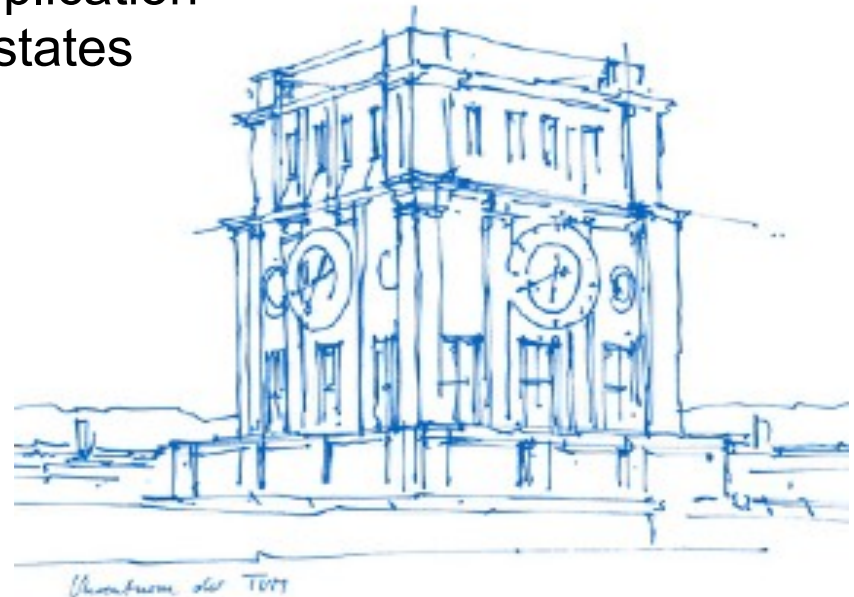
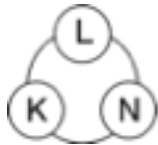


An augmented reality-based mobile application for visualizing robot models and robot states

Philipp Knestel

Prof. Dr.-Ing. Wolfgang Kellerer
Prof. Dr.-Ing. Eckehard Steinbach
Dr.-Ing. Daniel Wahrmann
M.Sc. Hasan Furkan Kaynar



Outline

1. Introduction
2. Pre-Study
3. Implementation
4. User Study
5. Conclusion



Source: Own Figure