



# Probabilistic Machine Learning

## Exercise Sheet #1

due on Tuesday 27 April 2021, 10am sharp

- 1. **EXAMple Question** The lecture introduced the two foundational rules of probabilistic reasoning, called
  - (a) the Sum Rule and
  - (b) the Product Rule, as well as their direct consquence,
  - (c) Bayes' Theorem

Formally state all three of them.

2. **Theory Question** Assume that, if A is true, B becomes more plausible. That is,

$$P(B|A) \ge P(B)$$
.

Using the rules of probability stated above, show the following relationships (stated in the lecture without proof)

(a)  $P(B|\neg A) \leq P(B)$  ("If A is false, B becomes less plausible")

(b)  $P(A|B) \ge P(A)$  ("If B is true, A becomes more plausible")

(c)  $P(A|\neg B) \leq P(A)$  ("If B is false, A becomes less plausible")

Additionally show that probabilistic reasoning includes Boolean logic as a special case, by showing that if  $A \Rightarrow B$  is interpreted as equivalent to  $P(B \mid A) = 1$ , then the following two statements hold:

(d)  $P(\neg A \mid \neg B) = 1$  ("modus tollens")

(e)  $P(B \mid \neg A) \leq P(B)$  ("If A is false, B becomes less plausible")

(f)  $P(A \mid B) \ge P(A)$  ("if B is true, A becomes more plausible")

3. Practical Question In previous lecture courses you have become accustomed with various models of *Deep Learning*. In popular texts it can sometimes sound as if deep learning has made all other concepts of machine learning obsolete. The point of this exercise is to reflect on this sentiment. On Ilias you can find a jupyter notebook that loads the famous "Keeling curve", a time series of atmospheric CO<sub>2</sub> concentrations collected at the Mauna Loa observatory in Hawaii. Your task is, using only a deep learning framework (like TensorFlow, pyTorch, etc.) to produce an *extrapolation* of this dataset from today 40 years into the future, until 2060. You are free to use whichever architecture you like, but try to use only 'deep neural networks' (that's a vague term, of course).

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1) For the probability space (2, F, P): a)  $\forall A, B \in \mathcal{F}: P(A) = P(A, B) + P(A, B)$ , where  $\neg B = \mathcal{R} \setminus B$ b)  $\forall A, B \in \mathcal{F}$ : P(A, B) = P(A|B)P(B) = P(B|A)P(A)c)  $P(B|A) \stackrel{4d}{=} \frac{P(A,B)}{P(A)} = \frac{P(A|B)P(B)}{P(A,B)+P(A,-B)}$  $\frac{2}{a)} P(B|A) = \frac{P(B,A)}{P(A)} = \frac{P(B) - P(A,B)}{P(A)} = \frac{P(B) - P(B|A) P(A)}{P(A)}$  $\frac{P(B) - P(B)P(A)}{P(A)} = P(B) \frac{A - P(A)}{P(A)} = P(B)$ b)  $P(A \mid B) = \frac{P(B \mid A) P(A)}{P(B)} = \frac{P(B) P(A)}{P(B)} = P(A)$ c)  $P(A \mid \neg B) = \frac{P(\neg B \mid A) P(A)}{P(\neg B)} = \frac{(A - P(B \mid A)) P(A)}{P(\neg B)} = \frac{(A - P(B \mid A)) P(A)}{P(\neg B)}$  $\frac{(\Lambda - P(B)) P(A)}{(\Lambda - P(B))} = P(A)$ d)  $P(1A|1B) = 1 - P(A|1B) = 1 - \frac{P(1B|A)}{1 - P(B)}$  = 1 - P(A) = 1

e) and f) follow direct by from a) and b) respectively,

because P(BIA) = 1 => P(BIA) > any probability => P(BIA) > P(B).

## ExerciseSheet 01

April 23, 2021

### 1 Probabilistic Machine Learning

University of Tübingen, Summer Term 2021

#### 1.1 Exercise Sheet 1

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This sheet is due on Tuesday 27 April 2021 at 10am sharp.

#### 1.2 Deep Learning on the Keeling curve

In previous lecture courses you have become accustomed with various models of *Deep Learning*. In popular texts it can sometimes sound as if deep learning has made all other concepts of machine learning obsolete. The point of this exercise is to reflect on this sentiment.

You will work with the famous Keeling curve, a time series of atmospheric CO2 concentrations collected at the Mauna Loa observatory in Hawaii. Your task is to produce an extrapolation of this dataset from today 40 years into the future, using a deep learning framework. This notebook will download the data and train a basic neural network using pytorch.

```
[1]: from matplotlib import pyplot as plt
%matplotlib inline

import pandas as pd
import torch
import torch.nn as nn
```

#### 1.2.1 1) Load Data

As a first step, let's load the CO2 data into a pandas dataframe.

```
header=52,
    usecols=[0, 1, 2, 3],
    names=['Year', 'Month', 'DecimalDate', 'CO2_av'])
display(data)
```

```
Year
         Month DecimalDate CO2 av
0
    1958
              3
                   1958.2027 315.70
1
    1958
                   1958.2877 317.45
2
    1958
              5
                   1958.3699 317.51
3
    1958
              6
                   1958.4548 317.24
4
              7
    1958
                   1958.5370 315.86
752 2020
             11
                   2020.8750 413.11
753 2020
             12
                   2020.9583 414.25
754 2021
             1
                   2021.0417 415.52
755 2021
              2
                   2021.1250 416.75
756 2021
              3
                   2021.2083 417.64
```

[757 rows x 4 columns]

#### 1.2.2 2) Split Data

Now, we split the data into training and test data.

```
[3]: # Convert to pytorch column "vectors"
X = torch.FloatTensor(data['DecimalDate'].values).reshape(-1, 1)
Y = torch.FloatTensor(data['CO2_av']).reshape(-1, 1)

# Use the last TEST_LENGTH months for testing, the rest for training
TEST_LENGTH = 3 * 12

# Training data
X_train = X[:-TEST_LENGTH]

Y_train = Y[:-TEST_LENGTH]

# Test data
X_test = X[-TEST_LENGTH:]
Y_test = Y[-TEST_LENGTH:]

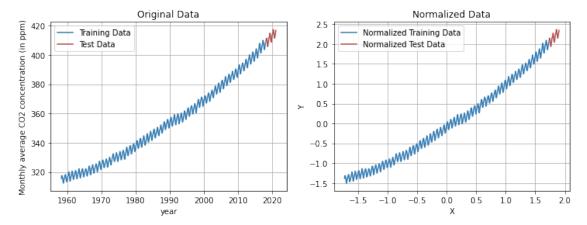
# Data for prediction
PRED_LENGTH = 40 * 12
X_pred = (X[-1] + torch.arange(1, PRED_LENGTH + 1) / 12.0).reshape(-1, 1)
```

#### 1.2.3 3) Preprocess Data

Let's normalize our data.

```
[4]: def apply_transform(data_list, shift, scale):
          """Return list of normalized data"""
          return [(data - shift) / scale for data in data_list]
      # Normalize X data
      X_shift = X_train.mean()
      X_scale = X_train.std()
      X_norm = apply_transform([X_train, X_test, X_pred],
                                shift=X shift, scale=X scale)
      [X_train_norm, X_test_norm, X_pred_norm] = X_norm
      # Normalize Y data
      Y_shift = Y_train.mean()
      Y_scale = Y_train.std()
      Y_norm = apply_transform([Y_train, Y_test],
                                shift=Y_shift, scale=Y_scale)
      [Y_train_norm, Y_test_norm] = Y_norm
[59]: col_train = '#327bb3' # blue
      col_test = '#b04f4f' # red
      col_pred = '#4fb062' # green
 [6]: # Visualization
      fig, axs = plt.subplots(1, 2, figsize=(12, 4))
      # Subplot 1: Original data
      ax = axs[0]
      ax.plot(X_train, Y_train,
              color=col_train, label='Training Data')
      ax.plot(X_test, Y_test,
              color=col_test, label='Test Data')
      ax.set_xlabel('year')
      ax.set_ylabel('Monthly average CO2 concentration (in ppm)')
      ax.set_title('Original Data')
      ax.grid()
      ax.legend()
      # Subplot 2: Normalized data
      ax = axs[1]
      ax.plot(X_train_norm, Y_train_norm,
              color=col_train, label='Normalized Training Data')
      ax.plot(X_test_norm, Y_test_norm,
              color=col_test, label='Normalized Test Data')
      ax.set_xlabel('X')
      ax.set_ylabel('Y')
```

```
ax.set_title('Normalized Data')
ax.grid()
ax.legend()
plt.show()
```



#### 1.2.4 4) Train the Neural Network

Define the model architecture, the loss function and the optimizer. Use the normalized data to train the neural network for a given number of epochs.

```
[7]: # Set seed value for reproducibility
     torch.manual_seed(0)
     # Compute on GPU, if available
     DEVICE = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
     # Choose neural network architecture
     model = nn.Sequential(
         nn.Linear(1, 100),
         nn.ReLU(),
         nn.Linear(100, 1)
     ).to(DEVICE)
     print(f'Network nof_parameters = {sum(p.numel() for p in model.
      →parameters())}\n')
     # Choose loss function (suitable for regression tasks)
     loss_func = torch.nn.MSELoss()
     # Choose optimizer and hyperparameters
     optimizer = torch.optim.Adam(model.parameters())
```

```
# Train for NOF_EPOCHS epochs
NOF\_EPOCHS = 500
print('Training Progress...')
for epoch in range(NOF_EPOCHS):
   model.train()
    # Forward pass
    inputs, labels = X_train_norm.to(DEVICE), Y_train_norm.to(DEVICE)
   outputs = model(inputs)
   train_loss = loss_func(outputs, labels)
    # Zero the parameter gradients, backward pass, optimize
   optimizer.zero_grad()
   train_loss.backward()
    optimizer.step()
    # Print progress
   if epoch % (NOF_EPOCHS / 10) == 0:
       model.eval()
       with torch.no_grad():
            # Forward pass on test data
            inputs, labels = X_test_norm.to(DEVICE), Y_test_norm.to(DEVICE)
            outputs = model(inputs)
            test_loss = loss_func(outputs, labels)
            print( f'Epoch {epoch:4};
                  + f'Training Loss: {train_loss.item():.3f};
                  + f'Test Loss: {test_loss.item():.3f}')
```

Network nof\_parameters = 301

```
Training Progress...
```

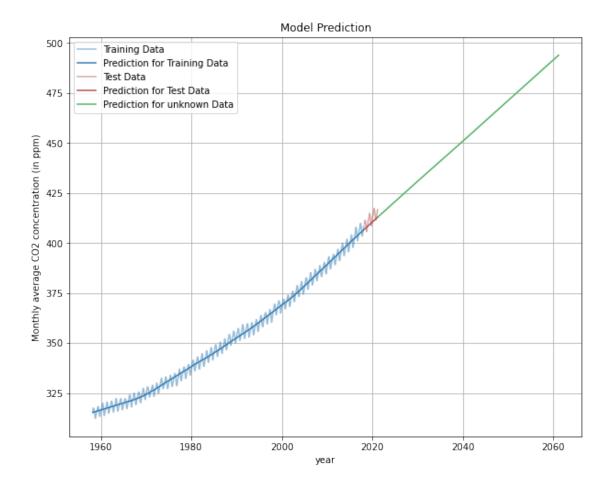
```
Epoch
             Training Loss: 1.344;
                                   Test Loss: 6.862
      0;
Epoch 50;
            Training Loss: 0.049;
                                   Test Loss: 0.231
Epoch 100; Training Loss: 0.019;
                                   Test Loss: 0.063
Epoch 150; Training Loss: 0.009; Test Loss: 0.023
Epoch 200; Training Loss: 0.007;
                                   Test Loss: 0.013
Epoch 250; Training Loss: 0.007;
                                   Test Loss: 0.011
Epoch 300; Training Loss: 0.007;
                                  Test Loss: 0.011
            Training Loss: 0.007; Test Loss: 0.012
Epoch 350;
Epoch 400;
            Training Loss: 0.007;
                                   Test Loss: 0.012
```

#### 1.2.5 5) Evaluate Trained Model

Let's explore the model extraplolation.

```
[8]: # Evaluate trained model
model.eval()
model.to('cpu')
with torch.no_grad():
    Y_train_predict = model(X_train_norm) * Y_scale + Y_shift
    Y_test_predict = model(X_test_norm) * Y_scale + Y_shift
    Y_pred_predict = model(X_pred_norm) * Y_scale + Y_shift
```

```
[9]: # Visualization
     fig, ax = plt.subplots(1, 1, figsize=(10, 8))
     # Training data
     ax.plot(X_train, Y_train,
             color=col_train, label='Training Data', alpha=0.5)
     ax.plot(X_train, Y_train_predict,
             color=col_train, label='Prediction for Training Data')
     # Test data
     ax.plot(X_test, Y_test,
             color=col_test, label='Test Data', alpha=0.5)
     ax.plot(X_test, Y_test_predict,
             color=col_test, label='Prediction for Test Data')
     # Pred data
     ax.plot(X_pred, Y_pred_predict,
            color=col_pred, label='Prediction for unknown Data')
     # General plot settings
     ax.set_xlabel('year')
     ax.set_ylabel('Monthly average CO2 concentration (in ppm)')
     ax.set_title('Model Prediction')
     ax.grid()
     ax.legend()
     plt.show()
```



#### 1.2.6 Your Tasks

First, provide answers to the following two questions.

#### (1) Are you happy with the extrapolation? Why/why not?

**Answer:** No, for three reasons. First, there is obvious yearly periodicity in the data, which is completely ignored by the prediction. Second, the extrapolation seems to grow linearly. In the data, it seems more like exponential growth to me. Third, it is not physically possible for the CO2-concentration to grow indefinitely as would probably be predicted by the model.

### (2) Do you trust the extrapolation? Why/why not?

**Answer:** No, for the reasons listed above.

Task: Your task is to come up with your own solution using a deep learning framework of your choice. First, develop an alternative concept to compute the extrapolation. Write down your idea and briefly describe why and in what way your approach is expected to be an improvement compared to the extrapolation above. A few lines of text should be enough. Note however, that

e.g. just adding layers and changing the optimizer won't be regarded as "sufficient". We want to see that you really put some thought into your concept.

**Your concept:** Two ideas: 1. If the output of the neural network is (a, b, c, d, e, f), let the actual prediction be  $h(t) = a + b \exp(ct) + d \sin(et + f)$ . This should address the first two problems mentioned above. The network has to be optimized with respect to the actual prediction h(t), of course. Of course, now a - f are just parameters that need to be found. In the implementation a neural network is used, but it is always called with the input 1.0 such that a - f are not dependent on the time, that is what h(t) is for.

Task: Actually implement your idea. You can use the above code as a template. Of course, you are free to re-organize the data, modify the network architecture, the optimizer, loss function etc. You can also use a different framework than pytorch, if you want.

#### 2 First idea

```
[169]: class Model(nn.Module):
           def init (self):
               super().__init__()
               self.base = nn.Sequential(
                   nn.Linear(1, 128),
                   nn.ReLU(),
                   nn.Linear(128, 128),
                   nn.ReLU(),
                   nn.Linear(128, 6)
               )
           def forward(self, t):
               a, b, c, d, e, f = self.base(torch.as_tensor([[1.]])).T
               h = a + b*torch.exp(c * t.T) + d*torch.sin(e*t.T + f)
               return h.T
           def loss(self, target):
               pred = model(X_train_norm)
               a, b, c, d, e, f = self.base(torch.as tensor([[1.]])).T
               return (F.mse_loss(pred, target)
                       + 100/torch.abs(e[0])
                                                   # Larger frequency
                       - 0.1*torch.tanh(d[0])
                                                   # Nonzero amplitude
                       - 0.1*torch.tanh(b[0])
                                                   # Positive b
                       - 0.1*torch.tanh(c[0]))
                                                   # Positive c
```

```
[38]: import torch.nn.functional as F
[170]: model = Model()
    optim = torch.optim.Adam(model.parameters())
```

```
for epoch in range(5000):
    optim.zero_grad()
    loss = model.loss(Y_train_norm)
    loss.backward()
    optim.step()
    if epoch % 100 == 0:
        a, b, c, d, e, f = model.base(torch.as_tensor([[1.]])).T
        print(f"Epoch {epoch:3d}, Training Loss = {loss:.4f}, frequency = {e[0]:
        --.4f}, amplitude = {d[0]:.4f}")
```

```
0, Training Loss = 2101.0332, frequency = 0.1391, amplitude = -0.0096
Epoch
Epoch 100, Training Loss = 90.3801, frequency = 1.1108, amplitude = 0.7709
Epoch 200, Training Loss = 53.3111, frequency = 1.8787, amplitude = 0.4358
Epoch 300, Training Loss = 35.8591, frequency = 2.7870, amplitude = 0.2630
Epoch 400, Training Loss = 26.6367, frequency = 3.7455, amplitude = 0.0937
Epoch 500, Training Loss = 21.0532, frequency = 4.7303, amplitude = 0.1067
Epoch 600, Training Loss = 17.3407, frequency = 5.7325, amplitude = 0.1256
Epoch 700, Training Loss = 14.7033, frequency = 6.7494, amplitude = 0.1320
Epoch 800, Training Loss = 12.7374, frequency = 7.7805, amplitude = 0.1047
Epoch 900, Training Loss = 11.2083, frequency = 8.8284, amplitude = 0.1061
Epoch 1000, Training Loss = 9.9862, frequency = 9.8932, amplitude = 0.1078
Epoch 1100, Training Loss = 5.8483, frequency = 16.8396, amplitude = 0.0973
Epoch 1200, Training Loss = 3.6055, frequency = 26.8412, amplitude = 0.1040
Epoch 1300, Training Loss = 2.7533, frequency = 34.7305, amplitude = 0.0988
Epoch 1400, Training Loss = 2.2752, frequency = 41.6047, amplitude = 0.1009
Epoch 1500, Training Loss = 1.9585, frequency = 47.8993, amplitude = 0.0973
Epoch 1600, Training Loss = 1.7285, frequency = 53.8099, amplitude = 0.0980
Epoch 1700, Training Loss = 1.5504, frequency = 59.4887, amplitude = 0.0944
Epoch 1800, Training Loss = 1.4078, frequency = 64.9882, amplitude = 0.1010
Epoch 1900, Training Loss = 1.2909, frequency = 70.3323, amplitude = 0.0974
Epoch 2000, Training Loss = 1.1942, frequency = 75.6580, amplitude = 0.0946
Epoch 2100, Training Loss = 1.1054, frequency = 80.8595, amplitude = 0.0990
Epoch 2200, Training Loss = 1.0320, frequency = 85.9741, amplitude = 0.0991
Epoch 2300, Training Loss = 0.9653, frequency = 91.1629, amplitude = 0.1013
Epoch 2400, Training Loss = 0.9070, frequency = 96.2765, amplitude = 0.0993
Epoch 2500, Training Loss = 0.8548, frequency = 101.3221, amplitude = 0.1041
Epoch 2600, Training Loss = 0.8095, frequency = 106.1202, amplitude = 0.1142
Epoch 2700, Training Loss = 0.7674, frequency = 109.6821, amplitude = 0.1819
Epoch 2800, Training Loss = 0.7672, frequency = 109.5604, amplitude = 0.1897
Epoch 2900, Training Loss = 0.7679, frequency = 109.5600, amplitude = 0.1821
Epoch 3000, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1897
Epoch 3100, Training Loss = 0.7673, frequency = 109.5610, amplitude = 0.1882
Epoch 3200, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
Epoch 3300, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
Epoch 3400, Training Loss = 0.7672, frequency = 109.5613, amplitude = 0.1898
Epoch 3500, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
Epoch 3600, Training Loss = 0.7675, frequency = 109.5610, amplitude = 0.1871
```

```
Epoch 3700, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1897
      Epoch 3800, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 3900, Training Loss = 0.7672, frequency = 109.5611, amplitude = 0.1893
      Epoch 4000, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 4100, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 4200, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1896
      Epoch 4300, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 4400, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1895
      Epoch 4500, Training Loss = 0.7672, frequency = 109.5611, amplitude = 0.1898
      Epoch 4600, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 4700, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
      Epoch 4800, Training Loss = 0.7672, frequency = 109.5613, amplitude = 0.1938
      Epoch 4900, Training Loss = 0.7672, frequency = 109.5610, amplitude = 0.1898
[172]: # Evaluate trained model
       model.eval()
       model.to('cpu')
       with torch.no_grad():
          Y_train_predict = model(X_train_norm) * Y_scale + Y_shift
          Y_test_predict = model(X_test_norm) * Y_scale + Y_shift
          Y_pred_predict = model(X_pred_norm) * Y_scale + Y_shift
[173]: # Visualization
       fig, ax = plt.subplots(1, 1, figsize=(10, 8))
       # Training data
       ax.plot(X_train, Y_train,
               color=col_train, label='Training Data', alpha=0.5)
       ax.plot(X_train, Y_train_predict,
               color=col_train, label='Prediction for Training Data')
       # Test data
       ax.plot(X_test, Y_test,
               color=col_test, label='Test Data', alpha=0.5)
       ax.plot(X_test, Y_test_predict,
               color=col_test, label='Prediction for Test Data')
       # Pred data
       ax.plot(X_pred, Y_pred_predict,
              color=col_pred, label='Prediction for unknown Data')
       # General plot settings
       ax.set xlabel('year')
       ax.set_ylabel('Monthly average CO2 concentration (in ppm)')
       ax.set title('Model Prediction')
       ax.grid()
       ax.legend()
```

## plt.show()

