

Module # 1.3

INTRODUCTION

Process Dynamics

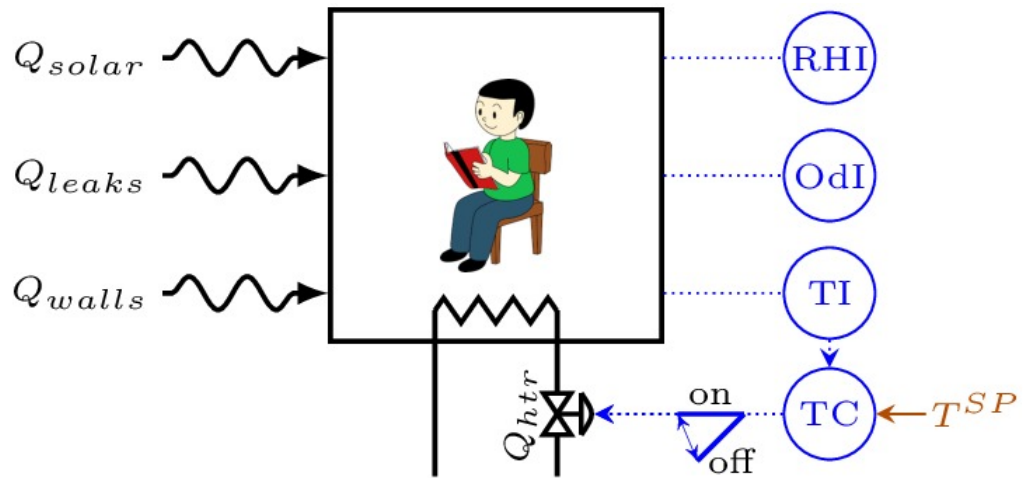
Lectures on

CHEMICAL PROCESS CONTROL
Theory and Practice

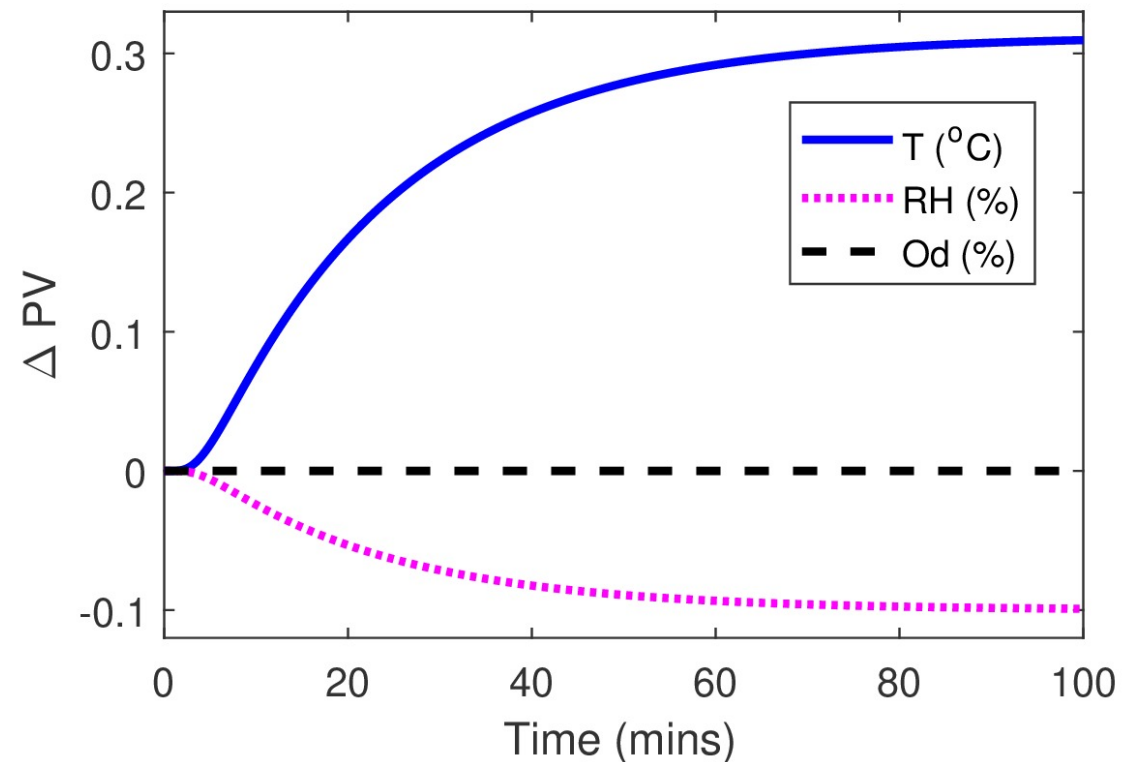
Process Dynamics

- Output PV trajectory over time in response to input PV changes
 - Process with no control
 - Process with a control system installed

ROOM EXAMPLE



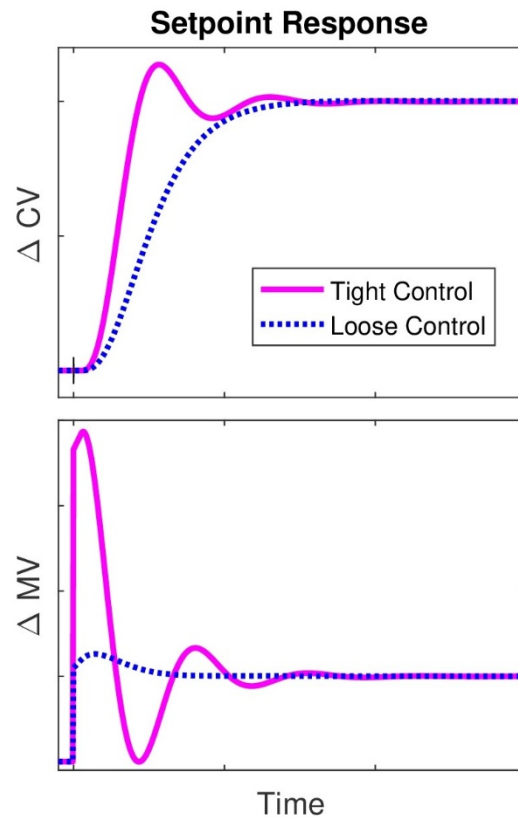
Output PV Dynamics: No control



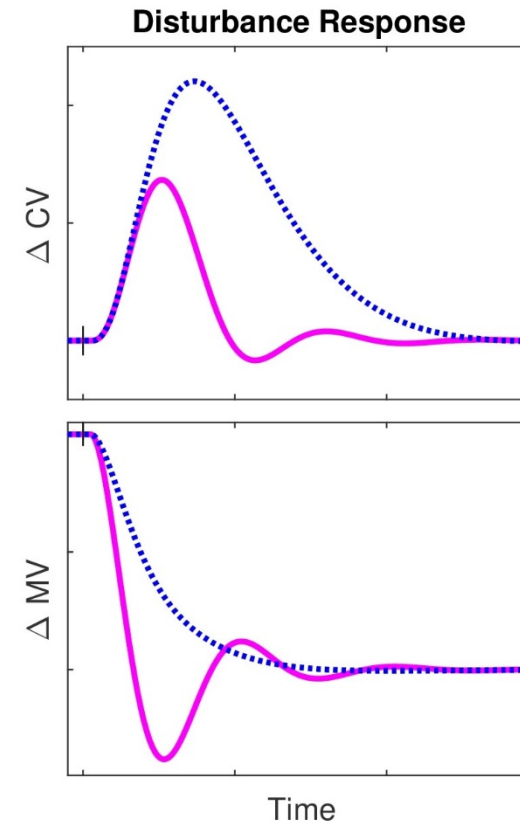
Dynamics with Control

- Two types of responses
 - Response to a CV setpoint change (SERVO)
 - Response to a disturbance change (REGULATOR)

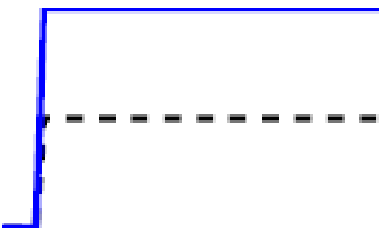
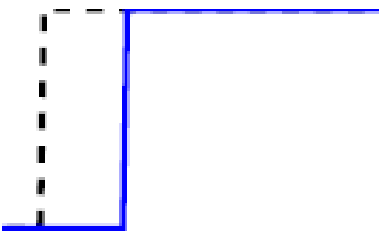
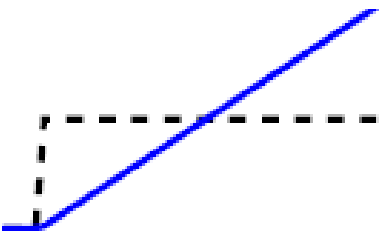
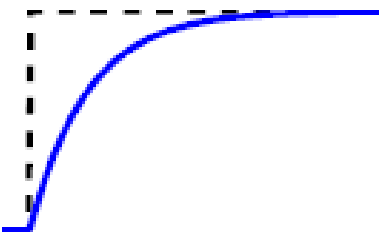
SERVO



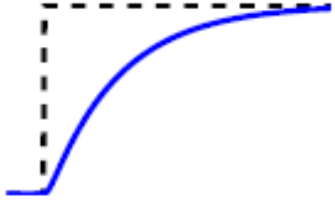
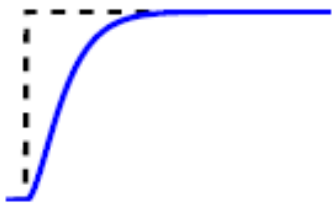
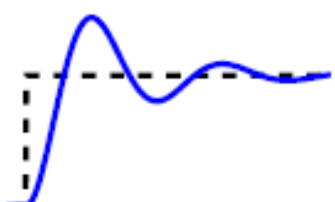
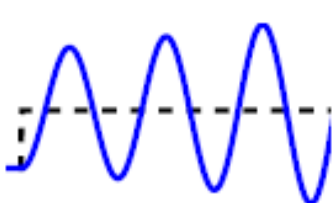
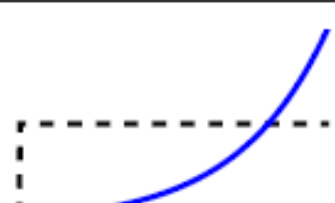
REGULATOR



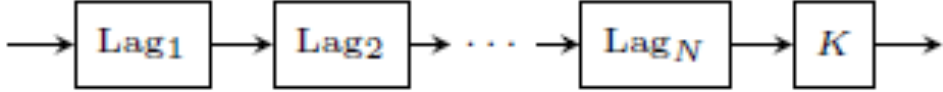
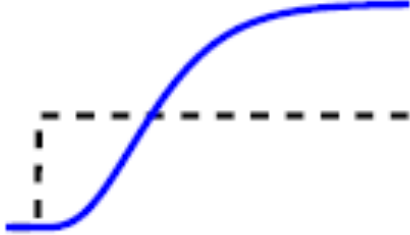
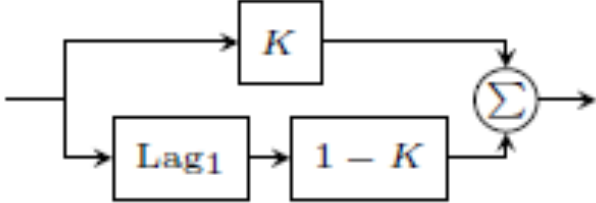
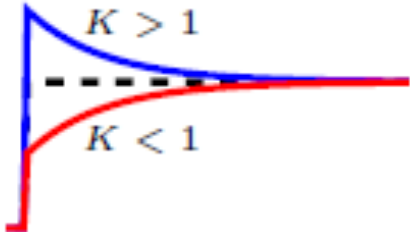
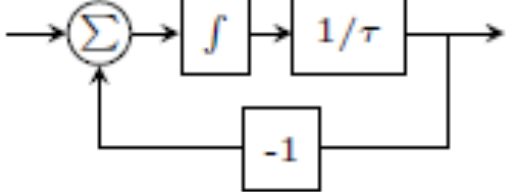
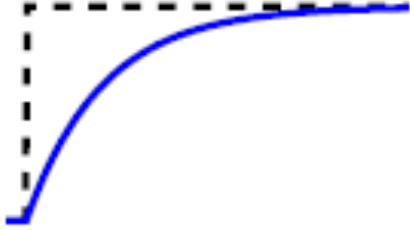
Basic Dynamic Responses

Pure Gain	
Pure Delay	
Integrator	
Lag	

Basic Dynamic Responses

2 nd order overdamped	
2 nd order critically damped	
2 nd order underdamped	
Unstable oscillatory	
Unstable non-oscillatory	

Complex Responses by Combining Basic Responses

Lags in Series		
Lead-Lag		
Lag from Feedback		

SERIES, PARALLEL & FEEDBACK STRUCTURES

Complex Responses by Combining Basic Responses

Inverse Response	<p>Speed $\text{Lag}_2 \gg \text{Lag}_1$</p> <p>$K_1 > K_2$</p>	
Inverse + Integrator		

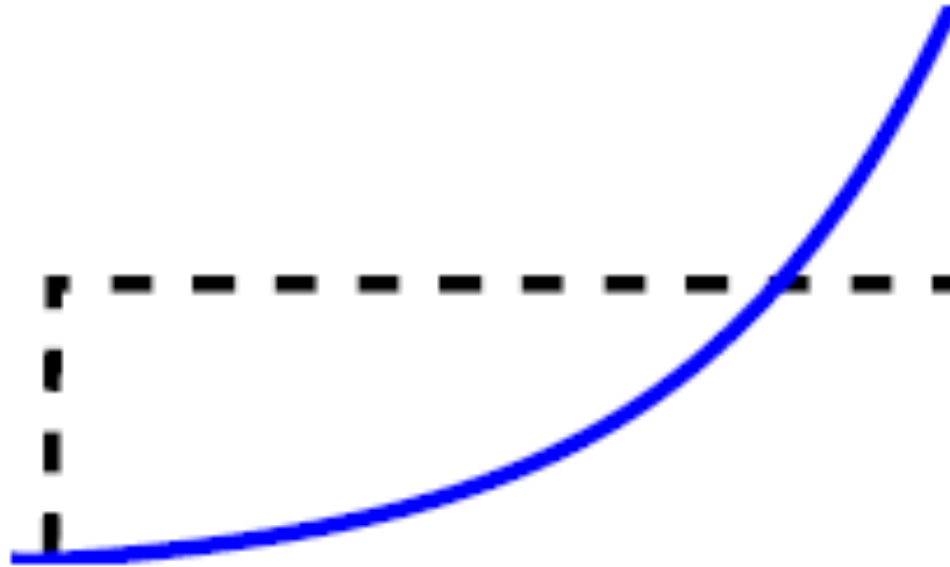
Examples in Nature?

Complex Responses by Combining Basic Responses

Pandemic	<p>Lags1 faster</p> <p>Lags</p> <p>Lags1</p> <p>Lags2</p> <p>K</p> <p>K</p> <p>-1</p> <p>Σ</p>	
Rippling Ramp	<p>∫</p> <p>1/τ</p> <p>2nd order</p> <p>K</p> <p>Σ</p> <p>Sustained oscillations</p>	

Examples in Nature?

Exercise: Combining Basic Responses



Real-life example?

Summary

- Nature exhibits a variety of dynamic responses
- The variety of responses well represented by a combination of basic dynamic response elements
 - Series
 - Parallel
 - Feedback or recycle
- The basic dynamic response elements
 - Pure gain
 - Pure dead time
 - Pure integrator
 - First order lag
 - Second order lag