Recorded at time: 1740664889.028 world map Broadcaster: /amcl Average rate: 13.873 Hz Most recent transform: 1740664889.396 (-0.368 sec old) Buffer length: 4.902 sec odom Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Most recent transform: 0.000 (1740664889.028 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot navigate Broadcaster: /robot navigate Broadcaster: /robot navigate Average rate:  $1000\overline{0}.000$  Hz Average rate:  $10.\overline{1}83 \text{ Hz}$ Average rate: 10.183 Hz Most recent transform: 0.000 (1740664889.028 sec old) Most recent transform: 1740664888.958 (0.070 sec old) Most recent transform: 1740664888.958 (0.070 sec old) Buffer length: 0.000 sec Buffer length: 4.910 sec Buffer length: 4.910 sec base\_footprint camera link laser Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 (1740664889.028 sec old) Most recent transform: 0.000 (1740664889.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth frame camera\_color\_frame Broadcaster: /camera/realsense2 camera manager Broadcaster: /camera/realsense2 camera manager Average rate:  $10000.\overline{0}00$  Hz Average rate:  $10000.\overline{0}00$  Hz Most recent transform: 0.000 ( 1740664889.028 sec old) Most recent transform: 0.000 (1740664889.028 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth optical frame camera color optical frame

view frames Result