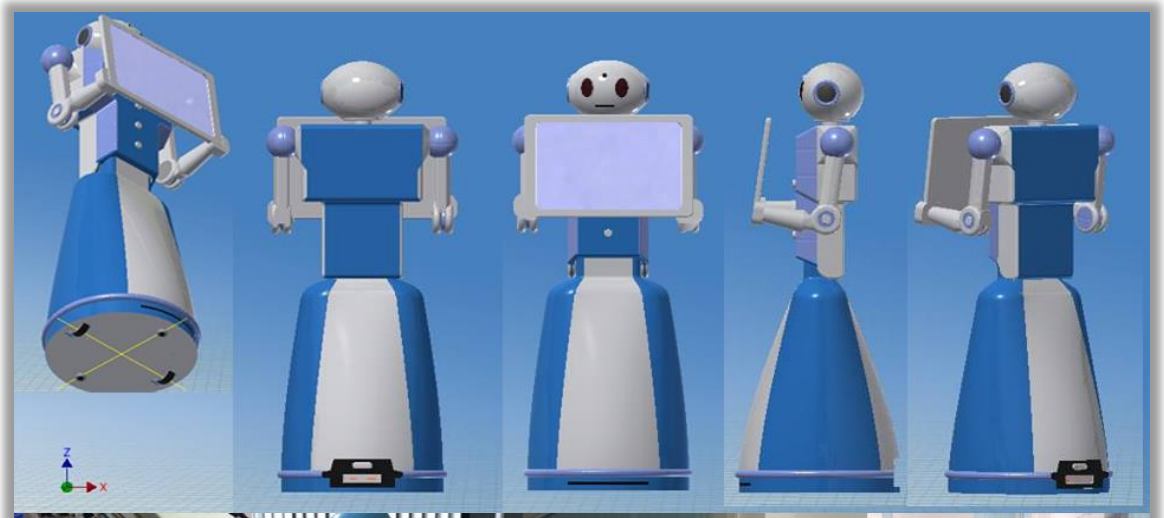
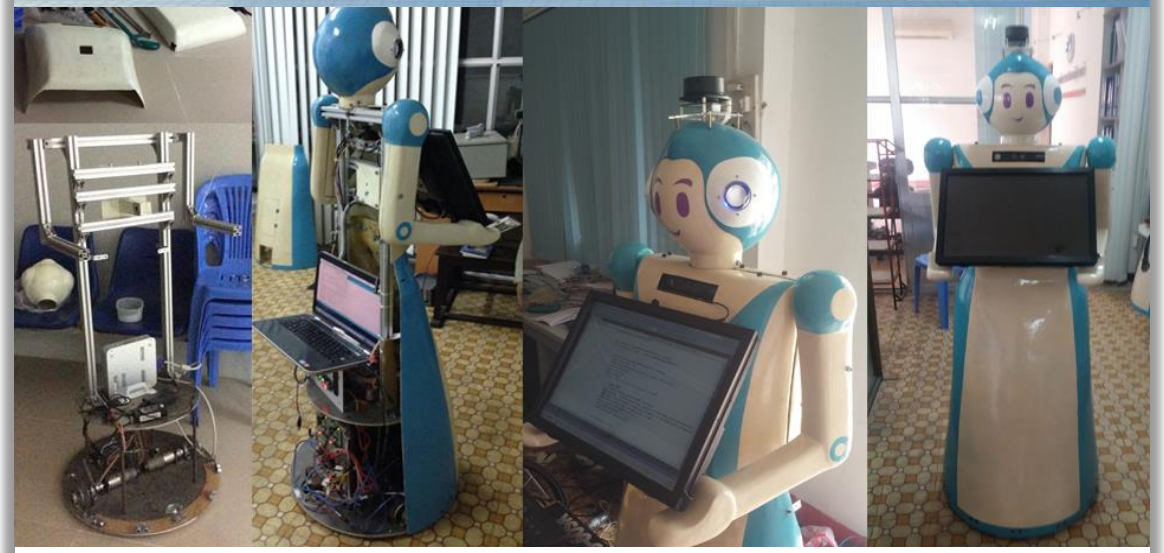
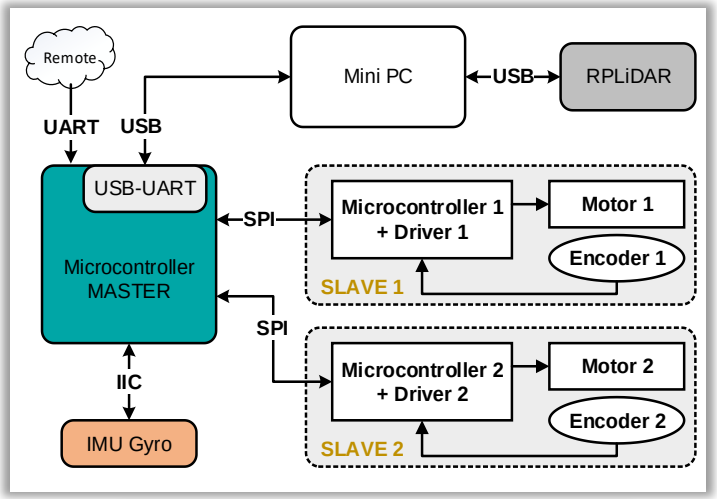
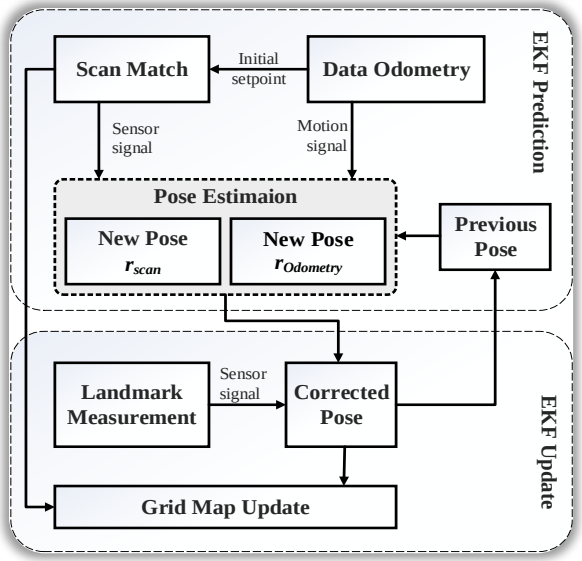
2. RESEARCH & WORK EXPERIENCE (09/2014 – 06/2016)

The Master Degree in **Mechatronics Engineering** at HCMUTE, Viet Nam. A thesis entitled: **"2D Lidar-Based SLAM Algorithm and Path Mapping for Reception Robot".** (Grade: 8.3/10)









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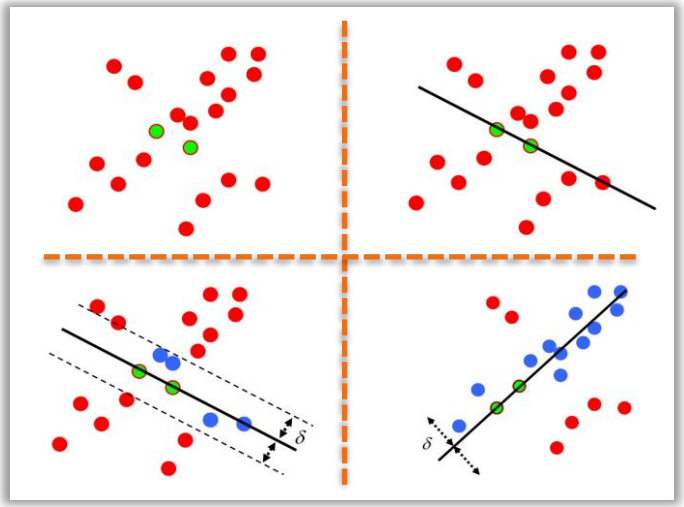

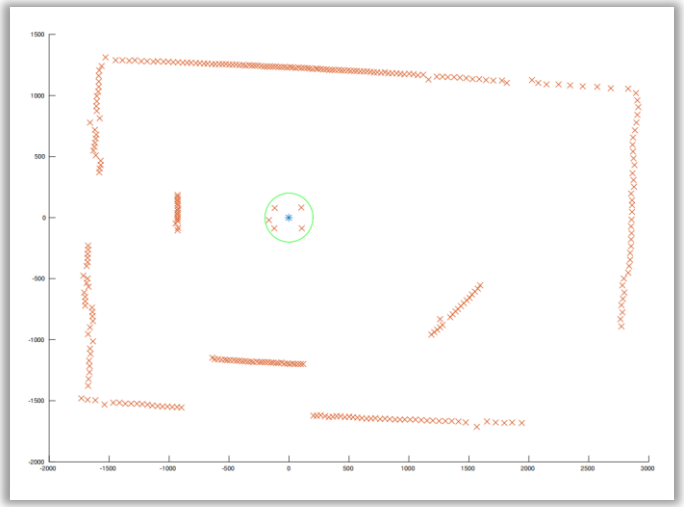

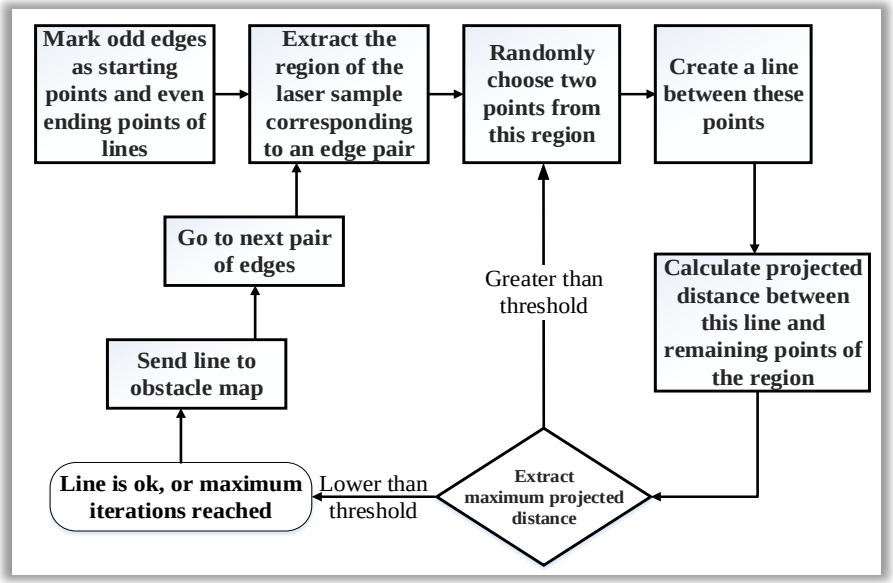

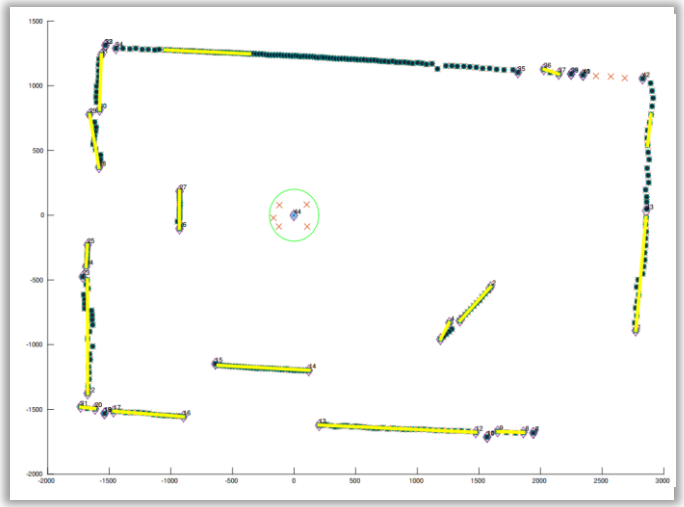

Flowchart of algorithms for line extraction - RANSAC

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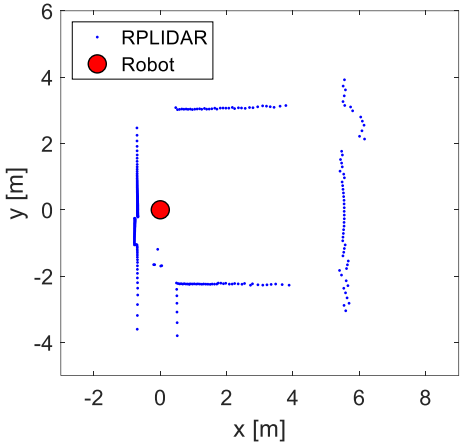

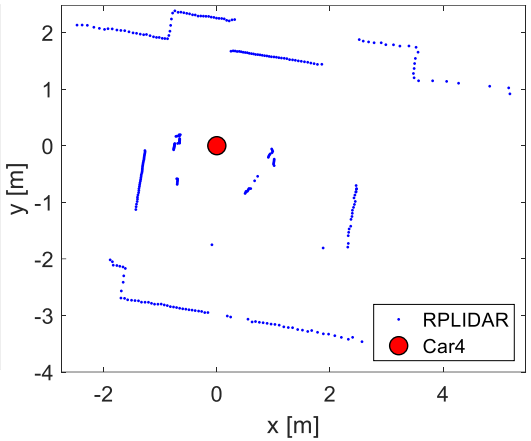

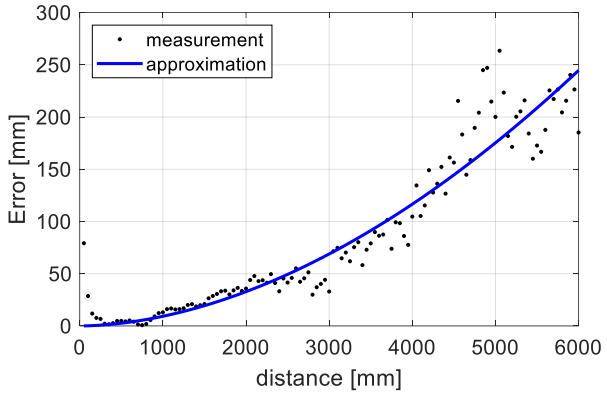

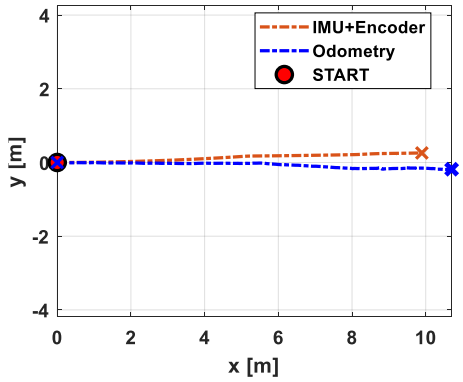

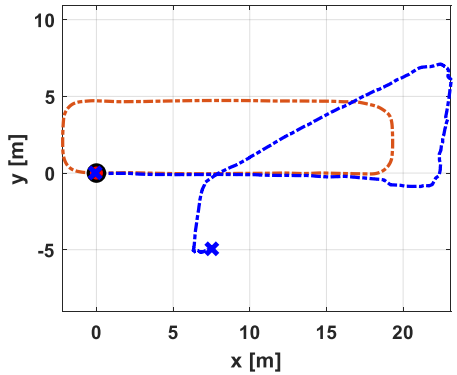

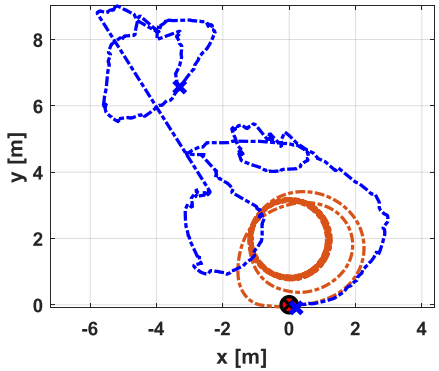

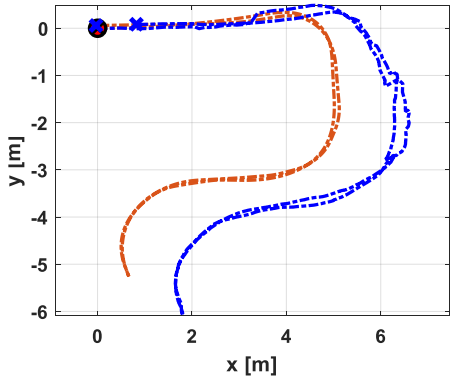

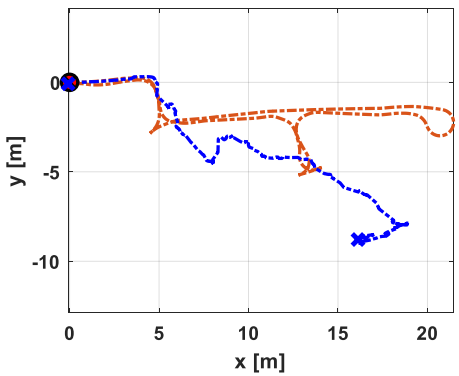

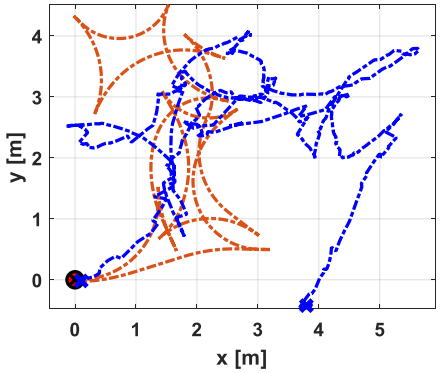
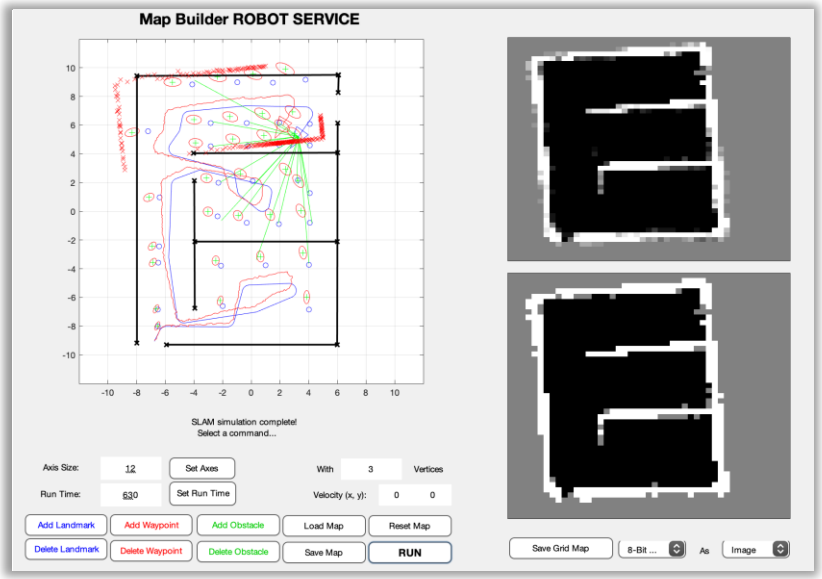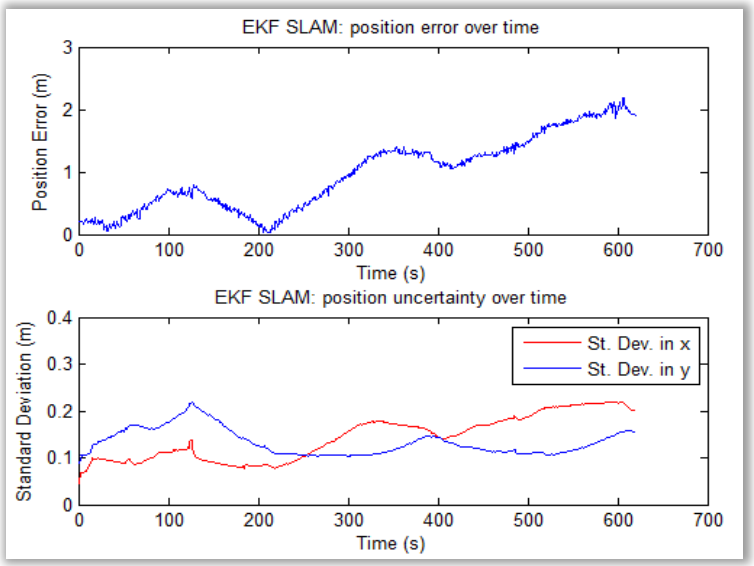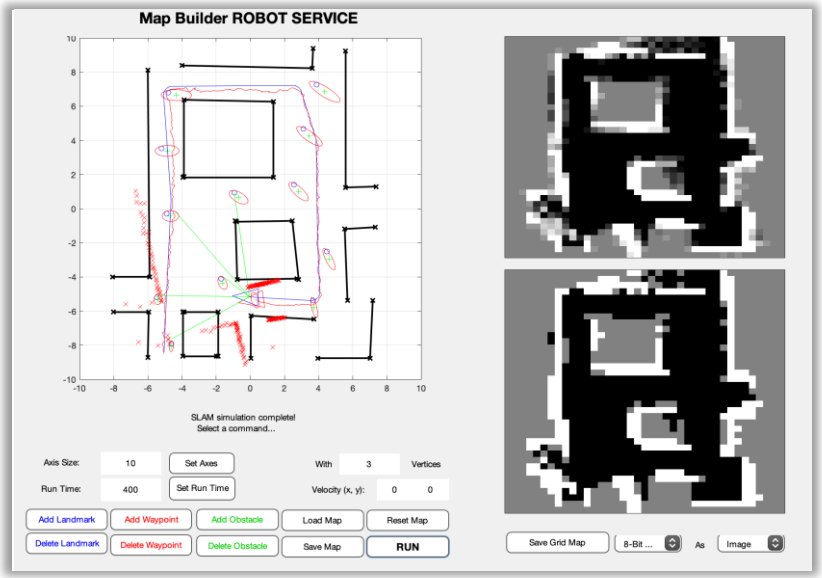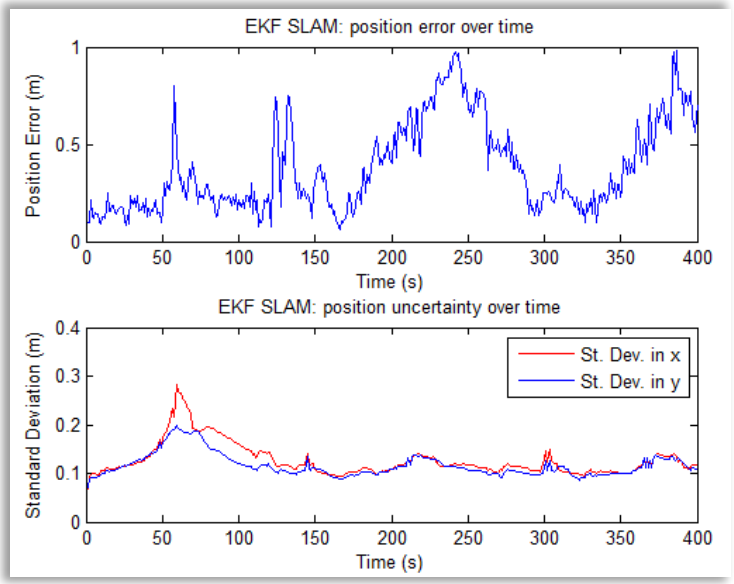
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