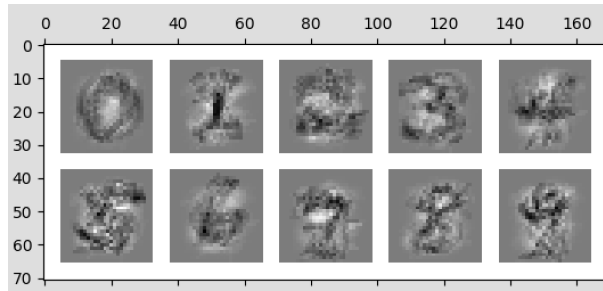


**Problem 1** (L2-Regularized Logistic Regression, 10 points)

In this question, we'll attempt to regularize logistic regression to deal with having such a small dataset. Recall that the likelihood given by this model is:

$$p(c|\mathbf{x}, \mathbf{w}) = \frac{\exp(\mathbf{w}_c^T \mathbf{x})}{\sum_{c'=0}^9 \exp(\mathbf{w}_{c'}^T \mathbf{x})} \quad (1)$$

- (a) Fit a maximum likelihood estimate of logistic regression to the 300 training points, plot the learned parameters as a set of 10 images.



- (b) Next, let's define a prior distribution on parameters, so that we can fit a *maximum a posteriori* (MAP) estimate. Let's consider a spherical Gaussian prior on the parameters:

$$p(\mathbf{w}|\sigma^2) = \prod_{c=0}^9 \prod_{d=0}^{784} \mathcal{N}(w_{cd}|0, \sigma^2) \quad (2)$$

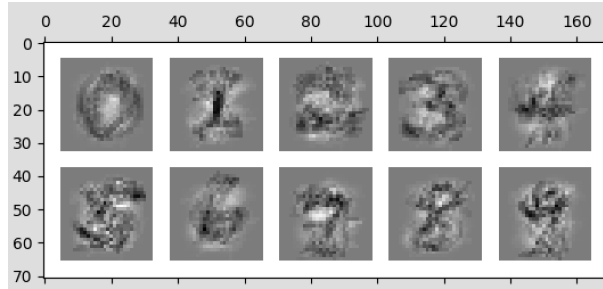
Write down  $\log(p(\mathbf{t}|\mathbf{X}, \mathbf{w})p(\mathbf{w}|\sigma^2))$ , the log-likelihood of the entire training set  $(\mathbf{X}, \mathbf{t})$  of 300 examples, multiplied by the prior on parameters.

$$\begin{aligned} \log(p(\mathbf{w}|\sigma^2)p(\mathbf{t}|\mathbf{X}, \mathbf{w})) &= \log(p(\mathbf{w}|\sigma^2)) + \log(p(\mathbf{t}|\mathbf{X}, \mathbf{w})) \\ \log(p(\mathbf{w}|\sigma^2)p(\mathbf{t}|\mathbf{X}, \mathbf{w})) &= \sum_{k,d=1}^{K,D} \frac{-(w_{kd})^2}{2\sigma^2} + \frac{1}{2} \log(2\pi\sigma^2) + \sum_{n=1}^N \sum_{k,d=1}^{K,D} P(c|x_d^n, w_{kd}) \\ \log(p(\mathbf{w}|\sigma^2)p(\mathbf{t}|\mathbf{X}, \mathbf{w})) &= \sum_{k,d=1}^{K,D} \frac{-(w_{kd})^2}{2\sigma_d^2} + \frac{1}{2} \log(2\pi\sigma_d^2) + \sum_{n=1}^N \sum_{k,d=1}^{K,D} \log \frac{\exp(w_{kd}^T x_d^n)}{\sum_{c=0}^9 \exp(w_{cd}^T x_d^n)} \end{aligned}$$

**Gradient:**

$$\begin{aligned} \nabla_w \log(p(\mathbf{t}|\mathbf{X}, \mathbf{w})p(\mathbf{w}|\sigma^2)) &= \nabla_w \log(p(\mathbf{t}|\mathbf{X}, \mathbf{w})) + \nabla_w \log(p(\mathbf{w}|\sigma^2)) \\ \nabla_w \log(p(\mathbf{t}|\mathbf{X}, \mathbf{w})p(\mathbf{w}|\sigma^2)) &= \sum_{n=1}^N \left( \sum_{k,d=1}^{K,D} x_d^n * (1(t_k^n=1) - \log \frac{\exp(w_{kd}^T x_d^n)}{\sum_{c=0}^9 \exp(w_{cd}^T x_d^n)}) \right) + \sum_{k,d=1}^{K,D} \frac{-(w_{kd})}{\sigma_d^2} \end{aligned}$$

- (c) **Fit a MAP estimate of the parameters  $\mathbf{w}$  on the training set using gradient ascent.**  
The accuracy is (only) 0.03% higher with a prior.



**Problem 2** (Bayesian Logistic Regression using Stochastic Variational Inference, 20 points)

In this question, we'll avoid choosing a single set of parameters  $\hat{\mathbf{w}}$ . Instead, we'll approximately *integrate over all possible  $\mathbf{w}$* . This will avoid over-fitting by making approximately Bayes-optimal predictions, given the assumptions of our model.

- (a) **Code up SVI for this model. That is, use stochastic gradient ascent to find locally optimal variational parameters maximizing the evidence lower bound:**

$$\phi^* = \operatorname{argmax}_{\phi} \mathbb{E}_{q(\mathbf{w}|\phi)} \left[ \log p(\mathbf{t}|\mathbf{X}, \mathbf{w}) p(\mathbf{w}|\sigma^2) - \log q(\mathbf{w}|\phi) \right] \quad (3)$$

- (b) **Use your code to find  $\phi^*$ . Compute the average predictive accuracy on the test set using simple Monte Carlo using your approximate posterior and 100 samples ( $S=100$ ):**

$$p(t_i|x_i) = \int p(t_i|x_i, \mathbf{w}) p(\mathbf{w}|\mathbf{t}, \mathbf{X}) d\mathbf{w} \approx \frac{1}{S} \sum_{j=1}^S p(t_i|x_i, \mathbf{w}^{(j)}), \quad \text{each } \mathbf{w}^{(j)} \sim q(\mathbf{w}|\phi^*) \quad (4)$$

**Play with the prior variance  $\sigma^2$  to see if you can get a higher test-set accuracy than MAP inference.**

With  $\sigma^2 = 1.0$ , we obtain a 77.22% accuracy over 100 iterations of training for 300 training examples.

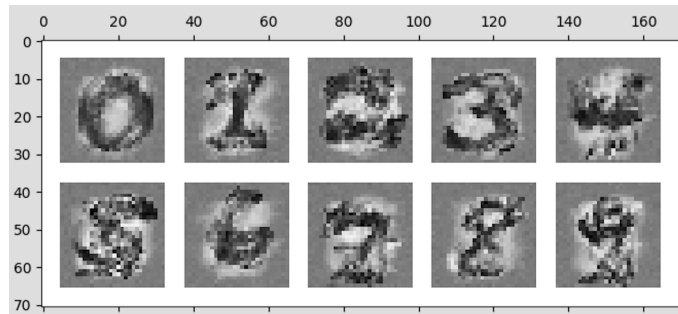


Figure 1: variational posterior means

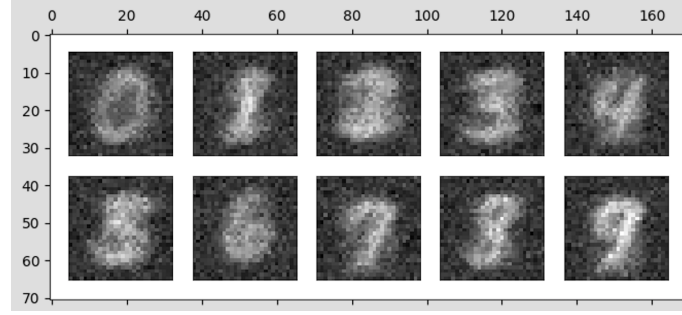


Figure 2: The variational posterior standard deviations

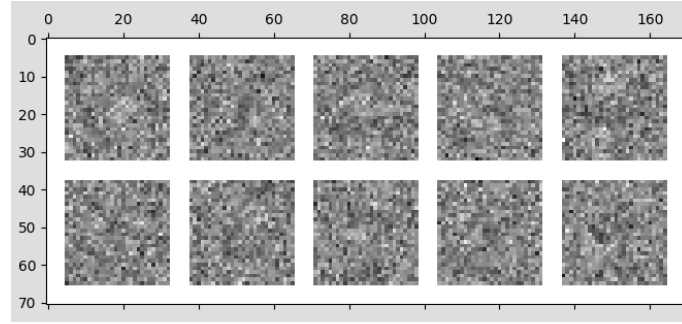


Figure 3: A single sample from the variational posterior

- (c) The above plot for a single sample from  $q(w|\phi^*)$  will be extremely noisy. Consider how our model treats pixels which it never sees 'on' across all training examples. In particular, starting from  $\log p(t|w, x)$  show that if  $x_d \in B$ , the set of pixels which are always off, then the training labels do not effect the optimal variational parameters for those pixels.

$x_d \in B$ , d' signifies that the pixel is not active throughout all of X.

$$\int q(w_{cd'}) \left( \int \prod_{cd', d' \neq d} q(w_{cd'} | \phi_{cd'}) p(t|w) dw_{cd', d' \neq d'} \right) dw_{cd'}$$

$$f(\phi_{cd', d' \neq d'}) = \prod_{cd', d' \neq d} q(w_{cd'} | \phi_{cd'}) p(t|w) dw_{cd', d' \neq d'}$$

contains no  $w_{cd'}$  at all instances.

. Using fubini theorem:  $(\int q(w_{cd'}) dw_{cd'}) f(\phi_{cd', d' \neq d'})$

$$Obj = f(\phi_{cd', d' \neq d'}) - KL(q(w|\phi) || p(w)), \text{ where } KL(..) = \int q(w | \mu_{cd'}, \sigma_{cd'}) \frac{q(w | \mu_{cd'}, \sigma_{cd'})}{p(w | 0, \epsilon)}$$

. The close form of  $KL$  is  $[\log \frac{\sigma_{cd'}}{\sigma} + \frac{\sigma_{cd'} + (\mu_{cd'} - 0)^2}{2\sigma^2} - \frac{1}{2}]$

$$\text{argmax}_{\mu_{cd'}, \sigma_{cd'}} Obj = 1 - 1 + (g_1(\sigma_{cd'}, \mu_{cd'}) + g_2(\sigma_{cd'}, \mu_{cd'})) - 0,$$

Where  $\sigma_{cd'}, \mu_{cd'}$  will equal to 0 and  $\epsilon$  respectively. Therefore as demonstrated, the training labels will not have an effect on the optimal variational parameters for the pixels which are off throughout all  $D$ .