3\cos^{2}(\omega_{1}t)\cos(\omega_{2}t) + 3\cos^{2}(\omega_{1}t)\cos(\omega_{3}t) + 6\cos(\omega_{1}t)\cos(\omega_{2}t)\cos(\omega_{3}t) + 3\cos(\omega_{1}t)\cos^{2}(\omega_{3}t) + \cos^{3}(\omega_{2}t) + 3\cos^{2}(\omega_{2}t)\cos(\omega_{3}t) + 3\cos(\omega_{2}t)\cos^{2}(\omega_{3}t) + \cos^{3}(\omega_{3}t)$$
(4)

Applying the trigonometric identities given below:

$$\cos^3 x = \frac{\cos(3x) + 3\cos x}{4} \tag{5}$$

$$\cos^2 x = \frac{\cos(2x) + 1}{2} \tag{6}$$

We can simplify 4 as follows

$$v_{in}^{3} = \frac{\cos(3\omega_{1}t) + 3\cos(\omega_{1}t)}{4} + \frac{\cos(3\omega_{2}t) + 3\cos(\omega_{2}t)}{4} + \frac{\cos(3\omega_{3}t) + 3\cos(\omega_{3}t)}{4} + \frac{3\cos(\omega_{1}t)\cos(\omega_{2}t) + 3\cos(\omega_{1}t)\cos(\omega_{3}t) + 3\cos(\omega_{2}t)\cos(\omega_{3}t)}{2} + \frac{3\cos(\omega_{1}t)\cos(\omega_{2}t)\cos(\omega_{3}t)}{4}$$

$$(7)$$

Simplifying further, we arrive at:

$$v_{in}^{3} = \frac{1}{4} (\cos(3\omega_{1}t) + \cos(3\omega_{2}t) + \cos(3\omega_{3}t))$$

$$+ \frac{3}{4} [\cos\{(2\omega_{1} + \omega_{2})t\} + \cos\{(2\omega_{1} - \omega_{2})t\}$$

$$+ \cos\{(2\omega_{1} + \omega_{3})t\} + \cos\{(2\omega_{1} - \omega_{3})t\}$$

$$+ \cos\{(2\omega_{2} + \omega_{1})t\} + \cos\{(2\omega_{2} - \omega_{1})t\}$$

$$+ \cos\{(2\omega_{2} + \omega_{3})t\} + \cos\{(2\omega_{2} - \omega_{3})t\}$$

$$+ \cos\{(2\omega_{3} + \omega_{1})t\} + \cos\{(2\omega_{3} - \omega_{1})t\}$$

$$+ \cos\{(2\omega_{3} + \omega_{1})t\} + \cos\{(2\omega_{3} - \omega_{1})t\}$$

$$+ \cos\{(2\omega_{3} + \omega_{2})t\} + \cos\{(2\omega_{3} - \omega_{2})t\} ]$$

$$+ \frac{3}{2} [\cos\{(\omega_{1} + \omega_{2} + \omega_{3})t\} + \cos\{(\omega_{1} + \omega_{2} - \omega_{3})t\} ]$$

$$+ \cos\{(\omega_{1} - \omega_{2} + \omega_{3})t\} + \cos\{(\omega_{1} - \omega_{2} - \omega_{3})t\} ]$$

$$+ \frac{15}{4} [\cos(\omega_{1}t) + \cos(\omega_{2}t) + \cos(\omega_{3}t)]$$

Hence the final value of  $v_{IM}$  is (accounting only for frequencies in the range  $f_{\ell}=3.7 \mathrm{GHz}$  to  $f_{u}=4.2 \mathrm{GHz}$ ):

$$v_{IM} = \left(b_1 + \frac{15}{4}b_3\right) \left(\cos(\omega_1 t) + \cos(\omega_2 t) + \cos(\omega_3 t)\right)$$

$$+ \frac{3}{4}b_3 \left[\cos(\{2\omega_2 - \omega_1\}t) + \cos(\{2\omega_2 - \omega_3\}t) + \cos(\{2\omega_3 - \omega_2\}t)\right]$$

$$+ \frac{3}{2}b_3 \left[\cos\{(\omega_1 + \omega_2 - \omega_3)t\} + \cos\{(\omega_1 - \omega_2 + \omega_3)t\} + \cos\{(\omega_1 - \omega_2 - \omega_3)t\}\right]$$

$$(9)$$

Presenting the frequencies received in a tabular format:

Amplitude	Location	Frequency
$b_1 + \frac{15}{4}b_3$	$f_1$	$3.8 \mathrm{GHz}$
	$f_2$	3.95GHz
	$f_3$	$4.05 \mathrm{GHz}$
$\frac{3}{4}b_3$	$2f_2 - f_1$	4.1GHz
	$2f_2 - f_3$	$3.85 \mathrm{GHz}$
	$2f_3 - f_2$	$4.15 \mathrm{GHz}$
$rac{3}{2}b_3$	$f_1 + f_2 - f_3$	3.7GHz
	$f_1 - f_2 + f_3$	3.9GHz
	$f_1 - f_2 - f_3$	4.2GHz

Table 1: IM frequencies