

Lecture # 30 CHE331A

Models for non-ideal reactors – from the RTD curves to conversions

Goutam Deo

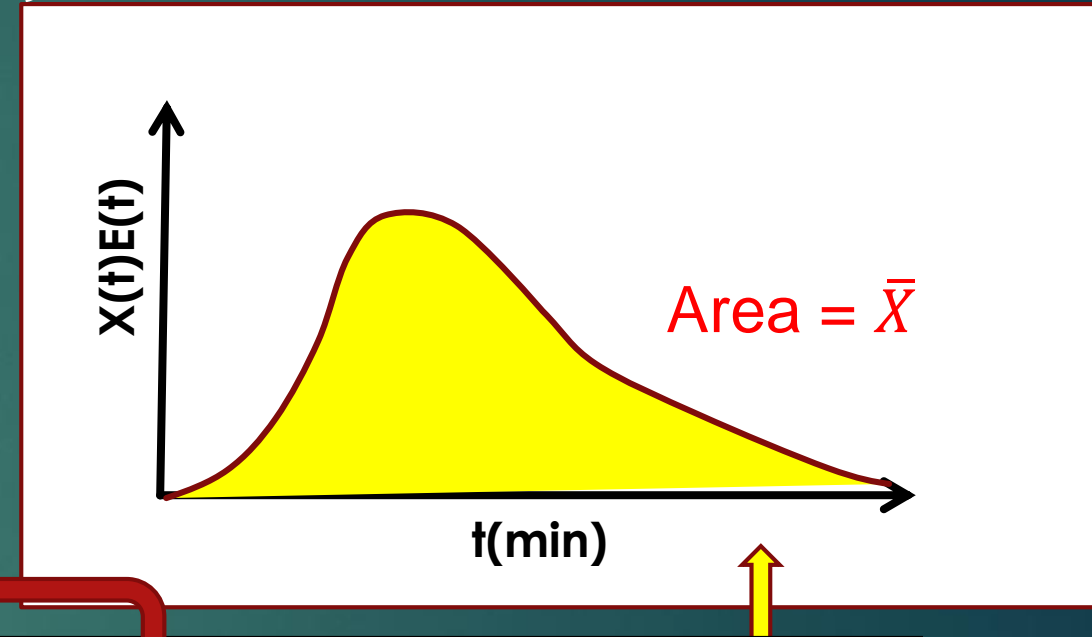
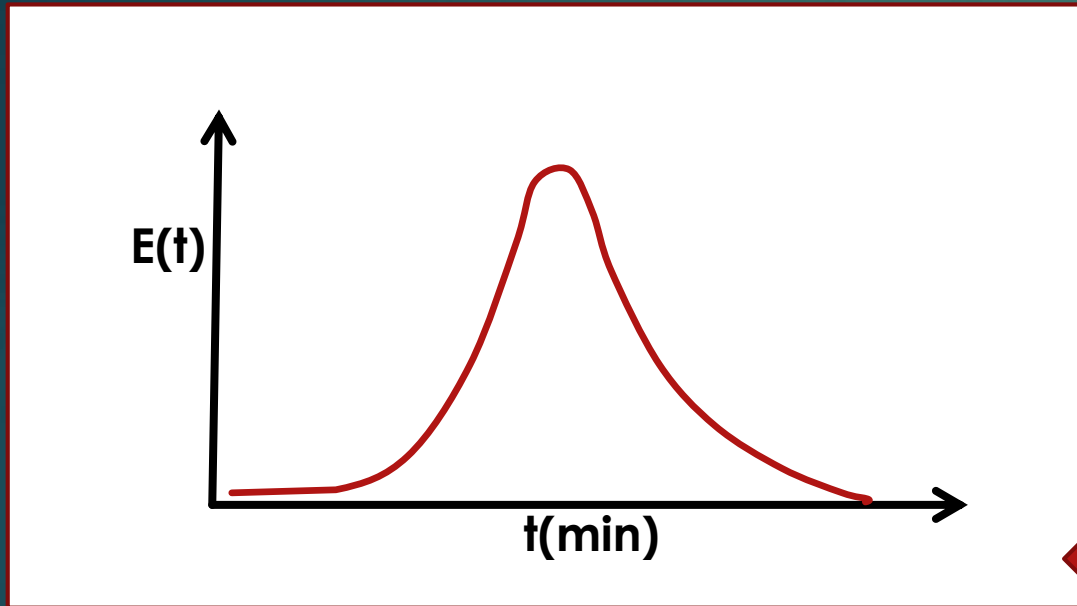
2020-2021 1st semester

- ❑ Non-ideal reactors
 - ❑ Construction of $C(t)$ and $E(t)$
 - ❑ Convolution integral & Step-input
 - ❑ Moments of the RTD and application to PFR/PBR and CSTR
 - ❑ RTD of LFR – an example of a non-ideal reactor
 - ❑ Models for real reactors



Given a $E(t)$, conversion can be calculated for the segregated model: PFR/PBR, CSTR, LFR and in general

- ▶ Experimentally determined $E(t)$ curve from $C(t)$



- ▶ $X(t)$ determined for a batch reactor for specified kinetics

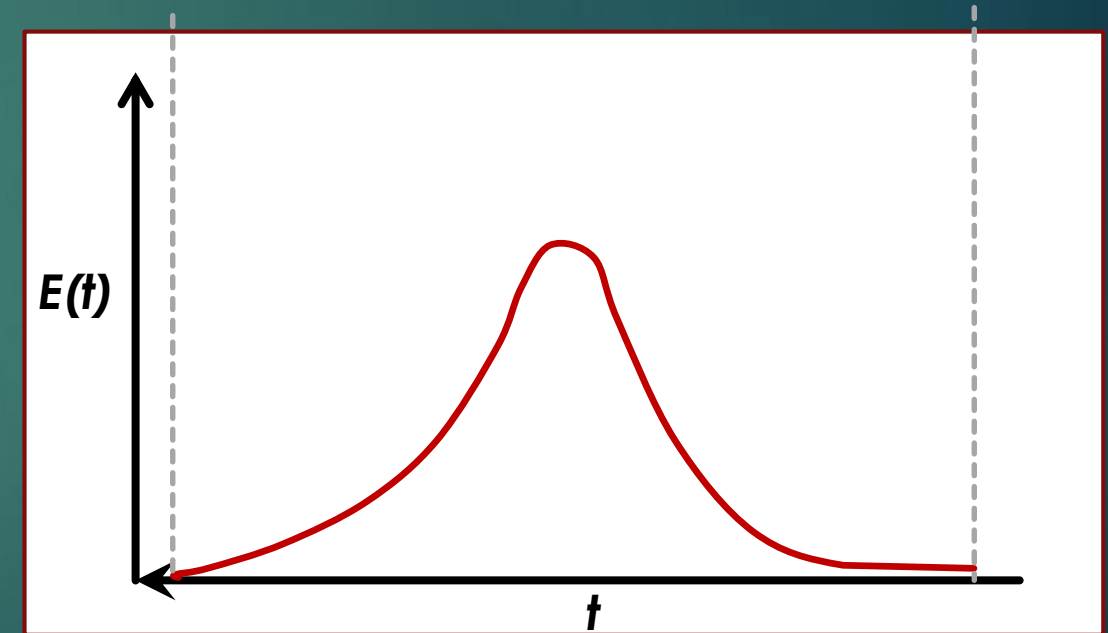
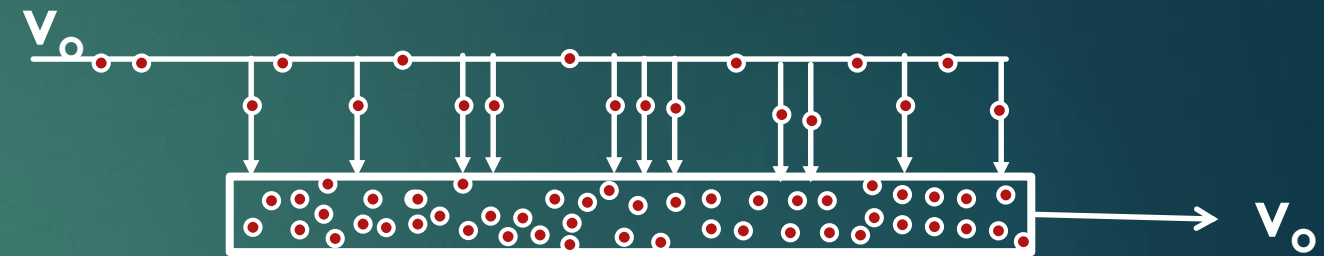
$$\bar{X} = \int_0^{\infty} X(t).E(t).dt$$

t (min)	$C(t)$	$E(t)$ min ⁻¹	$X(t)$	$X(t).E(t)$ min ⁻¹
0	0	0	0	0
1	1	0.02	0.095	0.0019
2	5	0.10	0.181	0.0180
And so on				



Maximum Mixedness model – the other zero parameter model

- ▶ Fluid elements enter, as per the $E(t)$ curve, and mix radially but not axially
- ▶ Fluid elements at the far left spend the most amount of time and those at the far right the least
- ▶ λ Is the time it takes for the fluid to move from a particular point in the reactor to the end (also called life expectancy)
- ▶ Thus, $E(\lambda)d\lambda$ is the fraction of molecules having a life expectancy between λ and $\lambda+d\lambda$



Note the t-axis direction



Mole balance for the elemental volume, ΔV

- Balance in the elemental volume

- $v_\lambda = v_{\lambda+\Delta\lambda} + v_o \cdot E(\lambda) \cdot \Delta\lambda \Rightarrow \frac{dv_\lambda}{d\lambda} = -v_o E(\lambda)$

- Integrating with $v_\lambda = 0$ at $\lambda = \infty$

- $v_\lambda = v_o \int_\lambda^\infty E(\lambda) \cdot d\lambda = v_o [1 - F(\lambda)]$

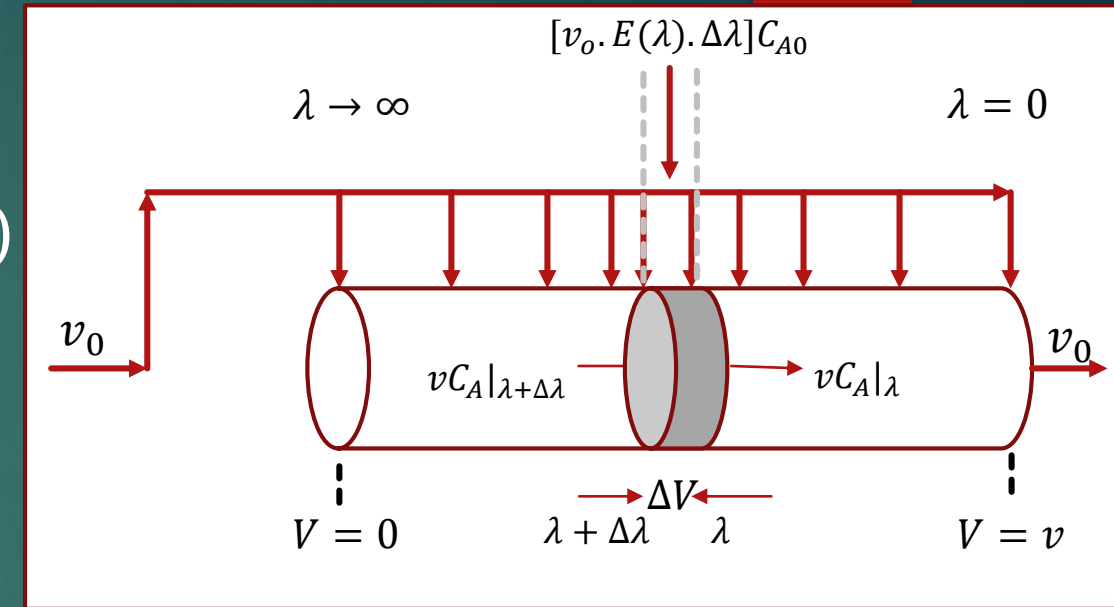
- Thus, the volume of fluid with life expectancy between λ and $\lambda+d\lambda$ is

$$\Delta V = v_o [1 - F(\lambda)] \Delta\lambda$$

- rate of generation of species A in this volume is: $r_A \Delta V = r_A v_o [1 - F(\lambda)] \Delta\lambda$

- Thus mole balance in the elemental volume is:

$$v_o \{ [1 - F(\lambda)] C_A \} |_{\lambda+\Delta\lambda} + v_o C_{A0} E(\lambda) \Delta\lambda - v_o \{ [1 - F(\lambda)] C_A \} |_\lambda + r_A v_o [1 - F(\lambda)] \Delta\lambda = 0$$



The differential equation for maximum mixedness model

► $v_0\{[1 - F(\lambda)]C_A\}|_{\lambda+\Delta\lambda} + v_0C_{A0}E(\lambda)\Delta\lambda - v_0\{[1 - F(\lambda)]C_A\}|_{\lambda} + r_Av_0[1 - F(\lambda)]\Delta\lambda = 0$

► Dividing by $v_0\Delta\lambda$ and taking the limits of $\Delta\lambda \rightarrow 0$ we have

► $C_{A0}E(\lambda) + \frac{d}{d\lambda} [[1 - F(\lambda)]C_A] + r_A[1 - F(\lambda)] = 0$ remember: $C_A = C_A(\lambda)$

► Thus, $C_{A0}E(\lambda) + [1 - F(\lambda)] \frac{d}{d\lambda} [C_A] - C_A E(\lambda) + r_A[1 - F(\lambda)] = 0$

$$\frac{dC_A}{d\lambda} = -r_A + (C_A - C_{A0}) \frac{E(\lambda)}{1 - F(\lambda)}$$

► And in terms of conversion:

$$\frac{dX}{d\lambda} = \frac{r_A}{C_{A0}} + X \frac{E(\lambda)}{1 - F(\lambda)}$$

○ With boundary conditions of $\lambda \rightarrow \infty$ then $C_A = C_{A0}$ or $X = 0$



Comparison between complete segregation and maximum mixedness models

► 2nd order liquid phase reaction $2A \rightarrow B$ $C_{A0} = 8 \frac{\text{mol}}{\text{dm}^3}$; $v_0 = 25 \frac{\text{dm}^3}{\text{min}}$

$-r_A = kC_A^2$ with $k = 0.01 \frac{\text{dm}^3}{\text{mol} \cdot \text{min}}$ at 320 K; Reactor vol = 1000 dm^3

Tracer test: $N_0 = 100 \text{ g}$ and $v = 25 \frac{\text{dm}^3}{\text{min}}$

► Determine $E(t)$ curve from $C(t)$ curve

- Is it a CSTR

- However, $\frac{1}{\tau} = \frac{v_0}{V} = \frac{25}{1000} = 0.025 \neq 0.028$

► For Segregation model: $\bar{X} = \int_0^\infty X(t)E(t)dt$

► Batch reactor equation for 2nd order reaction: $X = \frac{kC_{A0}t}{1+kC_{A0}t}$

► Numerical integration using trapezoid rule gives: $\bar{X} = \sum_0^\infty X(t)E(t)dt = 0.61$ 

t (min)	C(t)	E(t) min ⁻¹	X(t)	X(t).E(t) min ⁻¹	X(t)E(t)Δt
0	112	0.0280	0	0	0
5	95.8	0.0240	0.286	0.00686	0.0172
10	82.2	0.0206	0.444	0.00916	0.0400
15	70.6	0.0177	0.545	0.00965	0.0470
And so on					

Maximum mixedness the other bound for the zero parameter models

- ▶ Conversions for maximum mixedness: $\frac{dX}{d\lambda} = \frac{r_A}{C_{A0}} + X \frac{E(\lambda)}{1-F(\lambda)}$ Determine: $\frac{E(\lambda)}{1-F(\lambda)}$
- ▶ Using Euler method for numerical integration: $X_{i+1} = X_i + \Delta\lambda \left[\frac{r_A}{C_{A0}} + X_i \frac{E(\lambda)}{1-F(\lambda)} \right]$
 - This starts from $\lambda = 0$, however the solution is unstable and depends on the starting value of $X \rightarrow$ integrate backwards, i.e., start from $\lambda \rightarrow \infty$
- ▶ Integrating backward: $X_{i-1} = X_i - \Delta\lambda \left[X_i \frac{E(\lambda_i)}{1-F(\lambda_i)} - k C_{A0} (1 - X_i)^2 \right]$
- ▶ $\lambda \rightarrow \infty$ (or at the beginning), we have $X = 0$
- ▶ X at ($\lambda = 0$, outlet) = 0.564 compared to 0.61 for segregated model

t (min)	C(t)	E(t) min ⁻¹	1-F(t)	E(t)/[1-F(t)]	λ
0	112	0.0280	1.00	0.0280	0
5	95.8	0.0240	0.871	0.0276	5
10	82.2	0.0206	0.760	0.0271	10
And so on					
200	0.90	0.000225	0.003	0.0750	200

Maximum mixedness model by solving the ODE

- The maximum mixedness model: $\frac{dX}{d\lambda} = \frac{r_A}{C_{A0}} + X \frac{E(\lambda)}{1-F(\lambda)}$
- Which is to be integrated from $\lambda \rightarrow \infty$ (reactor beginning) to $\lambda = 0$ (reactor end)
 - Difficult to integrate backwards \rightarrow change variable so integration is in forward direction
 - Achieved by introducing a new variable, z , such that

$$z = \bar{T} - \lambda = 200 - \lambda \text{ OR } \lambda = \bar{T} - z = 200 - z$$

- Thus, $\frac{dX}{dz} = -\frac{r_A}{C_{A0}} - X \frac{E(\bar{T}-z)}{1-F(\bar{T}-z)}$
- To solve the ODE, the $E(t)$ or $F(t)$ curve are fit to polynomial(s)
- $E(t)$ should not be negative and $F(t)$ should not be equal to one at the beginning
- It is then possible to integrate from $z = 0$ (reactor beginning) to $z = 200$ (reactor end)
- For the same case (Example 13-7) $X = 0.56$ compared to 0.61



Comparison of ideal reactors and models and some comments

- ▶ Example 13-7 is a nice exercise on the application of segregated and maximum mixedness models in detail
 - Complete segregation: 0.61
 - Maximum mixedness: 0.56
 - For a PFR of this size: 0.76
 - For a CSTR of this size: 0.58
- ▶ Not all tank reactors are CSTRs nor are all tubular reactors PFRs
- ▶ RTD is sufficient if the reaction was 1st order; Non-1st order needs a model
- ▶ Segregation and Maximum mixedness models (zero parameter) are bounds to the real reactor



One parameter models

- ▶ One parameter is used to describe the non-ideality of the real reactor
 - One parameter models for CSTR are dead volume, V_D , or fraction of bypass, f
 - One parameter models for PFR include tanks-in-series (n) and dispersion (D_a)
- ▶ Often the parameter is obtained by analyzing the RTD function determined by from a tracer test
- ▶ Tubular reactors may be empty or packed
 - Ideal tubular (PFR) have piston like flow, no radial velocity profile, no axial mixing and every fluid element spends the same amount of time in the reactor
 - Often plug-flow and insufficient axial-mixing usually fail in real reactors
- ▶ One approach is to model the non-ideal tubular reactor as a series of identical CSTRs (tanks-in-series); the other is to consider axial dispersion along with plug-flow



Tanks-in-series (T-I-S) model is an one parameter model

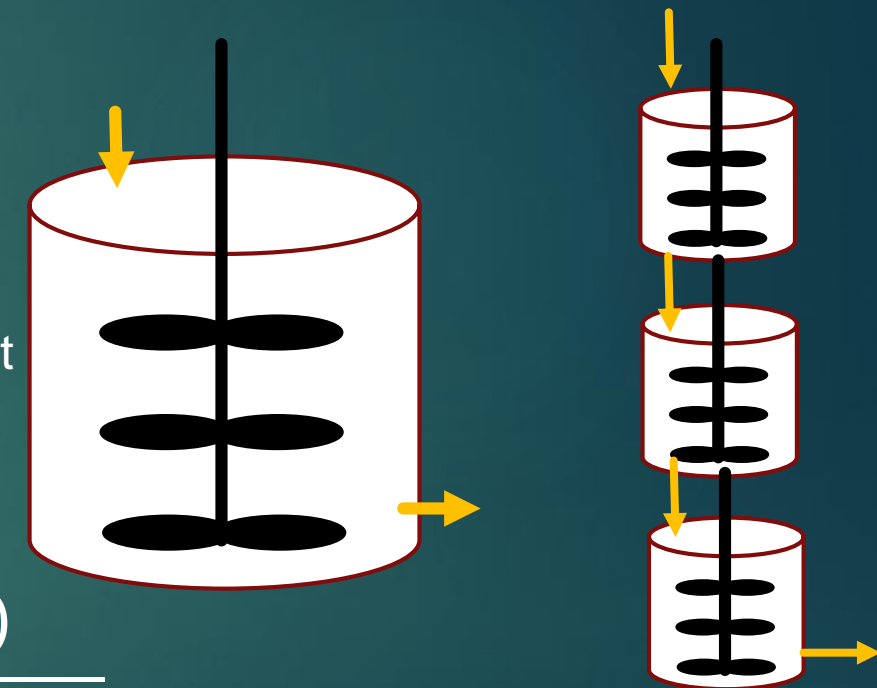
- ▶ Analyze the RTD to determine the number of ideal tanks in series that can approximate the non-ideal tubular reactor
- ▶ For example, 3 T-I-S to represent the real reactor
 - Then generalize for n T-I-S

- ▶ Analysis of the 3 T-I-S based on pulse injected to 1st

- ▶ From the $C(t)$ curve coming out of the 3rd reactor

$$E(t) = \frac{C_3(t) \cdot v}{\int_0^{\infty} C_3(t) \cdot v \cdot dt} = \frac{C_3(t)}{\int_0^{\infty} C_3(t) dt}$$

- ▶ For the 1st reactor: $C_1 = C_0 \exp(-t/\tau)$ and $C_0 = \frac{N_0}{V_1} = \frac{v_0 \int_0^{\infty} C_3(t) dt}{V_1}$



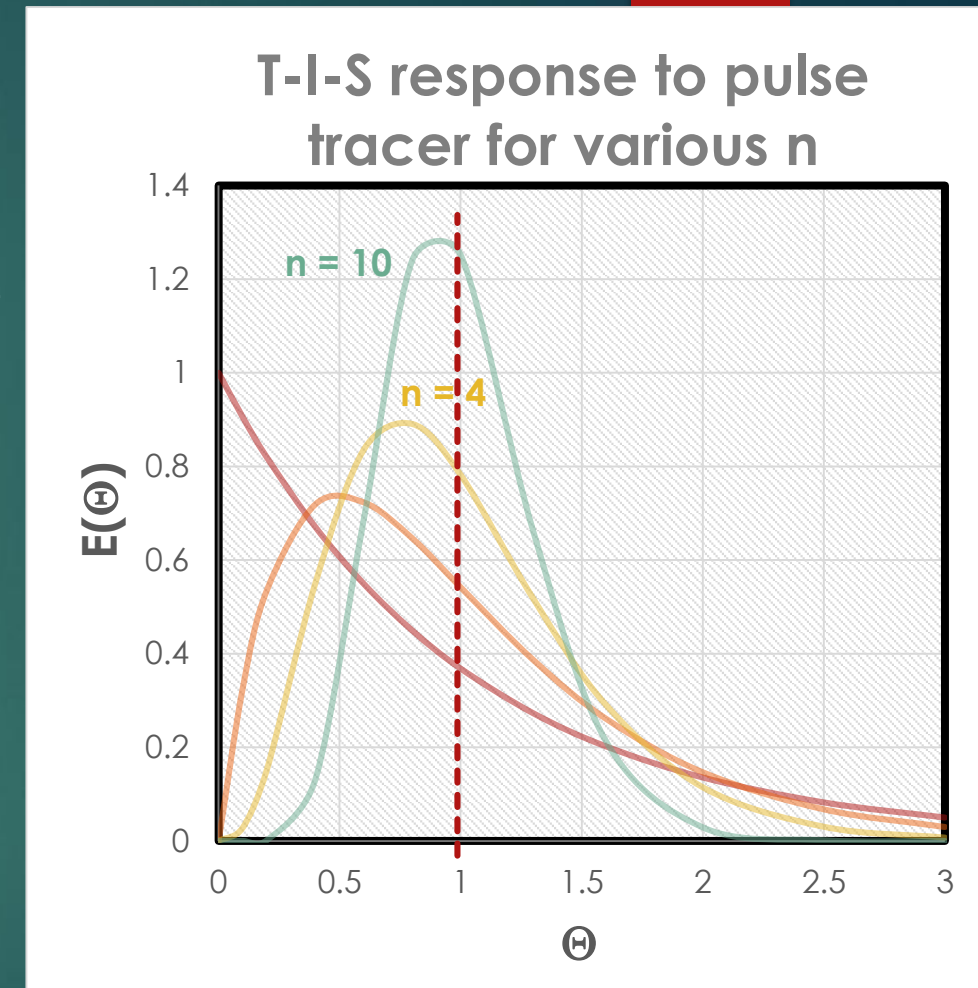
Material balance on tracer is useful for analysis

- ▶ For 1st reactor: $C_1 = C_0 \exp(-t/\tau_1)$
- ▶ For 2nd reactor: $V_2 \frac{dC_2}{dt} = vC_1 - vC_2 \rightarrow \tau_2 \frac{dC_2}{dt} = C_0 \exp(-t/\tau_1) - C_2$
- ▶ $\frac{dC_2}{dt} + \frac{C_2}{\tau_2} = \frac{C_0}{\tau_2} \exp(-t/\tau_1)$ since CSTRs are of equal vol: $\tau_1 = \tau_2 = \tau_3 = \tau_i$
- ▶ Thus, $C_2 = \frac{C_0 t}{\tau_i} \exp(-t/\tau_i)$ Similarly, $C_3 = \frac{C_0 t^2}{2\tau_i^2} \exp(-t/\tau_i)$
- ▶ Substituting in RTD: $E(t) = \frac{C_3(t)}{\int_0^\infty C_3(t) dt} = \frac{\frac{C_0 t^2}{2\tau_i^2} \exp(-t/\tau_i)}{\int_0^\infty \frac{C_0 t^2}{2\tau_i^2} \exp(-t/\tau_i) dt} = \frac{t^2}{2\tau_i^2} \exp(-t/\tau_i)$
- ▶ In general: $E(t) = \frac{t^{n-1}}{(n-1)!\tau_i^n} \exp(-t/\tau_i)$ Further, $V = nV_i$
- ▶ And, $\tau_i = \frac{\tau}{n}$ where τ is for real reactor Thus, $E(\theta) = \frac{n(n\theta)^{n-1}}{(n-1)!} \exp(-n\theta)$



RTD response depends on the number of Tanks-In-Series

- ▶ $E(\theta) = \frac{n(n\theta)^{n-1}}{(n-1)!} \exp(-n\theta)$ and σ_θ^2 is given by
- ▶ $\sigma_\theta^2 = \frac{\sigma^2}{\tau^2} = \int_0^\infty (\theta - 1)^2 E(\theta) d\theta = \int_0^\infty \theta^2 E(\theta) d\theta - 1$
- ▶ $\sigma_\theta^2 = \int_0^\infty \theta^2 \frac{n(n\theta)^{n-1}}{(n-1)!} \exp(-n\theta) d\theta - 1$
- ▶ $\sigma_\theta^2 = \frac{(n)^n}{(n-1)!} \int_0^\infty \theta^{n+1} \exp(-n\theta) d\theta - 1$
- ▶ $\sigma_\theta^2 = \frac{(n)^n}{(n-1)!} \left[\frac{(n+1)!}{n^{n+2}} \right] - 1 = 1/n \quad \rightarrow n = \frac{1}{\sigma_\theta^2} = \frac{\tau^2}{\sigma^2}$



- ▶ Thus, the number of reactors needed to model the real reactor as n ideal tanks in series can be determined from the variance of the $E(\Theta)$ vs Θ data
- ▶ Using n the conversion can be calculated for a series of CSTRs!

