Untitled5

February 17, 2019

1 Part 1 - Backprop

Best hyperparams found for highest validation acc at the end of 10 epochs:

With RELU nonlinearity:

Learning rate: 0.1

hidden layer sizes 512, 1024

batch_size: 200

These parameters are also going to be the 'fixed setting' that we use in the questions regarding initialisation and there onwards.

Gradient Computation: We can derive the gradient wrt. softmax with cross entropy loss as: (predictions-y)

where y is the one hot encoding of ground truth labels and predictions is the vector containing the softmax outputs. Gradients for weights and biases of layers are computed as per chain rule.

At the end of 10 epochs a validation accuracy of 97.2% is reached with the above hyperparams and settings.

The number of parameters in the above-mentioned setting is $785512 + 5131024 + 1025*10 \sim 937482$ params

```
self.num_classes = 10
    self.epochs = epochs
    self.lr = lr
    self.batch_size = batch_size
    self.dataprep()
    if(mode=='train'):
        self.initialize_weights()
        loss, val_loss = self.train()
        self.plot(loss, val_loss)
def dataprep(self):
    data = np.load('mnist.pkl.npy', encoding='latin1')
    train_set = data[0][0]
    self.val_set = data[1][0]
    self.test_set = data[2][0]
    self.val_labels = data[1][1]
    self.test_labels = data[2][1]
    self.train_size = train_set.shape[0]
    self.val_size = self.val_set.shape[0]
    self.test_size = self.test_set.shape[0]
    p = np.random.permutation(self.train_size)
    self.train_set = train_set[p]
    self.train_labels = data[0][1][p]
    print(self.train_set.shape)
    print(self.val_set.shape)
    print(self.test_set.shape)
def plot(self, loss, val_loss):
    plt.plot(loss)
    plt.plot(val_loss)
    plt.title('model loss')
    plt.ylabel('loss')
    plt.xlabel('epoch')
    plt.legend(['train', 'val'], loc='upper left')
    plt.show()
def train(self):
```

```
m = self.train_size
val_samples = self.val_size
loss_history = np.zeros(self.epochs)
val loss history = np.zeros(self.epochs)
n_batches = int(m/self.batch_size)
batch size = self.batch size
print('zero shot validation')
val_batches = 0
val_loss= 0.0
val_accuracy = 0
for i in range(0,val_samples-batch_size+1,batch_size):
   X_i_val = self.val_set[i:i+batch_size]
   y_i_val = self.val_labels[i:i+batch_size]
   outputs_val = self.forward(X_i_val)
   labels = np.argmax(outputs val[-1], axis=1)
   val_accuracy += (y_i_val == labels).sum()
   one_hot = np.zeros((self.batch_size, self.num_classes))
   one_hot[np.arange(self.batch_size), y_i_val] = 1
   loss_val_batch = self.loss(outputs_val[-1], one_hot)
   val_loss += loss_val_batch
   val_batches +=1
val_accuracy = val_accuracy/(1.0*val_batches*self.batch_size)
val_loss = val_loss/(1.0*val_batches*self.batch_size)
print('val accuracy : '+str(val_accuracy) + \
             val loss : ' + str(val_loss))
for it in range(self.epochs):
   print('epoch : '+str(it))
   loss = 0.0
   val loss= 0.0
   train_accuracy = 0
   indices = np.random.permutation(m)
   train_set = self.train_set[indices]
   train_labels = self.train_labels[indices]
   train_batches = 0
   for i in range(0,m-batch_size+1,batch_size):
       X_i = train_set[i:i+batch_size]
        y_i = train_labels[i:i+batch_size]
```

```
outputs = self.forward(X_i)
            loss_batch, accuracy_batch = self.backward(y_i)
            loss += loss_batch
            train_accuracy += accuracy_batch
            train batches +=1
       loss = loss/(1.0*train_batches*self.batch_size)
       train_accuracy = train_accuracy/(1.0*train_batches*self.batch_size)
       print('train accuracy : ' + str(train_accuracy) + \
                   train loss : '+ str(loss))
       val_batches = 0
       val_accuracy = 0
       for i in range(0,val_samples-batch_size+1,batch_size):
           X_i_val = self.val_set[i:i+batch_size]
           y_i_val = self.val_labels[i:i+batch_size]
            outputs_val = self.forward(X_i_val)
            labels = np.argmax(outputs val[-1], axis=1)
            val_accuracy += (y_i_val == labels).sum()
            one_hot = np.zeros((self.batch_size, self.num_classes))
            one_hot[np.arange(self.batch_size), y_i_val] = 1
            loss_val_batch = self.loss(outputs_val[-1], one_hot)
            val_loss += loss_val_batch
            val_batches +=1
       val_loss = val_loss/(1.0*val_batches*self.batch_size)
       val_accuracy = val_accuracy/(1.0*val_batches*self.batch_size)
       print('val accuracy : '+str(val_accuracy) + \
                    val loss : ' + str(val_loss))
       val_loss_history[it] = val_loss
       loss_history[it] = loss
   return loss_history, val_loss_history
def initialize_weights(self):
   if(self.init_method=='zeros'):
       for i in range(len(self.layer_sizes)-1):
            layer_weights = np.zeros((self.layer_sizes[i]+1,\)
                                      self.layer_sizes[i+1]))
            layer_weights[-1,:] = 0
            print(layer_weights.shape)
            self.network.append(layer_weights)
   elif(self.init_method=='glorot'):
```

```
for i in range(len(self.layer_sizes)-1):
            d = math.sqrt(6.0/(self.layer_sizes[i]+self.layer_sizes[i+1]))
            layer_weights = np.random.uniform(-d,d,\
                                (self.layer_sizes[i]+1,self.layer_sizes[i+1]))
            layer_weights[-1,:] = 0
           print(layer_weights.shape)
            self.network.append(layer_weights)
   else:
       for i in range(len(self.layer_sizes)-1):
            layer_weights = np.random.randn(self.layer_sizes[i]+1,\
                                            self.layer_sizes[i+1])
            layer_weights[-1,:] = 0
            print(layer_weights.shape)
            self.network.append(layer_weights)
def activation(self,inputs, layer_no):
   inputs = np.hstack((inputs, np.ones((inputs.shape[0],1)) ))
   activation = np.dot(inputs, self.network[layer_no])
   return activation
def softmax(self,inputs):
   # Result of softmax are invariant even if we add/subtract a constant.
   ex = np.exp(inputs - np.max(inputs, axis=1, keepdims=True))
    # Subtract such that the maximum value is one.
   return ex/np.sum(ex, axis=1, keepdims=True)
def stable_softmax(self,inputs):
   # Result of softmax are invariant even if we add/subtract a constant.
   max_inputs = np.max(inputs, axis=1, keepdims=True)
   ex = np.exp(inputs - max_inputs)
    # Subtract such that the maximum value is one.
   logsumexp = np.log(np.sum(ex, axis=1, keepdims=True)) + max_inputs
   return np.exp(inputs - logsumexp),inputs - logsumexp
def forward(self,inputs):
    #we are always appending inputs before doing relu to the cache
   self.layer_outputs = []
   self.layer_outputs.append(inputs)
   for layer_no in range(len(self.network)-1):
        inputs = self.activation(inputs, layer_no)
        self.layer_outputs.append(inputs)
```

```
np.maximum(inputs,0,inputs)
                                                  #relu
    inputs = self.activation(inputs, len(self.network)-1 )
    inputs, stable_inputs = self.stable_softmax(inputs)
    self.layer_outputs.append(inputs)
    return self.layer outputs
def relu(self, inputs):
    outputs = np.maximum(inputs,0)
    return outputs
def backward(self, labels, getGrads=False):
    self.grad_L_wrt_Ws = []
    softmax_output = self.layer_outputs[-1]
    one_hot = np.zeros((self.batch_size, self.num_classes))
    one_hot[np.arange(self.batch_size), labels] = 1
    # Loss, accuracy
    loss_batch = self.loss(softmax_output, one_hot)
    pred_labels = np.argmax(softmax_output, axis=1)
    accuracy_batch = (labels == pred_labels).sum()
    # Derivative of loss wrt softmax_input
    \# = softmax \ out[d] \ when \ target[d] = 0, = softmax \ out[d] - 1 \ when \ target[d] = 1
    grad_L_wrt_softmax_input = softmax_output - one_hot
    # softmax_in = layer3_output = W_h2_h3*layer3_input
    #= W_h2_h3*relu(layer2_output)
    # grad_L_wrt_W_h2_h3
    #= (grad_L_wrt_layer3_output)*(grad_layer3_output_wrt_W_h2_h3)
    # 2nd term grad_layer3_output_wrt_W_h2_h3 = layer3_input = max(layer2_output,
    grad_L_wrt_layer_out = grad_L_wrt_softmax_input
    for layer_neg_idx in range(-1, -len(self.network)-1, -1):
```

```
prev_layer_output = self.layer_outputs[layer_neg_idx-1]
       layer_input = self.relu(np.hstack(( prev_layer_output,\)
                                           np.ones((self.batch_size, 1)) )) )
       grad_L_wrt_W = np.matmul(layer_input.T, grad_L_wrt_layer_out)
       self.grad_L_wrt_Ws.append(grad_L_wrt_W/self.batch_size)
        # For prev layer
        # grad_L_wrt_layer2_output
            = (grad_L_wrt_layer3_output)*(grad_layer3_output_wrt_layer2_output)
           = (grad_L_wrt_layer3_output)*(grad_(W*relu(layer2_output))_wrt_layer2_
           = (grad_L_wrt_layer3_output)*W*(grad_(relu(layer2_output))_wrt_layer2_
            = (grad L wrt layer3 output)*W*(layer2 output > 0)
       grad_L_wrt_prev_layer_out = np.matmul(grad_L_wrt_layer_out,\
            self.network[layer_neg_idx][:-1, :].T) * (prev_layer_output > 0).astyp
       grad_L_wrt_layer_out = grad_L_wrt_prev_layer_out
   if(not getGrads):
       self.update(self.grad_L_wrt_Ws)
       return loss_batch, accuracy_batch
   else:
       return loss_batch, accuracy_batch, self.grad_L_wrt_Ws
def reluDerivative(x):
   x[x \le 0] = 0
   x[x>0] = 1
   return x
def loss(self,predictions,targets): #cross entropy
   epsilon = 1e-12
   predictions = np.clip(predictions, epsilon, 1. - epsilon)
   ce = -np.sum(np.multiply(targets,np.log(predictions+1e-9)), axis=1)
   ce = np.sum(ce)
```

print("backward", layer_neg_idx)

```
def update(self,grads):
    length_net = len(self.network)
    assert(len(grads) == length_net)
    i=0
    for layer_no in range(length_net):
        self.network[layer_no] -= self.lr * grads[length_net-1-i]
def test(self):
   m = self.test_size
    batch_size = self.batch_size
    for it in range(self.epochs):
        loss = 0.0
        test_batches = 0
        test_accuracy = 0
        for i in range(0,m-batch_size,batch_size):
            X_i = self.test_set[i:i+batch_size]
            y_i = self.test_labels[i:i+batch_size]
            outputs = self.forward(X_i)
            one_hot = np.zeros((self.batch_size, self.num_classes))
            one_hot[np.arange(self.batch_size), y_i] = 1
            loss += self.loss(outputs[-1], one_hot)
            test_batches +=1
            labels = np.argmax(outputs[-1], axis=1)
            test_accuracy += (y_i == labels).sum()
    test_loss = loss/(1.0*test_batches*self.batch_size)
    test_accuracy = test_accuracy/(1.0*test_batches*self.batch_size)
    print('test loss : ' + str(test_loss) + \
                    test accuracy : '+ str(test_accuracy))
def grad_check(self):
    self.batch_size=1
    X_i_val = self.val_set[1:1+self.batch_size]
    y_i_val = self.val_labels[1:1+self.batch_size]
    outputs_val = self.forward(X_i_val)
    loss_batch, accuracy_batch, gradients = self.backward(y_i_val, getGrads= True)
    diffs=[]
    for n in range (1,6):
        for m in [1,5]:
            numerical, computed = self.finite_diff(gradients, n, X_i_val, y_i_val,
            diffs.append(max(numerical-computed))
    plt.plot(diffs)
```

return ce

```
plt.show()
def finite_diff(self, gradients, n, inputs, labels, m):
   targets = np.zeros((self.batch_size, self.num_classes))
   targets[np.arange(self.batch_size), labels] = 1
   epsilon = 1/(m*1.0*(10**n))
   print('epsilon:'+str(epsilon))
   length_net = len(self.network)
   layer_no = 1
   layer_grad = []
   i=0
   for j in range(10):
        self.network[layer_no][i,j] = self.network[layer_no][i,j] + epsilon
       output_p =self.loss(self.forward(inputs)[-1], targets)
        self.network[layer_no][i,j] = self.network[layer_no][i,j] - 2*epsilon
       output_n = self.loss(self.forward(inputs)[-1], targets)
       self.network[layer_no][i,j] = self.network[layer_no][i,j] + epsilon
       grad = (output_p - output_n)/(2*epsilon)
       layer_grad.append(grad)
   compare_grad = gradients[length_net-2][0][:10]
   return np.array(layer_grad), compare_grad
```

2 Run neural net training and testing to see final loss curves after 10 epochs

```
In [36]: nn = NN()
(50000, 784)
(10000, 784)
(10000, 784)
(785, 700)
(701, 512)
(513, 10)
zero shot validation
val accuracy: 0.1224
                           val loss: 2.3177577554446294
epoch: 0
train accuracy: 0.8981
                           train loss: 0.36324488319177406
val accuracy : 0.937
                       val loss: 0.20939831820010887
epoch: 1
train accuracy: 0.95078
                            train loss: 0.1655519366089717
```

val accuracy : 0.9632 val loss : 0.13019896749798598

epoch: 2

train accuracy : 0.96608 train loss : 0.11469119600135884 val accuracy : 0.9713 val loss : 0.10111679563388112

epoch: 3

train accuracy : 0.97472 train loss : 0.08732825579168026 val accuracy : 0.9715 val loss : 0.09925817380184349

epoch: 4

train accuracy : 0.98058 train loss : 0.06812781888104029 val accuracy : 0.9759 val loss : 0.08379519445283257

epoch: 5

train accuracy : 0.98454 train loss : 0.05446491581376415 val accuracy : 0.9769 val loss : 0.08114256388627394

epoch: 6

train accuracy : 0.98746 train loss : 0.04421509691597075 val accuracy : 0.9773 val loss : 0.07876527500216929

epoch: 7

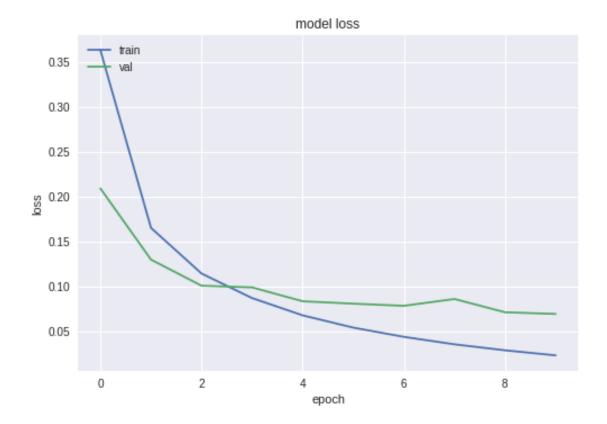
train accuracy : 0.99048 train loss : 0.03589308828233672 val accuracy : 0.974 val loss : 0.08634378018873633

epoch: 8

train accuracy : 0.99258 train loss : 0.02923917024514684 val accuracy : 0.9782 val loss : 0.07158835564931809

epoch: 9

train accuracy : 0.99464 train loss : 0.023607063784397437 val accuracy : 0.9797 val loss : 0.06972158314697587



In [21]: nn.test()

test loss: 0.2125267076205614 test accuracy: 0.9391939193919392

Out [21]: 2125.0545494979933

3 Trying different weight initialisations

train accuracy : 0.85578 train loss : 0.542020822468647 val accuracy : 0.9221 val loss : 0.26892395860852314

epoch: 1

train accuracy : 0.92466 train loss : 0.25971223105351704 val accuracy : 0.9389 val loss : 0.20602739685663674

epoch: 2

train accuracy : 0.94146 train loss : 0.20090755575504918 val accuracy : 0.9544 val loss : 0.17003026526937148

epoch: 3

train accuracy : 0.95158 train loss : 0.16600109674121463 val accuracy : 0.961 val loss : 0.14593449397780878

epoch: 4

train accuracy : 0.9596 train loss : 0.14008405793603723 val accuracy : 0.9649 val loss : 0.13401200857194148

epoch: 5

train accuracy : 0.96526 train loss : 0.12041383640381353 val accuracy : 0.9648 val loss : 0.12810445818959257

epoch: 6

train accuracy : 0.96884 train loss : 0.10584475650621325 val accuracy : 0.9705 val loss : 0.10911683195119119

epoch: 7

train accuracy : 0.97298 train loss : 0.09327815136212163 val accuracy : 0.9693 val loss : 0.10634678225255739

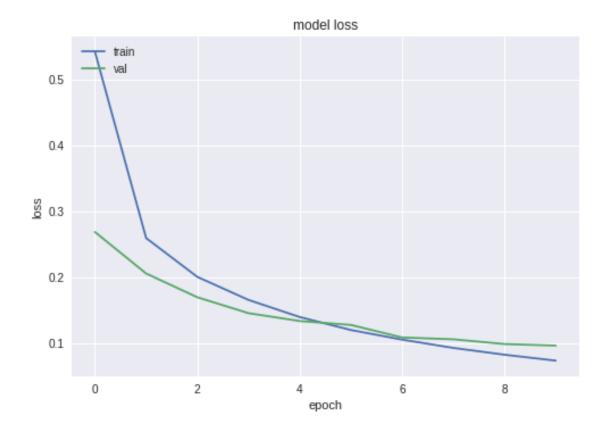
epoch: 8

train accuracy : 0.9765 train loss : 0.08299334071201722 val accuracy : 0.9733 val loss : 0.09913614277439181

epoch: 9

train accuracy : 0.9788 train loss : 0.07401202045509546

val accuracy : 0.9743 val loss : 0.096795421743254



```
In [51]: print('/////////zeros initialisation/////////////)
       nn_zero = NN(initmethod= 'zeros')
(50000, 784)
(10000, 784)
(10000, 784)
(785, 512)
(513, 1024)
(1025, 10)
zero shot validation
val accuracy: 0.0991
                        val loss: 2.302585082994046
epoch: 0
                         train loss: 2.3022687921666756
train accuracy : 0.11294
val accuracy : 0.1064
                       val loss: 2.3021843951713272
epoch: 1
train accuracy : 0.11356
                         train loss: 2.301777791376592
                       val loss: 2.301982066276648
val accuracy: 0.1064
epoch: 2
train accuracy : 0.11356
                         train loss: 2.3014790425272116
val accuracy : 0.1064
                       val loss: 2.301889863904215
epoch: 3
```

train accuracy : 0.11356 train loss : 2.301301302981305 val accuracy : 0.1064 val loss : 2.301854067208434

epoch: 4

train accuracy : 0.11356 train loss : 2.301192814163037 val accuracy : 0.1064 val loss : 2.3018503042713427

epoch: 5

epoch: 6

train accuracy : 0.11356 train loss : 2.301091209854322 val accuracy : 0.1064 val loss : 2.301880147978984

epoch: 7

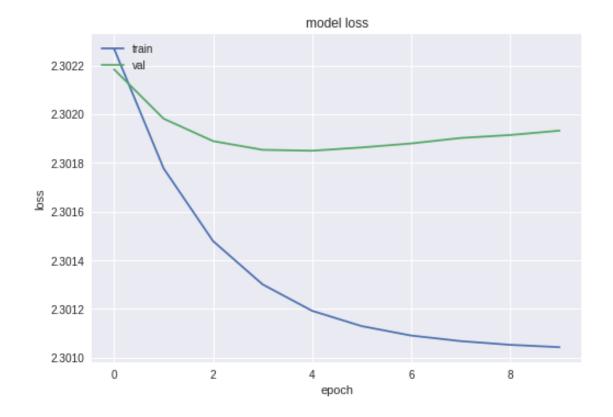
train accuracy : 0.11356 train loss : 2.3010683244790053 val accuracy : 0.1064 val loss : 2.3019026845408885

epoch: 8

train accuracy : 0.11356 train loss : 2.30105310022168 val accuracy : 0.1064 val loss : 2.3019147127129322

epoch: 9

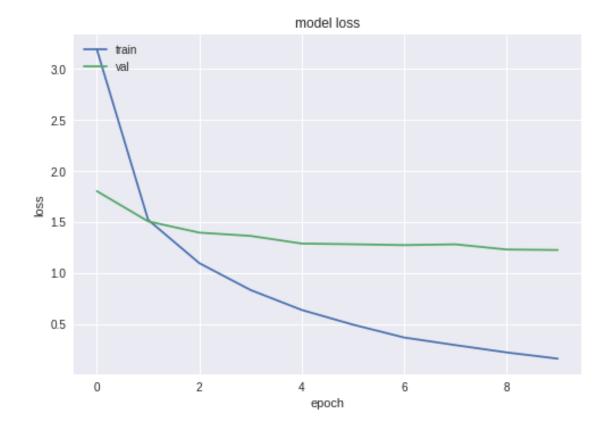
train accuracy : 0.11356 train loss : 2.3010434620082005 val accuracy : 0.1064 val loss : 2.301932918705967



In [50]: print('//////////gaussian initialisation/////////////)

nn_gaussian = NN(initmethod= '', lr=0.01)

(50000, 784) (10000, 784)(10000, 784)(785, 512)(513, 1024)(1025, 10)zero shot validation val accuracy: 0.1011 val loss: 18.627245209883068 epoch: 0 train accuracy : 0.8445 train loss: 3.1878481668288594 val accuracy : 0.9118 val loss: 1.8031152140938593 epoch: 1 train accuracy: 0.92512 train loss: 1.5222325269595003 val accuracy: 0.9259 val loss: 1.5073912996726935 epoch: 2 train accuracy : 0.94582 train loss: 1.0982559328256152 val accuracy : 0.9313 val loss: 1.397139344269522 epoch: 3 train accuracy : 0.9584 train loss: 0.835523906152143 val accuracy: 0.9326 val loss: 1.3650735630875819 epoch: 4 train accuracy: 0.96786 train loss: 0.6400965133504405 val accuracy : 0.9364 val loss: 1.2903830512495573 epoch: 5 train accuracy : 0.97472 train loss: 0.4964545655733264 val accuracy: 0.9374 val loss: 1.2834142365579424 epoch: 6 train loss: 0.37043973053987783 train accuracy: 0.98084 val accuracy: 0.9375 val loss: 1.274997894874585 epoch: 7 train loss: 0.29603632040179917 train accuracy: 0.98466 val accuracy: 0.9373 val loss: 1.2827460223924556 epoch: 8 train accuracy: 0.98798 train loss: 0.22451173613954029 val accuracy: 0.9389 val loss: 1.2320277774041173 epoch: 9 train accuracy: 0.99118 train loss: 0.1634423766663869 val accuracy: 0.9392 val loss: 1.2270870257843405



Conclusion: we see that with zeros as the weight init, as expected, no learning happens since backprop can't compute any useful gradients to propagate since the gradient for a weight that is zero will be zero. We see better performance, and more importantly faster convergence for the glorot initialisation. The gaussian weights give good performance too, but reach a lower final accuracy and take longer to converge to this accuracy. They also don't generalise as well as the case of the glorot init.

4 Best hyperparam search

-varied batch size, learning rate, hidden layer sizes and number of epochs

batch size: a,b,c -> 10, 80, 200

epochs: d,e -> 10, 50

Learning rate: g,h,i -> 0.1, 0.01, 0.001

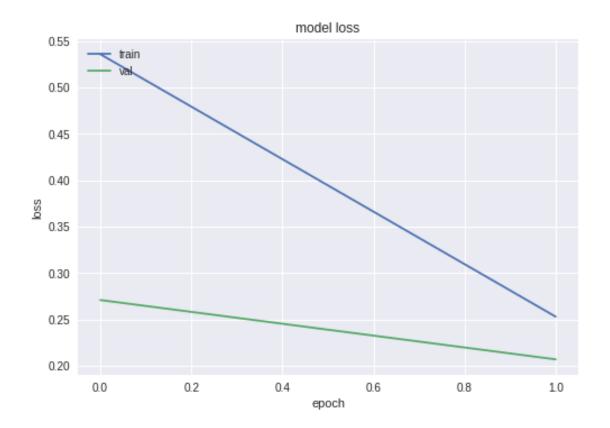
Hidden layer config: $j,k \rightarrow (512,1024), (700,512)$

The following indicates the setup along with the validation accuracy.

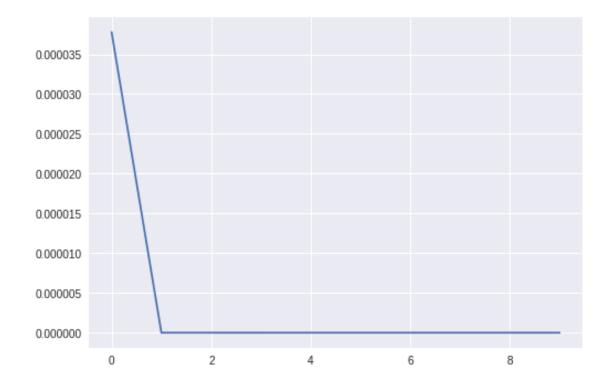
- adgk -> 98.12
- bdgk -> 97.97
- bdgj -> 98.19%
- cdgj -> 97.2%

- cdhj -> 92%
- cdik -> 84%
- cegj -> 98.12%
- 4.1 Run finite diff code and plot how the max difference betwen backprop-computed gradients and numerical gradients changes as we increase the value of N/decrease epsilon.

```
In [55]: nn = NN(epochs=2)
        nn.grad_check()
(50000, 784)
(10000, 784)
(10000, 784)
(785, 512)
(513, 1024)
(1025, 10)
zero shot validation
val accuracy : 0.1025
                           val loss: 2.341138418133865
epoch: 0
train accuracy : 0.8592
                           train loss: 0.535765870846202
val accuracy : 0.9224
                          val loss: 0.27096104212662897
epoch: 1
train accuracy : 0.92738
                            train loss: 0.2530637168297488
val accuracy: 0.9443
                           val loss: 0.20704507578480175
```



epsilon:0.1 epsilon:0.02 epsilon:0.01 epsilon:0.002 epsilon:0.0001 epsilon:0.0001 epsilon:2e-05 epsilon:1e-05 epsilon:2e-06



The plot above shows that the difference tends to 0 as we increase N/decrease epsilon,this is to be expected because the numerical gradient should approach the true gradient(from backprop) as epsilon becomes smaller.