

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]


[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]



\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

Figure 1 is a schematic diagram of the experimental setup. It shows a subject seated at a table, looking at a video screen. A camera is positioned above the screen. A horizontal bar is placed on the table, with a vertical rod attached to it. The rod is connected to a motor unit. The motor unit is connected to a power source. The video screen displays the visual feedback of the hand position.

[REDACTED]

[REDACTED]

[REDACTED]

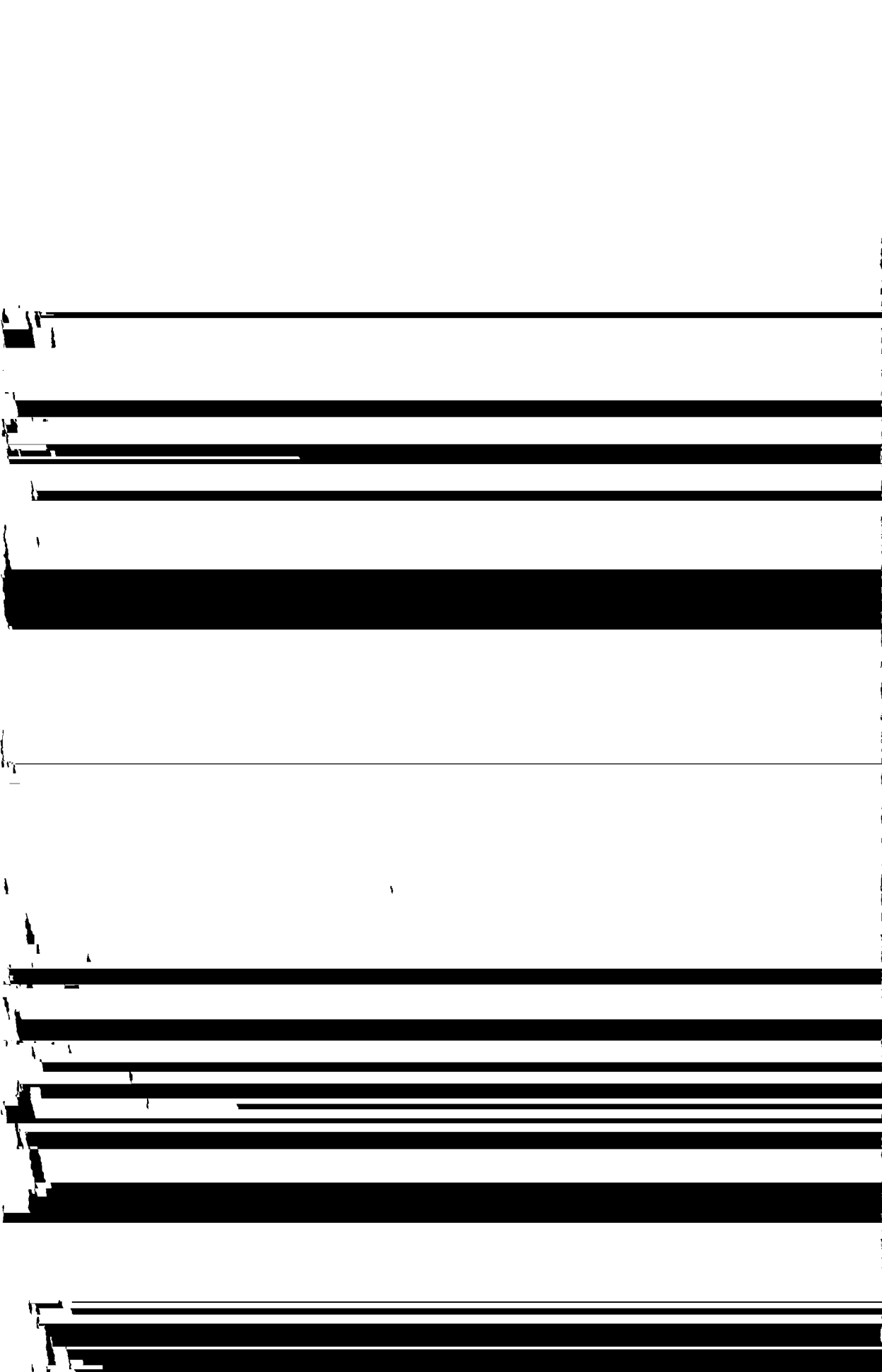
[REDACTED]

\_\_\_\_\_

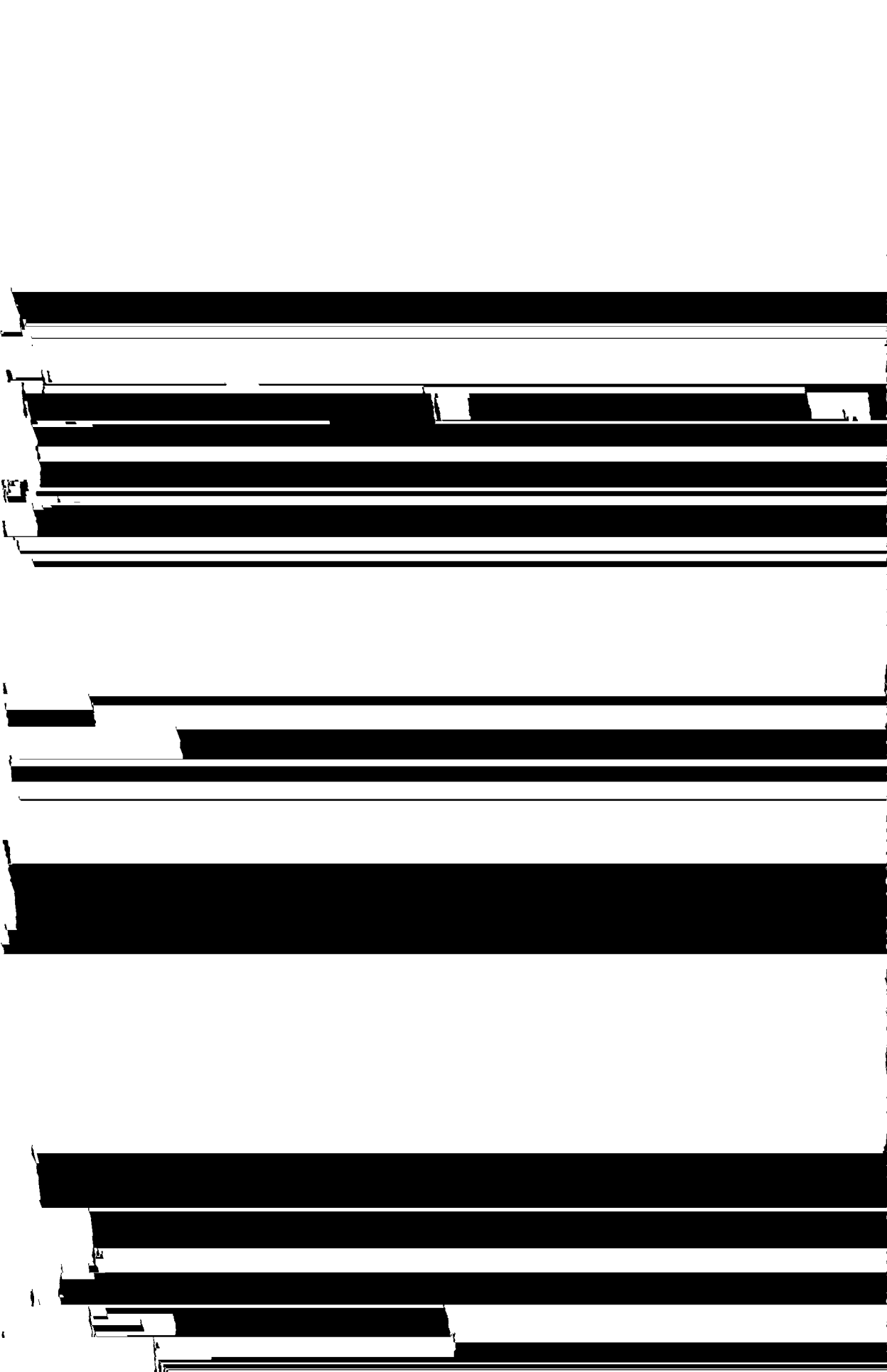
\_\_\_\_\_

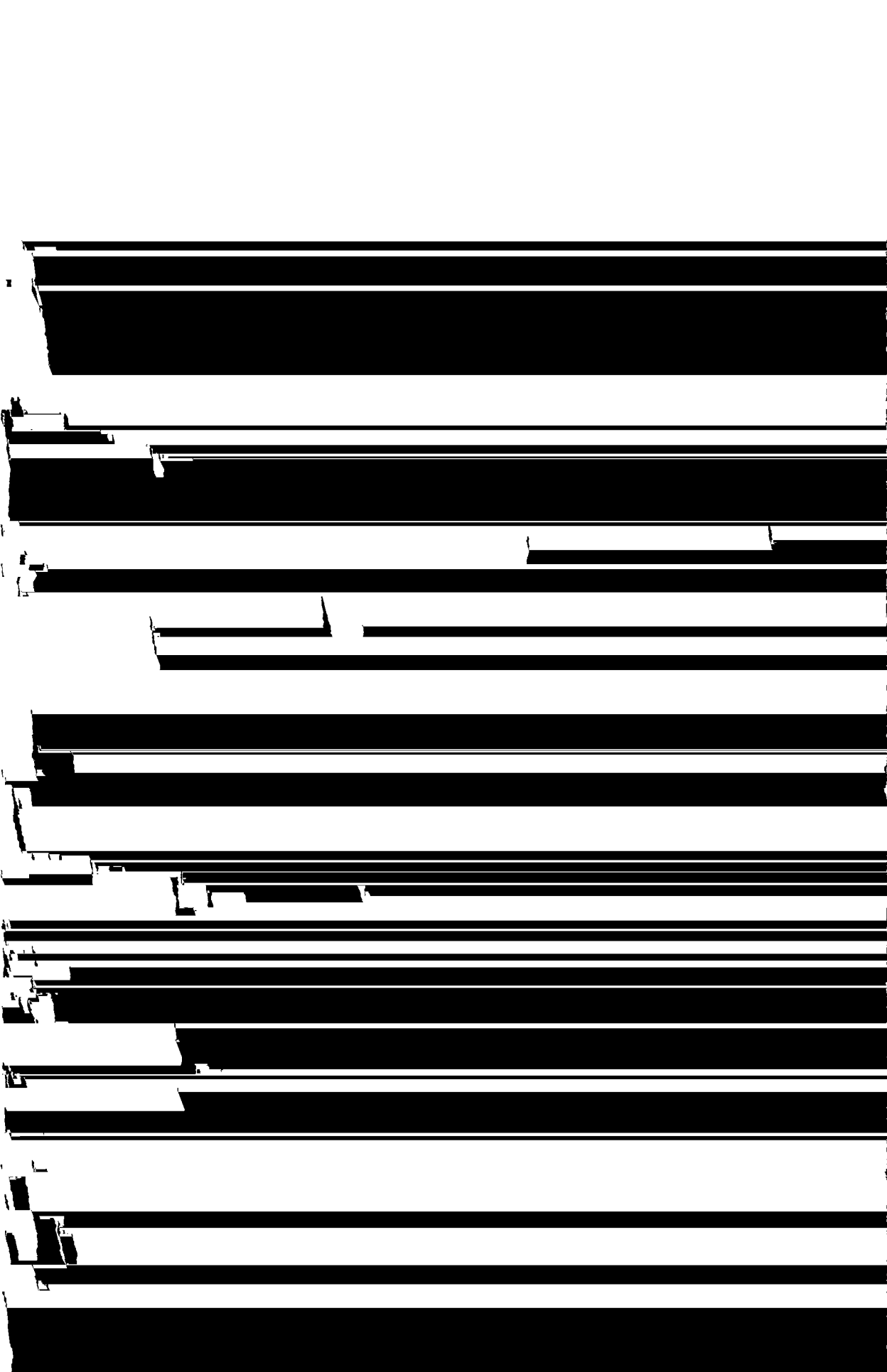
\_\_\_\_\_

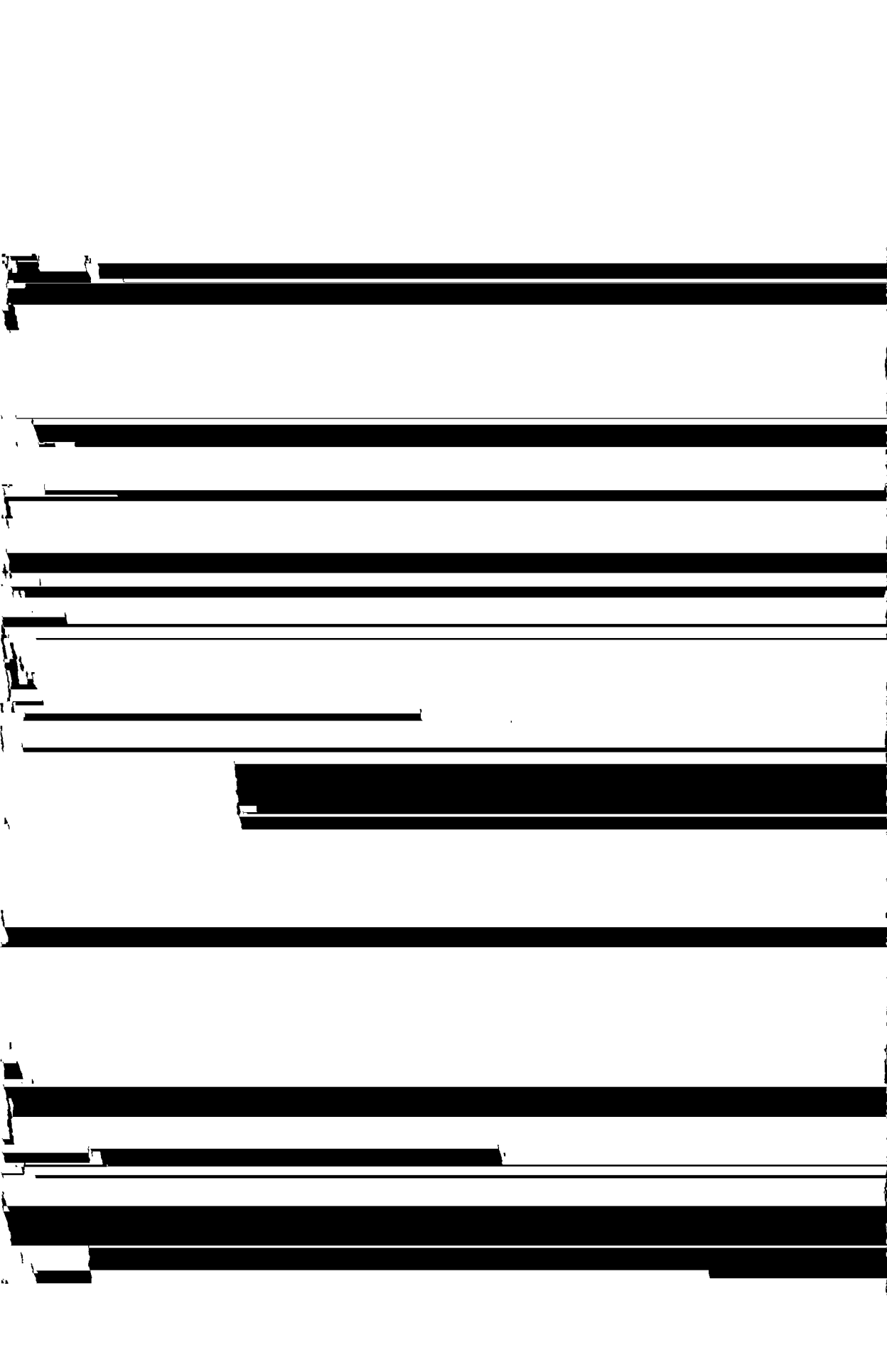
\_\_\_\_\_

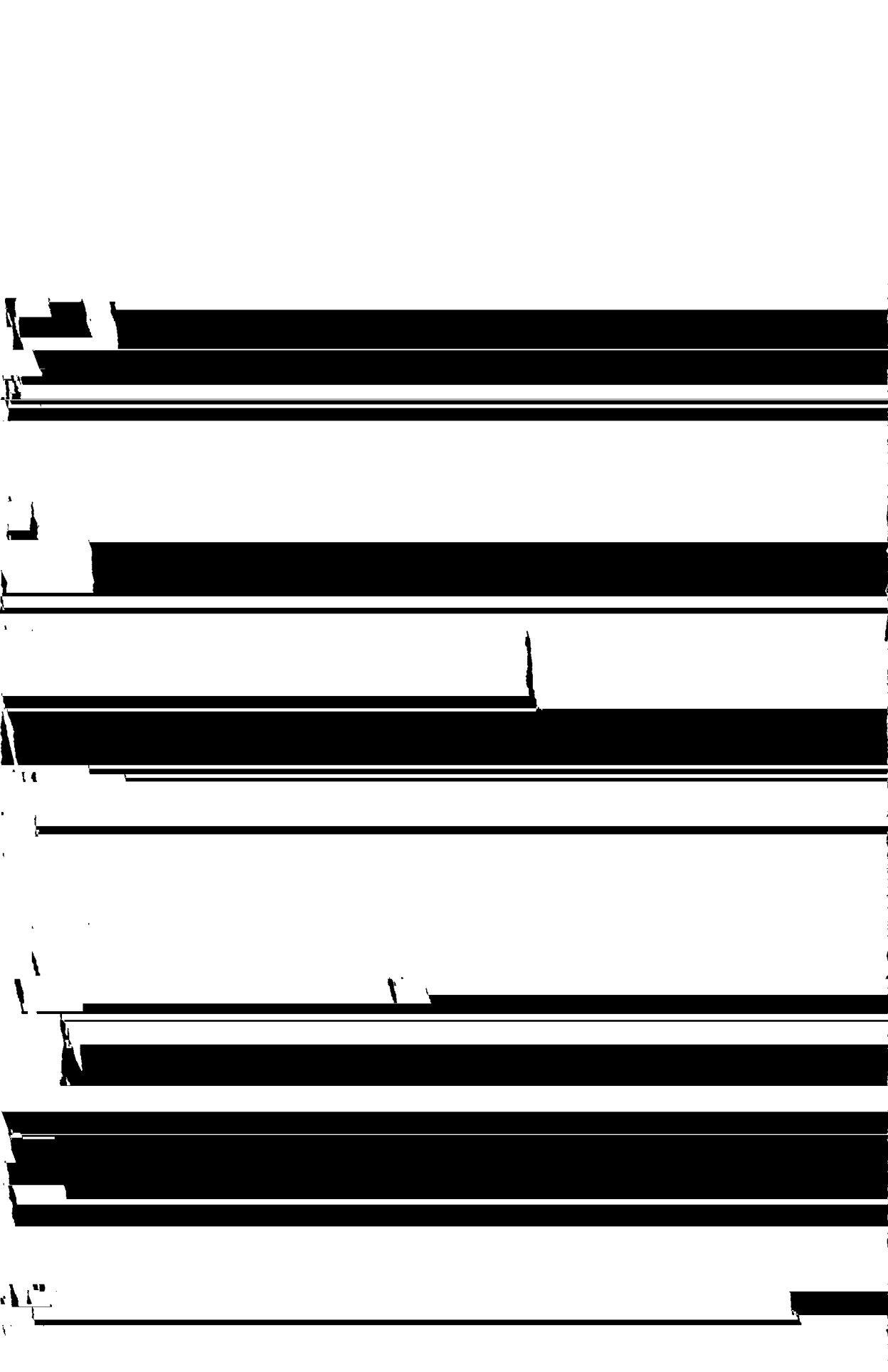


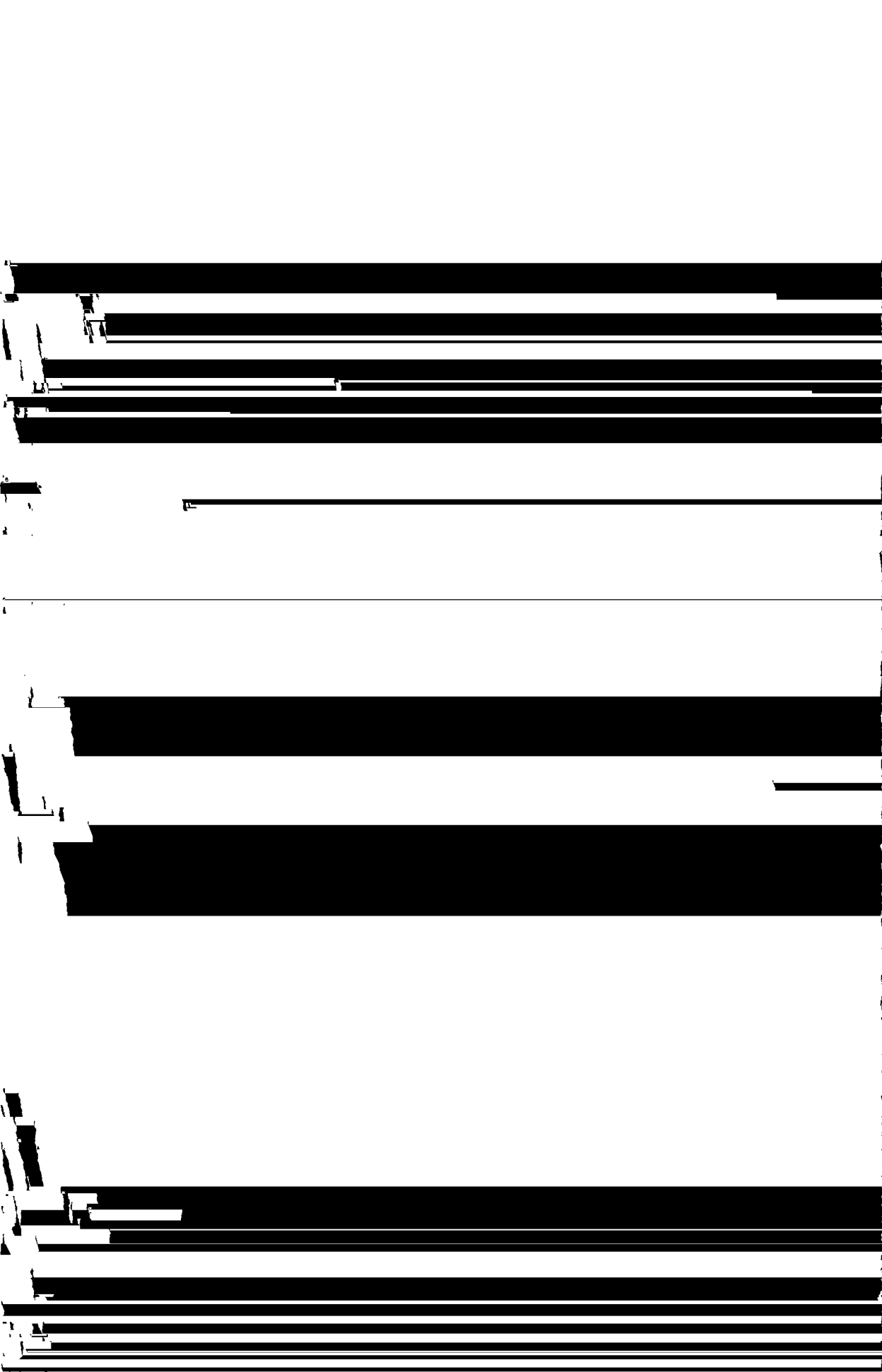


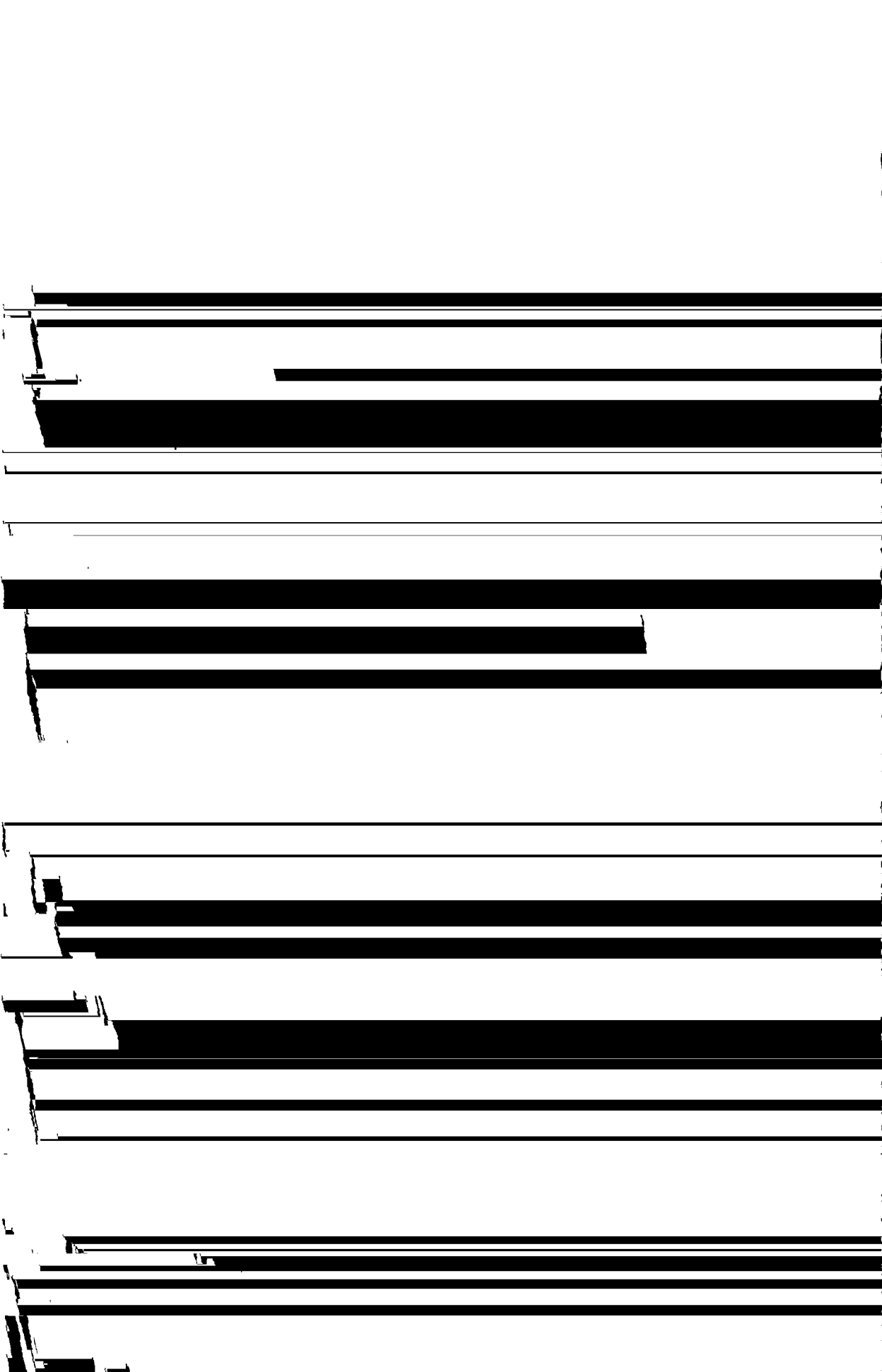


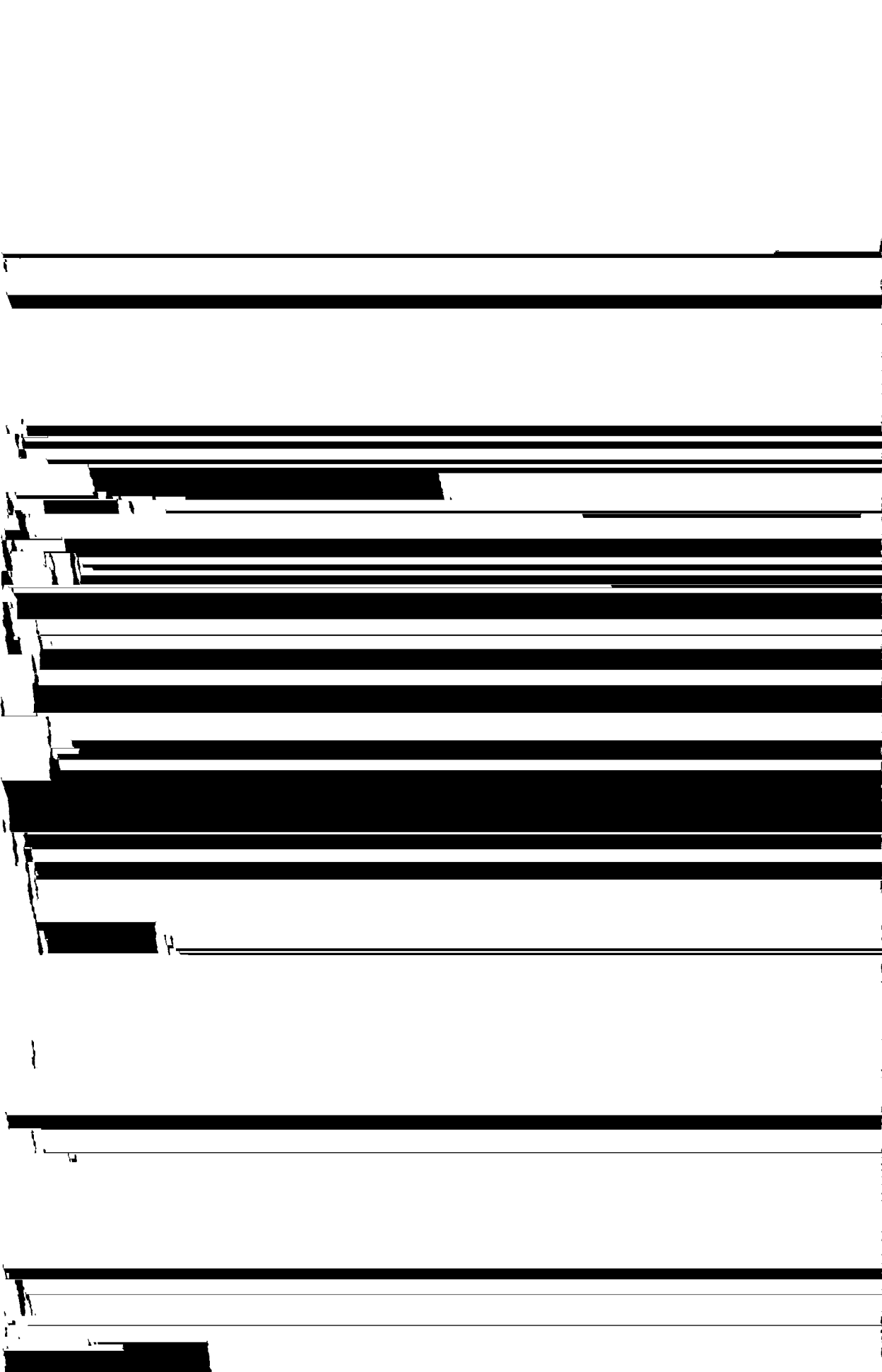


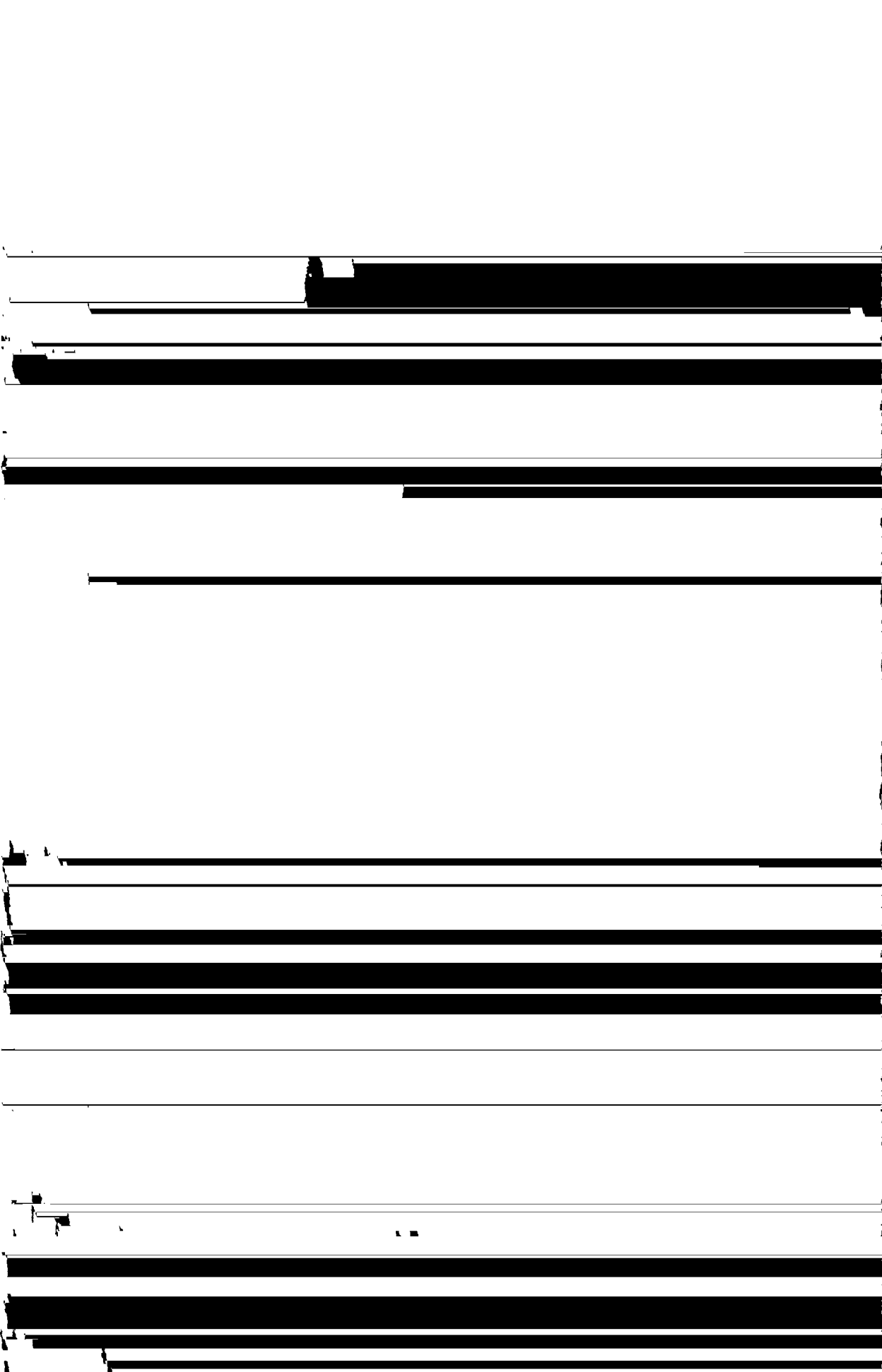




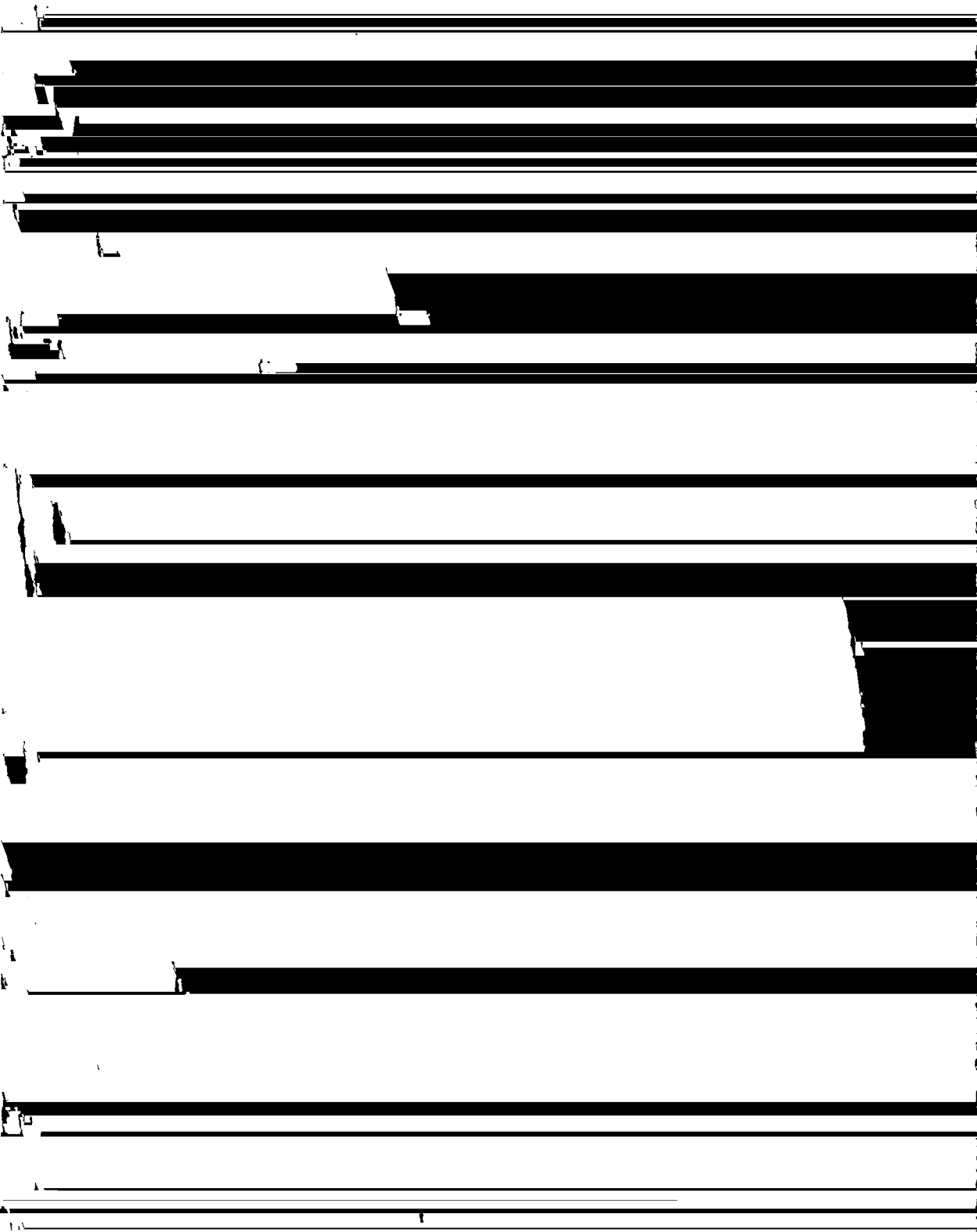


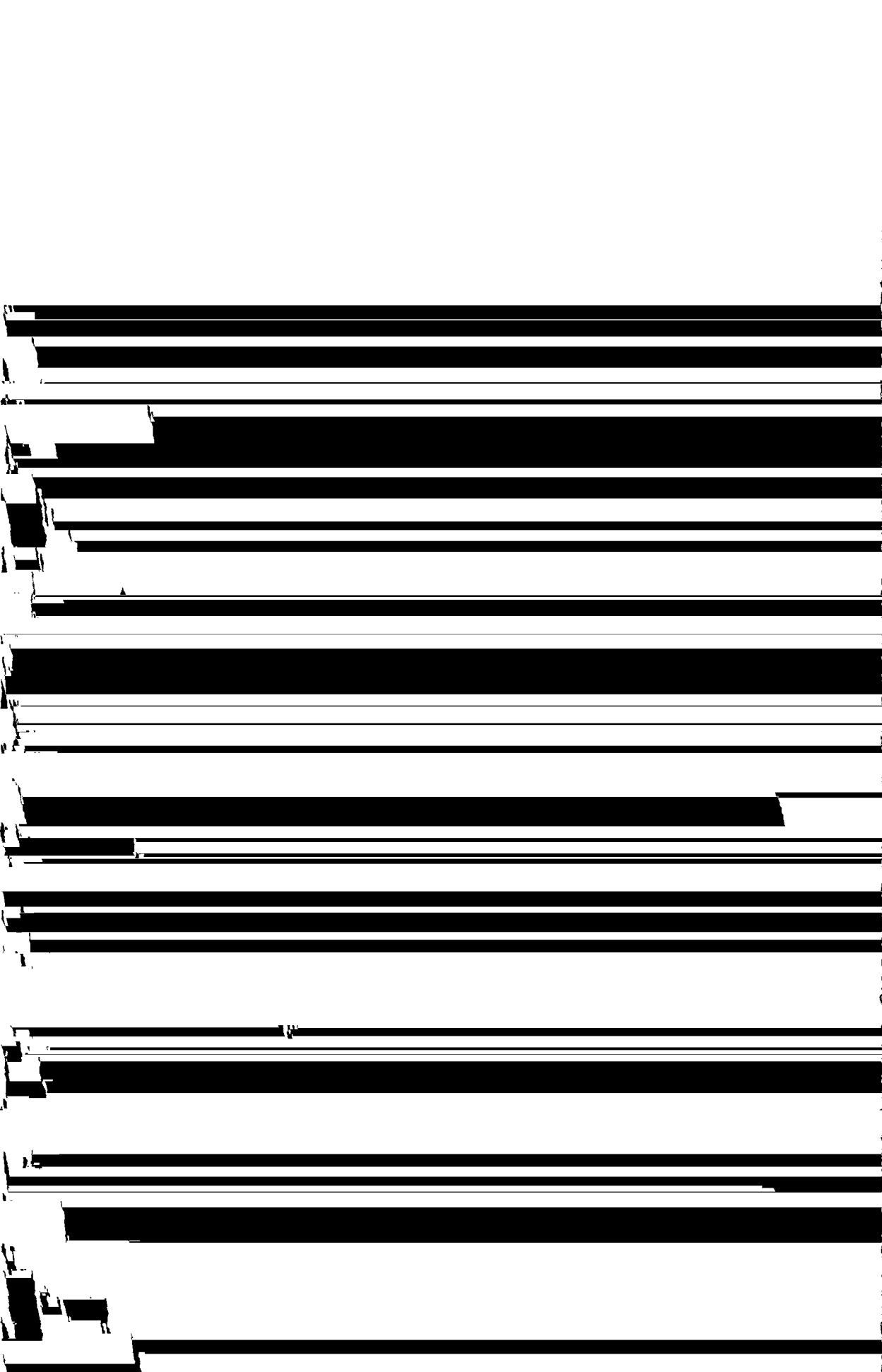


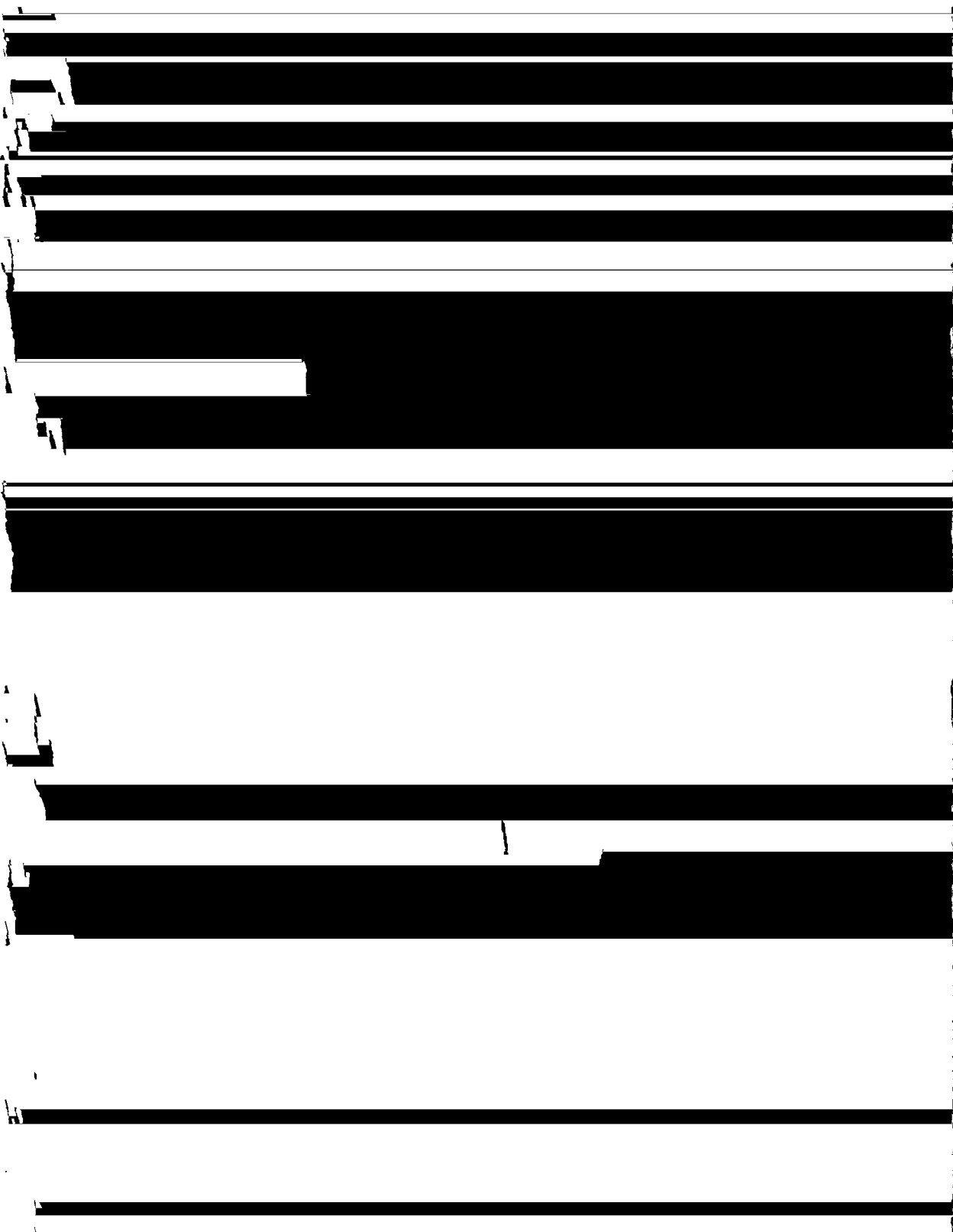






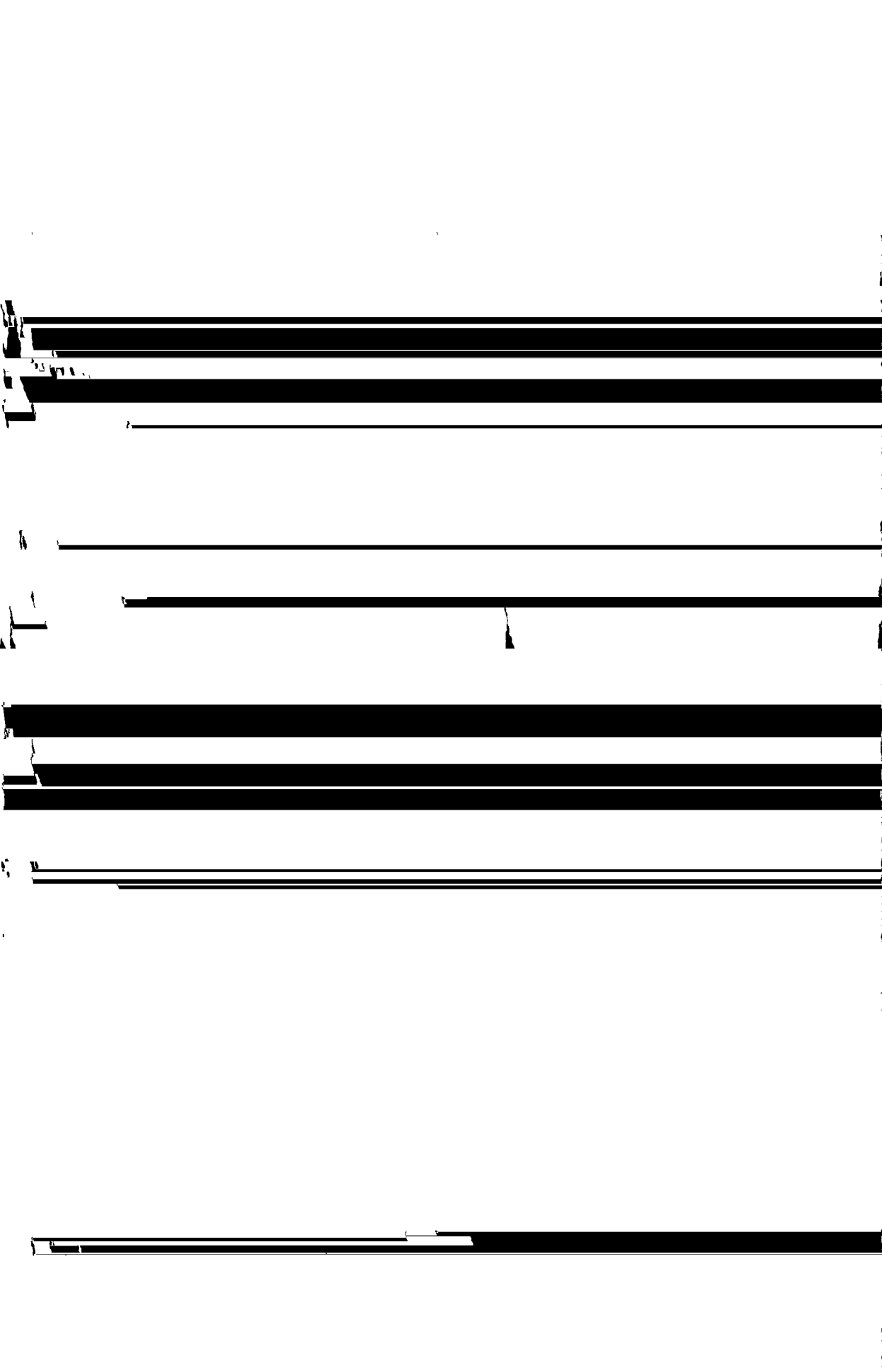


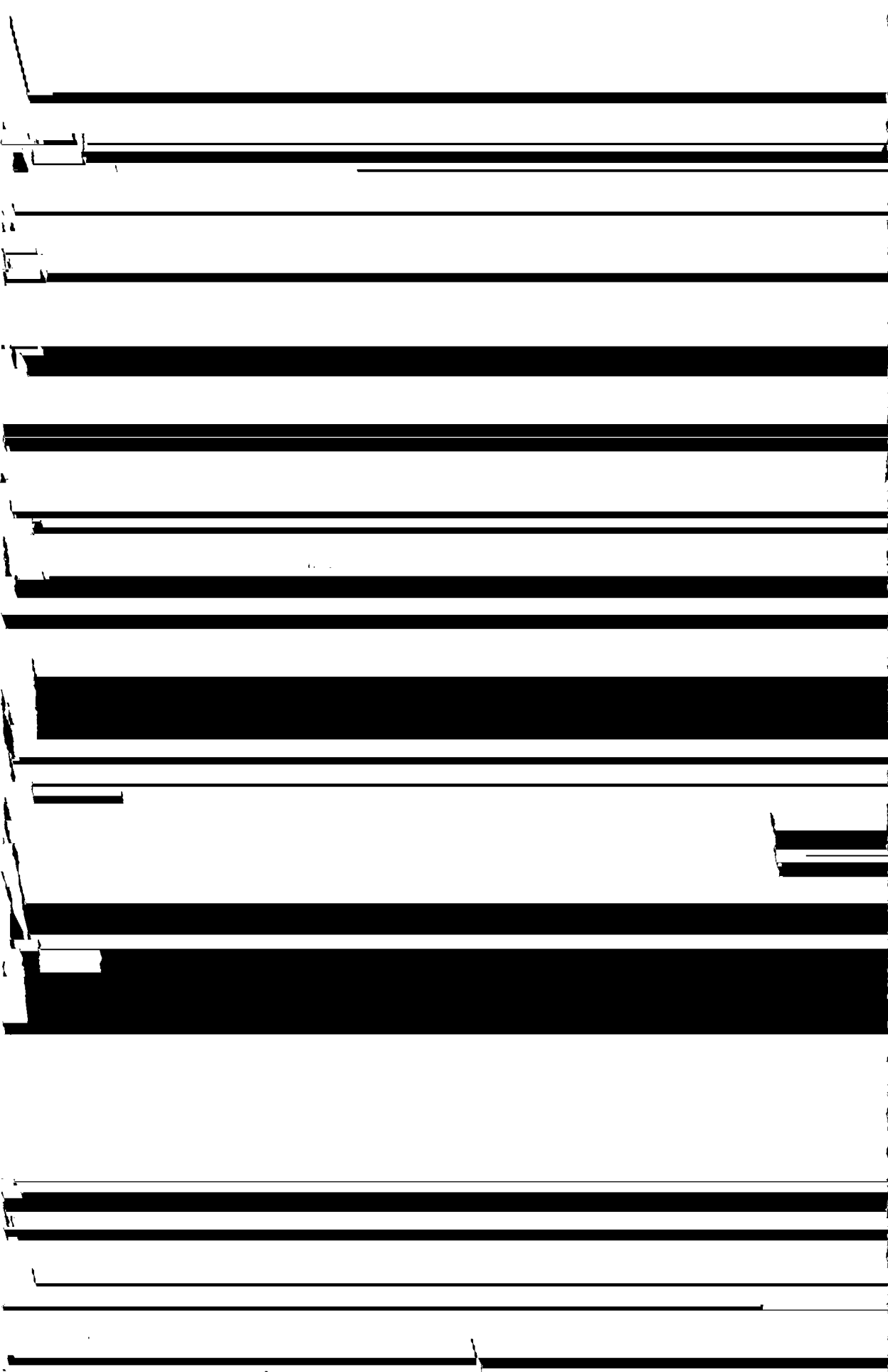






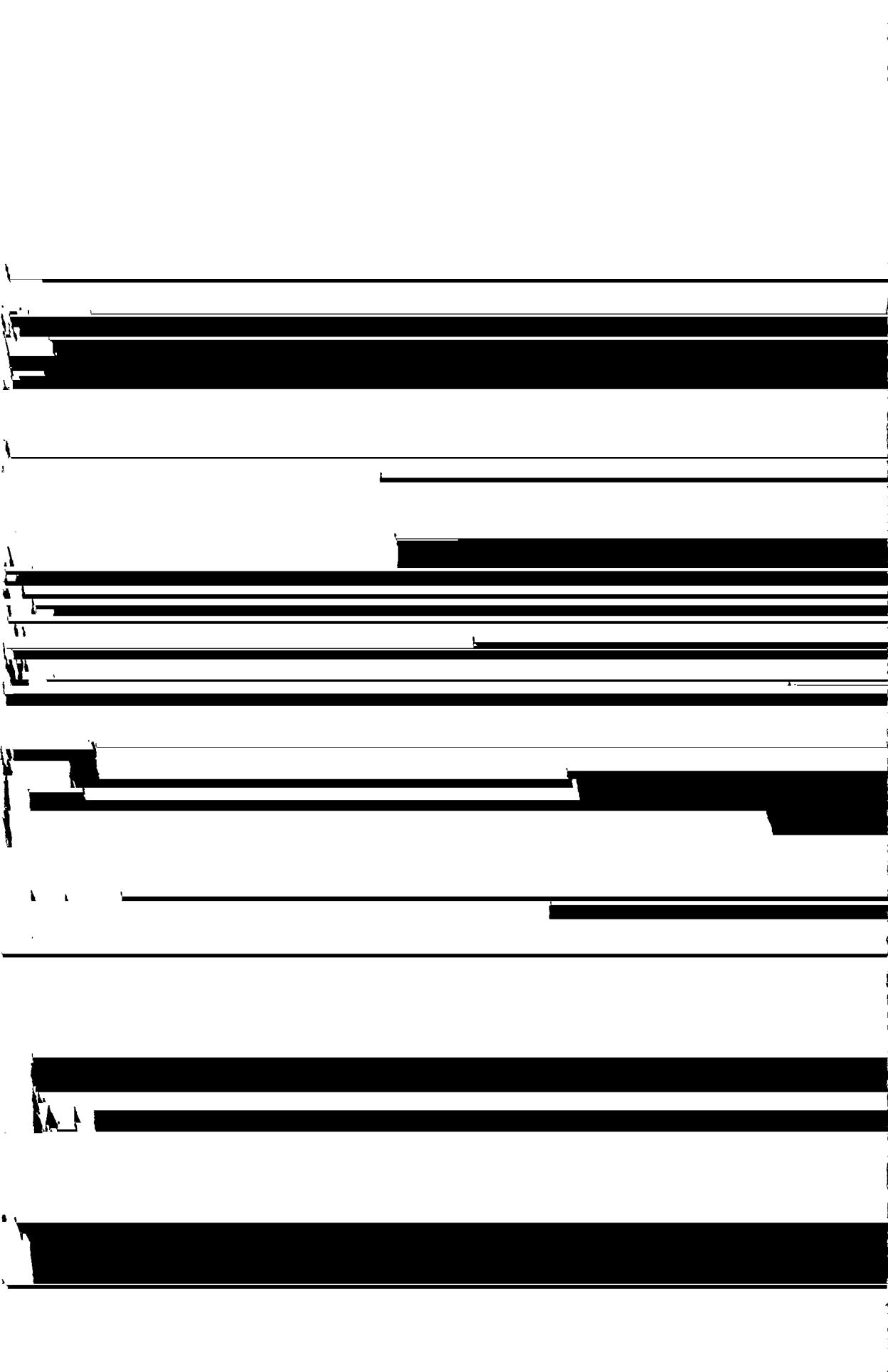












[REDACTED]

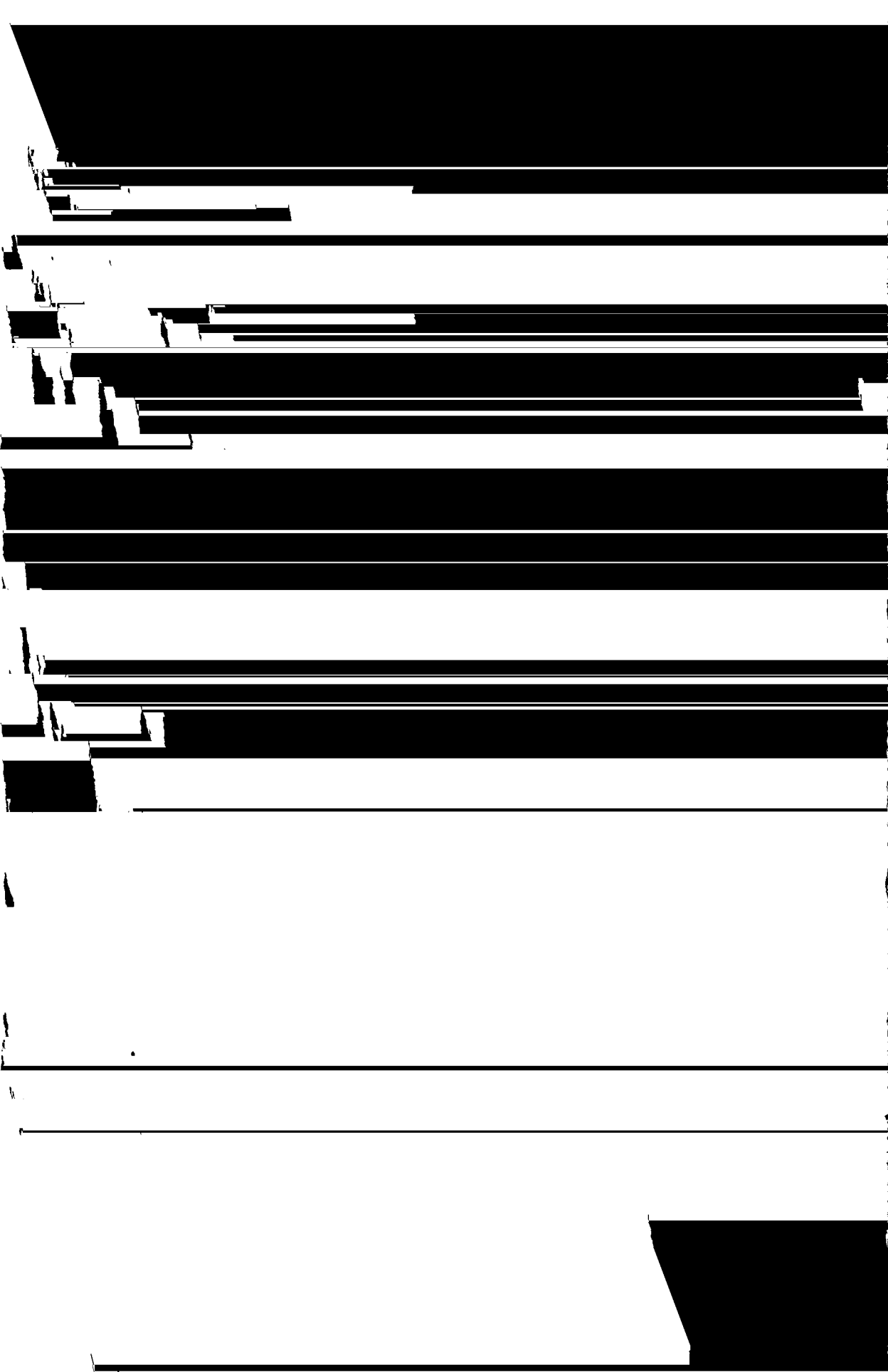
[REDACTED]

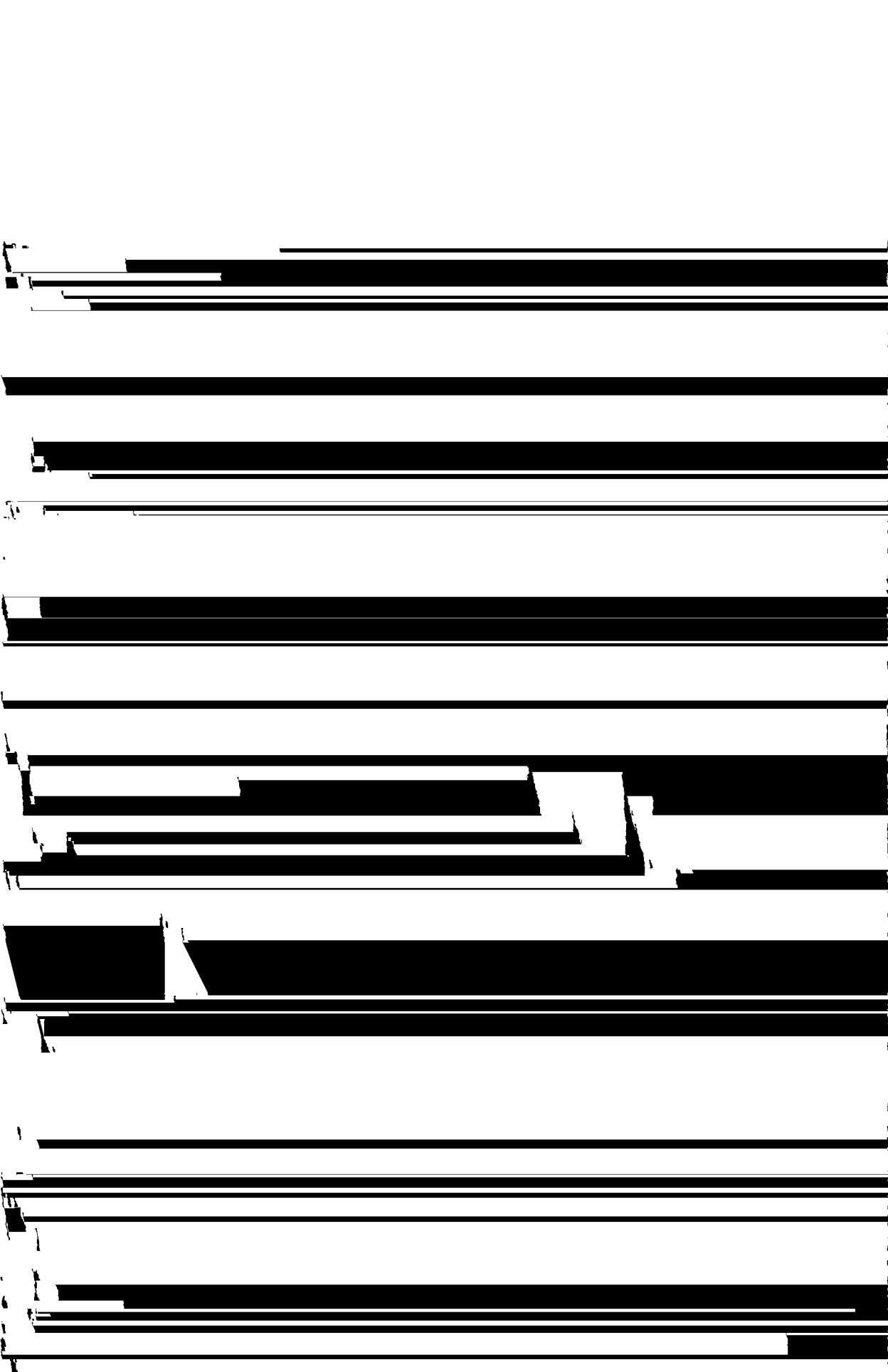
[REDACTED]

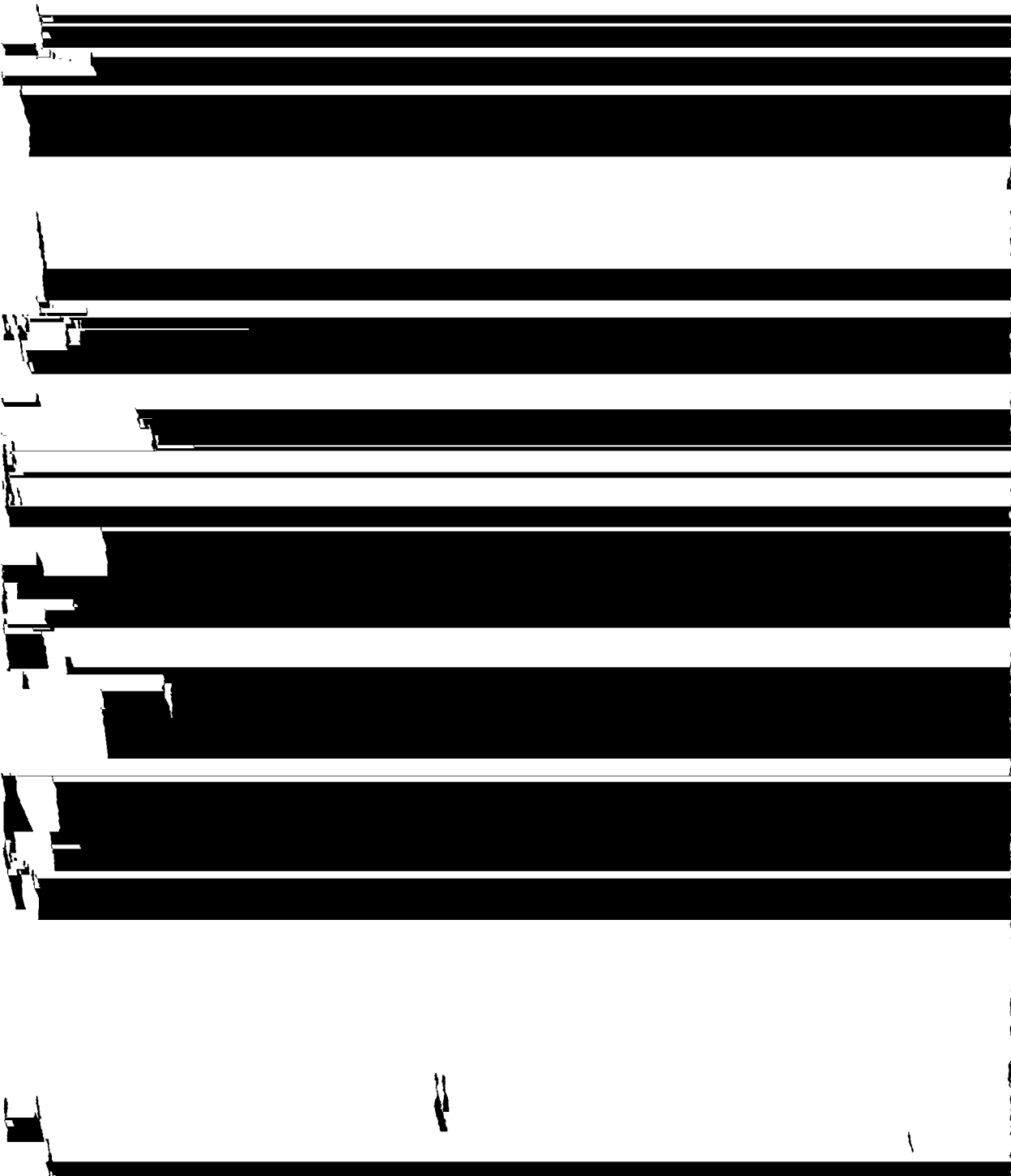
[REDACTED]

[REDACTED]

[REDACTED]







[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

[REDACTED]

