

**Golf Simulator in Scilab:
Capturing a swing and estimating the cary
with a tiny low-cost Radar**

Matthieu PHILIPPE
Publication Perso

February 2, 2025



Contents

1	Introduction	2
2	Golf Ball Flight	3
2.1	Drag Force	3
2.1.1	Air characteristics	3
2.1.2	Ball's characteristics in the air	3
2.2	Magnus Force	4
2.3	Gravity Force	5
2.4	Launch Velocity	5
2.5	Complete Model of flight	5
2.6	Ball's characteristics bouncing on the grass	5
2.7	Ball's characteristics rolling on the grass	5
3	Golf Ball Capturing	6
3.1	section	6
3.1.1	subsection	6
4	Listings	7
4.1	Golfball.sci	7

List of Figures

List of Tables



Listings

4.1 Listing of the golf ball fligth	7
---	---

List of Equations

2.1 Flight Forces	3
2.3 Air Force Resistance	3
2.3 Ball Mass, Diameter, Rayon, Intertia, Section, Reyolds Number	4
2.6 Drag Coefficient, Drag Force	4
2.11 Magnus Lift Force	5
2.13 Magnus Lift Force	5
2.14 Magnus Lift Force	5
2.14 My Cl1	5

List of Remarks

1 Finally, the equation of the drag Force along the 3-axes becomes 2.7	4
2 Knowing 2.8 and 2.14, we have the following Magnus force vector	5

List of definitions



ABSTRACT

By using the equations of golf ball flight dynamics, this article demonstrates how to code a swing simulator for a ball in Scilab.

The simulator uses an ODE (ordinary differential equation) solver from Scilab, the fluid dynamics equations on a ball (taking into account gravity, drag forces, and Magnus forces), the restitution of forces from a golf club applied to a ball for launches, its flight, bounce and roll.

In the second part, the article presents a method for capturing the speed of the ball in flight using 2 low-cost radars, coupled with an Arduino Mini and an adapted sound card.

The radar signal is recorded in WAV format and filtered to extract speed and spin information during flight, using spectral density.

Keywords: *Golf Ball, Simulator, Scilab, Radar, Spectral density.*



Chapter 1

Introduction

After spending a few years playing golf, I wanted to learn more about the dynamics of the interactions between the club, the ball, and the elements.

Of course, the academic literature and publications were quite abundant. But I came accross articles [PWB76] written in 1976 and [SS94] in 1994. The description of the ball's physics pushed me to undertake modeling this system in Scilab. Subsequently, I did it in Java, C++, and then C# to use it under *Unity game engine*®™.

When the results were satisfactory, I thought about capturing the flight of a golf ball with instrumentation. After tests with sonar, which were largely insufficient, I took small presence detection radars for automatic doors.

I didn't know what I was getting into, but after a updating my knowledge on signal filtering and a few lines of programming in Scilab, I found a way to capture the essential data. Namely the speed and backspin of the flight of a golf ball.

This article describes all items I found, and how I set all them together. Equations, programs, filtering, estimators and electronics compounents to make a Virtual Golf Simulation.

All the equations presented in this article are derived from public publications or books, with references listed in the bibliography. I will not revisit the demonstrations and physical explanations, as they are not the focus of these pages. What matters to me is the relationship between this information and how I have used or adapted it.



Chapter 2

Golf Ball Flight

The main equation is the ball's flight. The equation accounts 3 forces : Magnus Force, Air Drag Force and gravity, such as :

$$\sum F = F_M - m.g + F_d \quad (2.1)$$

2.1 Drag Force

2.1.1 Air characteristics

The Air Drag Force resistance is determined by the relation given by [BR] as 2.3 :

$$\rho(T) = 1,292 * \frac{273,15}{273,15 + T} \quad (2.2)$$

$$F_d(V) = -\frac{1}{2} \cdot \rho(T) \cdot C_d \cdot S \cdot V^2(t) \quad (2.3)$$

where:

$$\begin{aligned} \rho(T) &= \text{Rho depending on temperature } T \\ C_d &= \text{Drag Coefficient, depending on the object} \\ F_d(V) &= \text{Drag Force due to Air Resistance depending on velocity } V \end{aligned}$$

2.1.2 Ball's characteristics in the air

Considering those characteristics of a dimpled ball model,



$$\begin{aligned}
\text{mass } m &= 0,04593 \text{ g} \\
\text{Dynamic viscosity } \mu &= 1,5 \cdot 10^{-6} \text{ m}^2/\text{s} \\
\text{Diameter } D &= 0,04267 \text{ m} \\
\text{Radius } r &= \frac{D}{2} \\
\text{Inertia } I &= \frac{2}{5} \cdot m \cdot R^2 \\
\text{Cross-section } S &= \pi \cdot R^2 \\
\text{Ball Velocity} &= V
\end{aligned}$$

We have an estimated models,

$$Re = \frac{\rho(T) \cdot V \cdot D}{\mu} \quad (2.4)$$

$$Cd = 0,36 + \frac{24}{Re} + \frac{6}{1 + \sqrt{Re}} \quad (2.5)$$

$$\vec{F}_d = -\frac{1}{2} \cdot \rho(T) \cdot Cd \cdot S \cdot \sqrt{(V(x)^2 + V(y)^2 + V(z)^2)} \cdot \hat{V}(x) \quad (2.6)$$

where,

$$\begin{aligned}
Re &= \text{Reynolds Number estimator} \\
Cd &= \text{Drag Coefficient White's relation} \\
\vec{F}_d &= \text{Drag Force}
\end{aligned}$$

Remark 1: Finally, the equation of the drag Force along the 3-axes becomes 2.7

$$\vec{F}_d = \begin{pmatrix} -\frac{1}{2} \cdot \rho(T) \cdot Cd \cdot S \cdot V_x^2 \\ -\frac{1}{2} \cdot \rho(T) \cdot Cd \cdot S \cdot V_y^2 \\ -\frac{1}{2} \cdot \rho(T) \cdot Cd \cdot S \cdot V_z^2 \end{pmatrix} \quad (2.7)$$

2.2 Magnus Force

The main bibliography is [PAL05] et [SS94]. The Magnus Force depends on the Lift Coefficient. I have found several ways to calculate the Cl. given in 2.11, 2.13 or 2.13.

Given several Magnus Force equations bellow, found in litterature,

$$\vec{F}_M = Cm \cdot (\vec{\omega} \times \vec{V}) \quad (2.8)$$

$$F_M = 1/2 \cdot Cm \cdot \rho \cdot \mu^2 \quad (2.9)$$

$$Cm = \frac{r\omega}{V} \quad (2.10)$$

$$Cm = -0,05 + \sqrt{0,0025 + 0,36 \left(\frac{r\omega}{V_m} \right)} \quad ([PAL05]) \quad (2.11)$$



where,

$$\begin{aligned}\omega &= \text{spin in rad/s} \\ V_p &= r\omega \text{ periferal velocity} \\ V_m &= \text{Ball Velocity}\end{aligned}$$

And, espacially in [SS94] or [Ala98], an expression of Magnus Lift Coefficient.

$$Cl = \frac{1}{2 + (v/R * \sin(\zeta))} \zeta \text{ to be the angle between the axis of rotation and the direction of motion} \quad (2.12)$$

$$Cm = 0,5 \cdot \rho(T) \cdot S \cdot R^2 \cdot Cl \cdot \left| \frac{\omega}{V_m} \right|^{0,4} \cdot V_m \quad ([SS94]) \quad (2.13)$$

In order to meet my needs, I have chosen to provide adapted Cl values to (2.13) from experience with my own balls (texture and number dipples). These data are recorded in a Scilab table Cl_1 :

$$Cm = 0,5 \cdot \rho(T) \cdot S \cdot R^2 \cdot Cl_1 \cdot \left| \frac{\omega}{V_m} \right|^{0,4} \cdot V_m \quad (2.14)$$

$$\text{with my own } Cl_1(\text{Club}, \text{myball}) = \begin{bmatrix} 'D'; 'W5'; 'H3'; '5'; '6'; '7'; '8'; '9'; 'PW'; 'AW'; 'SW'; 'LW'; 'PU' \\ [0.64; 0.65; 0.54; 0.54; 0.83; 0.42; 0.53; 0.53; 0.52; 0.52; 0.51; 0.51; 0] \end{bmatrix}$$

Remark 2: Knowing 2.8 and 2.14, we have the following Magnus force vector

$$\vec{F}_m = \begin{pmatrix} Cm * (\omega_j * v_k - \omega_k * v_j) \\ Cm * (\omega_k * v_i - \omega_i * v_k) \\ Cm * (\omega_i * v_j - \omega_j * v_i) \end{pmatrix} \quad (2.15)$$

2.3 Gravity Force

2.4 Launch Velocity

[Pen01]

2.5 Complete Model of flight

2.6 Ball's characteristics bouncing on the grass

[RL10]

2.7 Ball's characteristics rolling on the grass

[Pen02b] [Pen02a]



Chapter 3

Golf Ball Capturing

3.1 section

section

3.1.1 subsection

subsection



Chapter 4

Listings

4.1 Golfball.sci

```
1 // Copyright (C) 2016 - Corporation - Author
2 //
3 // About your license if you have any
4 //
5 // Date of creation: 16 juin 2016
6 //
7 //SCI2C: DEFAULT_PRECISION= DOUBLE
8 //
9 // ReadWave : FFT_Mat.sce
10 //
```

Listing 4.1: Listing of the golf ball fligth



Bibliography

- [Ala98] Leroy Alaways. Aerodynamics of the curve-ball: An investigation of the effects of angular velocity on baseball trajectories. 01 1998.
- [BR] Burglund Brett and Street Ryan. Golf ball flight dynamics 5-13-2011 1. <https://www.math.union.edu/~wangj/courses/previous/math238w13/Golf>
- [PAL05] GRANT PALMER. *Physics for Game Programmers*. APRESS, 2005.
- [Pen01] Albert Penner. The physics of golf: The optimum loft of a driver. *American Journal of Physics - AMER J PHYS*, 69, 05 2001.
- [Pen02a] Albert Penner. The physics of putting. *Canadian Journal of Physics*, 80:83–96, 02 2002.
- [Pen02b] Albert Penner. The run of a golf ball. *Canadian Journal of Physics*, 80:931–940, 07 2002.
- [PWB76] J K HARVEY P W BEARMAN. Flight : Golf ball aerodynamics. In Imperial College Of Science and Technolgy, editors, *Journal of The AERONAUTICAL QUARTERLY*, volume v27, pages 112–122, 1976.
- [RL10] Woo-Jin Roh and Chong-Won Lee. Golf ball landing, bounce and roll on turf. *Procedia Engineering*, 2:3237–3242, 06 2010.
- [SS94] Alexander Smits and D.R. Smith. A new aerodynamic model of a golf ball in flight. *Science and Golf II*, pages 340–347, 01 1994.