

1	2	3	4	5	6
A	<div>PGA2350B</div> <div>File: PGA2350B.kicad_sch</div> <div>Stepper Output</div>	<div>Ethernet</div> <div>File: Ethernet.kicad_sch</div> <div>Misc IO</div>			A
	<div></div> <div>File: StepperOutput.kicad_sch</div> <div>Spindle</div>	<div></div> <div>File: MiscIO.kicad_sch</div> <div>Limit and Control Inputs</div>			
B	<div></div> <div>File: Spindle.kicad_sch</div> <div>DigitalIO and Relays</div>	<div></div> <div>File: LimitandControlInputs.kicad_sch</div> <div>Power</div>			B
	<div></div> <div>File: DigitalIO and Relays.kicad_sch</div> <div>Servo_error</div>	<div></div> <div>File: power.kicad_sch</div>			
	<div></div> <div>File: servo_error.kicad_sch</div>				
C					C
D					D
1	2	3	4	5	6

Brookwood Design

Sheet: /  
File: PGA2350.kicad\_sch

Title: **RP23U5XBB**

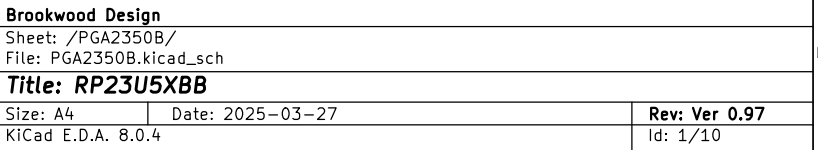
Size: A4

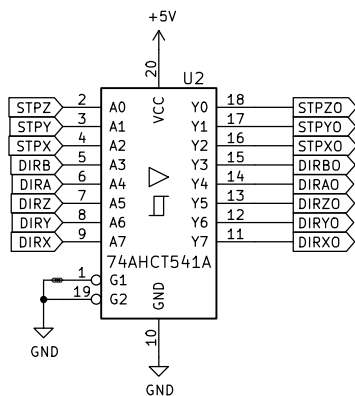
Date: 2025-03-27

Rev: **Ver 1.0**

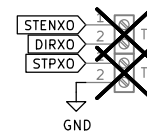
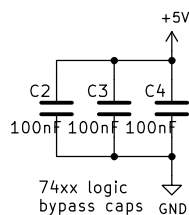
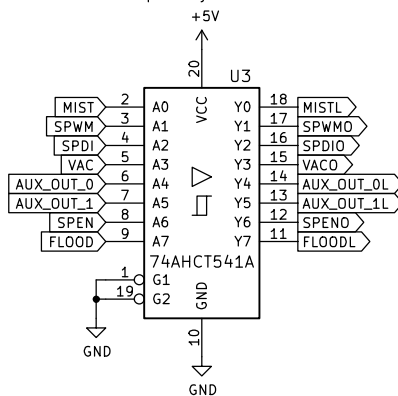
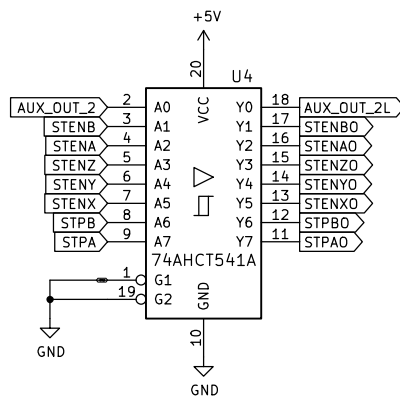
KiCad E.D.A. 8.0.4

Id: 1/10

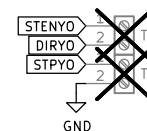




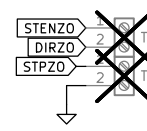
Digital output section. 3.3V inputs, 5V outputs. Use of AHCT logic allows this. Drive capability of 8mA.



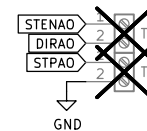
X Axis driver interface.



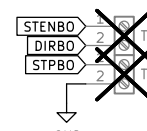
Y Axis driver interface.



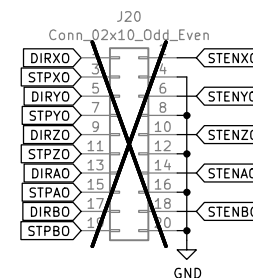
Z Axis driver interface.



A Axis driver interface.



B Axis driver interface.



Brookwood Design

Sheet: /Stepper Output/  
File: StepperOutput.kicad\_sch

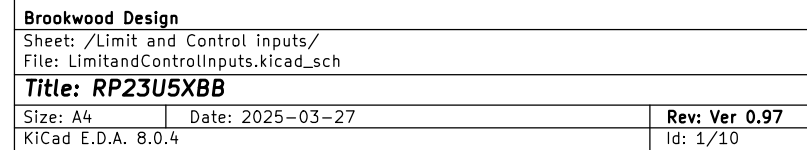
Title: RP23U5XBB

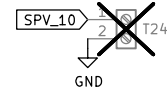
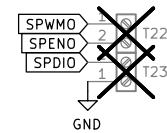
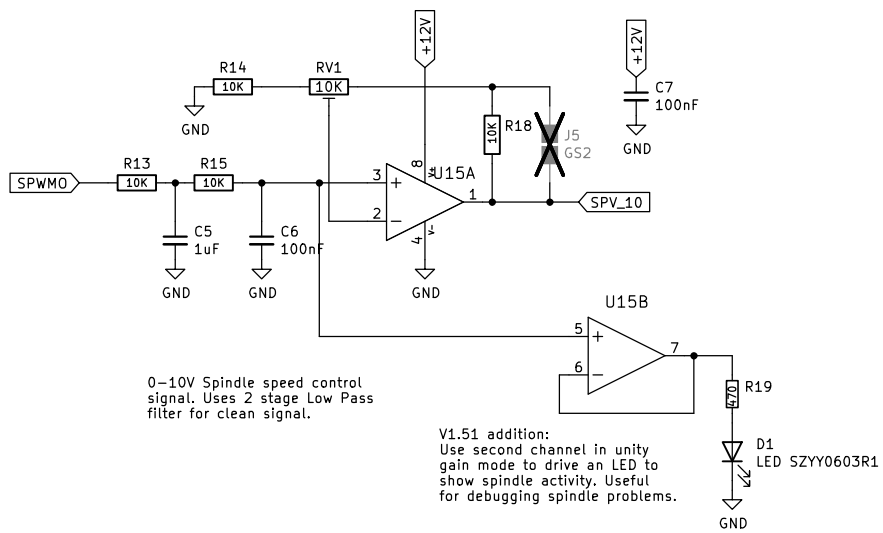
Size: A4 Date: 2025-03-27

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Rev: Ver 0.97

Id: 1/10





Brookwood Design

Sheet: /Spindle/  
File: Spindle.kicad\_sch

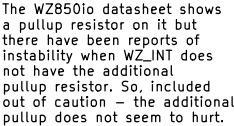
**Title: RP23U5XBB**

Size: A4 Date: 2025-03-27

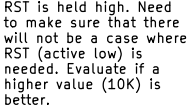
KiCad E.D.A. 8.0.4

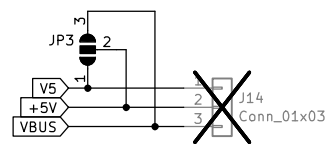
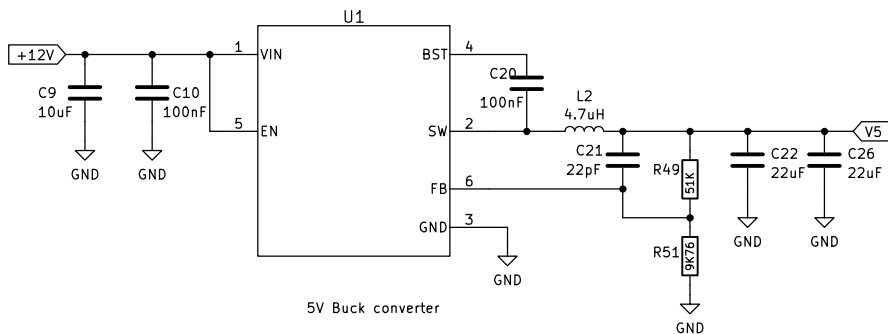
**Rev: Ver 0.97**

Id: 1/10

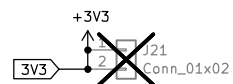


Yes, it is confusing – just make sure the module has a W5500 on it.

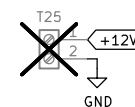
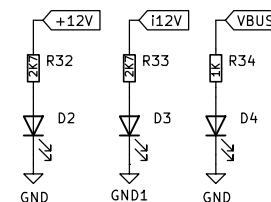
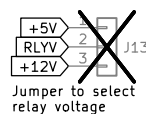
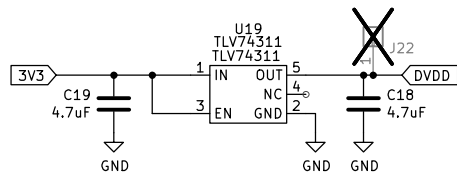
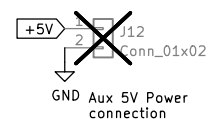
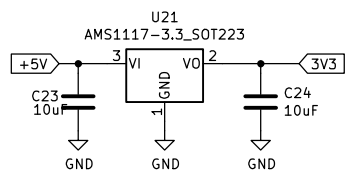




5V bypass to allow USB VBUS +5V for testing and current monitoring. Remove for production PCB? Convert to solder jumper?



3V3 bypass to allow external 3.3V for testing. Also, allows for current draw monitoring. Remove for production PCB and connect to +3V3.



Brookwood Design

Sheet: /Power/  
File: power.kicad\_sch

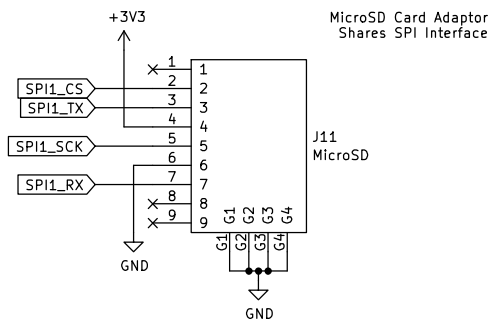
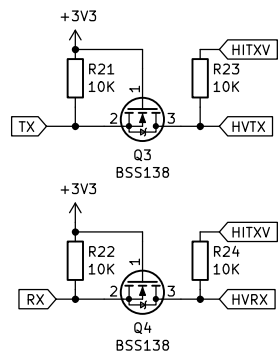
Title: RP23U5XBB

Size: A4 Date: 2025-03-27

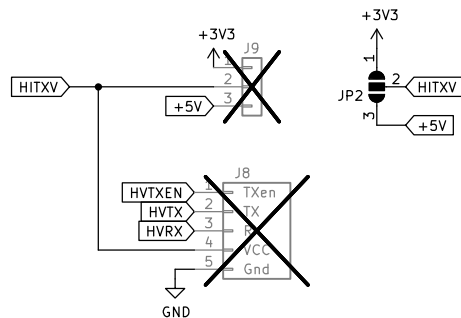
KiCad E.D.A. 8.0.4

Rev: Ver 0.97

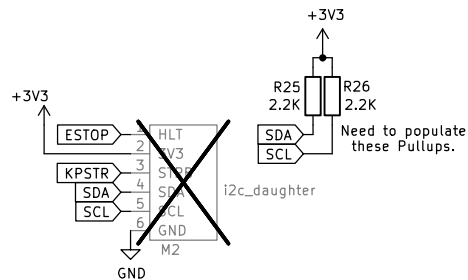
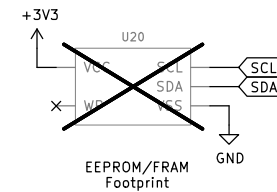
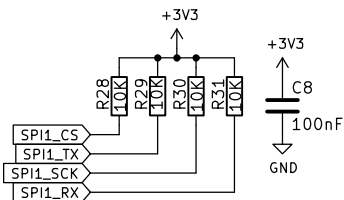
Id: 1/10



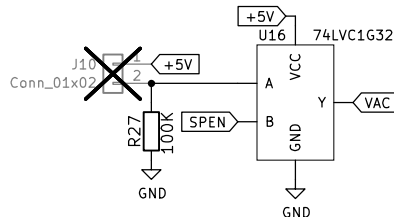
~~X~~ H1  
~~X~~ H2  
~~X~~ H3  
~~X~~ H4



UART 0 support. Adds standard mounting holes.



I2C Daughter card header. Adds standard mounting holes.



Independent Control for Dust Extractor. A switch attached to the pin header can turn on the DE separately from the spindle.

Brookwood Design

Sheet: /Misc IO/  
File: MiscIO.kicad\_sch

Title: RP23U5XBB

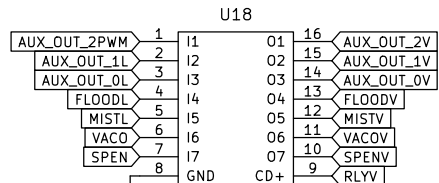
Size: A4 Date: 2025-03-27

KiCad E.D.A. 8.0.4

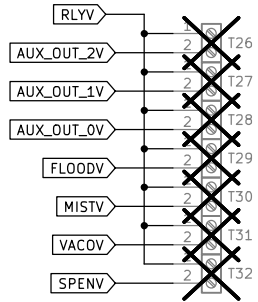
Rev: Ver 0.97

Id: 1/10

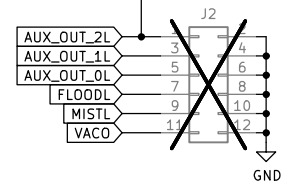




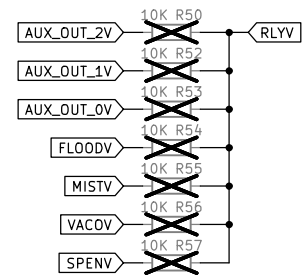
Relay Driver. Currently using ULN2003. Looking at using TBD620003 MOSFET Driver.



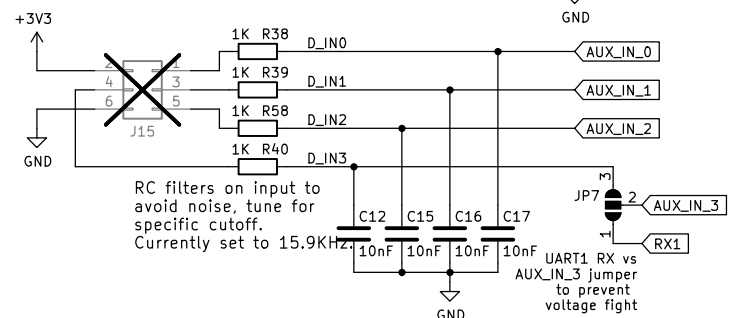
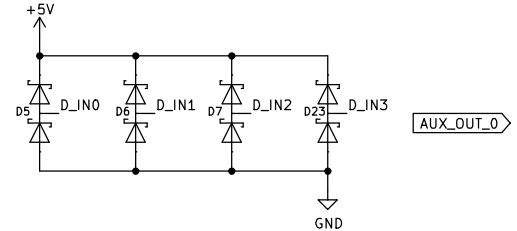
Jumper for Aux\_Out\_2 to be selected between spindle PWM and digital output. Allows driving 12V PWM loads (like lasers).



All these outputs have HC level drive capability. limited to 6mA.



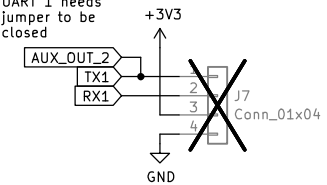
Digital input group. 3 inputs are 5V tolerant, diode protected with schmitt triggers. RC Low Pass noise filters.



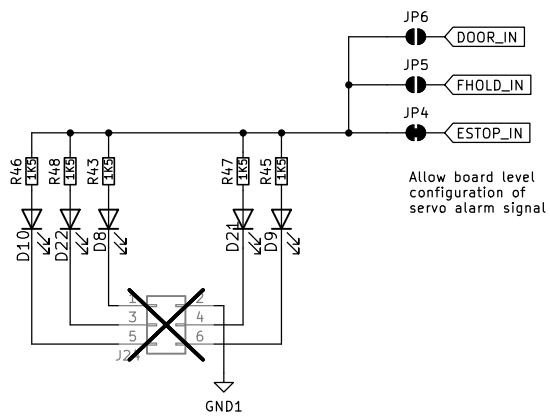
RC filters on input to avoid noise, tune for specific cutoff. Currently set to 15.9KHz.

UART1 RX vs AUX\_IN\_3 jumper to prevent voltage fight

Support for UART 1 needs jumper to be closed



Brookwood Design	
Sheet: /DigitalIO and Relays/	
File: DigitalIO and Relays.kicad_sch	
Title: RP23U5XBB	
Size: A4	Date: 2025-03-27
KiCad E.D.A. 8.0.4	Rev: Ver 0.97
	Id: 1/10



**Brookwood Design**

Sheet: /Servo\_error/  
File: servo\_error.kicad\_sch

**Title: RP23U5XBB**

Size: A4 Date: 2025-03-27

KiCad E.D.A. 8.0.4

**Rev: Ver 0.97**

Id: 1/10