Recorded at time: 1739872657.937 world map Broadcaster: /initialpose Average rate: 91.799 Hz Most recent transform: 1739872654.902 ( 3.035 sec old) Buffer length: 1.939 sec odom Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Most recent transform: 0.000 (1739872657.937 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot navigate Broadcaster: /robot navigate Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Average rate: 10.642 Hz Average rate: 10.764 Hz Most recent transform: 0.000 (1739872657.937 sec old) Most recent transform: 1739872654.456 (3.481 sec old) Most recent transform: 1739872654.456 (3.481 sec old) Buffer length: 0.000 sec Buffer length: 1.503 sec Buffer length: 1.394 sec base\_footprint camera link laser Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 (1739872657.937 sec old) Most recent transform: 0.000 (1739872657.937 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth frame camera\_color\_frame Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 ( 1739872657.937 sec old) Most recent transform: 0.000 (1739872657.937 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth optical frame camera color optical frame

view frames Result