

Programming Concepts

Comparing algorithms

Example problem:

Analyse two arrays to see which has the largest element

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Analyse two arrays to see which has the largest element

Algorithmic solution:

- (1) find maximum in first array
- (2) find maximum in second array
- (3) compare the two maxima
- (4) output name of appropriate array

Pseudo-code

Input: Arrays $A[1 \dots n]$, $B[1 \dots m]$

Output: name of array with largest item

```
1  PTR  $\leftarrow$  1
2  A_MAX  $\leftarrow$   $A[\text{PTR}]$ 
3  while PTR  $\neq$   $n$  do
4      |   PTR  $\leftarrow$  PTR + 1
5      |   if  $A[\text{PTR}] > \text{A\_MAX}$  then A_MAX  $\leftarrow$   $A[\text{PTR}]$ 
6  PTR  $\leftarrow$  1
7  B_MAX  $\leftarrow$   $B[\text{PTR}]$ 
8  while PTR  $\neq$   $m$  do
9      |   PTR  $\leftarrow$  PTR + 1
10     |   if  $B[\text{PTR}] > \text{B\_MAX}$  then B_MAX  $\leftarrow$   $B[\text{PTR}]$ 
11 if A_MAX  $>$  B_MAX then return  $A$  else return  $B$ 
```

Pseudo-code

Duplication of code in lines 1-5, and 6-10

Input: Arrays $A[1 \dots n]$, $B[1 \dots m]$

Output: name of array with largest item

```
1  PTR  $\leftarrow$  1
2  A_MAX  $\leftarrow$  A[PTR]
3  while PTR  $\neq$  n do
4      |   PTR  $\leftarrow$  PTR + 1
5      |   if A[PTR] > A_MAX then A_MAX  $\leftarrow$  A[PTR]
6  PTR  $\leftarrow$  1
7  B_MAX  $\leftarrow$  B[PTR]
8  while PTR  $\neq$  m do
9      |   PTR  $\leftarrow$  PTR + 1
10     |   if B[PTR] > B_MAX then B_MAX  $\leftarrow$  B[PTR]
11 if A_MAX > B_MAX then return A else return B
```

Pseudo-code with code reuse

Input: Arrays $A[1 \dots n]$, $B[1 \dots m]$

Output: name of array with largest item

$AMAX \leftarrow \text{Max}(A, 1, n)$

$BMAX \leftarrow \text{Max}(B, 1, m)$

if $AMAX > BMAX$ **then return** A **else return** B

Pseudo-code with code reuse

Input: Arrays $A[1 \dots n]$, $B[1 \dots m]$

Output: name of array with largest item

$AMAX \leftarrow \text{Max}(A, 1, n)$

$BMAX \leftarrow \text{Max}(B, 1, m)$

if $AMAX > BMAX$ **then return** A **else return** B

$\text{Max}(A, s, f)$ means a call to a procedure

- named Max
- with input parameters A, s, f
- which calculates largest item in A between s and f

An example procedure

Procedure: $\text{Max}(A, s, f)$

Input: array A , indices $s \leq f$

Output: largest item in sub-array $A[s \dots f]$

$\text{PTR} \leftarrow s$

$\text{CURRENTMAX} \leftarrow A[\text{PTR}]$

while $\text{PTR} \neq f$ **do**

$\text{PTR} \leftarrow \text{PTR} + 1$

if $A[\text{PTR}] > \text{CURRENTMAX}$ **then**

$\text{CURRENTMAX} \leftarrow A[\text{PTR}]$

return CURRENTMAX

In programming languages:

- procedures
- subroutines
- methods
- ...

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Programming issues

- How is input passed to procedures ?
- How are results returned from procedures ?

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See Dowek

How do we proceduralise an algorithm?

An example

An algorithm

Name: Sequential search

Input: Array $A[1 \dots n]$, item M

Output: true, if M in A , false otherwise

FOUND \leftarrow *false*

PTR \leftarrow 1

while *not* FOUND *and* $\text{PTR} \leq n$ **do**

if $A[\text{PTR}] = M$ **then**

 FOUND \leftarrow *true*

 PTR \leftarrow PTR + 1

return FOUND

Corresponding procedure

Procedure: `seqSearch(A, s, f, M)`

Input: array A , indices s, f , item M

Output: *true* if M in $A[s \dots f]$, *false* otherwise

FOUND \leftarrow *false*

PTR $\leftarrow s$

while *not* FOUND *and* $\text{PTR} \leq f$ **do**

if $A[\text{PTR}] = M$ **then**

 FOUND \leftarrow *true*

 PTR \leftarrow PTR + 1

return FOUND

Corresponding procedure

Procedure: $\text{seqSearch}(A, s, f, M)$

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Output: *true* if M in $A[s \dots f]$, *false* otherwise

$\text{FOUND} \leftarrow \text{false}$

$\text{PTR} \leftarrow s$

while *not* FOUND *and* $\text{PTR} \leq f$ **do**

if $A[\text{PTR}] = M$ **then**

$\text{FOUND} \leftarrow \text{true}$

$\text{PTR} \leftarrow \text{PTR} + 1$

return FOUND

Call $\text{seqSearch}(A, 1, n, M)$ to search entire array $A[1 \dots n]$ for M .

Putting procedures to work

Improving performance of searching

Searching sorted arrays

Procedure: $\text{seqSearch}(A, s, f, M)$

Input: *sorted* array A , indices s, f , item M

Output: *true* if M in $A[s \dots f]$, *false* otherwise

$\text{PTR} \leftarrow s$

while $\text{PTR} \leq f$ *and* $A[\text{PTR}] < M$ **do**

$\text{PTR} \leftarrow \text{PTR} + 1$

if $\text{PTR} > f$ **then**

return *false*

else

return $(A[\text{PTR}] = M)$

Improving performance of searching

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Procedure: $\text{seqSearch}(A, s, f, M)$

Input: *sorted* array A , indices s, f , item M

Output: *true* if M in $A[s \dots f]$, *false* otherwise

$\text{PTR} \leftarrow s$

while $\text{PTR} \leq f$ *and* $A[\text{PTR}] < M$ **do**

 | $\text{PTR} \leftarrow \text{PTR} + 1$

if $\text{PTR} > f$ **then**

 | **return** *false*

else

 | **return** $(A[\text{PTR}] = M)$

Scan through array only as far as expected slot for M

Improving performance of searching

Searching sorted arrays

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if $\text{PTR} > f$ **then**

 | **return** *false*

else

 | **return** $(A[\text{PTR}] = M)$

Scan through array only as far as expected slot for M

May still have to search entire array

Binary search of a sorted array $A[1 \dots n]$ for M :

- If array is empty, item is not *found*
- Calculate *middle* of list, m
- Compare M to $A[m]$
- If equal, item is *found*
- If less, search sub-array $A[1 \dots (m - 1)]$
- If greater, search sub-array $A[(m + 1) \dots n]$

More efficient searching

Binary search of a sorted array $A[1 \dots n]$ for M :

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Division:

Problem instance of size n

- decomposed in problem instance of size $n/2$

Binary search: looking for Ollie

Alice

Bob

Carol

David

Elaine

Fred

George

Harry

Irene

John

Kelly

Larry

Mary

Nancy

Ollie

Binary search: looking for Ollie

Alice	Alice
Bob	Bob
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Ollie	Ollie

Binary search: looking for Ollie

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Mary	Mary	Mary
Nancy	Nancy	Nancy
Ollie	Ollie	Ollie

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Irene	Irene	Irene	
John	John	John	
Kelly	Kelly	Kelly	
Larry	Larry	Larry	
Mary	Mary	Mary	Mary
Nancy	Nancy	Nancy	Nancy
Ollie	Ollie	Ollie	Ollie

Binary search: looking for Ollie

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John	John	John		
Kelly	Kelly	Kelly		
Larry	Larry	Larry		
Mary	Mary	Mary	Mary	
Nancy	Nancy	Nancy	Nancy	
Ollie	Ollie	Ollie	Ollie	Ollie

More efficient searching

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Can we write this in pseudocode?

Procedure: `binarySearch(A, s, f, M)`

Input: sorted array A , indices s, f , item M

Output: *true* if M in $A[s \dots f]$, *false* otherwise

Binary search

Procedure: `binarySearch(A, s, f, M)`

Input: sorted array A , indices s, f , item M

Output: *true* if M in $A[s \dots f]$, *false* otherwise

FOUND \leftarrow *false*

if $s \leq f$ **then**

$m \leftarrow (s + f) \text{ div } 2$ // middle of array

if $A[m] = M$ **then**

 FOUND \leftarrow *true*

else

if $M < A[m]$ **then**

 FOUND \leftarrow `binarySearch($A, s, (m-1), M$)`

else

 FOUND \leftarrow `binarySearch($A, (m+1), f, M$)`

return FOUND

How much faster is binary search?

Remember:

Sequential search: worst case n steps

Binary search: halves every time

Log to the base 2

Chopping arrays in half:

How many times can you chop an array of size n in half?

Log to the base 2

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How many times can you chop an array of size n in half?

Size	log
15	4
100	7
1000	10
1 million	20
1 billion	30
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sequential search	binary search

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sequential search	binary search
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A worst case analysis

Algorithm design technique:

- Decompose problem instance into smaller subinstances
- Solve subinstances successively and independently
- Combine subsolutions to obtain solution to original problem instance

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Most successful:

when problem instance of size n is decomposed into subinstances of size $n/2$

Divide and conquer in action

Divide and conquer for **sorting** \rightsquigarrow binary search

Divide and conquer for **searching** \rightsquigarrow merge sort

Mergesort:

Basic algorithm:

- Input array A to be sorted
- If size of A less than 2 it is sorted
- Otherwise
 - Divide A into two subarrays L and R
 - Sort L
 - Sort R
 - Merge sorted L and sorted R into a new, sorted array

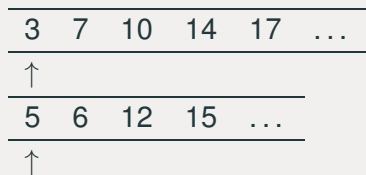
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Based on fact that merging sorted arrays is a simple operation

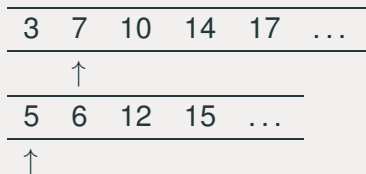
Merging sorted arrays



Merged array:



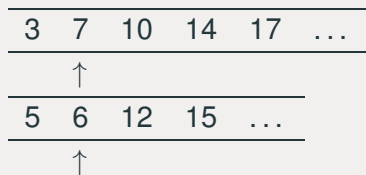
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Merged array:



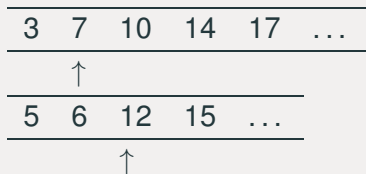
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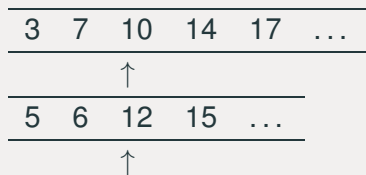
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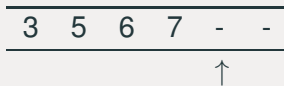
Merged array:



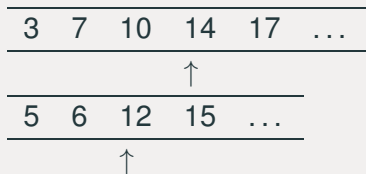
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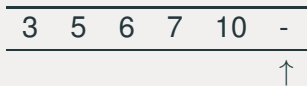
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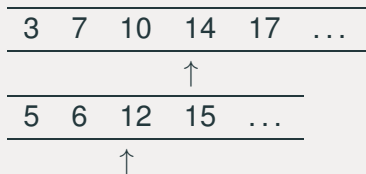
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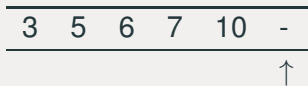
Merged array:



Merging sorted arrays



Merged array:



Needs only one scan through arrays

Mergesort: the idea

1. Input array A to be sorted
2. If size of A less than 2 it is sorted
3. Otherwise
 - 3.1 Divide A into two subarrays L and R
 - 3.2 Sort L
 - 3.3 Sort R
 - 3.4 Merge sorted L and sorted R into a new, sorted array

Can we write this as pseudocode?

Merge sort

Procedure: `mergeSort(A)`

Input: array $A[1 \dots n]$

Result: array $A[1 \dots n]$ sorted

if $n \leq 1$ **then**

return A

else

$M \leftarrow n \text{ div } 2$

 copy $A[1 \dots M]$ to $B[1 \dots M]$

 copy $A[(M + 1) \dots n]$ to $C[1 \dots (n - M)]$

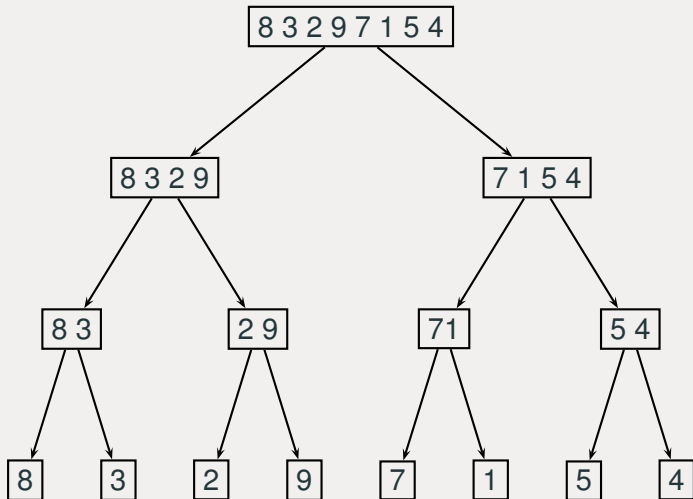
 mergeSort(B)

 mergeSort(C)

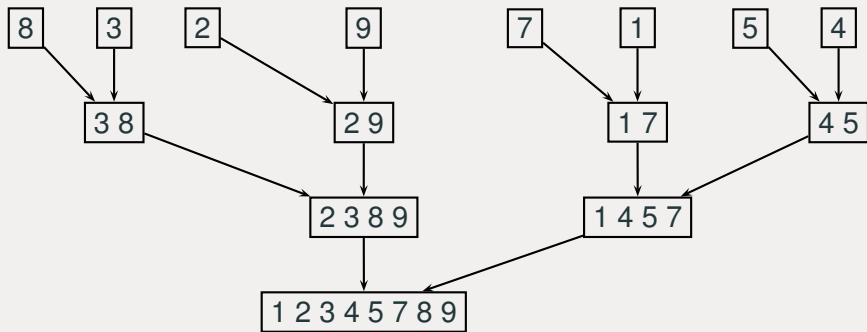
 merge(B, C, A)

return A

Merge sort in operation



Merging the sub-arrays



Divide and Conquer:

Problem of size n decomposed into

- two sub-problems of size $n/2$
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Merge sort:

Much more efficient than

- Bubble sort
- Insertion sort
- Selection sort

Given a problem . . .

- Does there exist an algorithm for solving it?
- Does there exist an *efficient* algorithm?
- Can I *improve* on a published algorithm for the problem?

Given an algorithm . . .

- How efficient is it?
- Does a more efficient algorithm exist for the same problem?
- Which algorithm for a given problem is the *best*?

Two algorithms for summing numbers

Name: Summing numbers

Input: positive integer n

Output: sum of first n positive numbers

$SUM \leftarrow 0$

$ITER \leftarrow 1$

while $ITER \leq n$ **do**

$SUM \leftarrow SUM + ITER$

$ITER \leftarrow ITER + 1$

return SUM

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Which is more efficient?

Measuring efficiency of algorithms

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- Cost of running an algorithm depends on size of input (usually)
- Efficiency of an algorithm is expressed as a cost function on the size of input
- Comparison between algorithms difficult to see when size of inputs are small
- Differences in efficiency become apparent as size of input get very large

Measuring efficiency of algorithms

We need

1. a measure on the size of inputs
2. a measure of cost of running an algorithm

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Dependent on type of data

- arrays: number of items
- lists: number of items
- numbers: ? often size of binary representation

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- lists: number of items
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Cost of running algorithm:

- time taken
- space required –less important these days
- energy consumed –becoming important

Measuring efficiency of algorithms

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2. a measure of cost of running an algorithm

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Dependent on type of data

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- lists: number of items
- numbers: ? often size of binary representation

Cost of running algorithm:

- time taken – we concentrate on this
- space required
- energy consumed

Measuring running time

- Difficult to use a stop watch

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Significant actions:

Depends on problem area:

- sorting: count comparisons between items
- searching: count comparisons between items
- summing: count arithmetic operations

Sometimes difficult to decide

Here we only care about the worst case complexity

Counting the cost

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Output: sum of first n positive numbers

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Input: positive integer n

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Number of operations:

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Input: positive integer n

return $n(n + 1)/2$

Number of operations:

more than n

3

Estimating growth functions

Constants don't count:

Function	F	G	G larger than F after
	$100n^2$	$2n^3$	$n > 50$
	$1000n^2$	$3n^3$	$n > 350$
	$1000n^3$	n^4	$n > 1000$

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The tyranny of large numbers

Estimating growth functions

Small terms get swamped:

Function	Insignificant after
$2n^2 + \underline{10n + 6}$	$n > 10$
$n^4 + \underline{100n^2 + 5n}$	$n > 10$
$2n^5 + \underline{1000n^4}$	$n > 500$

Estimating growth functions

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Function	Insignificant after
$2n^2 + \underline{10n + 6}$	$n > 10$
$n^4 + \underline{100n^2 + 5n}$	$n > 10$
$2n^5 + \underline{1000n^4}$	$n > 500$

The tyranny of large numbers

Approximating growth functions

Big Theta notation:

$\Theta(f(n))$: all functions which *grow* at the same rate as $f(n)$

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$\Theta(f(n))$: all functions which *grow* at the same rate as $f(n)$

$g(n)$ is in $\Theta(f(n))$ if

- there is a constant K_g such that $g(n) \leq K_g * f(n)$, once n gets sufficiently large
- there is a constant K_f such that $f(n) \leq K_f * g(n)$, once n gets sufficiently large

Approximating growth functions

Big Theta notation:

$\Theta(f(n))$: all functions which *grow* at the same rate as $f(n)$

$g(n)$ is in $\Theta(f(n))$ if

- there is a constant K_g such that $g(n) \leq K_g * f(n)$, once n gets sufficiently large
- there is a constant K_f such that $f(n) \leq K_f * g(n)$, once n gets sufficiently large

which means: once n gets big enough

- $k_1 * f(n) \leq g(n) \leq k_2 * f(n)$
- (and vice-versa)

Important complexity classes

constant $\Theta(1)$

logarithmic $\Theta(\log n)$

linear $\Theta(n)$

n-log-n $\Theta(n \log n)$

quadratic $\Theta(n^2)$

cubic $\Theta(n^3)$

polynomial $\Theta(n^k)$, for some $k \geq 1$

exponential $\Theta(2^n)$

Examples

- $2 * n + 6$ is in $\Theta(n)$
- $4 * n^2 + 10 * n + 6$ is NOT in $\Theta(n)$

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- $234 * n^2 + 658 * n + 200$ is in $\Theta(n^2)$
- $234 * n^2 + 658 * n + 200$ is NOT in $\Theta(n^3)$

Examples

- $2 * n + 6$ is in $\Theta(n)$
- $4 * n^2 + 10 * n + 6$ is NOT in $\Theta(n)$

- $234 * n^2 + 658 * n + 200$ is in $\Theta(n^2)$
- $234 * n^2 + 658 * n + 200$ is NOT in $\Theta(n^3)$

- $78 * 10^n + 34 * n^{27}$ is in $\Theta(2^n)$

Examples

- $2 * n + 6$ is in $\Theta(n)$
- $4 * n^2 + 10 * n + 6$ is NOT in $\Theta(n)$

- $234 * n^2 + 658 * n + 200$ is in $\Theta(n^2)$
- $234 * n^2 + 658 * n + 200$ is NOT in $\Theta(n^3)$

- $78 * 10^n + 34 * n^{27}$ is in $\Theta(2^n)$

Dominant exponent always wins out in the end

Orders of Growth

n	$\log n$	n	$n \log n$	n^2	n^3	2^n
10	3.3	10	33	100	1,000	1,000
100	6.6	100	660	10^4	10^6	$1.3 \cdot 10^{30}$
1,000	10	1,000	10,000	10^6	10^9	
10,000	13	10,000	130,000	10^8	10^{12}	
100,000	17	100,000	1.7 million	10^{10}	10^{15}	
1 million	20	1,000,000	20 million	10^{12}	10^{18}	

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Estimated age of the universe: 10^{14} seconds

Why buying a new computer will not help

Running an exponential algorithm

Current computer: 10,000 instructions per second

problem size	time
10	0.1 sec
20	2 mins approx.
30	> 24 hours
38	> one year

Why buying a new computer will not help

Running an exponential algorithm

New computer: 100 times faster

problem size	time
10	0.1 sec
20	1 minute approx
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Only minimal increase in effectiveness:

time T	problem size
old computer	n
new computer	n+7

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Algorithms v. fast computers

More efficient algorithms better than faster computers

Setup A:

- slow sorting algorithm: $\Theta(n^2)$
- crafty programmer: constant factor 2
- fast machine: 1 billion instructions per second

Setup B:

- fast sorting algorithm: $\Theta(n \log(n))$
- rubbish programmer: constant factor 50
- slow machine: 10 million instructions per second (100 times slower)

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- rubbish programmer: constant factor 50
- slow machine: 10 million instructions per second (100 times slower)

setup	1 million numbers	10 million numbers
A	> 30 mins	> 2 days
B	< 2 mins	< 20 mins

Comparing complexity classes

Double size of input	Extra time required
$\Theta(1)$	none
$\Theta(\log n)$	marginal increase
$\Theta(n)$	double
$\Theta(n \log n)$	double + tiny
$\Theta(n^2)$	four times longer
$\Theta(n^3)$	eight times longer
$\Theta(2^n)$	square of time

Examples: how to compute complexity

Remember we only care about the worse case

Example

Name: Sequential search

Input: Array $A[1 \dots n]$, item M

Output: true, if M in A , false otherwise

FOUND \leftarrow *false*

PTR \leftarrow 1

while *not* FOUND *and*

PTR $\leq n$ **do**

if $A[\text{PTR}] = M$ **then**

 FOUND \leftarrow *true*

 PTR \leftarrow PTR + 1

return FOUND

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- worst possible: n
- average: difficult to understand

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We only deal with *worst case analysis*

Improved searching?

First sort the list:

- Not necessary to scan all the array
- stop when an item *greater than or equal to* M is encountered

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Procedure:

`seqSearch(A, s, f, M)`

$PTR \leftarrow s$

while $PTR \leq f$ *and* $A[PTR] < M$

do

 | $PTR \leftarrow PTR + 1$

if $PTR > f$ **then return** *false*

else

 | **return** ($A[PTR] = M$)

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if PTR $> f$ **then return** *false*

else

 | **return** ($A[\text{PTR}] = M$)

No. of comparisons:

- best possible: 1
- worst possible: n
- average: probably an improvement

Analysis of binary search

Procedure: `binarySearch(A, s, f, M)`

`FOUND` \leftarrow *false*

if $s \leq f$ **then** $m \leftarrow (s + f) \text{ div } 2$ // middle of array

if $A[m] = M$ **then** `FOUND` \leftarrow *true* **else**

if $M < A[m]$ **then**

`FOUND` \leftarrow `binarySearch(A, s, (m-1), M)`

else

`FOUND` \leftarrow `binarySearch(A, (m+1), f, M)`

return `FOUND`

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- procedure called $\log n$ times
- each call gives 1 comparison

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- procedure called $\log n$ times
- each call gives 1 comparison

worst case analysis: $\log n$

Sequential v. binary search

Array size	sequential search	binary search
15	15	4
100	100	7
1000	1000	10
1 million	1 million	20
1 billion	1 billion	30
1 billion billion	1 billion billion	60

Calculating *spread* of an array

Input: Array $A[1 \dots n]$

Output: The *spread* of A

CSPREAD $\leftarrow 0$

for $i \leftarrow 1$ **to** n **do**

for $j \leftarrow 1$ **to** n **do**

$D \leftarrow \text{diff}(A[i], A[j])$

if CSPREAD $< D$ **then**

 CSPREAD $\leftarrow D$

return CSPREAD

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- inner loop executed n times
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Improved *spread* algorithm?

CSPREAD \leftarrow 0

for $i \leftarrow 1$ **to** n **do**

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return CSPREAD

Improved *spread* algorithm?

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CSPREAD  $\leftarrow$  0
for  $i \leftarrow 1$  to  $n$  do
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 - first $(n - 1)$ times, then $(n - 2)$ times , then $(n - 3)$ times, ...
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- outer loop executed n times

No. times C executed: $(n - 1) + (n - 2) + \dots + 1 + 0$

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- outer loop executed n times

Worst-case analysis: $\Theta(n^2)$

An improved spread algorithm

$C_{MAX} \leftarrow A[1]$

$C_{MIN} \leftarrow A[1]$

for $i \leftarrow 2$ **to** n **do**

if $A[i] < C_{MIN}$ **then**

$C_{MIN} \leftarrow A[i]$

else

if $A[i] > C_{MAX}$ **then**

$C_{MAX} \leftarrow A[i]$

$C_{SPREAD} \leftarrow \text{diff}(C_{MAX}, C_{MIN})$

return C_{SPREAD}

An improved spread algorithm

```
CMAX ← A[1]
CMIN ← A[1]
for  $i \leftarrow 2$  to  $n$  do
    if  $A[i] < C_{\text{MIN}}$  then
        | CMIN ← A[i]
    else
        | if  $A[i] > C_{\text{MAX}}$  then
            | CMAX ← A[i]

CSPREAD ← diff(CMAX, CMIN)
return CSPREAD
```

```
C1
for  $i \leftarrow 2$  to  $n$  do
    | C2

C3
```

An improved spread algorithm

$C_{MAX} \leftarrow A[1]$

$C_{MIN} \leftarrow A[1]$

for $i \leftarrow 2$ **to** n **do**

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$C_{MAX} \leftarrow A[i]$

C_1

for $i \leftarrow 2$ **to** n **do**

C_2

C_3

$C_{SPREAD} \leftarrow \text{diff}(C_{MAX}, C_{MIN})$

return C_{SPREAD}

Worst case:

- loop executed $(n - 1)$ times
- each C_i : constant no. of actions

An improved spread algorithm

```
CMAX ← A[1]
CMIN ← A[1]
for  $i \leftarrow 2$  to  $n$  do
    | if  $A[i] < C_{\text{MIN}}$  then
    | | CMIN ← A[i]
    | else
    | | if  $A[i] > C_{\text{MAX}}$  then
    | | | CMAX ← A[i]
```

```
CSPREAD ← diff(CMAX, CMIN)
return CSPREAD
```

```
C1
for  $i \leftarrow 2$  to  $n$  do
    | C2

C3
```

worst case analysis: $\Theta(n)$

Analysis of selection sort

Name: Selection sort

Input: Array $A[1 \dots n]$

Output: Array A sorted

for $i \leftarrow 1$ **to** $(n - 1)$ **do**

 // maintains $A[1 \dots i]$ sorted

 MINPTR $\leftarrow i$

for $j \leftarrow (i + 1)$ **to** n **do**

 // finds smallest item in $A[i \dots n]$

if $A[j] < A[\text{MINPTR}]$ **then**

 MINPTR $\leftarrow j$

$A[i] \leftrightarrow A[\text{MINPTR}]$ // swap items

return A

Analysis of selection sort

Name: Selection sort

Input: Array $A[1 \dots n]$

Output: Array A sorted

for $i \leftarrow 1$ **to** $(n - 1)$ **do**

C_1

for $j \leftarrow (i + 1)$ **to** n **do**

C_2

C_3

Analysis of selection sort

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Input: Array $A[1 \dots n]$

Output: Array A sorted

for $i \leftarrow 1$ **to** $(n - 1)$ **do**

| C_1

| **for** $j \leftarrow (i + 1)$ **to** n **do**

| | C_2

| C_3

- inner loop
 - first executed $(n - 1)$ times, then $(n - 2)$ times, ...
 - each time C_2 is executed
 - each C_3 : *constant* no. of comparisons

Analysis of selection sort

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Input: Array $A[1 \dots n]$

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 - first executed $(n - 1)$ times, then $(n - 2)$ times, ...
 - each time C_2 is executed
 - each C_3 : *constant* no. of comparisons

worst case analysis: $\Theta(n^2)$

Analysis of Merge sort

Procedure: `mergeSort(A)`

Input: array $A[1 \dots n]$

Result: array $A[1 \dots n]$ sorted

if $n > 1$ **then**

$M \leftarrow n \text{ div } 2$

 copy $A[1 \dots M]$ to $B[1 \dots M]$

 copy $A[(M + 1) \dots n]$ to $C[1 \dots (n - M)]$

 mergeSort(B)

 mergeSort(C)

 merge(B, C, A)

Analysis of Merge sort

Procedure: `mergeSort (A)`

$M \leftarrow n \text{ div } 2$

`mergeSort (left half of A)`

`mergeSort (right half of A)`

`merge (halves into whole)`

Analysis of Merge sort

Procedure: `mergeSort (A)`

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Each call to *mergeSort* leads to

- two sub-calls to *mergeSort*
- one call to *merge*

Each new call halves the array to be treated

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Each new call halves the array to be treated

Worst case:

- in total *around* $2 \log n$ calls
- each call uses one *merge*
- each *merge* uses *around* n comparisons

Analysis of Merge sort

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Each new call halves the array to be treated

worst case analysis: $\Theta(n \log n)$

Summary

Class	Name	Characteristics
$\Theta(1)$	constant	few interesting algorithms
$\Theta(\log n)$	logarithmic	result of cutting problem size in half each time round a loop
$\Theta(n)$	linear	Algorithms which scan an array/list
$\Theta(n \log n)$	n-log-n	Many divide-and-conquer algorithms
$\Theta(n^2)$	quadratic	Algorithms with two embedded loops
$\Theta(n^3)$	cubic	Algorithms with three embedded loops
$\Theta(2^n)$	exponential	Many important problems