

The Euler-Lagrange Eq.

Now let us establish the Euler-Lagrange equation for (P) more explicitly. Note that

$$\begin{aligned} & \nabla_{\dot{z}} \left(G \dot{z} \cdot \dot{z} + \sum_{i \in \mathbb{N}_6} \mu_i K_i(z, \dot{z}, t) \right) \\ &= 2 G \dot{z} + \sum_{i \in \mathbb{N}_6} \mu_i \nabla_{\dot{z}} K_i(z, \dot{z}, t) \\ &= 2 G \dot{z} - \Omega(\mu) \dot{z}. \end{aligned}$$

Similarly, we find that

$$\begin{aligned} & \nabla_z \left(G \dot{z} \cdot \dot{z} + \sum_{i \in \mathbb{N}_6} \mu_i K_i(z, \dot{z}, t) \right) \\ &= \Omega(\mu) \dot{z}. \end{aligned}$$

Hence, after rescaling the μ , the Euler-Lagrange equation reads

$$(EL) \quad G \ddot{z} - \Omega(\mu) \dot{z} = 0.$$

Integrating once and using the fact that \dot{z} is of mean zero, we have

$$(E') \quad G \dot{\zeta} - \Omega(\mu) \zeta = 0,$$

and finally by setting $\eta := G^{1/2} \zeta$
we find

$$(E'') \quad \dot{\eta} - \tilde{\Omega}(\mu) \eta = 0,$$

$$\text{where } \tilde{\Omega}(\mu) := \sum_{i \in \mathbb{N}_0} \mu_i G^{-1/2} M_i G^{-1/2}.$$

So the solution of (E'') is simply
given by $\eta(t) = \exp(\tilde{\Omega}(\mu)t) \eta_0$
where $\eta_0 := \eta(0)$.

Note that $\tilde{\Omega}(\mu) \in \text{Skew}_4(\mathbb{R})$. Hence, we
find $Q \in O(4)$ (c.f. previous section) such
that $\tilde{\Omega}(\mu) = Q \tilde{\Sigma}(\mu) Q^T$ with

$$\tilde{\Sigma}(\mu) = \begin{pmatrix} 0 & \sigma_1(\mu) & 0 & 0 \\ -\sigma_1(\mu) & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma_2(\mu) \\ 0 & 0 & -\sigma_2(\mu) & 0 \end{pmatrix}$$

Setting $\phi := Q \eta$ yields $\phi(t) = \exp(\tilde{\Sigma}(\mu)t) \phi_0$
with $\phi_0 := Q \eta_0$.

A straightforward computation shows that

$$\begin{aligned} \phi(t) = & \cos(\sigma_1(\mu)t) \begin{pmatrix} \phi_{0,1} \\ \phi_{0,2} \\ 0 \\ 0 \end{pmatrix} + \sin(\sigma_1(\mu)t) \begin{pmatrix} \phi_{0,1} \\ -\phi_{0,2} \\ 0 \\ 0 \end{pmatrix} \\ & + \cos(\sigma_2(\mu)t) \begin{pmatrix} 0 \\ 0 \\ \phi_{0,3} \\ \phi_{0,4} \end{pmatrix} + \sin(\sigma_2(\mu)t) \begin{pmatrix} 0 \\ 0 \\ -\phi_{0,4} \\ \phi_{0,3} \end{pmatrix}, \end{aligned}$$

which clearly shows that ϕ is a rotation in two orthogonal planes. Setting

$$\phi_1 := \begin{pmatrix} \phi_{0,1} \\ \phi_{0,2} \\ 0 \\ 0 \end{pmatrix}; \quad \phi_1' := \begin{pmatrix} \phi_{0,1} \\ -\phi_{0,2} \\ 0 \\ 0 \end{pmatrix}; \quad \phi_2 := \begin{pmatrix} 0 \\ 0 \\ \phi_{0,3} \\ \phi_{0,4} \end{pmatrix}; \quad \phi_2' := \begin{pmatrix} 0 \\ 0 \\ -\phi_{0,4} \\ \phi_{0,3} \end{pmatrix}$$

we clearly see that these vectors are pairwise orthogonal.

Resubstituting the basis transformations, we find that a solution ζ must be of the form

$$\zeta(t) = \sum_{i \in \mathbb{N}_2} [\cos(\sigma_i(\mu)t) a_i + \sin(\sigma_i(\mu)t) a_i']$$

where $\text{span}(a_1, a_1', a_2, a_2') = \mathbb{R}^4$ and the vectors $U^T a_1, U^T a_1', U^T a_2, U^T a_2'$ are G -orthogonal.

Setting $\tilde{a}_i := U^T a_i$, $\tilde{a}_i' := U^T a_i'$, $i \in \mathbb{N}_2$, we see from the relation between δp and the Fourier coefficients of $\eta = U^T \zeta$ that we cannot have $\sigma_2(\mu) = \sigma_2(\mu)^T$ since

then ϕ would have to be simple.

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