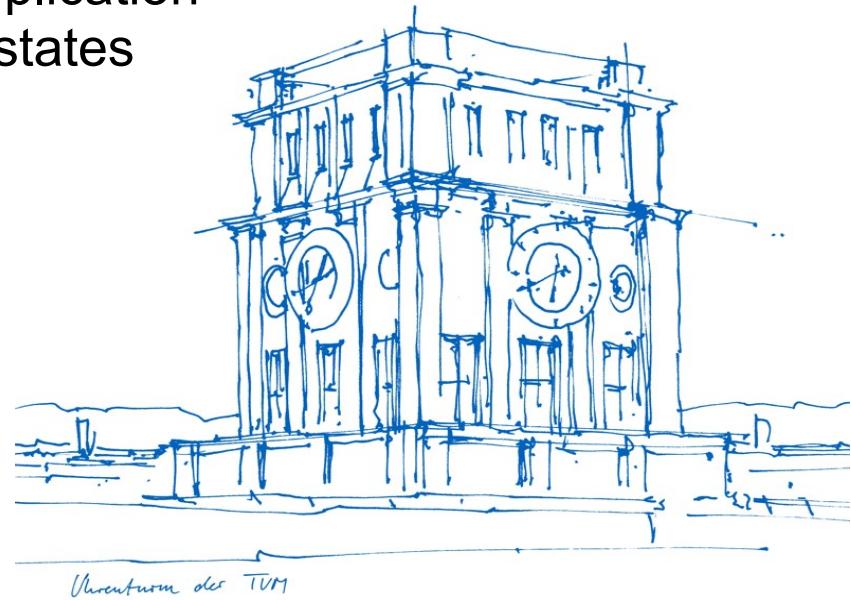
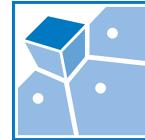
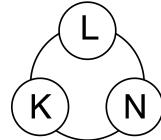


An augmented reality-based mobile application for visualizing robot models and robot states

Philipp Knestel

Prof. Dr.-Ing. Wolfgang Kellerer
Prof. Dr.-Ing. Eckehard Steinbach
Dr.-Ing. Daniel Wahrmann
M.Sc. Hasan Furkan Kaynar



Outline

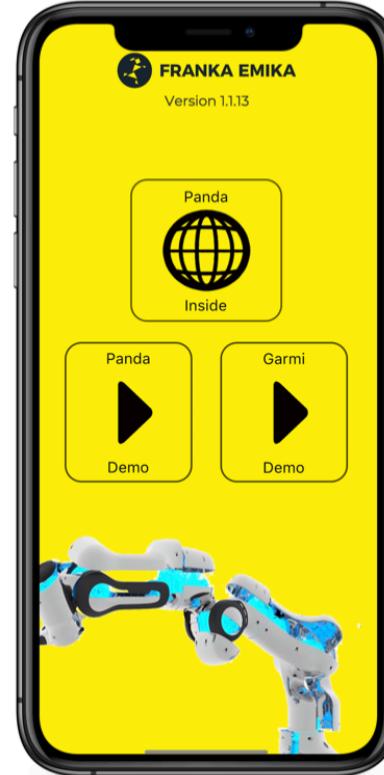
1. Introduction

2. Pre-Study

3. Implementation

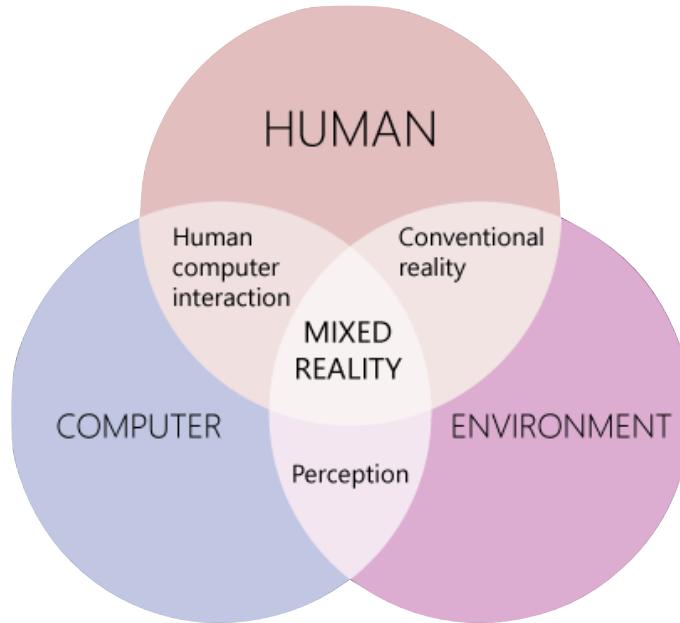
4. User Study

5. Conclusion



Source: Own Figure

Introduction



<https://docs.microsoft.com/de-de/windows/mixed-reality/discover/images/mixed-reality-venn-diagram-300px.png>

What is mixed reality?

- Blend of physical an digital world
- Links humans, computer and the environment
- Visualizing interaction

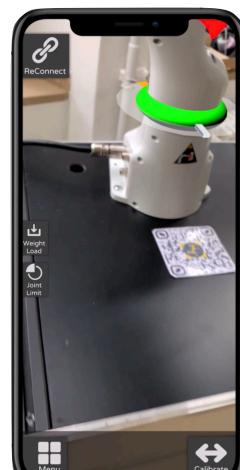
Research Question:

Can an AR application improve Human-Machine communication?

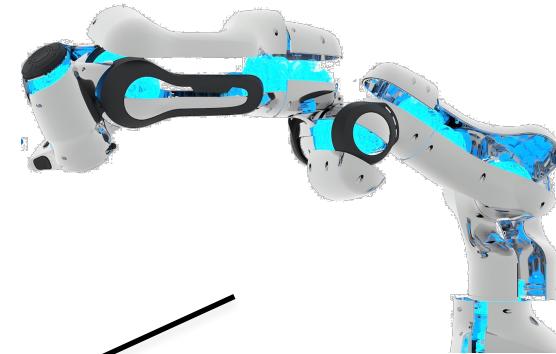


Source: [Link](#)

Human perception



Source: Own Figure



Source: Own Figure

Robot perception

FEAR App

Pre-Study: Which functions should be in this application?

Questions

1. Problems with:

- Joint limits?
- Payload?

2. Is a [...] useful?

- task preview
- recording function

Results

Joint Limits:

Problem for 9/12

Payload:

Problem for 8/12

Task Preview:

Useful for 11/12

Recording function:

Useful for 4/12

Pre-Study: Which functions should be in this application?

Questions

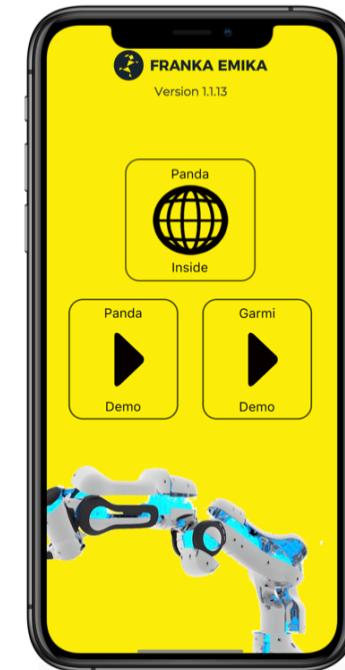
Personal feedback:

Results

Feedback:

- Garmi model
- Panda model
- External forces of the Panda

Conclusion

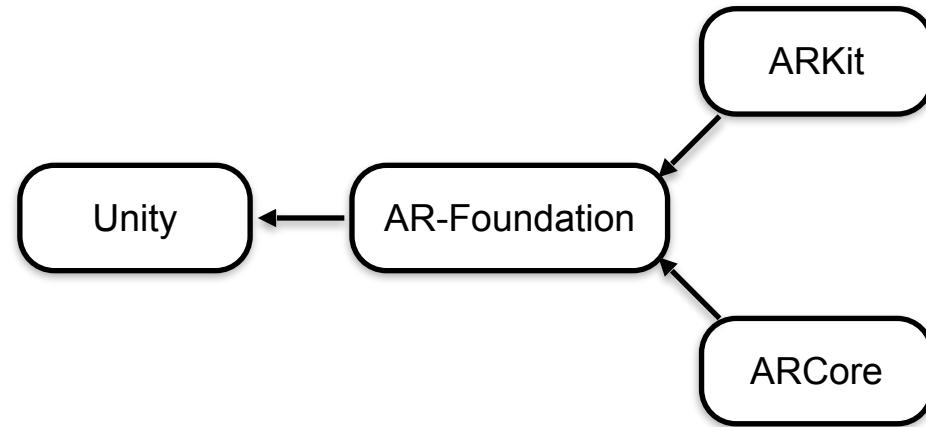


Source: Own Figure

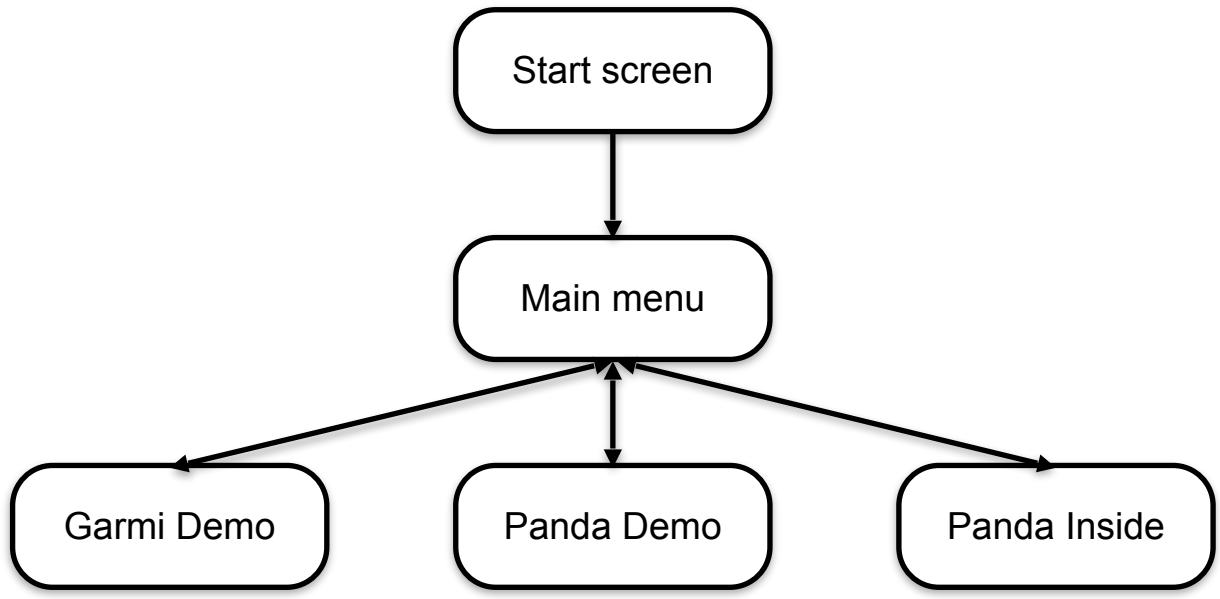
Implementation: Which development environment?

Requirements:

- Platform-independent
- Latest API
- Surface recognition
- 2D image recognition
- Anchor settling



Structure of the FEAR application



Source: Own Figure

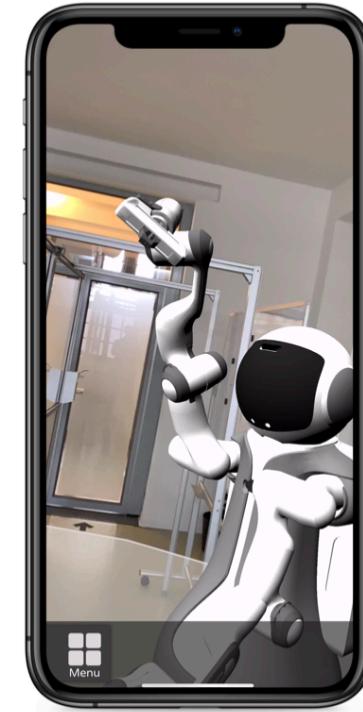
Function: Garmi Demo



Source: Own Figure

Components:

- Surface recognition by the AR-Foundation API
- Garmi (Humanoid Robot of Franka Emika)
- Tap to place model
- Shaking arm



Source: Own Figure

Function: Garmi Demo



Source: Own Figure

Function: Panda Demo

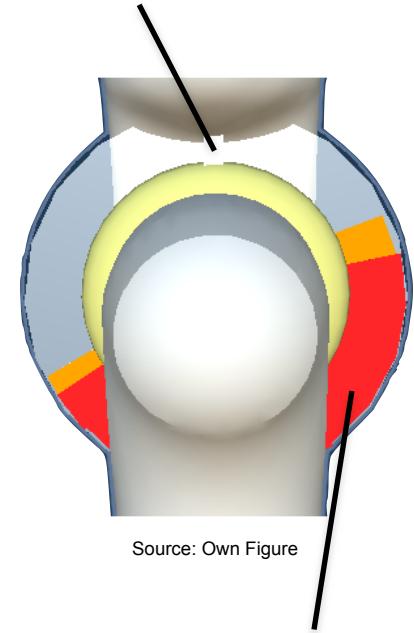


Source: Own Figure

Components:

- Same surface recognition
- Same tap to place
- Panda Arm model
- Slider for joint rotation
- Joint limits

Current position



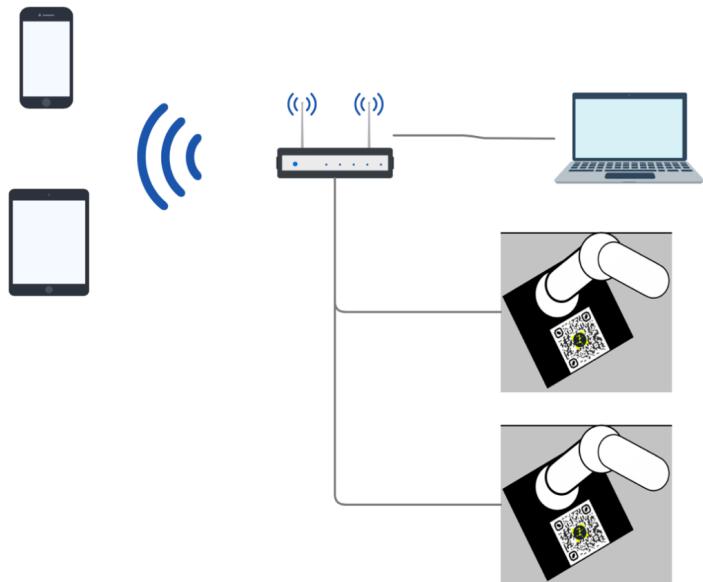
Joint limit

Function: Panda Demo

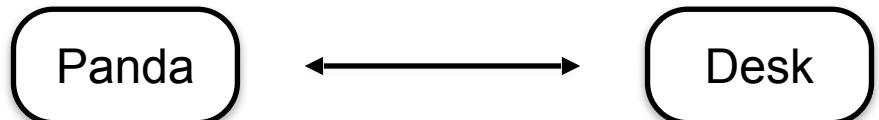


Source: Own Figure

Function: Panda Inside



Normal Connection

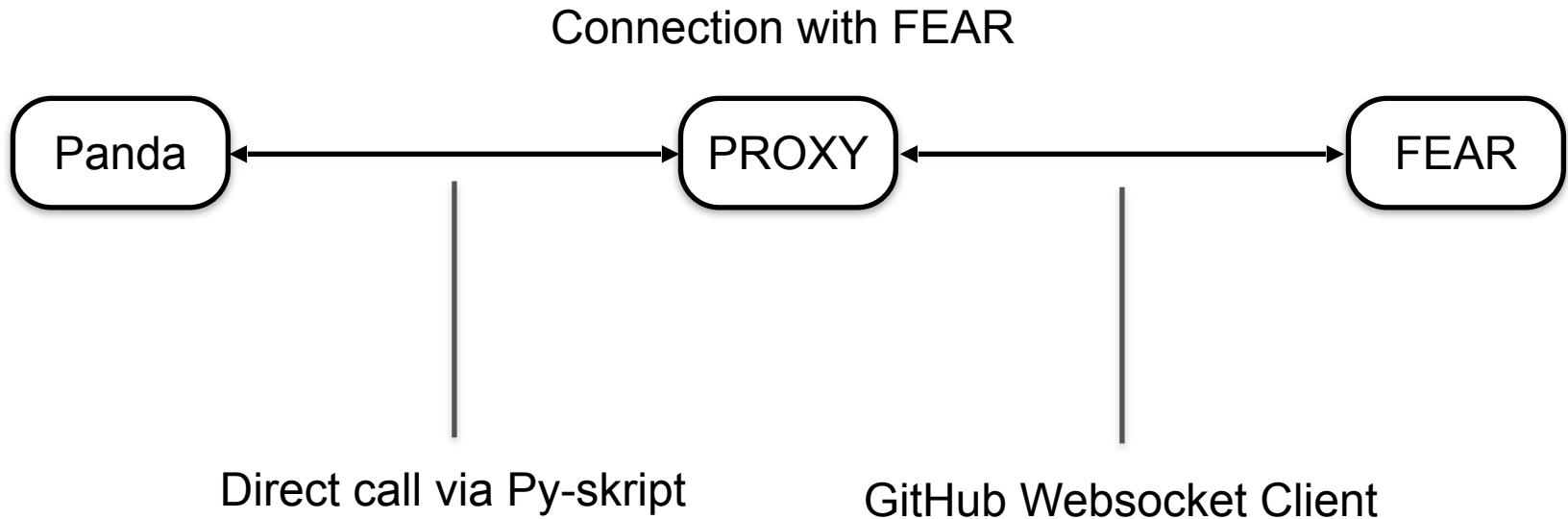


Connection with FEAR



Source: Own Figure

Function: Panda Inside



Function: Panda Inside



Step 1: Scan the QR-Code

Step 2: Connect to the Panda Arm

Step 3: Calibrate the digital model

Source: Own Figure

Function: Panda Inside

Problem



Solution



Solution:

- Human hand detection
- recognizes human hands and forearms
- AR-Foundation API

Function: Panda Inside



Source: Own Figure

User study

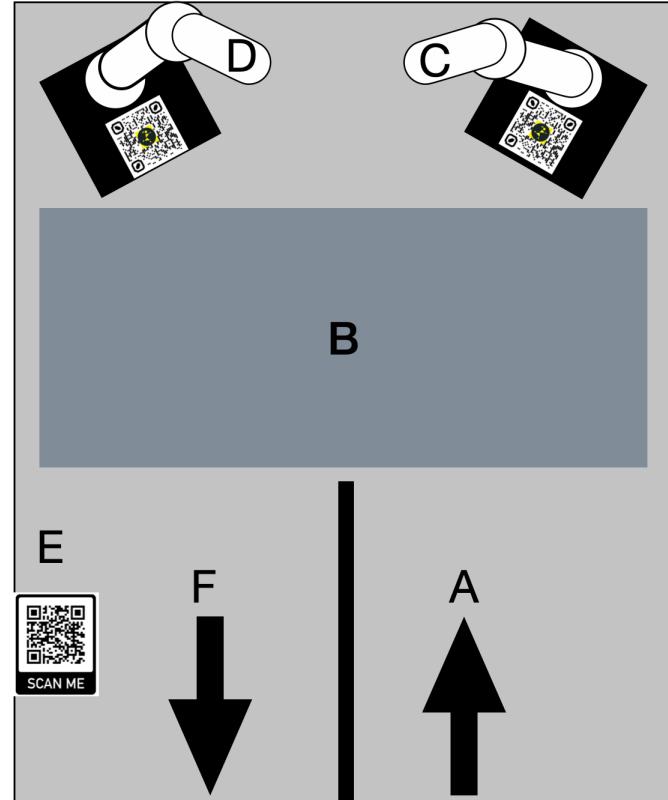
- 28 employees of Franka Emika to evaluate the Fear App
- 22 responded to the survey

Functions tested:

Garmi Demo (B)

Panda Demo (B)

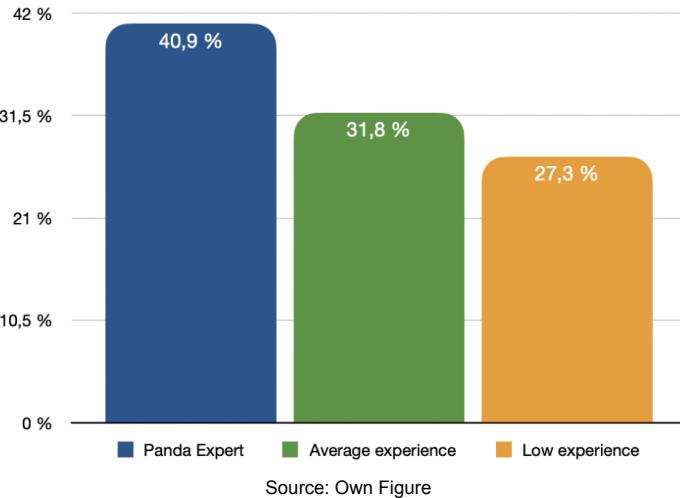
Panda Inside (C&D)



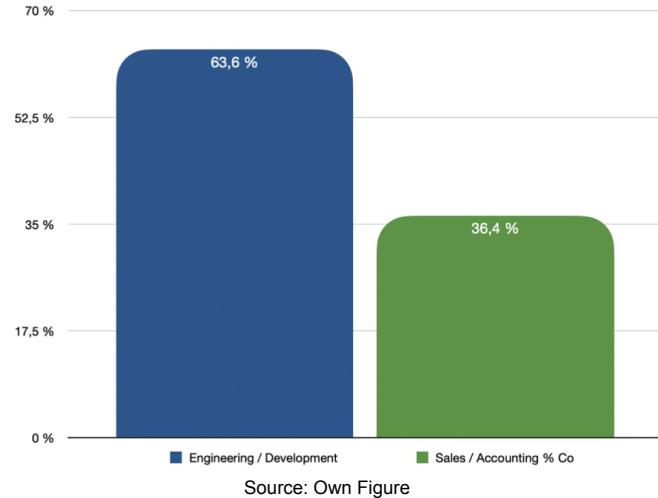
Source: Own Figure

Results

How would you rate your experience with the panda?

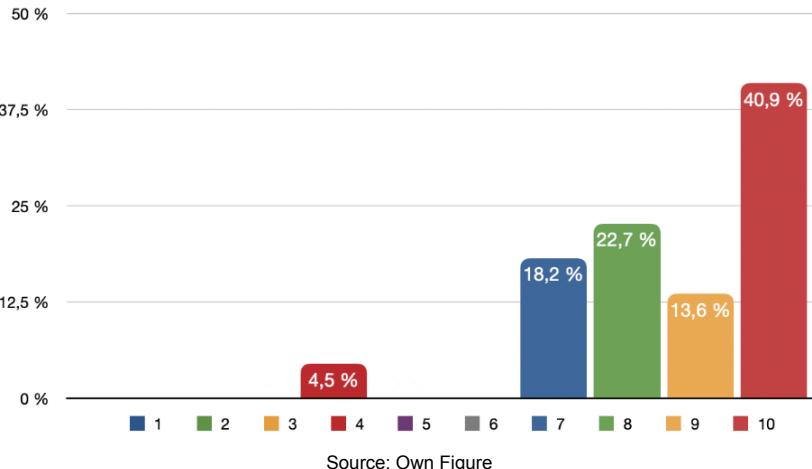


In which category of Franka Emika are you working?

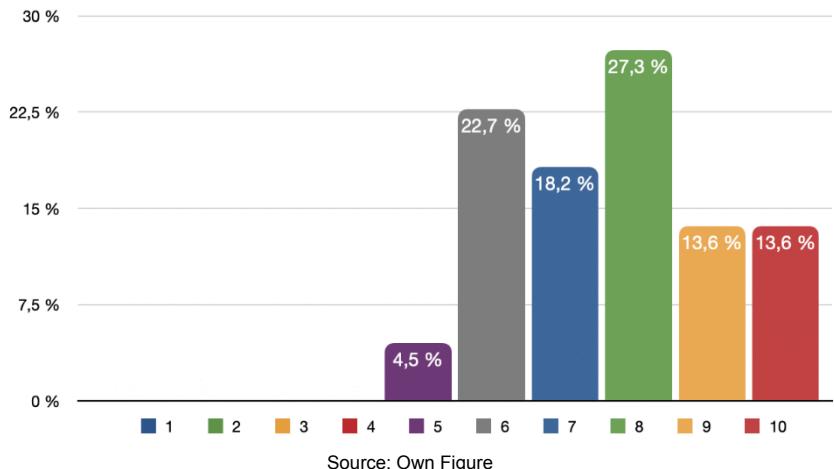


Results

How did you feel about the stability
of the models?
(1-10)

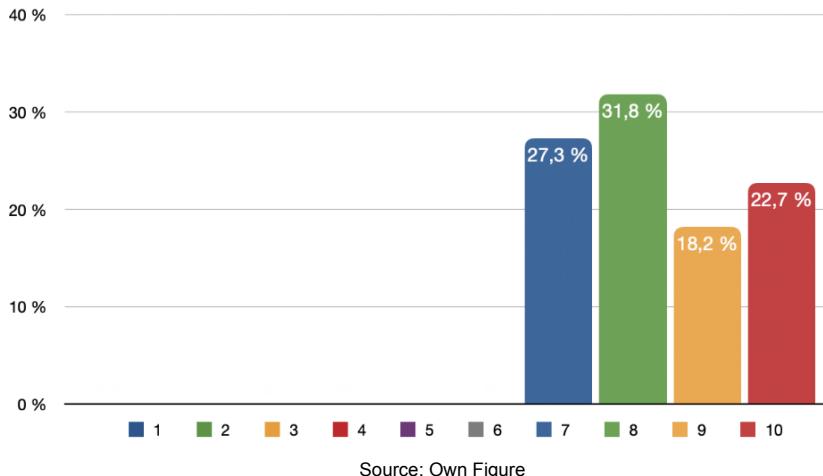


How much does the application
improve the
use of the panda? (1-10)

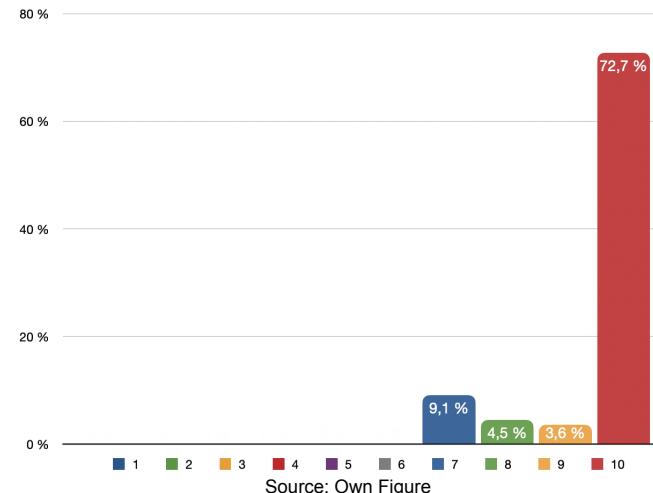


Results

How much potential and usability does an app like this have for customers and partners? (1-10)



Do you think that AR will play an important role in the future when working with robots and machines? (1-10)



Limitations of this thesis

Main feedback (User study):

- Cartesian motion fo the Panda demo
- Soft and hard joint limits
- Network connection

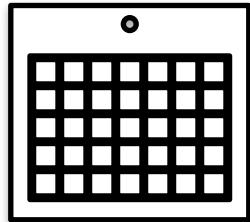
Other limitations

- Screen size
- No depth sensor



Source: Own Figure

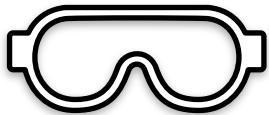
Conclusion



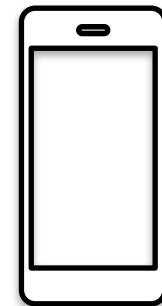
1. Pre-study to show the need of an AR-application
2. FEAR-App implemented in Unity with three main functions
3. User study to analyze the benefit

The results indicate that the Fear-App improves the human-machine communication.

Future Work



- New apple devices do have a depth sensor
- Easy to implement in Unity for the HoloLens 2
- Robot detection instead of QR-Code detection
- Support for multiple robots at the same time



Questions?

References

- Microsoft. (2020a, August 26). *Was ist Mixed Reality? - Mixed Reality*. Microsoft Docs.
<https://docs.microsoft.com/de-de/windows/mixed-reality/discover/mixed-reality>

Figures:

- Slide 3: <https://docs.microsoft.com/de-de/windows/mixed-reality/discover/images/mixed-reality-venn-diagram-300px.png>
- Slide 4: Kopf mit Gehirn icon Icon von [Icons8](https://icons8.de)