

Chapter 9

More About Graphs

Discrete Structures for Computing on 27 May 2014

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Acknowledgement

Some slides about Euler and Hamilton circuits are created by Chung Ki-hong and Hur Joon-seok from KAIST.

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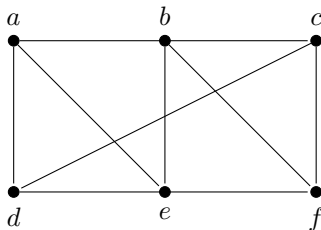
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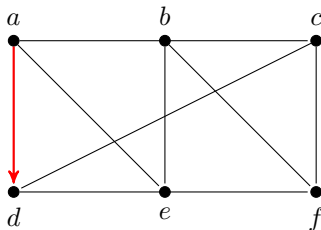
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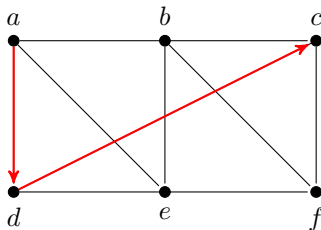
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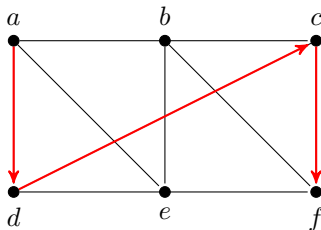
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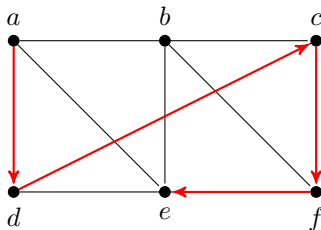
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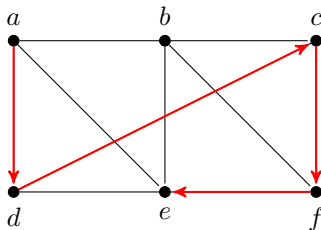
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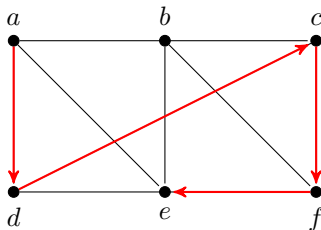
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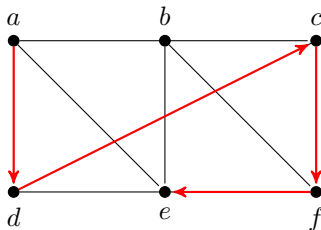
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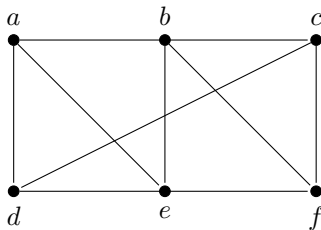
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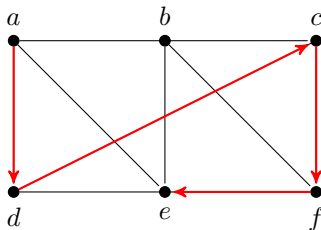
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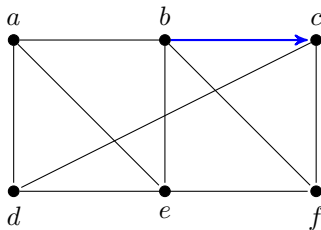
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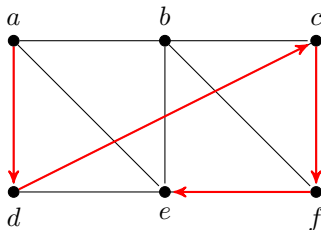
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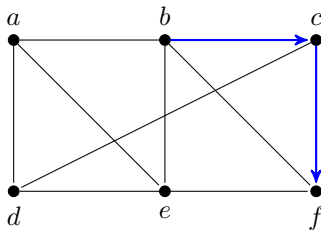
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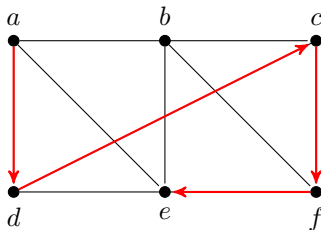
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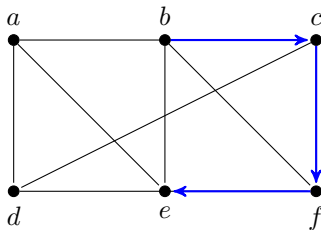
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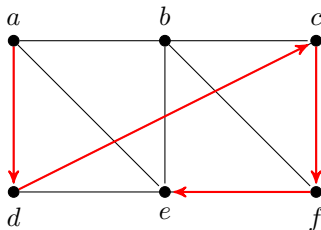
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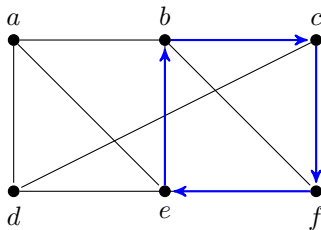
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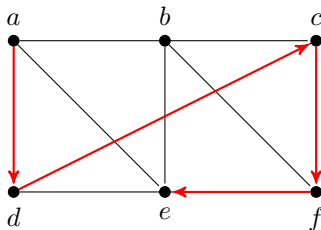
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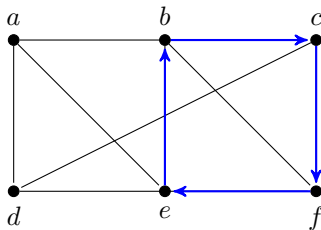
Simple path of length 4



Paths and Circuits



Simple path of length 4



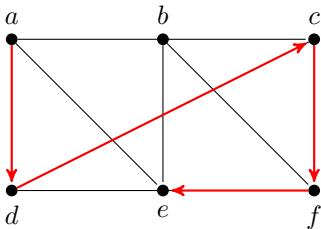
Circuit of length 4



Path and Circuits

Definition (in undirected graph)

- **Path** (*đường đi*) of length n from u to v : a sequence of n edges $\{x_0, x_1\}, \{x_1, x_2\}, \dots, \{x_{n-1}, x_n\}$, where $x_0 = u$ and $x_n = v$.
- A path is a **circuit** (*chu trình*) if it begins and ends at the same vertex, $u = v$.
- A path or circuit is **simple** (*đơn*) if it does not contain the same edge more than once.



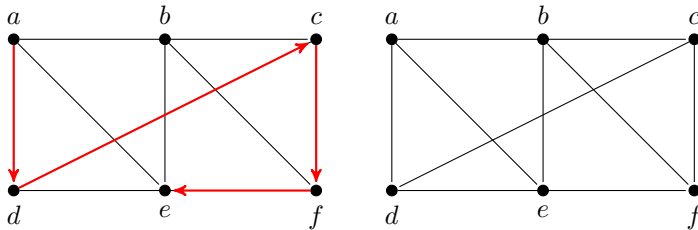
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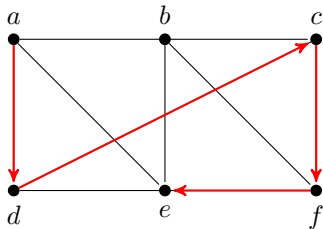
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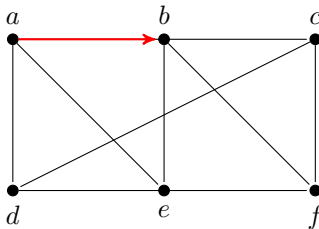
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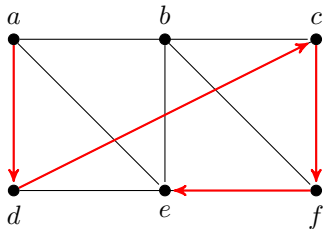
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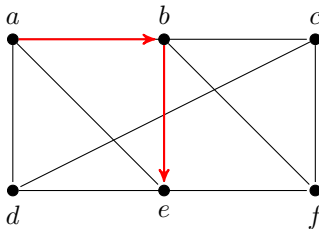
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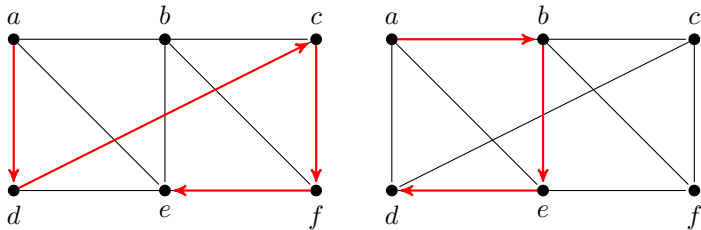
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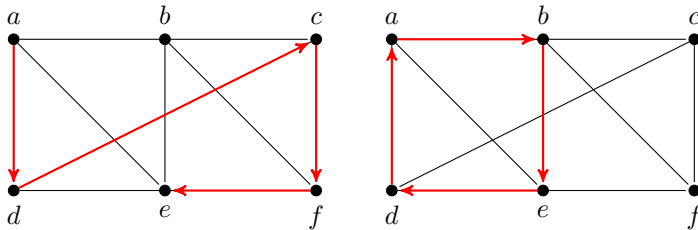
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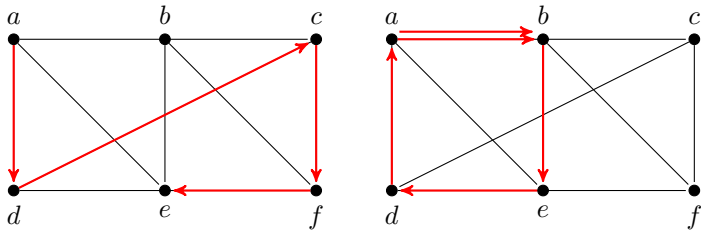
Simple path



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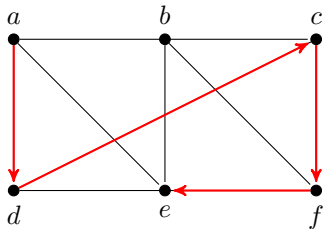
Simple path



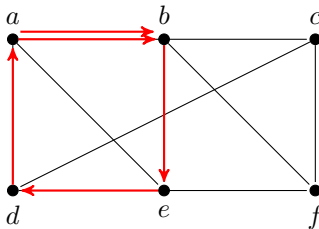
Path and Circuits

Definition (in undirected graph)

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Simple path



Not simple path





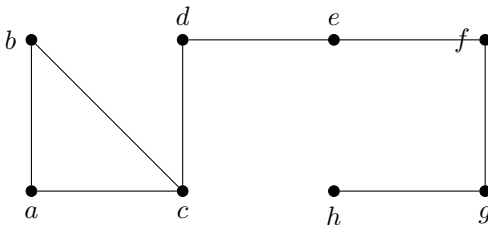
Definition (in directed graphs)

Path is a sequence of $(x_0, x_1), (x_1, x_2), \dots, (x_{n-1}, x_n)$, where $x_0 = u$ and $x_n = v$.

Connectedness in Undirected Graphs

Definition

- An undirected graph is called **connected** (*liên thông*) if there is a path between every pair of distinct vertices of the graph.
- There is a simple path between every pair of distinct vertices of a connected undirected graph.



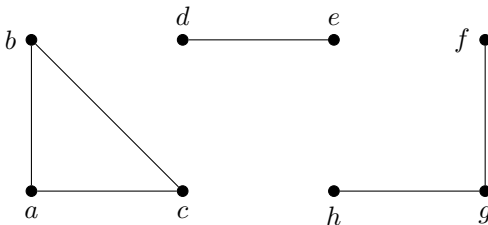
Connected graph



Connectedness in Undirected Graphs

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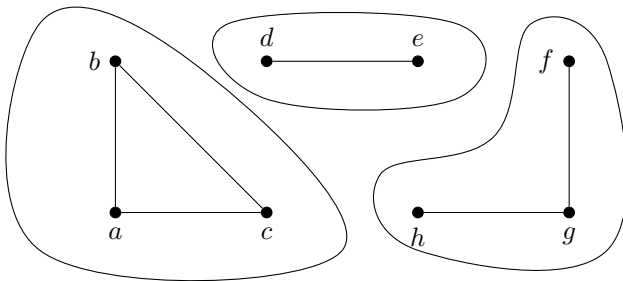
Disconnected graph



Connectedness in Undirected Graphs

Definition

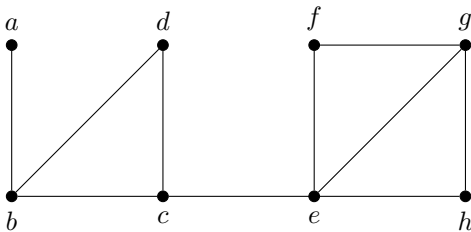
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Connected components (*thành phần liên thông*)



How Connected is a Graph?

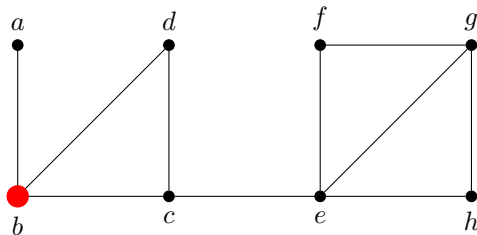


Definition

- b is a **cut vertex** (*đỉnh cắt*) or **articulation point** (*điểm khớp*).



How Connected is a Graph?

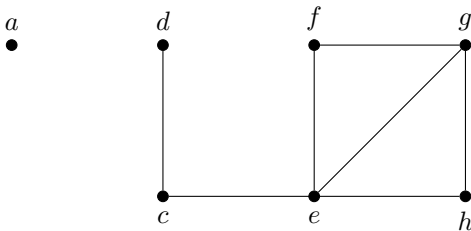


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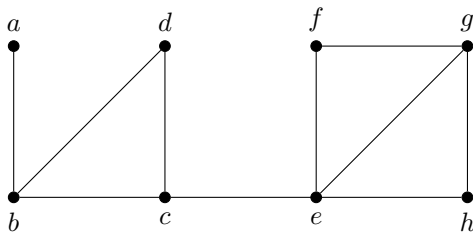


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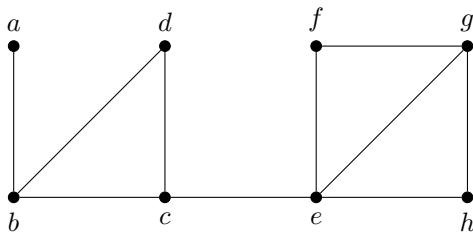


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What else?



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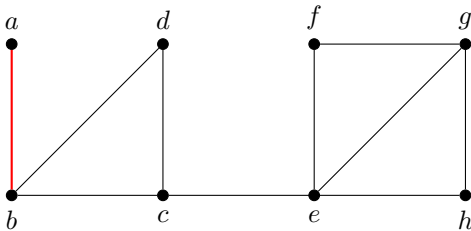


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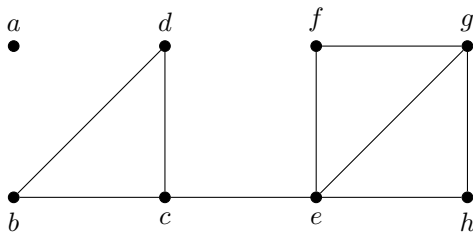


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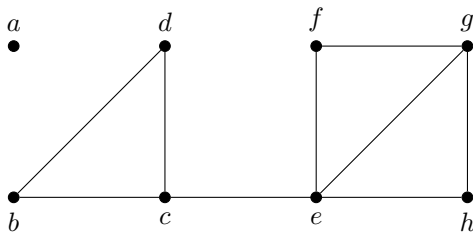


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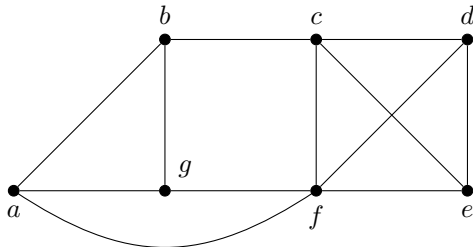


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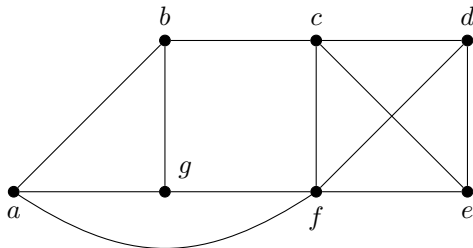
How Connected is a Graph?



Definition



How Connected is a Graph?

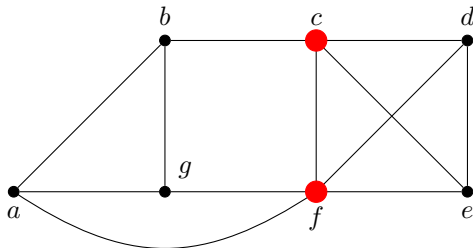


Definition

- This graph don't have cut vertices: **nonseparable graph** (*đồ thị không thể phân tách*)



How Connected is a Graph?

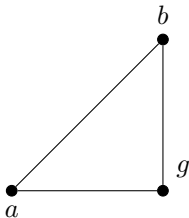


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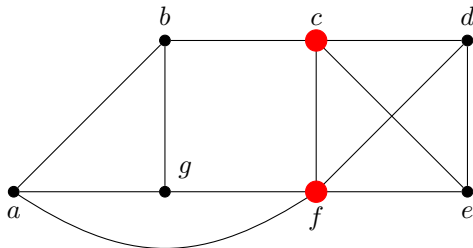


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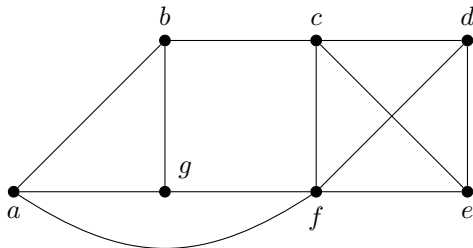


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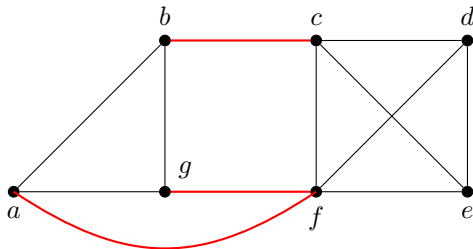


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How Connected is a Graph?

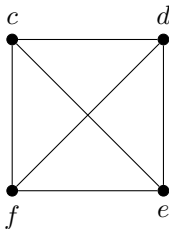
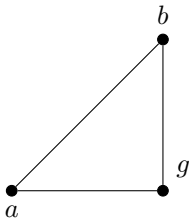


Definition

- This graph don't have cut vertices: **nonseparable graph** (*đồ thị không thể phân tách*)
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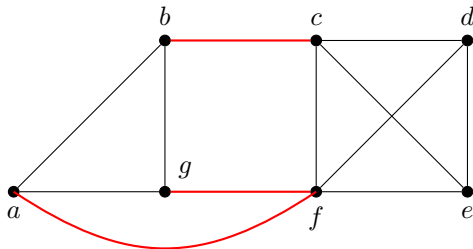


Definition

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How Connected is a Graph?



Definition

- This graph don't have cut vertices: **nonseparable graph** (*đồ thị không thể phân tách*)
- The **vertex cut** is $\{c, f\}$, so the minimum number of vertices in a vertex cut, **vertex connectivity** (*liên thông đỉnh*) $\kappa(G) = 2$.
- The **edge cut** is $\{\{b, c\}, \{a, f\}, \{f, g\}\}$, the minimum number of edges in an edge cut, **edge connectivity** (*liên thông cạnh*) $\lambda(G) = 3$.



Applications of Vertex and Edge Connectivity

- Reliability of networks
 - Minimum number of routers that disconnect the network
 - Minimum number of fiber optic links that can be down to disconnect the network
- Highway network
 - Minimum number of intersections that can be closed
 - Minimum number of roads that can be closed

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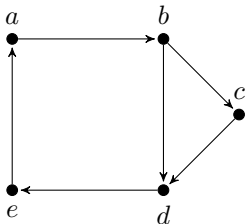
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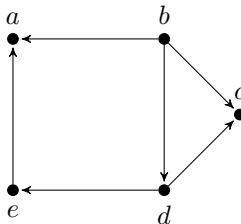
Connectedness in Directed Graphs

Definition

- An directed graph is **strongly connected** (*liên thông mạnh*) if there is a path between any two vertices in the graph (for both directions).
- An directed graph is **weakly connected** (*liên thông yếu*) if there is a path between any two vertices in the underlying undirected graph.



Strongly connected



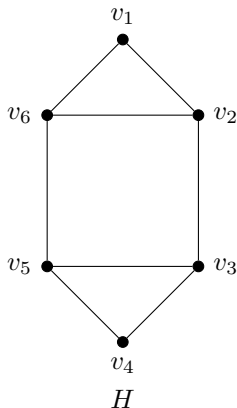
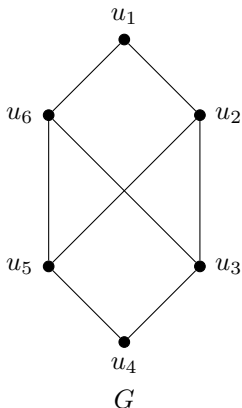
Weakly connected



Applications

Example

Determine whether the graphs below are isomorphic.



Solution

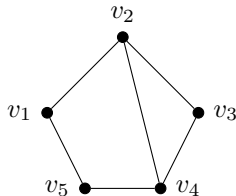
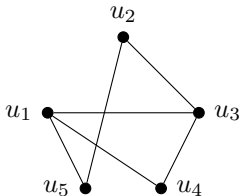
H has a simple circuit of length three, *not* G .





Example

Determine whether the graphs below are isomorphic.

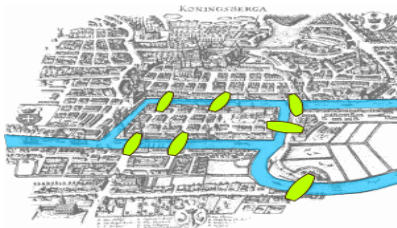


Solution

Both graphs have the same vertices, edges, degrees, circuits. They **may** be isomorphic.

To find a possible isomorphism, we can follow paths that go through all vertices so that the corresponding vertices in the two graphs have the same degrees.

The Famous Problem of Seven Bridges of Königsberg



- Is there a route that a person crosses all the seven bridges once?

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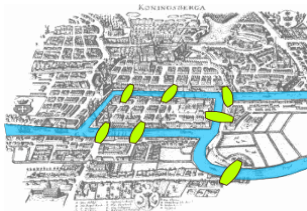
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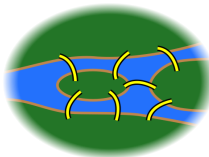
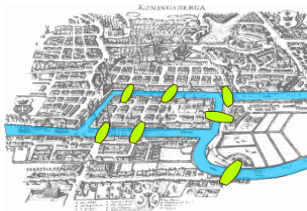
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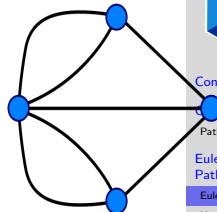
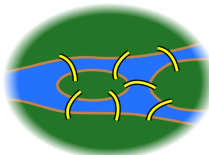
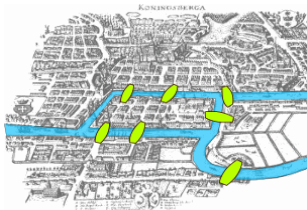
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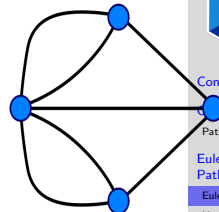
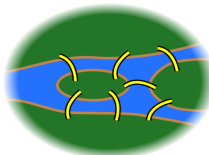
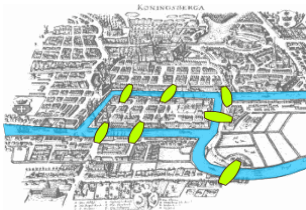
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- Euler gave the solution: It is **not** possible to cross all the bridges exactly once.



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What is Euler Path and Circuit?

- **Euler Path** (*đường đi Euler*) is a path in the graph that passes each edge only once.



What is Euler Path and Circuit?

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The problem of Seven Bridges of Königsberg can be also stated: Does Euler Path exist in the graph?



What is Euler Path and Circuit?

- **Euler Path** (*đường đi Euler*) is a path in the graph that passes each edge only once.
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- **Euler Circuit** (*chu trình Euler*) is a path in the graph that passes each edge only once and return back to its original position.



What is Euler Path and Circuit?

- **Euler Path** (*đường đi Euler*) is a path in the graph that passes each edge only once.
The problem of Seven Bridges of Königsberg can be also stated: Does Euler Path exist in the graph?
- **Euler Circuit** (*chu trình Euler*) is a path in the graph that passes each edge only once and return back to its original position.
From Definition, Euler Circuit is a subset of Euler Path.



Examples of Euler Path and Circuit

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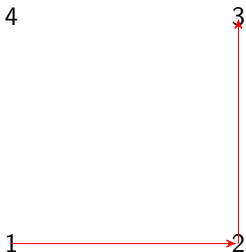
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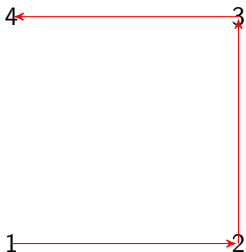
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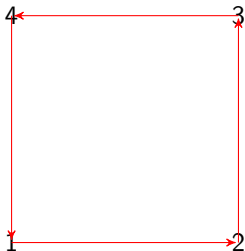
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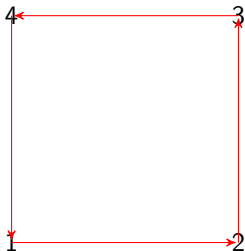
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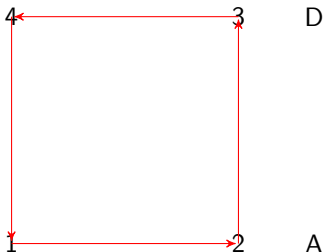
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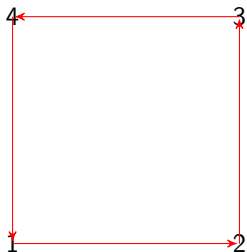
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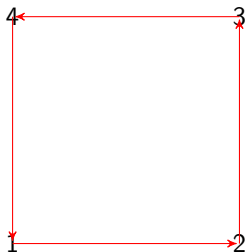
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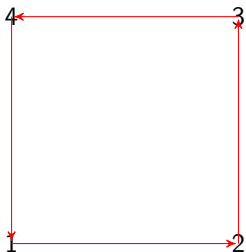
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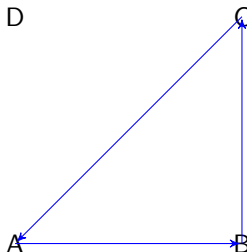
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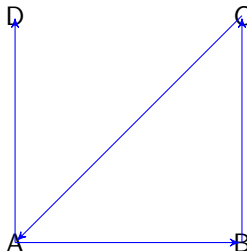
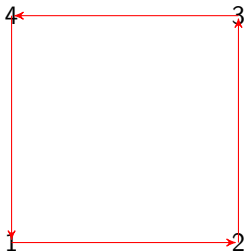
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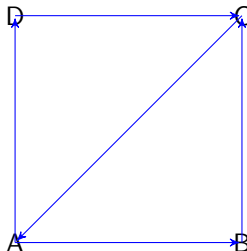
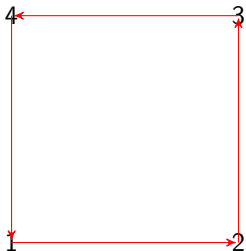
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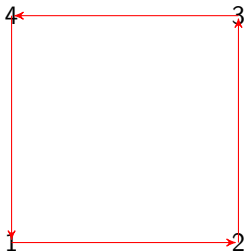
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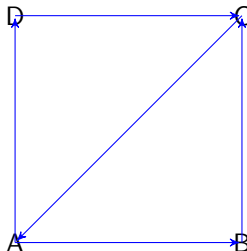
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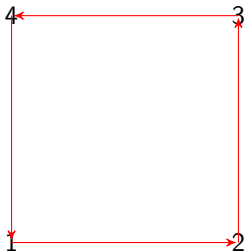
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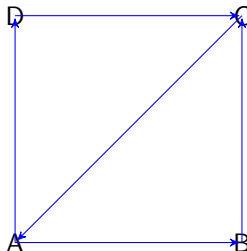
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Conditions for Existence

In a **connected multigraph**,

- Euler Circuit existence: **no odd-degree nodes exist** in the graph.

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In a **connected multigraph**,

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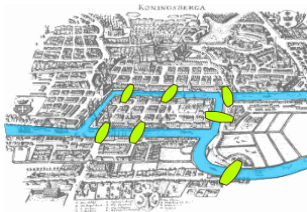
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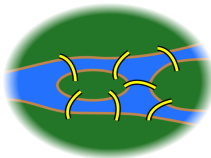
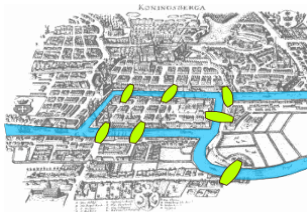
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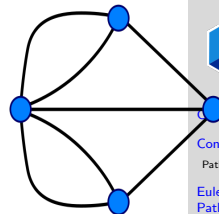
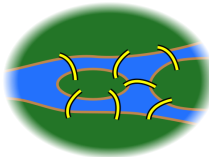
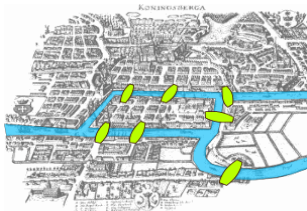
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- Four vertices of odd degree

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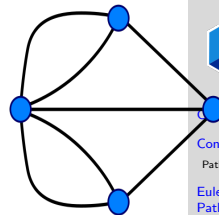
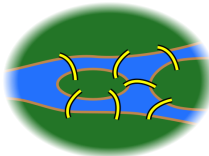
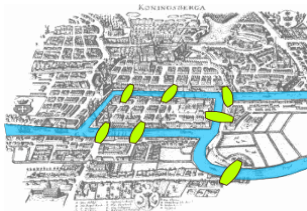
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Back to the Seven Bridges Problem



- Four vertices of odd degree
- No Euler circuit \rightarrow cannot cross each bridge exactly once, and return to starting point
- No Euler path, either



Searching Euler Circuits and Paths – Fleury's Algorithm

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Graph Coloring

- Choose a random vertex (if circuit) or an odd degree vertex (if path)

Searching Euler Circuits and Paths – Fleury's Algorithm

- Choose a random vertex (if circuit) or an odd degree vertex (if path)
- Pick an edge joined to another vertex so that it is not a cut edge unless there is no alternative

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Graph Coloring

- Choose a random vertex (if circuit) or an odd degree vertex (if path)
- Pick an edge joined to another vertex so that it is not a cut edge unless there is no alternative
- Remove the chosen edge. The above procedure is repeated until all edges are covered.

Searching Euler Circuits and Paths – Hierholzer's Algorithm

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Graph Coloring

- Choose a starting vertex and find a circuit

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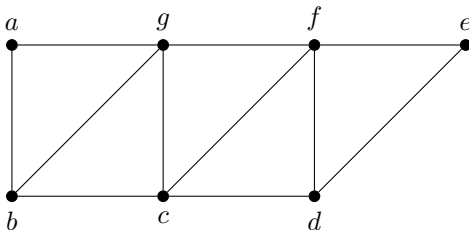
- Choose a starting vertex and find a circuit
- As long as there exists a vertex v that belongs to the current tour but that has adjacent edges not part of the tour, start another circuit from v

More efficient algorithm, $O(n)$.

Exercise

Example

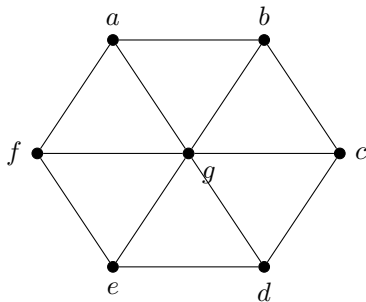
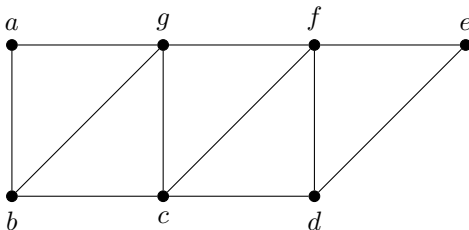
Are these following graph Euler path (circuit)? If yes, find one.



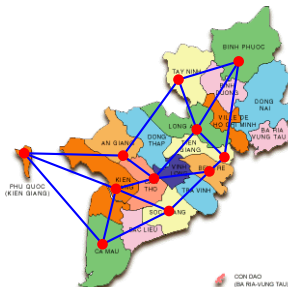
Exercise

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Traveling Salesman Problem



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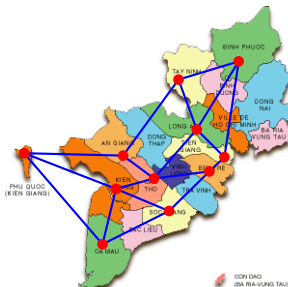
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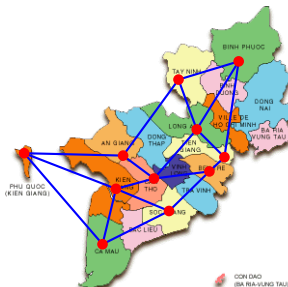
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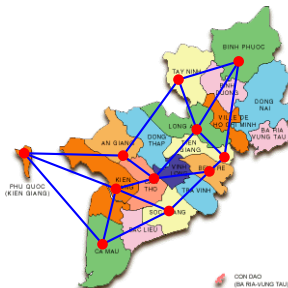
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Is there the possible tour that visits each city exactly once?

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What Is A Hamilton Circuit?

Definition

The circuit that visit each vertex in a graph **once**

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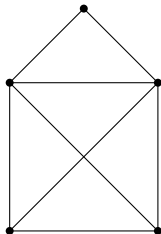
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What Is A Hamilton Circuit?

Definition

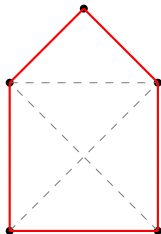
The circuit that visit each vertex in a graph **once**



What Is A Hamilton Circuit?

Definition

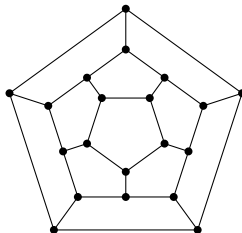
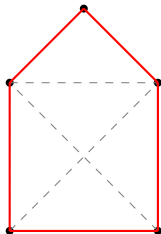
The circuit that visit each vertex in a graph **once**



What Is A Hamilton Circuit?

Definition

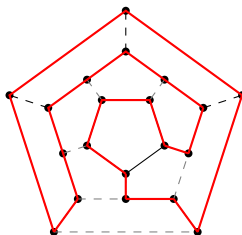
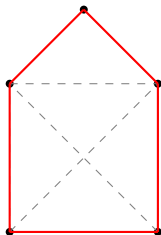
The circuit that visit each vertex in a graph **once**



What Is A Hamilton Circuit?

Definition

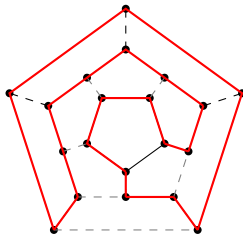
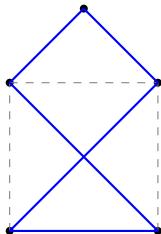
The circuit that visit each vertex in a graph **once**



What Is A Hamilton Circuit?

Definition

The circuit that visit each vertex in a graph **once**



Rules of Hamilton Circuits

$\deg(v) = 2$ for $\forall v$ in Hamilton circuit!

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Rules of Hamilton Circuits

$\deg(v) = 2$ for $\forall v$ in Hamilton circuit!

Rule 1 if $\deg(v) = 2$, both edge must be used.

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Rules of Hamilton Circuits

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Rule 2 No subcircuit (*chu trình con*) can be formed.



Rules of Hamilton Circuits

$\deg(v) = 2$ for $\forall v$ in Hamilton circuit!

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Rule 2 No subcircuit (*chu trình con*) can be formed.

Rule 3 Once two edges at a vertex v is determined, all other edges incident at v must be removed.



Rules of Hamilton Circuits

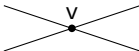
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Rules of Hamilton Circuits

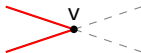
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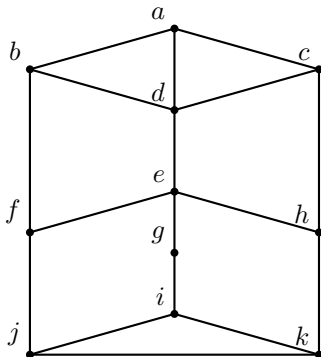
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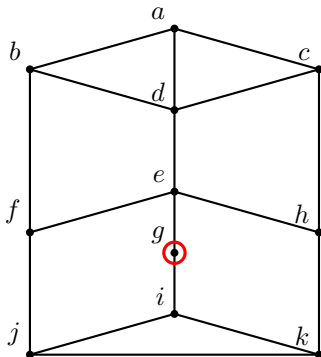
Finding Hamilton Circuits

Vertices : cities
Edges : possible routes

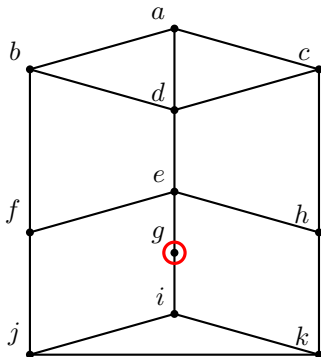


Finding Hamilton Circuits

Vertices : cities
Edges : possible routes



Finding Hamilton Circuits



Vertices : cities

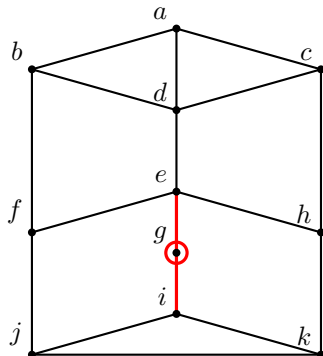
Edges : possible routes

Rule 1

$$\deg(v) = 2$$



Finding Hamilton Circuits



Vertices : cities

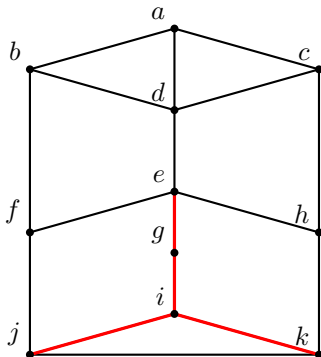
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Vertices : cities

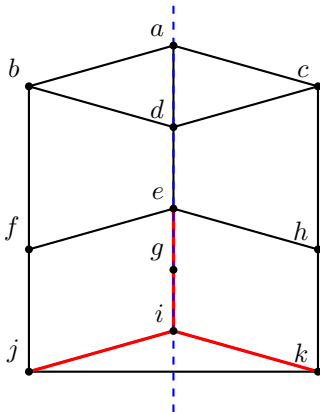
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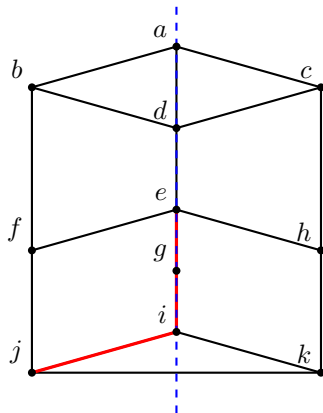
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Finding Hamilton Circuits



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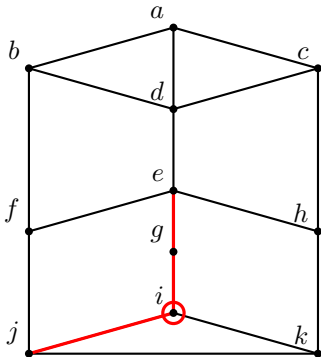
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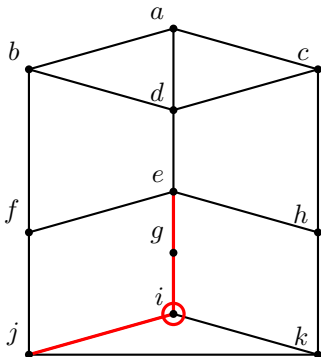
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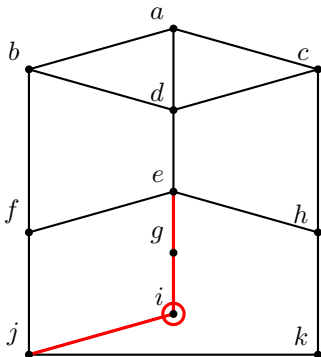
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Rule 3

Once two edges are determined,
other edges must be removed



Finding Hamilton Circuits



Vertices : cities

Edges : possible routes

Rule 1

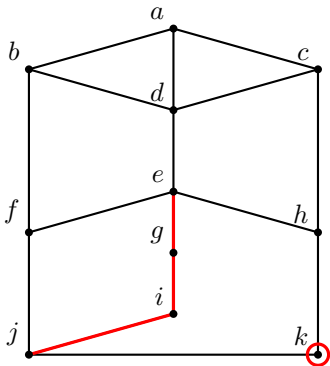
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Finding Hamilton Circuits



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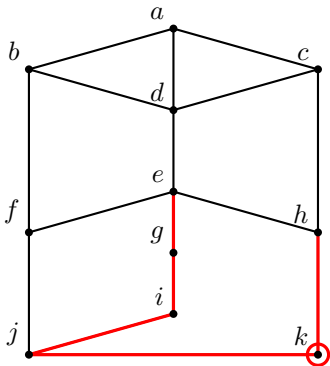
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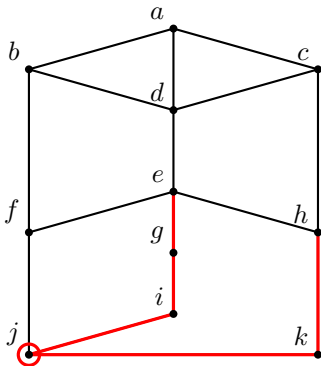
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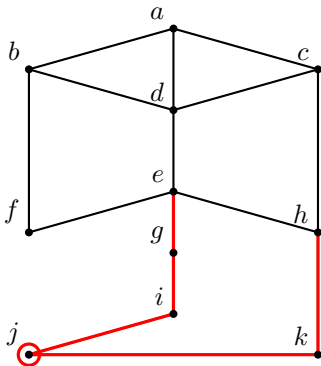
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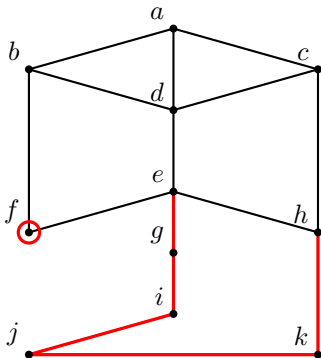
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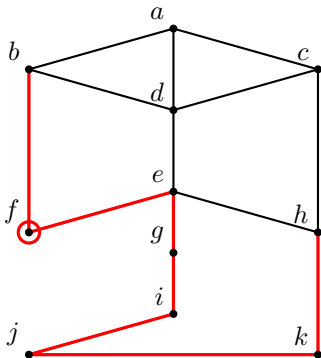
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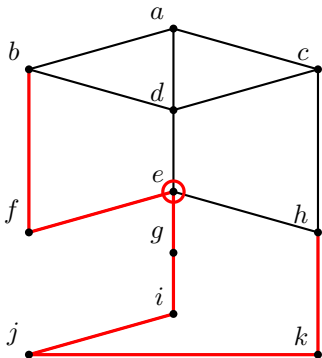
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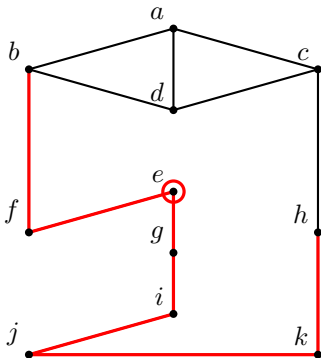
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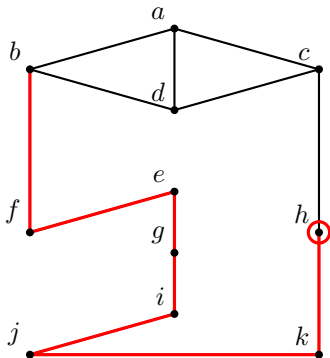
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Rule 3

Once two edges are determined,
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Edges : possible routes

$$\deg(v) = 2$$

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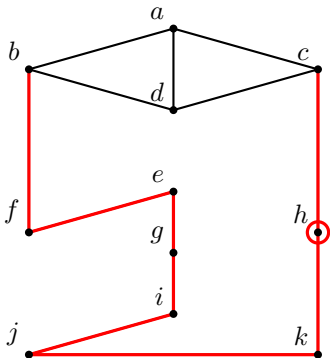
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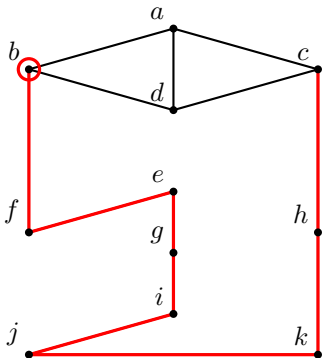
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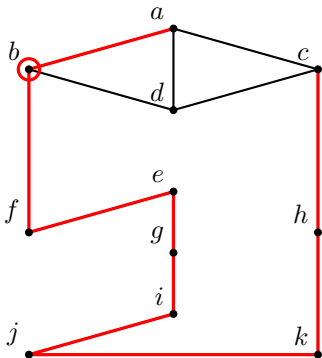
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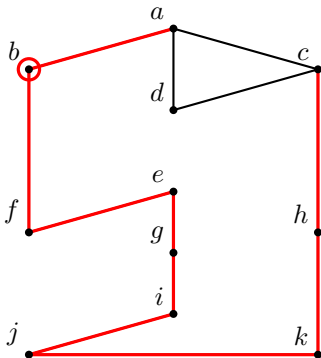
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Finding Hamilton Circuits



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Edges : possible routes

Rule 1

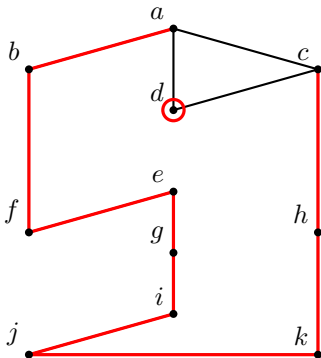
$$\deg(v) = 2$$

Rule 3

Once two edges are determined,
other edges must be removed



Finding Hamilton Circuits



Vertices : cities

Edges : possible routes

Rule 1

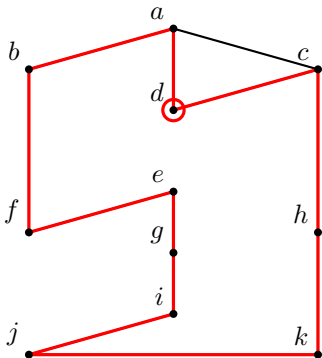
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Finding Hamilton Circuits



Vertices : cities

Edges : possible routes

Rule 1

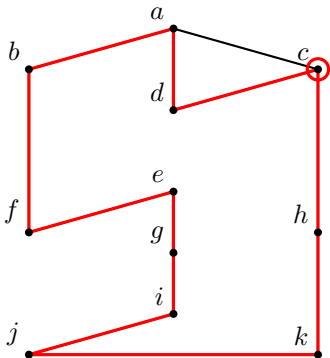
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Finding Hamilton Circuits



Vertices : cities

Edges : possible routes

Rule 1

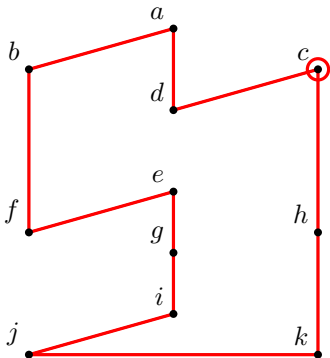
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Finding Hamilton Circuits



Vertices : cities

Edges : possible routes

Rule 1

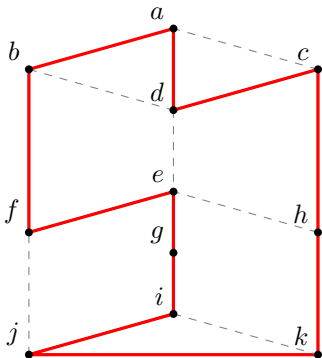
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Finding Hamilton Circuits



We get **Hamilton circuit!**

Vertices : cities

Edges : possible routes

Rule 1

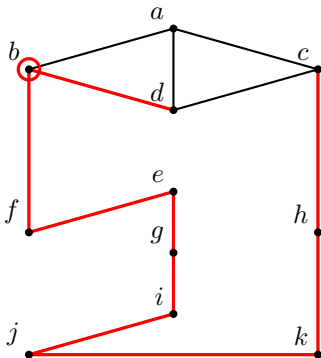
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Finding Hamilton Circuits



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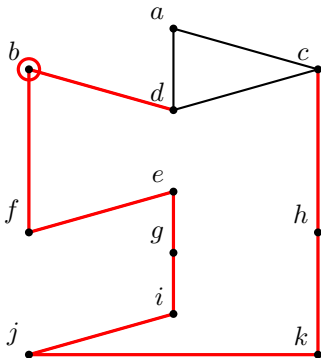
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Finding Hamilton Circuits



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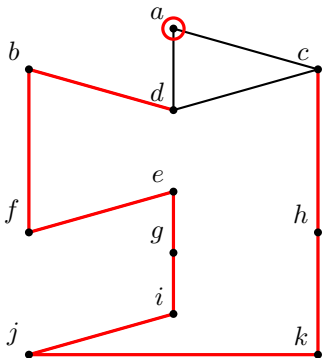
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Finding Hamilton Circuits



Vertices : cities

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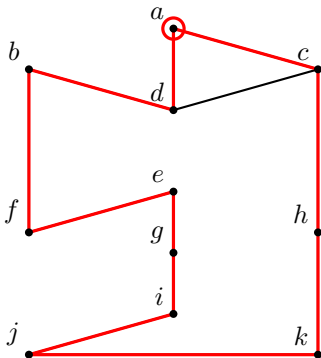
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Finding Hamilton Circuits



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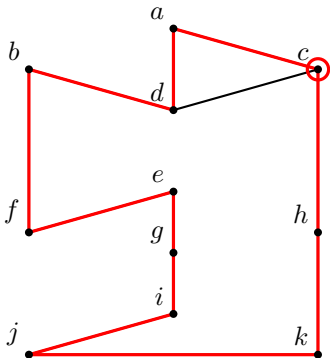
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Finding Hamilton Circuits



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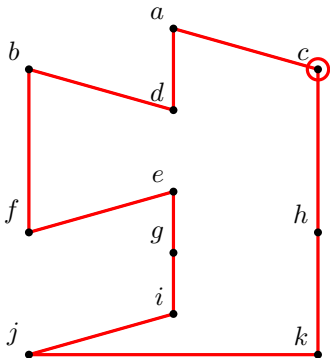
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Finding Hamilton Circuits



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Edges : possible routes

Rule 1

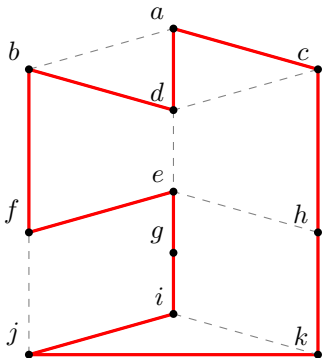
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Rule 3

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Finding Hamilton Circuits



We get **Hamilton circuit!**

Vertices : cities

Edges : possible routes

Rule 1

$$\deg(v) = 2$$

Rule 3

Once two edges are determined,
other edges must be removed



Existence of Hamilton Circuit

Hamilton circuit **does not** exist for all graph.

More About Graphs

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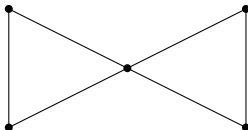
Simple check by rules of Hamilton circuit



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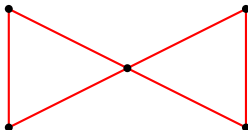
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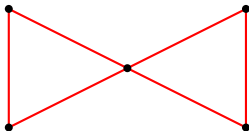
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Existence of Hamilton Circuit

Hamilton circuit **does not** exist for all graph. But, there is no specific way to find whether Hamilton circuit exists or not.

Simple check by rules of Hamilton circuit



Violates **Rule 2!** (No subcircuit)



We can verify **nonexistence** of the graph during find Hamilton circuit.



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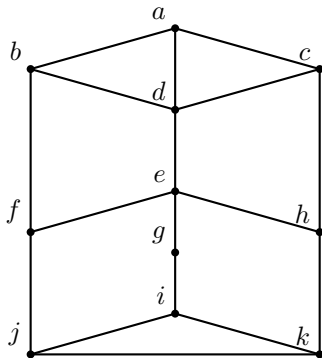
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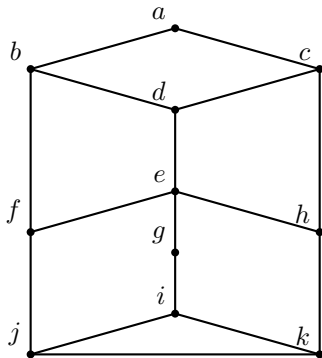
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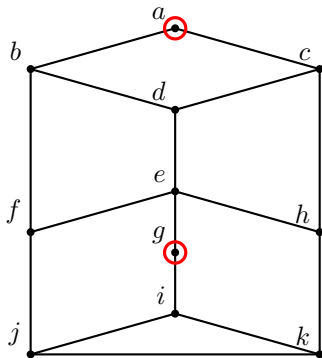
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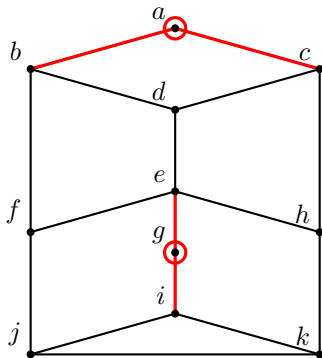
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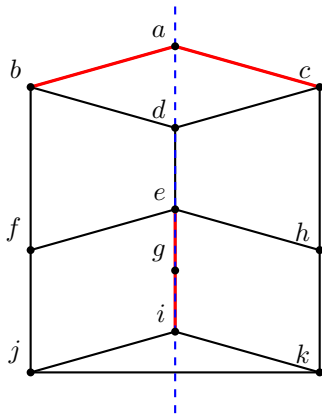
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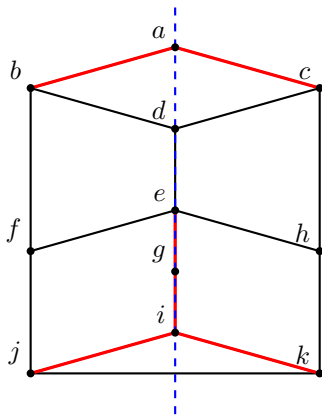
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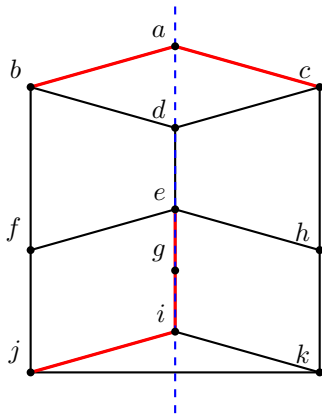
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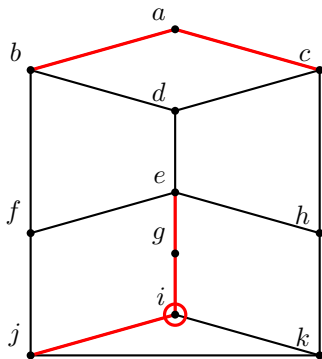
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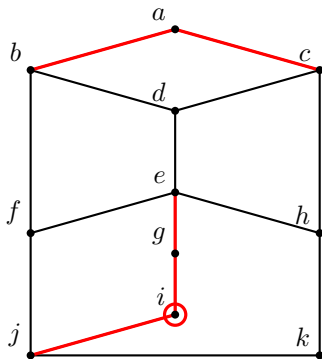
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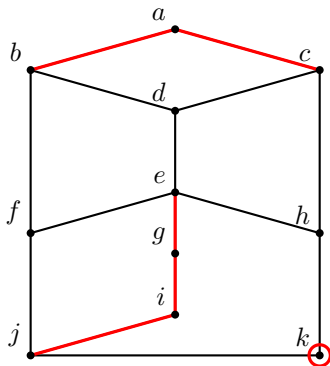
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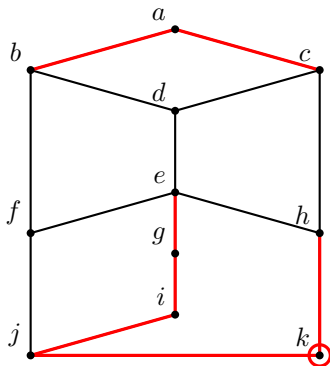
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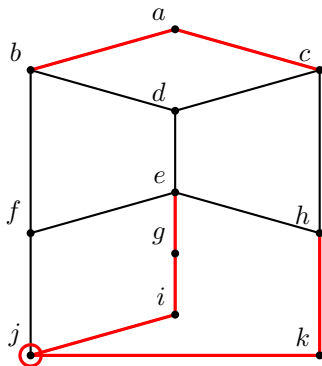
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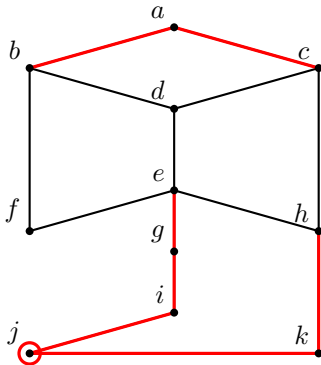
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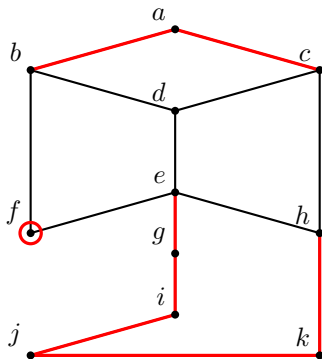
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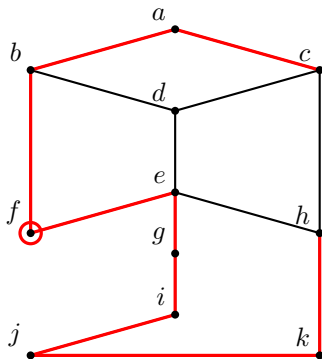
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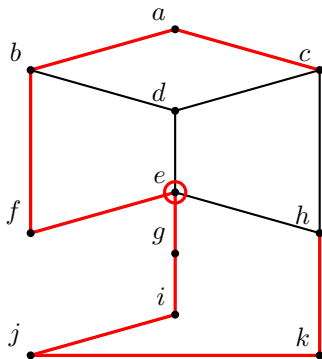
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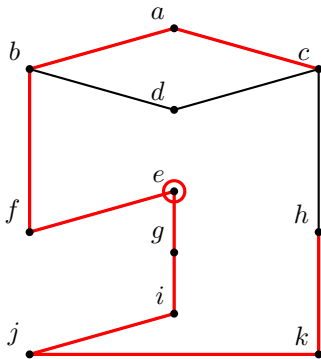
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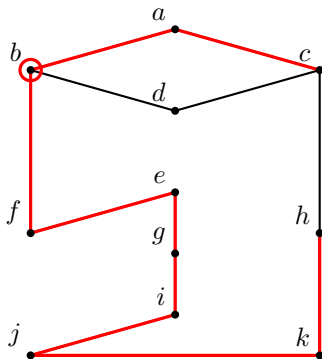
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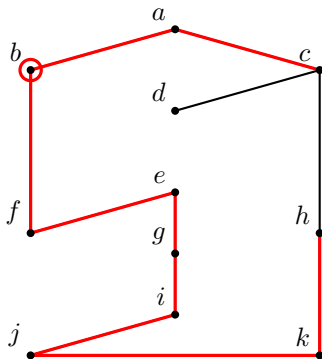
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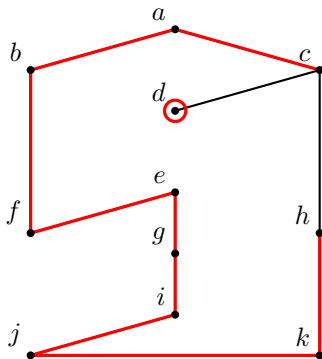
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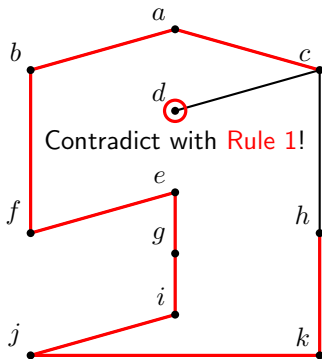
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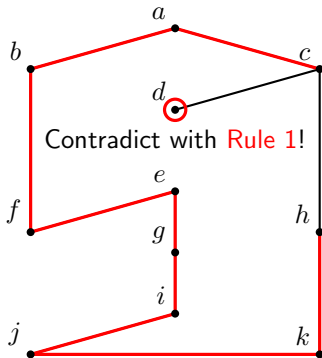
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We can verify **nonexistence** of the graph during find Hamilton circuit.



Hamilton circuit doesn't exist!

Application – Gray Code

Definition

The **binary sequence** that express consecutive numbers by differing just **one** position of sequence.

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Definition

The **binary sequence** that express consecutive numbers by differing just **one** position of sequence.

Decimal number		Binary number	Gray code
1	=	001	000
2	=	010	100
3	=	011	110
4	=	100	010
5	=	101	011
⋮		⋮	⋮

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5	=	101	011
⋮		⋮	⋮

Used at **digital communication** for reduce the effect of noise; it prevents serious changes of information by noise.



Gray Code

n -digit gray code can be generated by finding Hamilton circuits of n -dimensional hypercube!

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n -digit gray code can be generated by finding Hamilton circuits of n -dimensional hypercube! Consider the case $n = 3$.

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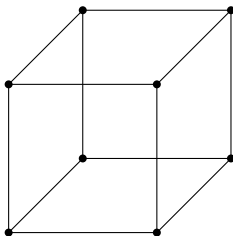
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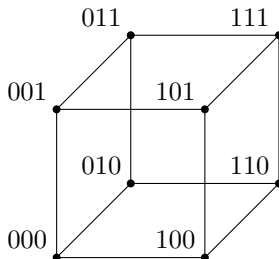
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Coordinate of each vertex is 3-digit binary sequences.



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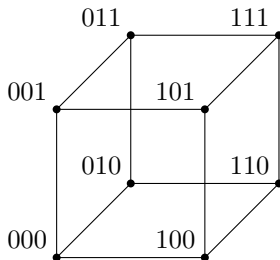
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Coordinate of each vertex is 3-digit binary sequences. Coordinates of adjacent vertices differ in just one place.



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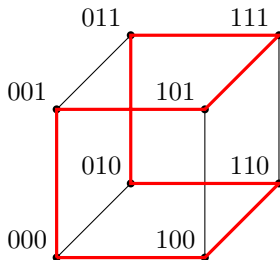
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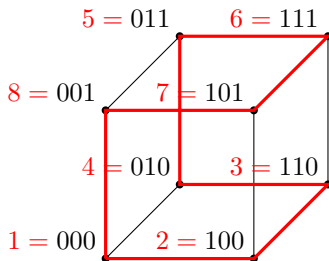


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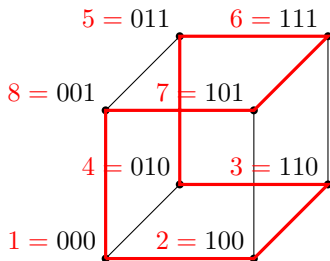


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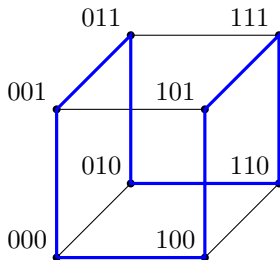


Coordinate of each vertex is 3-digit binary sequences. Coordinates of adjacent vertices differ in just one place. Hamilton circuits of a cubic graph makes the **order** of binary sequences!



Gray Code

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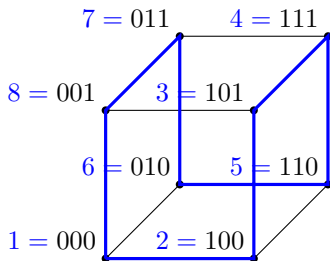


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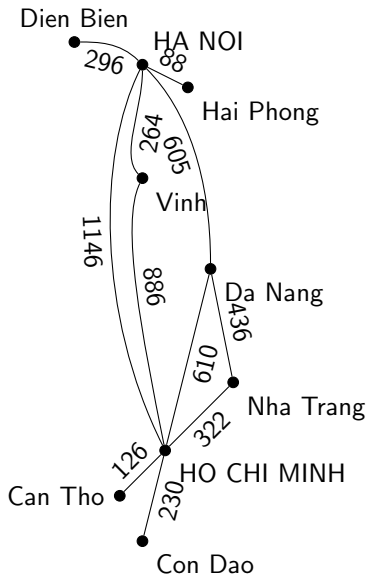
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Coordinate of each vertex is 3-digit binary sequences. Coordinates of adjacent vertices differ in just one place. Hamilton circuits of a cubic graph makes the **order** of binary sequences!



Weighted Graphs



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The problem is also sometimes called the single-pair shortest path problem, to distinguish it from the following generalizations:

- The **single-source shortest path problem**, in which we have to find shortest paths from a source vertex v to all other vertices in the graph.
- The **single-destination shortest path problem**, in which we have to find shortest paths from all vertices in the graph to a single destination vertex v . This can be reduced to the single-source shortest path problem by reversing the edges in the graph.
- The **all-pairs shortest path problem**, in which we have to find shortest paths between every pair of vertices v, v' in the graph.

These generalizations have significantly more efficient algorithms than the simplistic approach of running a single-pair shortest path algorithm on all relevant pairs of vertices.



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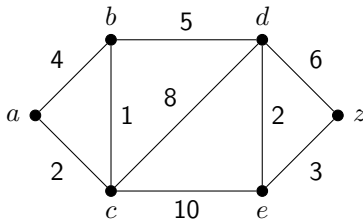
Dijkstra's Algorithm

```
procedure Dijkstra(G,a)
// Initialization Step
  forall vertices v
    Label[v] :=  $\infty$ 
    Prev[v] := -1
  endfor
  Label(a) := 0 // a is the source node
  S :=  $\emptyset$ 

// Iteration Step
  while  $z \notin S$ 
    u := a vertex not in S with minimal Label
    S := S  $\cup$  {u}
    forall vertices v not in S
      if (Label[u] + Wt(u,v)) < Label(v)
        then begin
          Label[v] := Label[u] + Wt(u,v)
          Pred[v] := u
        end
      end
    end
  endwhile
```



Example



S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞



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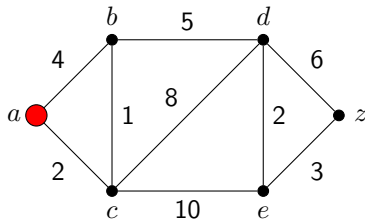
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞



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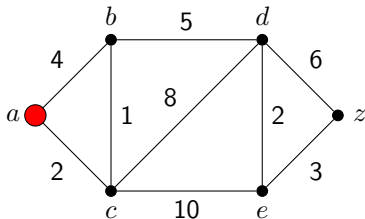
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0					



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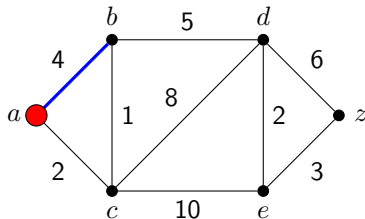
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0					



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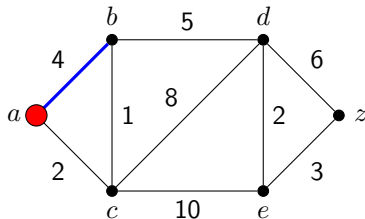
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4				



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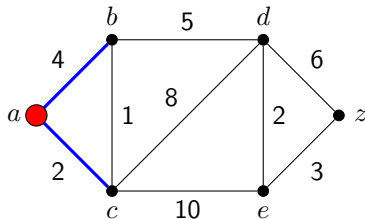
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4				



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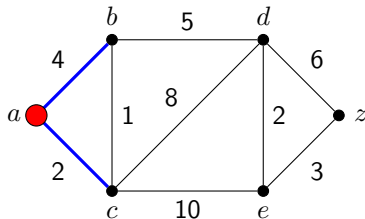
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞



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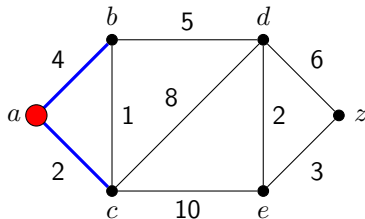
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞



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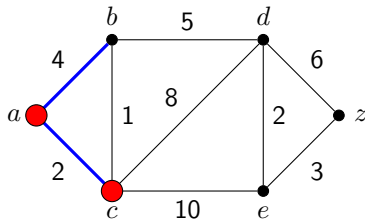
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞



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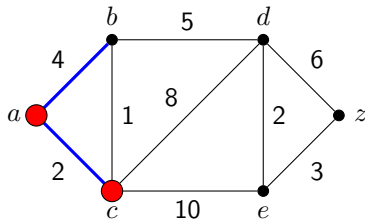
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0		2			



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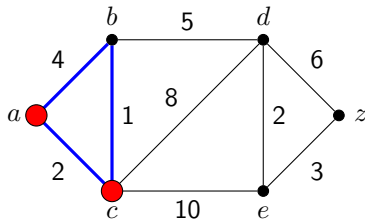
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0		2			



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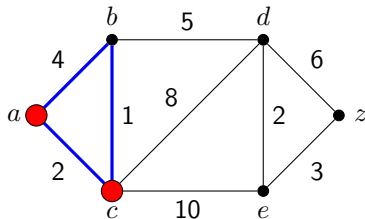
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	∞	∞	∞



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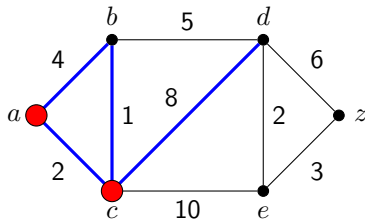
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	∞	∞	∞



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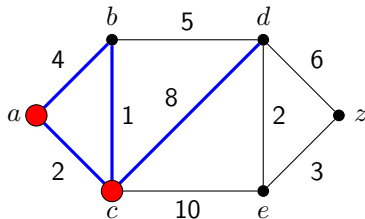
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10		



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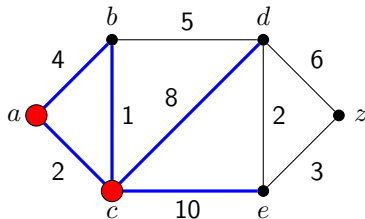
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10		



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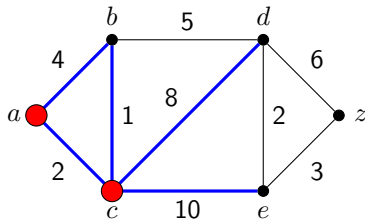
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	



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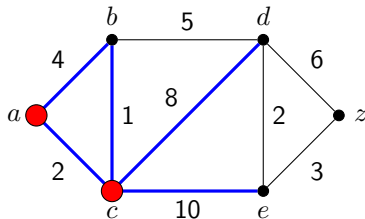
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞



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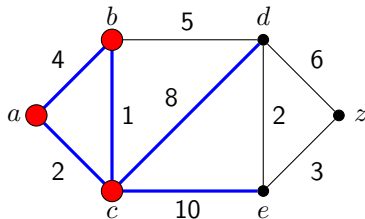
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞



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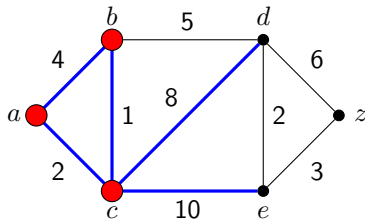
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2			



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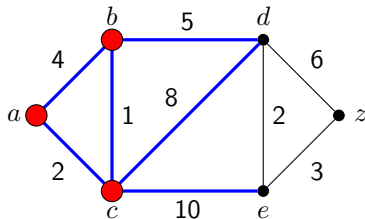
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2			



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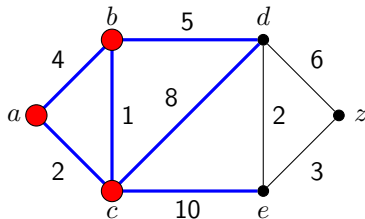
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8		



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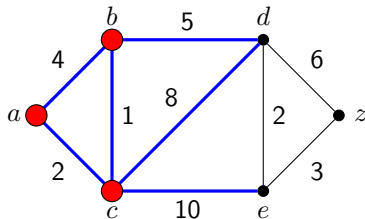
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞



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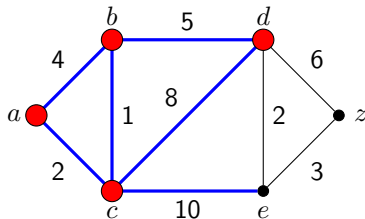
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞



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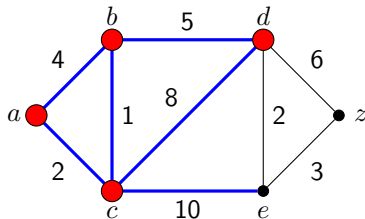
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8		



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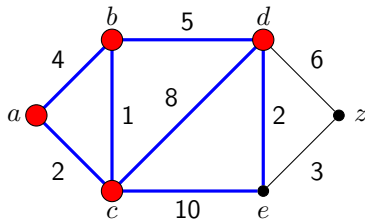
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8		



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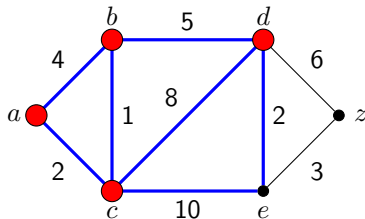
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	



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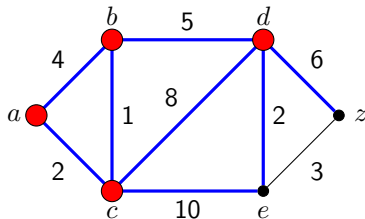
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	



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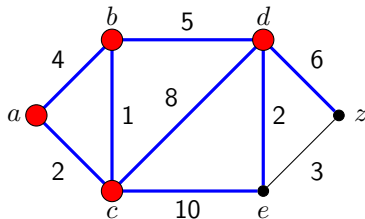
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\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14



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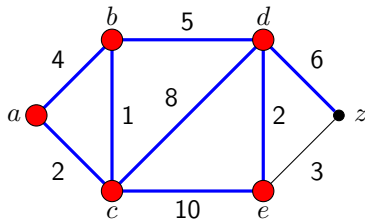
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c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14



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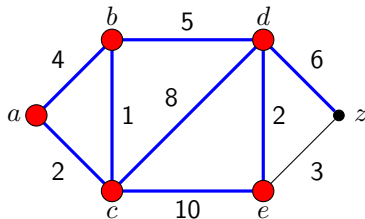
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c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14
e	0	3	2	8	10	



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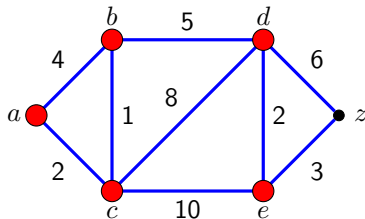
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\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14
e	0	3	2	8	10	



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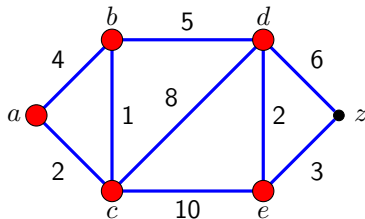
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14
e	0	3	2	8	10	13



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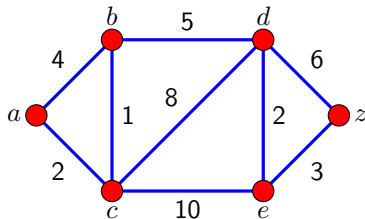
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S	a	b	c	d	e	z
\emptyset	0	∞	∞	∞	∞	∞
a	0	4	2	∞	∞	∞
c	0	3	2	10	12	∞
b	0	3	2	8	12	∞
d	0	3	2	8	10	14
e	0	3	2	8	10	13



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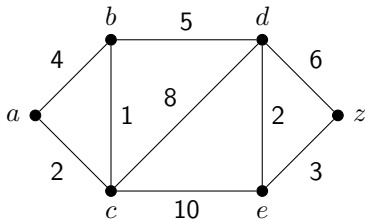
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞



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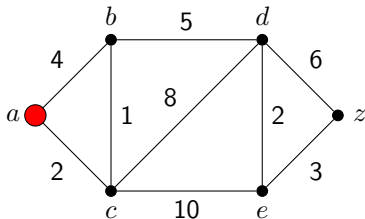
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞



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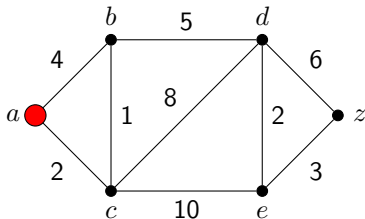
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a						



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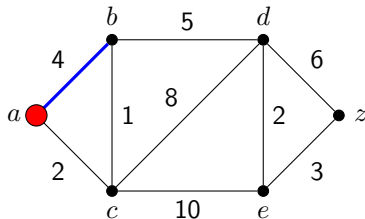
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a						



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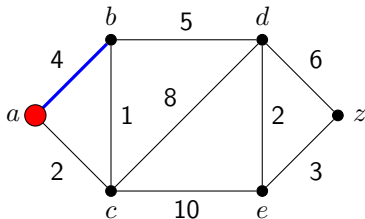
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4				



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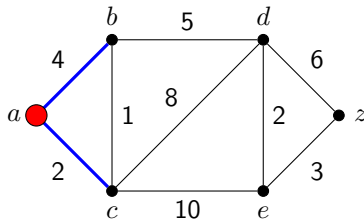
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4				



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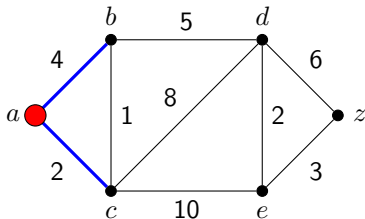
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	2			



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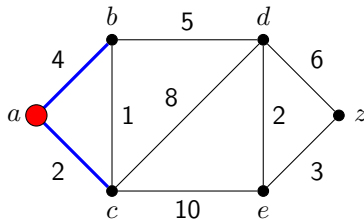
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	2	∞	∞	∞



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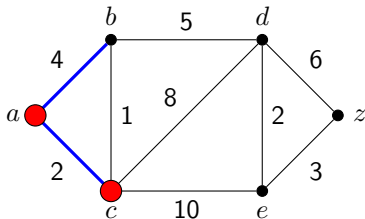
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞



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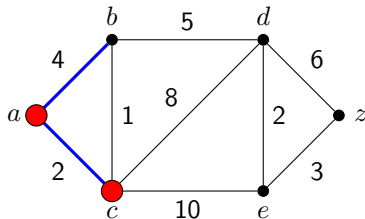
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c						



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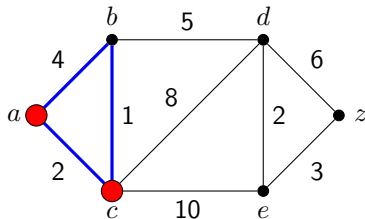
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c						



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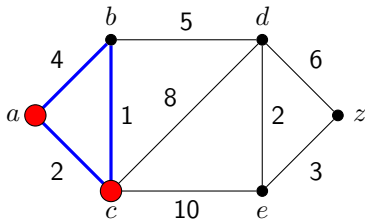
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3				



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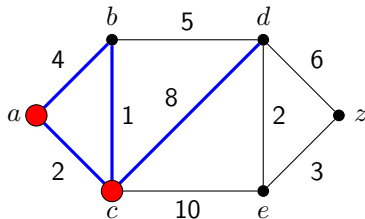
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3				



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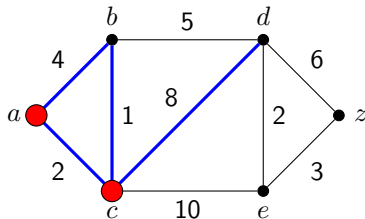
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3		10		



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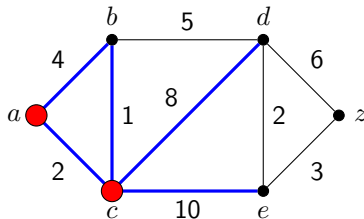
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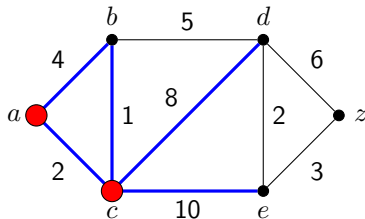
Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3		10		



Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3		10	12	



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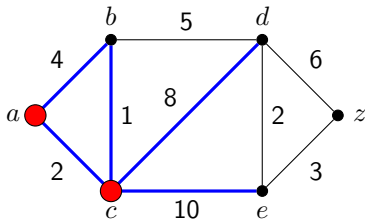
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		3		10	12	∞



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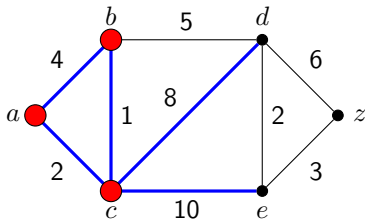
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\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞



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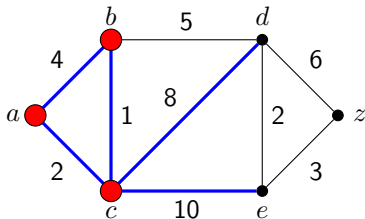
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b						



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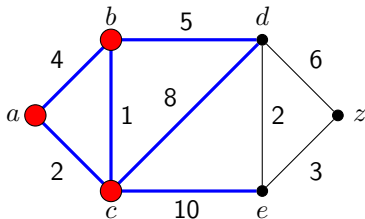
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a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b						



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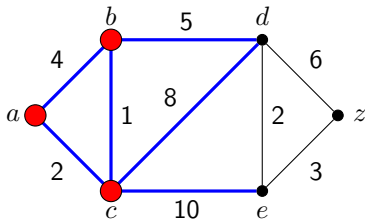
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				8		



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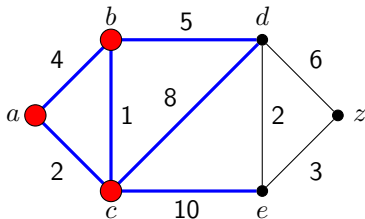
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				8	12	∞



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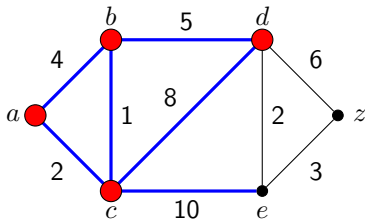
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a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞



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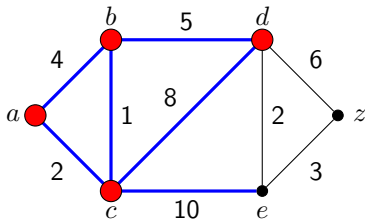
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S	a	b	c	d	e	z
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a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d						∞



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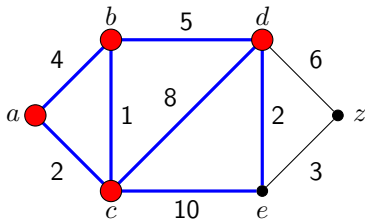
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a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d						∞



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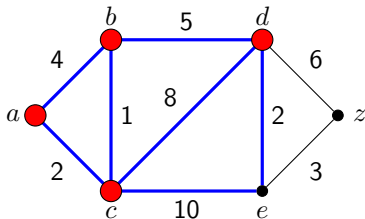
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S	a	b	c	d	e	z
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a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					10	



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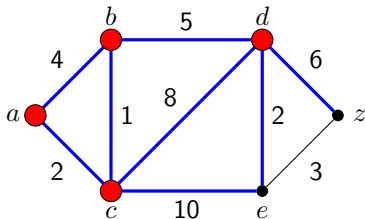
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					10	



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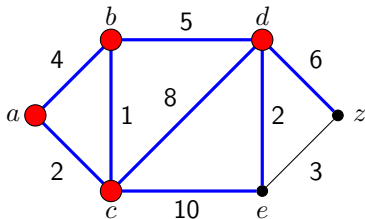
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					10	14



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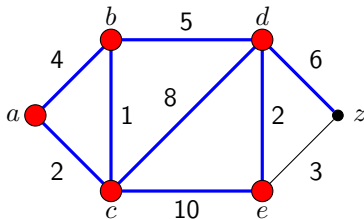
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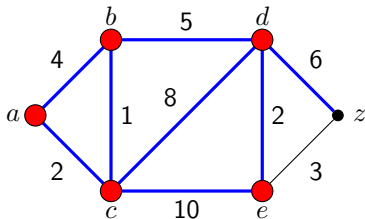
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S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					<u>10</u>	14



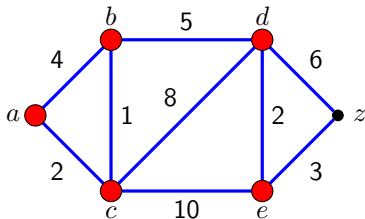
Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					<u>10</u>	14
e						



Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					<u>10</u>	14
e						



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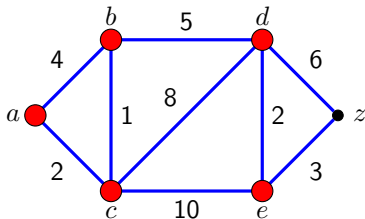
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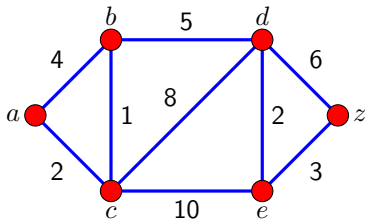
Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					<u>10</u>	14
e						13



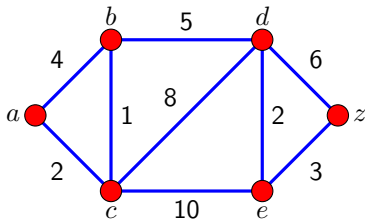
Example



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a		4	<u>2</u>	∞	∞	∞
c		<u>3</u>		10	12	∞
b				<u>8</u>	12	∞
d					<u>10</u>	14
e						<u>13</u>



Example

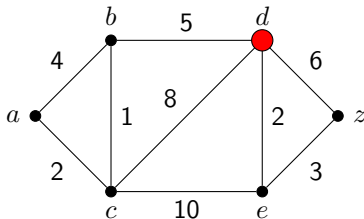


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

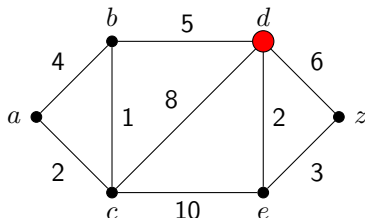


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

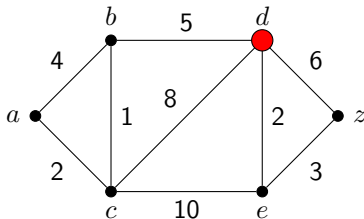


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

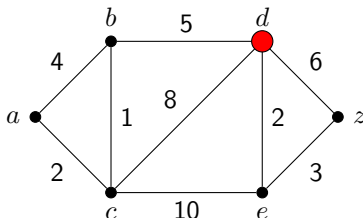


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

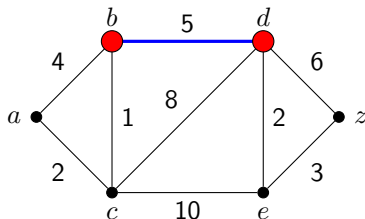


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	<u>8</u>	<u>10</u>	14
e	0	3	2	<u>8</u>	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

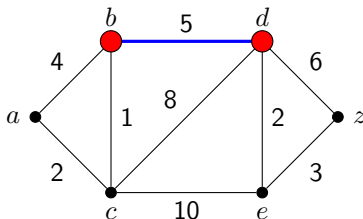


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	<u>8</u>	<u>10</u>	14
e	0	3	2	<u>8</u>	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

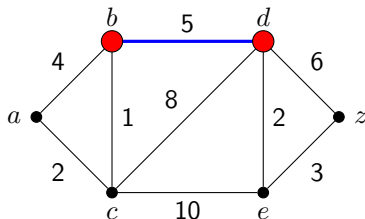


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
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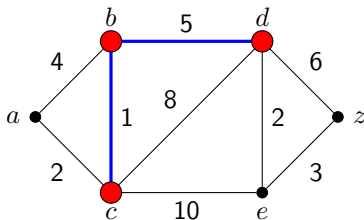
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How to determine shortest path from a to d according to Dijkstra's algorithm?

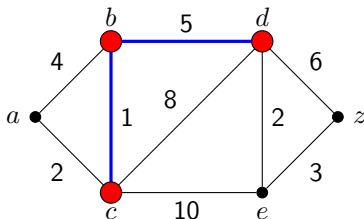


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	2	10	12	∞
b	0	3	2	<u>8</u>	12	∞
d	0	3	2	8	<u>10</u>	14
e	0	3	2	8	10	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?

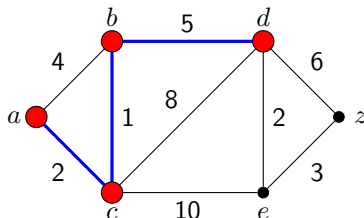


S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	<u>2</u>	10	12	∞
b	0	<u>3</u>	2	<u>8</u>	12	∞
d	0	3	2	<u>8</u>	<u>10</u>	14
e	0	3	2	<u>8</u>	<u>10</u>	<u>13</u>



Back tracking procedure

How to determine shortest path from a to d according to Dijkstra's algorithm?



S	a	b	c	d	e	z
\emptyset	<u>0</u>	∞	∞	∞	∞	∞
a	0	4	<u>2</u>	∞	∞	∞
c	0	<u>3</u>	<u>2</u>	10	12	∞
b	0	<u>3</u>	2	<u>8</u>	12	∞
d	0	3	2	<u>8</u>	<u>10</u>	14
e	0	3	2	<u>8</u>	<u>10</u>	<u>13</u>



Dijkstra's Algorithm

Property

Applicable for any G , any length $\ell(v_i) \geq 0, \forall i$; one-to-all; complexity $O(|V|^2)$.

More About Graphs

Huynh Tuong Nguyen,
Tran Vinh Tan



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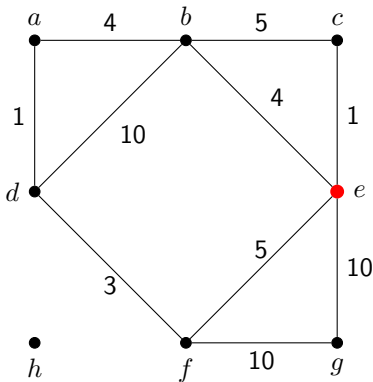
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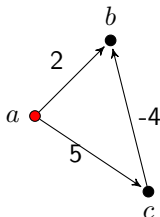
Find the shortest path from e to other vertices using Dijkstra's algorithm.



Dijkstra's Algorithm Flaw

Can Dijkstra's Algorithm be used on...

- ...digraph?
 - Yes!
- ...negative weighted graph?
 - No! Why?



Bellman-Ford Algorithm

```
procedure BellmanFord(G,a)
// Initialization Step
  forall vertices v
    Label[v] :=  $\infty$ 
    Prev[v] := -1
  Label(a) := 0 // a is the source node

// Iteration Step
  for i from 1 to size(vertices)-1
    forall vertices v
      if (Label[u] + Wt(u,v)) < Label[v]
        then
          Label[v] := Label[u] + Wt(u,v)
          Prev[v] := u

// Check circuit of negative weight
  forall vertices v
    if (Label[u] + Wt(u,v)) < Label(v)
      error "Contains circuit of negative weight"
```

Property

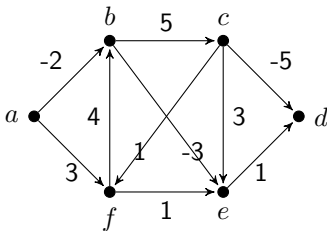
any G , any length; one-to-all; detect whether there exists a circle of negative length; complexity $O(|V| \times |E|)$.



Example

Example

Step	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>
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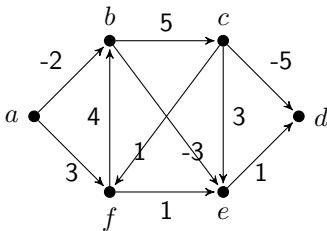
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Example

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞



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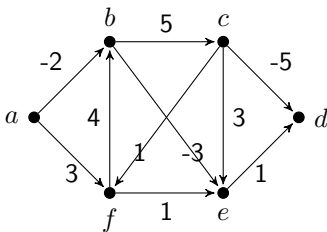
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Example

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$



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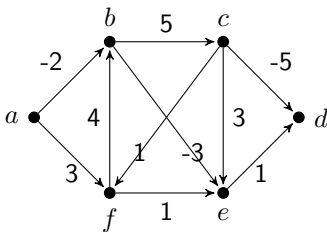
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3



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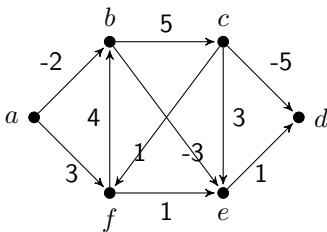
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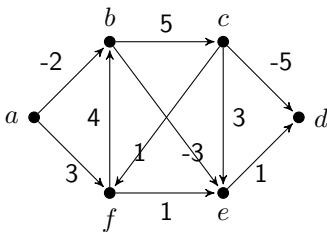
Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3



Example

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

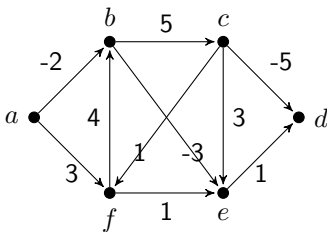


Example

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

Stop since Step 4 = Step 3.

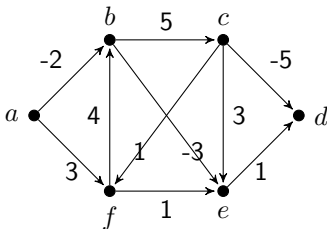


Backtracking procedure

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

Stop since Step 4 = Step 3.



Backtracking procedure

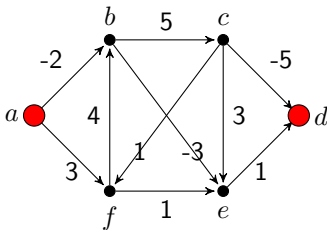
Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

Stop since Step 4 = Step 3.

How to find shortest path from a to d ? $a \rightarrow$

d



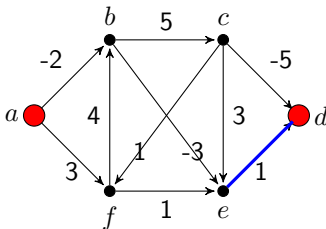
Backtracking procedure

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

Stop since Step 4 = Step 3.

How to find shortest path from a to d ? $a \rightarrow$ $e \rightarrow d$



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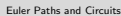


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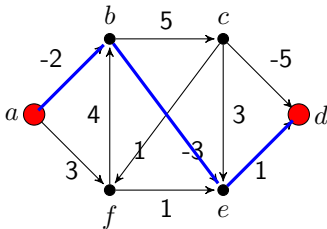
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	$3a$
2	0	-2	$3b$	∞	$-5b$	3
3	0	-2	3	$-4e$	-5	3
4	0	-2	3	-4	-5	3

Stop since Step 4 = Step 3.

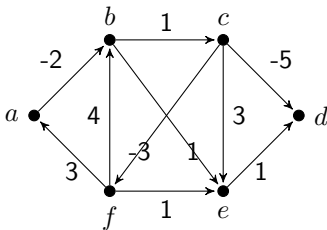
How to find shortest path from a to d ? $a \rightarrow b \rightarrow e \rightarrow d$



Example

Example

Step	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>
------	----------	----------	----------	----------	----------	----------



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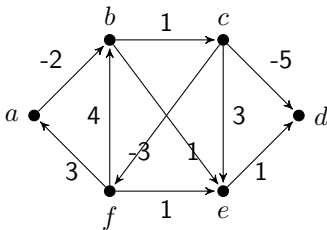
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞



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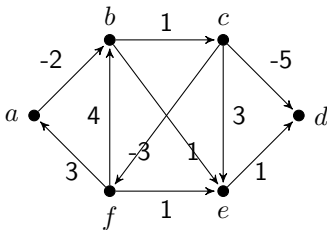
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Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞



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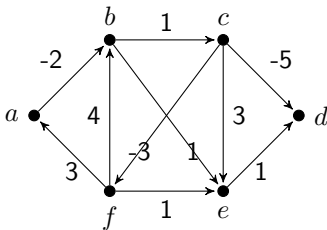
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞



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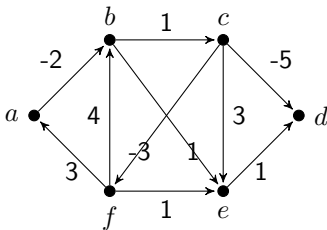
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$



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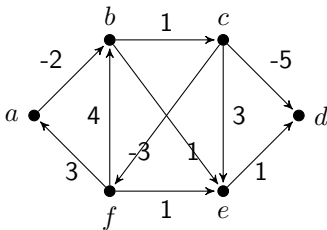
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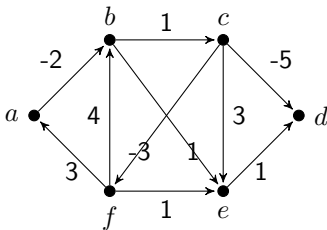
Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$
4	$-1f$	-2	-1	-6	$-3f$	-4



Example

Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$
4	$-1f$	-2	-1	-6	$-3f$	-4
5	-1	$-3a$	-1	-6	-3	-4



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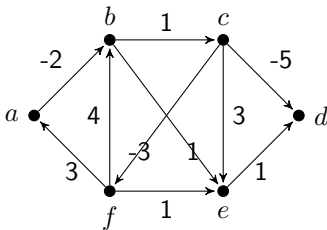
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$
4	$-1f$	-2	-1	-6	$-3f$	-4
5	-1	$-3a$	-1	-6	-3	-4
6	-1	-3	$-2b$	-6	-3	-4



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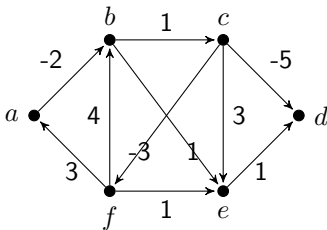
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Example

Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$
4	$-1f$	-2	-1	-6	$-3f$	-4
5	-1	$-3a$	-1	-6	-3	-4
6	-1	-3	$-2b$	-6	-3	-4

There exists a circle of negative length since Step 6 \neq Step 5.

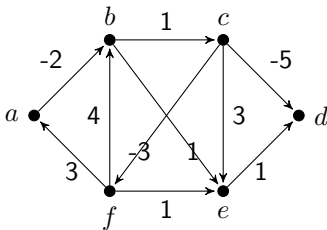


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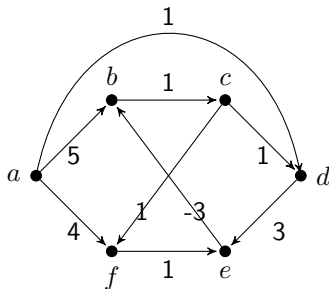
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Step	a	b	c	d	e	f
0	0	∞	∞	∞	∞	∞
1	0	$-2a$	∞	∞	∞	∞
2	0	-2	$-1b$	∞	$-1b$	∞
3	0	-2	-1	$-6c$	-1	$-4c$
4	$-1f$	-2	-1	-6	$-3f$	-4
5	-1	$-3a$	-1	-6	-3	-4
6	-1	-3	$-2b$	-6	-3	-4
7	-1	-3	-2	$-7c$	-3	-4

There exists a circle of negative length since Step 6 \neq Step 5.



Exercise



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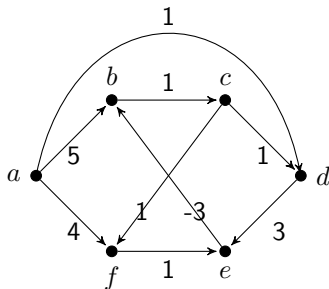
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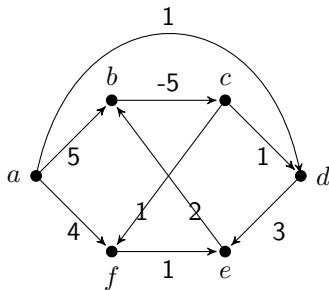


Example

Step	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>	<i>f</i>
0	0	∞	∞	∞	∞	∞
1	0	5a	∞	1a	∞	4a
2	0	5a	6b	1a	4d	4a
3	0	1e	6b	1a	4d	4a
4	0	1e	2b	1a	4d	4a
5	0	1e	2b	1a	4d	3c
6	0	1e	2b	1a	4d	3c



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Floyd-Warshall Algorithm [1962]

```
procedure FloydWarshall ()
  for k := 1 to n
    for i := 1 to n
      for j := 1 to n
        path[i,j] = min (path[i,j],
                          path[i,k]+path[k,j]);
```

Property

any G , any length; all-to-all; this is an software algorithm; complexity $O(|V|^3)$.

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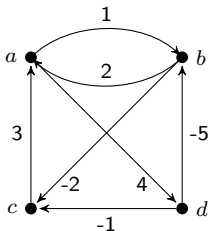
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$



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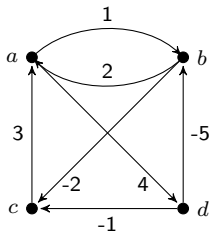
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$



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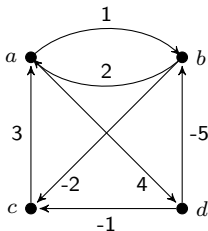
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$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$



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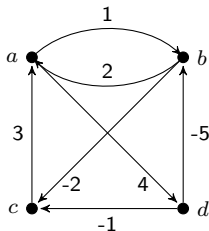
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 2_0 & 0_0 & -2_0 & 6_1 \\ 4_1 & 1_0 & -5_0 & 4_0 \\ -5_0 & 4_1 & 1_0 & 4_0 \end{pmatrix}$$



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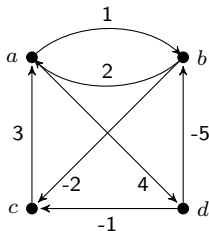
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$



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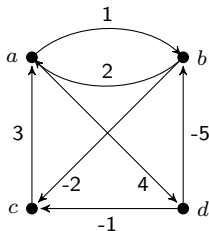
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$$\begin{aligned}
 L^{(0)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(1)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(2)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(3)} &= \begin{pmatrix} & & -1_2 & \\ & & -2_0 & \\ 3 & 4_1 & 0_0 & 7_1 \\ & & -7_2 & \end{pmatrix}
 \end{aligned}$$



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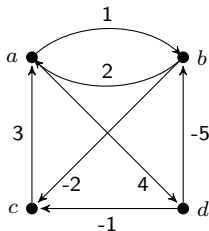
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$$\begin{aligned}
 L^{(0)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(1)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(2)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(3)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}
 \end{aligned}$$



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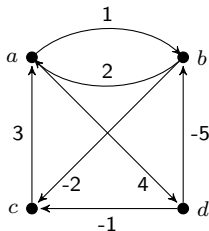
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(4)} = \begin{pmatrix} & & & 4_0 \\ & & & 5_3 \\ & & & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$



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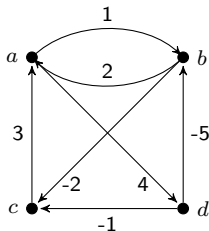
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$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(4)} = \begin{pmatrix} 0_0 & 1_0 & -3_4 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3_0 & 2_4 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$



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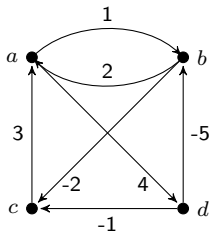
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Shortest path from b to d
(5_3 from $L^{(4)}$):

$$\begin{aligned}
 L^{(0)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(1)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(2)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(3)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(4)} &= \begin{pmatrix} & & & 4_0 \\ & & & 5_3 \\ & & & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}
 \end{aligned}$$



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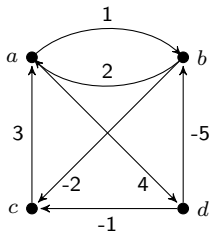
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Shortest path from b to d
 (5_3 from $L^{(4)}$):
 $bd = bc + cd$
 ($5_3 = -2_0 + 7_1$ from $L^{(3)}$)

$$\begin{aligned}
 L^{(0)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(1)} &= \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix} \\
 L^{(2)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(3)} &= \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix} \\
 L^{(4)} &= \begin{pmatrix} & & & 4_0 \\ & & & 5_3 \\ & & & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}
 \end{aligned}$$



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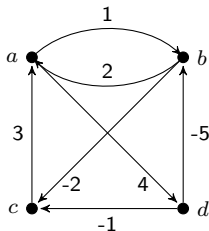
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Shortest path from b to d

(5_3 from $L^{(4)}$):

$$bd = bc + cd$$

($5_3 = -2_0 + 7_1$ from $L^{(3)}$)

$$cd = ca + ad$$

($7_1 = 3_0 + 4_0$ from $L^{(1)}$)

$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(4)} = \begin{pmatrix} & & & 4_0 \\ & & & 5_3 \\ & & & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$



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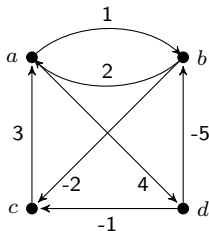
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Example



Shortest path from b to d

(5_3 from $L^{(4)}$):

$$bd = bc + cd$$

($5_3 = -2_0 + 7_1$ from $L^{(3)}$)

$$cd = ca + ad$$

($7_1 = 3_0 + 4_0$ from $L^{(1)}$)

$$\Rightarrow bd = bc + ca + ad$$

$$L^{(0)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & \infty_0 \\ 3_0 & \infty_0 & 0_0 & \infty_0 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0_0 & 1_0 & \infty_0 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3_0 & 4_1 & 0_0 & 7_1 \\ \infty_0 & -5_0 & -1_0 & 0_0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 2_0 & 0_0 & -2_0 & 6_1 \\ 3 & 4_1 & 0_0 & 7_1 \\ -3_2 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0_0 & 1_0 & -1_2 & 4_0 \\ 1_3 & 0_0 & -2_0 & 5_3 \\ 3 & 4_1 & 0_0 & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$

$$L^{(4)} = \begin{pmatrix} & & & 4_0 \\ & & & 5_3 \\ & & & 7_1 \\ -4_3 & -5_0 & -7_2 & 0_0 \end{pmatrix}$$



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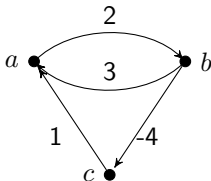
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$$L^{(0)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & \infty_0 & 0_0 \end{pmatrix}$$



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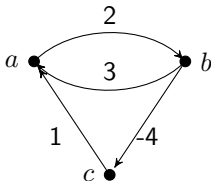
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$$L^{(0)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & \infty_0 & 0_0 \end{pmatrix} \quad L^{(1)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & 3_1 & 0_0 \end{pmatrix}$$



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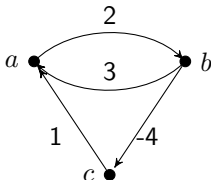
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$$L^{(0)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & \infty_0 & 0_0 \end{pmatrix} \quad L^{(1)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & 3_1 & 0_0 \end{pmatrix}$$
$$L^{(2)} = \begin{pmatrix} 0_0 & 2_0 & -2_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & 3_1 & -1_2 \end{pmatrix}$$



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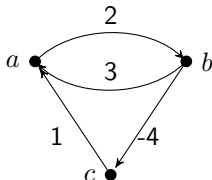
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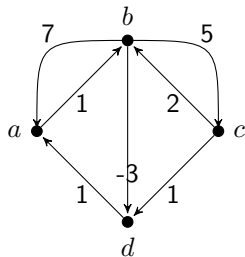


$$L^{(0)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & \infty_0 & 0_0 \end{pmatrix} \quad L^{(1)} = \begin{pmatrix} 0_0 & 2_0 & \infty_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & 3_1 & 0_0 \end{pmatrix}$$
$$L^{(2)} = \begin{pmatrix} 0_0 & 2_0 & -2_0 \\ 3_0 & 0_0 & -4_0 \\ 1_0 & 3_1 & -1_2 \end{pmatrix}$$

STOP, there exists a circuit of negative length.



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$$\pi(1) = 0$$

For each $j \in V$ **do**

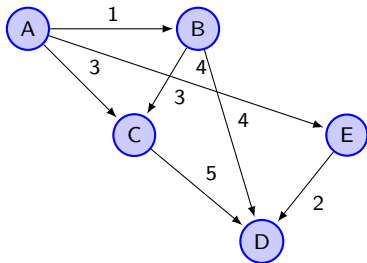
$$\pi(j) = \min_{i \in \rho_j^{-1}} (\pi(i) + \ell[i, j])$$

End

Property

G without circle, positive length; one-to-all; rank table definition; complexity $O(|V|)$.

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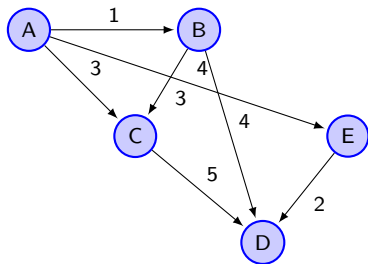
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i	Γ_i^{-1}	rank(i)
A		
B		
C		
D		
E		



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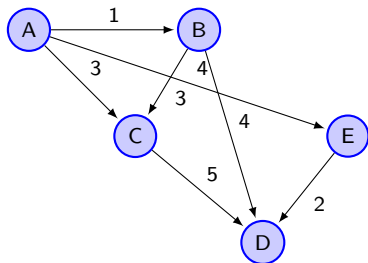
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i	Γ_i^{-1}	rank(i)
A	-	
B	A	
C	A, B	
D	B, C, E	
E	A	



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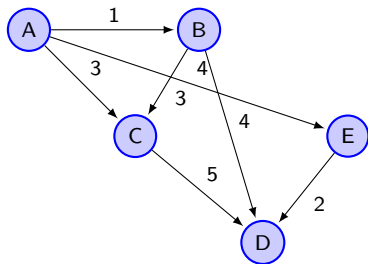
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i	Γ_i^{-1}	rank(i)
A	-	0
B	A	
C	A, B	
D	B, C, E	
E	A	



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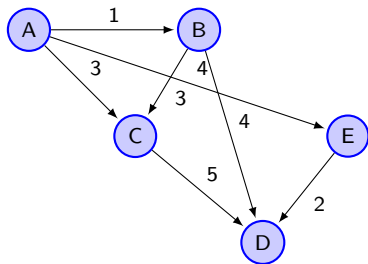
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i	Γ_i^{-1}	rank(i)
A	-	0
B		1
C	B	
D	B, C, E	
E		1



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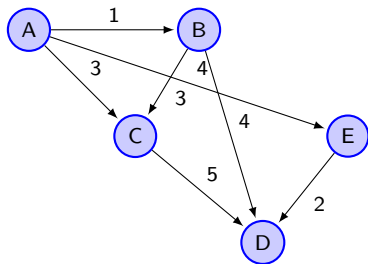
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i	Γ_i^{-1}	rank(i)
A	-	0
B	C	1
C		2
D		1
E		



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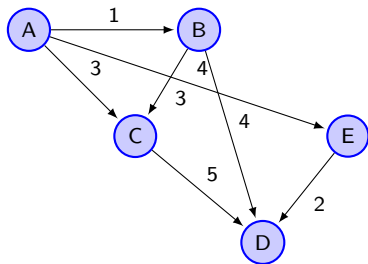
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i	Γ_i^{-1}	rank(i)
A	-	0
B		1
C		2
D		3
E		1



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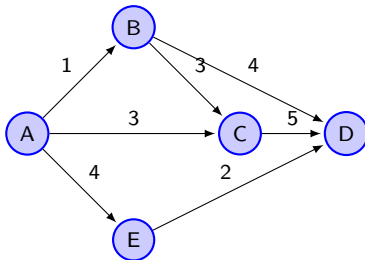
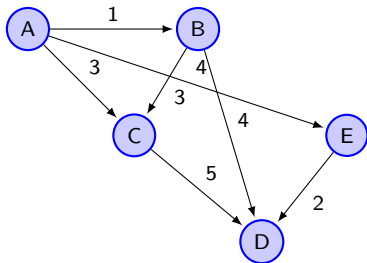
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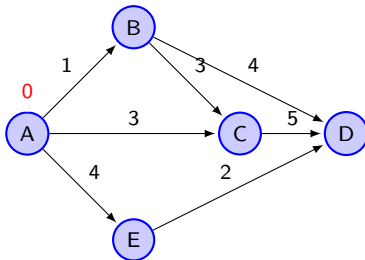
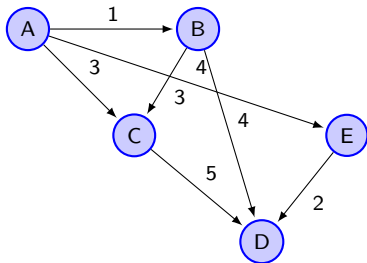
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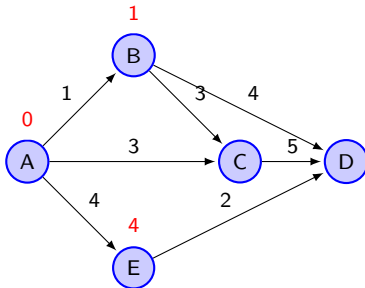
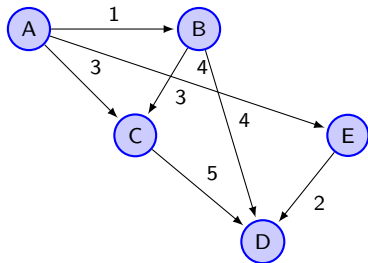
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i	Γ_i^{-1}	rank(i)
A	-	0
B		1
C		2
D		3
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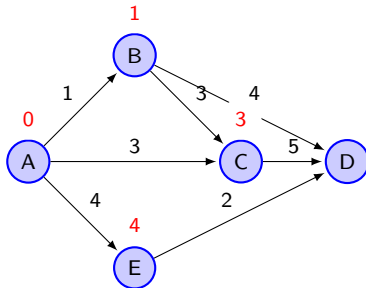
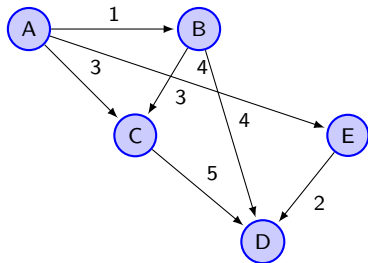
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A	-	0
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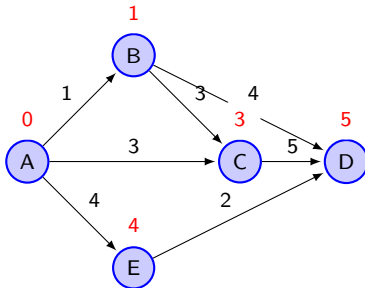
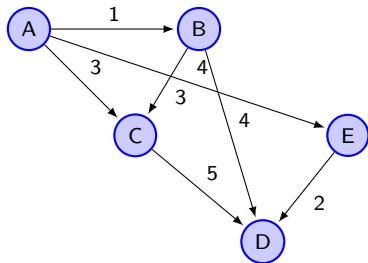
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i	Γ_i^{-1}	rank(i)
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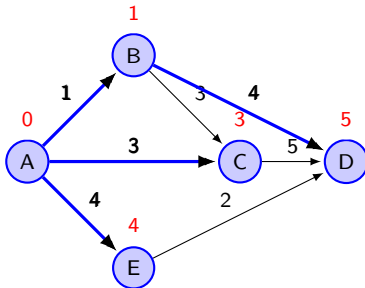
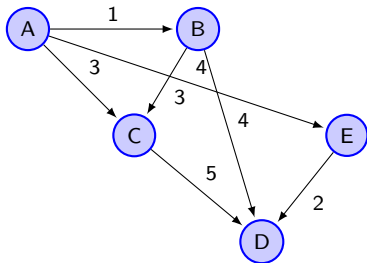
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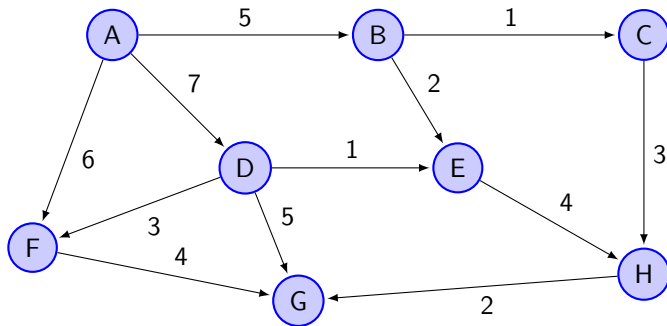
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i	Γ_i^{-1}	rank(i)
A	-	0
B		1
C		2
D		3
E		1



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Problem

A young professor in Hue is invited to teach some years in Ho Chi Minh university of technology. He decides to represent the diverse operations of his transfer by a graph and, in this purpose, establishes the list of following operations:

- A: Find a house in Ho Chi Minh city.
- B: Choose a removal man and sign a contract of move
- C: Make pack his furniture by the removal man
- D: Make transport his furniture towards Ho Chi Minh city
- E: Find an accommodation to HCM (from Hue)
- F: Transport his family to HCM
- G: Move into his new accommodation
- H: Register the children to their new school
 - I: Look for a temporary work for his wife
- J: Fit out the new accommodation and pay this arrangement with the first treatment of his wife
- K: Find a small bar to celebrate in family the success of the move and express the enjoyment to live in a good accommodation arrangement



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Application

Considering constraint of posteriority following: $A < F$; $B < C$; $C < D \wedge F$; $D < G$; $E < F$; $F < G \wedge H \wedge I$; $G < K$; $H < K$; $I < J$; $J < K$.

Approximated job processing times :

A	B	C	D	E	F	G	H	I	J	K
10	2	3	4	7	3	5	1	3	8	2



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Application

Considering constraint of posteriority following: $A < F$; $B < C$; $C < D \wedge F$; $D < G$; $E < F$; $F < G \wedge H \wedge I$; $G < K$; $H < K$; $I < J$; $J < K$.

Approximated job processing times :

A	B	C	D	E	F	G	H	I	J	K
10	2	3	4	7	3	5	1	3	8	2

Question

- Determine a schedule of the 'movement' with minimal duration.
- What happens if his new accommodation is not available before date 20? In that case, of what margin we have to make the task J ?



Question

How to determine a shortest path from u to v in graph G which traverses at most \leq a given constant number of intermediate vertices.



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Problem

- Given a set of n customers located in n cities and distances for each pair of cities, the problem involves finding a round-trip with the minimum traveling cost.
- The vehicle must visit each customer exactly once and return to its point of origin also called depot.
- The objective function is the total cost of the tour.
- \mathcal{NP} -complete: all known techniques for obtaining an exact solution require an exponentially increasing number of steps (computing resources) as the problems become larger.
- **TSP is one of the most intensely studied problems in computational mathematics, yet no effective solution method.**

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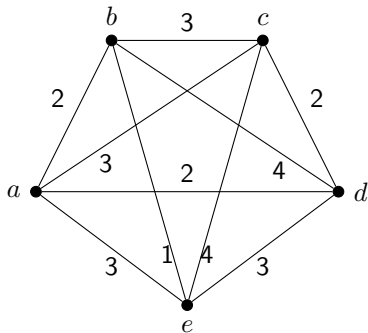
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- The total number of possible Hamilton circuit is $(n - 1)!/2$.
- For example, if there are 25 customers to visit, the total number of solutions is $24!/2 = 3.1 \times 10^{23}$.



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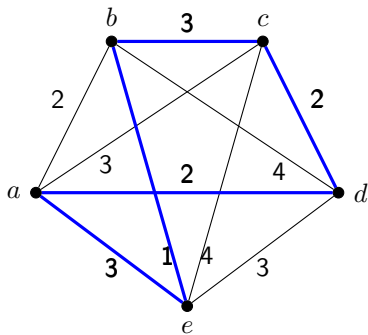
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- The total number of possible Hamilton circuit is $(n - 1)!/2$.
- For example, if there are 25 customers to visit, the total number of solutions is $24!/2 = 3.1 \times 10^{23}$.
- If the depot is located at node 1, then the optimal tour is $1 - 5 - 2 - 3 - 4 - 1$ with total cost equal to 11.



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Problem

- The vehicle routing problem involves finding a set of trips, one for each vehicle, to deliver known quantities of goods to a set of customers.
- The objective is to minimize the travel costs of all trips combined.
- There may be upper bounds on the total load of each vehicle and the total duration of its trip.
- The most basic Vehicle Routing Problem (VRP) is the single-depot capacitate VRP.

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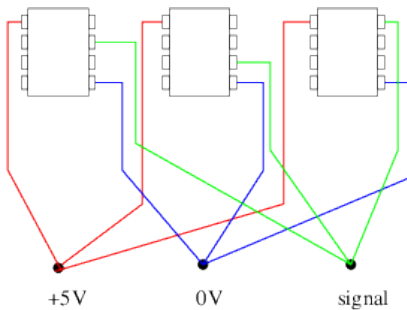
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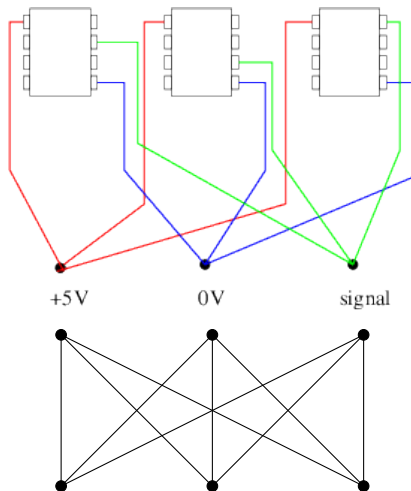
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More About Graphs

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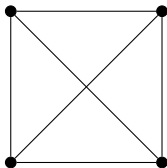
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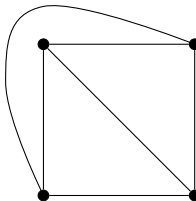
Graph Coloring

Definition

- A graph is called **planar** (*phẳng*) if it can be drawn in the plane **without any edges crossing**.
- Such a drawing is called **planar representation** (*biểu diễn phẳng*) of the graph.



K_4



K_4 with no crossing

Important Corollaries

Corollary

- If G is a **connected planar simple graph** with e edges and v vertices where $v \geq 3$, then $e \leq 3v - 6$.

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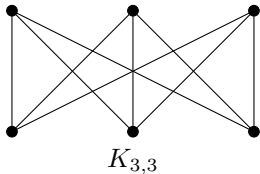
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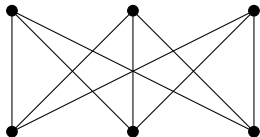
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$K_{3,3}$
Non-planar



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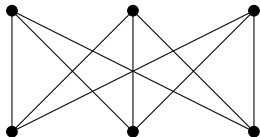
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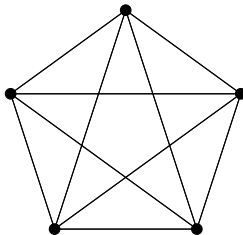
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Non-planar



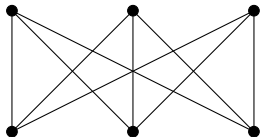
K_5



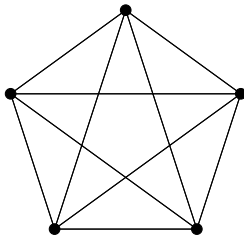
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$K_{3,3}$
Non-planar



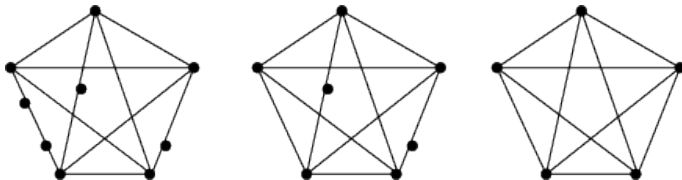
K_5
Non-planar





Definition

- Given a planar graph G , an **elementary subdivision** (*phân chia sơ cấp*) is removing an edge $\{u, v\}$ and adding a new vertex w together with edges $\{u, w\}$ and $\{w, v\}$.
- Graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are called **homeomorphic** (*đồng phôi*) if they can be obtained from the same graph by a sequence of elementary subdivisions.



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Theorem

A graph is nonplanar iff it contains a *subgraph homeomorphic to $K_{3,3}$ or K_5* .

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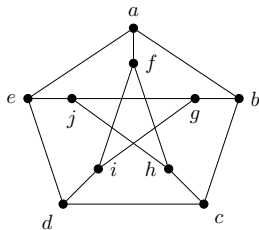
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Kuratowski's Theorem

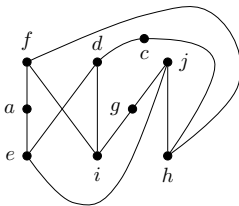
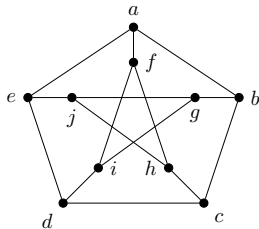
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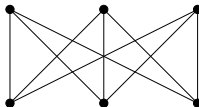
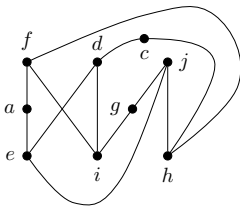
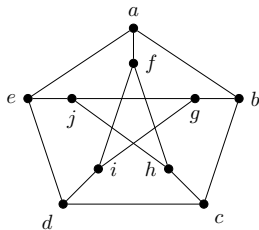
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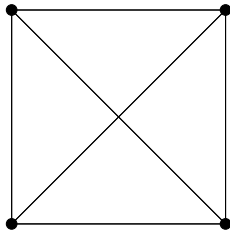
A graph is nonplanar iff it contains a *subgraph homeomorphic to $K_{3,3}$ or K_5* .



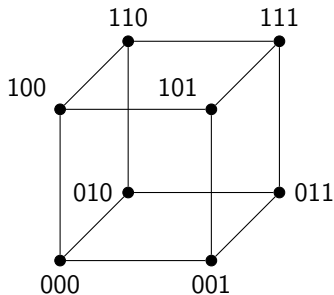
Exercise

Exercise

- Is K_4 planar?
- Is Q_3 planar?



K_4



Q_3



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Graph Coloring

Definition

- Every map can be represented by a graph. We call it **dual graph**.
- Problem of coloring the regions of a map \rightarrow coloring the vertices of the dual graph so that no two adjacent vertices have the same color.



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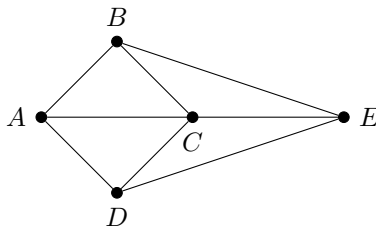
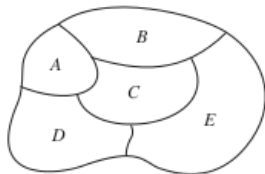
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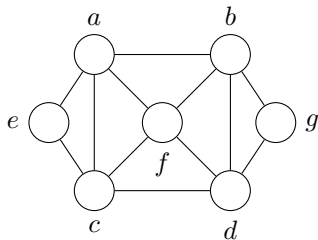
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Graph coloring

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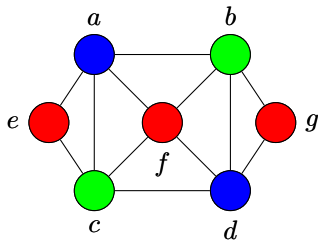
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Graph coloring

Definition

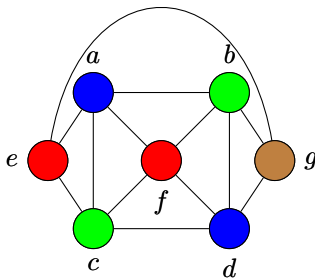
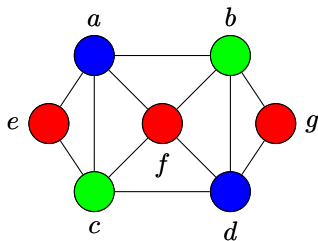
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- The **chromatic number** (*số màu*) of a graph, denoted by $\chi(G)$, is the least number of colors needed for a coloring of this graph.



Graph coloring

Definition

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Four color theorem



Theorem (Four color theorem)

*The chromatic number of a **planar graph** is no greater than four.*

- Was a conjecture in the 1850s
- Was not proved completely until 1976 by Kenneth Appel and Wolfgang Haken, using **computer**
- No proof not relying on a computer has yet been found

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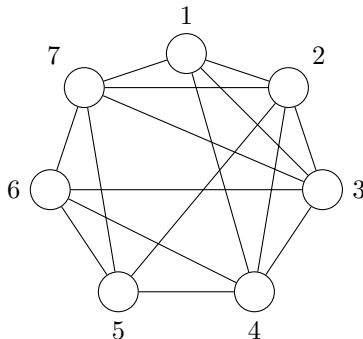
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Applications of Graph coloring

Scheduling Final Exam

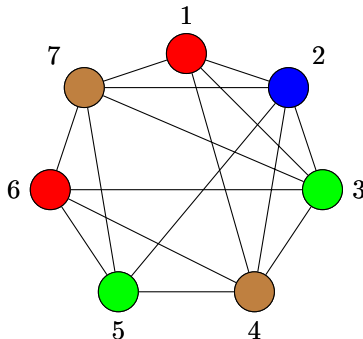
- How can the final exams at a university be scheduled so that no student has two exams at the same time?
- Suppose we have 7 finals, numbered 1 through 7.
- The pairs of courses have common students are depicted in the following graph



Applications of Graph coloring

Scheduling Final Exam

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Applications of Graph Coloring

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Other Applications

- **Frequency Assignments:** Television channels **2** through **12** are assigned to stations in North America so that no two stations within **150** miles can operate on the same channel. How can the assignment of channels be modeled by graph coloring?

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Other Applications

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- **Index Registers:** In an execution of loop, the frequently used variables should be stored in index registers to speed up. How many index registers are needed?

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