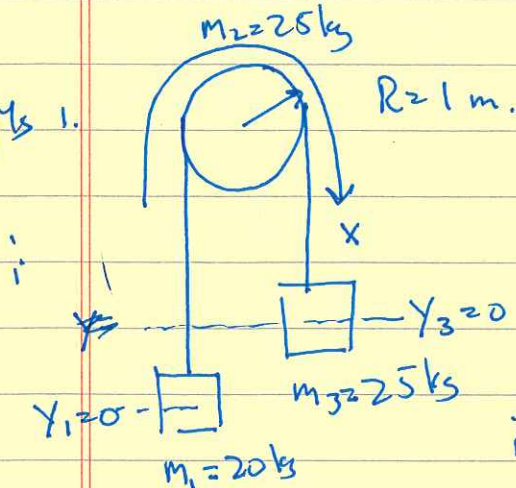


PS # 9

20 pts 1.



$$E_{\text{mech}} = KE + PE$$

$$E_{\text{mech}} = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} I_2 \omega_2^2 + \frac{1}{2} m_3 v_3^2 + m_1 g y_1 + m_3 g y_3$$

$$i: E_{\text{mech}, i} = 0 + 0 + 0 + m_1 g (0) + m_3 g (0) = 0$$

$$f: y_1 = 2 \text{ m} \quad y_3 = -2 \text{ m}$$

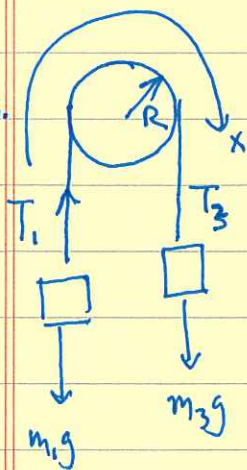
$$f: E_{\text{mech}, f} = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_3 v_{3f}^2 + \frac{1}{2} I_2 \omega_{2f}^2 + m_1 g y_{1f} + m_3 g y_{3f}$$

$$I_2 = \frac{1}{2} m_2 R^2 \quad \omega_{2f} \rightarrow v_{1f} = v_{3f} = +R\omega_{2f} = v_f$$

$$\begin{aligned} E_{\text{mech}, f} &= \left(\frac{1}{2} m_1 + \frac{1}{2} m_3 + \frac{1}{4} m_2 \right) v_f^2 + m_1 g (2) - m_3 g (2) \\ &= \left(\frac{1}{2} 20 + \frac{1}{2} 25 + \frac{1}{4} 25 \right) v_f^2 + 20 (9.8) (2) - 25 (9.8) (2) \\ &28.75 v_f^2 - 98 = E_{\text{mech}, i} = 0 \end{aligned}$$

$$E_{\text{mech}, f} = 0 \Rightarrow v_f^2 = \frac{98}{28.75} \Rightarrow v_f = 1.8 \text{ m/s}$$

20 pts 2.



$$\text{For } 1: \sum F = m_1 g - T_1 = m_1 a$$

$$3: \sum F = m_3 g - T_3 = m_3 a$$

$$2: \sum \tau = R T_3 - R T_1 = I_2 \alpha$$

$$\alpha = \frac{a}{R} \quad I_2 = \frac{1}{2} m_2 R^2$$

$$\Rightarrow T_3 - T_1 = \frac{1}{2} m_2 a$$

$$\Rightarrow T_1 = m_1 g + m_1 a$$

$$\Rightarrow T_3 = m_3 g - m_3 a$$

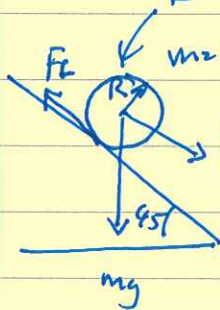
$$\text{ply into } T_3 - T_1 = \frac{1}{2} m_2 a$$

$$\Rightarrow m_3 g - m_3 a - m_1 g - m_1 a = \frac{1}{2} m_2 a$$

$$\Rightarrow (m_3 - m_1) g = (m_1 + m_3 + \frac{1}{2} m_2) a$$

$$\Rightarrow a = \frac{m_3 - m_1}{m_1 + m_3 + \frac{1}{2} m_2} g = \frac{5}{57.5} g = \boxed{0.85 \text{ m/s}^2}$$

20 pts. 3. $R = 0.1 \text{ m}$
 $m = 1 \text{ kg}$



$$\Sigma F_x = mg \sin 45 - F_f = ma$$

$$\Sigma \tau = -R F_f = -I \alpha$$

$$\alpha = \frac{a}{R} \quad I = \frac{1}{2} m R^2$$

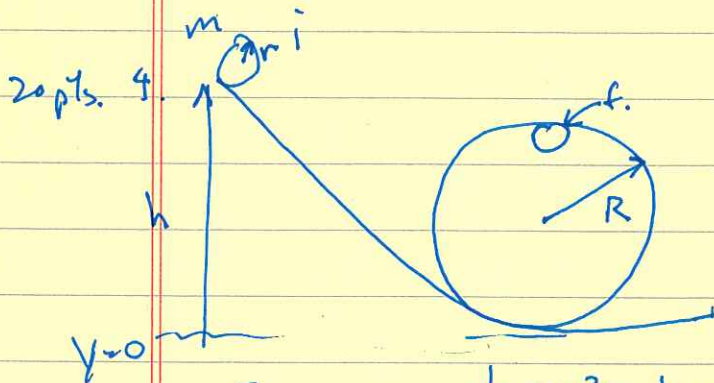
$$\Rightarrow -R F_f = -\frac{1}{2} m R^2 \frac{a}{R} \Rightarrow F_f = \frac{1}{2} m a$$

$$\Rightarrow mg \sin 45 - \frac{1}{2} m a = m a$$

$$\Rightarrow \frac{3}{2} m a = mg \sin 45 \Rightarrow$$

$$\boxed{a = \frac{2}{3} g \sin 45 = 4.6 \text{ m/s}^2}$$

$$F_f = \frac{1}{2} m a = \frac{1}{2} (1) (4.6) = \boxed{2.3 \text{ N}}$$



$$i: E_{\text{mech},i} = \frac{1}{2} m v_{xi}^2 + \frac{1}{2} I \omega_i^2 + mgh$$

$$f: E_{\text{mech},f} = \frac{1}{2} m v_f^2 + \frac{1}{2} I \omega_f^2 + mg 2R$$

$$E_{\text{mech},i} = mgh$$

$$E_{\text{mech},f} = \frac{1}{2} m v_f^2 + \frac{1}{2} \left(\frac{2}{5} m R^2 \right) \left(\frac{v_f}{R} \right)^2 + mg 2R$$

$$E_{\text{mech},f} = \cancel{m} v_f^2 \left(\frac{1}{2} + \frac{1}{5} \right) + \cancel{m} g 2R = E_{\text{mech},i} = \cancel{m} g h$$

$$\Rightarrow v_f^2 \left(\frac{5}{10} + \frac{2}{10} \right) = g(h - 2R)$$

$$\Rightarrow v_f^2 = \frac{10}{7} g(h - 2R)$$

but I also know $\frac{v_f^2}{R} = g$

$$\Rightarrow \frac{v_f^2}{R} = g = \frac{10}{7} \frac{g}{R} (h - 2R) \Rightarrow 1 = \frac{10}{7} \left(\frac{h}{R} - 2 \right)$$

$$\Rightarrow \frac{14}{10} = \frac{7}{10} + 2 = \frac{h}{R} \Rightarrow \boxed{h = \frac{24}{10} 2.7 R}$$

20 pts 5) (a) $\begin{matrix} \hat{i} & \hat{j} & \hat{k} \\ A & 4 & 3 & 0 \end{matrix} \Rightarrow \boxed{\vec{C} = 15\hat{i} - 20\hat{j}}$

B $\begin{matrix} \hat{i} & \hat{j} & \hat{k} \\ A & 2 & 3 & -4 \\ B & 2 & 6 & -8 \end{matrix} \Rightarrow \vec{C} = (-24 + 24)\hat{i} + (-8 + 16)\hat{j} + (12 - 6)\hat{k}$
 $\boxed{\vec{C} = 8\hat{j} + 6\hat{k}}$

(c) $\begin{matrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ 4 & 5 & -6 \end{matrix} \Rightarrow \vec{C} = (-12 + 15)\hat{i} + (12 + 6)\hat{j} + (5 - 8)\hat{k}$
 $\boxed{\vec{C} = 3\hat{i} + 18\hat{j} - 3\hat{k}}$