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# Existence and Ulam stability for fractional differential equations of Hilfer-Hadamard type

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## Abstract

This article deals with some existence and Ulam-Hyers-Rassias stability results for a class of functional differential equations involving the Hilfer-Hadamard fractional derivative. An application is made of a Schauder fixed point theorem for the existence of solutions. Next we prove that our problem is generalized Ulam-Hyers-Rassias stable.

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**Keywords:** functional differential equation; left-sided mixed Hadamard fractional integral; Hilfer-Hadamard fractional derivative; existence; Ulam-Hyers-Rassias stability

## 1 Introduction

Fractional differential equations have recently been applied in various areas of engineering, mathematics, physics and bio-engineering, and other applied sciences. For some fundamental results in the theory of fractional calculus and fractional ordinary and partial differential equations, we refer the reader to the monographs of Abbas *et al.* [1, 2], Samko *et al.* [3], Kilbas *et al.* [4] and Zhou [5], the papers [6–22] and the references therein.

The stability of functional equations was originally raised by Ulam [23], next by Hyers [24]. Thereafter, this type of stability is called the Ulam-Hyers stability. In 1978, Rassias [25] provided a remarkable generalization of the Ulam-Hyers stability of mappings by considering variables. The concept of stability for a functional equation arises when we replace the functional equation by an inequality which acts as a perturbation of the equation. Considerable attention has been given to the study of the Ulam-Hyers and Ulam-Hyers-Rassias stability of all kinds of functional equations; one can see the monographs of [26], and the papers of Abbas *et al.* [6, 8, 9, 27–29], Petru *et al.* [30], Rus [31, 32], and Wang *et al.* [33, 34]. More details from historical point of view, and recent developments of such stabilities are reported in [31, 35].

Recently, considerable attention has been given to the existence of solutions of initial and boundary value problems for fractional differential equations with Hilfer fractional derivative; see [36–42]. Motivated by the Hilfer fractional derivative (which interpolates the Riemann-Liouville derivative and the Caputo derivative), Qassim *et al.* [43, 44] considered a new type of fractional derivative (which interpolates the Hadamard derivative and its Caputo counterpart). Motivated by the above papers, in this article we discuss the

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existence and the Ulam stability of solutions for the following problem of Hilfer-Hadamard fractional differential equations of the form

$$\begin{cases} (^H D_1^{\alpha,\beta} u)(t) = f(t, u(t)), & t \in J := [1, T], \\ (^H I_1^{1-\gamma} u)(t)|_{t=1} = \phi, \end{cases} \quad (1)$$

where  $\alpha \in (0, 1)$ ,  $\beta \in [0, 1]$ ,  $\gamma = \alpha + \beta - \alpha\beta$ ,  $T > 1$ ,  $\phi \in \mathbb{R}$ ,  $f : J \times \mathbb{R} \rightarrow \mathbb{R}$  is a given function,  ${}^H I_1^{1-\gamma}$  is the left-sided mixed Hadamard integral of order  $1 - \gamma$ , and  ${}^H D_1^{\alpha,\beta}$  is the Hilfer-Hadamard fractional derivative of order  $\alpha$  and type  $\beta$ , introduced by Hilfer in [38].

The present paper initiates the Ulam stability for differential equations involving the Hilfer-Hadamard fractional derivative.

## 2 Preliminaries

Let  $C$  be the Banach space of all continuous functions  $v$  from  $J$  into  $\mathbb{R}$  with the supremum (uniform) norm

$$\|v\|_\infty := \sup_{t \in J} |v(t)|.$$

By  $L^1(J)$ , we denote the space of Lebesgue-integrable functions  $v : J \rightarrow \mathbb{R}$  with the norm

$$\|v\|_1 = \int_0^T |v(t)| dt.$$

As usual,  $AC(J)$  denotes the space of absolutely continuous functions from  $J$  into  $\mathbb{R}$ . We denote by  $AC^1(J)$  the space defined by

$$AC^1(J) := \left\{ w : J \rightarrow \mathbb{R} : \frac{d}{dt} w(t) \in AC(J) \right\}.$$

Let

$$\delta = t \frac{d}{dt}, \quad q > 0, \quad n = [q] + 1,$$

where  $[q]$  is the integer part of  $q$ . Define the space

$$AC_\delta^n := \{u : [1, T] \rightarrow E : \delta^{n-1}[u(t)] \in AC(J)\}.$$

Let  $\gamma \in (0, 1]$ , by  $C_{\gamma, \ln}(J)$ ,  $C_\gamma(J)$  and  $C_\gamma^1(J)$ , we denote the weighted spaces of continuous functions defined by

$$C_{\gamma, \ln}(J) = \{w(t) : (\ln t)^{1-\gamma} w(t) \in C\}$$

with the norm

$$\|w\|_{C_{\gamma, \ln}} := \sup_{t \in J} |(\ln t)^{1-\gamma} w(t)|,$$

$$C_\gamma(J) = \{w : (0, T] \rightarrow \mathbb{R} : t^{1-\gamma} w(t) \in C\}$$

with the norm

$$\|w\|_{C_\gamma} := \sup_{t \in J} |t^{1-\gamma} w(t)|,$$

and

$$C_\gamma^1(J) = \left\{ w \in C : \frac{dw}{dt} \in C_\gamma \right\}$$

with the norm

$$\|w\|_{C_\gamma^1} := \|w\|_\infty + \|w'\|_{C_\gamma}.$$

In the following, we denote  $\|w\|_{C_{\gamma,\ln}}$  by  $\|w\|_C$ .

Now, we give some results and properties of fractional calculus.

**Definition 2.1** ([2–4]; Riemann-Liouville fractional integral) The left-sided mixed Riemann-Liouville integral of order  $r > 0$  of a function  $w \in L^1(J)$  is defined by

$$(I_1^r w)(t) = \frac{1}{\Gamma(r)} \int_1^t (t-s)^{r-1} w(s) ds \quad \text{for a.e. } t \in J,$$

where  $\Gamma(\cdot)$  is the (Euler's) gamma function defined by

$$\Gamma(\xi) = \int_0^\infty t^{\xi-1} e^{-t} dt; \quad \xi > 0.$$

Notice that for all  $r, r_1, r_2 > 0$  and each  $w \in C$ , we have  $I_1^r w \in C$ , and

$$(I_1^{r_1} I_1^{r_2} w)(t) = (I_1^{r_1+r_2} w)(t) \quad \text{for a.e. } t \in J.$$

**Definition 2.2** ([2–4]; Riemann-Liouville fractional derivative) The Riemann-Liouville fractional derivative of order  $r > 0$  of a function  $w \in L^1(J)$  is defined by

$$\begin{aligned} (D_1^r w)(t) &= \left( \frac{d^n}{dt^n} I_1^{n-r} w \right)(t) \\ &= \frac{1}{\Gamma(n-r)} \frac{d^n}{dt^n} \int_1^t (t-s)^{n-r-1} w(s) ds \quad \text{for a.e. } t \in J, \end{aligned}$$

where  $n = [r] + 1$  and  $[r]$  is the integer part of  $r$ .

In particular, if  $r \in (0, 1]$ , then

$$\begin{aligned} (D_1^r w)(t) &= \left( \frac{d}{dt} I_1^{1-r} w \right)(t) \\ &= \frac{1}{\Gamma(1-r)} \frac{d}{dt} \int_1^t (t-s)^{-r} w(s) ds \quad \text{for a.e. } t \in J. \end{aligned}$$

Let  $r \in (0, 1]$ ,  $\gamma \in [0, 1)$  and  $w \in C_{1-\gamma}(J)$ . Then the following expression leads to the left inverse operator as follows:

$$(D_1^r I_1^r w)(t) = w(t) \quad \text{for all } t \in (1, T].$$

Moreover, if  $I_1^{1-r} w \in C_{1-\gamma}^1(J)$ , then the following composition is proved in [3]:

$$(I_1^r D_1^r w)(t) = w(t) - \frac{(I_1^{1-r} w)(1^+)}{\Gamma(r)} t^{r-1} \quad \text{for all } t \in (1, T].$$

**Definition 2.3** ([2–4]; Caputo fractional derivative) The Caputo fractional derivative of order  $r > 0$  of a function  $w \in L^1(J)$  is defined by

$$\begin{aligned} ({}^c D_1^r w)(t) &= \left( I_1^{n-r} \frac{d^n}{dt^n} w \right)(t) \\ &= \frac{1}{\Gamma(n-r)} \int_1^t (t-s)^{n-r-1} \frac{d^n}{ds^n} w(s) ds \quad \text{for a.e. } t \in J. \end{aligned}$$

In particular, if  $r \in (0, 1]$ , then

$$\begin{aligned} ({}^c D_1^r w)(t) &= \left( I_1^{1-r} \frac{d}{dt} w \right)(t) \\ &= \frac{1}{\Gamma(1-r)} \int_1^t (t-s)^{-r} \frac{d}{ds} w(s) ds \quad \text{for a.e. } t \in J. \end{aligned}$$

Let us recall some definitions and properties of Hadamard fractional integration and differentiation. We refer to [4, 45] for a more detailed analysis.

**Definition 2.4** ([4, 45]; Hadamard fractional integral) The Hadamard fractional integral of order  $q > 0$  for a function  $g \in L^1(I, E)$  is defined as

$$({}^H I_1^q g)(x) = \frac{1}{\Gamma(q)} \int_1^x \left( \ln \frac{x}{s} \right)^{q-1} \frac{g(s)}{s} ds,$$

provided the integral exists.

**Example 2.5** Let  $0 < q < 1$ . Then

$$({}^H I_1^q \ln t) = \frac{1}{\Gamma(2+q)} (\ln t)^{1+q} \quad \text{for a.e. } t \in [0, e].$$

Set

$$\delta = x \frac{d}{dx}, \quad q > 0, \quad n = [q] + 1$$

and

$$\text{AC}_{\delta}^n := \{u : [1, T] \rightarrow E : \delta^{n-1}[u(x)] \in \text{AC}(J)\}.$$

Analogous to the Riemann-Liouville fractional calculus, the Hadamard fractional derivative is defined in terms of the Hadamard fractional integral in the following way.

**Definition 2.6** ([4, 45]; Hadamard fractional derivative) The Hadamard fractional derivative of order  $q > 0$  applied to the function  $w \in AC_{\delta}^n$  is defined as

$$({}^H D_1^q w)(x) = \delta^n ({}^H I_1^{n-q} w)(x).$$

In particular, if  $q \in (0, 1]$ , then

$$({}^H D_1^q w)(x) = \delta ({}^H I_1^{1-q} w)(x).$$

**Example 2.7** Let  $0 < q < 1$ . Then

$${}^H D_1^q \ln t = \frac{1}{\Gamma(2-q)} (\ln t)^{1-q} \quad \text{for a.e. } t \in [0, e].$$

It has been proved (see, e.g., Kilbas [46], Theorem 4.8) that in the space  $L^1(J)$  the Hadamard fractional derivative is the left-inverse operator to the Hadamard fractional integral, i.e.,

$$({}^H D_1^q)({}^H I_1^q w)(x) = w(x).$$

From Theorem 2.3 of [4], we have

$$({}^H I_1^q)({}^H D_1^q w)(x) = w(x) - \frac{({}^H I_1^{1-q} w)(1)}{\Gamma(q)} (\ln x)^{q-1}.$$

Analogous to the Hadamard fractional calculus, the Caputo-Hadamard fractional derivative is defined in the following way.

**Definition 2.8** (Caputo-Hadamard fractional derivative) The Caputo-Hadamard fractional derivative of order  $q > 0$  applied to the function  $w \in AC_{\delta}^n$  is defined as

$$({}^{Hc} D_1^q w)(x) = ({}^H I_1^{n-q} \delta^n w)(x).$$

In particular, if  $q \in (0, 1]$ , then

$$({}^{Hc} D_1^q w)(x) = ({}^H I_1^{1-q} \delta w)(x).$$

In [38], Hilfer studied applications of a generalized fractional operator having the Riemann-Liouville and the Caputo derivatives as specific cases (see also [39–41]).

**Definition 2.9** (Hilfer fractional derivative) Let  $\alpha \in (0, 1)$ ,  $\beta \in [0, 1]$ ,  $w \in L^1(J)$ ,  $I_1^{(1-\alpha)(1-\beta)} w \in AC^1(J)$ . The Hilfer fractional derivative of order  $\alpha$  and type  $\beta$  of  $w$  is defined as

$$({}^H D_1^{\alpha,\beta} w)(t) = \left( I_1^{\beta(1-\alpha)} \frac{d}{dt} I_1^{(1-\alpha)(1-\beta)} w \right)(t) \quad \text{for a.e. } t \in J. \quad (2)$$

**Properties** Let  $\alpha \in (0, 1)$ ,  $\beta \in [0, 1]$ ,  $\gamma = \alpha + \beta - \alpha\beta$ , and  $w \in L^1(J)$ .

1. The operator  $(D_1^{\alpha, \beta} w)(t)$  can be written as

$$(D_1^{\alpha, \beta} w)(t) = \left( I_1^{\beta(1-\alpha)} \frac{d}{dt} I_1^{1-\gamma} w \right)(t) = (I_1^{\beta(1-\alpha)} D_1^\gamma w)(t) \quad \text{for a.e. } t \in J.$$

Moreover, the parameter  $\gamma$  satisfies

$$\gamma \in (0, 1], \quad \gamma \geq \alpha, \quad \gamma > \beta, \quad 1 - \gamma < 1 - \beta(1 - \alpha).$$

2. The generalization (2) for  $\beta = 0$  coincides with the Riemann-Liouville derivative and for  $\beta = 1$  with the Caputo derivative.

$$D_1^{\alpha, 0} = D_1^\alpha, \quad \text{and} \quad D_1^{\alpha, 1} = {}^c D_1^\alpha.$$

3. If  $D_1^{\beta(1-\alpha)} w$  exists and in  $L^1(J)$ , then

$$(D_1^{\alpha, \beta} I_1^\alpha w)(t) = (I_1^{\beta(1-\alpha)} D_1^{\beta(1-\alpha)} w)(t) \quad \text{for a.e. } t \in J.$$

Furthermore, if  $w \in C_\gamma(J)$  and  $I_1^{1-\beta(1-\alpha)} w \in C_\gamma^1(J)$ , then

$$(D_1^{\alpha, \beta} I_1^\alpha w)(t) = w(t) \quad \text{for a.e. } t \in J.$$

4. If  $D_1^\gamma w$  exists and in  $L^1(J)$ , then

$$(I_1^\alpha D_1^{\alpha, \beta} w)(t) = (I_1^\gamma D_1^\gamma w)(t) = w(t) - \frac{I_1^{1-\gamma}(1^+)}{\Gamma(\gamma)} t^{\gamma-1} \quad \text{for a.e. } t \in J.$$

From the Hadamard fractional integral, the Hilfer-Hadamard fractional derivative (introduced for the first time in [43]) is defined in the following way.

**Definition 2.10** (Hilfer-Hadamard fractional derivative) Let  $\alpha \in (0, 1)$ ,  $\beta \in [0, 1]$ ,  $\gamma = \alpha + \beta - \alpha\beta$ ,  $w \in L^1(J)$ , and  ${}^H I_1^{(1-\alpha)(1-\beta)} w \in AC^1(J)$ . The Hilfer-Hadamard fractional derivative of order  $\alpha$  and type  $\beta$  applied to the function  $w$  is defined as

$$\begin{aligned} ({}^H D_1^{\alpha, \beta} w)(t) &= ({}^H I_1^{\beta(1-\alpha)} ({}^H D_1^\gamma w))(t) \\ &= ({}^H I_1^{\beta(1-\alpha)} \delta ({}^H I_1^{1-\gamma} w))(t) \quad \text{for a.e. } t \in J. \end{aligned} \tag{3}$$

This new fractional derivative (3) may be viewed as interpolating the Hadamard fractional derivative and the Caputo-Hadamard fractional derivative. Indeed, for  $\beta = 0$ , this derivative reduces to the Hadamard fractional derivative, and when  $\beta = 1$ , we recover the Caputo-Hadamard fractional derivative.

$${}^H D_1^{\alpha, 0} = {}^H D_1^\alpha, \quad \text{and} \quad {}^H D_1^{\alpha, 1} = {}^{Hc} D_1^\alpha.$$

From Theorem 21 in [44], we concluded the following lemma.

**Lemma 2.11** Let  $f : I \times E \rightarrow E$  be such that  $f(\cdot, u(\cdot)) \in C_{\gamma, \ln}(J)$  for any  $u \in C_{\gamma, \ln}(J)$ . Then problem (1) is equivalent to the problem of the solutions of the Volterra integral equation

$$u(t) = \frac{\phi}{\Gamma(\gamma)} (\ln t)^{\gamma-1} + \left( {}^H I_1^\alpha f(\cdot, u(\cdot)) \right)(t).$$

Now, we consider the Ulam stability for problem (1). Let  $\epsilon > 0$  and  $\Phi : I \rightarrow [0, \infty)$  be a continuous function. We consider the following inequalities:

$$\left| ({}^H D_1^{\alpha, \beta} u)(t) - f(t, u(t)) \right| \leq \epsilon; \quad t \in J. \quad (4)$$

$$\left| ({}^H D_1^{\alpha, \beta} u)(t) - f(t, u(t)) \right| \leq \Phi(t); \quad t \in J. \quad (5)$$

$$\left| ({}^H D_1^{\alpha, \beta} u)(t) - f(t, u(t)) \right| \leq \epsilon \Phi(t); \quad t \in J. \quad (6)$$

**Definition 2.12** ([2, 31]) Problem (1) is Ulam-Hyers stable if there exists a real number  $c_f > 0$  such that for each  $\epsilon > 0$  and for each solution  $u \in C_{\gamma, \ln}$  of inequality (4) there exists a solution  $v \in C_{\gamma, \ln}$  of (1) with

$$|u(t) - v(t)| \leq \epsilon c_f; \quad t \in J.$$

**Definition 2.13** ([2, 31]) Problem (1) is generalized Ulam-Hyers stable if there exists  $c_f : C([0, \infty), [0, \infty))$  with  $c_f(0) = 0$  such that for each  $\epsilon > 0$  and for each solution  $u \in C_{\gamma, \ln}$  of inequality (4) there exists a solution  $v \in C_{\gamma, \ln}$  of (1) with

$$|u(t) - v(t)| \leq c_f(\epsilon); \quad t \in J.$$

**Definition 2.14** ([2, 31]) Problem (1) is Ulam-Hyers-Rassias stable with respect to  $\Phi$  if there exists a real number  $c_{f, \Phi} > 0$  such that for each  $\epsilon > 0$  and for each solution  $u \in C_{\gamma, \ln}$  of inequality (6) there exists a solution  $v \in C_{\gamma, \ln}$  of (1) with

$$|u(t) - v(t)| \leq \epsilon c_{f, \Phi} \Phi(t); \quad t \in J.$$

**Definition 2.15** ([2, 31]) Problem (1) is generalized Ulam-Hyers-Rassias stable with respect to  $\Phi$  if there exists a real number  $c_{f, \Phi} > 0$  such that for each solution  $u \in C_{\gamma, \ln}$  of inequality (5) there exists a solution  $v \in C_{\gamma, \ln}$  of (1) with

$$|u(t) - v(t)| \leq c_{f, \Phi} \Phi(t); \quad t \in J.$$

**Remark 2.16** It is clear that

- (i) Definition 2.12  $\Rightarrow$  Definition 2.13,
- (ii) Definition 2.14  $\Rightarrow$  Definition 2.15,
- (iii) Definition 2.14 for  $\Phi(\cdot) = 1 \Rightarrow$  Definition 2.12.

One can have similar remarks for inequalities (4) and (6).

In the sequel we will make use of the following fixed point theorem.

**Theorem 2.17** (Schauder fixed point theorem [47]) Let  $E$  be a Banach space and  $Q$  be a nonempty bounded convex and closed subset of  $E$ , and  $N : Q \rightarrow Q$  is a compact and continuous map. Then  $N$  has at least one fixed point in  $Q$ .

### 3 Existence of solutions

Let us start by defining what we mean by a solution of problem (1).

**Definition 3.1** By a solution of problem (1) we mean a measurable function  $u \in C_{\gamma, \ln}$  that satisfies the condition  $(^H I_1^{1-\gamma} u)(1^+) = \phi$  and the equation  $(^H D_1^{\alpha, \beta} u)(t) = f(t, u(t))$  on  $J$ .

The following hypotheses will be used in the sequel.

- ( $H_1$ ) The function  $t \mapsto f(t, u)$  is measurable on  $I$  for each  $u \in C_{\gamma, \ln}$ , and the function  $u \mapsto f(t, u)$  is continuous on  $C_{\gamma, \ln}$  for a.e.  $t \in J$ ,
- ( $H_2$ ) There exists a continuous function  $p : I \rightarrow [0, \infty)$  such that

$$|f(t, u)| \leq \frac{p(t)}{1 + |u|} |u| \quad \text{for a.e. } t \in J \text{ and each } u \in \mathbb{R}.$$

Set

$$p^* = \sup_{t \in J} p(t).$$

Now, we shall prove the following theorem concerning the existence of solutions of problem (1).

**Theorem 3.2** Assume that hypotheses ( $H_1$ ) and ( $H_2$ ) hold. Then problem (1) has at least one solution defined on  $J$ .

*Proof* Consider the operator  $N : C_{\gamma, \ln} \rightarrow C_{\gamma, \ln}$  defined by

$$(Nu)(t) = \frac{\phi}{\Gamma(\gamma)} (\ln t)^{\gamma-1} + \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{f(s, u(s))}{s \Gamma(\alpha)} ds. \quad (7)$$

Clearly, the fixed points of the operator  $N$  are solution of problem (1).

For any  $u \in C_{\gamma, \ln}$  and each  $t \in J$ , we have

$$\begin{aligned} |(\ln t)^{1-\gamma} (Nu)(t)| &\leq \frac{|\phi|}{\Gamma(\gamma)} + \frac{(\ln t)^{1-\gamma}}{\Gamma(\alpha)} \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} |f(s, u(s))| \frac{ds}{s} \\ &\leq \frac{|\phi|}{\Gamma(\gamma)} + \frac{(\ln t)^{1-\gamma}}{\Gamma(\alpha)} \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} p(s) \frac{ds}{s} \\ &\leq \frac{|\phi|}{\Gamma(\gamma)} + \frac{p^*(\ln T)^{1-\gamma}}{\Gamma(\alpha)} \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{ds}{s} \\ &\leq \frac{|\phi|}{\Gamma(\gamma)} + \frac{p^*(\ln T)^{1-\gamma+\alpha}}{\Gamma(1+\alpha)}. \end{aligned}$$

Thus

$$\|N(u)\|_C \leq \frac{|\phi|}{\Gamma(\gamma)} + \frac{p^*(\ln T)^{1-\gamma+\alpha}}{\Gamma(1+\alpha)} := R. \quad (8)$$

This proves that  $N$  transforms the ball  $B_R := B(0, R) = \{w \in C_{\gamma, \ln} : \|w\|_C \leq R\}$  into itself. We shall show that the operator  $N : B_R \rightarrow B_R$  satisfies all the assumptions of Theorem 2.17. The proof will be given in several steps.

*Step 1.*  $N : B_R \rightarrow B_R$  is continuous.

Let  $\{u_n\}_{n \in \mathbb{N}}$  be a sequence such that  $u_n \rightarrow u$  in  $B_R$ . Then, for each  $t \in J$ , we have

$$\begin{aligned} & |(\ln t)^{1-\gamma}(Nu_n)(t) - (\ln t)^{1-\gamma}(Nu)(t)| \\ & \leq \frac{(\ln t)^{1-\gamma}}{\Gamma(\alpha)} \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} |f(s, u_n(s)) - f(s, u(s))| \frac{ds}{s}. \end{aligned} \quad (9)$$

Since  $u_n \rightarrow u$  as  $n \rightarrow \infty$  and  $f$  is continuous, by the Lebesgue dominated convergence theorem, equation (9) implies

$$\|N(u_n) - N(u)\|_C \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

*Step 2.*  $N(B_R)$  is uniformly bounded.

This is clear since  $N(B_R) \subset B_R$  and  $B_R$  is bounded.

*Step 3.*  $N(B_R)$  is equicontinuous.

Let  $t_1, t_2 \in J$ ,  $t_1 < t_2$  and let  $u \in B_R$ . Thus, we have

$$\begin{aligned} & |(\ln t_2)^{1-\gamma}(Nu)(t_2) - (\ln t_1)^{1-\gamma}(Nu)(t_1)| \\ & \leq \left| (\ln t_2)^{1-\gamma} \int_1^{t_2} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} \frac{f(s, u(s))}{s\Gamma(\alpha)} ds - (\ln t_1)^{1-\gamma} \int_1^{t_1} \left( \ln \frac{t_1}{s} \right)^{\alpha-1} \frac{f(s, u(s))}{s\Gamma(\alpha)} ds \right| \\ & \leq (\ln t_2)^{1-\gamma} \int_{t_1}^{t_2} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} \frac{|f(s, u(s))|}{s\Gamma(\alpha)} ds \\ & \quad + \int_1^{t_1} \left| (\ln t_2)^{1-\gamma} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} - (\ln t_1)^{1-\gamma} \left( \ln \frac{t_1}{s} \right)^{\alpha-1} \right| \frac{|f(s, u(s))|}{s\Gamma(\alpha)} ds \\ & \leq (\ln t_2)^{1-\gamma} \int_{t_1}^{t_2} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} \frac{p(s)}{s\Gamma(\alpha)} ds \\ & \quad + \int_1^{t_1} \left| (\ln t_2)^{1-\gamma} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} - (\ln t_1)^{1-\gamma} \left( \ln \frac{t_1}{s} \right)^{\alpha-1} \right| \frac{p(s)}{s\Gamma(\alpha)} ds. \end{aligned}$$

Hence, we get

$$\begin{aligned} & |(\ln t_2)^{1-\gamma}(Nu)(t_2) - (\ln t_1)^{1-\gamma}(Nu)(t_1)| \\ & \leq \frac{p_*(\ln T)^{1-\gamma+\alpha}}{\Gamma(1+\alpha)} \left( \ln \frac{t_2}{t_1} \right)^\alpha \\ & \quad + \frac{p_*}{\Gamma(\alpha)} \int_1^{t_1} \left| (\ln t_2)^{1-\gamma} \left( \ln \frac{t_2}{s} \right)^{\alpha-1} - (\ln t_1)^{1-\gamma} \left( \ln \frac{t_1}{s} \right)^{\alpha-1} \right| ds. \end{aligned}$$

As  $t_1 \rightarrow t_2$ , the right-hand side of the above inequality tends to zero.

As a consequence of Steps 1 to 3 together with the Arzelá-Ascoli theorem, we can conclude that  $N$  is continuous and compact. From an application of Schauder's theorem (Theorem 2.17), we deduce that  $N$  has at least a fixed point  $u$  which is a solution of problem (1).  $\square$

#### 4 Ulam-Hyers-Rassias stability

Now, we are concerned with the generalized Ulam-Hyers-Rassias stability of our problem (1).

**Theorem 4.1** Assume that hypotheses  $(H_1)$ ,  $(H_2)$  and the following hypotheses hold.

$(H_3)$  There exists  $\lambda_\phi > 0$  such that for each  $t \in J$ , we have

$$({}^H I_1^\alpha \Phi)(t) \leq \lambda_\phi \Phi(t);$$

$(H_4)$  There exists  $q \in C(J, [0, \infty))$  such that for each  $t \in J$ , we have

$$p(t) \leq q(t)\Phi(t).$$

Then problem (1) is generalized Ulam-Hyers-Rassias stable.

*Proof* Consider the operator  $N : C_{\gamma, \ln} \rightarrow C_{\gamma, \ln}$  defined in (7). Let  $u$  be a solution of inequality (5), and let us assume that  $v$  is a solution of problem (1). Thus, we have

$$v(t) = \frac{\phi}{\Gamma(\gamma)} (\ln t)^{\gamma-1} + \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{f(s, v(s))}{s \Gamma(\alpha)} ds.$$

From inequality (5), for each  $t \in J$ , we have

$$\left| u(t) - \frac{\phi}{\Gamma(\gamma)} (\ln t)^{\gamma-1} - \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{f(s, u(s))}{s \Gamma(\alpha)} ds \right| \leq ({}^H I_1^\alpha \Phi)(t).$$

Set

$$q^* = \sup_{t \in J} q(t).$$

From hypotheses  $(H_3)$  and  $(H_4)$ , for each  $t \in J$ , we get

$$\begin{aligned} |u(t) - v(t)| &\leq \left| u(t) - \frac{\phi}{\Gamma(\gamma)} (\ln t)^{\gamma-1} - \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{f(s, u(s))}{s \Gamma(\alpha)} ds \right| \\ &\quad + \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{|f(s, u(s)) - f(s, v(s))|}{s \Gamma(\alpha)} ds \\ &\leq ({}^H I_1^\alpha \Phi)(t) + \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{2q^* \Phi(s)}{s \Gamma(\alpha)} ds \\ &\leq \lambda_\phi \Phi(t) + 2q^* ({}^H I_1^\alpha \Phi)(t) \\ &\leq [1 + 2q^*] \lambda_\phi \Phi(t) \\ &:= c_{f, \Phi} \Phi(t). \end{aligned}$$

Hence, problem (1) is generalized Ulam-Hyers-Rassias stable.  $\square$

In the sequel, we will use the following theorem.

**Theorem 4.2** Let  $(\Omega, d)$  be a generalized complete metric space and  $\Theta : \Omega \rightarrow \Omega$  be a strictly contractive operator with a Lipschitz constant  $L < 1$ . If there exists a nonnegative integer  $k$  such that  $d(\Theta^{k+1}x, \Theta^kx) < \infty$  for some  $x \in \Omega$ , then the following propositions hold true:

- (A) The sequence  $(\Theta^k x)_{n \in \mathbb{N}}$  converges to a fixed point  $x^*$  of  $\Theta$ ;
- (B)  $x^*$  is the unique fixed point of  $\Theta$  in  $\Omega^* = \{y \in \Omega \mid d(\Theta^k x, y) < \infty\}$ ;
- (C) If  $y \in \Omega^*$ , then  $d(y, x^*) \leq \frac{1}{1-L} d(y, \Theta x)$ .

Let  $X = X(I, \mathbb{R})$  be the metric space, with the metric

$$d(u, v) = \sup_{t \in J} \frac{\|u(t) - v(t)\|_C}{\Phi(t)}.$$

**Theorem 4.3** Assume that  $(H_3)$  and the following hypothesis hold.

$(H_5)$  There exists  $\varphi \in C(J, [0, \infty))$  such that for each  $t \in J$  and all  $u, v \in \mathbb{R}$ , we have

$$|f(t, u) - f(t, v)| \leq (\ln t)^{1-\gamma} \varphi(t) \Phi(t) |u - v|.$$

If

$$L := (\ln T)^{1-\gamma} \varphi^* \lambda_\phi < 1, \quad (10)$$

where  $\varphi^* = \sup_{t \in J} \varphi(t)$ , then there exists a unique solution  $u_0$  of problem (1), and problem (1) is generalized Ulam-Hyers-Rassias stable. Furthermore, we have

$$|u(t) - u_0(t)| \leq \frac{\Phi(t)}{1-L}.$$

*Proof* Let  $N : C_{\gamma, \ln} \rightarrow C_{\gamma, \ln}$  be the operator defined in (7). Applying Theorem 4.2, we have

$$\begin{aligned} |(Nu)(t) - (Nv)(t)| &\leq \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{|f(s, u(s)) - f(s, v(s))|}{s \Gamma(\alpha)} ds \\ &\leq \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{\varphi(s) \Phi(s) |(\ln s)^{1-\gamma} u(s) - (\ln s)^{1-\gamma} v(s)|}{s \Gamma(\alpha)} ds \\ &\leq \int_1^t \left( \ln \frac{t}{s} \right)^{\alpha-1} \frac{\varphi^* \Phi(s) \|u - v\|_C}{s \Gamma(\alpha)} ds \\ &\leq \varphi^* ({}^H I_1^\alpha \Phi)(t) \|u - v\|_C \\ &\leq \varphi^* \lambda_\phi \Phi(t) \|u - v\|_C. \end{aligned}$$

Thus

$$|(\ln t)^{1-\gamma} (Nu)(t) - (\ln t)^{1-\gamma} (Nv)(t)| \leq (\ln T)^{1-\gamma} \varphi^* \lambda_\phi \Phi(t) \|u - v\|_C.$$

Hence, we get

$$d(N(u), N(v)) = \sup_{t \in J} \frac{\|(Nu)(t) - (Nv)(t)\|_C}{\Phi(t)} \leq L \|u - v\|_C,$$

from which we conclude the theorem.  $\square$

## 5 An example

As an application of our results, we consider the following problem of Hilfer-Hadamard fractional differential equation of the form

$$\begin{cases} (^H D_1^{\frac{1}{2}, \frac{1}{2}} u)(t) = f(t, u(t)); & t \in [1, e], \\ (^H I_1^{\frac{1}{4}} u)(t)|_{t=1} = 0, \end{cases} \quad (11)$$

where

$$\begin{cases} f(t, u) = \frac{(t-1)^{-\frac{1}{4}} \sin(t-1)}{64(1+\sqrt{t-1})(1+|u|)}; & t \in (1, e], u \in \mathbb{R}, \\ f(1, u) = 0; & u \in \mathbb{R}. \end{cases}$$

Clearly, the function  $f$  is continuous.

Hypothesis  $(H_2)$  is satisfied with

$$\begin{cases} p(t) = \frac{(t-1)^{-\frac{1}{4}} |\sin(t-1)|}{64(1+\sqrt{t-1})}; & t \in (1, e], \\ p(1) = 0. \end{cases}$$

Hence, Theorem 3.2 implies that problem (11) has at least one solution defined on  $[1, e]$ .

Also, hypothesis  $(H_3)$  is satisfied with

$$\Phi(t) = e^3, \quad \text{and} \quad \lambda_\Phi = \frac{2}{\sqrt{\pi}}.$$

Indeed, for each  $t \in [1, e]$ , we get

$$\begin{aligned} (^H I_1^\alpha \Phi)(t) &\leq \frac{2e^3}{\sqrt{\pi}} \\ &= \lambda_\Phi \Phi(t). \end{aligned}$$

Consequently, Theorem 4.1 implies that problem (11) is generalized Ulam-Hyers-Rassias stable.

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### Competing interests

The authors declare that they have no competing interests.

### Authors' contributions

SA, MB, and JEL contributed to Sections 1, 2, 3, and 4. AA and YZ contributed to Sections 1 and 5.

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