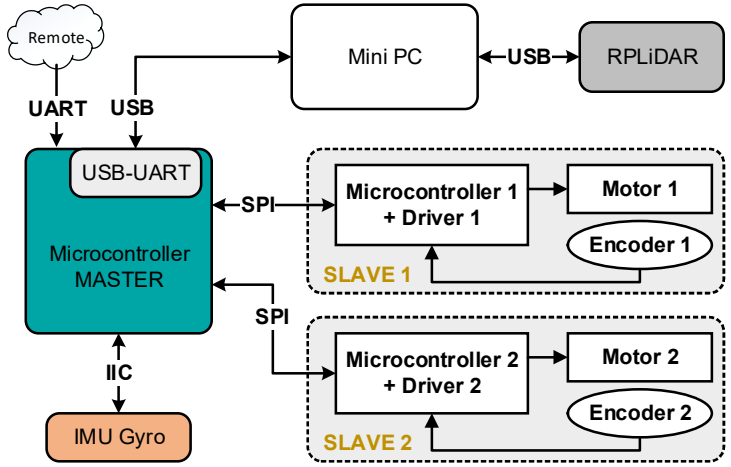
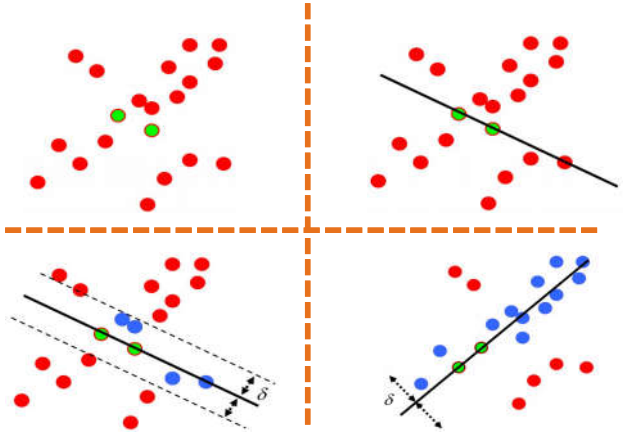
1. INTRODUCTION

The Master Degree in **Mechatronics Engineering** at HCMUTE, Viet Nam, 2016. A thesis entitled: **"2D Lidar-Based SLAM Algorithm and Path Mapping for Reception Robot".** (Grade: 8.3/10)





Random Sampling Consensus (RANSAC)

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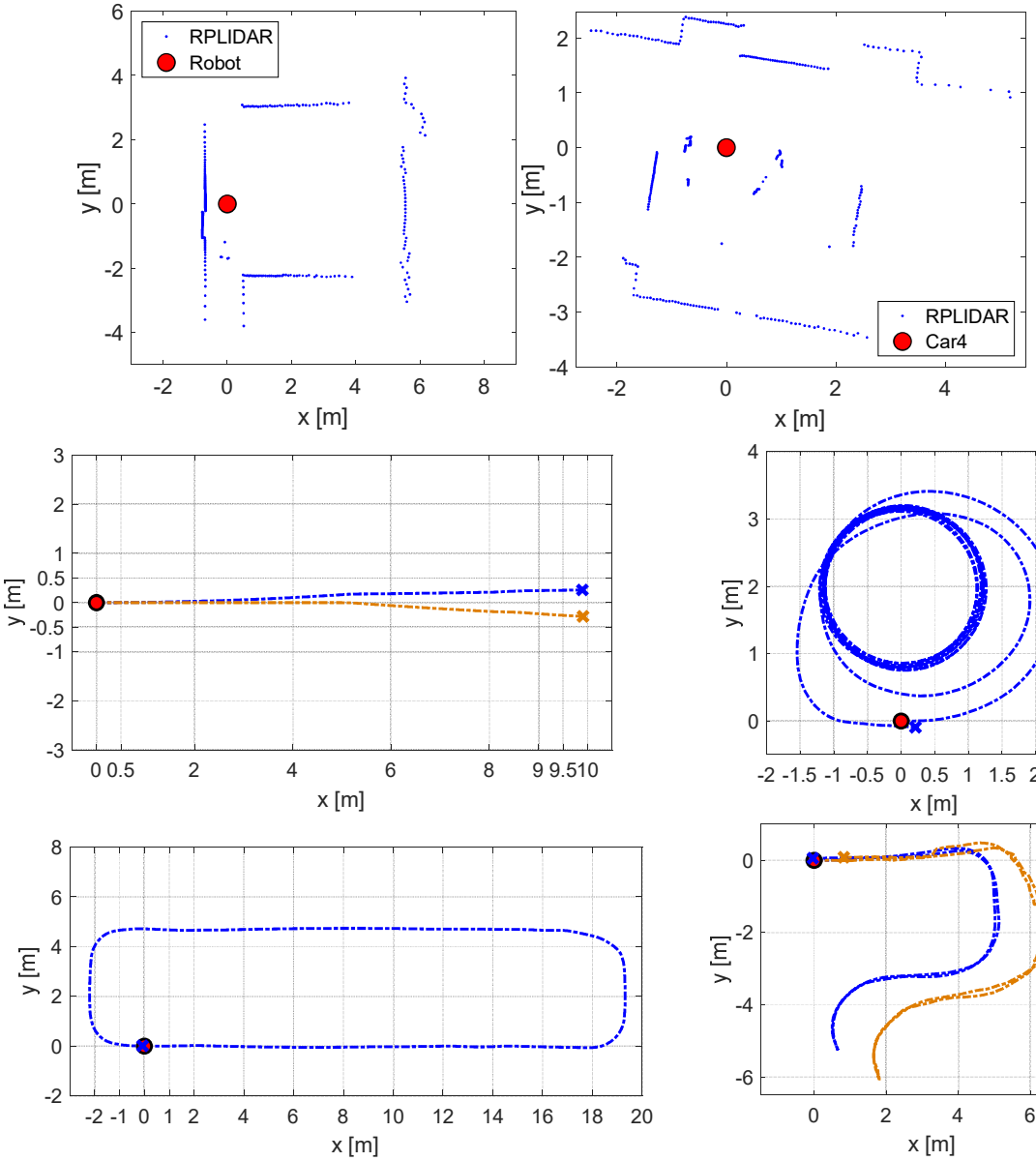
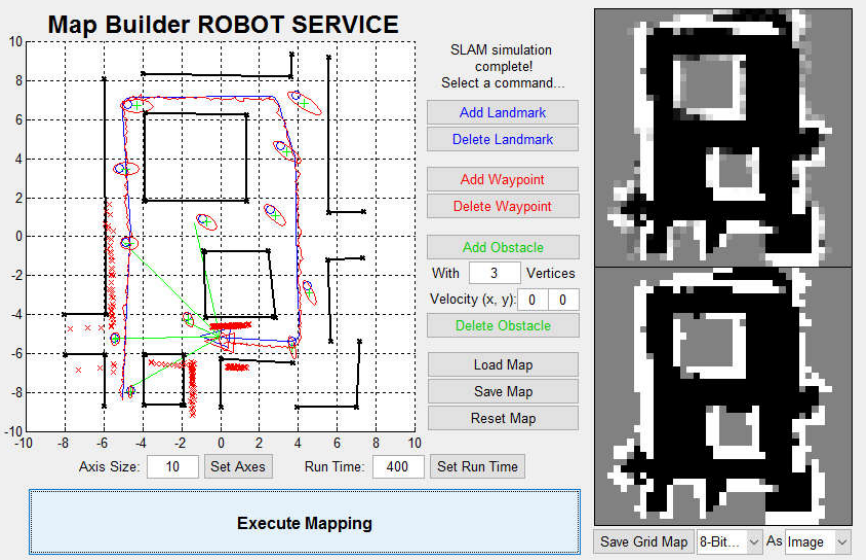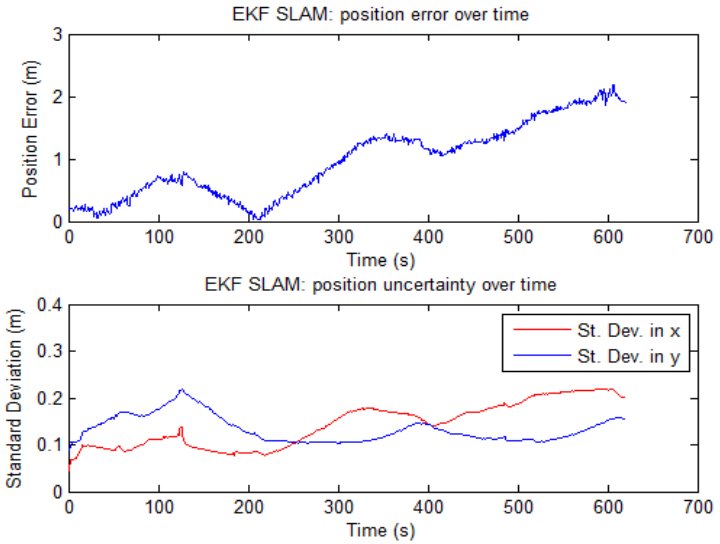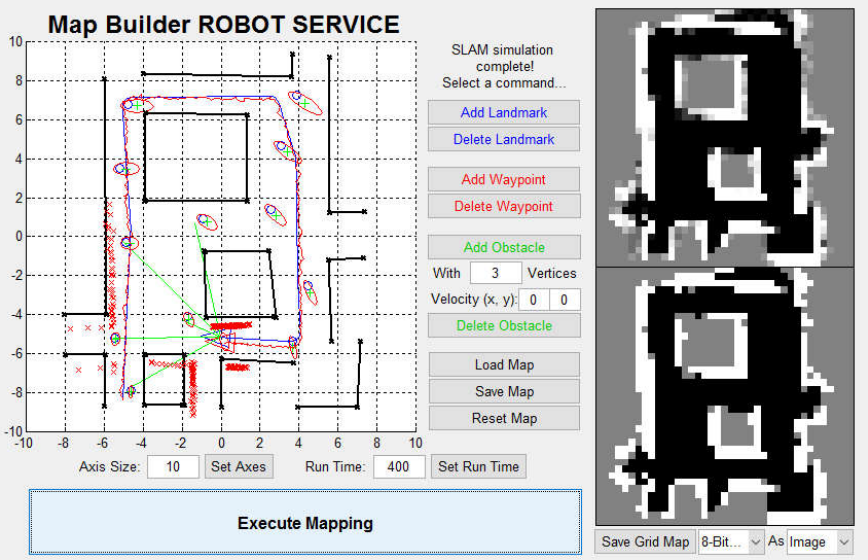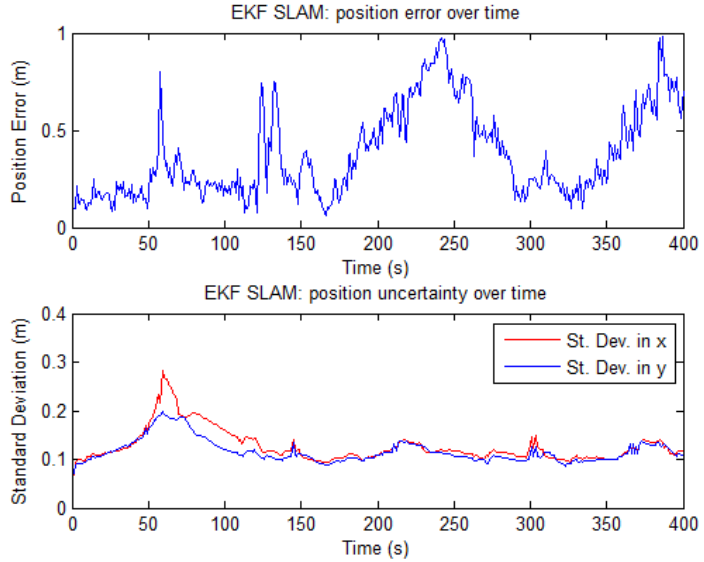
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