

$$\frac{|\nabla_{x_{1}}|^{2}}{|\nabla_{x_{1}}|^{2}} = \frac{||\nabla_{x_{1}}|^{2}}{|\nabla_{x_{1}}|^{2}} = \frac{||\nabla_{x_{1}}|^{2$$

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\underbrace{\left(p_{d_{1}} + \frac{\sigma_{d_{1}, q_{1}}}{1}\right) \cdot \frac{\sigma_{d_{1}, q_{1}}}{v_{d_{2}} - \left[v_{d_{1}} + \frac{\sigma_{d_{2}, q_{1}}}{2}\right]} P_{d_{1}} \left[\tau_{d_{2}} \left(\frac{p_{d_{1}}}{p_{d_{2}}}\right)^{\frac{q_{1} - 1}{2}}\right] - \sigma_{d_{1}} \left(\sigma_{d_{1}} + \frac{\sigma_{d_{2}, q_{1}}}{2}\right) \left[\left(\sigma_{d_{1}} + \frac{\sigma_{d_{2}, q_{1}}}{2}\right)\right] \left(\sigma_{d_{1}} + \frac{\sigma_{d_{2}, q_{1}}}{2}\right) \left(\sigma_{d_{1}} + \frac{\sigma_{d_
                                                                                                                                                                                           \left[ p_1 - \left( p_{4_1} + \frac{4p_{4,2_1}}{2} \right) - \xi_2 \left( m_{1_1} + \frac{4m_{1,2_2}}{2} \right) \left[ \left( m_{4_1} + \frac{4m_{1,2_2}}{2} \right) \right] \right]
                                                                                                                                                                                \begin{bmatrix} & & & & & \\ & & & & \\ p_2 - \left(p_{2j} + \frac{4p_{2,2}}{2}\right) - \xi_{2,0}\left(m_{2j} + \frac{4m_{2,2j}}{2}\right) \left[\left(m_{2j} + \frac{4m_{2,2j}}{2}\right)\right] \end{bmatrix}
                                                                                                                                                                                            \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_1} & \sigma_{q_2} \\ \end{pmatrix} - \rho_{r} - \left( \begin{bmatrix} \sigma_{q_1} & \sigma_{g_2} \\ \sigma_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \sigma_{q_1} & \sigma_{q_2} \\ \sigma_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \sigma_{q_2} \\ \rho_{q_2} & \sigma_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{bmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_{q_1} & \rho_{q_2} \\ \rho_{q_2} & \rho_{q_2} \\ \end{pmatrix} \begin{bmatrix} \rho_
\sin_{R_1} \leftarrow \frac{1}{6} \left( \sin_{R_1} + 2 \sin_{R_2} + 2 \sin_{R_3} + \sin_{R_4} \right)
                                            m_1 \leftarrow \frac{1}{6} \left( m_{1,1} + 2 m_{1,2} + 2 m_{1,3} + m_{1,4} \right)
                                 \mathrm{d} u_{2_i} \leftarrow \frac{1}{6} \left( \mathrm{d} u_{2,1_i} + 2 \, \mathrm{d} u_{2,2_i} + 2 \, \mathrm{d} u_{2,3_i} + \mathrm{d} u_{2,4_i} \right)
                                 \deg_{\tilde{I}_{j}} = \frac{1}{6} \left( \deg_{\tilde{I}_{j}} + 2 \deg_{\tilde{I}_{j}} + 2 \deg_{\tilde{I}_{j}} + \deg_{\tilde{I}_{j}} \right)
                      \Phi_{k_1} \leftarrow \frac{1}{6} \left(\Phi_{k,k_1} + 2\Phi_{k,k_2} + 2\Phi_{k,k_1} + \Phi_{k,k_2}\right)

a = a_1 \cdot a_2 \cdot a_3 \cdot a_4 \cdot a_7 \cdot T_7 \cdot T_7 \cdot T_8 \cdot t
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 \begin{aligned} & C_{J_{R}} \exp_{\mathbf{p} \in \mathcal{P}_{R}} \exp_{\mathbf{p} \in \mathcal{P}_{R}} & y_{1} \cdot \nabla_{\mathbf{p}} \cdot
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 \begin{aligned} & \{ c_{i} - C_{i} \\ & \{ c_{i} c_{i} = c_{i} + \left( \frac{1}{2} \left[ \left( c_{i} \cdot \frac{n}{n} \right) \cdot \frac{n}{n} \right] - 1 \right] - 1 \right] \\ & \{ c_{i} c_{i} + c_{i} + c_{i} - \left( \frac{1}{2} \left[ \left( c_{i} \cdot \frac{n}{n} \right) \cdot \frac{n}{n} \right] - 1 \right] \\ & \{ c_{i} - c_{i} + c_{i} - c_
                                                                                                                                                        otherwise t_1 \leftarrow t_{i-1} + dt d' = 0 \le \eta \le \frac{T}{2}
                                                                                                                                                                                                                         \begin{split} & \mathbf{f} \cdot \mathbf{g} \leq \mathbf{f}_{i} \leq \frac{1}{2} \\ & \mathbf{f}_{i,j} \leftarrow \mathbf{f}_{i,j,0} + \mathbf{A} \left[ \sin \left( \frac{2\pi}{T} \left( \mathbf{f}_{i} - \frac{T}{4} \right) \right) + 1 \right] \\ & \mathbf{f}_{i,0,0,\mathbf{h}_{i}} \leftarrow \mathbf{f}_{i,0} + \mathbf{A} \left[ \sin \left( \frac{2\pi}{T} \left[ \left( \mathbf{f}_{i} + \frac{d\mathbf{g}}{2} \right) - \frac{T}{4} \right] \right) + 1 \right] \\ & \mathbf{f}_{i,0,0,\mathbf{h}_{i}} \leftarrow \mathbf{f}_{i,0} + \mathbf{A} \left[ \sin \left( \frac{2\pi}{T} \left[ \left( \mathbf{f}_{i} + \frac{d\mathbf{g}}{2} \right) - \frac{T}{4} \right] \right] + 1 \right] \end{split}
                                                                                                                                                                                                                         \begin{aligned} & \{\zeta_{2k_1} \leftarrow \zeta_{2,0} + \lambda_1 \text{ and } \\ & \text{otherwise} \\ & \{\zeta_1 \leftarrow \zeta_{2,0} + 2\lambda, \\ \zeta_{2,0} \zeta_{2,0} \leftarrow \zeta_{2,0} + 2\lambda, \\ \zeta_{2k_1} \leftarrow \zeta_{2,0} + 2\lambda, \\ \zeta_{2k_1} \leftarrow \zeta_{2,0} + 2\lambda, \\ \forall k_1 \leftarrow k_{2k_1} \leftarrow k_{2k_1-1} \\ & k_2 \leftarrow k_{2k_1} + k_{2k_1-1} \\ & k_3 \leftarrow k_{2k_1} + k_{2k_1-1} \\ & k_4 \leftarrow k_{2k_1-1} + k_{2k_1-1} \\ & k_5 \leftarrow k
                                                                                                                                                                                                                         T_{\ell_1} \leftarrow T_{\ell,0} \left( \frac{p_{\ell_1}}{p_{\ell,0}} \right)^{\frac{k-1}{k}}
                                                                                                                                                        p_{k_1} \leftarrow \frac{m_{k,0}}{V_{k_1}} \, R_k \, T_{k_1}
                                                                 \begin{aligned} & \mathbf{d} \mathbf{u}_{[h]} = \mathbf{d} \begin{bmatrix} \mathbf{z}_{[h]} \\ \mathbf{u}_{[h]} - \frac{\mathbf{u}_{[h]}}{\mathbf{v}_{[h]} - \mathbf{v}_{[h]}} \mathbf{v}_{[h]} \end{bmatrix} \mathbf{v}_{[h]} \begin{bmatrix} \mathbf{z}_{[h]} \\ \mathbf{z}_{[h]} \end{bmatrix} - \mathbf{v}_{[h]} \mathbf{u}_{[h]} \end{bmatrix} \\ & \mathbf{u}_{[h]} = \mathbf{d} \begin{bmatrix} \mathbf{v}_{[h]} - \mathbf{v}_{[h]} \\ \mathbf{v}_{[h]} - \mathbf{v}_{[h]} - \mathbf{v}_{[h]} \end{bmatrix} \\ & \mathbf{y}_{[h]} = \mathbf{v}_{[h]} - \mathbf{v}_{[h]} - \mathbf{v}_{[h]} \end{bmatrix} \end{aligned}
                                                                 \begin{split} & \text{dist}_{2,1} = \text{d} \left[ \frac{\gamma_{2} - \kappa_{1} - \kappa_{1} + \kappa_{1} + \kappa_{2}}{2\gamma_{2} - \kappa_{1} + \kappa_{2}} \right] \sigma_{2,1} \\ & \text{dist}_{2,1} = \text{d} \left[ \frac{\gamma_{2} - \kappa_{1} - \kappa_{1} + \kappa_{1}}{2\gamma_{2}} \right] \sigma_{2,1} \\ & \text{dist}_{2,1} = \text{d} \left[ \frac{\kappa_{1} - \gamma_{2} - \kappa_{2} + \kappa_{2}}{2\gamma_{2} - \kappa_{1} + \kappa_{2}} \right] \\ & \sigma_{2,1_{1}} = \text{d} \left[ \frac{\kappa_{1} - \gamma_{2} - \kappa_{2} - \kappa_{2}}{2\gamma_{2} - \kappa_{2} + \kappa_{2}} \right] \\ & \sigma_{2,1_{2}} = \text{d} \left[ \frac{\kappa_{2} - \kappa_{2} - \kappa_{2}}{2\gamma_{2} - \kappa_{2} + \kappa_{2}} \right] \end{split}
                                                                                                                                                                                                                                                                                                                                      a \underbrace{\left[ \mu_1, \frac{\Phi_{1,1}}{2} \right] \cdot \frac{\pi_{12}}{V_{10} \cdot \left[V_{11}, \frac{\Phi_{1,1}}{2} \right]} \pi \left[ \tau_{10} \left[ \frac{\eta_1 \cdot \frac{\Phi_{1,1}}{2}}{\mu_{10}} \right]^{\frac{1}{2}} \right] \cdot \tau_{1} \left[ \sigma_1, \frac{\Phi_{1,1}}{2} \right] \left[ \left[ \sigma_1, \frac{\Phi_{1,1}}{2} \right] \left[ \left[ \sigma_1, \frac{\Phi_{1,1}}{2} \right] \right] \right] + \frac{1}{2} \left[ \left[ \frac{1}{2} \left[ \frac{\Phi_{1,1}}{2} \right] + \frac{1}{2} \left[ \frac{\Phi_{1,1}}{2} \right] \right] \left[ \frac{\Phi_{1,1}}{2} \right] + \frac{1}{2} \left[ \frac{\Phi_{1,1}}{2} \right] \left[ \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} \right] \left[ \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} \right] \left[ \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,1}}{2} \right] \left[ \frac{\Phi_{1,1}}{2} + \frac{\Phi_{1,
\left[\begin{array}{c} a_{i,j}\\\\ a_{i1,l_1}=d\\ \\ a_{i1,l_2}=d\\ \end{array}\right]\underbrace{\begin{array}{c} a_{i1,l_2}\\\\ a_{i1}-a_{i1,l_2}\\\\ a_{i1}-a_{i1,l
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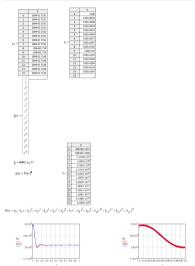
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dt \left| \frac{y_2 - \left( p_{4_1} + \frac{d p_{4,3_1}}{2} \right) - \xi_{2,0,3b_1} \left[ m_{2_1} + \frac{d m_{2,1_1}}{2} \right] \cdot \left| \left| m_{2_1} + \frac{d m_{2,1_2}}{2} \right| \right| \right|
                                                                                                                            \left[\left(g_{\delta_1}+\frac{dg_{\delta,\delta_2}}{2}\right)-g_{\delta}-\xi_2\left(m_{\delta_1}+\frac{dm_{\delta,\delta_2}}{2}\right)\left[\left(m_{\delta_1}+\frac{dm_{\delta,\delta_2}}{2}\right)\right]\right]
                                                                                                                            \begin{bmatrix} b & b \\ \left[ \frac{d\sigma_{2,1}}{2} \right] + \left( \frac{d\sigma_{2,1}}{2} \right) - \left( \frac{d\sigma_{3,1}}{2} \right) - \left( \frac{d\sigma_{3,1}}{2} \right) - \left( \frac{d\sigma_{3,1}}{2} \right) - \left( \frac{d\sigma_{3,1}}{2} \right) \\ & \frac{V_{KST} \left( V_{1} + \frac{d\sigma_{2,1}}{2} \right)}{2} \end{bmatrix}
       dV_{g,h_i} \leftarrow ds \left[ \frac{m_{h_i} + \frac{dm_{g,h_i}}{2}}{2} \right]
                                                                                                                                                                                                                                                                -\frac{e_{1,2}}{\frac{e_{1,2}}{e_{1,2}-\left(\frac{1}{e_{1}}\frac{d^{2}}{e_{2,2}}\right)}} e_{1}\left[r_{1}\left[\frac{\mu_{1,1}-\frac{d^{2}}{e_{2,2}}}{\mu_{1,2}}\right]^{\frac{k-1}{k}}\right] - \zeta_{2}\left(e_{3}+\frac{de_{3,2}}{e_{2,2}}\right)\left[\left(e_{3}+\frac{de_{3,2}}{e_{2,2}}\right)\left[\left(e_{3}+\frac{de_{3,2}}{e_{2,2}}\right)\right]\right]
                                                                                                                            \boxed{ p_1 - \left(p_{d_1} + \frac{4p_{d,2}}{2}\right) - \varepsilon_1\left(m_{\tilde{l}_1} + \frac{4m_{\tilde{l}_1,2}}{2}\right) \left[\left(m_{\tilde{l}_1} + \frac{4m_{\tilde{l}_2,2}}{2}\right)\right]}
                                                                                                                     \left[\frac{p_2 - \left(p_{4_1} + \frac{4p_{4,2_1}}{2}\right) - \zeta_{2,0,2p_4}\left(m_{2_1} + \frac{4m_{2,2_1}}{2}\right) \left|\left(m_{2_1} + \frac{4m_{2,2_1}}{2}\right)\right|\right]
                                                                                                                     \left[ \left[ g_{4_{\frac{1}{2}}} \cdot \frac{d g_{2, 2_{\frac{1}{2}}}}{2} \right] - g_{2} - \xi_{2} \left( m_{2_{\frac{1}{2}}} \cdot \frac{d m_{2, 2_{\frac{1}{2}}}}{2} \right) \left[ \left( m_{2_{\frac{1}{2}}} \cdot \frac{d m_{2, 2_{\frac{1}{2}}}}{2} \right) \right] \right]
                                                                                                      \begin{bmatrix} m_{1_{1}} + \frac{d\alpha_{1}\gamma_{1}}{2} + \left(m_{1_{1}} + \frac{d\alpha_{2}\gamma_{1}}{2} - \left(m_{1_{1}} + \frac{d\alpha_{2}\gamma_{1}}{2}\right) - \left(m_{1_{1}} + \frac{d\alpha_{2}\gamma_{1}}{2}\right) - \left(m_{1_{1}} + \frac{d\alpha_{2}\gamma_{1}}{2}\right) \\ & \frac{V_{KOT}\left(V_{A} + \frac{d\alpha_{2}\gamma_{1}}{2}\right)}{2} \end{bmatrix}
                             \delta r_{\mathbf{x}, \delta_{j}} \leftarrow ds \left[ \frac{n_{[k]} + dn_{[k], \delta_{j}}}{r_{[k]}} \right]
                                                                                 \begin{split} & & - \frac{1}{2} \left[ \frac{(\alpha_1 + \hat{\alpha}_{1A}) - \frac{\alpha_1}{\beta_1 + (\hat{\alpha}_1 + \hat{\alpha}_{1A})} + \left[ \frac{1}{\beta_1} \left[ \frac{(\alpha_1 + \hat{\alpha}_{1A})}{\alpha_2} \right]^{\frac{1}{2}} \right] - \left[ \epsilon_2 \left( \alpha_1 + \hat{\alpha}_{2A} \right) \left[ \alpha_1 + \hat{\alpha}_{2A} \right] \left[ \alpha_1 + \hat{\alpha}_{2A} \right] \right]}{\frac{1}{2} \left[ \epsilon_2 \left[ \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \left( \alpha_1 + \hat{\alpha}_{2A} \right) \right) \right] \right] - \left[ \epsilon_2 \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \left( \alpha_1 + \hat{\alpha}_{2A} \right) \right) \right) \right] \right]} \right] - \left[ \epsilon_2 \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \alpha_1 + \hat{\alpha}_{2A} \right) \right) \right] \right] \right] \right] \right] + \left[ \left[ \frac{1}{2} \left( \alpha_1 + \hat{\alpha}_{2A} \right) + \left( \alpha_1 + \hat{\alpha}_{2A} \right) - \left( \alpha_1 + \hat{\alpha}_{2A} \right) \right) \right] \right] \right] \right] \right
              \begin{aligned} & a_{1,k_{1}} - a_{1} \\ & a_{2,k_{1}} - a_{2} \\ & a_{2,k_{1}} - a_{2,k_{1}} \\ & a_{2,k_{1}} - a_{2} \\ & a_{2,k_{1}} - a_{2} \\ & a_{2,k_{1}} - a_{2,k_{1}} \\ & a_{2,k_{1}} - a_{2} \\ & a_{2,k_{1}} - a_{2} \\ & a_{2,k_{1}} - a_{2,k_{1}} \\ & 
              dV_{B_i} \leftarrow \frac{1}{4} \left( dV_{BB_i} + 2 dV_{BB_i} + 2 dV_{BB_i} + 2 dV_{BB_i} + dV_{BA_i} \right)
              du_{2_i} \leftarrow \frac{1}{6} \left( du_{3,1_i} + 2 du_{3,2_i} + 2 du_{3,2_i} + du_{3,4_i} \right)
              dm_1 \leftarrow \frac{1}{6} \left(dm_{1,1_1} + 2dm_{1,2_1} + 2dm_{2,2_1} + dm_{1,2_1} + dm_{1,2_1}\right)
              \operatorname{du}_{2_i} \leftarrow \frac{1}{6} \left( \operatorname{du}_{2,1_i} + 2 \operatorname{du}_{2,2_i} + 2 \operatorname{du}_{2,2_i} + \operatorname{du}_{2,4_i} \right)
              \operatorname{dis}_{\tilde{\beta}_1} \leftarrow \frac{1}{6} \left(\operatorname{dis}_{\tilde{\beta},\tilde{\beta}_1} + 2\operatorname{dis}_{\tilde{\beta},\tilde{\beta}_1} + 2\operatorname{dis}_{\tilde{\beta},\tilde{\beta}_1} + \operatorname{dis}_{\tilde{\beta},\tilde{\beta}_1} \right)
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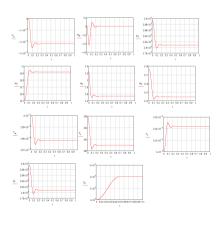
## Биз димфера (с учётом — 1800) — 20000.

 $(\mathbf{e}_1 \ \mathbf{e}_2 \ \mathbf{e}_3 \ \mathbf{e}_4 \ \mathbf{V}_{\mathbf{K}} + \mathbf{t}_2 \ \mathbf{t}_{20.3h} \ \mathbf{t}_{2h}) = \| \mathbf{fer} \ \mathbf{i} \in 0.N$ 

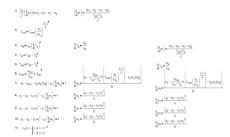
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 \begin{aligned} & \left\{ \zeta_{2} \leftarrow \zeta_{2} \right\} \\ & \left\{ \zeta_{2} \zeta_{3} \right\} \leftarrow \left\{ \zeta_{2} + A \left[ \omega \left[ \frac{2\pi}{2} \left[ \left( \chi + \frac{d}{d} \right) - \frac{\pi}{2} \right] + 1 \right] \right. \\ & \left\{ \zeta_{2} \right\} \leftarrow \left\{ \zeta_{2} \right\} + A \left[ \omega \left[ \frac{2\pi}{2} \left[ \left( \chi + d \right) - \frac{\pi}{2} \right] \right] + 1 \right] \\ & \omega_{1} \leftarrow \omega_{1} \beta \\ & \omega_{2} \leftarrow \omega_{2} \beta \\ & \omega_{3} \leftarrow \omega_{3} \beta \\ & \omega_{3} \leftarrow \omega_{3} \beta \\ & \omega_{4} \leftarrow \omega_{3} \beta \end{aligned} 
 \begin{aligned} & \left\{ \zeta_{3} \right\} \leftarrow \left\{ \zeta_{3} \right\} + 
          otherwise t_1 \leftarrow t_{i-1} + dt dt = t_i \leq \frac{T}{2}
                                           \begin{split} & \mathbf{c} & = \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \frac{1}{2} \\ & \mathbf{c}_{2,1} = \mathbf{c}_{2,0} + \Lambda \left[ \inf \left[ \frac{3\pi}{T} \left( \mathbf{c}_1 - \frac{\pi}{4} \right) \right] + 1 \right] \\ & \mathbf{c}_{2,0,2b_1} \leftarrow \mathbf{c}_{2,0} + \Lambda \left[ \inf \left[ \frac{3\pi}{T} \left[ \left( \mathbf{c}_1 + \frac{4h}{2} \right) - \frac{\pi}{4} \right] \right] + 1 \right] \\ & \mathbf{c}_{2,b_1} \leftarrow \mathbf{c}_{2,0} + \Lambda \left[ \inf \left[ \frac{3\pi}{T} \left[ \left( \mathbf{c}_1 + \mathbf{c}_0 \right) - \frac{\pi}{4} \right] \right] + 1 \right] \end{split}
 \begin{aligned} & \{2g_{i_{1}} \leftarrow 2g_{2}, \cdots, \frac{1}{1}\}_{i_{1}} \\ & \text{etherwise} \\ & \{c_{1} \leftarrow (2g + 2A) \\ & \{c_{2}, c_{1} \leftarrow (2g + 2A) \\ & \{c_{2}, c_{3}, c_{4} \leftarrow (2g + 2A) \\ & \{c_{2}, c_{3}, c_{4} \leftarrow (2g + 2A) \\ & \{c_{3}, c_{4} \leftarrow (2g + 2A) \\ & \{c_{4}, c_{4} \leftarrow (2g
          a_{1,1_i} \leftarrow a_i \left[ \frac{s_1 - s_{i_i} - c_{i_i} = t_i}{t_i} \right] = t_i
          du_{2,1_i} \leftarrow dt \left[ \frac{y_2 - y_{4_i} - z_{3_i} w_{3_i} ||v_{2_i}||}{1} \right]
          a_{3,1_1} \leftarrow a \left[ \frac{s_{k_1} - s_3 - c_3 a_{k_1} |a_{2_1}|}{s_3} \right]
          \Phi_{k,l_j} \leftarrow \Phi\left(\frac{n_{l_j} + n_{2_j} - n_{2_j}}{\frac{v_{\mathbf{x}_j}}{c^2}}\right)
                                                                                                                                                                 \left\lceil p_1 - \left(p_{d_1^-} + \frac{dp_{d_1^- l_2^-}}{2}\right) - c_2 \left(m_{l_1^-} + \frac{dm_{l_1 l_2^-}}{2}\right) \cdot \left| \left(m_{l_1} + \frac{dm_{l_1 l_2^-}}{2}\right) \right| \right\rceil
                                                                                                                                                                 \left[ \frac{z_2}{p_2 - \left(p_{4_1} + \frac{4p_{4, k_1}}{2}\right) - \xi_{2,0,2k_1} \left(m_{k_1} + \frac{4m_{2, k_1}}{2}\right) \left[ \left(m_{k_1} + \frac{4m_{2, k_1}}{2}\right) \right] \right]
                                                                                                                                                       \begin{bmatrix} y_4 & \frac{dp_{i_1 i_2}}{2} \\ y_4 & \frac{dp_{i_1 i_2}}{2} \\ -p_3 - 6g \left[ m_{3_1} + \frac{dm_{3_1 i_2}}{2} \right] \cdot \left[ m_{3_1} + \frac{dm_{3_1 i_2}}{2} \right] \end{bmatrix}
                                                                                                                                                                            \frac{\left(\underline{\alpha_{i_1} + \frac{4\alpha_{i_1,i_2}}{2}\right) \cdot \left(\underline{\alpha_{i_1} + \frac{4\alpha_{i_2,i_2}}{2}\right) \cdot \left(\underline{\alpha_{i_1} + \frac{4\alpha_{i_1,i_2}}{2}}\right)}{V_{\underline{\alpha_{i_1}}}}\right)}{V_{\underline{\alpha_{i_1}}}
                                                                                                                                                                 \left[ p_1 \cdot \left( p_{4_1} + \frac{4p_{4,2_1}}{2} \right) \cdot \varepsilon_1 \left( m_1 + \frac{4m_{1,2_1}}{2} \right) \cdot \left( m_1 + \frac{4m_{1,2_1}}{2} \right) \right]
                                                                                                                                                       \left[ p_2 - \left( p_{4_1} + \frac{d \phi_{4,2_1}}{2} \right) - c_{2,0,3b_1} \left( m_{2_1} + \frac{d m_{2,2_1}}{2} \right) \cdot \left[ \left( m_{2_1} + \frac{d m_{2,2_1}}{2} \right) \right] \right]
                                                                                                                                 \left[\left(g_{\tilde{q}_1} + \frac{4p_{\tilde{q},\tilde{q}_2}}{2}\right) - g_{\tilde{q}} - \xi_{\tilde{q}}\left(m_{\tilde{q}_1} + \frac{4m_{\tilde{q},\tilde{q}_2}}{2}\right) \cdot \left[\left(m_{\tilde{q}_1} + \frac{4m_{\tilde{q},\tilde{q}_2}}{2}\right)\right]\right]
\begin{aligned} & = 3 J_1 \cdot \frac{1}{2} \\ & = \frac{1}{2} \left[ \frac{g_1}{g_1 + \frac{4 m_2 J_1}{2}} + \left( m_{J_1} + \frac{4 m_2 J_2}{2} \right) - \left( m_{J_1} + \frac{4 m_2 J_2}{2} \right) \\ & = \frac{V_{m_1}}{c^2} \end{aligned} \right]
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 \begin{split} & 2 - \gamma_{m_1} - \gamma_{m_2} \left(\frac{p_1}{p_1}\right)^{\frac{1}{2}} \\ & 2 - \gamma_{m_2} - \gamma_{m_1} \left(\frac{p_2}{p_2}\right) \\ & 2 - \gamma_{m_2} - \gamma_{m_2} \left(\frac{p_2}{p_2}\right) \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 2 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{m_2} - \gamma_{m_2} \\ & 3 - \gamma_{m_2} - \gamma_{
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 $\begin{bmatrix} \frac{(a_1 * a_2 - a_3 - a_3)}{Y_2} \\ \frac{y_2}{\zeta_2} \\ \frac{y_3}{\zeta_2} \\ \frac{y_4}{y_5} \\ \frac{(p_4 - p_{12} - c_4 \cdot a_3)}{b_4} [a_3] \\ \frac{(p_4 - p_{12} - c_4 \cdot a_2)^2}{b_3} \\ \frac{(p_2 - p_2 - c_3 \cdot a_2)^2}{b_3} \\ \frac{(p_2 - p_2 - c_3 \cdot a_2)^2}{b_2} \end{bmatrix}$