# **Data Structures and Algorithms**

(ESO207)

#### Lecture 17:

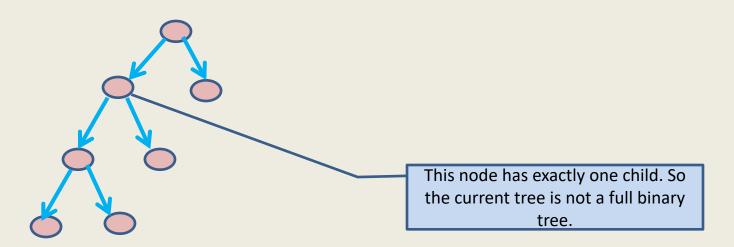
#### **Height balanced BST**

Red-black trees

# **Terminologies**

#### **Full binary tree:**

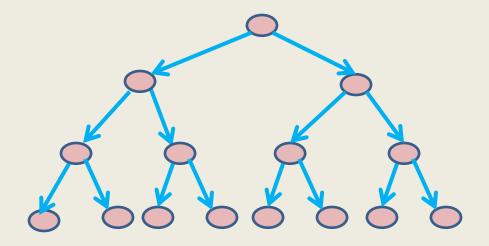
A binary tree where every internal node has exactly two children.



# **Terminologies**

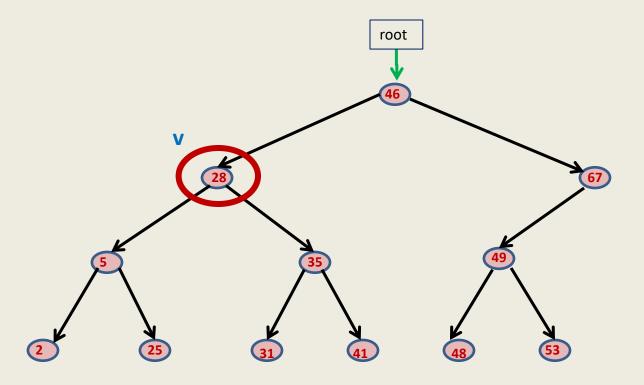
#### **Complete binary tree:**

A full binary tree where every leaf node is at the same level.



We shall later extend this definition when we discuss "Binary heap".

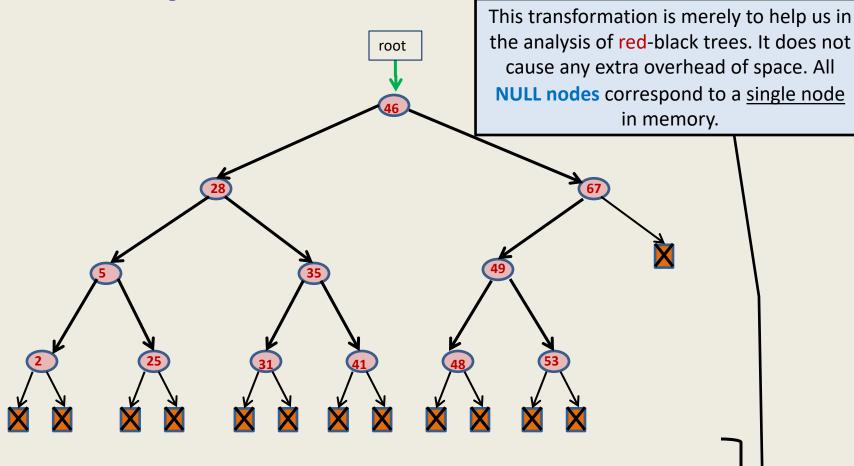
# **Binary Search Tree**



**Definition:** A Binary Tree **T** storing values is said to be Binary Search Tree if for each node **v** in T

- If left(v) <> NULL, then value(v) > value of every node in subtree(left(v)).
- If right(v)<>NULL, then value(v) < value of every node in subtree(right(v)).</li>

Binary Search Tree: a slight change



Henceforth, for each **NULL child link** of a node in a **BST**, we create a **NULL** node

- **1.** Each **leaf node** in a BST will be a **NULL** node.
  - **2.** the BST will always be a **full binary tree**.

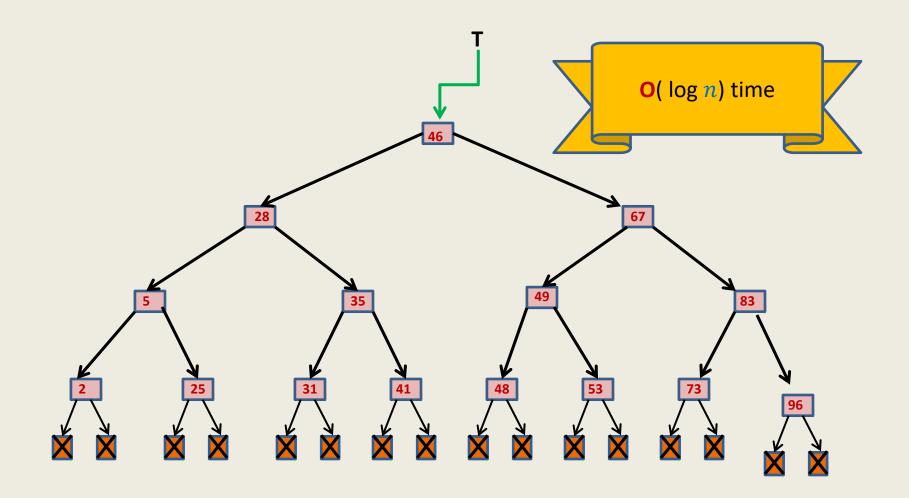
# A fact we noticed in our previous discussion on BSTs (Lecture 9)

Time complexity of Search(T,x) and Insert(T,x) in a Binary Search Tree T = O(Height(T))

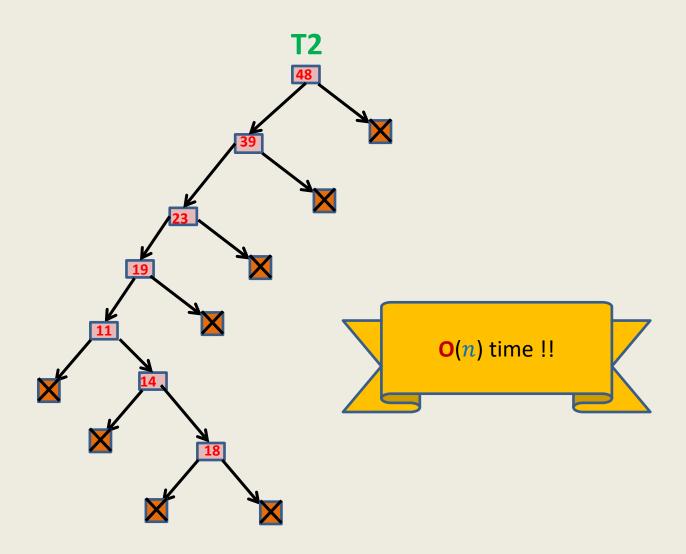
#### Height(T):

The maximum number of nodes on any path from root to a leaf node.

## Searching and inserting in a perfectly balanced BST



## Searching and inserting in a skewed BST on n nodes



## **Nearly balanced Binary Search Tree**

#### **Terminology:**

size of a binary tree is the number of nodes present in it.

**Definition:** A binary search tree **T** is said to be <u>nearly balanced</u> at node **v**, if

$$size(left(v)) \le \frac{3}{4} size(v)$$
 and

$$size(right(v)) \le \frac{3}{4} size(v)$$

**Definition:** A binary search tree **T** is said to be **nearly balanced** if it is **nearly balanced** at each node.

## **Nearly balanced Binary Search Tree**

- Search(T,x) operation is the same.
- Modify Insert(T,x) operation as follows:
  - Carry out normal insert and update the size fields of nodes traversed.
  - If BST T is ceases to be nearly imbalanced at any node v,
     transform subtree(v) into perfectly balanced BST.
- $\rightarrow$  O(log n) time for search
- $\rightarrow$  O(n log n) time for n insertions

#### **Disadvantages:**

- How to handle deletions?
- Some insertions may take O(n) time  $\Theta$

This fact will be proved soon in a subsequent lecture.

# Can we achieve O(log n) time for search/insert/delete?

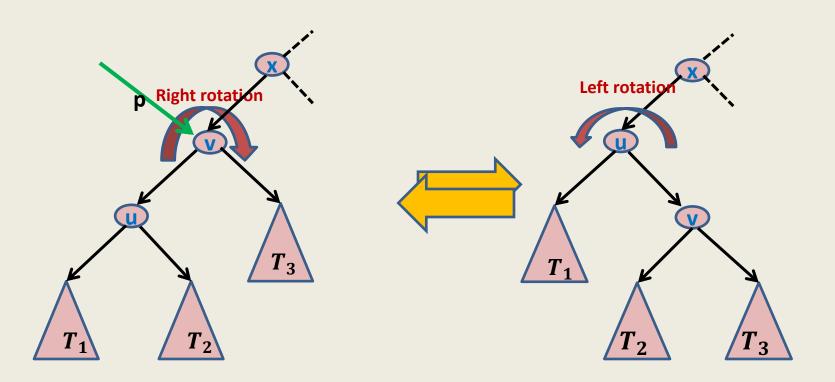
- AVL Trees [1962]
- Red Black Trees [1978]

#### **Rotation** around a node

#### An important tool for balancing trees

Fach height balanced **BST** employs this tool which is derived from the **flexibility** which is <u>hidden</u> in the structure of a **BST**. This flexibility (**pointer manipulation**) was inherited from linked list ©.

## **Rotation** around a node



Note that the tree **T** continues to remain a BST even after rotation around any node.

# Red Black Tree A height balanced BST

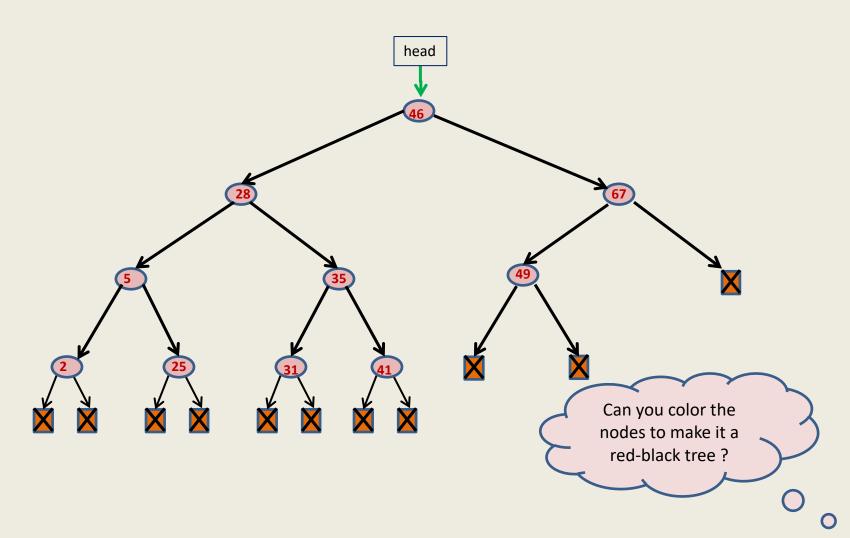
## Red Black Tree

Red-Black tree is a binary search tree satisfying the following properties:

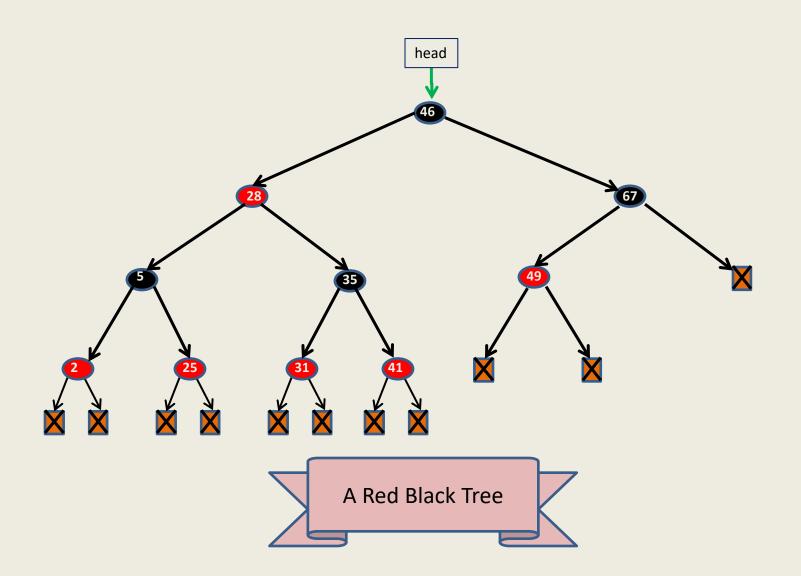
- Each node is colored red or black.
- Each leaf is colored black and so is the root.
- Every red node will have both its children black.
- No. of <u>black nodes</u> on a path from root to each leaf node is same.

**black** height

# A binary search tree



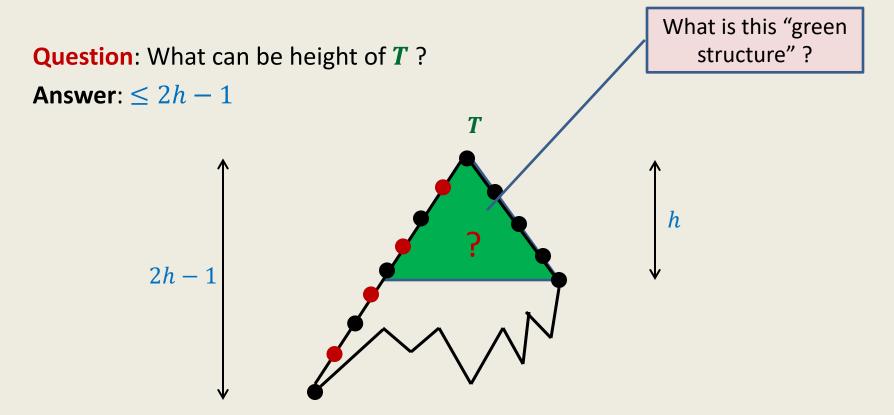
## A binary search tree



## Why is a red black tree height balanced?

T: a red black tree

h: black height of T.

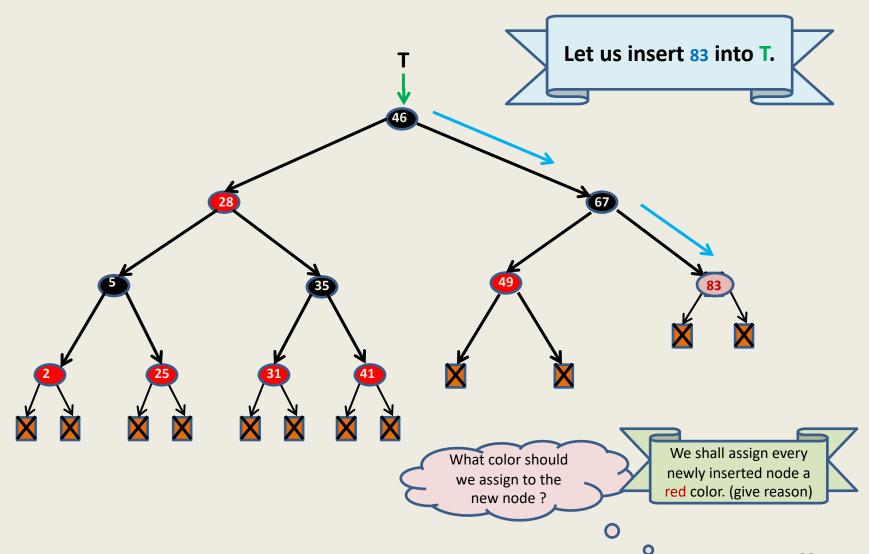


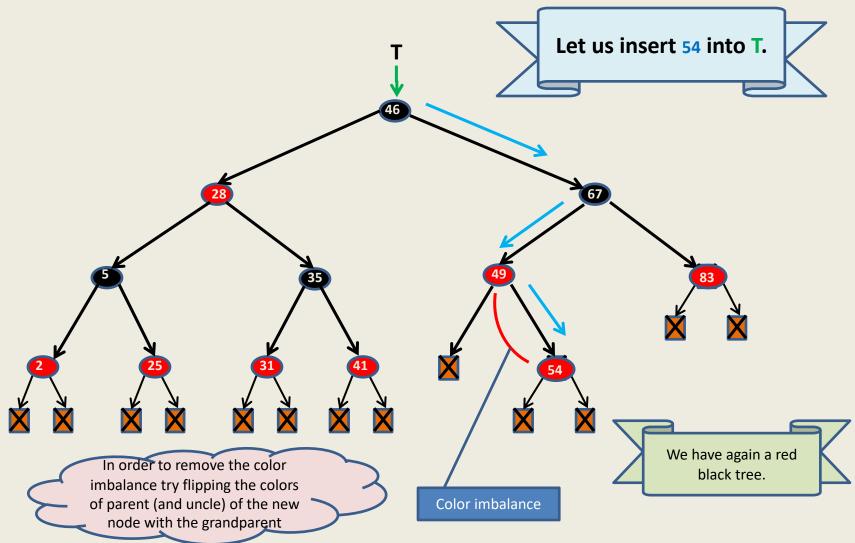
**Homework**: Ponder over the above hint to prove that T has  $\geq 2^h - 1$  elements.

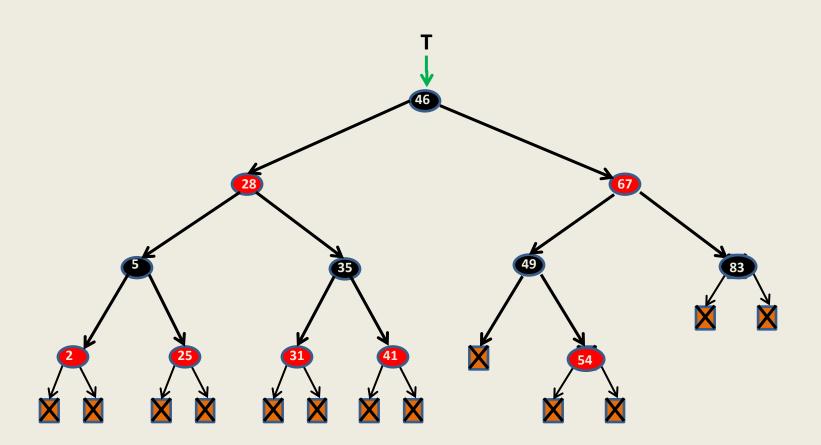
# Insertion in a Red Black tree

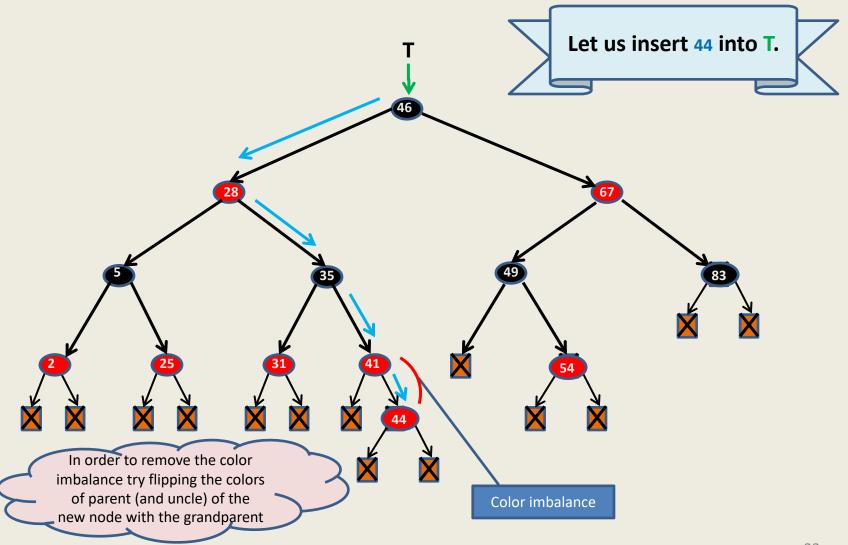
#### All it involves is

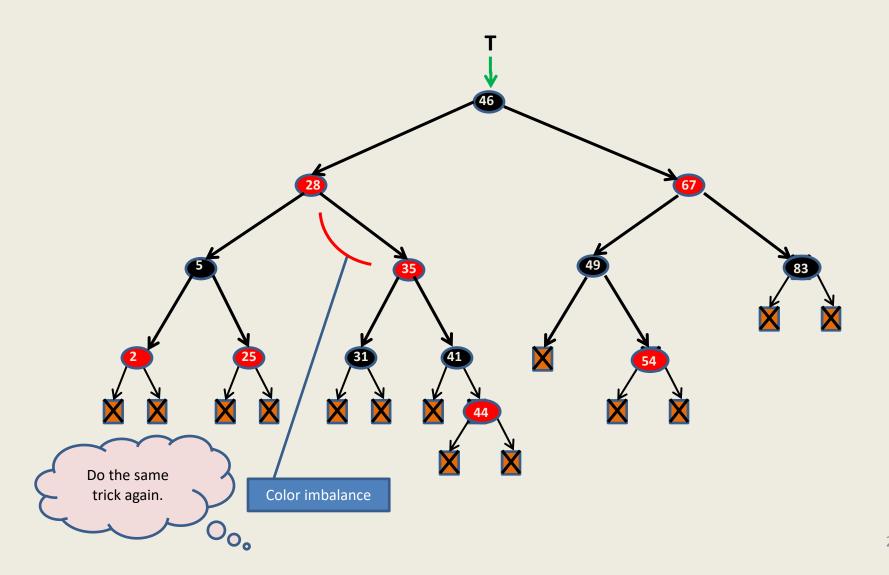
- playing with colors ©
- and rotations ©

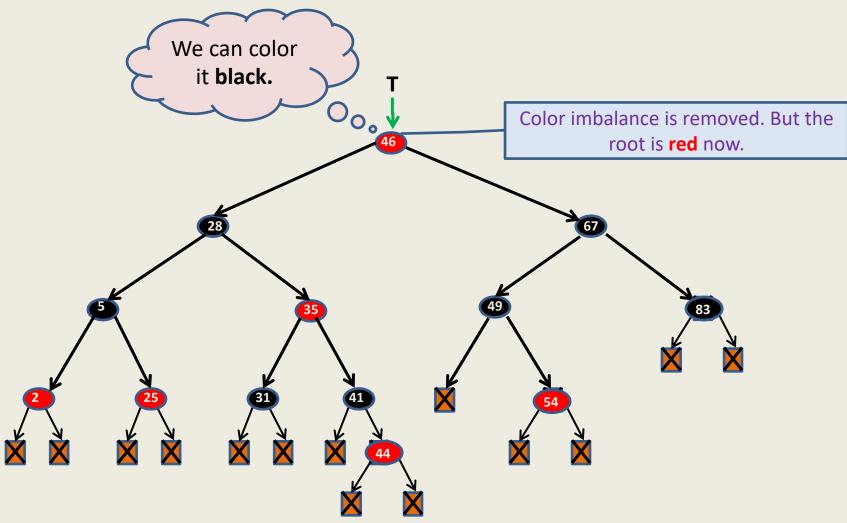


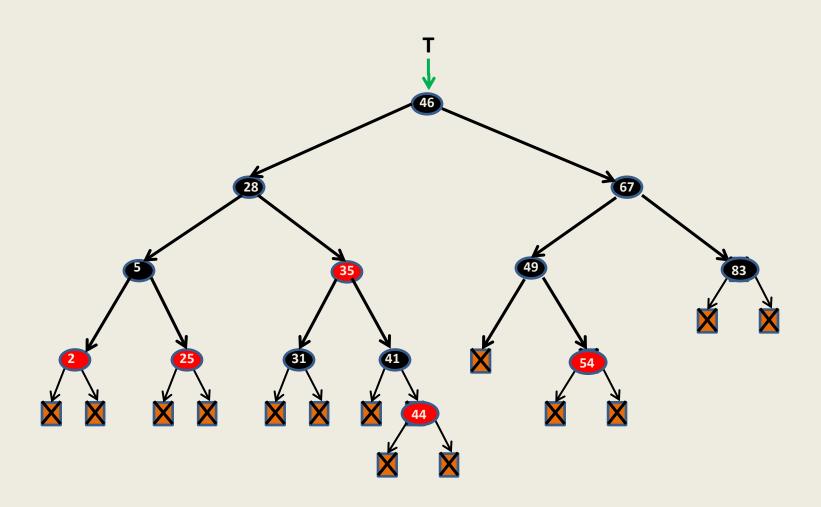












# Insertion in a red-black tree summary till now ...

Let p be the newly inserted node. Assign red color to p.

Case 1: parent(p) is black nothing needs to be done.

Case 2: parent(p) is red and uncle(p) is red,
Swap colors of parent (and uncle) with grandparent(p).
This balances the color at p but may lead to imbalance of color at grandparent of p. So p ← grandparent(p), and proceed upwards similarly.
If in this manner p becomes root, then we color it black.

Case 3: parent(p) is red and uncle(p) is black.

This is a nontrivial case. So we need some more tools ....

# **Handling case 3**

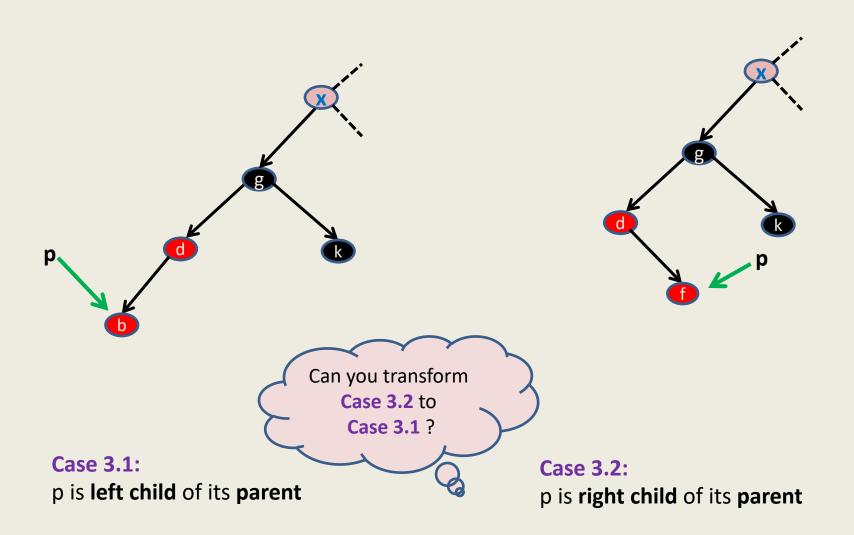
## **Description of Case 3**

- p is a red colored node.
- parent(p) is also red.
- uncle(p) is black.

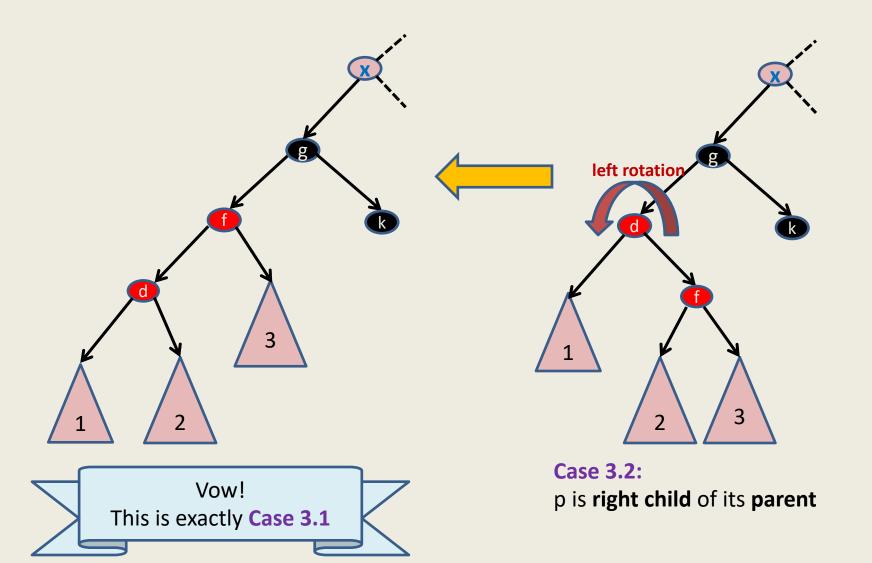
Without loss of generality assume: **parent(p)** is **left child** of grandparent(p).

(The case when parent(p) is right child of grandparent(p) is handled similarly.)

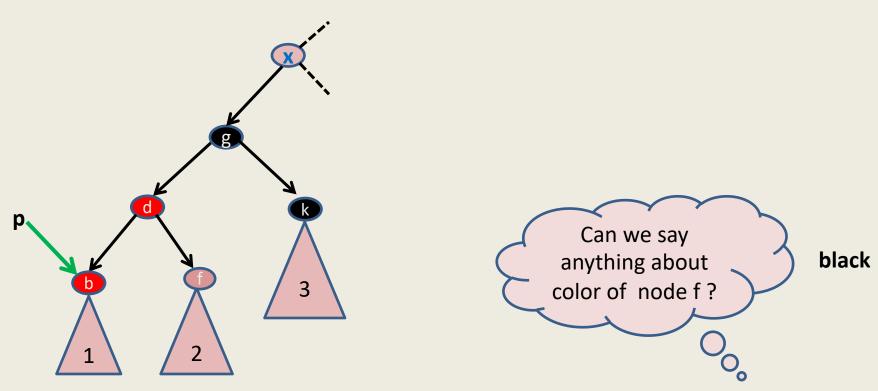
two cases arise depending upon whether p is left/right child of its parent

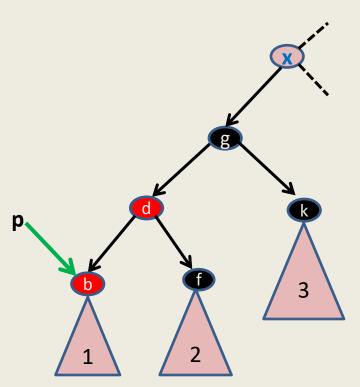


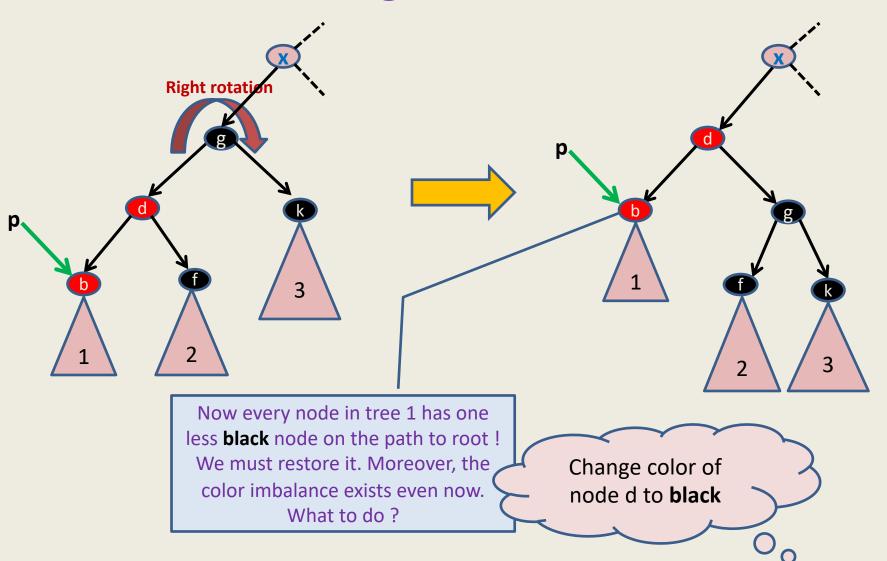
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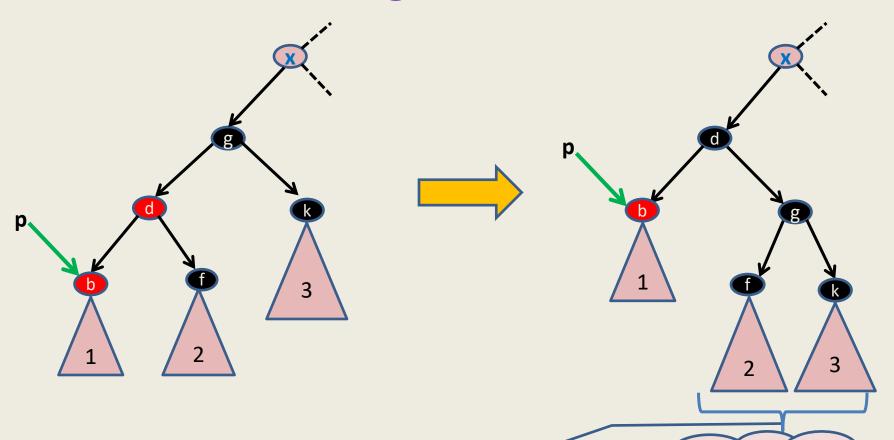


## We need to handle only case 3.1



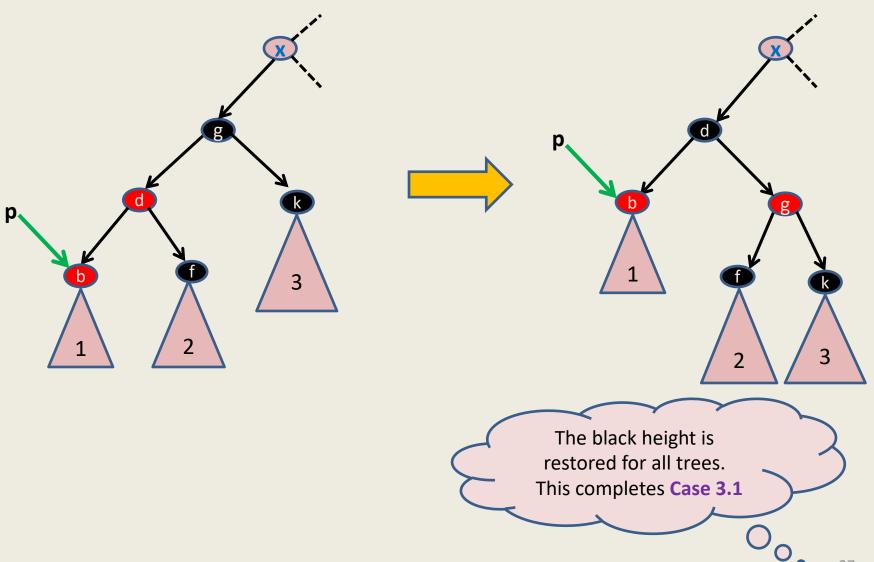






The number of **black** nodes on the patherestored for tree 1. Color imbalance is But the number of **black** nodes on the patherestored for trees 2 and 3. What to do now

Color node g red



#### Theorem:

We can maintain **red-black** trees under insertion of nodes in  $O(\log n)$  time per <u>insert/search</u> operation where n is the number of the nodes in the tree.

I hope you enjoyed the real fun in handling insertion in a red black tree.

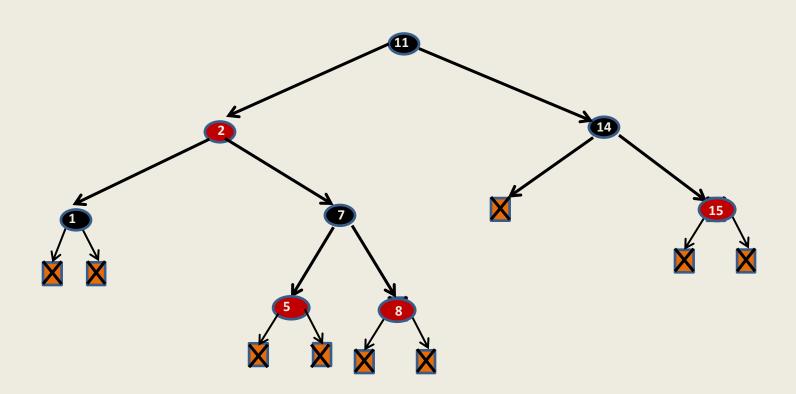
The following are the natural questions to ask.

- Why we are handling insertions in "this particular way"?
- Are there alternative and simpler ways to handle insertions?

You are encouraged to explore the answer to both these questions. You are welcome to discuss them with me.

• Please solve the problem on the following slide.

## How to insert 4?



#### How do will we handle deletion?

This is going to be a bit more complex.

So please try on your own first before next lecture.

It will still involve playing with colors and rotations ©

