

HW and SW Development Tools for the HCS12

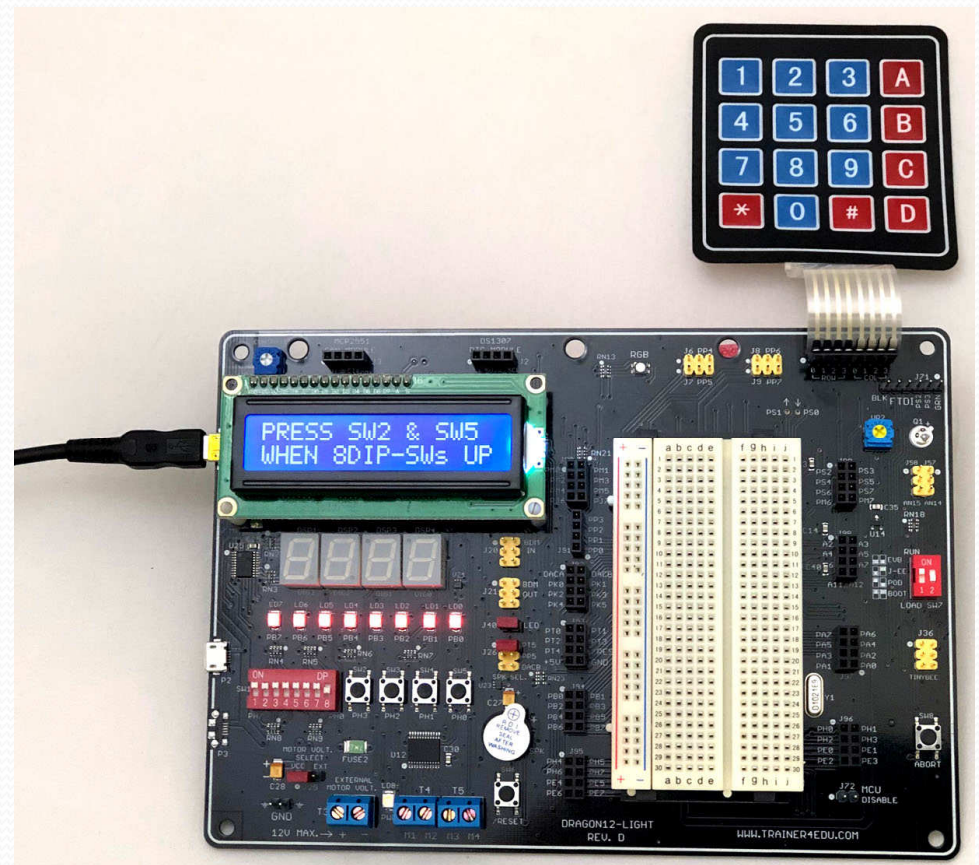
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COEN 317 (Fall 2019)

Outline

- HW development tools for the HCS12
- Software development tools for the HCS12
- Using CodeWarrior and Full Chip Simulation mode
- Introduction to parallel I/O port and simple I/O devices

Hardware Development Tools

- Dragon12-Light Board pre-loaded with Freescale Serial Monitor for CodeWarrior.
- The board includes the MC9S12DG256BCPV.
- Dragon12-Light Board Manual contains many information on the components connections to the microprocessor.



Hardware Development Tools

- Among many other components, the Dragon12-Light Board includes:
 - Dual 10-bit DAC for testing SPI interface and generating analog waveforms
 - 4-digit, 7-segment display for learning multiplexing technique
 - 16×2 LCD display module with LED backlight
 - Eight LEDs connected to port B
 - An 8-position DIP switch connected to port H
 - Four pushbutton switches connected to PH0-PH3
 - Speaker driven by timer, DAC, or PWM for alarm, voice and music
 - 4×4 membrane keypad (made of push button switches)
 - Light sensor for home automation applications
 - Temperature sensor for home automation applications
 - RGB color LED

Hardware Development Tools

- The crystal frequency is 8 MHz and this results in a 4 MHz bus speed.
- The bus speed can be boosted to 25 MHz by configuring the PLL.

Software Development Tools

- CodeWarrior IDE for HCS12(X) Microcontrollers (Classic) v. 5.1 SE (Special Edition).
- Projects can be created in purely Assembly Code, in C, or in mixed C/Assembly.
- The software can be used in two modes:
 - Full Chip Simulation:
 - The Board is not required to be connected.
 - The register and memory data are simulated values.
 - HCS12 Serial Monitor:
 - The Board is required to be connected.
 - The registers and memory data are the actual ones.

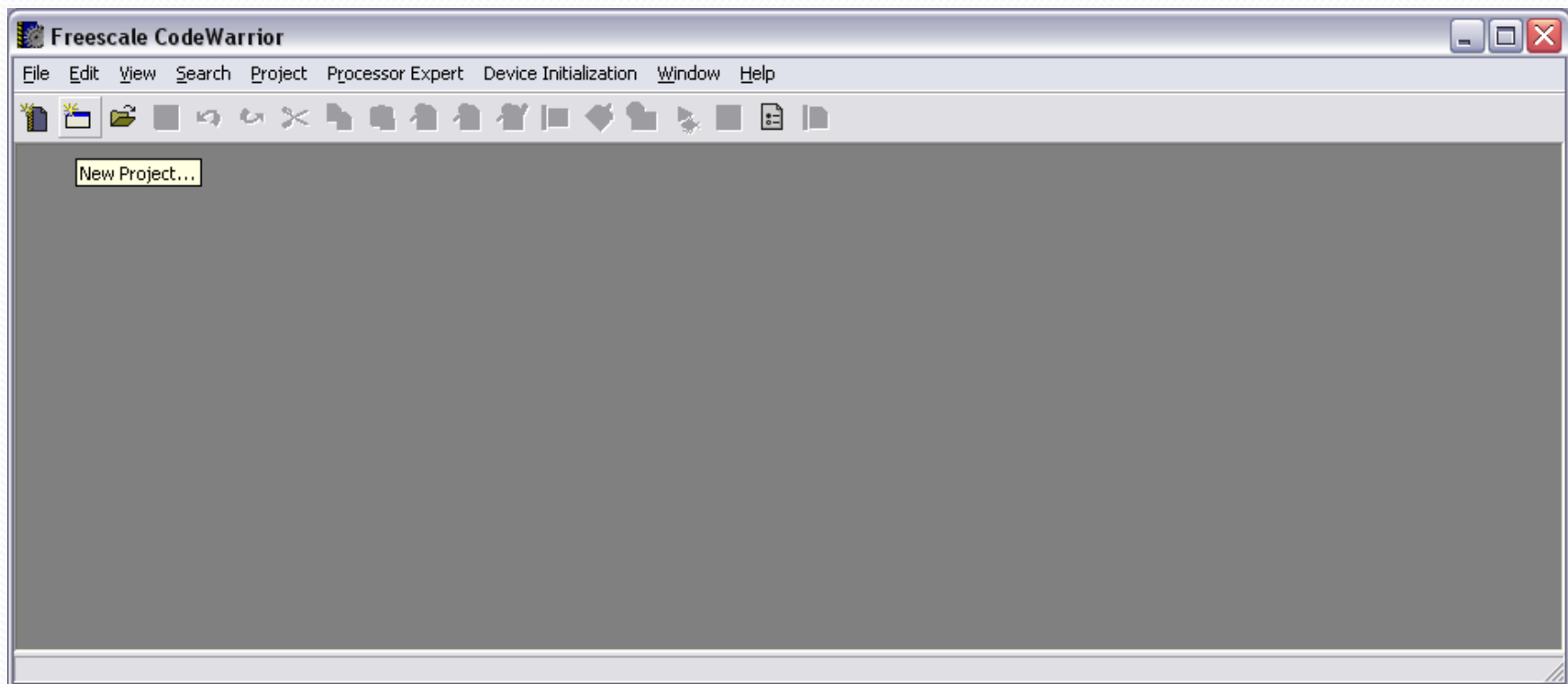
CodeWarrior for HCS12 Assembly Programming

- Start CodeWarrior for HCS12 and click Create New Project.



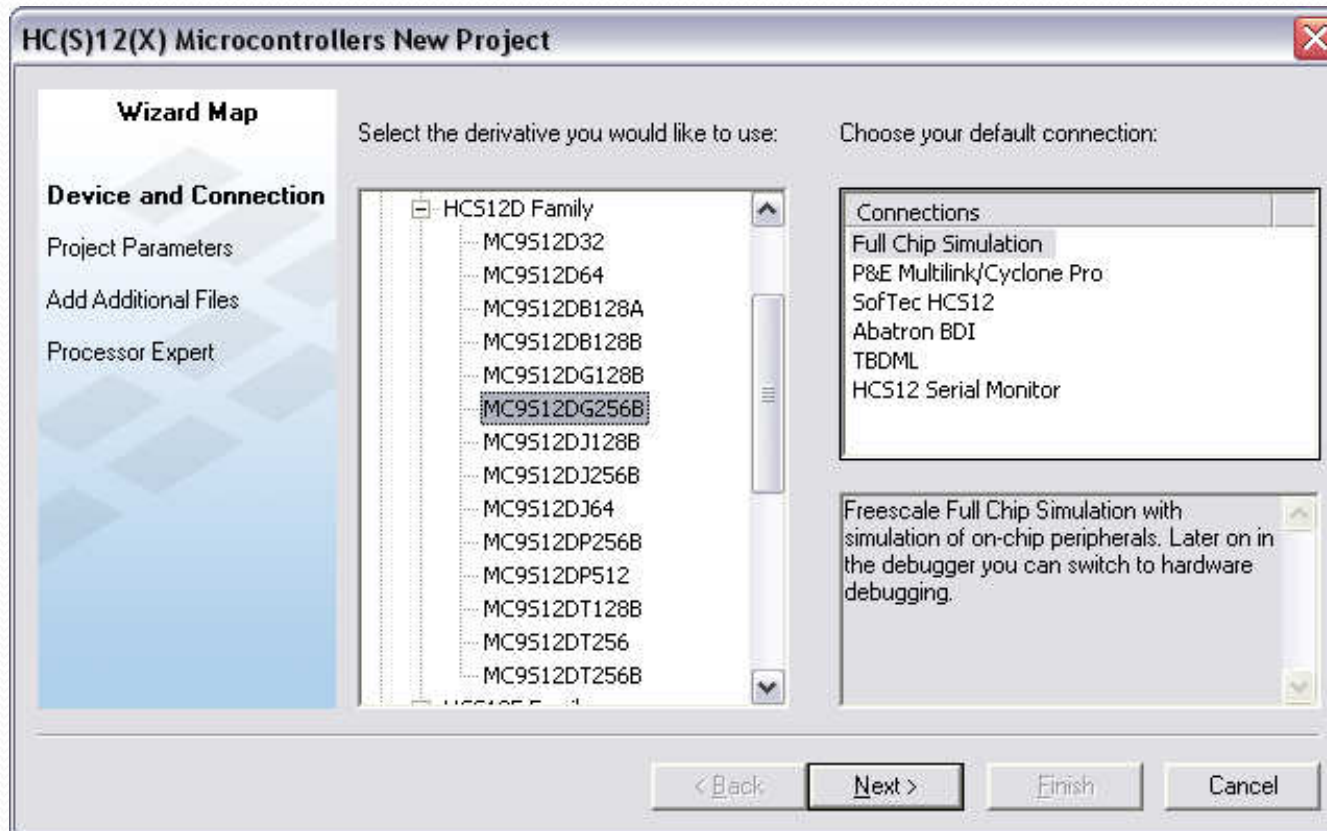
CodeWarrior for HSC12 Assembly Programming

- If CodeWarrior is already running, you may select new project from the file menu or click the icon on the tool bar.



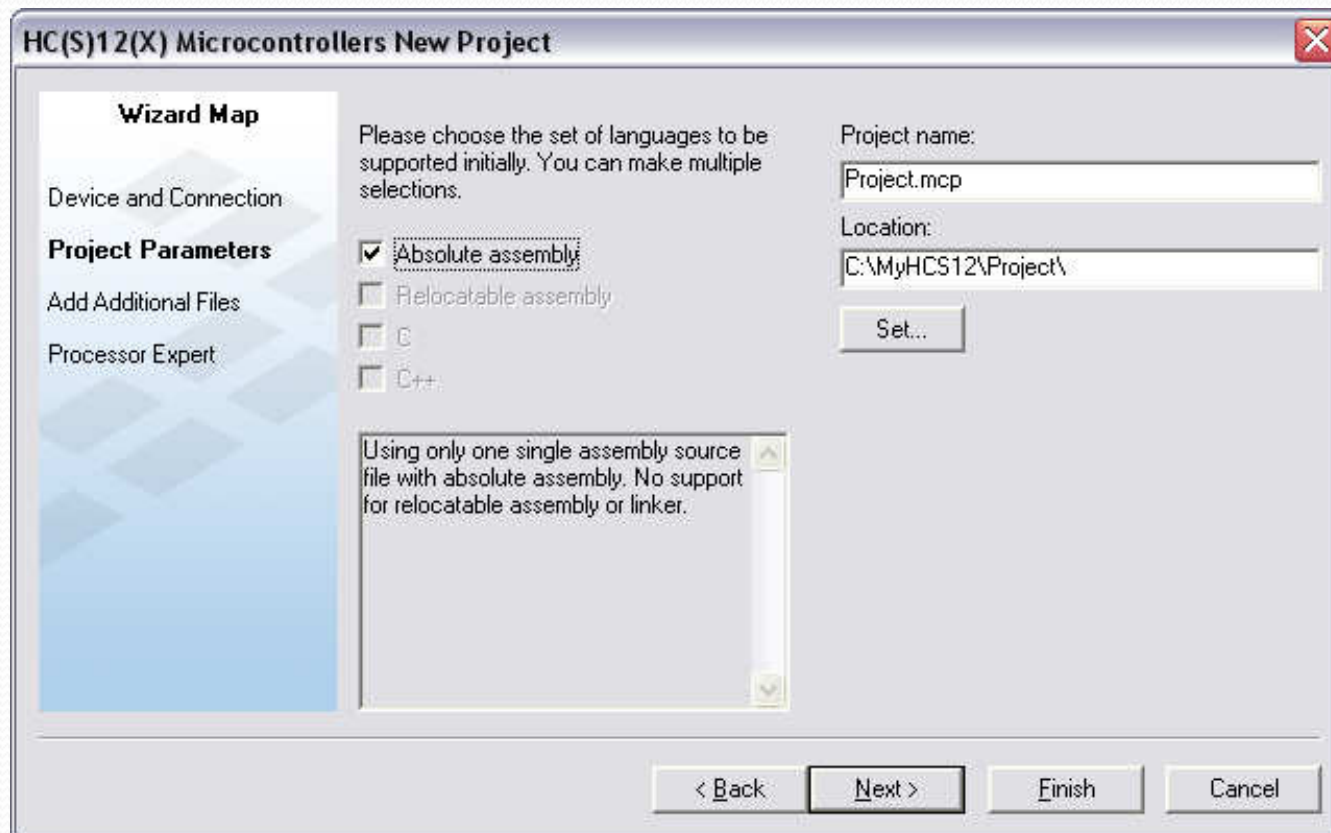
CodeWarrior for HSC12 Assembly Programming

- Select the MCU to program as well as your connection.
 - Choose MC9S12DG256B and Full Chip Simulation (click Next).
 - You can change your connection at any time after creating a project.



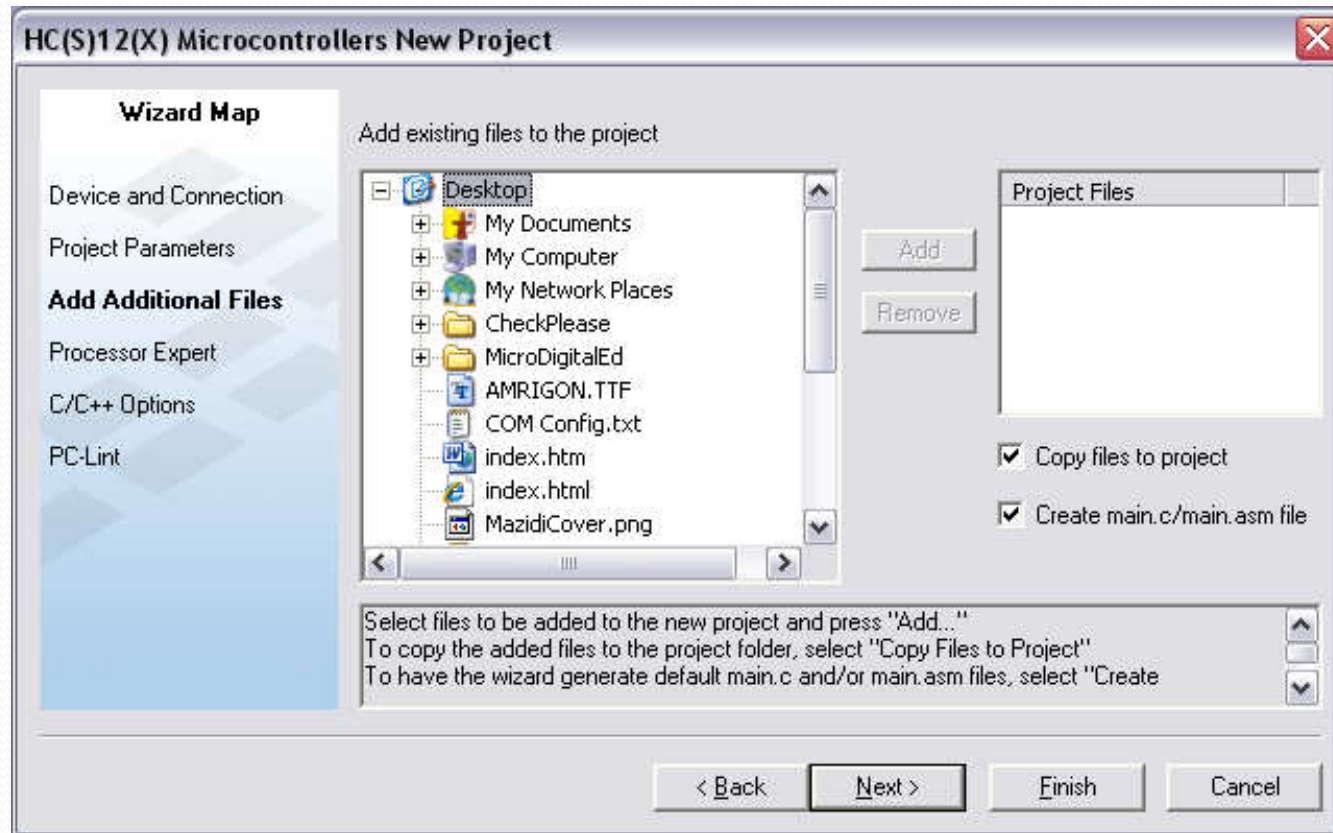
CodeWarrior for HSC12 Assembly Programming

- Set the location where the project is stored and name the project.
- Choose the language(s) you will be using
 - **Unselect** the “Relocatable assembly” then **select** “Absolute assembly” (click Next).



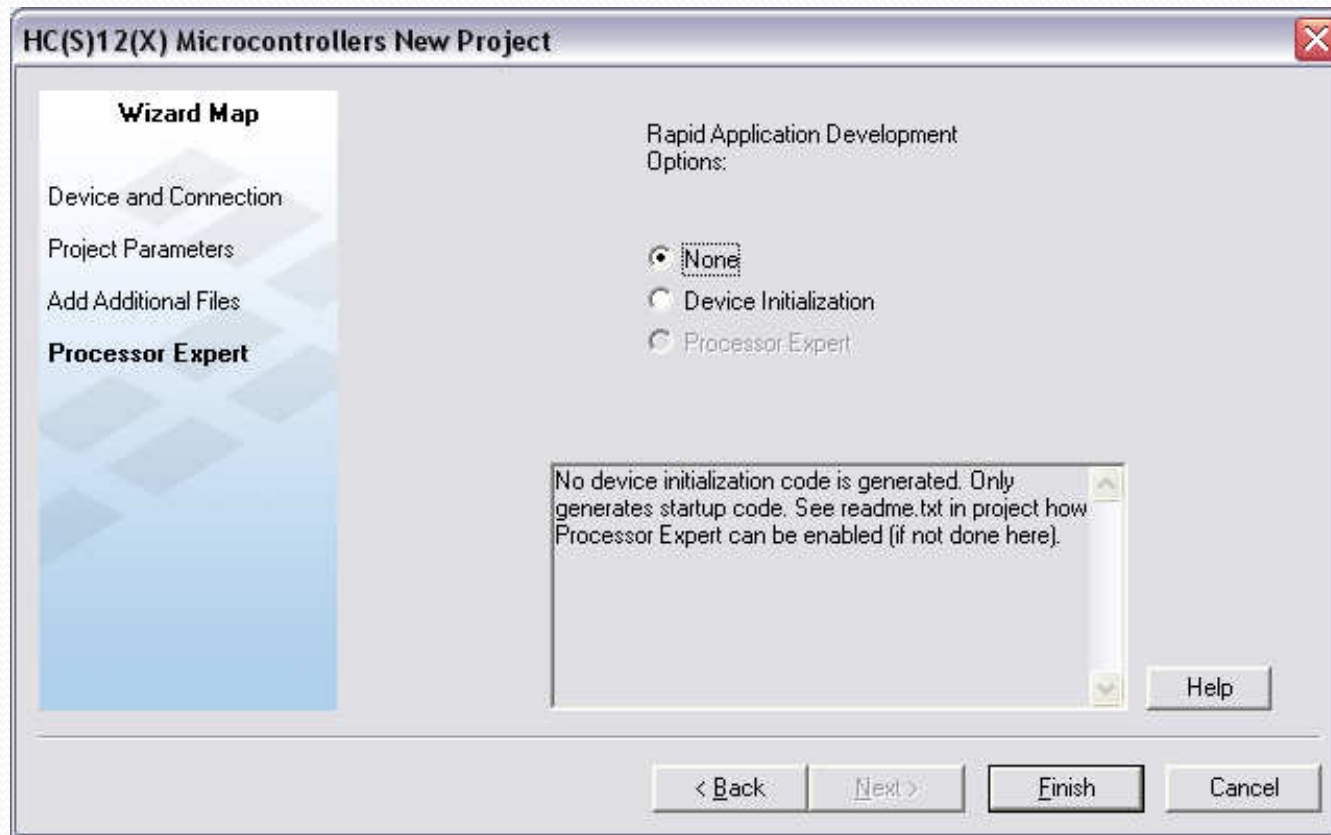
CodeWarrior for HSC12 Assembly Programming

- Choose any files your project will use.
 - In this lecture, no need for any additional files (click Next).
 - You can also add files to your project after it has been created.



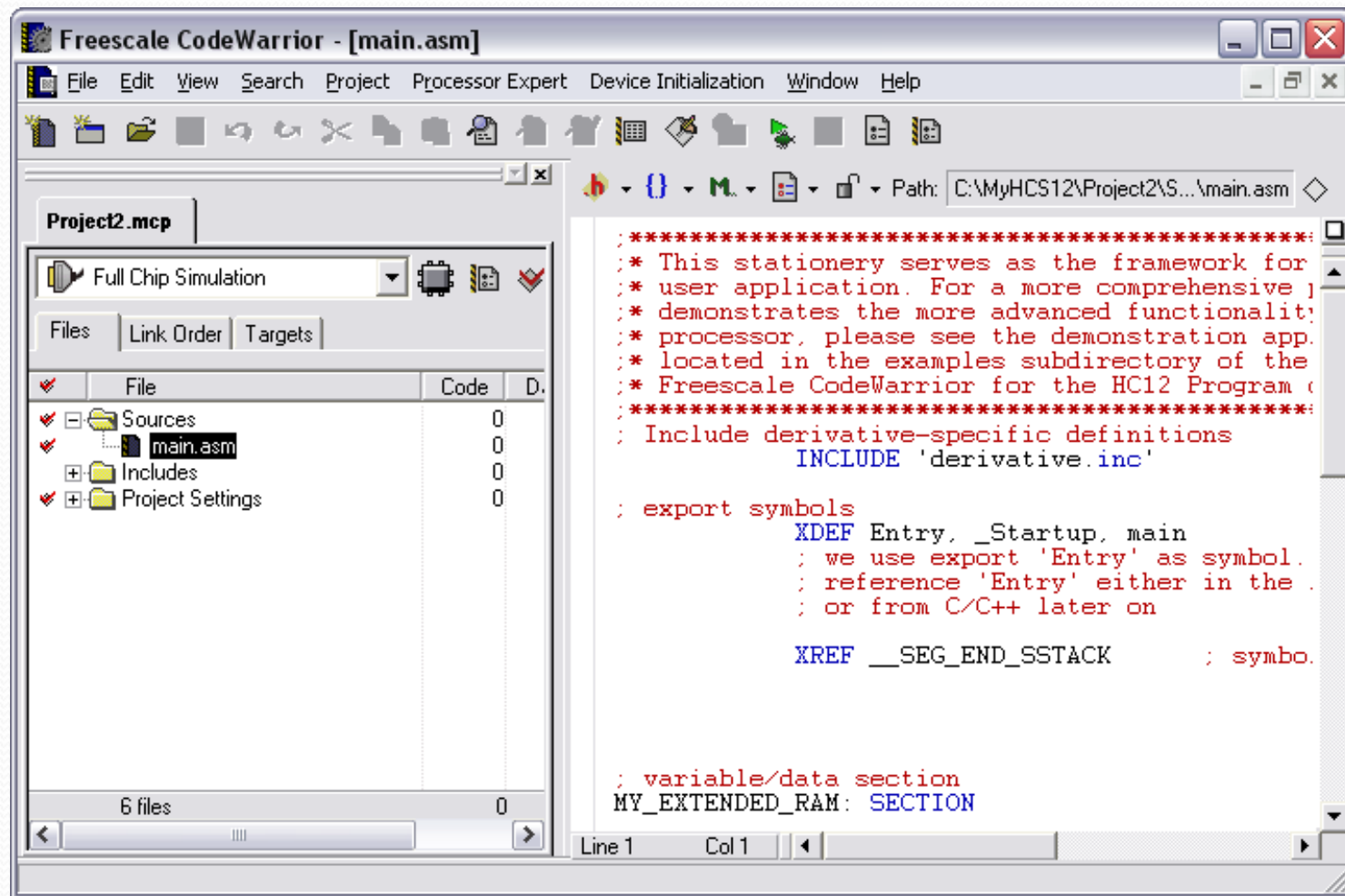
CodeWarrior for HSC12 Assembly Programming

- Choose '**None**' for Rapid Application Development (click Finish).



CodeWarrior for HSC12 Assembly Programming

- Expand the **Sources** folder created by CodeWarrior and double click on main.asm

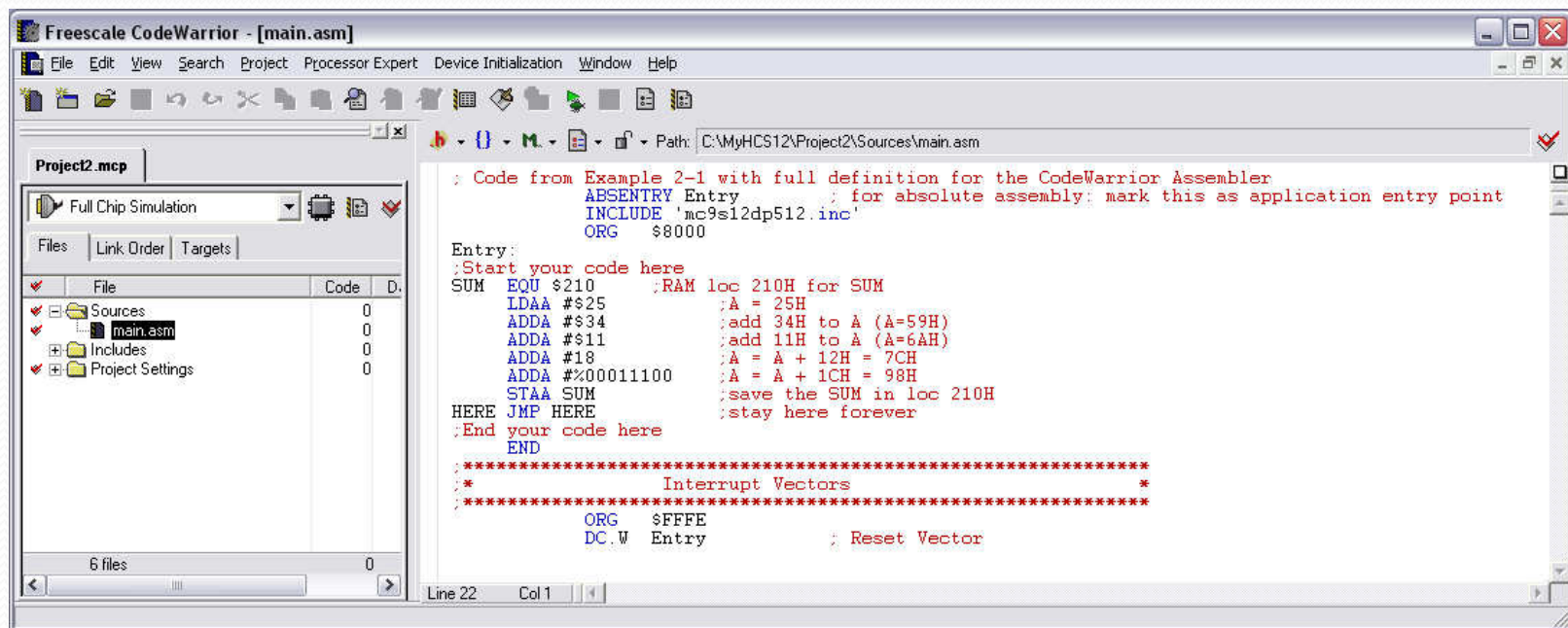


CodeWarrior for HSC12 Assembly Programming

- Minimal requirements for an Assembly program are as follows:
 - ABSEENTRY Entry declaration at the top (i.e., application entry point for absolute assembly).
 - INCLUDE file that defines registers of the MCU.
 - ORG declaration above the Entry label.
 - ORG \$FFFE and DS.W Entry declaration below the program for reset vector.

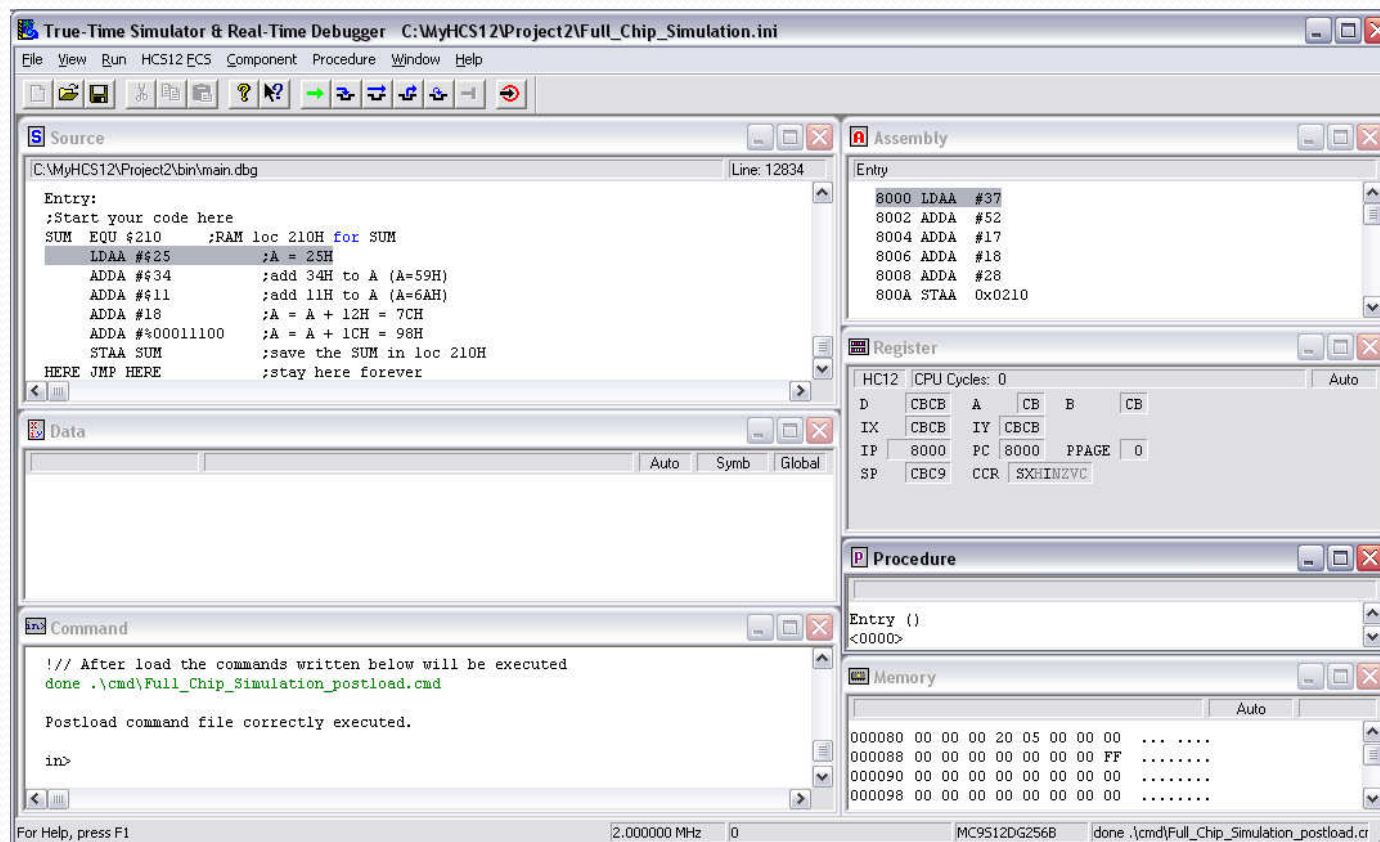
CodeWarrior for HSC12 Assembly Programming

- Note that the book does not define Assembly code this way.
 - This is for compatibility with a variety of Assemblers for the HCS12.
 - You can use the code as template for the examples in the book by replacing the code between Entry: and END.



CodeWarrior for HSC12 Assembly Programing

- Copy the program “Toggling_LEDs_on_PORTB” provided on Moodle course page and paste it into the main.asm program.
- Full Chip Simulation should be selected in the drop-down box
 - Click Make icon (F7) Click Debug (F5).



CodeWarrior for HSC12 Assembly Programming

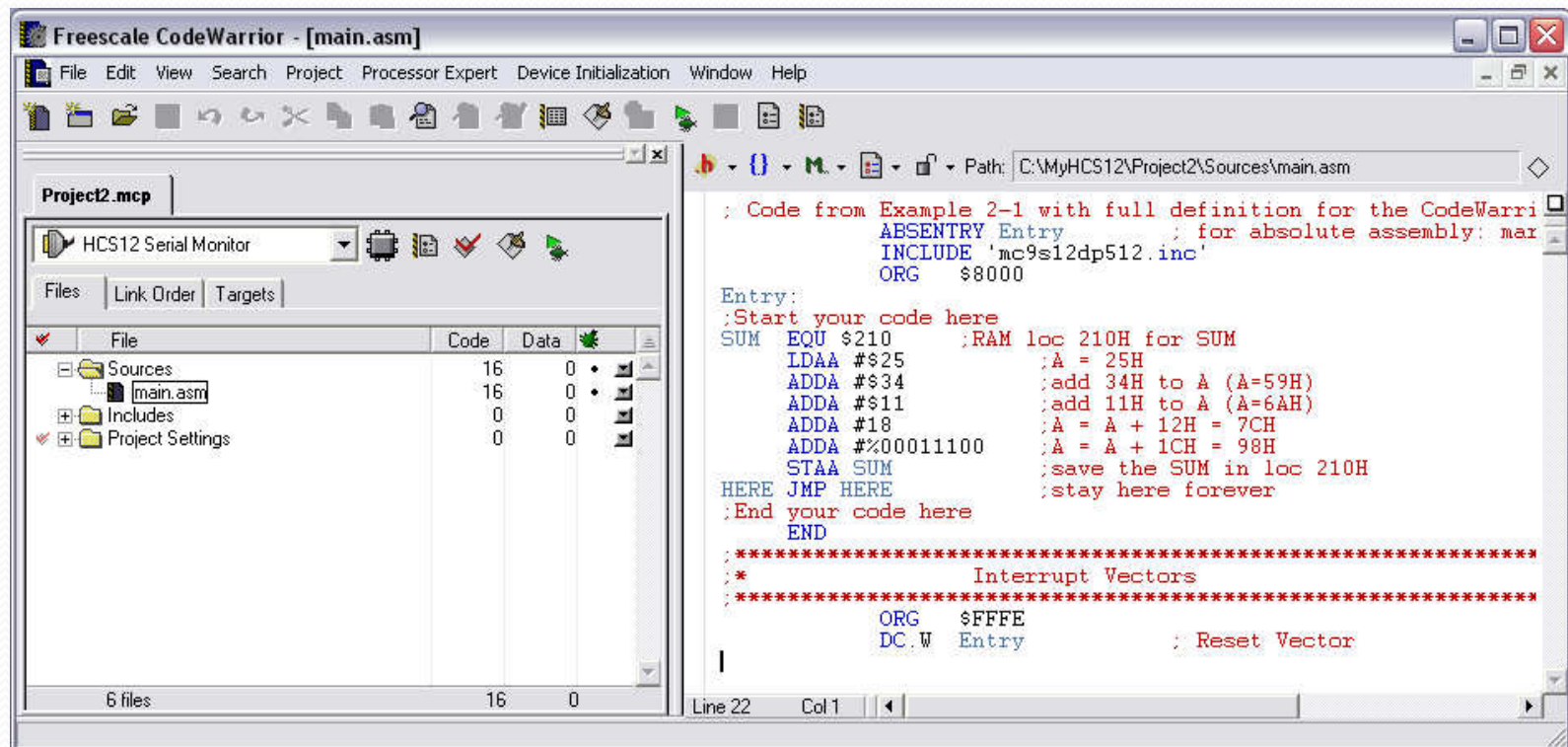
- After clicking F5 (Debug) CodeWarrior will give you “True Time Simulator & Real Time Debugger” screen.
- Use F11 to single step through the program or use blue icons to debug the program.
- To examine the contents of memory locations, click on Memory window and you will see Memory at the top (next to Component).
- Click on Memory and drop-down menu gives you the options
 - See “CodeWarrior_Debugger_HC12” file provided on Moodle course page for more details.

CodeWarrior for HSC12 Assembly Programming

- Compiling, downloading and executing a program for Dragon12-Light Board
 - In the drop-down where it shows Full Chip Simulation choose HCS12 Serial Monitor.
 - Connect your Dragon12 board to the x86 PC USB port and power up the board.
 - Press the RESET button.
 - Then Press F7 (make), F5 (Debug) to Download (make sure you choose the right COM port), and F5 (run) to execute the program.
 - You will see the LEDs toggle on and off.

CodeWarrior for HCS12 Assembly Programming

- Always close the True-time Simulation window, RESET the board, and make sure you are in HCS12 Serial Monitor mode before you download and execute any program.



Parallel I/O Port and Simple I/O Devices

- HCS12 device may have from 48 to 144 pins arranged in 3 to 12 I/O Ports.
 - An I/O port consists of a set of I/O pins and the registers required to control its operation.
 - Each I/O port has a data direction register (DDRx, x is the port name)
 - An I/O pin can be configured for input (0) or output (1).
 - An I/O pin usually serves multiple functions.
 - When it is not used as a peripheral function, an I/O pin can be used as a GP I/O pin.

Parallel I/O Port and Simple I/O Devices

- I/O REGISTERS

- **Device User Guide** (provided on Moodle course page) shows the detailed register map (Section 1.6) of the MC9S12DG256 from \$0000 to \$03FF (1KB).
- Some of the registers which are linked to the most common components in the Dragon12-Light Board will be used.
- The mc9s12dg256.inc file contains all the numeric equivalent of the port numbers as well as memory positions.

Parallel I/O Port and Simple I/O Devices

- I/O REGISTERS

- PORTA

- GPIO register located at \$0000.
 - Connected to the keypad on the Board.
 - If the keypad is used, PORTA must be configured so that the bits 7 to 4 are outputs and the bits 3 to 0 are inputs.
 - This is done via **DDRA** register located at \$0002.
 - For Keypad: $\text{DDRA} \leftarrow \$F0 = 1111000$.

- PORTB

- GPIO register located at \$0001.
 - Connected to the LEDs on the Board.
 - If LEDs are used, PORTB must be configured so that all the bits are outputs.
 - This is done via **DDRB** register located at \$0003.
 - For LEDs and the 7-segment displays: $\text{DDRB} \leftarrow \$FF$.

Parallel I/O Port and Simple I/O Devices

- I/O REGISTERS

- PORTP

- GPIO register located at \$0258.
 - On the Board, the bits 3 to 0 are connected to the cathodes of the 7-segment displays; while the bits 4 to 6 are connected to the RGB LED.
 - If used with the 7-segment display and the RGB LED, PTP must be configured so that the bits are outputs.
 - This is done via **DDRP** register located at \$025A.
 - For the 7-segment displays and RGB LED: $\text{DDRP} \leftarrow \$\text{FF}$.

- PORTH

- GPIO register located at \$0260.
 - Connected to DIP Switch and Push Buttons (last 4 bits) on the Board.
 - To use the DIP Switch and the Push Buttons, we must configure PTH so that the bits are inputs.
 - This is done via **DDRH** register located at \$0262.
 - For DIP Switches: $\text{DDRH} \leftarrow \$\text{00}$.

Parallel I/O Port and Simple I/O Devices

- I/O REGISTERS

- PORTK

- GPIO register located at \$0032.
 - Connected to the LCD controller on the Board.
 - If the LCD Controller is used, PORTK must be configured so that some bits are outputs and other inputs.
 - This is done via **DDRK** register located at \$0033.

Parallel I/O Port and Simple I/O Devices

- I/O REGISTERS

Number of pins available in each parallel port

Port Name	No. of Pins	Pin Name
A	8	PA7~PA0
B	8	PB7~PB0
E	8	PE7~PE0
H	8	PH7~PH0
J	4	PJ7~PJ0
K	7	PK4~PK0
M	8	PM7~PM0
P	8	PP7~PP0
S	8	PS3~PS0
T	8	PT7~PT0
PAD1, PADO	16	PAD15~PADO
L	8	PL7~PL0
U	8	PU7~PU0
V	8	PV7~PV0
W	8	PW7~PW0

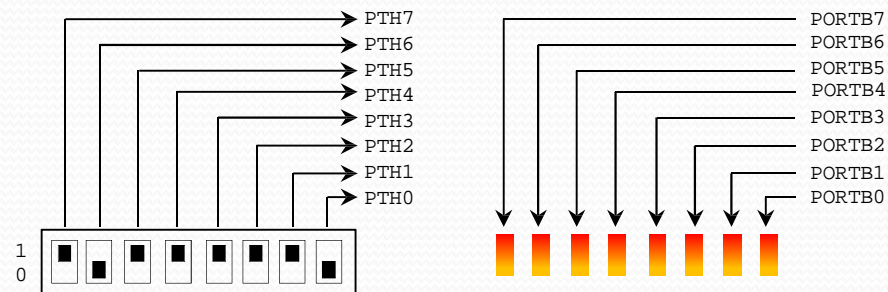
Parallel I/O Port and Simple I/O Devices

- Example 1

Read the DIP switches and output the result to the LEDs.

```
DDRH ← $00
DDRB ← $FF
while (1)
    A ← PORTH
    PORTB ← A
end
```

ASM Code: unit5a.asm



Parallel I/O Port and Simple I/O Devices

• Example 2

Read 4-bit data from DIP switches (the last 4 LSBs) and display the hexadecimal value on the four 7-segment displays.

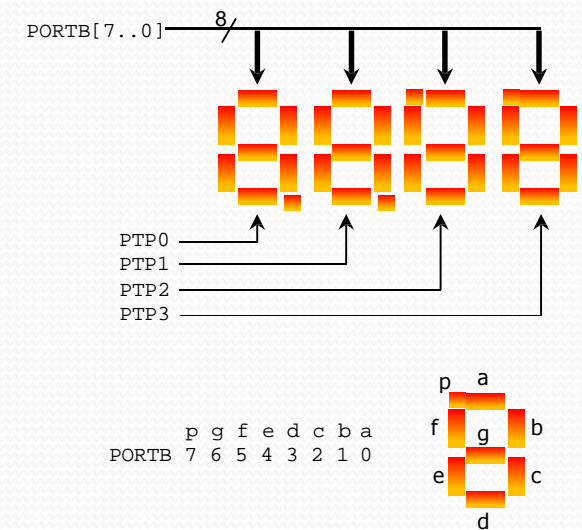
```

DDRB ← $FF, DDRP ← $FF
DDRH ← $00
X ← sevsegdata
PTP ← $00
while (1)
    A ← PORTH
    A ← A AND $0F
    Display data on A on
    all 7-seg displays
    B ← m[[X] + [A]]
    PORTB ← B
end

```

ASM Code: unit5b.asm

Address	8 bits
...	
sevsegdata → 0x1000	\$BF
0x1001	\$86
0x1002	\$DB
0x1003	\$CF
0x1004	\$E6
0x1005	\$ED
0x1006	\$FD
0x1007	\$87
0x1008	\$FF
0x1009	\$EF
0x100A	\$F7
0x100B	\$FC
0x100C	\$B9
0x100D	\$DE
0x100E	\$F9
0x100F	\$F1
...	



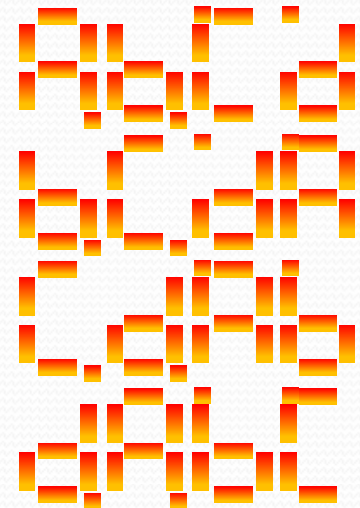
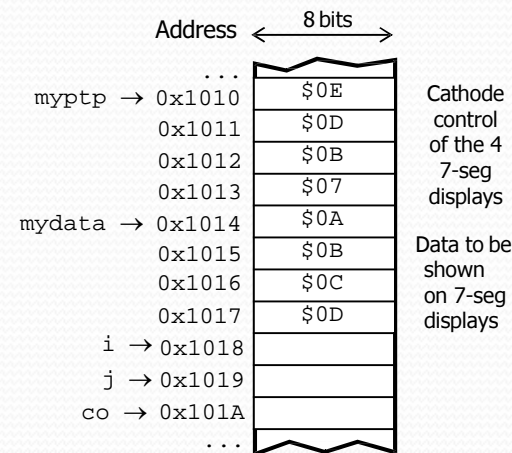
Parallel I/O Port and Simple I/O Devices

- Example 3

Read 4 bytes of data from memory and display the hexadecimal values on the four 7-segment displays. Then, rotate the 4 digits to the left every 1 second. For visual persistence, display each digit for only 1 ms. This delay was computed using a bus speed of 24 MHz (this requires an extra piece of code, this code could not run on the Debugger step by step).

```
X ← sevsegdata
Y ← myptp
co ← 0      ; indicates the 'shift'
while (1)
  for j = 0 to 249
    for i = 0 to 3
      idx ← i + co
      if i+co ≥ 4 then
        idx ← i+co-4
      end
      Display data on
        'idx+mydata' on display 'i'
      Delay 1 ms
    end
  end
  co ← co+1
  if co ≥ 4 then
    co ← 0
  end
end
```

ASM Code: unit5c.asm



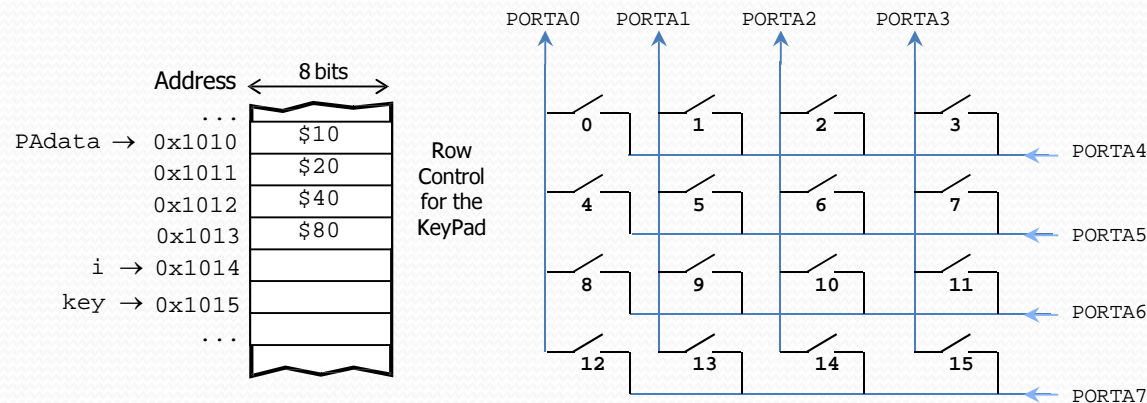
Parallel I/O Port and Simple I/O Devices

- Example 4

Read the key pad, and display the hexadecimal value on all 7-segment displays.

	Output	Input			
	PORTA[7..4]	PORTA[3..0] = 0001 idx = 0	PORTA[3..0] = 0010 idx = 1	PORTA[3..0] = 0100 idx = 2	PORTA[3..0] = 1000 idx = 3
i=0	0001	KEY0	KEY1	KEY2	KEY3
i=1	0010	KEY4	KEY5	KEY6	KEY7
i=2	0100	KEY8	KEY9	KEY10	KEY11
i=3	1000	KEY12	KEY13	KEY14	KEY15

$$\text{KEY} = 4*i + \text{idx}$$



Parallel I/O Port and Simple I/O Devices

- Example 4 (contd.)

Read the key pad, and display the hexadecimal value on all 7-segment displays.

Main Routine	getidx subroutine. Input: A(3..0)
<pre>DDRA ← \$F0, DDRB ← \$FF, DDRP ← \$FF, DDRH ← \$00 E← sevsegdata PTP ← \$00 Ψ← PAdata while (1) for i = 0 to 3 PORTA ← [PAdata + i] Delay 1 ms A ← PORTA ; Read PORTA idx = getidx (A(3..0)) If idx = 15 then Display blank on all 7-seg displays else key ← i*4 + idx ; Display hex value of 'key' on all 7-seg displays end end end end</pre>	<pre>if A(3..0) = 1000 idx = 3 elseif A(3..0) = 0100 idx = 2 elseif A(3..0) = 0010 idx = 1 elseif A(3..0) = 0001 idx = 0 else idx = 15 end if</pre>

ASM Code: unit5d.asm

Parallel I/O Port and Simple I/O Devices

• Example 5

RGB LED control via DIP switch.

PORTP4 = RED LED cathode, PORTP5 = BLUE LED cathode, PORTP6 = GREEN LED cathode.

The anodes of these 3 LEDs are connected to PTM2. All the pins that control the LEDs are in negative logic.

Input: PTH[2..0]. PTH2 = Red, PTH1 = Green, PTH0 = Blue

Output: PTP[6..4]. /R = not (PTP4), /G = not (PTP6), /B = not (PTP5).

```
DDRH ← $00, DDRM ← $FF, PTM ← $00;
PTM2 = 0          ; sets the anodes to '1'
while (1)
  A ← PTH
  A ← A AND $07    ; A stores only the 3 LSBs or PORTH
  temp(4) ← A(2), temp(6) ← A(1), temp(5) ← A(0)
  ; Rewires the bits of PTH[2..0] into PTP[6..4]
  PTP ← temp       ; PTP controls the cathodes.
  if a bit in PTP is '1' then
    that cathode is '0'
  end
```

ASM Code: unit5e.asm

R	G	B	Color
0	0	0	Black
0	0	1	Blue
0	1	0	Green
0	1	1	Cyan
1	0	0	Red
1	0	1	Magenta
1	1	0	Yellow
1	1	1	White

