STIR and Tensorflow

Philipp Windischhofer

July 27, 2017

The big picture

- STIR
- iterative reconstruction algorithms
- find the optimum of a *cost function*

$$P(\text{global LOR response}|\text{image}) = \prod_{\text{all LORs}} P(\text{LOR response}|\text{image})$$

$$P(\text{LOR response}|\text{image}) = \int_{\text{LOR}} \text{image density}$$

- Image (estimate) $\rightsquigarrow$ LOR response: *forward projection*

Ray tracing

- in the following: how to compute / approximate this integral?
- represent *image* as a discretized array of voxels

$$\int_{\text{LOR}} \text{image density} \rightsquigarrow \sum_{\text{traversed voxels}} \text{LOI} \cdot \text{voxel brightness}$$

- LOI = length of intersection of the LOR through a specific voxel

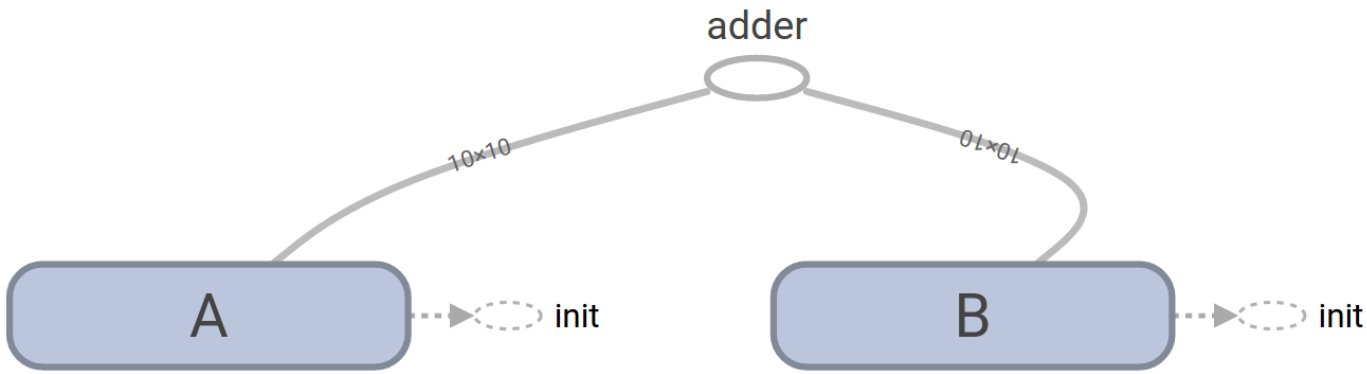
(Standard) STIR spends $> 90\%$ of the reconstruction time for *forward projection*

- is there a way to make it faster?

Table of Contents

Tensorflow

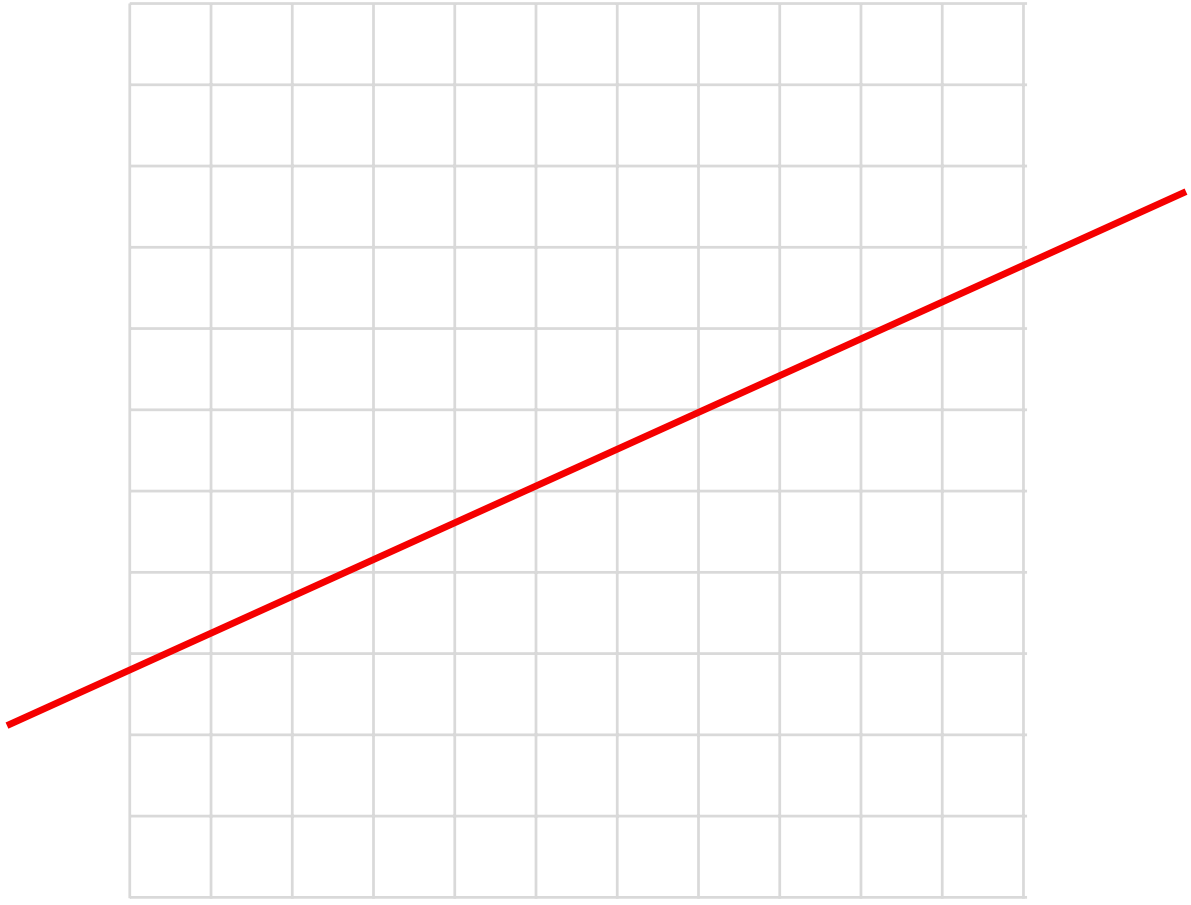
- *Google*: "An open-source software library for machine intelligence"
  - heavily used in the machine-learning community
- Much more than that:
  - a software package for numerical calculations using data-flow *graphs*



- Design the graph *now*, save it to a file, run it *later*...
- Can run it (almost) everywhere: CPU, GPU, a cluster, ...

How to do ray tracing on a CPU?

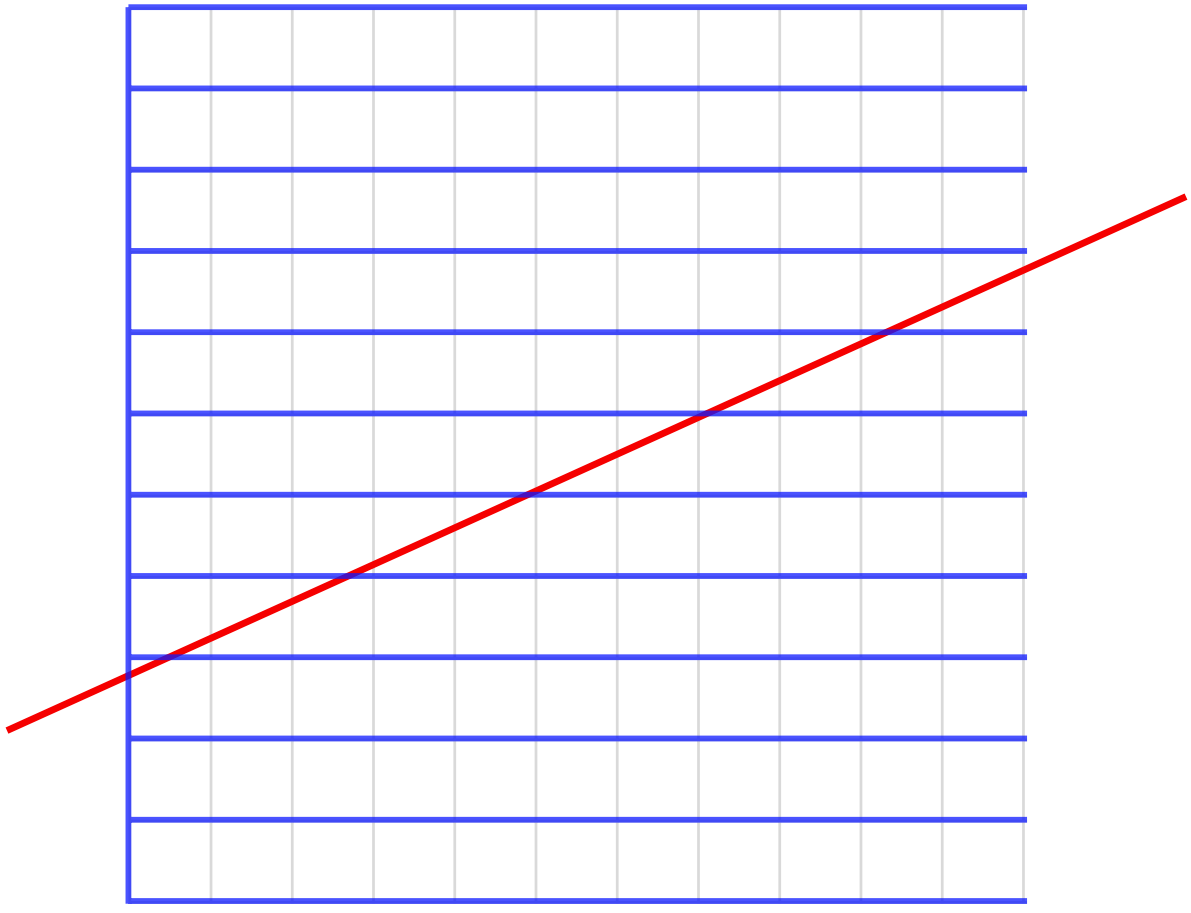
Siddon's algorithm (2D)



- a (very) sequential algorithm

How to do ray tracing on a CPU?

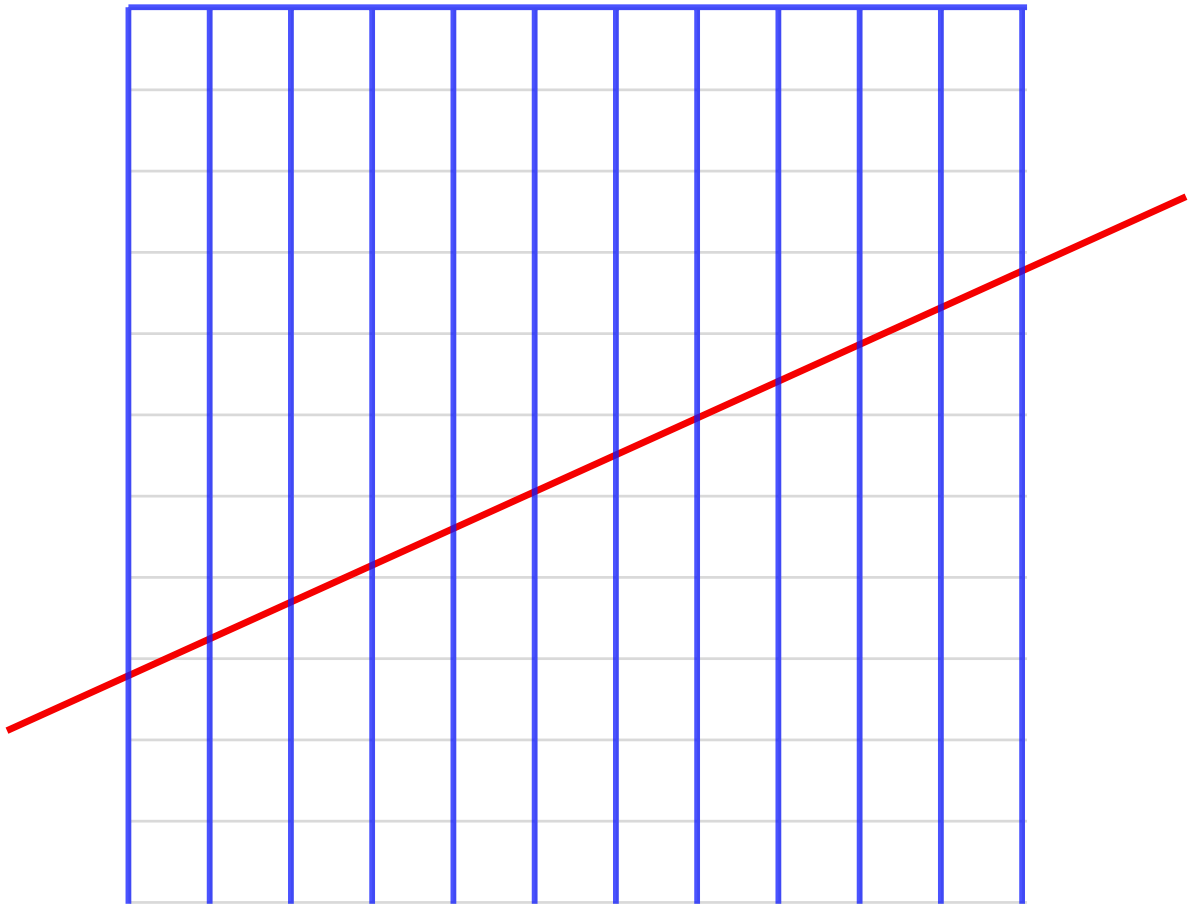
Siddon's algorithm (2D)



- get intersections of LOI with all horizontal planes

How to do ray tracing on a CPU?

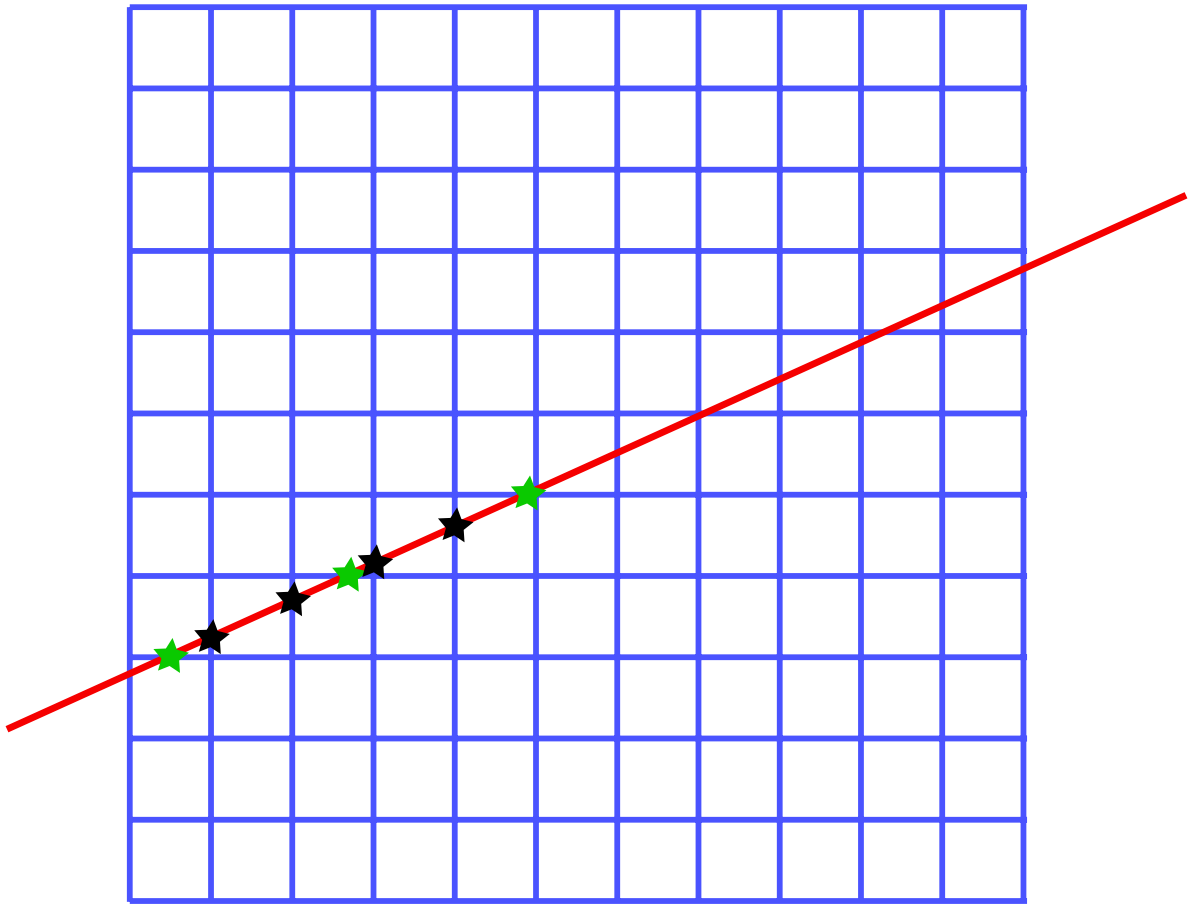
Siddon's algorithm (2D)



- get intersections of LOI with all vertical planes

How to do ray tracing on a CPU?

Siddon's algorithm (2D)



- combine them and get the individual LOIs

How to do ray tracing on a CPU?

Siddon's algorithm (2D)

- parametrize the LOR

$$\mathbf{x} = (\mathbf{x_{end}} - \mathbf{x_{start}}) \cdot \alpha + \mathbf{x_{start}}$$

$$\alpha \in [0, 1]$$

- get intersections with horizontal and vertical planes in terms of the line parameter α
- merge and sort them
- *differences* between neighbouring α values in the merged list describe the LOIs!

Siddon and Tensorflow

- Siddon: $\mathcal{O}(N)$ for a LOR of length N (this means a voxel array of size N^3!!)
- many branches, a loop over the LOR, ...
- very inefficient when running with Tensorflow (GPU $\neq$ CPU architecture)
  - especially problematic when trying to trace multiple LORs "in parallel"
- for Tensorflow: need an algorithm that ...
  - uses the same algorithmic steps on *all* voxels of the LOR
  - uses the same algorithmic steps on *all* LORs

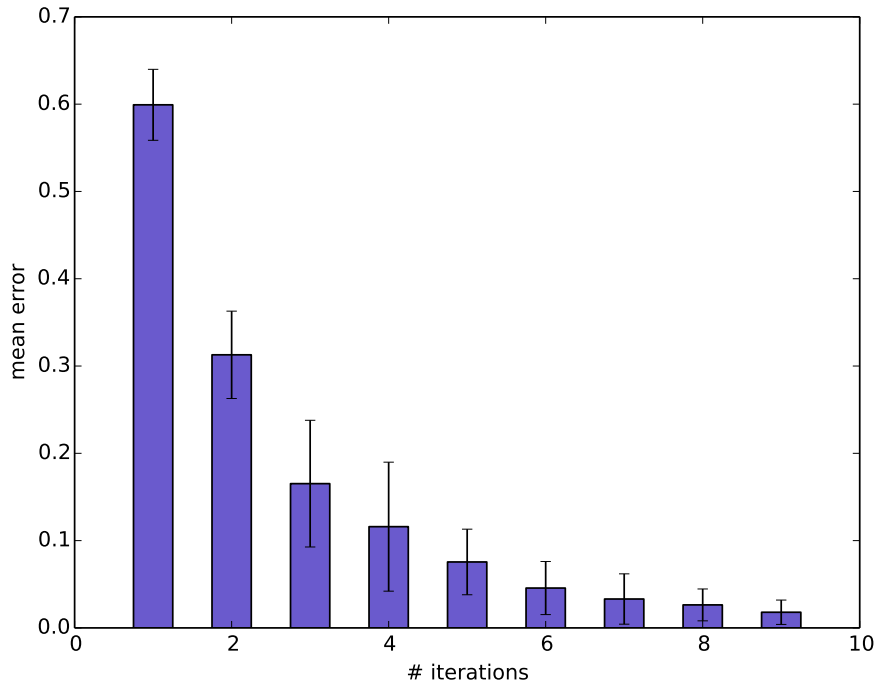
Alternatives to Siddon

- naive approach: for every LOR, compute the LOI through *every* voxel, then add them all up
  - works fine with Tensorflow, but scales as $\mathcal{O}(N^3)$
  - CPU & Siddon beat it again for real-world array sizes
- alternative approach: think of (intersection) points *without* the notion of an LOR

Ray marching: an iterative algorithm

Accuracy

- assume: have "enough" points along the LOR



- with 6 iterations, are already at $\sim 5\%$ level!

Ray marching: an iterative algorithm

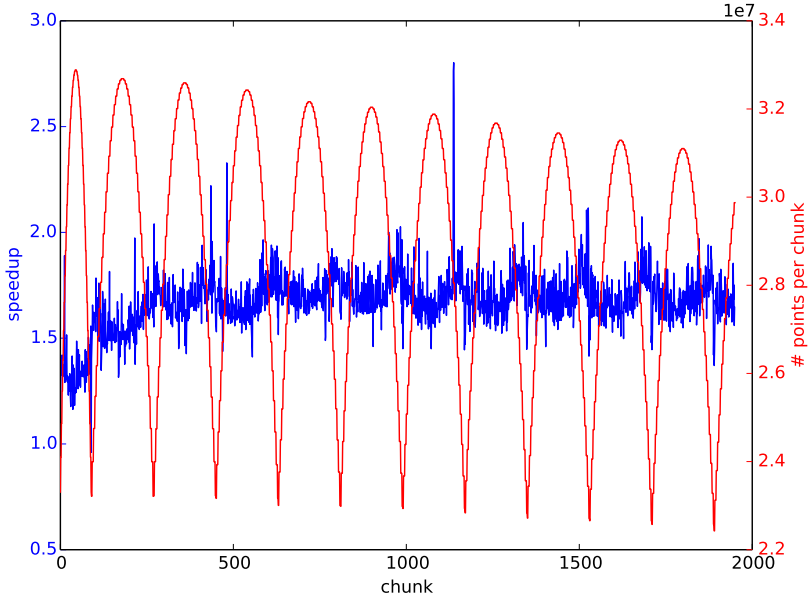
Accuracy

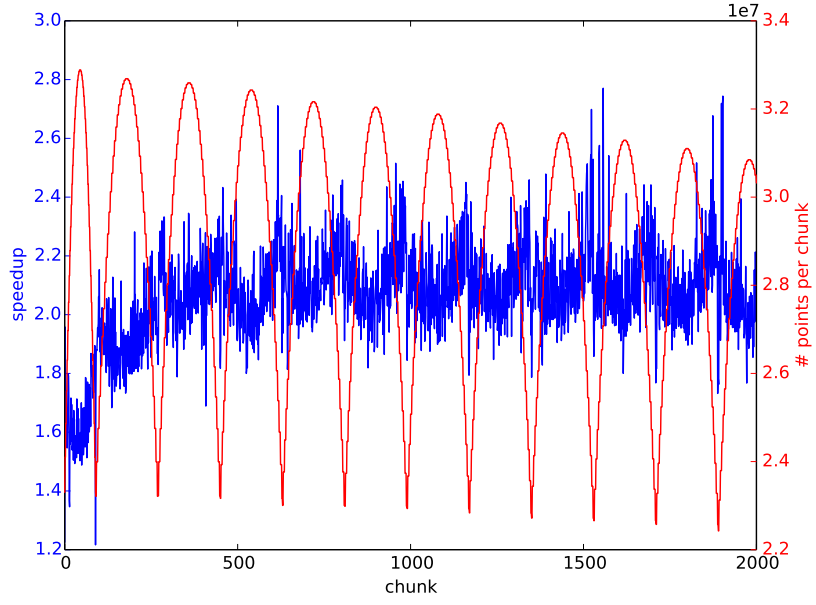
- are there ever enough points?
- does not matter for STIR!

Bringing together STIR and Tensorflow

graph generation in python and graph utilization in c++

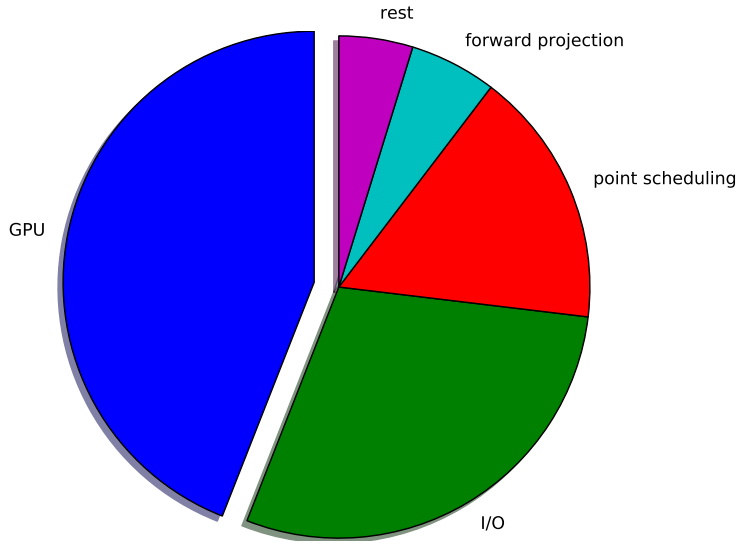
Speedup without caching

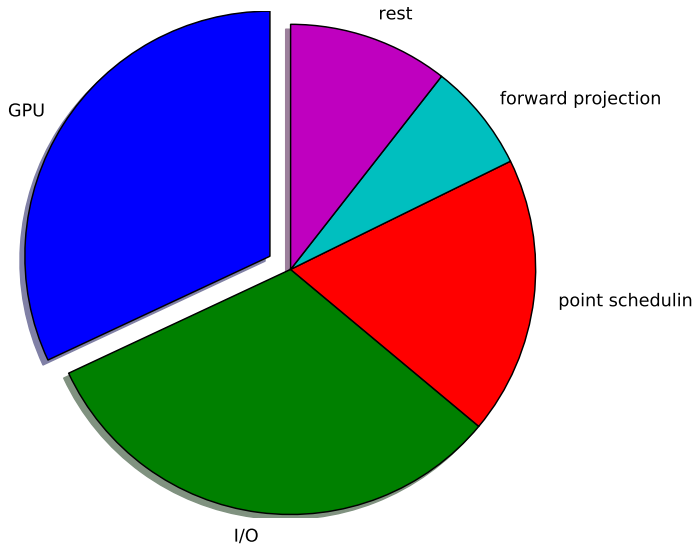




left: 6 iterations, **right**: 2 iterations

- average speedup is similar

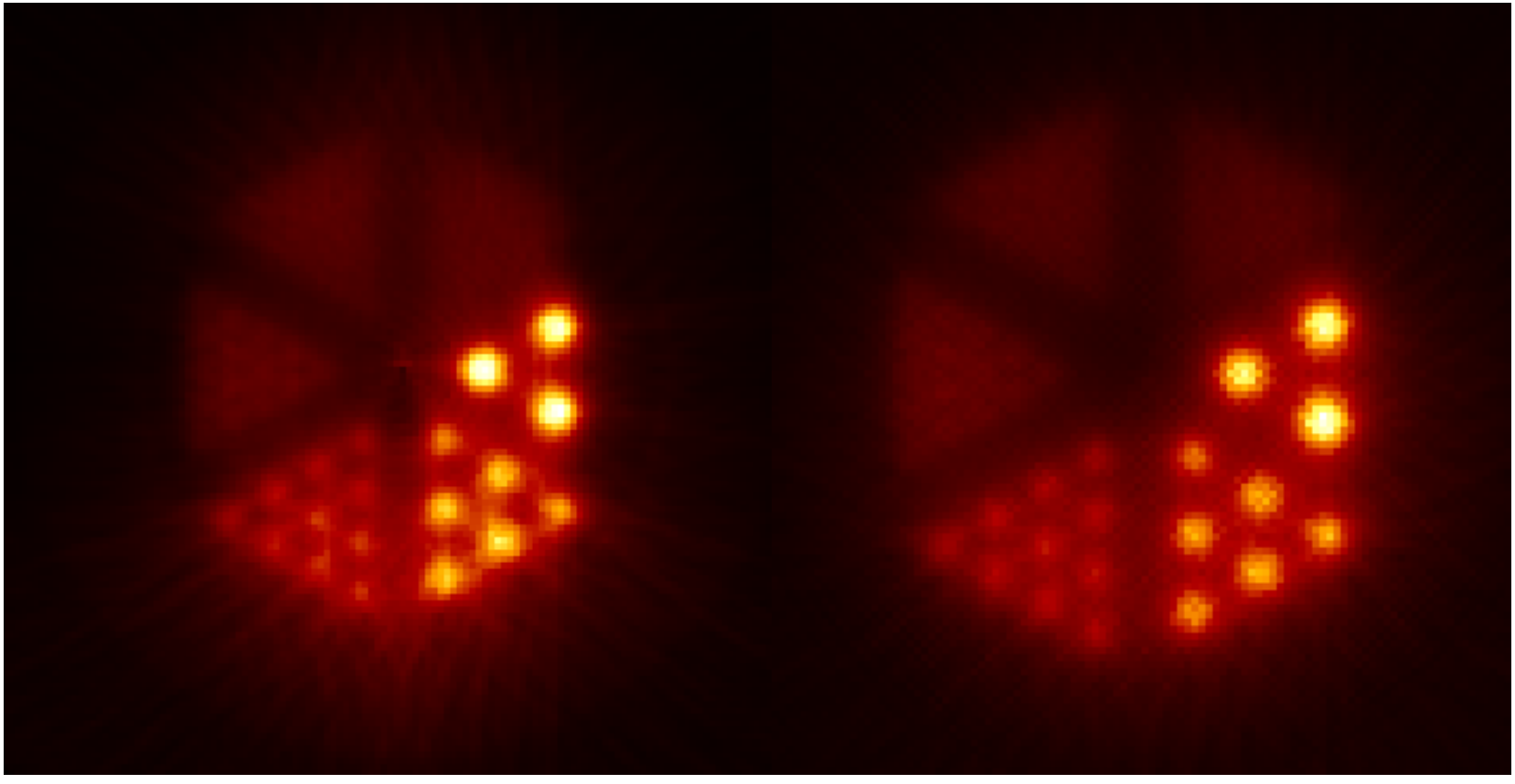




left: 6 iterations, **right**: 2 iterations

- *I/O*: converting from `ProjMatrixElemsForOneBin` to `Tensor` and back
- *point scheduling*: choose points to sample the TOR / LOR

Images



left: 2 iterations, 20LORs per matrix element, **right**: original STIR

- some artefacts: too few points

How to proceed?

- whole toolchain is in place

Where to find the code?

- STIR-TF: `https://github.com/philippwindischhofer/STIR/tree/stir-tf`
- ray tracing scripts: `https://gitlab.phys.ethz.ch/luster/tf-raytracing`

Any comments and contributions are welcome!