

Optimizing Looping ROC Curves

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Area Under the ROC Curve (AUC)

- Setup: model outputs a prediction vector given some examples, comparing the values to a threshold of zero to get classifications.
- Different points on the ROC curve are obtained by adding a constant to the predicted values (TPR vs FPR).
- AUC is an evaluation metric which accounts for every possible threshold
- AUC can be interpreted as the probability of ranking a positive example higher than a negative example

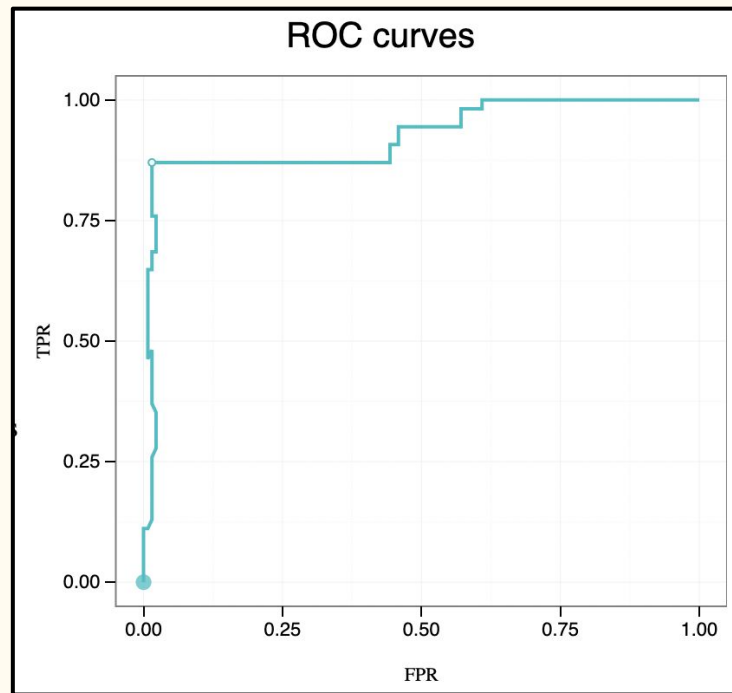
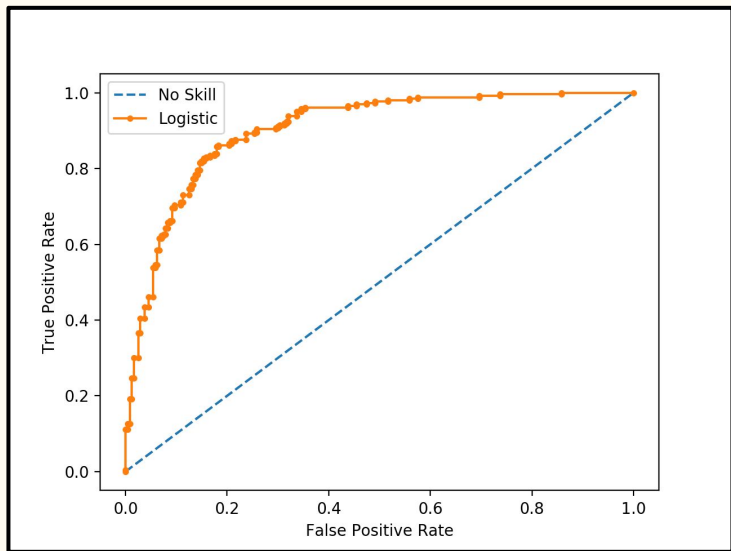


Figure from [Dr. Hocking](#)

Where do non-convex ROC curves come from?

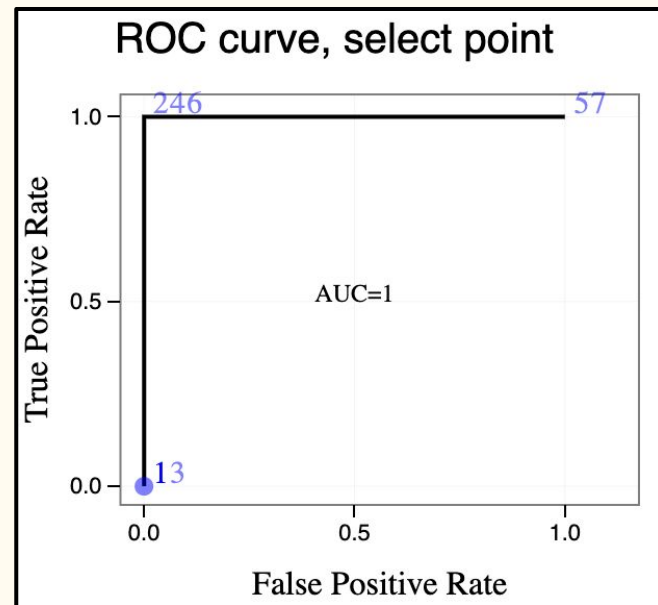
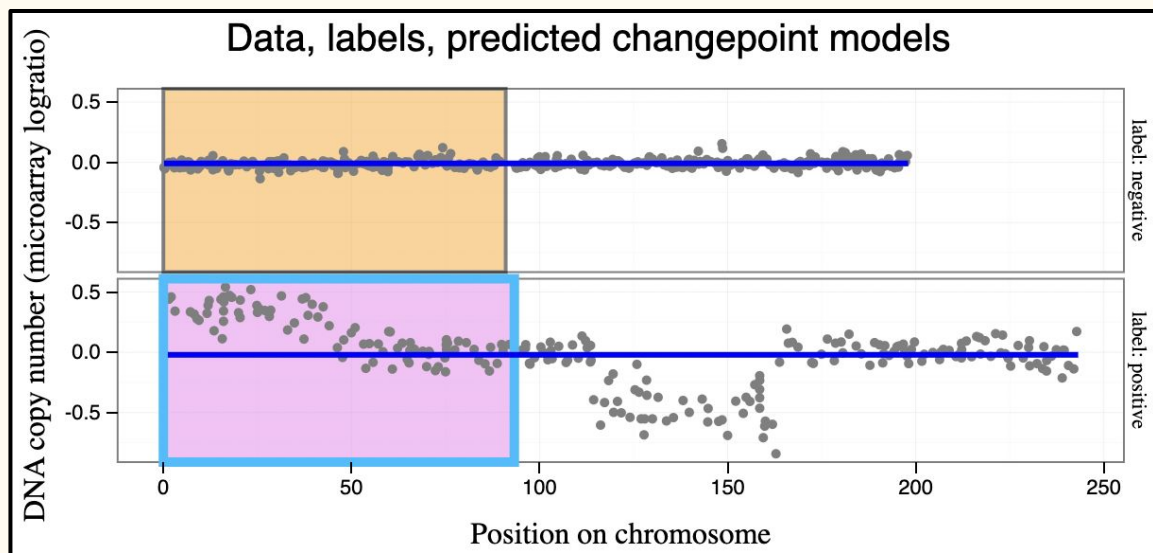


Concave ROC curve from [ML Mastery](#)

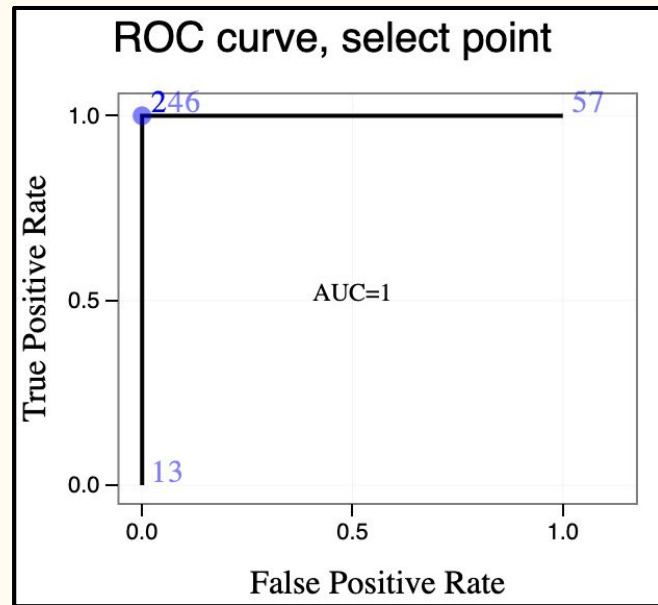
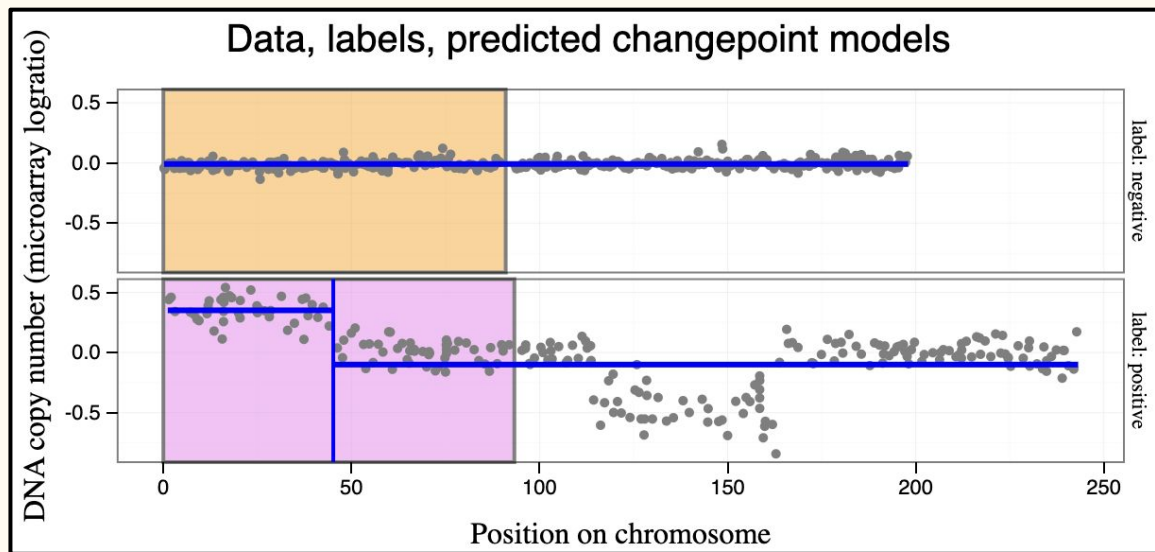
- In binary classification problems, there's a relationship between the increasing the classification thresholding and the TPR/FPR.
- In change point detection, gradual increases to the constant added to this prediction vector don't imply gradual increases to ROC points.

Expected changepoints in orange box: 0

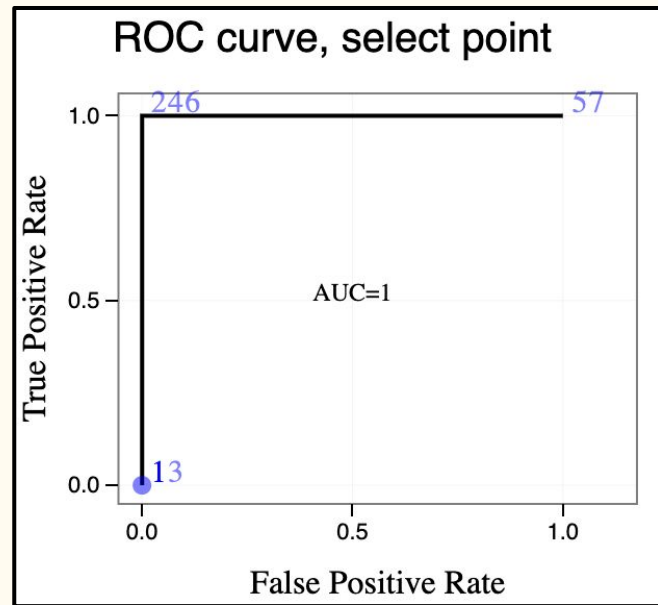
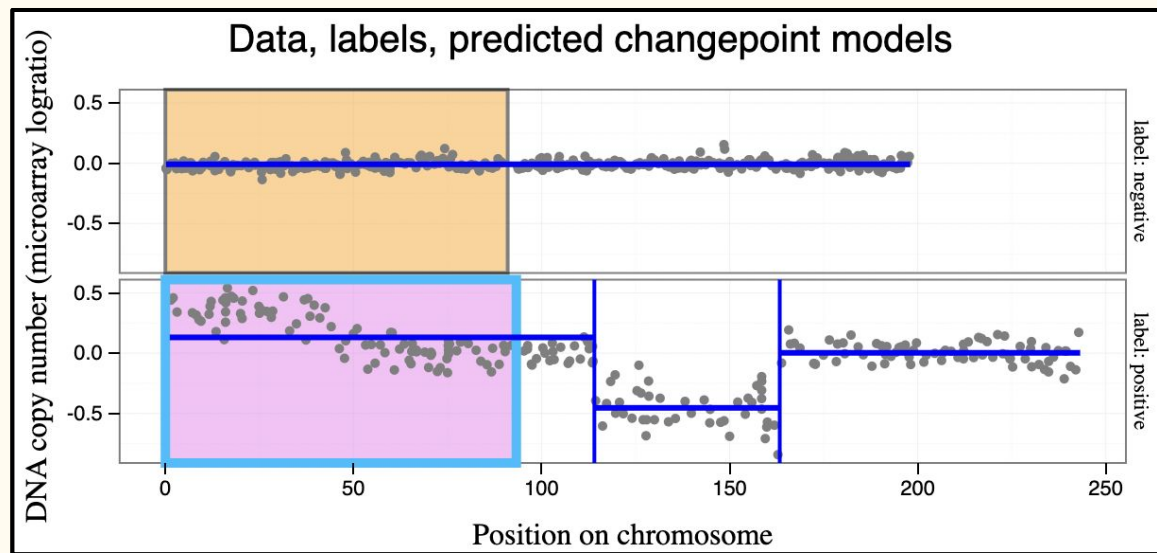
Expected changepoints in pink box: 1



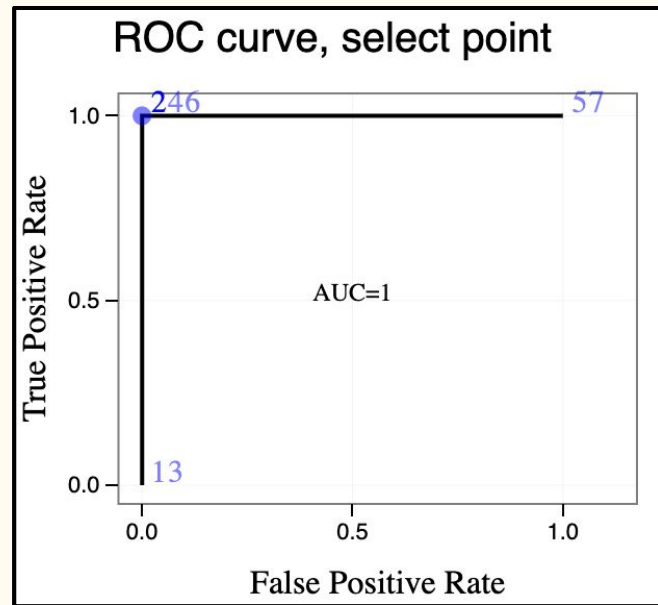
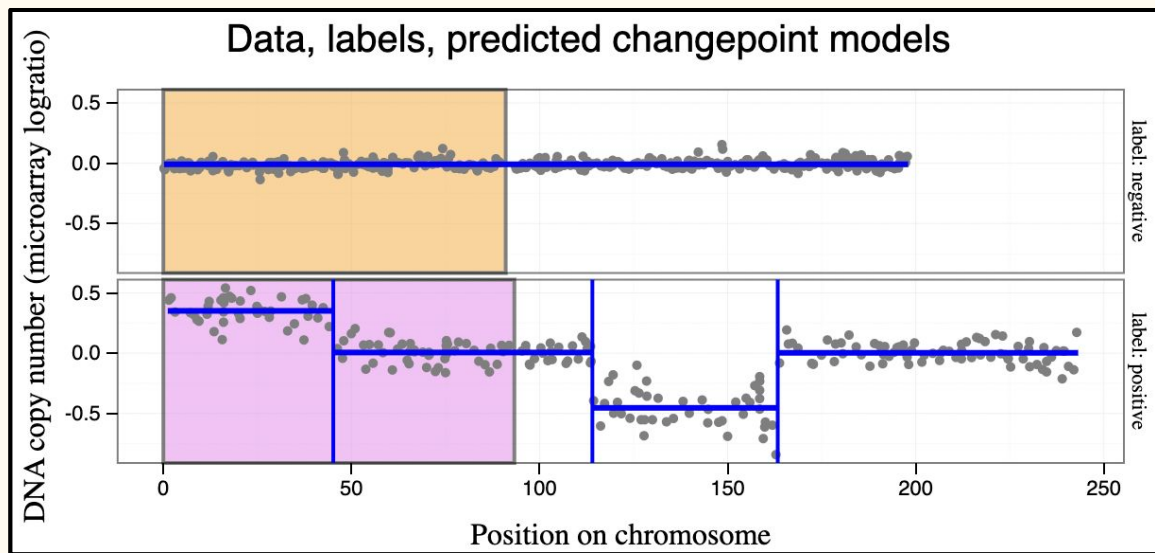
ROC Point: 1



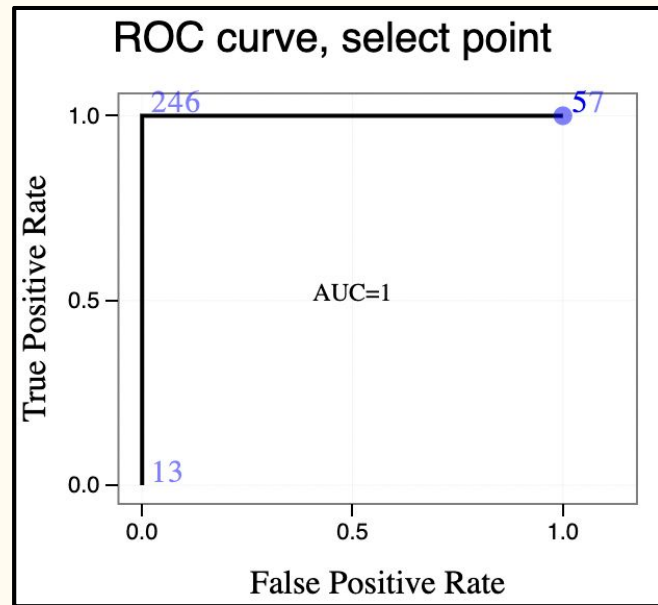
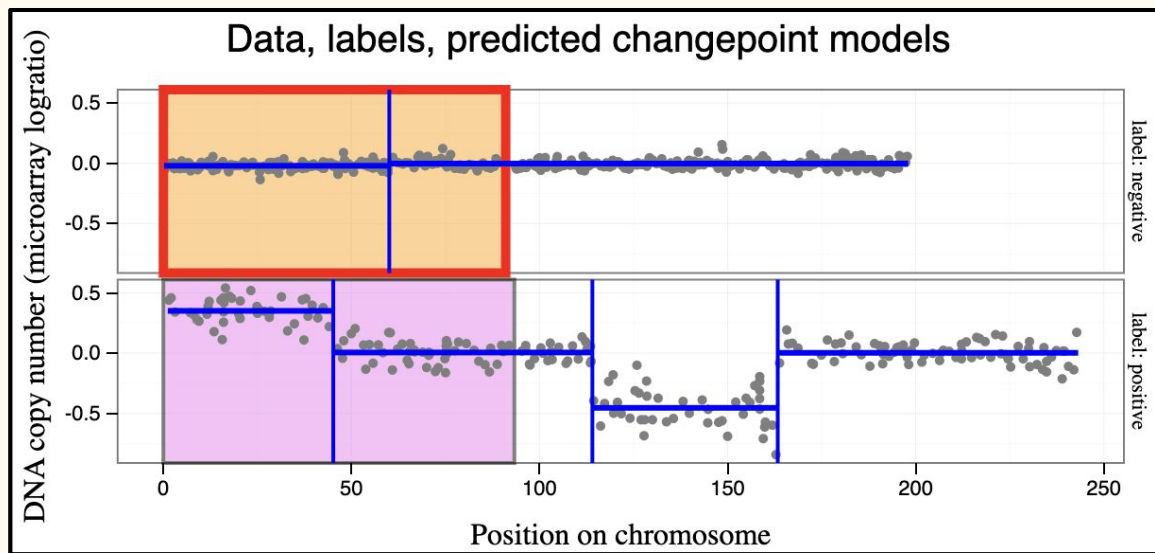
ROC Point: 2



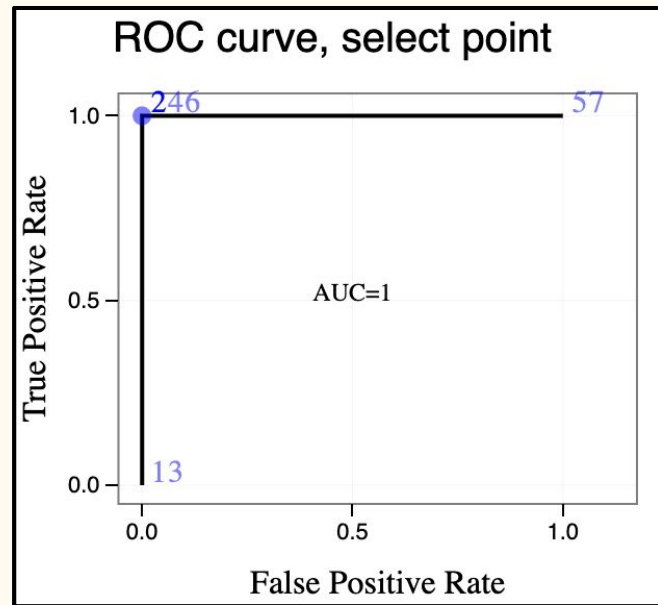
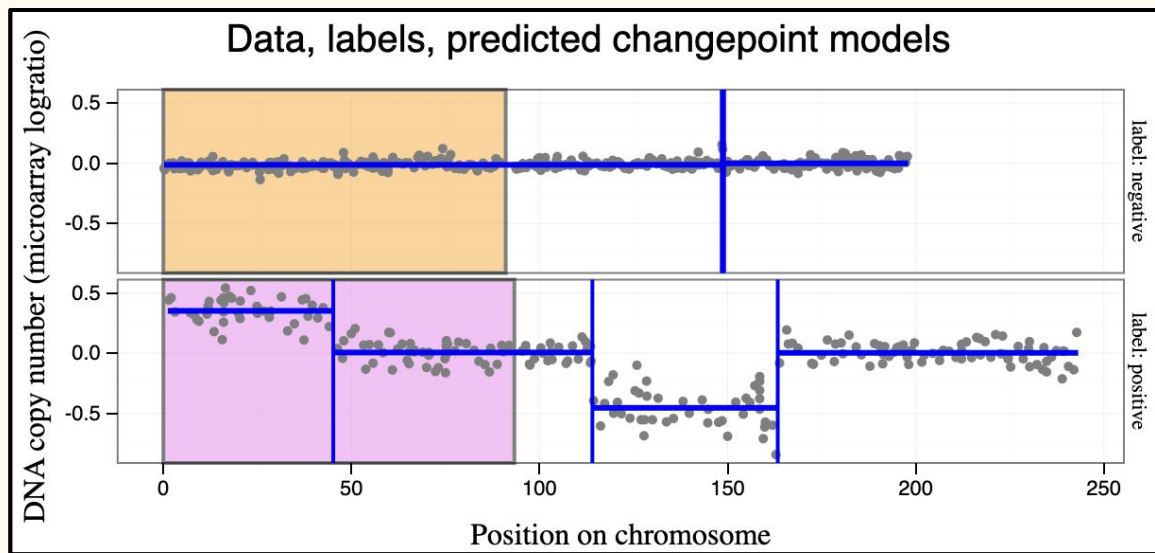
ROC Point: 3



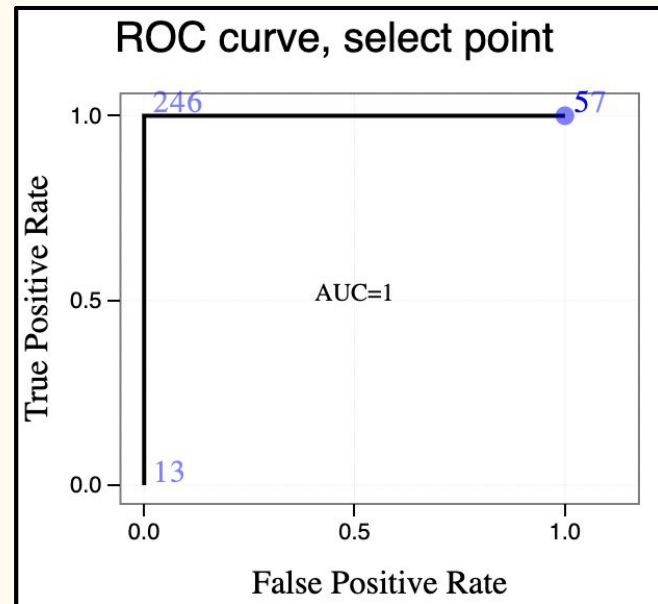
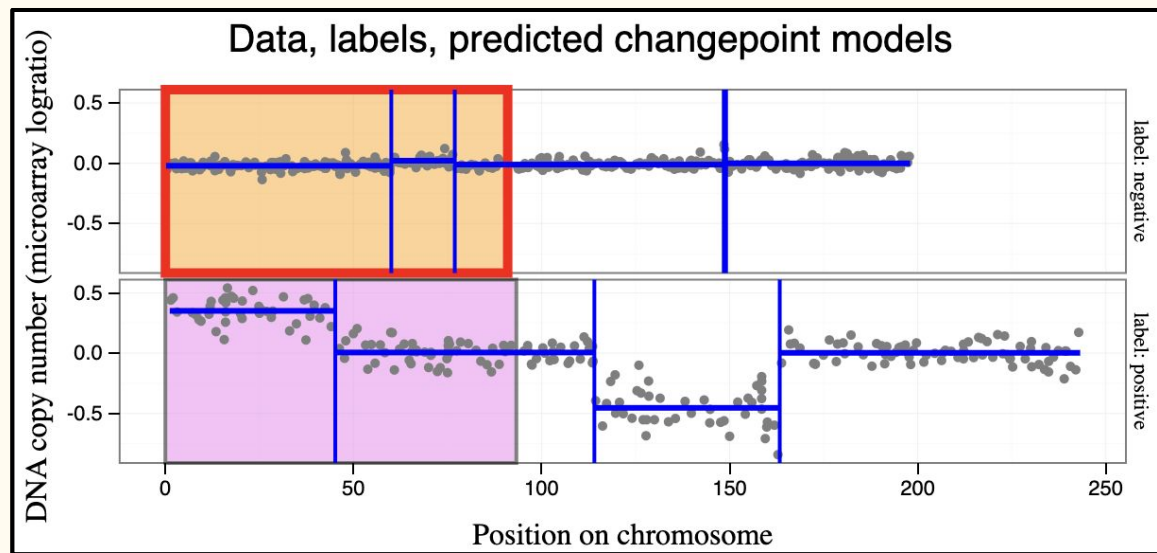
ROC Point: 4



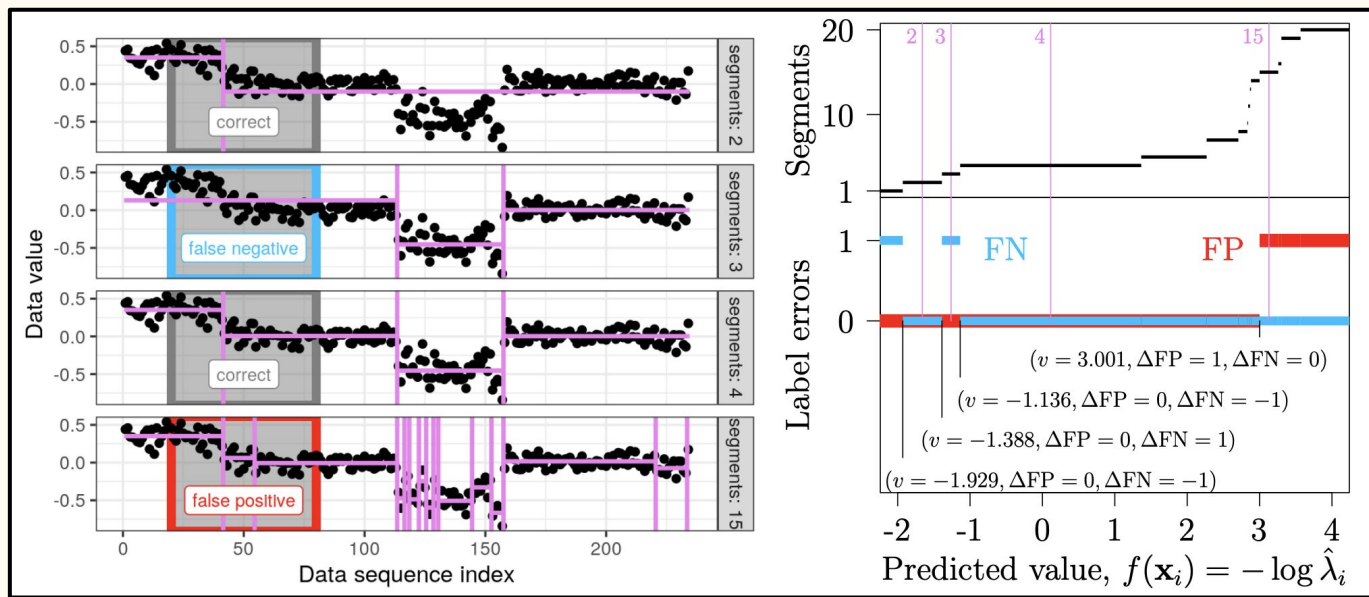
ROC Point: 5



ROC Point: 6

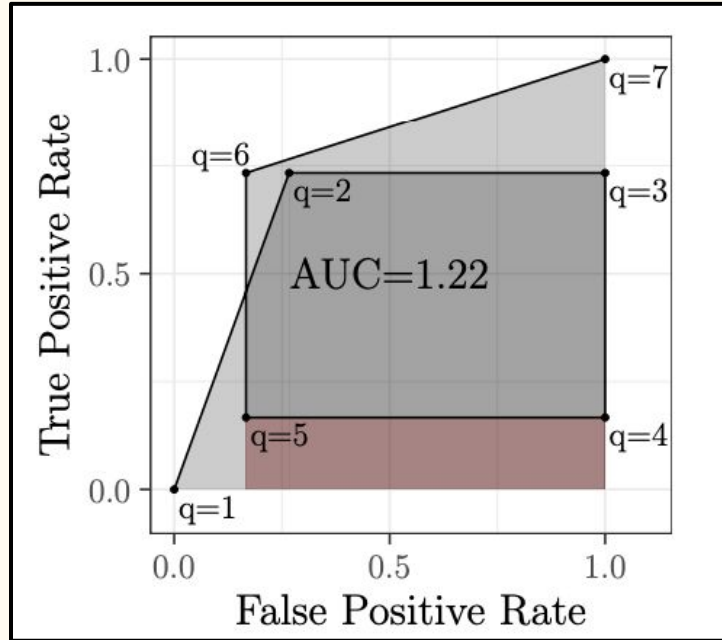


ROC Point: 7



FN and FP are piecewise functions

ROC Curves can Loop?!



Example ROC curve with $AUC \geq 1$ due to the loop which results in double counting the dark grey area (but single counting the red area which is positive counted twice and negative counted once). [*Hillman & Hocking 2021*](#)

Optimizing ROC Curves with a Sort-Based Surrogate Loss Function for Binary Classification and Changepoint Detection

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July 6, 2021

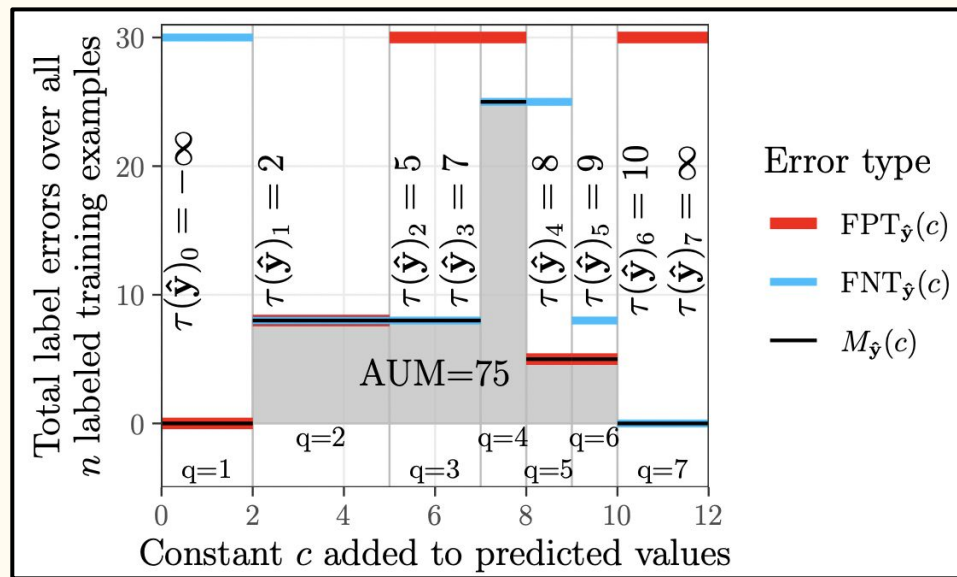
[arxiv link](#)

Area Under Min(FP, FN)

- Motivation: certain problems non-convex AUC
- $M(c) = \text{Minimum of the False Positive Total and the False Negative Total for some constant added to our prediction vector}$
- FPT / FNT change at breakpoints
- Shown than minimizing AUM corresponds to maximizing AUC
- How do we minimize this?

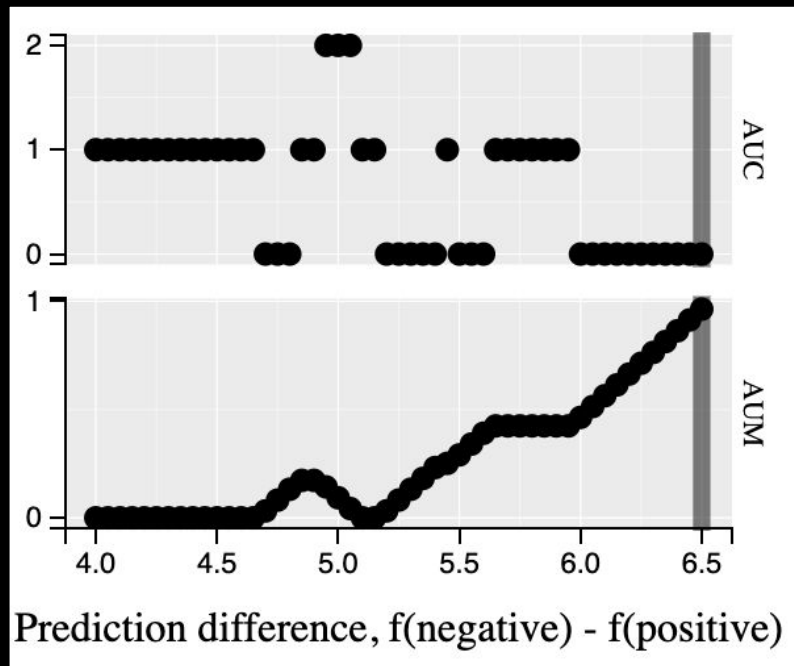
$$M_{\hat{\mathbf{y}}}(c) = \min\{\text{FPT}_{\hat{\mathbf{y}}}(c), \text{FNT}_{\hat{\mathbf{y}}}(c)\}.$$

$$\text{AUM}(\hat{\mathbf{y}}) = \int_{-\infty}^{\infty} M_{\hat{\mathbf{y}}}(c) dc.$$



How to minimize?

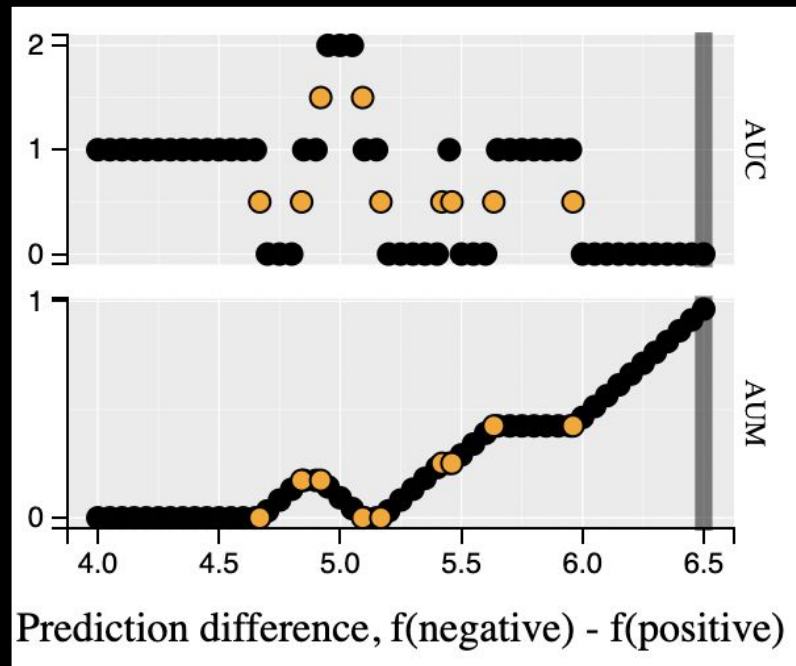
- Walk down AUM function
- Calculate gradient and move in the descent direction
- Line search to find the step size that decreases AUM the most



AUC vs. AUM

How to minimize?

- Non-differentiable points occur at breakpoints
- The gradient is not defined at these points!
- We use directional derivatives as a replacement



AUC vs. AUM with
non-differentiable points?!

Minimizing AUM for a Linear Model

Given a Linear Model,

$$f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + \beta$$

we can define a weight update

$$\mathbf{w}^{(j+1)} = \mathbf{w}^{(j)} - \alpha^{(j)} \mathbf{X}^\top \bar{\mathbf{D}}_{\text{AUM}}(\mathbf{X} \mathbf{w}^{(j)} + \beta^{(j)})$$

using a matrix of directional derivatives for a given prediction vector

$$\mathbf{D}_f(\mathbf{x}) = \begin{bmatrix} \nabla_{\mathbf{v}(-1,1)} f(\mathbf{x}) & \cdots & \nabla_{\mathbf{v}(-1,n)} f(\mathbf{x}) \\ \nabla_{\mathbf{v}(1,1)} f(\mathbf{x}) & \cdots & \nabla_{\mathbf{v}(1,n)} f(\mathbf{x}) \end{bmatrix}^\top$$

Minimizing AUM for a Linear Model

Given a Linear Model,

$$f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + \beta$$

$$\begin{aligned}\nabla_{\mathbf{v}(-1,i)} \text{AUM}(\hat{\mathbf{y}}) &= \sum_{b:\mathcal{I}_b=i} \min\{\overline{\text{FP}}_b, \overline{\text{FN}}_b\} - \min\{\overline{\text{FP}}_b - \Delta \text{FP}_b, \overline{\text{FN}}_b - \Delta \text{FN}_b\}, \\ \nabla_{\mathbf{v}(1,i)} \text{AUM}(\hat{\mathbf{y}}) &= \sum_{b:\mathcal{I}_b=i} \min\{\underline{\text{FP}}_b + \Delta \text{FP}_b, \underline{\text{FN}}_b + \Delta \text{FN}_b\} - \min\{\underline{\text{FP}}_b, \underline{\text{FN}}_b\}.\end{aligned}$$

we can define a weight update

Directional derivatives of AUM

$$\mathbf{w}^{(j+1)} = \mathbf{w}^{(j)} - \alpha^{(j)} \mathbf{X}^\top \bar{\mathbf{D}}_{\text{AUM}}(\mathbf{X} \mathbf{w}^{(j)} + \beta^{(j)})$$

using a matrix of directional derivatives for a given prediction vector

$$\mathbf{D}_f(\mathbf{x}) = \begin{bmatrix} \nabla_{\mathbf{v}(-1,1)} f(\mathbf{x}) & \cdots & \nabla_{\mathbf{v}(-1,n)} f(\mathbf{x}) \\ \nabla_{\mathbf{v}(1,1)} f(\mathbf{x}) & \cdots & \nabla_{\mathbf{v}(1,n)} f(\mathbf{x}) \end{bmatrix}^\top$$

Condensed running title of 50 characters or less: Sort-Based Surrogate for AUC Optimization

Five keywords: AUC, ROC, loss functions, gradient descent, optimization, line search.

Efficient line search for a piecewise linear relaxation of ROC curve optimization

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Efficient AUM Line Search

- Exact line search is $O(n^2)$ in the worst case
- New approximate line search is $O(n \cdot \log(n))$ in the worse case

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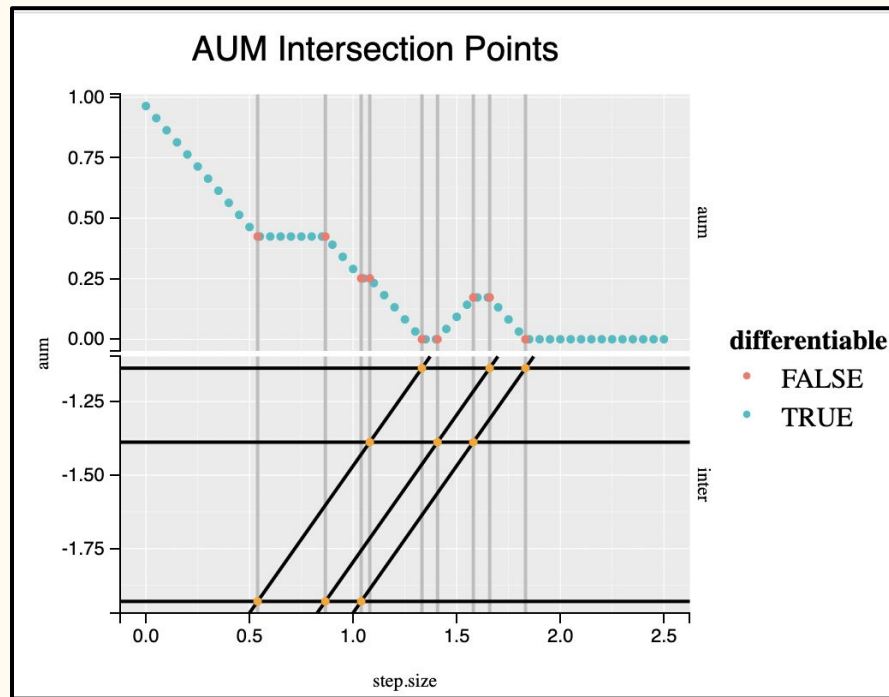
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Reconstructing the AUM line

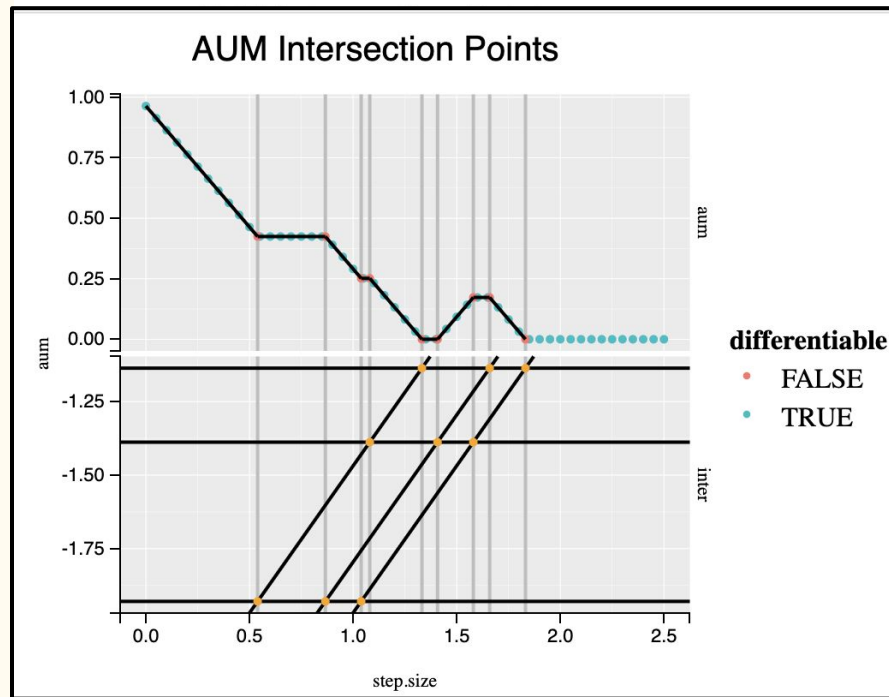
- Breakpoints are tuples: $(v, \Delta FP, \Delta FN)$. They tell us how the FP/FN functions change over time.
- Non-differentiable points line up with these intersections of the bottom lines.
- Bottom lines can be constructed from breakpoint data



Graph by Jadon

Reconstructing the AUM line

- Goal: reconstruct the AUM line using these breakpoints.
- We wouldn't have to calculate the AUM at every point
- Gradient descent for AUM would be much faster



Graph by Jadon