view_frames Result

Recorded at time: 1986.641

odom

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 1986.573 (0.068 sec old)
Buffer length: 4.900 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1986.641 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1986.641 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1986.575 (0.066 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1986.575 (0.066 sec old)
Buffer length: 4.900 sec

camera

left_wheel

right_wheel

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1986.641 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1986.641 sec old)
Buffer length: 0.000 sec

camera_link_optical

hokuyo