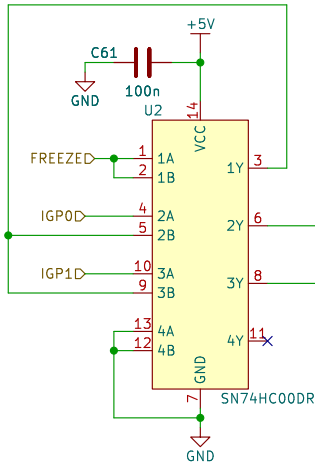
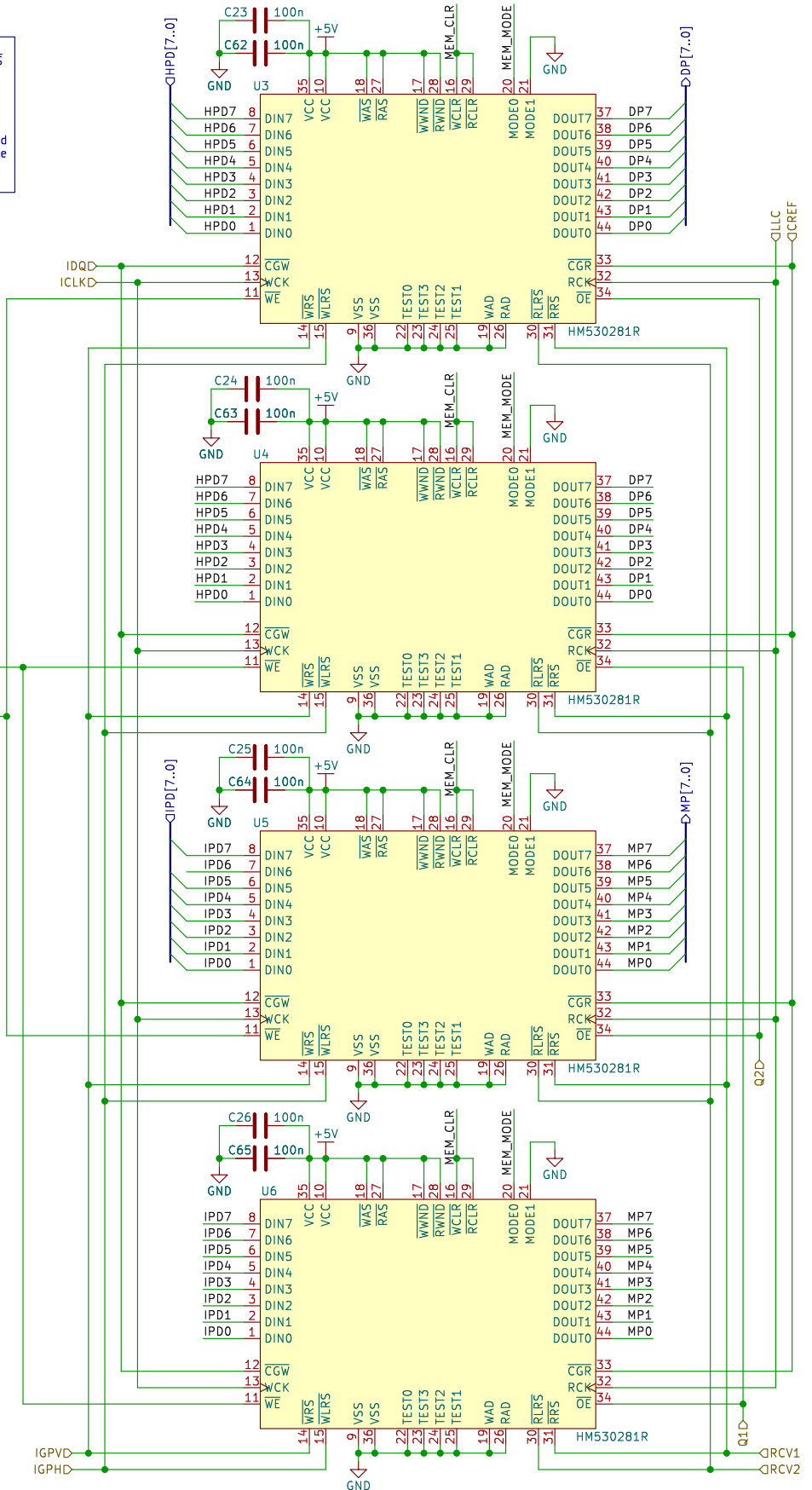
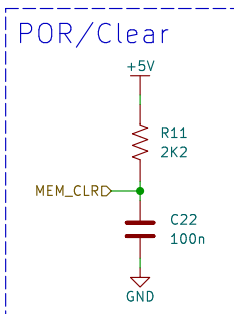
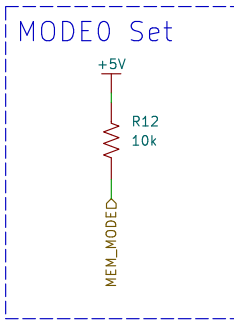


NOTES:
 1. I believe Marcus's schematic has \overline{RRS} and \overline{WRS} transposed, and \overline{RLRS} and \overline{WLRS} transposed. I have made the corrections in this design;
 2. Marcus doesn't perform the correct power-up sequence identified on pg. 17 on the datasheet. I'm not sure whether I'll actually implement it either, but I have connected the $\overline{MODE0}$, \overline{WCLR} and \overline{RCLR} pins to the microcontroller so I can be done if the power-up reset circuit doesn't work as expected.



NOTE:
 - when IGP0 is high, \overline{WE} asserted on memories 2 and 4
 - when IGP1 is high, \overline{WE} asserted on memories 1 and 3
 - when Q1 is high, \overline{OE} asserted on memories 2 and 4
 - when Q2 is high, \overline{OE} asserted on memories 1 and 3



Sheet: /Frame Memories and Freeze/
 File: memory.kicad_sch

Title: Time Base Corrector and Video Scaler

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NOTES: this circuit differs from Marcus's in the following areas:
 1. added the second 75R resistor for each output, similar to the datasheet. This might be an error in Marcus's schematic;
 2. added a ferrite and capacitor (LC) to create the analog supply. Marcus's design is not clear on how the separate 3V3A and 3V3D supplies are created, so I used my own judgement on it ;-);
 3. for the oscillator circuit, I made a decision to go with a different design, similar to that used for the STM32 microcontroller. Left the pads for the inductor and 1nF capacitor but they are DNP, so that I can revert to Marcus's design same as datasheet) if need be;
 4. connected a microcontroller open-drain GPIO to Marcus's POR circuit connecting to the RESET pin.
 5. this circuit does not split GND (no separate AGND and DGND);
 ** 6. I believe RCV1 and RCV2 are reversed on Marcus's schematic, or potentially D and CLK on the LS74 are reversed.
 Datasheet states RCV1 contains ON/EVEN, which I think should be the data we want to latch up.

TODO: Unsure on level matching for the LS74; check RCV1 and RCV2 specs and make sure they are ok to drive the flip-flop input and clock.

TODO: determine if RTC1 should be connected to ground

Sheet: /Video Encoder/
 File: encoder.kicad_sch

Title: Time Base Corrector and Video Scaler

Size: A4 Date: 2024-01-15

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Id: 4/5

