Recorded at time: 1740227279.776 world map Broadcaster: /amcl Average rate: 13.534 Hz Most recent transform: 1740227280.140 ( -0.364 sec old) Buffer length: 4.877 sec odom Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Most recent transform: 0.000 (1740227279.776 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot navigate Broadcaster: /robot navigate Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Average rate: 10.150 Hz Average rate: 10.150 Hz Most recent transform: 0.000 (1740227279.776 sec old) Most recent transform: 1740227279.732 (0.045 sec old) Most recent transform: 1740227279.732 (0.045 sec old) Buffer length: 0.000 sec Buffer length: 4.926 sec Buffer length: 4.926 sec base\_footprint camera link laser Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 (1740227279.776 sec old) Most recent transform: 0.000 (1740227279.776 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth frame camera\_color\_frame Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 ( 1740227279.776 sec old) Most recent transform: 0.000 (1740227279.776 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth optical frame camera color optical frame

view frames Result