

CCS C Compiler Manual

PCB / PCM / PCH



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Table of Contents

Overview	1
PCB, PCM and PCH Overview	1
Installation	1
Technical Support	2
Directories	2
File Formats	3
Invoking the Command Line Compiler	5
PCW Overview	7
Menu	8
Editor Tabs	8
Slide Out Windows	8
Editor	9
Debugging Windows	9
Status Bar	10
Output Messages	10
Program Syntax	11
Overall Structure	11
Comment	11
Trigraph Sequences	13
Multiple Project Files	13
Multiple Compilation Units	14
Full Example Program	14
Statements	17
Statements	17
if	18
while	19
do-while	19
for	20
switch	20
return	21
goto	21
label	22
break	22
continue	22
expr	23
;	23
stmt	23
Expressions	25
Constants	25
Identifiers	26
Operators	26
Operator Precedence	28
Data Definitions	29
Data Definitions	29
Type Specifiers	30

Table of Contents

Type Qualifiers	31
Enumerated Types	32
Structures and Unions	32
typedef	33
Non-RAM Data Definitions	34
Using Program Memory for Data	36
Named Registers	38
Function Definition	39
Function Definition	39
Overloaded Functions	40
Reference Parameters	40
Default Parameters	41
Variable Argument Lists	41
Functional Overview	43
I2C	43
ADC	44
Analog Comparator	45
CAN Bus	46
CCP	49
Code Profile	50
Configuration Memory	51
DAC	52
Data Eeprom	53
Data Signal Modulator	54
External Memory	56
General Purpose I/O	56
Internal LCD	57
Internal Oscillator	59
Interrupts	59
Low Voltage Detect	61
PMP/EPMP	62
Power PWM	63
Program Eeprom	64
PSP	66
QE1	67
RS232 I/O	68
RTOS	71
SPI	73
Timer0	74
Timer1	75
Timer2	76
Timer3	77
Timer4	77
Timer5	77
TimerA	78
TimerB	79
USB	80
Voltage Reference	83

CCS C Compiler

WDT or Watch Dog Timer	84
interrupt_enabled()	85
Stream I/O	86
PreProcessor	89
PRE-PROCESSOR DIRECTORY	89
__address__	89
#asm #endasm #asm asis	91
#bit	93
__buildcount__	94
#build	94
#byte	95
#case	96
date	97
#define	97
definedinc	98
#device	99
device	102
#if expr #else #elif #endif	103
#error	104
#export (options)	104
__file__	106
__filename__	106
#fill_rom	107
#fuses	107
#hexcomment	109
#id	109
#ifdef #ifndef #else #elif #endif	110
#ignore_warnings	111
#import (options)	111
#include	113
#inline	114
#int_xxxx	114
#INT_DEFAULT	118
#int_global	119
__line__	120
#list	120
#line	121
#locate	121
#module	122
#nolist	123
#ocs	123
#opt	124
#org	125
#pin_select	127
__pcb__	129
__pcm__	130
__pch__	130
#pragma	130

Table of Contents

#priority	131
#profile	132
#reserve	133
#rom	133
#separate	134
#serialize	135
#task.....	137
__time__	138
#type	139
#undef	140
_unicode.....	141
#use capture	142
#use delay.....	143
#use dynamic_memory	145
#use fast_io.....	145
#use fixed_io	146
#use i2c.....	147
#use profile()	148
#use pwm()	149
#use rs232	151
#use rtos	157
#use spi.....	159
#use standard_io.....	161
#use timer	161
#use touchpad.....	163
#warning.....	164
#word	165
#zero_ram	166
Built-in Functions	167
BUILT-IN FUNCTIONS	167
abs()	167
sin() cos() tan() asin() acos() atan() sinh() cosh() tanh() atan2()	168
adc_done()	169
adc_read().....	170
adc_status()	171
adc_write()	172
assert()	172
atof	173
atof().....	174
pin_select().....	174
atoi() atol() atoi32()	176
at_clear_interrupts()	176
at_disable_interrupts()	178
at_enable_interrupts()	179
at_get_capture()	180
at_get_missing_pulse_delay()	180
at_get_period()	181
at_get_phase_counter()	182

CCS C Compiler

at_get_resolution()	182
at_get_set_point()	183
at_get_set_point_error()	184
at_get_status()	185
at_interrupt_active()	185
at_set_compare_time()	187
at_set_missing_pulse_delay()	187
at_set_resolution()	188
at_set_set_point()	189
at_setup_cc()	190
bit_clear()	191
bit_set()	191
bit_test()	192
brownout_enable()	193
bsearch()	193
calloc()	194
ceil()	195
clc1_setup_gate() clc2_setup_gate() clc3_setup_gate() clc4_setup_gate()	196
clear_interrupt()	197
clear_pwm1_interrupt() clear_pwm2_interrupt() clear_pwm3_interrupt() clear_pwm4_interrupt() clear_pwm5_interrupt() clear_pwm6_interrupt()	197
cog_status()	198
cog_restart()	199
crc_calc() crc_calc8() crc_calc16()	199
crc_init(mode)	200
cwg_status()	201
cwg_restart()	201
dac_write()	202
delay_cycles()	203
delay_ms()	203
delay_us()	204
disable_interrupts()	205
disable_pwm1_interrupt() disable_pwm2_interrupt() disable_pwm3_interrupt() disable_pwm4_interrupt() disable_pwm5_interrupt() disable_pwm6_interrupt()	206
div() ldiv()	207
enable_interrupts()	208
enable_pwm1_interrupt() enable_pwm2_interrupt() enable_pwm3_interrupt() enable_pwm4_interrupt() enable_pwm5_interrupt() enable_pwm6_interrupt()	209
erase_eeprom()	210
erase_program_eeprom()	211
exp()	211
ext_int_edge()	212
fabs()	213
floor()	213
fmod()	214
free()	215
frexp()	215
scanf()	216

Table of Contents

get_capture()	219
get_capture_event()	220
get_capture_time()	220
get_capture32()	221
get_hspwm_capture()	222
get_nco_accumulator()	223
get_nco_inc_value()	223
get_ticks()	224
get_timerA()	224
get_timerB()	225
get_timerx()	225
get_tris_x()	226
getc() getch() getchar() fgetc()	227
getenv()	228
gets() fgets()	233
goto_address()	234
high_speed_adc_done()	235
i2c_init()	235
i2c_isr_state()	236
i2c_poll()	237
i2c_read()	238
i2c_slaveaddr()	239
i2c_speed()	239
i2c_start()	240
i2c_stop()	241
i2c_write()	242
input()	243
input_change_x()	244
input_state()	244
input_x()	245
interrupt_active()	246
isalnum(char) isalpha(char) iscntrl(x) isdigit(char) isgraph(x) islower(char)	
isspace(char) isupper(char) isxdigit(char) isprint(x) ispunct(x)	247
isamong()	248
itoa()	249
jump_to_isr()	249
kbhit()	250
label_address()	251
labs()	252
lcd_contrast()	252
lcd_load()	253
lcd_symbol()	253
ldexp()	254
log()	255
log10()	256
longjmp()	256
make8()	257
make16()	258

CCS C Compiler

make32()	258
malloc()	259
memcpy() memmove()	260
memset()	261
modf()	261
_mul()	262
nargs()	263
offsetof() offsetofbit()	264
output_x()	265
output_bit()	265
output_drive()	267
output_float()	267
output_high()	268
output_low()	269
output_toggle()	270
perror()	270
pid_busy()	271
pid_get_result()	271
pid_read()	273
pid_write()	274
pll_locked()	275
port_x_pullups()	275
pow() pwr()	276
printf() fprintf()	277
profileout()	279
psmc_blanking()	280
psmc_deadband()	282
psmc_duty()	283
psmc_freq_adjust()	284
psmc_modulation()	285
psmc_pins()	286
psmc_shutdown()	287
psmc_sync()	289
psp_output_full() psp_input_full() psp_overflow()	290
putc() putchar() fputc()	290
putc_send(); fputc_send();	291
puts() fputs()	293
pwm_off()	293
pwm_on()	294
pwm_set_duty()	295
pwm_set_duty_percent	295
pwm_set_frequency	296
pwm1_interrupt_active() pwm2_interrupt_active() pwm3_interrupt_active() pwm4_interrupt_active() pwm5_interrupt_active() pwm6_interrupt_active()	297
qei_get_count()	298
qei_set_count()	298
qei_status()	299
qsort()	299

Table of Contents

rand().....	300
rcv_buffer_bytes()	301
rcv_buffer_full()	302
read_adc().....	302
read_bank().....	304
read_calibration()	305
read_configuration_memory()	305
read_eeprom()	306
read_extended_ram().....	307
read_program_memory() read_external_memory()	307
read_program_eeprom()	308
read_rom_memory().....	309
read_sd_adc()	309
realloc()	310
release_io()	311
reset_cpu()	312
restart_cause()	312
restart_wdt()	313
rotate_left()	314
rotate_right().....	315
rtc_alarm_read().....	315
rtc_alarm_write()	316
rtc_read().....	317
rtc_write()	317
rtos_await()	318
rtos_disable()	319
rtos_enable()	319
rtos_msg_poll()	320
rtos_overrun().....	320
rtos_run().....	321
rtos_signal()	322
rtos_stats()	322
rtos_terminate().....	323
rtos_wait()	324
rtos_yield()	325
set_adc_channel().....	325
set_adc_trigger().....	326
set_analog_pins().....	327
scanf()	328
set_cog_blanking().....	331
set_cog_dead_band()	332
set_cog_phase()	333
set_compare_time()	333
set_dedicated_adc_channel()	334
set_input_level_x()	335
set_nco_inc_value()	336
set_power_pwm_override().....	338
set_power_pwm_duty()	338

CCS C Compiler

set_pwm1_duty()	set_pwm2_duty()	set_pwm3_duty()	set_pwm4_duty()
set_pwm5_duty()	339		
set_pwm1_offset()	set_pwm2_offset()	set_pwm3_offset()	set_pwm4_offset()
set_pwm5_offset()	set_pwm6_offset()		340
set_pwm1_period()	set_pwm2_period()	set_pwm3_period()	
set_pwm4_period()	set_pwm5_period()	set_pwm6_period()	341
set_pwm1_phase()	set_pwm2_phase()	set_pwm3_phase()	
set_pwm4_phase()	set_pwm5_phase()	set_pwm6_phase()	342
set_open_drain_x()			343
set_rtcc()	set_timer0()	set_timer1()	set_timer2()
set_timer4()	set_timer5()		344
set_ticks()			345
setup_sd_adc_calibration()			346
set_sd_adc_channel()			346
set_timerA()			347
set_timerB()			348
set_tris_x()			348
set_uart_speed()			349
setjmp()			350
setup_adc(mode)			351
setup_adc_ports()			352
setup_adc_reference()			353
setup_at()			354
setup_ccp1()	setup_ccp2()	setup_ccp3()	setup_ccp4()
setup_ccp6()	355		
setup_clc1()	setup_clc2()	setup_clc3()	setup_clc4()
			357
setup_comparator()			358
setup_counters()			359
setup_cog()			360
setup_crc()			361
setup_cwg()			362
setup_dac()			363
setup_external_memory()			364
setup_lcd()			364
setup_low_volt_detect()			365
setup_nco()			366
setup_opamp1()	setup_opamp2()	setup_opamp3()	
			367
setup_pid()			368
setup_pmp(option,address_mask)			369
setup_psmc()			370
setup_power_pwm()			372
setup_power_pwm_pins()			374
setup_psp(option,address_mask)			374
setup_pwm1()	setup_pwm2()	setup_pwm3()	setup_pwm4()
			375
setup_qei()			376
setup_rtc()			377
setup_rtc_alarm()			378
setup_smtx()			378

Table of Contents

setup_spi() setup_spi2()	379
setup_timer_A()	380
setup_timer_B()	380
setup_timer_0()	381
setup_timer_1()	382
setup_timer_2()	383
setup_timer_3()	384
setup_timer_4()	384
setup_timer_5()	385
setup_uart()	386
setup_vref()	387
setup_wdt()	387
setup_zdc()	388
shift_left()	389
shift_right()	389
sleep()	390
smtx_read()	392
smtx_reset_timer()	393
smtx_start()	393
smtx_status()	394
smtx_stop()	394
smtx_write()	395
smtx_update()	395
spi_data_is_in() spi_data_is_in2()	396
spi_init()	397
spi_prewrite(data);	397
spi_read() spi_read2()	398
spi_read2_16() spi_read3_16() spi_read4_16()	399
spi_speed	400
spi_write() spi_write2()	400
spi_xfer()	401
SPI_XFER_IN()	402
sprintf()	403
sqrt()	403
srand()	404
STANDARD STRING FUNCTIONS() memchr() memcmp() strcat()	
strchr() strcmp() strcoll() strcspn() strerror() stricmp() strlen() strlwr()	
strncat() strncmp() strncpy() strpbrk() strrchr() strspn() strstr() strxfrm()	405
strcpy() strcpy()	407
strtod()	407
strtok()	408
strtol()	409
strtoul()	410
swap()	411
tolower() toupper()	412
touchpad_getc()	413
touchpad_hit()	414
touchpad_state()	414

CCS C Compiler

tx_buffer_available()	416
tx_buffer_bytes()	417
tx_buffer_full()	417
va_arg()	418
va_end()	419
va_start	420
write_bank()	421
write_configuration_memory()	421
write_eeprom()	422
write_external_memory()	423
write_extended_ram()	424
write_program_eeprom()	425
write_program_memory()	425
zdc_status()	427
Standard C Include Files	429
errno.h	429
float.h	429
limits.h	430
locale.h	431
setjmp.h	431
stddef.h	431
stdio.h	432
stdlib.h	432
Software License Agreement	433

OVERVIEW

PCB, PCM and PCH Overview

The PCB, PCM, and PCH are separate compilers. PCB is for 12-bit opcodes, PCM is for 14-bit opcodes, and PCH is for 16-bit opcode PIC® microcontrollers. Due to many similarities, all three compilers are covered in this reference manual. Features and limitations that apply to only specific microcontrollers are indicated within. These compilers are specifically designed to meet the unique needs of the PIC® microcontroller. This allows developers to quickly design applications software in a more readable, high-level language.

IDE Compilers (PCW, PCWH and PCWHD) have the exclusive C Aware integrated development environment for compiling, analyzing and debugging in real-time. Other features and integrated tools can be viewed in the help file.

When compared to a more traditional C compiler, PCB, PCM, and PCH have some limitations. As an example of the limitations, function recursion is not allowed. This is due to the fact that the PIC® has no stack to push variables onto, and also because of the way the compilers optimize the code. The compilers can efficiently implement normal C constructs, input/output operations, and bit twiddling operations. All normal C data types are supported along with pointers to constant arrays, fixed point decimal, and arrays of bits.

Installation

1. Insert the CD ROM, select each of the programs you wish to install and follow the on-screen instructions.
2. If the CD does not auto start run the setup program in the root directory.
3. For help answering the version questions see the "Directories" Help topic.
4. Key Questions that may come up:

- Keep Settings- Unless you are having trouble select this
- Link Compiler Extensions- If you select this the file extensions like .c will start the compiler IDE when you double click on files with that extension. .hex files start the CCSLOAD program. This selection can be change in the IDE.
- Install MP LAB Plug In- If you plan to use MPLAB and you don't select this you will need to download and manually install the Plug-In.
- Install ICD2, ICD3...drivers-select if you use these microchip ICD units.
- Delete Demo Files- Always a good idea
- Install WIN8 APP- Allows you to start the IDE from the WIN8 Start Menu.

Technical Support

Compiler, software, and driver updates are available to download at:
<http://www.ccsinfo.com/download>

Compilers come with 30 or 60 days of download rights with the initial purchase. One year maintenance plans may be purchased for access to updates as released.

The intent of new releases is to provide up-to-date support with greater ease of use and minimal, if any, transition difficulty.

To ensure any problem that may occur is corrected quickly and diligently, it is recommended to send an email to: support@ccsinfo.com or use the Technical Support Wizard in PCW. Include the version of the compiler, an outline of the problem and attach any files with the email request. CCS strives to answer technical support timely and thoroughly.

Technical Support is available by phone during business hours for urgent needs or if email responses are not adequate. Please call 262-522-6500 x32.

Directories

The compiler will search the following directories for Include files.

- Directories listed on the command line
- Directories specified in the .CCSPJT file

- The same directory as the source.directories in the ccsc.ini file

By default, the compiler files are put in C:\Program Files\PICC and the example programs are in \PICC\EXAMPLES. The include files are in PICC\drivers. The device header files are in PICC\devices.

The compiler itself is a DLL file. The DLL files are in a DLL directory by default in \PICC\DLL.

It is sometimes helpful to maintain multiple compiler versions. For example, a project was tested with a specific version, but newer projects use a newer version. When installing the compiler you are prompted for what version to keep on the PC. IDE users can change versions using Help>about and clicking "other versions." Command Line users use start>all programs>PIC-C>compiler version.

Two directories are used outside the PICC tree. Both can be reached with start>all programs>PIC-C.

- 1.) A project directory as a default location for your projects. By default put in "My Documents." This is a good place for VISTA and up.
- 2.) User configuration settings and PCWH loaded files are kept in %APPDATA%\PICC

File Formats

.c	This is the source file containing user C source code.
.h	These are standard or custom header files used to define pins, register, register bits, functions and preprocessor directives.
.pj1	This is the older pre- Version 5 project file which contains information related to the project.
.ccspjt	This is the project file which contains information related to the project.

	This is the listing file which shows each C source line and the associated assembly code generated for that line.
	The elements in the .LST file may be selected in PCW under Options>Project>Output Files
.lst	CCS Basic Standard assembly instructions
	with Opcodes Includes the HEX opcode for each instruction
	Old Standard
	Symbolic Shows variable names instead of addresses
.sym	This is the symbol map which shows each register location and what program variables are stored in each location.
.sta	The statistics file shows the RAM, ROM, and STACK usage. It provides information on the source codes structural and textual complexities using Halstead and McCabe metrics.
.tre	The tree file shows the call tree. It details each function and what functions it calls along with the ROM and RAM usage for each function.
.hex	The compiler generates standard HEX files that are compatible with all programmers.
	The compiler can output 8-bit hex, 16-bit hex, and binary files.
.cof	This is a binary containing machine code and debugging information.
	The debug files may be output as Microchip .COD file for MPLAB 1-5, Advanced Transdata .MAP file, expanded .COD file for CCS debugging or MPLAB 6 and up .xx .COF file. All file formats and extensions may be selected via Options File Associations option in Windows IDE.
.cod	This is a binary file containing debug information.
.rtf	The output of the Documentation Generator is exported in a Rich Text File format which can be viewed using the RTF editor or Wordpad.
.rvf	The Rich View Format is used by the RTF Editor within the IDE to view the Rich Text File.
.dgr	The .DGR file is the output of the flowchart maker.
.esym .xsym	These files are generated for the IDE users. The file contains Identifiers and Comment information. This data can be used for automatic documentation generation and for the IDE helpers.
.o	Relocatable object file

<code>.osym</code>	This file is generated when the compiler is set to export a relocatable object file. This file is a <code>.sym</code> file for just the one unit.
<code>.err</code>	Compiler error file
<code>.ccsload</code>	used to link Windows 8 apps to CCSLoad
<code>.ccssio.w</code>	used to link Windows 8 apps to Serial Port Monitor

Invoking the Command Line Compiler

The command line compiler is invoked with the following command:

```
CCSC [options] [cfilename]
```

Valid options:

+FB	Select PCB (12 bit)	-D	Do not create debug file
+FM	Select PCM (14 bit)	+DS	Standard .COD format debug file
+FH	Select PCH (PIC18XXX)	+DM	.MAP format debug file
+Yx	Optimization level x (0-9)	+DC	Expanded .COD format debug file
		+DF	Enables the output of an COFF debug file.
+FS	Select SXC (SX)	+EO	Old error file format
+ES	Standard error file	-T	Do not generate a tree file
+T	Create call tree (.TRE)	-A	Do not create stats file (.STA)
+A	Create stats file (.STA)	-EW	Suppress warnings (use with +EA)
+EW	Show warning messages	-E	Only show first error
+EA	Show all error messages and all warnings	+EX	Error/warning message format uses GCC's "brief format" (compatible with GCC editor environments)

The xxx in the following are optional. If included it sets the file extension:

+LNxxx	Normal list file	+O8xxx	8-bit Intel HEX output file
+LSxxx	MPASM format list file	+OWxxx	16-bit Intel HEX output file
+LOxxx	Old MPASM list file	+OBxxx	Binary output file
+LYxxx	Symbolic list file	-O	Do not create object file
-L	Do not create list file		
+P	Keep compile status window up after compile		
+Pxx	Keep status window up for xx seconds after compile		

+PN	Keep status window up only if there are no errors
+PE	Keep status window up only if there are errors
+Z	Keep scratch files on disk after compile
+DF	COFF Debug file
I+= "..."	Same as I= "...". Except the path list is appended to the current list
I= "..."	Set include directory search path, for example: I="c:\picc\examples;c:\picc\myincludes" If no I= appears on the command line the .PJT file will be used to supply the include file paths.
-P	Close compile window after compile is complete
+M	Generate a symbol file (.SYM)
-M	Do not create symbol file
+J	Create a project file (.PJT)
-J	Do not create PJT file
+ICD	Compile for use with an ICD
#xxx="yyy"	Set a global #define for id xxx with a value of yyy, example: #debug="true"
+Gxxx="yyy"	Same as #xxx="yyy"
+?	Brings up a help file
-?	Same as +?
+STDOUT	Outputs errors to STDOUT (for use with third party editors)
+SETUP	Install CCSC into MPLAB (no compile is done)
sourceline=	Allows a source line to be injected at the start of the source file. Example: CCSC +FM myfile.c sourceline="#include <16F887.h>"
+V	Show compiler version (no compile is done)
+Q	Show all valid devices in database (no compile is done)

A / character may be used in place of a + character. The default options are as follows:
+FM +ES +J +DC +Y9 -T -A +M +LNlst +O8hex -P -Z

If @filename appears on the CCSC command line, command line options will be read from the specified file. Parameters may appear on multiple lines in the file.

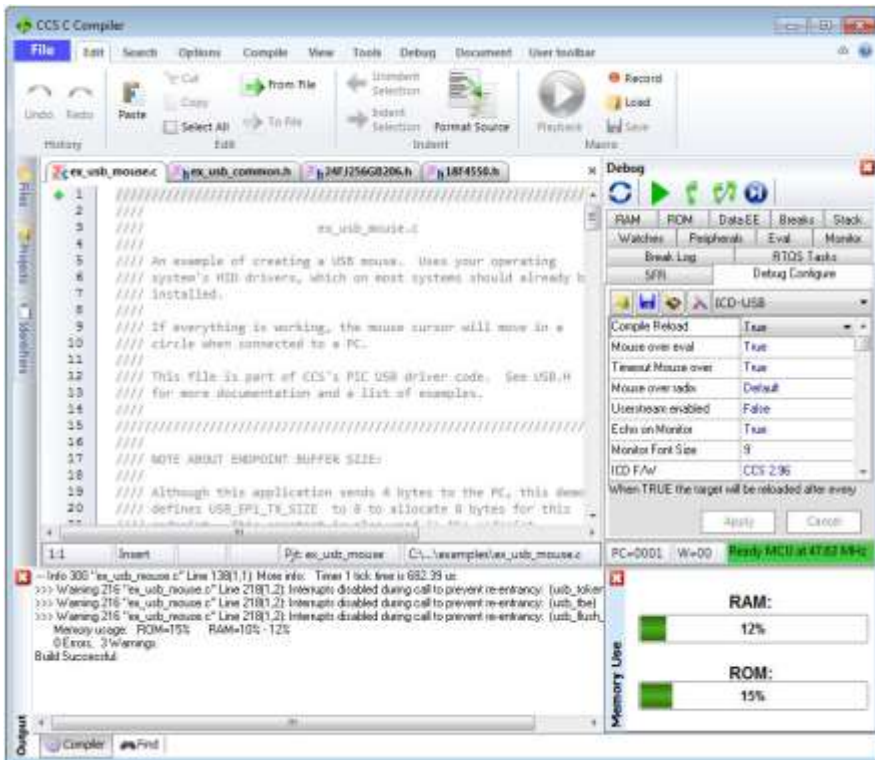
If the file CCSC.INI exists in the same directory as CCSC.EXE, then command line parameters are read from that file before they are processed on the command line.

Examples:

```
CCSC +FM C:\PICSTUFF\TEST.C
CCSC +FM +P +T TEST.C
```

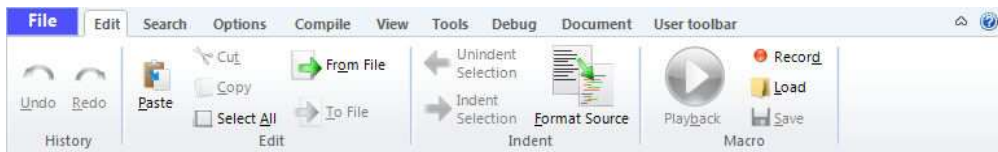
The PCW IDE provides the user an easy to use editor and environment for developing microcontroller applications. The IDE comprises of many components, which are summarized below. For more information and details, use the Help>PCW in the compiler..

Many of these windows can be re-arranged and docked into different positions.



Menu

All of the IDE's functions are on the main menu. The main menu is divided into separate sections, click on a section title ('Edit', 'Search', etc) to change the section. Double clicking on the section, or clicking on the chevron on the right, will cause the menu to minimize and take less space.



Editor Tabs

All of the open files are listed here. The active file, which is the file currently being edited, is given a different highlight than the other files. Clicking on the X on the right closes the active file. Right clicking on a tab gives a menu of useful actions for that file.



Slide Out Windows

'Files' shows all the active files in the current project. 'Projects' shows all the recent projects worked on. 'Identifiers' shows all the variables, definitions, prototypes and identifiers in your current project.

Editor

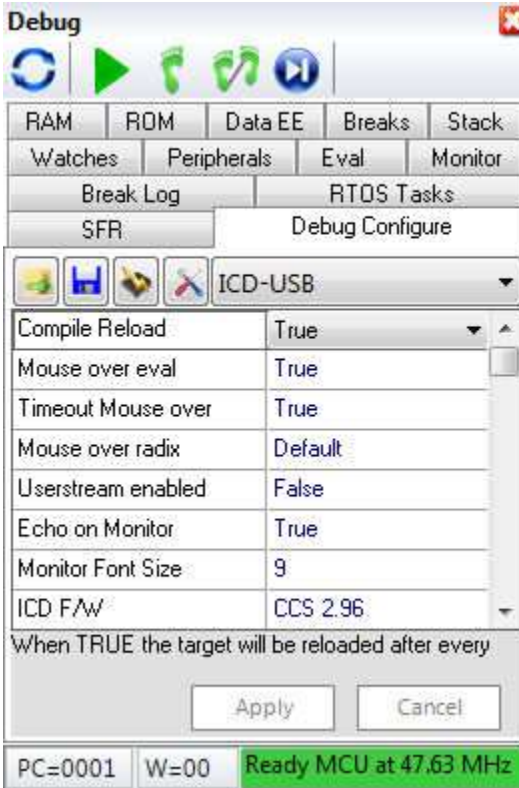
The editor is the main work area of the IDE and the place where the user enters and edits source code. Right clicking in this area gives a menu of useful actions for the code being edited.

```

100  #if defined(USB_HW_CCS_PIC18F4550)
101      #include <18F4550.h>
102      #fuses HSPLL,NOWDT,NOPROTECT,NOLVP,NODEBUG,USBDIV,PLL5,CPUDIV1,VREGEN
103      #use delay(clock=48000000)
104
105      //leds ordered from bottom to top
106      #DEFINE LED1 PIN_A5 //green

```

Debugging Windows



Debugger control is done in the debugging windows. These windows allow you set breakpoints, single step, watch variables and more.

Status Bar

The status bar gives the user helpful information like the cursor position, project open and file being edited.



Output Messages

Output messages are displayed here. This includes messages from the compiler during a build, messages from the programmer tool during programming or the results from find and searching.



PROGRAM SYNTAX

Overall Structure

A program is made up of the following four elements in a file:

Comment

Pre-Processor Directive

Data Definition

Function Definition

Statements

Expressions

Every C program must contain a main function which is the starting point of the program execution. The program can be split into multiple functions according to their purpose and the functions could be called from main or the sub-functions. In a large project functions can also be placed in different C files or header files that can be included in the main C file to group the related functions by their category. CCS C also requires to include the appropriate device file using #include directive to include the device specific functionality. There are also some preprocessor directives like #fuses to specify the fuses for the chip and #use delay to specify the clock speed. The functions contain the data declarations, definitions, statements and expressions. The compiler also provides a large number of standard C libraries as well as other device drivers that can be included and used in the programs. CCS also provides a large number of built-in functions to access the various peripherals included in the PIC microcontroller.

Comment

Comments – Standard Comments

A comment may appear anywhere within a file except within a quoted string. Characters between /* and */ are ignored. Characters after a // up to the end of the line are ignored.

Comments for Documentation Generator

The compiler recognizes comments in the source code based on certain markups. The compiler recognizes these special types of comments that can be later exported for use in the documentation generator. The documentation generator utility uses a user selectable

template to export these comments and create a formatted output document in Rich Text File Format. This utility is only available in the IDE version of the compiler. The source code markups are as follows.

Global Comments

These are named comments that appear at the top of your source code. The comment names are case sensitive and they must match the case used in the documentation template.

For example:

```
/**PURPOSE This program implements a Bootloader.  
/**AUTHOR John Doe
```

A `/**` followed by an `*` will tell the compiler that the keyword which follows it will be the named comment. The actual comment that follows it will be exported as a paragraph to the documentation generator.

Multiple line comments can be specified by adding a `:` after the `*`, so the compiler will not concatenate the comments that follow. For example:

```
/**:CHANGES  
    05/16/06  Added PWM loop  
    05/27.06  Fixed Flashing problem  
*/
```

Variable Comments

A variable comment is a comment that appears immediately after a variable declaration.

For example:

```
int seconds; // Number of seconds since last entry  
long day,    // Current day of the month, /* Current Month */  
long year;   // Year
```

Function Comments

A function comment is a comment that appears just before a function declaration. For example:

```
// The following function initializes outputs  
void function_foo()  
{  
    init_outputs();  
}
```

Function Named Comments

The named comments can be used for functions in a similar manner to the Global Comments. These comments appear before the function, and the names are exported as-is to the documentation generator.

For example:

```
/**PURPOSE This function displays data in BCD format
void display_BCD( byte n)
{
    display_routine();
}
```

Trigraph Sequences

The compiler accepts three character sequences instead of some special characters not available on all keyboards as follows:

Sequence	Same as
??=	#
??([
??/	\
??)]
??'	^
??<	{
??!	
??>	}
??-	~

Multiple Project Files

When there are multiple files in a project they can all be included using the #include in the main file or the sub-files to use the automatic linker included in the compiler. All the header files, standard libraries and driver files can be included using this method to automatically link them.

For example: if you have main.c, x.c, x.h, y.c,y.h and z.c and z.h files in your project, you can say in:

main.c	#include <device header file>
--------	-------------------------------

```
#include<x.c>
#include<y.c>
#include <z.c>
```

x.c	#include <x.h>
y.c	#include <y.h>
z.c	#include <z.h>

In this example there are 8 files and one compilation unit. Main.c is the only file compiled.

Note that the #module directive can be used in any include file to limit the visibility of the symbol in that file.

To separately compile your files see the section "multiple compilation units".

Multiple Compilation Units

Multiple Compilation Units are only supported in the IDE compilers, PCW, PCWH, PCHWD and PCDIDE. When using multiple compilation units, care must be given that pre-processor commands that control the compilation are compatible across all units. It is recommended that directives such as #FUSES, #USE and the device header file all put in an include file included by all units. When a unit is compiled it will output a relocatable object file (*.o) and symbol file (*.osym).

There are several ways to accomplish this with the CCS C Compiler. All of these methods and example projects are included in the MCU.zip in the examples directory of the compiler.

Full Example Program

Here is a sample program with explanation using CCS C to read adc samples over rs232:

Program Syntax

```
/////////////////////////////////////////////////////////////////
/////////////////////////////////////////////////////////////////
//////                                EX_ADMC.C                                ////
//////                                ////
////// This program displays the min and max of 30 A/D samples over the RS-232 interface. The process is repeated forever.
////// If required configure the CCS prototype card as follows:
//////     Insert jumper from output of POT to pin A5
//////     Use a 10K POT to vary the voltage.
//////
////// Jumpers:
//////     PCM,PCH    pin C7 to RS232 RX, pin C6 to RS232 TX
//////     PCD        none
//////
////// This example will work with the PCM, PCH, and PCD compilers.
////// The following conditional compilation lines are used to include a valid device for each compiler. Change the device, clock and RS232 pins for your hardware if needed.
/////////////////////////////////////////////////////////////////
////// (C) Copyright 1996,2007 Custom Computer Services
////// This source code may only be used by licensed users of the CCS C compiler. This source code may only be distributed to other licensed users of the CCS C compiler. No other use, reproduction or distribution is permitted without written permission. Derivative programs created using this software in object code form are not restricted in any way.
/////////////////////////////////////////////////////////////////
#if defined(__PCM__) // Preprocessor directive that chooses
// the compiler
#include <16F877.h> // Preprocessor directive that selects
// the chip
#fuses HS,NOWDT,NOPROTECT,NOLVP // Preprocessor directive that defines
// the chip fuses
#use delay(clock=20000000) // Preprocessor directive that specifies clock speed
//
#use rs232(baud=9600, xmit=PIN_C6, rcv=PIN_C7) // Preprocessor directive that includes
// RS232 libraries

#elif defined(__PCH__)
#include <18F452.h>
#fuses HS,NOWDT,NOPROTECT,NOLVP
#use delay(clock=20000000)
#use rs232(baud=9600, xmit=PIN_C6, rcv=PIN_C7)
#fuses HS,NOWDT
```

CCS C Compiler

```
#device ADC=8
#use delay(clock=20000000)
#use rs232(baud=9600, UART1A)
#endif

void main() {
    unsigned int8 i, value, min, max;
    printf("Sampling:"); // Printf function included
in RS232 // library

    setup_adc_ports(AN0);
    #endif

    setup_adc(ADC_CLOCK_INTERNAL); // Built-in A/D setup
function
    set_adc_channel(0); // Built-in A/D setup
function
    do {
        min=255;
        max=0;
        for(i=0; i<=30; ++i) {
            delay_ms(100); // Built-in delay function
            value = read_adc(); // Built-in A/D read function
            if(value<min)
                min=value;
            if(value>max)
                max=value;
        }

        printf("\r\nMin: %2X Max: %2X\n\r",min,max);
    } while (TRUE);
}
```

STATEMENTS

Statements

STATEMENT	Example
<u>if</u> (expr) stmt; [<u>else</u> stmt;]	if (x==25) x=0; else x=x+1;
<u>while</u> (expr) stmt;	while (get_rtcc()!=0) putc('\n');
<u>do</u> stmt <u>while</u> (expr);	do { putc(c=getc()); } while (c!=0);
<u>for</u> (expr1;expr2;expr3) stmt;	for (i=1;i<=10;++i) printf("%u\r\n",i);
<u>switch</u> (expr) { <u>case</u> cexpr: stmt; //one or more case [default:stmt] ... }	switch (cmd) { case 0: printf("cmd 0");break; case 1: printf("cmd 1");break; default: printf("bad cmd");break; }
<u>return</u> [expr];	return (5);
<u>goto</u> label;	goto loop;
<u>label</u> : stmt;	loop: i++;
<u>break</u> ;	break;
<u>continue</u> ;	continue;
<u>expr</u> ;	i=1;
<u>i</u> ;	;
{ <u>[stmt]</u> }	{a=1;

	b=1; }
Zero or more declaration;	int i;

Note: Items in [] are optional

if

if-else

The if-else statement is used to make decisions.

The syntax is:

```
if (expr)
    stmt-1;
[else
    stmt-2;]
```

The expression is evaluated; if it is true stmt-1 is done. If it is false then stmt-2 is done.

else-if

This is used to make multi-way decisions.

The syntax is:

```
if (expr)
    stmt;
[else if (expr)
    stmt;]
...
[else
    stmt;]
```

The expressions are evaluated in order; if any expression is true, the statement associated with it is executed and it terminates the chain. If none of the conditions are satisfied the last else part is executed.

Example:

```
if (x==25)
    x=1;
else
    x=x+1;
```

Also See: [Statements](#)

while

While is used as a loop/iteration statement.

The syntax is:

```
while (expr)
    statement
```

The expression is evaluated and the statement is executed until it becomes false in which case the execution continues after the statement.

Example:

```
while (get_rtcc() !=0)
    putc('n');
```

Also See: [Statements](#)

do-while

do-while: Differs from *while* and *for* loop in that the termination condition is checked at the bottom of the loop rather than at the top and so the body of the loop is always executed at least once. The syntax is:

```
do
    statement
while (expr);
```

The statement is executed; the expr is evaluated. If true, the same is repeated and when it becomes false the loop terminates.

Also See: [Statements](#) , [While](#)

for

For is also used as a loop/iteration statement.

The syntax is:

```
for (expr1;expr2;expr3)  
    statement
```

The expressions are loop control statements. expr1 is the initialization, expr2 is the termination check and expr3 is re-initialization. Any of them can be omitted.

Example:

```
for (i=1;i<=10;++i)  
    printf("%u\r\n",i);
```

Also See: [Statements](#)

switch

Switch is also a special multi-way decision maker.

The syntax is

```
switch (expr) {  
    case const1: stmt sequence;  
                break;  
    ...  
    [default:stmt]  
}
```

This tests whether the expression matches one of the constant values and branches accordingly.

If none of the cases are satisfied the default case is executed. The break causes an immediate exit, otherwise control falls through to the next case.

Example:

```
switch (cmd) {  
    case 0:printf("cmd 0");  
           break;  
    case 1:printf("cmd 1");  
           break;
```



```
default:printf("bad cmd");  
        break; }
```

Also See: [Statements](#)

return

return

A **return** statement allows an immediate exit from a switch or a loop or function and also returns a value.

The syntax is:

```
return(expr);
```

Example:

```
return (5);
```

Also See: [Statements](#)

goto

goto

The goto statement cause an unconditional branch to the label.

The syntax is:

```
goto label;
```

A label has the same form as a variable name, and is followed by a colon.

The goto's are used sparingly, if at all.

Example:

```
goto loop;
```

Also See: [Statements](#)

label

label

The label a goto jumps to.

The syntax is:

label: stmt;

Example:

```
loop: i++;
```

Also See: [Statements](#)

break

break.

The break statement is used to exit out of a control loop. It provides an early exit from while, for ,do and switch.

The syntax is

break;

It causes the innermost enclosing loop (or switch) to be exited immediately.

Example:

```
break;
```

Also See: [Statements](#)

continue

The **continue** statement causes the next iteration of the enclosing loop(While, For, Do) to begin.

The syntax is:

continue;

It causes the test part to be executed immediately in case of do and while and the control passes the re-initialization step in case of for.

Example:

```
continue;
```

Also See: [Statements](#)

expr

The syntax is:

```
expr;
```

Example:

```
i=1;
```

Also See: [Statements](#)

;

Statement: ;

Example:

```
;
```

Also See: [Statements](#)

stmt

Zero or more semi-colon separated.

The syntax is:

{[stmt]}

Example:

```
{ a=1 ;  
  b=1 ; }
```

Also See: [Statements](#)

EXPRESSIONS

Constants

123	Decimal
123L	Forces type to & long (UL also allowed)
123LL	Forces type to & int32;
0123	Octal
0x123	Hex
0b010010	Binary
123.456	Floating Point
123F	Floating Point (FL also allowed)
123.4E-5	Floating Point in scientific notation
'x'	Character
'\010'	Octal Character
'\xA5'	Hex Character
'\c'	Special Character. Where c is one of: \n Line Feed - Same as \x0a \r Return Feed - Same as \x0d \t TAB - Same as \x09 \b Backspace - Same as \x08 \f Form Feed - Same as x0c \a Bell - Same as \x07 \v Vertical Space - Same as \x0b

	\? Question Mark - Same as \x3f
	\' Single Quote - Same as \x22
	\" Double Quote - Same as \x22
	\\ A Single Backslash - Same as \x5c
"abcdef"	String (null is added to the end)

Identifiers

ABCDE	Up to 32 characters beginning with a non-numeric. Valid characters are A-Z, 0-9 and _ (underscore). By default not case sensitive Use #CASE to turn on.
ID[X]	Single Subscript
ID[X][X]	Multiple Subscripts
ID.ID	Structure or union reference
ID->ID	Structure or union reference

Operators

+	Addition Operator
+=	Addition assignment operator, x+=y, is the same as x=x+y
[]	Array subscript operator
&=	Bitwise and assignment operator, x&=y, is the same as x=x&y
&	Address operator
&	Bitwise and operator
^=	Bitwise exclusive or assignment operator, x^=y, is the same as x=x^y
^	Bitwise exclusive or operator
=	Bitwise inclusive or assignment operator, x =y, is the same as x=x y

 	Bitwise inclusive or operator
?:	Conditional Expression operator
--	Decrement
/=	Division assignment operator, $x/=y$, is the same as $x=x/y$
/	Division operator
==	Equality
>	Greater than operator
>=	Greater than or equal to operator
++	Increment
*	Indirection operator
!=	Inequality
<=<=	Left shift assignment operator, $x<=<y$, is the same as $x=x<<y$
<	Less than operator
<<	Left Shift operator
<=	Less than or equal to operator
&&	Logical AND operator
!	Logical negation operator
 	Logical OR operator
.	Member operator for structures and unions
%=	Modules assignment operator $x\%=y$, is the same as $x=x\%y$
%	Modules operator
=	Multiplication assignment operator, $x=y$, is the same as $x=x*y$
*	Multiplication operator
~	One's complement operator
>>=	Right shift assignment, $x>>=y$, is the same as $x=x>>y$
>>	Right shift operator
->	Structure Pointer operation
-=	Subtraction assignment operator, $x-=y$, is the same as $x=x-y$
-	Subtraction operator
sizeof	Determines size in bytes of operand

Operator Precedence

PIN DESCENDING PRECEDENCE		Associativity		
(expr)	expr++	expr->expr	expr.expr	Left to Right
++expr	expr++	- -expr	expr - -	Left to Right
!expr	~expr	+expr	-expr	Right to Left
(type)expr	*expr	&value	sizeof(type)	Right to Left
expr*expr	expr/expr	expr%expr		Left to Right
expr+expr	expr-expr			Left to Right
expr<<expr	expr>>expr			Left to Right
expr<expr	expr<=expr	expr>expr	expr>=expr	Left to Right
expr==expr	expr!=expr			Left to Right
expr&expr				Left to Right
expr^expr				Left to Right
expr expr				Left to Right
expr&& expr				Left to Right
expr expr				Left to Right
expr ? expr: expr				Right to Left
lvalue = expr	lvalue+=expr	lvalue-=expr		Right to Left
lvalue*=expr	lvalue/=expr	lvalue%=expr		Right to Left
lvalue>>=expr	lvalue<<=expr	lvalue&=expr		Right to Left
lvalue^=expr	lvalue =expr			Right to Left
expr, expr				Left to Right

(Operators on the same line are equal in precedence)

DATA DEFINITIONS

Data Definitions

This section describes what the basic data types and specifiers are and how variables can be declared using those types. In C all the variables should be declared before they are used. They can be defined inside a function (local) or outside all functions (global). This will affect the visibility and life of the variables.

A declaration consists of a type qualifier and a type specifier, and is followed by a list of one or more variables of that type.

For example:

```
int a,b,c,d;
mybit e,f;
mybyte g[3][2];
char *h;
colors j;
struct data_record data[10];
static int i;
extern long j;
```

Variables can also be declared along with the definitions of the *special* types.

For example:

```
enum colors{red, green=2,blue}i,j,k; // colors is the
enum type and i,j,k
//are variables of that type
```

SEE ALSO:

Type Specifiers/ Basic Types

Type Qualifiers

Enumerated Types

Structures & Unions

typedef

Named Registers

Type Specifiers

Basic Types

Type-Specifier	Size	Range		Digits
		Unsigned	Signed	
int1	1 bit number	0 to 1	N/A	1/2
int8	8 bit number	0 to 255	-128 to 127	2-3
int16	16 bit number	0 to 65535	-32768 to 32767	4-5
int32	32 bit number	0 to 4294967295	-2147483648 to 2147483647	9-10
float32	32 bit float	-1.5×10^{45} to 3.4×10^{38}		7-8

C Standard Type	Default Type
short	int1
char	unsigned int8
int	int8
long	int16
long long	int32
float	float32
double	N/A

Note: All types, except float char , by default are un-signed; however, may be preceded by unsigned or signed (Except int64 may only be signed) . Short and long may have the keyword INT following them with no effect. Also see #TYPE to change the default size.

SHORT INT1 is a special type used to generate very efficient code for bit operations and I/O. Arrays of bits (INT1 or SHORT) in RAM are now supported. Pointers to bits are not permitted. The device header files contain defines for BYTE as an int8 and BOOLEAN as an int1.

Integers are stored in little endian format. The LSB is in the lowest address. Float formats are described in common questions.

SEE ALSO: Declarations, Type Qualifiers, Enumerated Types, Structures & Unions, typedef, Named Registers


Type Qualifiers

Type-Qualifier	
static	Variable is globally active and initialized to 0. Only accessible from this compilation unit.
auto	Variable exists only while the procedure is active. This is the default and AUTO need not be used.
do ubl e	Is a reserved word but is not a supported data type.
extern	External variable used with multiple compilation units. No storage is allocated. Is used to make otherwise out of scope data accessible. there must be a non-extern definition at the global level in some compilation unit.
register	Is allowed as a qualifier however, has no effect.
_fixed(n)	Creates a fixed point decimal number where <i>n</i> is how many decimal places to implement.
unsigned	Data is always positive. This is the default data type if not specified.
signed	Data can be negative or positive.
volatile	Tells the compiler optimizer that this variable can be changed at any point during execution.
const	Data is read-only. Depending on compiler configuration, this qualifier may just make the data read-only -AND/OR- it may place the data into program memory to save space. (see #DEVICE const=)
rom	Forces data into program memory. Pointers may be used to this data but they can not be mixed with RAM pointers.
void	Built-in basic type. Type void is used to indicate no specific type in places where a type is required.

<code>readonly</code>	Writes to this variable should be dis-allowed
<code>_bif</code>	Used for compiler built in function prototypes on the same line
<code>__attribute__</code>	Sets various attributes

Enumerated Types

enum enumeration type: creates a list of integer constants.

<code>enum</code>	<code>[id]</code>	<code>{ [id [= cexpr]] }</code>
		
		One or more comma separated

The id after **enum** is created as a type large enough to the largest constant in the list. The ids in the list are each created as a constant. By default the first id is set to zero and they increment by one. If a = cexpr follows an id that id will have the value of the constant expression and the following list will increment by one.

For example:

```
enum colors{red, green=2, blue};    // red will be 0,  
green will be 2 and                // blue will be 3
```

Structures and Unions



Struct structure type: creates a collection of one or more variables, possibly of different types, grouped together as a single unit.

<code>struct[*] [id]</code>			
<code>{</code>	<code>type-qualifier [*] id</code>	<code>[:bits];</code>	<code>} [id]</code>
			
	One or more, semi-colon		Zero or more

separated

```
For example:
struct data_record {
    int  a[2];
    int  b : 2; /*2 bits */
    int  c : 3; /*3 bits*/
    int d;
} data_var;                                     //data_record is a structure
type                                           //data_var is a variable
```

Union type: holds objects of different types and sizes, with the compiler keeping track of size and alignment requirements. They provide a way to manipulate different kinds of data in a single area of storage.

union[*] [id] {	type-qualifier [*] id	[:bits];	} [id]
			
	One or more, semi-colon separated		Zero or more

```
For example:
union u_tag {
    int ival;
    long lval;
    float fval;
};          //u_tag is a union type that can hold a float
```

typedef

If **typedef** is used with any of the basic or special types it creates a new type name that can be used in declarations. The identifier does not allocate space but rather may be used as a type specifier in other data definitions.

typedef	[type-qualifier] [declarator];	[type-specifier]
---------	-----------------------------------	------------------

For example:

```
typedef int mybyte;           // mybyte can
be used in                   // specify the
    //declaration to          // specify the

int type                      // specify the
typedef short mybit;          // mybyte can
be used in                    // specify the
    //declaration to          // specify the

int type                      // specify the
typedef enum {red, green=2,blue}colors; //colors can
be used to declare            //variable of

this enum type                //variable of
```

Non-RAM Data Definitions

CCS C compiler also provides a custom qualifier *addressmod* which can be used to define a memory region that can be RAM, program eeprom, data eeprom or external memory. *Addressmod* replaces the older *typemod* (with a different syntax).

The usage is :

```
addressmod
(name,read_function,write_function,start_addr
ess,end_address, share);
```

Where the `read_function` and `write_function` should be blank for RAM, or for other memory should be the following prototype:

```
// read procedure for reading n bytes from the
memory starting at location addr
void read_function(int32 addr,int8 *ram, int
nbytes){
```

```

}

//write procedure for writing n bytes to the
memory starting at location addr
void write_function(int32 addr,int8 *ram, int
nbytes){
}

```

For RAM the share argument may be true if unused RAM in this area can be used by the compiler for standard variables.

Example:

```

void DataEE_Read(int32 addr, int8 * ram, int
bytes) {
    int i;
    for(i=0;i<bytes;i++,ram++,addr++)
        *ram=read_eeprom(addr);
}

void DataEE_Write(int32 addr, int8 * ram, int
bytes) {
    int i;
    for(i=0;i<bytes;i++,ram++,addr++)
        write_eeprom(addr,*ram);
}

addressmod
(DataEE,DataEE_read,DataEE_write,5,0xff);

    // would define a region called DataEE
    between
    // 0x5 and 0xff in the chip data EEPROM.

void main (void)
{
    int DataEE test;
    int x,y;
    x=12;
    test=x;  // writes x to the Data EEPROM
    y=test;  // Reads the Data EEPROM
}

```

Note: If the area is defined in RAM then read and write functions are not required, the variables assigned in the memory region defined by the addressmod can be treated as a regular variable in all valid expressions. Any structure or data type can be used with an

addressmod. Pointers can also be made to an addressmod data type. The #type directive can be used to make this memory region as default for variable allocations.

The syntax is :

```
#type default=addressmodname          // all the
variable declarations that              // follow
will use this memory region
#type default=                          // goes back
to the default mode
```

For example:

```
Type default=emi                      //emi is the
addressmod name defined
char buffer[8192];
#include <memoryhog.h>
#type default=
```

Using Program Memory for Data

CCS C Compiler provides a few different ways to use program memory for data. The different ways are discussed below:

Constant Data:

The **const** qualifier will place the variables into program memory. If the keyword **const** is used before the identifier, the identifier is treated as a constant. Constants should be initialized and may not be changed at run-time. This is an easy way to create lookup tables.

The **rom** Qualifier puts data in program memory with 3 bytes per instruction space. The address used for ROM data is not a physical address but rather a true byte address. The & operator can be used on ROM variables however the address is logical not physical.

The syntax is:

```
const type id[cexpr] = {value}
```

For example:

Placing data into ROM

```
const int table[16]={0,1,2...15}
```

Placing a string into ROM

```
const char cstring[6]="hello"
```

Creating pointers to constants

```
const char *cptr;
cptr = string;
```


The `#org` preprocessor can be used to place the constant to specified address blocks.

For example:

The constant ID will be at 1C00.

```
#ORG 0x1C00, 0x1C0F
CONST CHAR ID[10]= {"123456789"};
```

Note: Some extra code will precede the 123456789.

The function **label_address** can be used to get the address of the constant. The constant variable can be accessed in the code. This is a great way of storing constant data in large programs. Variable length constant strings can be stored into program memory.

A special method allows the use of pointers to ROM. This method does not contain extra code at the start of the structure as does constant.

For example:

```
char rom commands[] = {"put|get|status|shutdown"};
```

The compiler allows a non-standard C feature to implement a constant array of variable length strings.

The syntax is:

```
const char id[n] [*] = { "string", "string" ...};
```

Where `n` is optional and `id` is the table identifier.

For example:

```
const char colors[] [*] = {"Red", "Green", "Blue"};
```

#ROM directive:

Another method is to use `#rom` to assign data to program memory.

The syntax is:

```
#rom address = {data, data, ... , data}
```

For example:

Places 1,2,3,4 to ROM addresses starting at 0x1000

```
#rom 0x1000 = {1, 2, 3, 4}
```

Places null terminated string in ROM

```
#rom 0x1000={"hello"}
```

This method can only be used to initialize the program memory.

Built-in-Functions:

The compiler also provides built-in functions to place data in program memory, they are:

- `write_program_eeprom(address,data);`
- Writes **data** to program memory
- `write_program_memory(address, dataptr, count);`
- Writes **count** bytes of data from **dataptr** to **address** in program memory.
-

Please refer to the help of these functions to get more details on their usage and limitations regarding erase procedures. These functions can be used only on chips that allow writes to program memory. The compiler uses the flash memory erase and write routines to implement the functionality.

The data placed in program memory using the methods listed above can be read from within the following functions:

- `read_program_memory((address, dataptr, count)`
- Reads count bytes from program memory at address to RAM at dataptr.

These functions can be used only on chips that allow reads from program memory. The compiler uses the flash memory read routines to implement the functionality.

Named Registers

The CCS C Compiler supports the new syntax for filing a variable at the location of a processor register. This syntax is being proposed as a C extension for embedded use. The same functionality is provided with the non-standard **#byte**, **#word**, **#bit** and **#locate**.

The syntax is:

register _name type id;
Or
register constant type id;

name is a valid SFR name with an underscore before it.




Examples:

```
register _status int8 status_reg;  
register _T1IF int8 timer_interrupt;  
register 0x04 int16 file_select_register;
```

FUNCTION DEFINITION

Function Definition

The format of a function definition is as follows:

[qualifier] id	([type-specifier id])	{ [stmt] }
 Optional See Below	 Zero or more comma separated. See Data Types	 Zero or more Semi-colon separated. See Statements.

The qualifiers for a function are as follows:

- VOID
- type-specifier
- #separate
- #inline
- #int_..

When one of the above are used and the function has a prototype (forward declaration of the function before it is defined) you must include the qualifier on both the prototype and function definition.

A (non-standard) feature has been added to the compiler to help get around the problems created by the fact that pointers cannot be created to constant strings. A function that has one CHAR parameter will accept a constant string where it is called. The compiler will generate a loop that will call the function once for each character in the string.

Example:

```
void lcd_putc(char c ) {  
    ...  
}  
  
lcd_putc ("Hi There.");
```

Overloaded Functions

Overloaded functions allow the user to have multiple functions with the same name, but they must accept different parameters.

Here is an example of function overloading: Two functions have the same name but differ in the types of parameters. The compiler determines which data type is being passed as a parameter and calls the proper function.

This function finds the square root of a long integer variable.

```
long FindSquareRoot(long n){
}
```

This function finds the square root of a float variable.

```
float FindSquareRoot(float n){
}
```

FindSquareRoot is now called. If variable is of long type, it will call the first FindSquareRoot() example. If variable is of float type, it will call the second FindSquareRoot() example.

```
result=FindSquareRoot(variable);
```

Reference Parameters

The compiler has limited support for reference parameters. This increases the readability of code and the efficiency of some inline procedures. The following two procedures are the same. The one with reference parameters will be implemented with greater efficiency when it is inline.

```
funct_a(int*x,int*y){
    /*Traditional*/
    if(*x!=5)
        *y=*x+3;
}

funct_a(&a,&b);
```

```

func_t_b(int&x,int&y){
    /*Reference params*/
    if(x!=5)
        y=x+3;
}

func_t_b(a,b);

```

Default Parameters

Default parameters allows a function to have default values if nothing is passed to it when called.

```

int mygetc(char *c, int n=100){
}

```

This function waits n milliseconds for a character over RS232. If a character is received, it saves it to the pointer c and returns TRUE. If there was a timeout it returns FALSE.

```

//gets a char, waits 100ms for timeout
mygetc(&c);
//gets a char, waits 200ms for a timeout
mygetc(&c, 200);

```

Variable Argument Lists

The compiler supports a variable number of parameters. This works like the ANSI requirements except that it does not require at least one fixed parameter as ANSI does. The function can be passed any number of variables and any data types. The access functions are VA_START, VA_ARG, and VA_END. To view the number of arguments passed, the NARGS function can be used.

```

/*
stdarg.h holds the macros and va_list data type needed for variable
number of parameters.
*/
#include <stdarg.h>

```

A function with variable number of parameters requires two things. First, it requires the ellipsis (...), which must be the last parameter of the function. The ellipsis represents the variable argument list. Second, it requires one more variable before the ellipsis (...). Usually you will use this variable as a method for determining how many variables have been pushed onto the ellipsis.

Here is a function that calculates and returns the sum of all variables:

```
int Sum(int count, ...)
{
    //a pointer to the argument list
    va_list al;
    int x, sum=0;
    //start the argument list
    //count is the first variable before the ellipsis
    va_start(al, count);
    while(count--) {
        //get an int from the list
        x = var_arg(al, int);
        sum += x;
    }
    //stop using the list
    va_end(al);
    return(sum);
}
```

Some examples of using this new function:

```
x=Sum(5, 10, 20, 30, 40, 50);
y=Sum(3, a, b, c);
```

FUNCTIONAL OVERVIEW

I2C

I2C™ is a popular two-wire communication protocol developed by Phillips. Many PIC microcontrollers support hardware-based I2C™. CCS offers support for the hardware-based I2C™ and a software-based master I2C™ device. (For more information on the hardware-based I2C module, please consult the datasheet for you target device; not all PICs support I2C™.)

Relevant Functions:

i2c_start()	Issues a start command when in the I2C master mode.
i2c_write(data)	Sends a single byte over the I2C interface.
i2c_read()	Reads a byte over the I2C interface.
i2c_stop()	Issues a stop command when in the I2C master mode.
i2c_poll()	Returns a TRUE if the hardware has received a byte in the buffer.

Relevant Preprocessor:

#USE I2C	Configures the compiler to support I2C™ to your specifications.
-----------------	---

Relevant Interrupts:

#INT_SSP	I2C or SPI activity
#INT_BUSCOL	Bus Collision
#INT_I2C	I2C Interrupt (Only on 14000)
#INT_BUSCOL2	Bus Collision (Only supported on some PIC18's)
#INT_SSP2	I2C or SPI activity (Only supported on some PIC18's)

Relevant Include Files:

None, all functions built-in

Relevant getenv() Parameters:

I2C_SLAVE	Returns a 1 if the device has I2C slave H/W
I2C_MASTER	Returns a 1 if the device has a I2C master H/W

Example Code:

```
#define Device_SDA PIN_C3           // Pin defines
#define Device_SLC PIN_C4
#include i2c(master, sda=Device_SDA, scl=Device_SLC) // Configure Device as Master
..
..
BYTE data;                         // Data to be transmitted
i2c_start();                       // Issues a start command when in the I2C master
                                   // mode.
i2c_write(data);                   // Sends a single byte over the I2C interface.
i2c_stop();                        // Issues a stop command when in the I2C master
                                   // mode.
```

ADC

These options let the user configure and use the analog to digital converter module. They are only available on devices with the ADC hardware. The options for the functions and directives vary depending on the chip and are listed in the device header file. On some devices there are two independent ADC modules, for these chips the second module is configured using secondary ADC setup functions (Ex. setup_ADC2).

Relevant Functions:

setup_adc(mode)	Sets up the a/d mode like off, the adc clock etc.
setup_adc_ports(value)	Sets the available adc pins to be analog or digital.
set_adc_channel(channel)	Specifies the channel to be use for the a/d call.
read_adc(mode)	Starts the conversion and reads the value. The mode can also control the functionality.
adc_done()	Returns 1 if the ADC module has finished its conversion.

Relevant Preprocessor:

#DEVICE ADC=xx	Configures the read_adc return size. For example, using a PIC with a 10 bit A/D you can use 8 or 10 for xx- 8 will return the most significant byte, 10 will return the full A/D reading of 10 bits.
-----------------------	--

Relevant Interrupts:

INT_AD	Interrupt fires when a/d conversion is complete
---------------	---

INT_ADOF	Interrupt fires when a/d conversion has timed out
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters:	
ADC_CHANNELS	Number of A/D channels
ADC_RESOLUTION	Number of bits returned by read_adc
Example Code:	
#DEVICE ADC=10	
...	
long value;	
...	
setup_adc(ADC_CLOCK_INTERNAL);	//enables the a/d module //and sets the clock to internal adc clock
setup_adc_ports(ALL_ANALOG);	//sets all the adc pins to analog
set_adc_channel(0);	//the next read_adc call will read channel 0
delay_us(10);	//a small delay is required after setting the channel //and before read
value=read_adc();	//starts the conversion and reads the result //and store it in value
read_adc(ADC_START_ONLY);	//only starts the conversion //reads the result of the last conversion and store it in //value. Assuming the device has a 10bit ADC module, //value will range between 0-3FF. If #DEVICE ADC=8 had //been used instead the result will yield 0-FF. If #DEVICE //ADC=16 had been used instead the result will yield 0-//FFC0
value=read_adc(ADC_READ_ONLY);	

Analog Comparator

These functions set up the analog comparator module. Only available in some devices.

Relevant Functions:	
setup_comparator(mode)	Enables and sets the analog comparator module. The options vary depending on the chip. Refer to the header file for details.
Relevant Preprocessor:	
None	

Relevant Interrupts:

INT_COMP

Interrupt fires on comparator detect. Some chips have more than one comparator unit, and thus, more interrupts.

Relevant Include Files:

None, all functions built-in

Relevant getenv() Parameters:

Returns 1 if the device has a comparator

COMP

Example Code:

```
setup_comparator(A4_A5_N  
C_NC);  
if(C1OUT)  
output_low(PIN_D0);  
else  
output_high(PIN_D1);
```

CAN Bus

These functions allow easy access to the Controller Area Network (CAN) features included with the MCP2515 CAN interface chip and the PIC18 MCU. These functions will only work with the MCP2515 CAN interface chip and PIC microcontroller units containing either a CAN or an ECAN module. Some functions are only available for the ECAN module and are specified by the work ECAN at the end of the description. The listed interrupts are no available to the MCP2515 interface chip.

Relevant Functions:

can_init(void);

Initializes the CAN module and clears all the filters and masks so that all messages can be received from any ID.

can_set_baud(void);

Initializes the baud rate of the CAN bus to 125kHz, if using a 20 MHz clock and the default CAN-BRG defines, it is called inside the can_init() function so there is no need to call it.

can_set_mode (CAN_OP_MODE mode);	Allows the mode of the CAN module to be changed to configuration mode, listen mode, loop back mode, disabled mode, or normal mode.
can_set_functional_mode (CAN_FUN_OP_MODE mode);	Allows the functional mode of ECAN modules to be changed to legacy mode, enhanced legacy mode, or first in firstout (fifo) mode. ECAN
can_set_id (int* addr, int32 id, int1 ext);	Can be used to set the filter and mask ID's to the value specified by addr. It is also used to set the ID of the message to be sent.
can_get_id (int * addr, int1 ext);	Returns the ID of a received message.
can_putd (int32 id, int * data, int len, int priority, int1 ext, int1 rtr);	Constructs a CAN packet using the given arguments and places it in one of the available transmit buffers.
can_getd (int32 & id, int * data, int & len, struct rx_stat & stat);	Retrieves a received message from one of the CAN buffers and stores the relevant data in the referenced function parameters.
can_enable_rtr (PROG_BUFFER b);	Enables the automatic response feature which automatically sends a user created packet when a specified ID is received. ECAN
can_disable_rtr (PROG_BUFFER b);	Disables the automatic response feature. ECAN
can_load_rtr (PROG_BUFFER b, int * data, int len);	Creates and loads the packet that will automatically transmitted when the triggering ID is received. ECAN
can_enable_filter (long filter);	Enables one of the extra filters included in the ECAN module. ECAN
can_disable_filter (long filter);	Disables one of the extra filters included in the ECAN module. ECAN
can_associate_filter_to_buffer (CAN_FILTER_ASSOCIATION_BUFFERS buffer, CAN_FILTER_ASSOCIATION filter);	Used to associate a filter to a specific buffer. This allows only specific buffers to be filtered and is available in the ECAN module. ECAN
can_associate_filter_to_mask (CAN_MASK_FILTER_ASSOCIATE	Used to associate a mask to a specific buffer. This allows only specific buffer to have this mask applied.

mask, CAN_FILTER_ASSOCIATION filter);	This feature is available in the ECAN module. ECAN
can_fifo_getd(int32 & id,int * data, int &len,struct rx_stat & stat);	Retrieves the next buffer in the fifo buffer. Only available in the ECON module while operating in fifo mode. ECAN
Relevant Preprocessor: None	
Relevant Interrupts:	
#int_canirx	This interrupt is triggered when an invalid packet is received on the CAN.
#int_canwake	This interrupt is triggered when the PIC is woken up by activity on the CAN.
#int_canerr	This interrupt is triggered when there is an error in the CAN module.
#int_cantx0	This interrupt is triggered when transmission from buffer 0 has completed.
#int_cantx1	This interrupt is triggered when transmission from buffer 1 has completed.
#int_cantx2	This interrupt is triggered when transmission from buffer 2 has completed.
#int_canrx0	This interrupt is triggered when a message is received in buffer 0.
#int_canrx1	This interrupt is triggered when a message is received in buffer 1.
Relevant Include Files:	
can-mcp2510.c	Drivers for the MCP2510 and MCP2515 interface chips
can-18xxx8.c	Drivers for the built in CAN module
can-18F4580.c	Drivers for the build in ECAN module
Relevant getenv() Parameters: none	
Example Code:	
can_init();	// initializes the CAN bus
can_putd(0x300,data,8,3,TRUE,FALSE);	// places a message on the CAN buss with
	// ID = 0x300 and eight bytes of data pointed to by
	// "data", the TRUE creates an extended ID, the
	// FALSE creates
can_getd(ID,data,len,stat);	// retrieves a message from the CAN bus storing the

```
// ID in the ID variable, the data at the array pointed
// to by
// "data", the number of data bytes in len, and
// statistics
// about the data in the stat structure.
```

CCP

These options lets to configure and use the CCP module. There might be multiple CCP modules for a device. These functions are only available on devices with CCP hardware. They operate in 3 modes: capture, compare and PWM. The source in capture/compare mode can be timer1 or timer3 and in PWM can be timer2 or timer4. The options available are different for different devices and are listed in the device header file. In capture mode the value of the timer is copied to the CCP_X register when the input pin event occurs. In compare mode it will trigger an action when timer and CCP_x values are equal and in PWM mode it will generate a square wave.

Relevant Functions:

setup_ccp1(mode)	Sets the mode to capture, compare or PWM. For capture
set_pwm1_duty(value)	The value is written to the pwm1 to set the duty.

Relevant Preprocessor:

None

Relevant Interrupts :

INT_CCP1	Interrupt fires when capture or compare on CCP1
-----------------	---

Relevant Include Files:

None, all functions built-in

Relevant getenv() parameters:

CCP1	Returns 1 if the device has CCP1
-------------	----------------------------------

Example Code:

```
#int_ccp1
void isr()
{
    rise = CCP_1;           //CCP_1 is the time the pulse went high
    fall = CCP_2;           //CCP_2 is the time the pulse went low
    pulse_width = fall - rise; //pulse width
}
```

```
..
setup_ccp1(CCP_CAPTURE_RE); // Configure CCP1 to capture rise
setup_ccp2(CCP_CAPTURE_FE); // Configure CCP2 to capture fall
setup_timer_1(T1_INTERNAL); // Start timer 1
```

Some chips also have fuses which allows to multiplex the ccp/pwm on different pins. So check the fuses to see which pin is set by default. Also fuses to enable/disable pwm outputs.

Code Profile

Profile a program while it is running. Unlike in-circuit debugging, this tool grabs information while the program is running and provides statistics, logging and tracing of it's execution. This is accomplished by using a simple communication method between the processor and the ICD with minimal side-effects to the timing and execution of the program. Another benefit of code profile versus in-circuit debugging is that a program written with profile support enabled will run correctly even if there is no ICD connected.

In order to use Code Profiling, several functions and pre-processor statements need to be included in the project being compiled and profiled. Doing this adds the proper code profile run-time support on the microcontroller.

See the help file in the Code Profile tool for more help and usage examples.

Relevant Functions:

<u>profileout()</u>	Send a user specified message or variable to be displayed or logged by the code profile tool.
----------------------------	---

Relevant Pre-Processor:

<u>#use profile()</u>	Global configuration of the code profile run-time on the microcontroller.
<u>#profile</u>	Dynamically enable/disable specific elements of the profiler.

Relevant Interrupts:	The profiler can be configured to use a microcontroller's internal timer for more accurate timing of events over the clock on the PC. This timer is configured using the #profile pre-processor command.
Relevant Include Files:	None – all the functions are built into the compiler.
Relevant getenv():	None
Example Code:	<pre> #include <18F4520.h> #use delay(crystal=10MHz, clock=40MHz) #profile functions, parameters void main(void) { int adc; setup_adc(ADC_CLOCK_INTER NAL); set_adc_channel(0); for(;;) { adc = read_adc(); profileout(adc); delay_ms(250); } } </pre>

Configuration Memory

On all PIC18 Family of chips, the configuration memory is readable and writable. This functionality is not available on the PIC16 Family of devices..

Relevant Functions:

write_configuration_memory
(ramaddress, count)

Writes count bytes, no erase needed

or	
write_configuration_memory(offset,ramaddress, count)	Writes count bytes, no erase needed starting at byte address offset
read_configuration_memory(ramaddress,count)	Read count bytes of configuration memory
Relevant Preprocessor:	
None	
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters:	
None	
Example Code:	
For PIC18f452	
int16 data=0xc32;	
...	
write_configuration_memory(data,2);	//writes 2 bytes to the configuration memory

DAC

These options let the user configure and use the digital to analog converter module. They are only available on devices with the DAC hardware. The options for the functions and directives vary depending on the chip and are listed in the device header file.

Relevant Functions:	
setup_dac(divisor)	Sets up the DAC e.g. Reference voltages
dac_write(value)	Writes the 8-bit value to the DAC module
	Sets up the d/a mode e.g. Right enable, clock divisor
	Writes the 16-bit value to the specified channel
Relevant Preprocessor:	
#USE DELAY(clock=20M, Aux: crystal=6M, clock=3M)	

Relevant Interrupts:	None
Relevant Include Files:	None, all functions built-in
Relevant getenv() parameters:	None
Example Code:	<pre>int8 i=0; setup_dac (DAC_VSS_VDD); while (TRUE) { itt; dac_write(i); }</pre>

Data Eeprom

The data eeprom memory is readable and writable in some chips. These options lets the user read and write to the data eeprom memory. These functions are only available in flash chips.

Relevant Functions:	
<i>(8 bit or 16 bit depending on the device)</i>	
read_eeprom(address)	Reads the data EEPROM memory location
write_eeprom(address, value)	Erases and writes value to data EEPROM location address.
	Reads N bytes of data EEPROM starting at memory location address. The maximum return size is int64.
	Reads from EEPROM to fill variable starting at address
	Reads N bytes, starting at address, to pointer
	Writes value to EEPROM address
	Writes N bytes to address from pointer
Relevant Preprocessor:	
#ROM address={list}	Can also be used to put data EEPROM memory data into the hex file.
write_eeprom = noint	Allows interrupts to occur while the write_eeprom() operations is polling the done bit to check if the write operations has completed. Can be used as long as no EEPROM operations are performed during an ISR.
Relevant Interrupts:	

INT_EEPROM	Interrupt fires when EEPROM write is complete
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters:	
DATA_EEPROM	Size of data EEPROM memory.
Example Code:	
For 18F452	//inserts this data into the hex file. The data eeprom address
#rom 0xf00000={1,2,3,4,5}	//differs for different family of chips. Please refer to the //programming specs to find the right value for the device
write_eeprom(0x0,0x12);	//writes 0x12 to data eeprom location 0
value=read_eeprom(0x0);	//reads data eeprom location 0x0 returns 0x12
#ROM	
0x007FFC00={1,2,3,4,5}	// Inserts this data into the hex file
	// The data EEPROM address differs between PICs
	// Please refer to the device editor for device specific values.
write_eeprom(0x10, 0x1337);	// Writes 0x1337 to data EEPROM location 10.
value=read_eeprom(0x0);	// Reads data EEPROM location 10 returns 0x1337.

Data Signal Modulator

The Data Signal Modulator (DSM) allows the user to mix a digital data stream (the “modulator signal”) with a carrier signal to produce a modulated output. Both the carrier and the modulator signals are supplied to the DSM module, either internally from the output of a peripheral, or externally through an input pin. The modulated output signal is generated by performing a logical AND operation of both the carrier and modulator signals and then it is provided to the MDOUT pin. Using this method, the DSM can generate the following types of key modulation schemes:

- Frequency Shift Keying (FSK)
- Phase Shift Keying (PSK)
- On-Off Keying (OOK)

Relevant Functions:	<i>(8 bit or 16 bit depending on the device)</i>
setup_dsm(mode,source,carrier)	Configures the DSM module and selects the source signal and carrier signals.
setup_dsm(TRUE)	Enables the DSM module.
setup_dsm(FALSE)	Disables the DSM module.
Relevant Preprocessor:	None
Relevant Interrupts:	None
Relevant Include Files:	None, all functions built-in
Relevant getenv() parameters:	None
Example Code:	
setup_dsm(DSM_ENABLED	//Enables DSM module with the output enabled and selects UART1
 	
DSM_OUTPUT_ENABLED,	//as the source signal and VSS as the high carrier signal and OC1's
DSM_SOURCE_UART1,	//PWM output as the low carrier signal.
DSM_CARRIER_HIGH_VSS	
 	
DSM_CARRIER_LOW_OC1)	
;	
if(input(PIN_B0))	
setup_dsm(FALSE);	Disable DSM module
else	
setup_dsm(TRUE);	Enable DSM module

External Memory

Some PIC18 devices have the external memory functionality where the external memory can be mapped to external memory devices like (Flash, EPROM or RAM). These functions are available only on devices that support external memory bus.

General Purpose I/O

These options let the user configure and use the I/O pins on the device. These functions will affect the pins that are listed in the device header file.

Relevant Functions:

output_high(pin)	Sets the given pin to high state.
output_low(pin)	Sets the given pin to the ground state.
output_float(pin)	Sets the specified pin to the input mode. This will allow the pin to float high to represent a high on an open collector type of connection.
output_x(value)	Outputs an entire byte to the port.
output_bit(pin,value)	Outputs the specified value (0,1) to the specified I/O pin.
input(pin)	The function returns the state of the indicated pin.
input_state(pin)	This function reads the level of a pin without changing the direction of the pin as INPUT() does.
set_tris_x(value)	Sets the value of the I/O port direction register. A '1' is an input and '0' is for output.
input_change_x()	This function reads the levels of the pins on the port, and compares them to the last time they were read to see if there was a change, 1 if there was, 0 if there was not.
<u>set_open_drain_x(value)</u>	This function sets the value of the I/O port Open-Drain register. A 1 makes the output open-drain and 0 makes the output push-pull.
set_input_level_x(value)	This function sets the value of the I/O port Input Level Register. A 1 sets the input level to ST and 0 sets the input level to TTL.

Relevant Preprocessor:

#USE STANDARD_IO(port)	This compiler will use this directive by default and it will automatically insert code for the direction register whenever an I/O function like output_high() or input() is used.
-----------------------------------	---

#USE FAST_IO(<i>port</i>)	This directive will configure the I/O port to use the fast method of performing I/O. The user will be responsible for setting the port direction register using the <code>set_tris_x()</code> function.
#USE FIXED_IO (<i>port_outputs=;in,pin?</i>)	This directive set particular pins to be used an input or output, and the compiler will perform this setup every time this pin is used.
Relevant Interrupts:	None
Relevant Include Files:	None, all functions built-in
Relevant getenv() parameters:	PIN:pb ----Returns a 1 if bit b on port p is on this part
Example Code:	<pre>#use fast_io(b)\ ... Int8 Tris_value= 0x0F; int1 Pin value; set_tris_b(Tris_value); //Sets B0:B3 as input and B4:B7 as output output_high(PIN_B7); //Set the pin B7 to High If(input(PIN_B0)){ //Read the value on pin B0, set B7 to low if pin B0 is high output_high(PIN_B7);}</pre>

Internal LCD

Some families of PIC microcontrollers can drive a glass segment LCD directly, without the need of an LCD controller. For example, the PIC16C92X, PIC16F91X, and PIC16F193X series of chips have an internal LCD driver module.

Relevant Functions:	
setup_lcd (<i>mode, prescale,</i> <i>[segments]</i>)	Configures the LCD Driver Module to use the specified mode, timer prescaler, and segments. For more information on valid modes and settings, see the <code>setup_lcd()</code> manual page and the *.h header file for the PIC micro-controller being used.
lcd_symbol (<i>symbol,</i> <i>segment_b7 ...</i>	The specified symbol is placed on the desired segments, where <code>segment_b7</code> to <code>segment_b0</code> represent SEGXX pins on the PIC micro-controller. For example, if bit 0 of <code>symbol</code> is set,

segment_b0)	then segment_b0 is set, and if segment_b0 is 15, then SEG15 would be set.
lcd_load(ptr, offset, length)	Writes length bytes of data from pointer directly to the LCD segment memory, starting with offset .
lcd_contrast (contrast)	Passing a value of 0 – 7 will change the contrast of the LCD segments, 0 being the minimum, 7 being the maximum.
Relevant Preprocessor:	
None	
Relevant Interrupts:	
#int_lcd	LCD frame is complete, all pixels displayed
Relevant Include Files:	None, all functions built-in to the compiler.
Relevant getenv() Parameters:	
LCD	Returns TRUE if the device has an Internal LCD Driver Module.
Example Program:	<pre>// How each segment of the LCD is set (on or off) for the ASCII digits 0 to 9. byte CONST DIGIT_MAP[10] = {0xFC, 0x60, 0xDA, 0xF2, 0x66, 0xB6, 0xBE, 0xE0, 0xFE, 0xE6}; // Define the segment information for the first digit of the LCD #define DIGIT1 COM1+20, COM1+18, COM2+18, COM3+20, COM2+28, COM1+28, COM2+20, COM3+18 // Displays the digits 0 to 9 on the first digit of the LCD. for(i = 0; i <= 9; i++) { lcd_symbol(DIGIT_MAP[i], DIGIT1); delay_ms(1000); }</pre>

Internal Oscillator

Many chips have internal oscillator. There are different ways to configure the internal oscillator. Some chips have a constant 4 Mhz factory calibrated internal oscillator. The value is stored in some location (mostly the highest program memory) and the compiler moves it to the osccl register on startup. The programmers save and restore this value but if this is lost they need to be programmed before the oscillator is functioning properly. Some chips have factory calibrated internal oscillator that offers software selectable frequency range(from 31Kz to 8 Mhz) and they have a default value and can be switched to a higher/lower value in software. They are also software tunable. Some chips also provide the PLL option for the internal oscillator.

Relevant Functions:	
setup_oscillator(mode, finetune)	Sets the value of the internal oscillator and also tunes it. The options vary depending on the chip and are listed in the device header files.
Relevant Preprocessor:	None
Relevant Interrupts:	
INT_OSC_FAIL or INT_OSCF	Interrupt fires when the system oscillator fails and the processor switches to the internal oscillator.
Relevant Include Files:	None, all functions built-in
Relevant getenv() parameters:	None
Example Code:	For PIC18F8722
setup_oscillator(OSC_32MHZ); //sets the internal oscillator to 32MHz (PLL enabled)	
If the internal oscillator fuse option are specified in the #fuses and a valid clock is specified in the #use delay(clock=xxx) directive the compiler automatically sets up the oscillator. The #use delay statements should be used to tell the compiler about the oscillator speed.	

Interrupts

The following functions allow for the control of the interrupt subsystem of the microcontroller. With these functions, interrupts can be enabled, disabled, and cleared. With the preprocessor directives, a default function can be called for any interrupt that

does not have an associated ISR, and a global function can replace the compiler generated interrupt dispatcher.

Relevant Functions:

<code>disable_interrupts()</code>	Disables the specified interrupt.
<code>enable_interrupts()</code>	Enables the specified interrupt.
<code>ext_int_edge()</code>	Enables the edge on which the edge interrupt should trigger. This can be either rising or falling edge.
<code>clear_interrupt()</code>	This function will clear the specified interrupt flag. This can be used if a global isr is used, or to prevent an interrupt from being serviced.
<code>interrupt_active()</code>	This function checks the interrupt flag of specified interrupt and returns true if flag is set.
<code>interrupt_enabled()</code>	This function checks the interrupt enable flag of the specified interrupt and returns TRUE if set.

Relevant Preprocessor:

<code>#DEVICE HIGH_INTS=</code>	This directive tells the compiler to generate code for high priority interrupts.
<code>#INT_XXX fast</code>	This directive tells the compiler that the specified interrupt should be treated as a high priority interrupt.

Relevant Interrupts:

<code>#int_default</code>	This directive specifies that the following function should be called if an interrupt is triggered but no routine is associated with that interrupt.
<code>#int_global</code>	This directive specifies that the following function should be called whenever an interrupt is triggered. This function will replace the compiler generated interrupt dispatcher.
<code>#int_xxx</code>	This directive specifies that the following function should be called whenever the xxx interrupt is triggered. If the compiler generated interrupt dispatcher is used, the compiler will take care of clearing the interrupt flag bits.

Relevant Include Files:

none, all functions built in.

Relevant getenv() Parameters:
none

Example Code:

```
#int_timer0
void timer0interrupt()           // #int_timer associates the following function with the
                                // interrupt service routine that should be called
enable_interrupts(TIMER0);      // enables the timer0 interrupt
disable_interrups(TIMER0);      // disables the timer0 interrupt
clear_interrupt(TIMER0);        // clears the timer0 interrupt flag
```

Low Voltage Detect

These functions configure the high/low voltage detect module. Functions available on the chips that have the low voltage detect hardware.

Relevant Functions:

setup_low_volt_detect(mode)	Sets the voltage trigger levels and also the mode (below or above in case of the high/low voltage detect module). The options vary depending on the chip and are listed in the device header files.
------------------------------------	---

Relevant Preprocessor:

None

Relevant Interrupts :

INT_LOWVOLT	Interrupt fires on low voltage detect
--------------------	---------------------------------------

Relevant Include Files:

None, all functions built-in

Relevant getenv() parameters:

None

Example Code:

```
For PIC18F8722
setup_low_volt_detect(LVD_36|LVD_TRIGGER_ABOVE
); //sets the trigger level as 3.6 volts and

//
trigger direction as above. The interrupt
//if enabled is fired
```

```
when the voltage is                                     //above 3.6 volts.
```

PMP/EPMP

The Parallel Master Port (PMP)/Enhanced Parallel Master Port (EPMP) is a parallel 8-bit/16-bit I/O module specifically designed to communicate with a wide variety of parallel devices. Key features of the PMP module are:

- 8 or 16 Data lines
- Up to 16 or 32 Programmable Address Lines
- Up to 2 Chip Select Lines
- Programmable Strobe option
- Address Auto-Increment/Auto-Decrement
- Programmable Address/Data Multiplexing
- Programmable Polarity on Control Signals
- Legacy Parallel Slave(PSP) Support
- Enhanced Parallel Slave Port Support
- Programmable Wait States

Relevant Functions:	
	This will setup the PMP/EPMP module for various mode and specifies which address lines to be used.
setup_psp (options,address_mask)	This will setup the PSP module for various mode and specifies which address lines to be used.
setup_pmp_csx(options,[off set])	Sets up the Chip Select X Configuration, Mode and Base Address registers
setup_psp_es(options)	Sets up the Chip Select X Configuration and Mode registers
	Write the data byte to the next buffer location.
	This will write a byte of data to the next buffer location or will write a byte to the specified buffer location.
	Reads a byte of data.
	psp_read() will read a byte of data from the next buffer location and psp_read (address) will read the buffer location address.
	Configures the address register of the PMP module with the destination address during Master mode operation.
	This will return the status of the output buffer underflow bit.
	This will return the status of the input buffers.

psp_input_full()	This will return the status of the input buffers.
psp_output_full()	This will return the status of the output buffers.
Relevant Preprocessor:	
None	
Relevant Interrupts :	
#INT_PMP	Interrupt on read or write strobe
Relevant Include Files:	None, all functions built-in
Relevant getenv() parameters:	
	None
Example Code:	<pre> setup pmp(PAR ENABLE // Sets up Master mode with // address lines PMA0:PMA7 PAR MASTER MODE 1 PAR STOP IN IDLE,0xFF); if (pmp_output_full()) { pmp_write(next_byte); } </pre>

Power PWM

These options lets the user configure the Pulse Width Modulation (PWM) pins. They are only available on devices equipped with PWM. The options for these functions vary depending on the chip and are listed in the device header file.

Relevant Functions:	
setup_power_pwm(config)	Sets up the PWM clock, period, dead time etc.
setup_power_pwm_pins(module x)	Configure the pins of the PWM to be in Complimentary, ON or OFF mode.
set_power_pwmx_duty(duty)	Stores the value of the duty cycle in the PDCXL/H register. This duty cycle value is the time for which the PWM is in active state.

set_power_pwm_override(pwm,override,value)	This function determines whether the OVDCONS or the PDC registers determine the PWM output .
Relevant Preprocessor:	None
Relevant Interrupts:	
#INT_PWMTB	PWM Timebase Interrupt (Only available on PIC18XX31)
Relevant getenv() Parameters:	None
Example Code:	<pre>..... long duty_cycle, period; ... // Configures PWM pins to be ON,OFF // or in Complimentary mode. setup_power_pwm_pins(PWM_COMPLEMENTARY ,PWM_OFF, PWM_OFF, PWM_OFF; // Sets up PWM clock , postscale and // period. Here period is used to set the // PWM Frequency as follows: // Frequency=Fosc/(4* (period+1) // *postscale) setup_power_pwm(PWM_CLOCK_DIV_4 PWM_FREE_ RUN,1,0,period,0,1,0); set_power_pwm0_duty(duty_cycle)); // Sets the duty cycle of the PWM 0,1 in // Complementary mode</pre>

Program Eeprom

The Flash program memory is readable and writable in some chips and is just readable in some. These options lets the user read and write to the Flash program memory. These functions are only available in flash chips.

Relevant Functions:	
read_program_eeprom(addr	Reads the program memory location (16 bit or 32 bit

ess)	depending on the device).
write_program_eeprom(addr ess, value)	Writes value to program memory location address.
erase_program_eeprom(addr ess)	Erases FLASH_ERASE_SIZE bytes in program memory.
write_program_memory(addr ess,dataptr,count)	Writes count bytes to program memory from dataptr to address. When address is a mutiple of FLASH_ERASE_SIZE an erase is also performed.
read_program_memory(addr ess,dataptr,count)	Read count bytes from program memory at address to dataptr.
Relevant Preprocessor:	
#ROM address={list}	Can be used to put program memory data into the hex file.
#DEVICE(WRITE_EEPROM= ASYNC)	Can be used with #DEVICE to prevent the write function from hanging. When this is used make sure the eeprom is not written both inside and outside the ISR.
Relevant Interrupts:	
INT_EEPROM	Interrupt fires when eeprom write is complete.
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters	
PROGRAM_MEMORY	Size of program memory
READ_PROGRAM	Returns 1 if program memory can be read
FLASH_WRITE_SIZE	Smallest number of bytes written in flash
FLASH_ERASE_SIZE	Smallest number of bytes erased in flash
Example Code:	
For 18F452 where the write size is 8 bytes and erase size is 64 bytes	
#rom 0xa00={1,2,3,4,5}	//inserts this data into the hex file.
erase_program_eeprom(0x1 000);	//erases 64 bytes strting at 0x1000
write_program_eeprom(0x10 00,0x1234);	//writes 0x1234 to 0x1000
value=read_program_eepro m(0x1000);	//reads 0x1000 returns 0x1234
write_program_memory(0x1 000,data,8);	//erases 64 bytes starting at 0x1000 as 0x1000 is a multiple

	//of 64 and writes 8 bytes from data to 0x1000
read_program_memory(0x1000,value,8);	//reads 8 bytes to value from 0x1000
erase_program_eeprom(0x1000);	//erases 64 bytes starting at 0x1000
write_program_memory(0x1010,data,8);	//writes 8 bytes from data to 0x1000
read_program_memory(0x1000,value,8);	//reads 8 bytes to value from 0x1000
For chips where getenv("FLASH_ERASE_SIZE") > getenv("FLASH_WRITE_SIZE")	
WRITE_PROGRAM_EEPROM -	Writes 2 bytes,does not erase (use ERASE_PROGRAM_EEPROM)
WRITE_PROGRAM_MEMORY -	Writes any number of bytes,will erase a block whenever the first (lowest) byte in a block is written to. If the first address is not the start of a block that block is not erased.
ERASE_PROGRAM_EEPROM -	Will erase a block. The lowest address bits are not used.
For chips where getenv("FLASH_ERASE_SIZE") = getenv("FLASH_WRITE_SIZE")	
WRITE_PROGRAM_EEPROM -	Writes 2 bytes, no erase is needed.
WRITE_PROGRAM_MEMORY -	Writes any number of bytes, bytes outside the range of the write block are not changed. No erase is needed.
ERASE_PROGRAM_EEPROM -	Not available.

PSP

These options let to configure and use the Parallel Slave Port on the supported devices.

Relevant Functions:	
setup_psp(mode)	Enables/disables the psp port on the chip
psp_output_full()	Returns 1 if the output buffer is full(waiting to be read by the external bus)
psp_input_full()	Returns 1 if the input buffer is full(waiting to read by the cpu)
psp_overflow()	Returns 1 if a write occurred before the previously written byte was read
Relevant Preprocessor:	None

Relevant Interrupts :

INT_PSP Interrupt fires when PSP data is in

Relevant Include Files: None, all functions built-in

Relevant getenv() parameters: PSP

Returns 1 if the device has PSP

Example Code:

```
while(psp_output_full()); //waits
till the output buffer is cleared
psp_data=command; //writes to
the port
while(!input_buffer_full()); //waits
till input buffer is cleared
if (psp_overflow())
    error=true //if there is
an overflow set the error flag
else
    data=psp_data; //if there is
no overflow then read the port
```

QEI

The Quadrature Encoder Interface (QEI) module provides the interface to incremental encoders for obtaining mechanical positional data.

Relevant Functions:

setup_qei(options, filter,maxcount) Configures the QEI module.

qei_status() Returns the status of the QEI module.

qei_set_count(value) Write a 16-bit value to the position counter.

qei_get_count() Reads the current 16-bit value of the position counter.

Relevant Preprocessor: None

Relevant Interrupts : #INT_QEI - Interrupt on rollover or underflow of the position counter

Relevant Include Files: None, all functions built-in

Relevant getenv() parameters:	None
Example Code:	<pre>int16 value; setup_qei(QEI_MODE_X2 //Setup the QEI module QEI_TIMER_INTERNAL, QEI_FILTER_DIV_2,QEI_FORWARD); Value=qei_get_count(); //Read the count</pre>

RS232 I/O

These functions and directives can be used for setting up and using RS232 I/O functionality.

Relevant Functions:

getc() or getch() getchar() or fgetc()	Gets a character on the receive pin (from the specified stream in case of fgetc, stdin by default). Use KBHIT to check if the character is available.
gets() or fgets()	Gets a string on the receive pin (from the specified stream in case of fgets, STDIN by default). Use getc to receive each character until return is encountered.
putc() or putchar() or fputc()	Puts a character over the transmit pin (on the specified stream in the case of fputc, stdout by default)
puts() or fputs()	Puts a string over the transmit pin (on the specified stream in the case of fputc, stdout by default). Uses putc to send each character.
printf() or fprintf()	Prints the formatted string (on the specified stream in the case of fprintf, stdout by default). Refer to the printf help for details on format string.

kbhit()	Return true when a character is received in the buffer in case of hardware RS232 or when the first bit is sent on the RCV pin in case of software RS232. Useful for polling without waiting in getc.
setup_uart(baud,[stream])	
or	
setup_uart_speed(baud,[stream])	Used to change the baud rate of the hardware UART at run-time. Specifying stream is optional. Refer to the help for more advanced options.
assert(condition)	Checks the condition and if false prints the file name and line to STDERR. Will not generate code if #DEFINE NODEBUG is used.
perror(message)	Prints the message and the last system error to STDERR.
putc_send() or fputc_send()	When using transmit buffer, used to transmit data from buffer. See function description for more detail on when needed.
rcv_buffer_bytes()	When using receive buffer, returns the number of bytes in buffer that still need to be retrieved.
tx_buffer_bytes()	When using transmit buffer, returns the number of bytes in buffer that still need to be sent.
tx_buffer_full()	When using transmit buffer, returns TRUE if transmit buffer is full.
receive_buffer_full()	When using receive buffer, returns TRUE if receive buffer is full.
tx_buffer_available()	When using transmit buffer, returns number of characters that can be put into transmit buffer before it overflows.
#useRS232	Configures the compiler to support RS232 to specifications.
Relevant Interrupts:	
INT_RDA	Interrupt fires when the receive data available

INT_TBE	Interrupt fires when the transmit data empty
----------------	--

Some chips have more than one hardware UART, and hence more interrupts.

Relevant Include Files:

None, all functions built-in

Relevant getenv() parameters:

UART	Returns the number of UARTs on this PIC
AUART	Returns true if this UART is an advanced UART
UART_RX	Returns the receive pin for the first UART on this PIC (see PIN_XX)
UART_TX	Returns the transmit pin for the first UART on this PIC
UART2_RX	Returns the receive pin for the second UART on this PIC
UART2_TX	TX – Returns the transmit pin for the second UART on this PIC

Example Code:

```
/*configure and enable uart, use first hardware UART on PIC*/
#include rs232(uart1, baud=9600)

/* print a string*/
printf("enter a character");

/* get a character*/
if (kbhit())
has been received
c=getc();
UART
//check if a character
//read character from
```

RTOS

These functions control the operation of the CCS Real Time Operating System (RTOS). This operating system is cooperatively multitasking and allows for tasks to be scheduled to run at specified time intervals. Because the RTOS does not use interrupts, the user must be careful to make use of the `rtos_yield()` function in every task so that no one task is allowed to run forever.

Relevant Functions:

rtos_run()	Begins the operation of the RTOS. All task management tasks are implemented by this function.
rtos_terminate()	This function terminates the operation of the RTOS and returns operation to the original program. Works as a return from the <code>rtos_run()</code> function.
rtos_enable(task)	Enables one of the RTOS tasks. Once a task is enabled, the <code>rtos_run()</code> function will call the task when its time occurs. The parameter to this function is the name of task to be enabled.
rtos_disable(task)	Disables one of the RTOS tasks. Once a task is disabled, the <code>rtos_run()</code> function will not call this task until it is enabled using <code>rtos_enable()</code> . The parameter to this function is the name of the task to be disabled.
rtos_msg_poll()	Returns true if there is data in the task's message queue.
rtos_msg_read()	Returns the next byte of data contained in the task's message queue.
rtos_msg_send(task, byte)	Sends a byte of data to the specified task. The data is placed in the receiving task's message queue.
rtos_yield()	Called with in one of the RTOS tasks and returns control of the program to the <code>rtos_run()</code> function. All tasks should call this function when finished.
rtos_signal(sem)	Increments a semaphore which is used to broadcast the availability of a limited resource.
rtos_wait(sem)	Waits for the resource associated with the semaphore to become available and then decrements to semaphore to

	claim the resource.
rtos_await(expre)	Will wait for the given expression to evaluate to true before allowing the task to continue.
rtos_overrun(task)	Will return true if the given task over ran its allotted time.
rtos_stats(task,stat)	Returns the specified statistic about the specified task. The statistics include the minimum and maximum times for the task to run and the total time the task has spent running.
Relevant Preprocessor:	
#USE RTOS(options)	This directive is used to specify several different RTOS attributes including the timer to use, the minor cycle time and whether or not statistics should be enabled.
#TASK(options)	This directive tells the compiler that the following function is to be an RTOS task.
#TASK	specifies the rate at which the task should be called, the maximum time the task shall be allowed to run, and how large it's queue should be
Relevant Interrupts:	
none	
Relevant Include Files:	
none all functions are built in	
Relevant getenv()	
Parameters:	
none	
Example Code:	
#USE RTOS(timer=0,minor_cyc // RTOS will use timer zero, minor cycle will be 20ms le=20ms)	
...	
int sem;	
...	
#TASK(rate=1s,max=20m // Task will run at a rate of once per second s,queue=5)	
void task_name(); // with a maximum running time of 20ms and	
rtos_run(); // begins the RTOS	
rtos_terminate(); // ends the RTOS	

rtos_enable(task_name);	// enables the previously declared task.
rtos_disable(task_name)	// disables the previously declared task
;	
rtos_msg_send(task_name,5);	// places the value 5 in task_names queue.
rtos_yield();	// yields control to the RTOS
rtos_sigal(sem);	// signals that the resource represented by sem is available.

For more information on the CCS RTOS please

SPI

SPI™ is a fluid standard for 3 or 4 wire, full duplex communications named by Motorola. Most PIC devices support most common SPI™ modes. CCS provides a support library for taking advantage of both hardware and software based SPI™ functionality. For software support, see [#USE SPI](#).

Relevant Functions:

setup_spi(mode) setup_spi2(mode) setup_spi3 (mode) setup_spi4 (mode)	Configure the hardware SPI to the specified mode. The mode configures setup_spi2(mode) thing such as master or slave mode, clock speed and clock/data trigger configuration.
---	--

Note: for devices with dual SPI interfaces a second function, **setup_spi2()**, is provided to configure the second interface.

spi_data_is_in()	Returns TRUE if the SPI receive buffer has a byte of data.
-------------------------	--

spi_data_is_in2()

spi_write(value) spi_write2(value)	Transmits the value over the SPI interface. This will cause the data to be clocked out on the SDO pin.
---	--

spi_read(value) spi_read2(value)	Performs an SPI transaction, where the value is clocked out on the SDO pin and data clocked in on the SDI pin is returned. If you just want to clock in data then you can use spi_read() without a parameter.
---	---

Relevant Preprocessor:

None

Relevant Interrupts:

#int_ssp	Transaction (read or write) has completed on the indicated peripheral.
#int_ssp2	

Relevant getenv() Parameters:

SPI	Returns TRUE if the device has an SPI peripheral
------------	--

Example Code:

//configure the device to be a master, data transmitted on H-to-L clock transition
setup_spi(SPI_MASTER | SPI_H_TO_L | SPI_CLK_DIV_16);

spi_write(0x80);	//write 0x80 to SPI device
value=spi_read();	//read a value from the SPI device
value=spi_read(0x80);	//write 0x80 to SPI device the same time you are reading a value.

Timer0

These options lets the user configure and use timer0. It is available on all devices and is always enabled. The clock/counter is 8-bit on pic16s and 8 or 16 bit on pic18s. It counts up and also provides interrupt on overflow. The options available differ and are listed in the device header file.

Relevant Functions:

setup_timer_0(mode)	Sets the source, prescale etc for timer0
set_timer0(value) or set_rtcc(value)	Initializes the timer0 clock/counter. Value may be a 8 bit or 16 bit depending on the device.

value=get_timer0	Returns the value of the timer0 clock/counter
-------------------------	---

Relevant Preprocessor:	None
------------------------	------

Relevant Interrupts :

INT_TIMER0 or INT_RTCC	Interrupt fires when timer0 overflows
-------------------------------	---------------------------------------

Relevant Include Files:

None, all functions built-in

Relevant getenv() parameters:

TIMER0	Returns 1 if the device has timer0
Example Code: For PIC18F452	
setup_timer_0(RTCC_INTERNAL RTCC_DIV_2 RTCC_8_BIT);	//sets the internal clock as source //and prescale 2. At 20Mhz timer0 //will increment every 0.4us in this //setup and overflows every //102.4us
set_timer0(0);	//this sets timer0 register to 0
time=get_timer0();	//this will read the timer0 register //value

Timer1

These options lets the user configure and use timer1. The clock/counter is 16-bit on pic16s and pic18s. It counts up and also provides interrupt on overflow. The options available differ and are listed in the device header file.

Relevant Functions:	
setup_timer_1(mode)	Disables or sets the source and prescale for timer1
set_timer1(value)	Initializes the timer1 clock/counter
value=get_timer1	Returns the value of the timer1 clock/counter
Relevant Preprocessor:	
None	
Relevant Interrupts:	
INT_TIMER1	Interrupt fires when timer1 overflows
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters:	
TIMER1	Returns 1 if the device has timer1
Example Code: For PIC18F452	

setup_timer_1(T1_DISABLED);	//disables timer1
or	
setup_timer_1(T1_INTERNAL T1_DIV_BY_8);	//sets the internal clock as source
	//and prescale as 8. At 20Mhz timer1 will increment
	//every 1.6us in this setup and overflows every
	//104.896ms
set_timer1(0);	//this sets timer1 register to 0
time=get_timer1();	//this will read the timer1 register value

Timer2

These options lets the user configure and use timer2. The clock/counter is 8-bit on pic16s and pic18s. It counts up and also provides interrupt on overflow. The options available differ and are listed in the device header file.

Relevant Functions:	
setup_timer_2(mode,period,postscale)	Disables or sets the prescale, period and a postscale for timer2
set_timer2(value)	Initializes the timer2 clock/counter
value=get_timer2	Returns the value of the timer2 clock/counter
Relevant Preprocessor:	
None	
Relevant Interrupts:	
INT_TIMER2	Interrupt fires when timer2 overflows
Relevant Include Files:	
None, all functions built-in	
Relevant getenv() parameters:	
TIMER2	Returns 1 if the device has timer2
Example Code:	
For PIC18F452	
setup_timer_2(T2_DISABLED);	//disables timer2
or	
setup_timer_2(T2_DIV_BY_4,0x	//sets the prescale as 4, period as 0xc0 and

c0,2);	//postscales as 2.
	//At 20Mhz timer2 will increment every .8us in this
	//setup overflows every 154.4us and interrupt every 308.2us
set_timer2(0);	//this sets timer2 register to 0
time=get_timer2();	//this will read the timer1 register value

Timer3

Timer3 is very similar to timer1. So please refer to the [Timer1](#) section for more details.

Timer4

Timer4 is very similar to Timer2. So please refer to the [Timer2](#) section for more details.

Timer5

These options lets the user configure and use timer5. The clock/counter is 16-bit and is available only on 18Fxx31 devices. It counts up and also provides interrupt on overflow. The options available differ and are listed in the device header file.

Relevant Functions:	
setup_timer_5(mode)	Disables or sets the source and prescale for timer5
set_timer5(value)	Initializes the timer5 clock/counter
value=get_timer5	Returns the value of the timer51 clock/counter
Relevant Preprocessor:	
None	
Relevant Interrupts :	
INT_TIMER5	Interrupt fires when timer5 overflows
Relevant Include Files:	
None, all functions built-in	

Relevant getenv() parameters:

TIMER5

Returns 1 if the device has timer5

Example Code:

For PIC18F4431

setup_timer_5(T5_DISABLED) //disables timer5

or

setup_timer_5(T5_INTERNAL|T5 //sets the internal clock as source and
_DIV_BY_1); //prescale as 1.

//At 20Mhz timer5 will increment every .2us in this

//setup and overflows every 13.1072ms

set_timer5(0); //this sets timer5 register to 0

time=get_timer5(); //this will read the timer5 register value

TimerA

These options lets the user configure and use timerA. It is available on devices with Timer A hardware. The clock/counter is 8 bit. It counts up and also provides interrupt on overflow. The options available are listed in the device's header file.

Relevant Functions:

setup_timer_A(mode) Disable or sets the source and prescale for timerA

set_timerA(value) Initializes the timerA clock/counter

value=get_timerA() Returns the value of the timerA clock/counter

Relevant Preprocessor:

None

Relevant Interrupts :

INT_TIMER_A Interrupt fires when timerA overflows

Relevant Include Files: None, all functions built-in

Relevant getenv()
parameters:

TIMER_A Returns 1 if the device has timerA

Example Code:

setup_timer_A(TA_OFF); //disable timerA

or

setup_timer_A //sets the internal clock as source

(TA_INTERNAL TA_DIV_8);	//and prescale as 8. At 20MHz timerA will increment //every 1.6us in this setup and overflows every //409.6us
set_timerA(0);	//this sets timerA register to 0
time=get_timerA();	//this will read the timerA register value

TimerB

These options lets the user configure and use timerB. It is available on devices with TimerB hardware. The clock/counter is 8 bit. It counts up and also provides interrupt on overflow. The options available are listed in the device's header file.

Relevant Functions:

setup_timer_B(mode)	Disable or sets the source and prescale for timerB
set_timerB(value)	Initializes the timerB clock/counter
value=get_timerB()	Returns the value of the timerB clock/counter

Relevant Preprocessor:

None

Relevant Interrupts :

INT_TIMERB	Interrupt fires when timerB overflows
-------------------	---------------------------------------

Relevant Include Files: None, all functions built-in

Relevant getenv()
parameters:

TIMERB	Returns 1 if the device has timerB
---------------	------------------------------------

Example Code:

setup_timer_B(TB_OFF);	//disable timerB
or	
setup_timer_B	//sets the internal clock as source
(TB_INTERNAL TB_DIV_8);	//and prescale as 8. At 20MHz timerB will increment //every 1.6us in this setup and overflows every //409.6us
set_timerB(0);	//this sets timerB register to 0

```
time=get_timerB();      //this will read the timerB register value
```

USB

Universal Serial Bus, or USB, is used as a method for peripheral devices to connect to and talk to a personal computer. CCS provides libraries for interfacing a PIC to PC using USB by using a PIC with an internal USB peripheral (like the PIC16C765 or the PIC18F4550 family) or by using any PIC with an external USB peripheral (the National USBN9603 family).

Relevant Functions:

usb_init()	Initializes the USB hardware. Will then wait in an infinite loop for the USB peripheral to be connected to bus (but that doesn't mean it has been enumerated by the PC). Will enable and use the USB interrupt.
-------------------	---

usb_init_cs()	The same as usb_init(), but does not wait for the device to be connected to the bus. This is useful if your device is not bus powered and can operate without a USB connection.
----------------------	---

usb_task()	If you use connection sense, and the usb_init_cs() for initialization, then you must periodically call this function to keep an eye on the connection sense pin. When the PIC is connected to the BUS, this function will then prepare the USB peripheral. When the PIC is disconnected from the BUS, it will reset the USB stack and peripheral. Will enable and use the USB interrupt.
-------------------	--

Note: In your application you must define USB_CON_SENSE_PIN to the connection sense pin.

usb_detach()	Removes the PIC from the bus. Will be called automatically by usb_task() if connection is lost, but can be called manually by the user.
---------------------	---

usb_attach()	Attaches the PIC to the bus. Will be called automatically by usb_task() if connection is made, but can be called manually by the user.
---------------------	--

usb_attached()	If using connection sense pin (USB_CON_SENSE_PIN), returns TRUE if that pin is high. Else will always return TRUE.
-----------------------	--

usb_enumerated()	Returns TRUE if the device has been enumerated by the PC. If the device has been enumerated by the PC, that means it is in normal operation mode and you can send/receive packets.
usb_put_packet(endpoint, data, len, tgl)	Places the packet of data into the specified endpoint buffer. Returns TRUE if success, FALSE if the buffer is still full with the last packet.
usb_puts(endpoint, data, len, timeout)	Sends the following data to the specified endpoint. <code>usb_puts()</code> differs from <code>usb_put_packet()</code> in that it will send multi packet messages if the data will not fit into one packet.
usb_kbhit(endpoint)	Returns TRUE if the specified endpoint has data in it's receive buffer
usb_get_packet(endpoint, ptr, max)	Reads up to max bytes from the specified endpoint buffer and saves it to the pointer ptr. Returns the number of bytes saved to ptr.
usb_gets(endpoint, ptr, max, timeout)	Reads a message from the specified endpoint. The difference <code>usb_get_packet()</code> and <code>usb_gets()</code> is that <code>usb_gets()</code> will wait until a full message has received, which a message may contain more than one packet. Returns the number of bytes received.
Relevant CDC Functions:	
A CDC USB device will emulate an RS-232 device, and will appear on your PC as a COM port. The follow functions provide you this virtual RS-232/serial interface	
Note: When using the CDC library, you can use the same functions above, but do not use the packet related function such as <code>usb_kbhit()</code>, <code>usb_get_packet()</code>, etc.	
usb_cdc_kbhit()	The same as <code>kbhit()</code> , returns TRUE if there is 1 or more character in the receive buffer.
usb_cdc_getc()	The same as <code>getc()</code> , reads and returns a character from the receive buffer. If there is no data in the receive buffer it will wait indefinitely until there a character has been received.
usb_cdc_putc(c)	The same as <code>putc()</code> , sends a character. It actually puts a character into the transmit buffer, and if the transmit buffer is

	full will wait indefinitely until there is space for the character.
usb_cdc_putc_fast(c)	The same as <code>usb_cdc_putc()</code> , but will not wait indefinitely until there is space for the character in the transmit buffer. In that situation the character is lost.
usb_cdc_puts(*str)	Sends a character string (null terminated) to the USB CDC port. Will return FALSE if the buffer is busy, TRUE if buffer is string was put into buffer for sending. Entire string must fit into endpoint, if string is longer than endpoint buffer then excess characters will be ignored.
usb_cdc_putready()	Returns TRUE if there is space in the transmit buffer for another character.
Relevant Preprocessor: None	
Relevant Interrupts:	
#int_usb	A USB event has happened, and requires application intervention. The USB library that CCS provides handles this interrupt automatically.
Relevant Include files:	
pic_usb.h	Hardware layer driver for the PIC16C765 family PICmicro controllers with an internal USB peripheral.
pic18_usb.h	Hardware layer driver for the PIC18F4550 family PICmicro controllers with an internal USB peripheral.
usbn960x.h	Hardware layer driver for the National USBN9603/USBN9604 external USB peripheral. You can use this external peripheral to add USB to any microcontroller.
usb.h	Common definitions and prototypes used by the USB driver
usb.c	The USB stack, which handles the USB interrupt and USB Setup Requests on Endpoint 0.
usb_cdc.h	A driver that takes the previous include files to make a CDC USB device, which emulates an RS232 legacy device and shows up as a COM port in the MS Windows device manager.
Relevant getenv() Parameters:	

USB	Returns TRUE if the PICmicro controller has an integrated internal USB peripheral.
Example Code: Due to the complexity of USB example code will not fit here. But you can find the following examples installed with your CCS C Compiler:	
ex_usb_hid.c	A simple HID device
ex_usb_mouse.c	A HID Mouse, when connected to your PC the mouse cursor will go in circles.
ex_usb_kbmouse.c	An example of how to create a USB device with multiple interfaces by creating a keyboard and mouse in one device.
ex_usb_kbmouse2.c	An example of how to use multiple HID report Ids to transmit more than one type of HID packet, as demonstrated by a keyboard and mouse on one device.
ex_usb_scope.c	A vendor-specific class using bulk transfers is demonstrated.
ex_usb_serial.c	The CDC virtual RS232 library is demonstrated with this RS232 < - > USB example.
ex_usb_serial2.c	Another CDC virtual RS232 library example, this time a port of the ex_intee.c example to use USB instead of RS232.

Voltage Reference

These functions configure the voltage reference module. These are available only in the supported chips.

Relevant Functions:

setup_vref(mode value)	Enables and sets up the internal voltage reference value. Constants are defined in the device's .h file.
---------------------------------	--

Relevant Preprocessor:

None

Relevant Interrupts:

None

Relevant Include Files:

None, all functions built-in

Relevant getenv()

parameters:

VREF Returns 1 if the device has VREF

```
#INT_COMP //comparator interrupt handler
void isr() {
    safe_conditions = FALSE;
    printf("WARNING!!!! Voltage level is
above 3.6V. \r\n");
}
```

Example code: for PIC12F675

```
setup_comparator(A1_VR_OUT_ON_A2)//sets 2
comparators(A1 and VR and A2 as output)
{
    setup_vref(VREF_HIGH | 15);//sets
3.6(vdd * value/32 + vdd/4) if vdd is 5.0V
    enable_interrupts(INT_COMP); // enable
the comparator interrupt
    enable_interrupts(GLOBAL); //enable
global interrupts
}
```

WDT or Watch Dog Timer

Different chips provide different options to enable/disable or configure the WDT.

Relevant Functions:

setup_wdt()	Enables/disables the wdt or sets the prescaler.
restart_wdt()	Restarts the wdt, if wdt is enables this must be periodically called to prevent a timeout reset.

For PCB/PCM chips it is enabled/disabled using WDT or NOWDT fuses whereas on PCH device it is done using the setup_wdt function.

The timeout time for PCB/PCM chips are set using the setup_wdt function and on PCH using fuses like WDT16, WDT256 etc.

RESTART_WDT when specified in #USE DELAY, #USE I2C and #USE RS232 statements like this #USE DELAY(clock=2000000, restart_wdt) will cause the wdt

to restart if it times out during the delay or I2C_READ or GETC.

Relevant Preprocessor:

#FUSES WDT/NOWDT Enabled/Disables wdt in PCB/PCM devices

#FUSES WDT16

Sets up the timeout time in PCH devices

Relevant Interrupts: None

Relevant Include Files: None, all functions built-in

Relevant getenv()
parameters: None

Example Code: **for
PIC16F877**

```
#fuses wdt  setup_wdt(WDT_2304MS);
while(true){
    restart_wdt();
    perform_activity();
}
```

For PIC18F452

```
#fuse WDT1
setup_wdt(WDT_ON);
while(true){
    restart_wdt();
    perform_activity();
}
```

interrupt_enabled()

This function checks the interrupt enabled flag for the specified interrupt and returns TRUE if set.

Syntax	interrupt_enabled(interrupt);
Parameters	interrupt- constant specifying the interrupt
Returns	Boolean value
Function	The function checks the interrupt enable flag of the specified interrupt and returns TRUE when set.
Availability	Devices with interrupts
Requires	Interrupt constants defined in the device's .h file.
Examples	if(interrupt_enabled(INT_RDA)) disable_interrupt(INT_RDA);
Example Files	None
Also see	DISABLE_INTERRUPTS() , , Interrupts Overview ,

[CLEAR_INTERRUPT\(\)](#),
[ENABLE_INTERRUPTS\(\)](#), [INTERRUPT_ACTIVE\(\)](#)

Stream I/O

Syntax:	#include <ios.h> is required to use any of the ios identifiers.
----------------	--

output:

stream << variable_or_constant_or_manipulator ;

one or more repeats

stream may be the name specified in the #use RS232 stream= option or for the default stream use cout.

stream may also be the name of a char array. In this case the data is written to the array with a 0 terminator.

stream may also be the name of a function that accepts a single char parameter. In this case the function is called for each character to be output.

Output:

variables/constants: May be any integer, char, float or fixed type. Char arrays are output as strings and all other types are output as an address of the variable.

manipulators:

hex -Hex format numbers

dec- Decimal format numbers (default)

setprecision(x) -Set number of places after the decimal point

setw(x) -Set total number of characters output for numbers

boolalpha- Output int1 as true and false

noboolalpha -Output int1 as 1 and 0 (default)

fixed Floats- in decimal format (default)

scientific Floats- use E notation

iosdefault- All manipulators to default settings

endl -Output CR/LF

ends- Outputs a null ('\000')

Examples:

```
cout << "Value is " << hex << data << endl;
cout << "Price is $" << setw(4) << setprecision(2) << cost << endl;
lcdputc << '\f' << setw(3) << count << " " << min << " " << max;
string1 << setprecision(1) << sum / count;
```

```
string2 << x << ',' << y;
```

```
stream >> variable_or_constant_or_manipulator ;
```

one or more repeats

stream may be the name specified in the #use RS232 stream= option or for the default stream use cin.

stream may also be the name of a char array. In this case the data is read from the array up to the 0 terminator.

stream may also be the name of a function that returns a single char and has no parameters. In this case the function is called for each character to be input.

Make sure the function returns a \r to terminate the input statement.

Input:

variables/constants: May be any integer, char, float or fixed type. Char arrays are

input as strings. Floats may use the E format.

Reading of each item terminates with any character not valid for the type.

Usually

items are separated by spaces. The termination character is discarded. At the end

of any stream input statement characters are read until a return (\r) is read.

No

termination character is read for a single char input.

manipulators:

hex -Hex format numbers

dec- Decimal format numbers (default)

noecho- Suppress echoing

strspace- Allow spaces to be input into strings

nostrspace- Spaces terminate string entry (default)

iosdefault -All manipulators to default settings

```
cout << "Enter number: ";
```

```
cin >> value;
```

```
cout << "Enter title: ";
```

```
cin >> strspace >> title;
```

```
cin >> data[i].recordid >> data[i].xpos >> data[i].ypos >> data[i].sample ;
```

```
string1 >> data;
```

```
lcdputc << "\fEnter count";
```

```
lcdputc << keypadgetc >> count; // read from keypad, echo to lcd
```

```
// This syntax only works with
```

```
// user defined functions.
```

Examples:

PREPROCESSOR

PRE-PROCESSOR DIRECTORY

Pre-processor directives all begin with a # and are followed by a specific command. Syntax is dependent on the command. Many commands do not allow other syntactical elements on the remainder of the line. A table of commands and a description is listed on the previous page.

Several of the pre-processor directives are extensions to standard C. C provides a pre-processor directive that compilers will accept and ignore or act upon the following data. This implementation will allow any pre-processor directives to begin with #PRAGMA. To be compatible with other compilers, this may be used before non-standard features.

Examples:

Both of the following are valid

```
#INLINE
```

```
#PRAGMA INLINE
```

__address__

A predefined symbol __address__ may be used to indicate a type that must hold a program memory address.

For example:

```
__address__ testa = 0x1000 //will allocate 16 bits for  
test a and                //initialize to 0x1000
```

`__attribute__ x`

Syntax:	<code>__attribute__ x</code> x is the attribute you want to apply. Valid values for x are as follows: ((packed)) By default each element in a struct or union are padded to be evenly spaced by the size of 'int'. This is to prevent an address fault when accessing an element of struct. See the following example: struct { int8 a; int16 b; } test; On architectures where 'int' is 16bit (such as dsPIC or PIC24 PICmicrocontrollers), 'test' would take 4 bytes even though it is comprised of 3 bytes. By applying the 'packed' attribute to this struct then it would take 3 bytes as originally intended: struct __attribute__((packed)) { int8 a; int16 b; } test; Care should be taken by the user when accessing individual elements of a packed struct – creating a pointer to 'b' in 'test' and attempting to dereference that pointer would cause an address fault. Any attempts to read/write 'b' should be done in context of 'test' so the compiler knows it is packed: test.b = 5; ((aligned(y)) By default the compiler will allocate a variable in the first free memory location. The aligned attribute will force the compiler to allocate a location for the specified variable at a location that is modulus of the y parameter. For example: int8 array[256] __attribute__((aligned(0x1000))); This will tell the compiler to try to place 'array' at either 0x0, 0x1000, 0x2000, 0x3000, 0x4000, etc.
Purpose	To alter some specifics as to how the compiler operates struct __attribute__((packed)) { int8 a; int8 b; }
Examples:	

	<pre> } test; int8 array[256] __attribute__((aligned(0x1000))); </pre>
Example Files:	None

#asm #endasm #asm asis

Syntax:	#ASM or #ASM ASIS code #ENDASM
Elements:	code is a list of assembly language instructions

Examples:	<pre> int find_parity(int data){ int count; #asm MOV #0x08, W0 MOV W0, count CLR W0 loop: XOR.B data,W0 RRC data,W0 DEC count,F BRA NZ, loop MOV #0x01,W0 ADD count,F MOV count, W0 MOV W0, __RETURN__ #endasm } </pre>
------------------	--

Example Files:	FFT.c
Also See:	None

12 Bit and 14 Bit	
ADDWF f,d	ANDWF f,d
CLRF f	CLRWF
COMF f,d	DECF f,d
DECFSZ f,d	INCF f,d
INCFSZ f,d	IORWF f,d
MOVF f,d	MOVPHW
MOVPLW	MOVWF f
NOP	RLF f,d
RRF f,d	SUBWF f,d
SWAPF f,d	XORWF f,d
BCF f,b	BSF f,b
BTFSC f,b	BTFSS f,b
ANDLW k	CALL k
CLRWDT	GOTO k
IORLW k	MOVLW k
RETLW k	SLEEP
XORLW	OPTION
TRIS k	
14 Bit	
	ADDLW k
	SUBLW k
	RETFIE
	RETURN

f	may be a constant (file number) or a simple variable
d	may be a constant (0 or 1) or W or F
f,b	may be a file (as above) and a constant (0-7) or it may be just a bit variable reference.
k	may be a constant expression

Note that all expressions and comments are in C like syntax.

PIC 18					
ADDWF	f,d	ADDWFC	f,d	ANDWF	f,d
CLRF	f	COMF	f,d	CPFSEQ	f
CPFSGT	f	CPFSLT	f	DECf	f,d
DECFSZ	f,d	DCFSNZ	f,d	INCF	f,d
INFSNZ	f,d	IORWF	f,d	MOVf	f,d
MOVFF	fs,d	MOVWF	f	MULWF	f
NEGF	f	RLCF	f,d	RLNCF	f,d
RRCF	f,d	RRNCF	f,d	SETf	f

SUBFWB	f,d	SUBWF	f,d	SUBWFB	f,d
SWAPF	f,d	TSTFSZ	f	XORWF	f,d
BCF	f,b	BSF	f,b	BTFSZ	f,b
BTFSZ	f,b	BTG	f,d	BC	n
BN	n	BNC	n	BNN	n
BNOV	n	BNZ	n	BOV	n
BRA	n	BZ	n	CALL	n,s
CLRWDI	-	DAW	-	GOTO	n
NOP	-	NOP	-	POP	-
PUSH	-	RCALL	n	RESET	-
RETFIE	s	RETLW	k	RETURN	s
SLEEP	-	ADDLW	k	ANDLW	k
IORLW	k	LFSR	f,k	MOVLB	k
MOVLW	k	MULLW	k	RETLW	k
SUBLW	k	XORLW	k	TBLRD	*
TBLRD	*+	TBLRD	*-	TBLRD	+*
TBLWT	*	TBLWT	*+	TBLWT	*-
TBLWT	+*				

The compiler will set the access bit depending on the value of the file register.

If there is just a variable identifier in the #asm block then the compiler inserts an & before it. And if it is an expression it must be a valid C expression that evaluates to a constant (no & here). In C an un-subscripted array name is a pointer and a constant (no need for &).

#bit

Syntax: **#BIT** *id* = *x.y*

Elements: *id* is a valid C identifier,
x is a constant or a C variable,
y is a constant 0-7

Purpose: A new C variable (one bit) is created and is placed in memory at byte *x* and bit *y*. This is useful to gain access in C directly to a bit in the processors special function register map. It may also be used to easily access a bit of a standard C variable.

Examples: #bit T0IF = 0x b.2

```
...
T1IF = 0; // Clear Timer 0 interrupt flag

int result;
#bit result odd = result.0
...
if (result_odd)
```

Example

Files: [ex_glint.c](#)

Also See: [#BYTE](#), [#RESERVE](#), [#LOCATE](#), [#WORD](#)

__buildcount__

Only defined if Options>Project Options>Global Defines has global defines enabled.

This id resolves to a number representing the number of successful builds of the project.

#build

Syntax:	#BUILD (<i>segment</i> = <i>address</i>) #BUILD (<i>segment</i> = <i>address</i> , <i>segment</i> = <i>address</i>) #BUILD (<i>segment</i> = <i>start: end</i>) #BUILD (<i>segment</i> = <i>start: end</i> , <i>segment</i> = <i>start: end</i>) #BUILD (<i>nosleep</i>)
Elements:	<p>segment is one of the following memory segments which may be assigned a location: MEMORY, RESET, or INTERRUPT</p> <p>address is a ROM location memory address. Start and end are used to specify a range in memory to be used.</p> <p>start is the first ROM location and end is the last ROM location to be used.</p> <p>nosleep is used to prevent the compiler from inserting a sleep at the end of main()</p> <p>Bootload produces a bootloader-friendly hex file (in order, full block size).</p>

NOSLEEP_LOCK is used instead of A sleep at the end of a main A infinite loop.

Purpose:

PIC18XXX devices with external ROM or PIC18XXX devices with no internal ROM can direct the compiler to utilize the ROM. When linking multiple compilation units, this directive must appear exactly the same in each compilation unit.

Examples:

```
#build(memory=0x20000:0x2FFFF) //Assigns memory space
#build(reset=0x200,interrupt=0x208) //Assigns start
//location
//of reset and
//interrupt
//vectors
#build(reset=0x200:0x207, interrupt=0x208:0x2ff)
//Assign limited space
//for reset and
//interrupt vectors.
#build(memory=0x20000:0x2FFFF) //Assigns memory space
```

Example

None

Files:**Also See:**

[#LOCATE](#), [#RESERVE](#), [#ROM](#), [#ORG](#)

#byte

Syntax:

#byte *id* = *x*

Elements:

id is a valid C identifier,
x is a C variable or a constant

Purpose:

If the *id* is already known as a C variable then this will locate the variable at address *x*. In this case the variable type does not change from the original definition. If the *id* is not known a new C variable is created and placed at address *x* with the type `int` (8 bit)

Warning: In both cases memory at *x* is not exclusive to this variable. Other variables may be located at the same location. In fact when *x* is a variable, then *id* and *x* share the same memory location.

Examples:	<pre>#byte status = 3 #byte b_port = 6 struct { short int r_w; short int c_d; int unused : 2; int data : 4 ; } a_port; #byte a_port = 5 ... a_port.c_d = 1;</pre>
	Example Files: ex_glint.c
	Also See: #bit , #locate , #reserve , #word , Named Registers , Type Specifiers , Type Qualifiers , Enumerated Types , Structures & Unions , Typedef

#case

Syntax:	#CASE
Elements:	None
Purpose:	Will cause the compiler to be case sensitive. By default the compiler is case insensitive. When linking multiple compilation units, this directive must appear exactly the same in each compilation unit. Warning: Not all the CCS example programs, headers and drivers have been tested with case sensitivity turned on.
Examples:	<pre>#case int STATUS; void func() { int status; ... STATUS = status; // Copy local status to //global }</pre>
Example Files:	ex_cust.c
Also See:	None

__date__

Syntax:	<code>__DATE__</code>
Elements:	None
Purpose:	This pre-processor identifier is replaced at compile time with the date of the compile in the form: "31-JAN-03"
Examples:	<pre>printf("Software was compiled on "); printf(__DATE__);</pre>
Example Files:	None
Also See:	None

#define

Syntax:	#define <i>id</i> text or #define <i>id</i>(<i>x,y...</i>) text
Elements:	<p><i>id</i> is a preprocessor identifier, text is any text, <i>x,y</i> is a list of local preprocessor identifiers, and in this form there may be one or more identifiers separated by commas.</p> <p>Used to provide a simple string replacement of the ID with the given text from this point of the program and on.</p>
Purpose:	<p>In the second form (a C macro) the local identifiers are matched up with similar identifiers in the text and they are replaced with text passed to the macro where it is used.</p> <p>If the text contains a string of the form #idx then the result upon evaluation will be the parameter id concatenated with the string x.</p> <p>If the text contains a string of the form #idx#idy then parameter idx is</p>

concatenated with parameter *idy* forming a new identifier.

Within the define text two special operators are supported:

#x is the stringize operator resulting in "x"

x##y is the concatenation operator resulting in *xy*

The varadic macro syntax is supported where the last parameter is specified as ... and the local identifier used is `__va_args__`. In this case, all remaining arguments are combined with the commas.

Examples:

```
#define BITS 8
a=a+BITS; //same as a=a+8;

#define hi(x) (x<<4)
a=hi(a); //same as a=(a<<4);

#define isequal(a,b) (primary_##a[b]==backup_##a[b])
// usage isequal(names,5) is the same as
// (primary_names[5]==backup_names[5])

#define str(s) #s
#define part(device) #include str(device##.h)
// usage part(16F887) is the same as
// #include "16F887.h"

#define DBG(...) fprintf(debug,__VA_ARGS__)
```

Example Files: [ex_stwt.c](#), [ex_macro.c](#)

Also See: [#UNDEF](#), [#IFDEF](#), [#IFNDEF](#)

definedinc

Syntax:	<code>value = definedinc(<i>variable</i>);</code>
Parameters:	<i>variable</i> is the name of the variable, function, or type to be checked.
Returns:	A C status for the type of <i>id</i> entered as follows: 0 – not known 1 – typedef or enum 2 – struct or union type

	3 – typemod qualifier 4 – defined function 5 – function prototype 6 – compiler built-in function 7 – local variable 8 – global variable
Function:	This function checks the type of the variable or function being passed in and returns a specific C status based on the type.
Availability:	All devices
Requires:	None.
Examples:	int x, y = 0; y = definedinc(x); // y will return 7 – x is a local variable
Example Files:	None
Also See:	None

#device

Syntax:	#DEVICE <i>chip options</i> #DEVICE <i>Compilation mode selection</i>				
Elements:	<p>Chip Options-</p> <p>chip is the name of a specific processor (like: PIC16C74), To get a current list of supported devices:</p> <p>START RUN CCSC +Q</p> <p>Options are qualifiers to the standard operation of the device. Valid options are:</p> <table><tr><td>*=5</td><td>Use 5 bit pointers (for all parts)</td></tr><tr><td>*=8</td><td>Use 8 bit pointers (14 and 16 bit</td></tr></table>	*=5	Use 5 bit pointers (for all parts)	*=8	Use 8 bit pointers (14 and 16 bit
*=5	Use 5 bit pointers (for all parts)				
*=8	Use 8 bit pointers (14 and 16 bit				

	parts)
*=16	Use 16 bit pointers (for 14 bit parts)
ADC=x	Where x is the number of bits read_adc() should return
ICD=TRUE	Generates code compatible with Microchips ICD debugging hardware.
ICD=n	For chips with multiple ICSP ports specify the port number being used. The default is 1.
WRITE_EEPROM=ASYNC	Prevents WRITE_EEPROM from hanging while writing is taking place. When used, do not write to EEPROM from both ISR and outside ISR.
WRITE_EEPROM = NOINT	Allows interrupts to occur while the write_eeprom() operations is polling the done bit to check if the write operations has completed. Can be used as long as no EEPROM operations are performed during an ISR.
HIGH_INTS=TRUE	Use this option for high/low priority interrupts on the PIC® 18.
%f=.	No 0 before a decimal pint on %f numbers less than 1.
OVERLOAD=KEYWORD	Overloading of functions is now supported. Requires the use of the keyword for overloading.
OVERLOAD=AUTO	Default mode for overloading.
PASS_STRINGS=IN_RAM	A new way to pass constant strings to a function by first copying the string to RAM and then passing a pointer to RAM to the function.
CONST=READ_ONLY	Uses the ANSI keyword CONST definition, making CONST variables read only, rather than located in program memory.
CONST=ROM	Uses the CCS compiler traditional keyword CONST definition, making CONST variables located in program memory.
NESTED_INTERRUPTS=TRUE	Enables interrupt nesting for PIC24, dsPIC30, and dsPIC33

	devices. Allows higher priority interrupts to interrupt lower priority interrupts.
NORETFIE	ISR functions (preceeded by a #int_xxx) will use a RETURN opcode instead of the RETFIE opcode. This is not a commonly used option; used rarely in cases where the user is writing their own ISR handler.
NO_DIGITAL_INIT	Normally the compiler sets all I/O pins to digital and turns off the comparator. This option prevents that action.

Both chip and options are optional, so multiple #DEVICE lines may be used to fully define the device. Be warned that a #DEVICE with a chip identifier, will clear all previous #DEVICE and #FUSE settings.

Compilation mode selection-

The #DEVICE directive supports compilation mode selection. The valid keywords are CCS2, CCS3, CCS4 and ANSI. The default mode is CCS4. For the CCS4 and ANSI mode, the compiler uses the default fuse settings NOLVP, PUT for chips with these fuses. The NOWDT fuse is default if no call is made to restart_wdt().

CCS4	This is the default compilation mode. The pointer size for PCM and PCH is set to *=16 if the pointer size is over 0FF.
ANSI	Default data type is SIGNED all other modes default to UNSIGNED. Compilation is case sensitive, all other modes are case insensitive. Pointer size is set to *=16 if the pointer size is over 0FF.
CCS2 CCS3	var16 = NegConst8 is compiled as: var16 = NegConst8 (signed sign extension) Pointer size is set to *=8 for PCM and *=5 for PCB . The overload keyword is required.
CCS2 only	The default #DEVICE ADC is set to the resolution of 8. All other modes default to 8. onebit = eightbits is compiled as onebit = (eightbits < 8 ? 8 : eightbits) All other modes compile as: onebit = (eightbits < 8 ? 8 : eightbits)

	Chip Options -Defines the target processor. Every program must have exactly one #DEVICE with a chip. When linking multiple compilation units, this directive must appear exactly the same in each compilation unit.
Purpose:	Compilation mode selection - The compilation mode selection allows existing code to be compiled without encountering errors created by compiler compliance. As CCS discovers discrepancies in the way expressions are evaluated according to ANSI, the change will generally be made only to the ANSI mode and the next major CCS release.
Examples:	<p>Chip Options-</p> <pre>#device PIC16C74 #device PIC16C67 *=16 #device *=16 ICD=TRUE #device PIC16F877 *=16 ADC=10 #device %f=. printf("%f",.5); //will print .5, without the directive it will print 0.5</pre> <p>Compilation mode selection-</p> <pre>#device CCS2 // This will set the ADC to the resolution of the part</pre>
Example Files:	ex_mxram.c , ex_icd.c , 16c74.h ,
Also See:	read_adc()

__device__

Syntax:	<u>__DEVICE__</u>
Elements:	None
Purpose:	This pre-processor identifier is defined by the compiler with the base number of the current device (from a #DEVICE). The base number is usually the number after the C in the part number. For example the PIC16C622 has a base number of 622.
Examples:	<pre>#if __device__==71</pre>

```
SETUP_ADC_PORTS ( ALL_DIGITAL );
#endif
```

Example Files: None

Also See: [#DEVICE](#)

#if expr #else #elif #endif

Syntax:

```
#if expr
code
#elif expr //Optional, any number may be used
code
#else //Optional
code
#endif
```

Elements: *expr* is an expression with constants, standard operators and/or preprocessor identifiers. *Code* is any standard c source code.

The pre-processor evaluates the constant expression and if it is non-zero will process the lines up to the optional #ELSE or the #ENDIF.

Purpose: Note: you may NOT use C variables in the #IF. Only preprocessor identifiers created via #define can be used. The preprocessor expression DEFINED(id) may be used to return 1 if the id is defined and 0 if it is not. == and != operators now accept a constant string as both operands. This allows for compile time comparisons and can be used with GETENV() when it returns a string result.

Examples:

```
#if MAX_VALUE > 255
    long value;
#else
    int value;
#endif
#if getenv("DEVICE")== "PIC16F877"
    //do something special for the PIC16F877
#endif
```

Example Files: [ex_extee.c](#)

Also See: [#IFDEF](#), [#IFNDEF](#), [getenv\(\)](#)

#error

Syntax:	#ERROR <i>text</i> #ERROR / warning <i>text</i> #ERROR / information <i>text</i>
Elements:	<i>text</i> is optional and may be any text
Purpose:	Forces the compiler to generate an error at the location this directive appears in the file. The text may include macros that will be expanded for the display. This may be used to see the macro expansion. The command may also be used to alert the user to an invalid compile time situation.
Examples:	<pre>#if BUFFER_SIZE>16 #error Buffer size is too large #endif #error Macro test: min(x,y)</pre>
Example Files:	ex_psp.c
Also See:	#WARNING

#export (options)

Syntax:	#EXPORT (options)
Elements:	FILE=filename The filename which will be generated upon compile. If not given, the filename will be the name of the file you are compiling, with a .o or .hex extension (depending on output format).

ONLY=symbol+symbol+.....+symbol

Only the listed symbols will be visible to modules that import or link this relocatable object file. If neither ONLY or EXCEPT is used, all symbols are exported.

EXCEPT=symbol+symbol+.....+symbol

All symbols except the listed symbols will be visible to modules that import or link this relocatable object file. If neither ONLY or EXCEPT is used, all symbols are exported.

RELOCATABLE

CCS relocatable object file format. Must be imported or linked before loading into a PIC. This is the default format when the #EXPORT is used.

HEX

Intel HEX file format. Ready to be loaded into a PIC. This is the default format when no #EXPORT is used.

RANGE=start:stop

Only addresses in this range are included in the hex file.

OFFSET=address

Hex file address starts at this address (0 by default)

ODD

Only odd bytes place in hex file.

EVEN

Only even bytes placed in hex file.

Purpose:

This directive will tell the compiler to either generate a relocatable object file or a stand-alone HEX binary. A relocatable object file must be linked into your application, while a stand-alone HEX binary can be programmed directly into the PIC.

The command line compiler and the PCW IDE Project Manager can also be used to compile/link/build modules and/or projects.

Multiple #EXPORT directives may be used to generate multiple hex files. this may be used for 8722 like devices with external memory.

Examples:

```
#EXPORT(RELOCATABLE, ONLY=TimerTask)
void TimerFunc1(void) { /* some code */ }
void TimerFunc2(void) { /* some code */ }
void TimerFunc3(void) { /* some code */ }
void TimerTask(void)
```

```
{
    TimerFunc1();
    TimerFunc2();
    TimerFunc3();
}
/*
This source will be compiled into a relocatable object,
but the object this is being linked to can only see
TimerTask()
*/
```

Example Files: None

See Also: [#IMPORT](#), [#MODULE](#), [Invoking the Command Line Compiler](#), [Multiple Compilation Unit](#)

__file__

Syntax: __FILE__

Elements: None

Purpose: The pre-processor identifier is replaced at compile time with the file path and the filename of the file being compiled.

Examples:

```
if(index>MAX_ENTRIES)
    printf("Too many entries, source file: "
        __FILE__ " at line " __LINE__ "\r\n");
```

Example Files: [assert.h](#)

Also See: [line](#)

__filename__

Syntax: __FILENAME__

Elements:	None
Purpose:	The pre-processor identifier is replaced at compile time with the filename of the file being compiled.
Examples:	<pre>if(index>MAX_ENTRIES) printf("Too many entries, source file: " "__FILENAME__ " at line " __LINE__ "\r\n");</pre>
Example Files:	None
Also See:	line

#fill_rom

Syntax:	#fill_rom <i>value</i>
Elements:	<i>value</i> is a constant 16-bit value
Purpose:	This directive specifies the data to be used to fill unused ROM locations. When linking multiple compilation units, this directive must appear exactly the same in each compilation unit.
Examples:	<code>#fill_rom 0x36</code>
Example Files:	None
Also See:	#ROM

#fuses

Syntax:	#FUSES <i>options</i>
Elements:	<i>options</i> vary depending on the device. A list of all valid options has been put at the top of each devices .h file in a comment for reference.

The PCW device edit utility can modify a particular devices fuses. The PCW pull down menu VIEW | Valid fuses will show all fuses with their descriptions.

Some common options are:

- LP, XT, HS, RC
- WDT, NOWDT
- PROTECT, NOPROTECT
- PUT, NOPUT (Power Up Timer)
- BROWNOUT, NOBROWNOUT

This directive defines what fuses should be set in the part when it is programmed. This directive does not affect the compilation; however, the information is put in the output files. If the fuses need to be in Parallax format, add a PAR option. SWAP has the special function of swapping (from the Microchip standard) the high and low BYTES of non-program data in the Hex file. This is required for some device programmers.

Some fuses are set by the compiler based on other compiler directives. For example, the oscillator fuses are set up by the #USE delay directive. The debug, No debug and ICSPN Fuses are set by the #DEVICE ICD=directive.

Purpose:

Some processors allow different levels for certain fuses. To access these levels, assign a value to the fuse. For example, on the 18F452, the fuse PROTECT=6 would place the value 6 into CONFIG5L, protecting code blocks 0 and 3.

When linking multiple compilation units be aware this directive applies to the final object file. Later files in the import list may reverse settings in previous files.

To eliminate all fuses in the output files use:
#FUSES none

To manually set the fuses in the output files use:
#FUSES 1 = 0xC200 // sets config word 1 to 0xC200

Examples: #fuses HS, NOWDT

Example Files: [ex_sqw.c](#)

Also See: None

#hexcomment

Syntax:	#HEXCOMMENT text comment for the top of the hex file #HEXCOMMENT\ text comment for the end of the hex file
Elements:	None
	Puts a comment in the hex file
Purpose:	Some programmers (MPLAB in particular) do not like comments at the top of the hex file.
Examples:	<code>#HEXCOMMENT Version 3.1 - requires 20MHz crystal</code>
Example Files:	None
Also See:	None

#id

Syntax:	#ID number 16 #ID number, number, number, number #ID "filename" #ID CHECKSUM
Elements:	Number 16 is a 16 bit number, number is a 4 bit number, filename is any valid PC filename and checksum is a keyword.
Purpose:	This directive defines the ID word to be programmed into the part. This directive does not affect the compilation but the information is put in the output file. The first syntax will take a 16 -bit number and put one nibble in each of the four ID words in the traditional manner. The second syntax

specifies the exact value to be used in each of the four ID words .

When a filename is specified the ID is read from the file. The format must be simple text with a CR/LF at the end. The keyword CHECKSUM indicates the device checksum should be saved as the ID.

Examples:	<pre>#id 0x1234 #id "serial.num" #id CHECKSUM</pre>
Example Files:	ex_cust.c
Also See:	None

#ifdef #ifndef #else #elif #endif

	<pre>#IFDEF <i>id</i> <i>code</i> #ELIF <i>code</i> #ELSE <i>code</i> #ENDIF</pre>
Syntax:	<pre>#IFNDEF <i>id</i> <i>code</i> #ELIF <i>code</i> #ELSE <i>code</i> #ENDIF</pre>
Elements:	<i>id</i> is a preprocessor identifier, <i>code</i> is valid C source code.
Purpose:	This directive acts much like the #IF except that the preprocessor simply checks to see if the specified ID is known to the preprocessor (created with a #DEFINE). #IFDEF checks to see if defined and #IFNDEF checks to see if it is not defined.

Examples:	<pre>#define debug // Comment line out for no debug ... #ifdef DEBUG printf("debug point a"); #endif</pre>
Example Files:	ex_sqw.c
Also See:	#IF

#ignore_warnings

Syntax:	#ignore_warnings ALL #IGNORE_WARNINGS NONE #IGNORE_WARNINGS <i>warnings</i>
Elements:	warnings is one or more warning numbers separated by commas
Purpose:	This function will suppress warning messages from the compiler. ALL indicates no warning will be generated. NONE indicates all warnings will be generated. If numbers are listed then those warnings are suppressed.
Examples:	<pre>#ignore_warnings 203 while(TRUE) { #ignore_warnings NONE</pre>
Example Files:	None
Also See:	Warning messages

#import (options)

Syntax:	#IMPORT (options)
----------------	--------------------------

Elements:***FILE=filename***

The filename of the object you want to link with this compilation.

ONLY=symbol+symbol+.....+symbol

Only the listed symbols will imported from the specified relocatable object file. If neither ONLY or EXCEPT is used, all symbols are imported.

EXCEPT=symbol+symbol+.....+symbol

The listed symbols will not be imported from the specified relocatable object file. If neither ONLY or EXCEPT is used, all symbols are imported.

RELOCATABLE

CCS relocatable object file format. This is the default format when the #IMPORT is used.

COFF

COFF file format from MPASM, C18 or C30.

HEX

Imported data is straight hex data.

RANGE=start:stop

Only addresses in this range are read from the hex file.

LOCATION=id

The identifier is made a constant with the start address of the imported data.

SIZE=id

The identifier is made a constant with the size of the imported data.

Purpose:

This directive will tell the compiler to include (link) a relocatable object with this unit during compilation. Normally all global symbols from the specified file will be linked, but the EXCEPT and ONLY options can prevent certain symbols from being linked.

The command line compiler and the PCW IDE Project Manager can also be used to compile/link/build modules and/or projects.

Examples:

```
#IMPORT(FILE=timer.o, ONLY=TimerTask)
void main(void)
{
    while(TRUE)
```

```

        TimerTask();
    }
    /*
    timer.o is linked with this compilation, but only
    TimerTask() is visible in scope from this object.
    */

```

Example Files: None

See Also: [#EXPORT](#), [#MODULE](#), [Invoking the Command Line Compiler](#), [Multiple Compilation Unit](#)

#include

Syntax: **#INCLUDE** <filename>
or
#INCLUDE "filename"

Elements: **filename** is a valid PC filename. It may include normal drive and path information. A file with the extension ".encrypted" is a valid PC file. The standard compiler #INCLUDE directive will accept files with this extension and decrypt them as they are read. This allows include files to be distributed without releasing the source code.

Purpose: Text from the specified file is used at this point of the compilation. If a full path is not specified the compiler will use the list of directories specified for the project to search for the file. If the filename is in "" then the directory with the main source file is searched first. If the filename is in <> then the directory with the main source file is searched last.

Examples:

```
#include <16C54.H>
#include <C:\INCLUDES\COMLIB\MYRS232.C>
```

Example Files: [ex_sqw.c](#)

Also See: None

#inline

Syntax:	#INLINE
Elements:	None
Purpose:	Tells the compiler that the function immediately following the directive is to be implemented INLINE. This will cause a duplicate copy of the code to be placed everywhere the function is called. This is useful to save stack space and to increase speed. Without this directive the compiler will decide when it is best to make procedures INLINE.
Examples:	<pre>#inline swapbyte(int &a, int &b) { int t; t=a; a=b; b=t; }</pre>
Example Files:	ex_cust.c
Also See:	#SEPARATE

#int_xxxx

Syntax:	#INT_AD	Analog to digital conversion complete
	#INT_ADOF	Analog to digital conversion timeout
	#INT_BUSCOL	Bus collision
	#INT_BUSCOL2	Bus collision 2 detected
	#INT_BUTTON	Pushbutton

#INT_CANERR	An error has occurred in the CAN module
#INT_CANIRX	An invalid message has occurred on the CAN bus
#INT_CANRX0	CAN Receive buffer 0 has received a new message
#INT_CANRX1	CAN Receive buffer 1 has received a new message
#INT_CANTX0	CAN Transmit buffer 0 has completed transmission
#INT_CANTX1	CAN Transmit buffer 0 has completed transmission
#INT_CANTX2	CAN Transmit buffer 0 has completed transmission
#INT_CANWAKE	Bus Activity wake-up has occurred on the CAN bus
#INT_CCP1	Capture or Compare on unit 1
#INT_CCP2	Capture or Compare on unit 2
#INT_CCP3	Capture or Compare on unit 3
#INT_CCP4	Capture or Compare on unit 4
#INT_CCP5	Capture or Compare on unit 5
#INT_COMP	Comparator detect
#INT_COMP0	Comparator 0 detect
#INT_COMP1	Comparator 1 detect
#INT_COMP2	Comparator 2 detect
#INT_CR	Cryptographic activity complete
#INT_EEPROM	Write complete
#INT_ETH	Ethernet module interrupt
#INT_EXT	External interrupt
#INT_EXT1	External interrupt #1
#INT_EXT2	External interrupt #2
#INT_EXT3	External interrupt #3
#INT_I2C	I2C interrupt (only on 14000)
#INT_IC1	Input Capture #1

#INT_IC2QE1	Input Capture 2 / QE1 Interrupt
#IC3DR	Input Capture 3 / Direction Change Interrupt
#INT_LCD	LCD activity
#INT_LOWVOLT	Low voltage detected
#INT_LVD	Low voltage detected
#INT_OSC_FAIL	System oscillator failed
#INT_OSCF	System oscillator failed
#INT_PMP	Parallel Master Port interrupt
#INT_PSP	Parallel Slave Port data in
#INT_PWMTB	PWM Time Base
#INT_RA	Port A any change on A0_A5
#INT_RB	Port B any change on B4-B7
#INT_RC	Port C any change on C4-C7
#INT_RDA	RS232 receive data available
#INT_RDA0	RS232 receive data available in buffer 0
#INT_RDA1	RS232 receive data available in buffer 1
#INT_RDA2	RS232 receive data available in buffer 2
#INT_RTCC	Timer 0 (RTCC) overflow
#INT_SPP	Streaming Parallel Port Read/Write
#INT_SSP	SPI or I2C activity
#INT_SSP2	SPI or I2C activity for Port 2
#INT_TBE	RS232 transmit buffer empty
#INT_TBE0	RS232 transmit buffer 0 empty
#INT_TBE1	RS232 transmit buffer 1 empty
#INT_TBE2	RS232 transmit buffer 2 empty
#INT_TIMER0	Timer 0 (RTCC) overflow
#INT_TIMER1	Timer 1 overflow

#INT_TIMER2	Timer 2 overflow
#INT_TIMER3	Timer 3 overflow
#INT_TIMER4	Timer 4 overflow
#INT_TIMER5	Timer 5 overflow
#INT_ULPWU	Ultra-low power wake up interrupt
#INT_USB	Universal Serial Bus activity

Note many more #INT_ options are available on specific chips. Check the devices .h file for a full list for a given chip.

Elements:	None
	<p>These directives specify the following function is an interrupt function. Interrupt functions may not have any parameters. Not all directives may be used with all parts. See the devices .h file for all valid interrupts for the part or in PCW use the pull down VIEW Valid Ints</p> <p>The compiler will generate code to jump to the function when the interrupt is detected. It will generate code to save and restore the machine state, and will clear the interrupt flag. To prevent the flag from being cleared add NOCLEAR after the #INT_xxxx. The application program must call ENABLE_INTERRUPTS(INT_xxxx) to initially activate the interrupt along with the ENABLE_INTERRUPTS(GLOBAL) to enable interrupts.</p> <p>The keywords HIGH and FAST may be used with the PCH compiler to mark an interrupt as high priority. A high-priority interrupt can interrupt another interrupt handler. An interrupt marked FAST is performed without saving or restoring any registers. You should do as little as possible and save any registers that need to be saved on your own. Interrupts marked HIGH can be used normally. See #DEVICE for information on building with high-priority interrupts.</p> <p>A summary of the different kinds of PIC18 interrupts:</p> <p>#INT_xxxx Normal (low priority) interrupt. Compiler saves/restores key registers. This interrupt will not interrupt any interrupt in progress.</p> <p>#INT_xxxx FAST High priority interrupt. Compiler DOES NOT save/restore key registers.</p>
Purpose:	

This interrupt will interrupt any normal interrupt in progress.
Only one is allowed in a program.

#INT_xxxx HIGH
High priority interrupt. Compiler saves/restores key registers.
This interrupt will interrupt any normal interrupt in progress.

#INT_xxxx NOCLEAR
The compiler will not clear the interrupt.
The user code in the function should call `clear_interrupt()` to clear the interrupt in this case.

#INT_GLOBAL
Compiler generates no interrupt code. User function is located at address 8 for user interrupt handling.

Some interrupts shown in the devices header file are only for the enable/disable interrupts. For example, `INT_RB3` may be used in enable/interrupts to enable pin B3. However, the interrupt handler is `#INT_RB`.

Similarly `INT_EXT_L2H` sets the interrupt edge to falling and the handler is `#INT_EXT`.

Examples:

```
#int_ad
adc_handler() {
    adc_active=FALSE;
}

#int_rtcc noclear
isr() {
    ...
}
```

Example Files:

See [ex_sisr.c](#) and [ex_stwt.c](#) for full example programs.

Also See:

[enable_interrupts\(\)](#), [disable_interrupts\(\)](#), [#INT_DEFAULT](#), [#INT_GLOBAL](#), [#PRIORITY](#)

#INT_DEFAULT

Syntax:	#INT_DEFAULT
Elements:	None

Purpose:	The following function will be called if the PIC® triggers an interrupt and none of the interrupt flags are set. If an interrupt is flagged, but is not the one triggered, the #INT_DEFAULT function will get called.
Examples:	<pre>#int_default default_isr() { printf("Unexplained interrupt\r\n"); }</pre>
Example Files:	None
Also See:	#INT_xxxx , #INT_global

#int_global

Syntax:	#INT_GLOBAL
Elements:	None
Purpose:	This directive causes the following function to replace the compiler interrupt dispatcher. The function is normally not required and should be used with great caution. When used, the compiler does not generate start-up code or clean-up code, and does not save the registers.
Examples:	<pre>#int_global ISR() { // Will be located at location 4 for PIC16 chips. #asm bsf isr_flag retfie #endasm }</pre>
Example Files:	ex_glint.c
Also See:	#INT_xxxx

__line__

Syntax:	<u>__line__</u>
Elements:	None
Purpose:	The pre-processor identifier is replaced at compile time with line number of the file being compiled.
Examples:	<pre>if(index>MAX_ENTRIES) printf("Too many entries, source file: " "__FILE__" at line " __LINE__ "\r\n");</pre>
Example Files:	assert.h
Also See:	<u>__file__</u>

#list

Syntax:	#LIST
Elements:	None
Purpose:	#LIST begins inserting or resumes inserting source lines into the .LST file after a #NOLIST.
Examples:	<pre>#NOLIST // Don't clutter up the list file #include <cdriver.h> #LIST</pre>
Example Files:	16c74.h
Also See:	<u>#NOLIST</u>

#line

Syntax:	#LINE number file name
Elements:	Number is non-negative decimal integer. File name is optional.
Purpose:	The C pre-processor informs the C Compiler of the location in your source code. This code is simply used to change the value of <code>_LINE_</code> and <code>_FILE_</code> variables.
Examples:	<pre> 1. void main(){ #line 10 // specifies the line number that // should be reported for // the following line of input 2. #line 7 "hello.c" // line number in the source file // hello.c and it sets the // line 7 as current line // and hello.c as current file </pre>
Example Files:	None
Also See:	None

#locate

Syntax:	#LOCATE <i>id</i>=<i>x</i>
Elements:	<i>id</i> is a C variable, <i>x</i> is a constant memory address
Purpose:	<p>#LOCATE allocates a C variable to a specified address. If the C variable was not previously defined, it will be defined as an INT8.</p> <p>A special form of this directive may be used to locate all A functions local variables starting at a fixed location. Use: #LOCATE Auto = address</p>

	This directive will place the indirected C variable at the requested address.
Examples:	<pre>// This will locate the float variable at 50-53 // and C will not use this memory for other // variables automatically located. float x; #locate x=0x 50</pre>
Example Files:	ex_glint.c
Also See:	#byte , #bit , #reserve , #word , Named Registers , Type Specifiers , Type Qualifiers , Enumerated Types , Structures & Unions , Typedef

#module

Syntax:	#MODULE
Elements:	None
Purpose:	<p>All global symbols created from the #MODULE to the end of the file will only be visible within that same block of code (and files #INCLUDE within that block). This may be used to limit the scope of global variables and functions within include files. This directive also applies to pre-processor #defines.</p> <p>Note: The extern and static data qualifiers can also be used to denote scope of variables and functions as in the standard C methodology. #MODULE does add some benefits in that pre-processor #DEFINE can be given scope, which cannot normally be done in standard C methodology.</p>
Examples:	<pre>int GetCount(void); void SetCount(int newCount); #MODULE int g_count; #define G_COUNT_MAX 100 int GetCount(void) {return(g_count);} void SetCount(int newCount) { if (newCount>G_COUNT_MAX) newCount=G_COUNT_MAX; g_count=newCount; }</pre>

```

/*
the functions GetCount() and SetCount() have global scope,
but the variable g_count and the #define G_COUNT_MAX only
has scope to this file.
*/

```

Example Files: None

See Also: [#EXPORT](#), [Invoking the Command Line Compiler](#), [Multiple Compilation Unit](#)

#nolist

Syntax:	#NOLIST
Elements:	None
Purpose:	Stops inserting source lines into the .LST file (until a #LIST)
Examples:	<pre> #NOLIST // Don't clutter up the list file #include <cdriver.h> #LIST </pre>
Example Files:	16c74.h
Also See:	#LIST

#ocs

Syntax:	#OCS x
Elements:	x is the clock's speed and can be 1 Hz to 100 MHz.
Purpose:	Used instead of the #use delay(clock = x)
Examples:	<pre>#include <18F4520.h></pre>

```
#device ICD=TRUE
#OCS 20 MHz
#use rs232(debugger)

void main() {
    -----;
}
```

Example Files: None

Also See: [#USE DELAY](#)

#opt

Syntax:	#OPT <i>n</i>
Elements:	All Devices: <i>n</i> is the optimization level 1-9 or by using the word "compress" for PIC18 and Enhanced PIC16 families.
Purpose:	The optimization level is set with this directive. This setting applies to the entire program and may appear anywhere in the file. The PCW default is 9 for normal. When Compress is specified the optimization is set to an extreme level that causes a very tight rom image, the code is optimized for space, not speed. Debugging with this level may be more difficult.
Examples:	#opt 5
Example Files:	None
Also See:	None

#org

Syntax:	<pre> #ORG <i>start, end</i> or #ORG <i>segment</i> or #ORG <i>start, end { }</i> or #ORG <i>start, end auto=0</i> #ORG <i>start,end DEFAULT</i> or #ORG <i>DEFAULT</i> </pre>
Elements:	<p>start is the first ROM location (word address) to use, end is the last ROM location, segment is the start ROM location from a previous #ORG</p>
Purpose:	<p>This directive will fix the following function, constant or ROM declaration into a specific ROM area. End may be omitted if a segment was previously defined if you only want to add another function to the segment.</p> <p>Follow the ORG with a { } to only reserve the area with nothing inserted by the compiler.</p> <p>The RAM for a ORG'd function may be reset to low memory so the local variables and scratch variables are placed in low memory. This should only be used if the ORG'd function will not return to the caller. The RAM used will overlap the RAM of the main program. Add a AUTO=0 at the end of the #ORG line.</p> <p>If the keyword DEFAULT is used then this address range is used for all functions user and compiler generated from this point in the file until a #ORG DEFAULT is encountered (no address range). If a compiler function is called from the generated code while DEFAULT is in effect the compiler generates a new version of the function within the specified address range.</p> <p>#ORG may be used to locate data in ROM. Because CONSTANT are implemented as functions the #ORG should proceed the CONSTANT</p>

and needs a start and end address. For a ROM declaration only the start address should be specified.

When linking multiple compilation units be aware this directive applies to the final object file. It is an error if any #ORG overlaps between files unless the #ORG matches exactly.

Examples:

```
#ORG 0x1E00, 0x1FFF
MyFunc() {
//This function located at 1E00
}

#ORG 0x1E00
Anotherfunc(){
// This will be somewhere 1E00-1F00
}

#ORG 0x800, 0x820 {}
//Nothing will be at 800-820

#ORG 0x1B80
ROM int32 seridl_N0=12345;

#ORG 0x1C00, 0x1C0F
CHAR CONST ID[10]= {"123456789"};
//This ID will be at 1C00
//Note some extra code will
//proceed the 123456789

#ORG 0x1F00, 0x1FF0
Void loader (){
.
.
.
}
```

Example Files: [loader.c](#)

Also See: [#ROM](#)

#pin_select

Syntax:	#PIN_SELECT function=pin_xx																																	
Element s:	<p><i>function</i> is the Microchip defined pin function name, such as: U1RX (UART1 receive), INT1 (external interrupt 1), T2CK (timer 2 clock), IC1 (input capture 1), OC1 (output capture 1).</p>																																	
	<table><tr><td>INT1</td><td>External Interrupt 1</td></tr><tr><td>INT2</td><td>External Interrupt 2</td></tr><tr><td>INT3</td><td>External Interrupt 3</td></tr><tr><td>T0CK</td><td>Timer0 External Clock</td></tr><tr><td>T3CK</td><td>Timer3 External Clock</td></tr><tr><td>CCP1</td><td>Input Capture 1</td></tr><tr><td>CCP2</td><td>Input Capture 2</td></tr><tr><td>T1G</td><td>Timer1 Gate Input</td></tr><tr><td>T3G</td><td>Timer3 Gate Input</td></tr><tr><td>U2RX</td><td>EUSART2 Asynchronous Receive/Synchronous Receive (also named: RX2)</td></tr><tr><td>U2CK</td><td>EUSART2 Asynchronous Clock Input</td></tr><tr><td>SDI2</td><td>SPI2 Data Input</td></tr><tr><td>SCK2IN</td><td>SPI2 Clock Input</td></tr><tr><td>SS2IN</td><td>SPI2 Slave Select Input</td></tr><tr><td>FLT0</td><td>PWM Fault Input</td></tr><tr><td>T0CKI</td><td>Timer0 External Clock Input</td></tr><tr><td>T3CK</td><td>Timer3 External Clock Input</td></tr></table>	INT1	External Interrupt 1	INT2	External Interrupt 2	INT3	External Interrupt 3	T0CK	Timer0 External Clock	T3CK	Timer3 External Clock	CCP1	Input Capture 1	CCP2	Input Capture 2	T1G	Timer1 Gate Input	T3G	Timer3 Gate Input	U2RX	EUSART2 Asynchronous Receive/Synchronous Receive (also named: RX2)	U2CK	EUSART2 Asynchronous Clock Input	SDI2	SPI2 Data Input	SCK2IN	SPI2 Clock Input	SS2IN	SPI2 Slave Select Input	FLT0	PWM Fault Input	T0CKI	Timer0 External Clock Input	T3CK
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FLT0	PWM Fault Input																																	
T0CKI	Timer0 External Clock Input																																	
T3CK	Timer3 External Clock Input																																	

KI	
RX2	EUSART2 Asynchronous Transmit/Asynchronous Clock Output (also named: TX2)
NUL L	NULL
C1O UT	Comparator 1 Output
C2O UT	Comparator 2 Output
U2T X	EUSART2 Asynchronous Transmit/ Asynchronous Clock Output (also named: TX2)
U2D T	EUSART2 Synchronous Transmit (also named: DT2)
SDO 2	SPI2 Data Output
SCK 2OU T	SPIC2 Clock Output
SS2 OUT	SPI2 Slave Select Output
ULP OUT	Ultra Low-Power Wake-Up Event
P1A	ECCP1 Compare or PWM Output Channel A
P1B	ECCP1 Enhanced PWM Output, Channel B
P1C	ECCP1 Enhanced PWM Output, Channel C
P1D	ECCP1 Enhanced PWM Output, Channel D
P2A	ECCP2 Compare or PWM Output Channel A
P2B	ECCP2 Enhanced PWM Output, Channel B
P2C	ECCP2 Enhanced PWM Output, Channel C
P2D	ECCP1 Enhanced PWM Output, Channel D
TX2	EUSART2 Asynchronous Transmit/Asynchronous Clock Output (also named: TX2)
DT2	EUSART2 Synchronous

	Transmit (also named: U2DT)
SCK 2	SPI2 Clock Output
SSD MA	SPI DMA Slave Select
	<i>pin_xx</i> is the CCS provided pin definition. For example: PIN_C7, PIN_B0, PIN_D3, etc.
Purpose:	When using PPS chips a #PIN_SELECT must be appear before these peripherals can be used or referenced.
Examples:	<pre>#pin_select U1TX=PIN_C6 #pin_select U1RX=PIN_C7 #pin_select INT1=PIN_B0</pre>
Example Files:	None
Also See:	pin_select()

__pcb__

Syntax:	<u>__PCB__</u>
Elements:	None
Purpose:	The PCB compiler defines this pre-processor identifier. It may be used to determine if the PCB compiler is doing the compilation.
Examples:	<pre>#ifdef __pcb__ #device PIC16c54 #endif</pre>
Example Files:	ex_sqw.c
Also See:	__PCM__ , __PCH__

__pcm__

Syntax:	<u>__PCM__</u>
Elements:	None
Purpose:	The PCM compiler defines this pre-processor identifier. It may be used to determine if the PCM compiler is doing the compilation.
Examples:	<pre>#ifdef __pcm__ #device PIC16c71 #endif</pre>
Example Files:	ex_sqw.c
Also See:	__PCB__ , __PCH__

__pch__

Syntax:	<u>__PCH__</u>
Elements:	None
Purpose:	The PCH compiler defines this pre-processor identifier. It may be used to determine if the PCH compiler is doing the compilation.
Examples:	<pre>#ifdef __PCH__ #device PIC18C452 #endif</pre>
Example Files:	ex_sqw.c
Also See:	__PCB__ , __PCM__

#pragma

Syntax:	#PRAGMA <i>cmd</i>
----------------	---------------------------

Elements:	<i>cmd</i> is any valid preprocessor directive.
Purpose:	This directive is used to maintain compatibility between C compilers. This compiler will accept this directive before any other pre-processor command. In no case does this compiler require this directive.
Examples:	<code>#pragma device PIC16C54</code>
Example Files:	ex_cust.c
Also See:	None

#priority

Syntax:	#PRIORITY <i>ints</i>
Elements:	<i>ints</i> is a list of one or more interrupts separated by commas.
Purpose:	<i>export</i> makes the functions generated from this directive available to other compilation units within the link. The priority directive may be used to set the interrupt priority. The highest priority items are first in the list. If an interrupt is active it is never interrupted. If two interrupts occur at around the same time then the higher one in this list will be serviced first. When linking multiple compilation units be aware only the one in the last compilation unit is used.
Examples:	<code>#priority rtcc,rb</code>
Example Files:	None
Also See:	#INT xxxx

#profile

Syntax:	#profile options												
Elements:	<i>options</i> may be one of the following:												
	<table><tr><td>functions</td><td>Profiles the start/end of functions and all profileout() messages.</td></tr><tr><td>functions, parameters</td><td>Profiles the start/end of functions, parameters sent to functions, and all profileout() messages.</td></tr><tr><td>profileout</td><td>Only profile profileout() messages.</td></tr><tr><td>paths</td><td>Profiles every branch in the code.</td></tr><tr><td>off</td><td>Disable all code profiling.</td></tr><tr><td>on</td><td>Re-enables the code profiling that was previously disabled with a #profile off command. This will use the last options before disabled with the off command.</td></tr></table>	functions	Profiles the start/end of functions and all profileout() messages.	functions, parameters	Profiles the start/end of functions, parameters sent to functions, and all profileout() messages.	profileout	Only profile profileout() messages.	paths	Profiles every branch in the code.	off	Disable all code profiling.	on	Re-enables the code profiling that was previously disabled with a #profile off command. This will use the last options before disabled with the off command.
	functions	Profiles the start/end of functions and all profileout() messages.											
	functions, parameters	Profiles the start/end of functions, parameters sent to functions, and all profileout() messages.											
	profileout	Only profile profileout() messages.											
	paths	Profiles every branch in the code.											
	off	Disable all code profiling.											
on	Re-enables the code profiling that was previously disabled with a #profile off command. This will use the last options before disabled with the off command.												
Purpose:	Large programs on the microcontroller may generate lots of profile data, which may make it difficult to debug or follow. By using #profile the user can dynamically control which points of the program are being profiled, and limit data to what is relevant to the user.												
Examples:	<pre>#profile off void BigFunction(void) { // BigFunction code goes here. // Since #profile off was called above, // no profiling will happen even for other // functions called by BigFunction(). } #profile on</pre>												
Example Files:	ex_profile.c												
Also See:	#use profile() , profileout() , Code Profile overview												

#reserve

Syntax:	#RESERVE <i>address</i> or #RESERVE <i>address, address, address</i> or #RESERVE <i>start:end</i>
Elements:	<i>address</i> is a RAM address, <i>start</i> is the first address and <i>end</i> is the last
Purpose:	This directive allows RAM locations to be reserved from use by the compiler. #RESERVE must appear after the #DEVICE otherwise it will have no effect. When linking multiple compilation units be aware this directive applies to the final object file.
Examples:	<pre>#DEVICE PIC16C74 #RESERVE 0x60:0X6f</pre>
Example Files:	ex_cust.c
Also See:	#ORG

#rom

Syntax:	#ROM <i>address</i> = { <i>list</i> } #ROM <i>type</i> <i>address</i> = { <i>list</i> }
Elements:	<i>address</i> is a ROM word address, <i>list</i> is a list of words separated by commas
Purpose:	<p>Allows the insertion of data into the .HEX file. In particular, this may be used to program the '84 data EEPROM, as shown in the following example.</p> <p>Note that if the #ROM address is inside the program memory space, the directive creates a segment for the data, resulting in an error if a #ORG is over the same area. The #ROM data will also be counted as used program memory space.</p>

The type option indicates the type of each item, the default is 16 bits. Using char as the type treats each item as 7 bits packing 2 chars into every pcm 14-bit word.

When linking multiple compilation units be aware this directive applies to the final object file.

Some special forms of this directive may be used for verifying program memory:

- #ROM address = checksum
This will put a value at address such that the entire program memory will sum to 0x1248
- #ROM address = crc16
This will put a value at address that is a crc16 of all the program memory except the specified address
- #ROM address = crc16(start, end)
This will put a value at address that is a crc16 of all the program memory from start to end.
- #ROM address = crc8
This will put a value at address that is a crc16 of all the program memory except the specified address

Examples:	<pre>#rom getnev ("EEPROM ADDRESS")={1,2,3,4,5,6,7,8} #rom int8 0x1000={"(c)CCS, 2010"}</pre>
Example Files:	None
Also See:	#ORG

#separate

Syntax:	#SEPARATE
Elements:	None
Purpose:	Tells the compiler that the procedure IMMEDIATELY following the

directive is to be implemented SEPARATELY. This is useful to prevent the compiler from automatically making a procedure INLINE. This will save ROM space but it does use more stack space. The compiler will make all procedures marked SEPARATE, separate, as requested, even if there is not enough stack space to execute.

Examples:

```
#separate
swapbyte (int *a, int *b) {
    int t;
    t=*a;
    *a=*b;
    *b=t;
}
```

Example Files:

[ex_cust.c](#)

Also See:

[#INLINE](#)

#serialize

Syntax:

```
#SERIALIZE(id=xxx, next="x" | file="filename.txt" " |
listfile="filename.txt", "prompt="text", log="filename.txt") -
or
#SERIALIZE(dataee=x, binary=x, next="x" | file="filename.txt" |
listfile="filename.txt", prompt="text", log="filename.txt")
```

Elements:

id=xxx - Specify a C CONST identifier, may be int8, int16, int32 or char array

Use in place of id parameter, when storing serial number to EEPROM:

dataee=x - The address x is the start address in the data EEPROM.

binary=x - The integer x is the number of bytes to be written to address specified. -or-

string=x - The integer x is the number of bytes to be written to address specified.

unicode=n - If n is a 0, the string format is normal unicode. For n>0 n indicates the string number in a USB descriptor.

Use only one of the next three options:

file="filename.txt" - The file x is used to read the initial serial number

from, and this file is updated by the ICD programmer. It is assumed this is a one line file with the serial number. The programmer will increment the serial number.

listfile="filename.txt" - The file x is used to read the initial serial number from, and this file is updated by the ICD programmer. It is assumed this is a file one serial number per line. The programmer will read the first line then delete that line from the file.

next="x" - The serial number X is used for the first load, then the hex file is updated to increment x by one.

Other optional parameters:

prompt="text" - If specified the user will be prompted for a serial number on each load. If used with one of the above three options then the default value the user may use is picked according to the above rules.

log=xxx - A file may optionally be specified to keep a log of the date, time, hex file name and serial number each time the part is programmed. If no id=xxx is specified then this may be used as a simple log of all loads of the hex file.

Purpose:

Assists in making serial numbers easier to implement when working with CCS ICD units. Comments are inserted into the hex file that the ICD software interprets.

Examples:

```
//Prompt user for serial number to be placed
//at address of serialNumA
//Default serial number = 200int8int8 const
serialNumA=100;
#serialize(id=serialNumA,next="200",prompt="Enter the
serial number")

//Adds serial number log in seriallog.txt
#serialize(id=serialNumA,next="200",prompt="Enter the
serial number", log="seriallog.txt")

//Retrieves serial number from serials.txt
#serialize(id=serialNumA,listfile="serials.txt")

//Place serial number at EEPROM address 0, reserving 1
byte
#serialize(dataee=0,binary=1,next="45",prompt="Put in
Serial number")

//Place string serial number at EEPROM address 0,
```

	<pre>reserving 2 bytes #serialize(dataee=0, string=2,next="AB",prompt="Put in Serial number")</pre>
Example Files:	None
Also See:	None

#task

(The RTOS is only included with the PCW, PCWH, and PCWHD software packages.)

Each RTOS task is specified as a function that has no parameters and no return. The #TASK directive is needed just before each RTOS task to enable the compiler to tell which functions are RTOS tasks. An RTOS task cannot be called directly like a regular function can.

Syntax:	#TASK (<i>options</i>)
Elements:	<p>options are separated by comma and may be:</p> <p>rate=time Where time is a number followed by s, ms, us, or ns. This specifies how often the task will execute.</p> <p>max=time Where time is a number followed by s, ms, us, or ns. This specifies the budgeted time for this task.</p> <p>queue=bytes Specifies how many bytes to allocate for this task's incoming messages. The default value is 0.</p> <p>enabled=value Specifies whether a task is enabled or disabled by rtos_run(). True for enabled, false for disabled. The default value is enabled.</p>
Purpose:	<p>This directive tells the compiler that the following function is an RTOS task.</p> <p>The rate option is used to specify how often the task should execute.</p>

	<p>This must be a multiple of the <code>minor_cycle</code> option if one is specified in the <code>#USE RTOS</code> directive.</p> <p>The <code>max</code> option is used to specify how much processor time a task will use in one execution of the task. The time specified in <code>max</code> must be equal to or less than the time specified in the <code>minor_cycle</code> option of the <code>#USE RTOS</code> directive before the project will compile successfully. The compiler does not have a way to enforce this limit on processor time, so a programmer must be careful with how much processor time a task uses for execution. This option does not need to be specified.</p> <p>The <code>queue</code> option is used to specify the number of bytes to be reserved for the task to receive messages from other tasks or functions. The default queue value is 0.</p>
Examples:	<code>#task(rate=1s, max=20ms, queue=5)</code>
Also See:	#USE RTOS

__time__

Syntax:	<code>__TIME__</code>
Elements:	None
Purpose:	This pre-processor identifier is replaced at compile time with the time of the compile in the form: "hh:mm:ss"
Examples:	<pre>printf("Software was compiled on "); printf(__TIME__);</pre>
Example Files:	None
Also See:	None

#type

Syntax:	#TYPE <i>standard-type</i> = <i>size</i> #TYPE <i>default</i> = <i>area</i> #TYPE unsigned #TYPE signed
Elements:	<i>standard-type</i> is one of the C keywords short, int, long, or default <i>size</i> is 1,8,16, or 32 <i>area</i> is a memory region defined before the #TYPE using the addressmod directive
Purpose:	<p>By default the compiler treats SHORT as one bit , INT as 8 bits, and LONG as 16 bits. The traditional C convention is to have INT defined as the most efficient size for the target processor. This is why it is 8 bits on the PIC[®] . In order to help with code compatibility a #TYPE directive may be used to allow these types to be changed. #TYPE can redefine these keywords.</p> <p>Note that the commas are optional. Since #TYPE may render some sizes inaccessible (like a one bit int in the above) four keywords representing the four ints may always be used: INT1, INT8, INT16, and INT32. Be warned CCS example programs and include files may not work right if you use #TYPE in your program.</p> <p>This directive may also be used to change the default RAM area used for variable storage. This is done by specifying default=area where area is a addressmod address space.</p> <p>When linking multiple compilation units be aware this directive only applies to the current compilation unit.</p> <p>The #TYPE directive allows the keywords UNSIGNED and SIGNED to set the default data type.</p>
Examples:	<pre>#TYPE SHORT= 8 , INT= 16 , LONG= 32 #TYPE default=area addressmod (user ram block, 0x100, 0x1FF); #type default=user_ram_block // all variable declarations</pre>

```

// in this area will be in
// 0x100-0x1FF

#type default=
allocation

// restores memory

// back to normal

#TYPE SIGNED

...
void main()
{
int variable1; // variable1 can only take values from -
128 to 127
...
...
}
```

Example Files: [ex_cust.c](#)

Also See: None

#undef

Syntax: **#UNDEF** *id*

Elements: *id* is a pre-processor id defined via #DEFINE

Purpose: The specified pre-processor ID will no longer have meaning to the pre-processor.

Examples: `#if MAXSIZE<100
#undef MAXSIZE
#define MAXSIZE 100
#endif`

Example Files: None

Also See: [#DEFINE](#)

_unicode

Syntax: `__unicode(constant-string)`

Elements: Unicode format string

This macro will convert a standard ASCII string to a Unicode format string by inserting a \000 after each character and removing the normal C string terminator.

For example: `__unicode("ABCD")`
will return: `"A\00B\000C\000D"` (8 bytes total with the terminator)

Purpose

Since the normal C terminator is not used for these strings you need to do one of the following for variable length strings:

```
string = __unicode(KEYWORD) "\000\000";
OR
string = __unicode(KEYWORD);
string_size = sizeof(__unicode(KEYWORD));
```

Examples:

```
#define USB_DESC_STRING_TYPE 3

#define USB_STRING(x)
(sizeof(__unicode(x))+2),USB_DESC_STRING_TYPE,__unicode
#define USB_ENGLISH_STRING 4,USB_DESC_STRING_TYPE,0:

//Microsoft Defined for US-English

char const USB_STRING_DESC[]={
    USB_ENGLISH_STRING,
    USB_STRING("CCS"),
    USB_STRING("CCS HID DEMO")
};
```

Example Files: `usb_desc_hid.h`

#use capture

Syntax:	#USE CAPTURE(options)
	ICx/CCPx Which CCP/Input Capture module to us.
	INPUT = PIN_xx Specifies which pin to use. Useful for device with remappable pins, this will cause compiler to automatically assign pin to peripheral.
	TIMER=x Specifies the timer to use with capture unit. If not specified default to timer 1 for PCM and PCH compilers and timer 3 for PCD compiler.
	TICK=x The tick time to setup the timer to. If not specified it will be set to fastest as possible or if same timer was already setup by a previous stream it will be set to that tick time. If using same timer as previous stream and different tick time an error will be generated.
Elements:	FASTEST Use instead of TICK=x to set tick time to fastest as possible.
	SLOWEST Use instead of TICK=x to set tick time to slowest as possible.
	CAPTURE_RISING Specifies the edge that timer value is captured on. Defaults to CAPTURE_RISING.
	CAPTURE_FALLING Specifies the edge that timer value is captured on. Defaults to CAPTURE_RISING.
	CAPTURE_BOTH PCD only. Specifies the edge that timer value is

	<p>captured on. Defaults to CAPTURE_RISING.</p> <p>PRE=x Specifies number of rising edges before capture event occurs. Valid options are 1, 4 and 16, default to 1 if not specified. Options 4 and 16 are only valid when using CAPTURE_RISING, will generate an error is used with CAPTURE_FALLING or CAPTURE_BOTH.</p> <p>ISR=x</p> <p>STREAM=id Associates a stream identifier with the capture module. The identifier may be used in functions like <code>get_capture_time()</code>.</p> <p>DEFINE=id Creates a define named id which specifies the number of capture per second. Default define name if not specified is CAPTURES_PER_SECOND. Define name must start with an ASCII letter 'A' to 'Z', an ASCII letter 'a' to 'z' or an ASCII underscore ('_').</p> <p>This directive tells the compiler to setup an input capture on the specified pin using the specified settings. The <code>#USE DELAY</code> directive must appear before this directive can be used. This directive enables use of built-in functions such as <code>get_capture_time()</code> and <code>get_capture_event()</code>.</p>
Purpose:	
Examples:	<pre>#USE CAPTURE(INPUT=PIN_C2,CAPTURE_RISING,TIMER= 1,FASTEST)</pre>
Example Files:	None.
Also See:	get_capture_time() , get_capture_event()

#use delay

Syntax:	#USE DELAY (options)
Elements:	Options may be any of the following separated by commas:

clock=speed speed is a constant 1-100000000 (1 hz to 100 mhz). This number can contains commas. This number also supports the following denominations: M, MHZ, K, KHZ. This specifies the clock the CPU runs at. Depending on the PIC this is 2 or 4 times the instruction rate. This directive is not needed if the following ***type=speed*** is used and there is no frequency multiplication or division.

type=speed type defines what kind of clock you are using, and the following values are valid: oscillator, osc (same as oscillator), crystal, xtal (same as crystal), internal, int (same as internal) or rc. The compiler will automatically set the oscillator configuration bits based upon your defined type. If you specified internal, the compiler will also automatically set the internal oscillator to the defined speed. Configuration fuses are modified when this option is used. Speed is the input frequency.

restart_wdt will restart the watchdog timer on every delay_us() and delay_ms() use.

clock_out when used with the internal or oscillator types this enables the clockout pin to output the clock.

fast_start some chips allow the chip to begin execution using an internal clock until the primary clock is stable.

lock some chips can prevent the oscillator type from being changed at run time by the software.

USB or USB_FULL for devices with a built-in USB peripheral. When used with the ***type=speed*** option the compiler will set the correct configuration bits for the USB peripheral to operate at Full-Speed.

USB_LOW for devices with a built-in USB peripheral. When used with the ***type=speed*** option the compiler will set the correct configuration bits for the USB peripheral to operate at Low-Speed.

PLL_WAIT for devices with a PLL and a PLL Ready Status flag to test. When a PLL clock is specified it will cause the compiler to poll the ready PLL Ready Flag and only continue program execution when flag indicates that the PLL is ready.

ACT or ACT=type for device with Active Clock Tuning, type can be either USB or SOSC. If only using ACT type will default to USB. ACT=USB causes the compiler to enable the active clock tuning and to tune the internal oscillator to the USB clock. ACT=SOSC causes

the compiler to enable the active clock tuning and to tune the internal oscillator to the secondary clock at 32.768 kHz. ACT can only be used when the system clock is set to run from the internal oscillator.

Also See: [delay_ms\(\)](#), [delay_us\(\)](#)

#use dynamic_memory

Syntax: **#USE DYNAMIC_MEMORY**

Elements: *None*

Purpose: This pre-processor directive instructs the compiler to create the `_DYNAMIC_HEAD` object. `_DYNAMIC_HEAD` is the location where the first free space is allocated.

Examples:

```
#USE DYNAMIC_MEMORY
void main ( ){
}
```

Example Files: [ex_malloc.c](#)

Also See: None

#use fast_io

Syntax: **#USE FAST_IO** (*port*)

Elements: *port* is A, B, C, D, E, F, G, H, J or ALL

Purpose: Affects how the compiler will generate code for input and output instructions that follow. This directive takes effect until another `#use xxxx_IO` directive is encountered. The fast method of doing I/O will

	cause the compiler to perform I/O without programming of the direction register. The compiler's default operation is the opposite of this command, the direction I/O will be set/cleared on each I/O operation. The user must ensure the direction register is set correctly via <code>set_tris_X()</code> . When linking multiple compilation units be aware this directive only applies to the current compilation unit.
Examples:	<code>#use fast_io(A)</code>
Example Files:	ex_cust.c
Also See:	#USE FIXED_IO , #USE STANDARD_IO , set_tris_X() , General Purpose I/O

#use fixed_io

Syntax:	#USE FIXED_IO (<i>port_outputs=pin, pin?</i>)
Elements:	port is A-G, pin is one of the pin constants defined in the devices .h file.
Purpose:	This directive affects how the compiler will generate code for input and output instructions that follow. This directive takes effect until another <code>#USE XXX_IO</code> directive is encountered. The fixed method of doing I/O will cause the compiler to generate code to make an I/O pin either input or output every time it is used. The pins are programmed according to the information in this directive (not the operations actually performed). This saves a byte of RAM used in standard I/O. When linking multiple compilation units be aware this directive only applies to the current compilation unit.
Examples:	<code>#use fixed_io(a_outputs=PIN_A2, PIN_A3)</code>
Example Files:	None
Also See:	#USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

#use i2c

Syntax:

#USE I2C (*options*)

Elements:

Options are separated by commas and may be:

MASTER	Sets to the master mode
MULTI_MASTER	Set the multi_master mode
SLAVE	Set the slave mode
SCL=pin	Specifies the SCL pin (pin is a bit address)
SDA=pin	Specifies the SDA pin
ADDRESS=nn	Specifies the slave mode address
FAST	Use the fast I2C specification.
FAST=nnnnnn	Sets the speed to nnnnnn hz
SLOW	Use the slow I2C specification
RESTART_WDT	Restart the WDT while waiting in I2C_READ
FORCE_HW	Use hardware I2C functions.
FORCE_SW	Use software I2C functions.
NOFLOAT_HIGH	Does not allow signals to float high, signals are driven from low to high
SMBUS	Bus used is not I2C bus, but very similar
STREAM=id	Associates a stream identifier with this I2C port. The identifier may then be used in functions like i2c_read or i2c_write.
NO_STRETCH	Do not allow clock stretching
MASK=nn	Set an address mask for parts that support it
I2C1	Instead of SCL= and SDA= this sets the pins to the first module
I2C2	Instead of SCL= and SDA= this sets the pins to the second module
NOINIT	No initialization of the I2C peripheral is performed. Use I2C_INIT() to initialize peripheral at run time.

Only some chips allow the following:	
DATA_HOLD	No ACK is sent until I2C_READ is called (slave only)
ADDRESS_HOLD	No ACK is sent until I2C_read is called for (slave only)
SDA_HOLD	Min of 300ns holdtime on SDA a from SCI

Purpose:

CCS offers support for the hardware-based I2C™ and a software-based master I2C™ device.(For more information on the hardware-based I2C module, please consult the datasheet for your target device; not all PICs support I2C™.

The I2C library contains functions to implement an I2C bus. The #USE I2C remains in effect for the I2C_START, I2C_STOP, I2C_READ, I2C_WRITE and I2C_POLL functions until another USE I2C is encountered. Software functions are generated unless the FORCE_HW is specified. The SLAVE mode should only be used with the built-in SSP. The functions created with this directive are exported when using multiple compilation units. To access the correct function use the stream identifier.

Examples:

```
#use I2C(master, sda=PIN_B0, scl=PIN_B1)

#use I2C(slave,sda=PIN_C4,scl=PIN_C3
        address=0xa0, FORCE_HW)

#use I2C(master, scl=PIN_B0, sda=PIN_B1, fast=450000)
//sets the target speed to 450 KBSP
```

Example Files:

[ex_extee.c](#) with [16c74.h](#)

Also See:

[i2c_poll](#), [i2c_speed](#), [i2c_start](#), [i2c_stop](#), [i2c_slaveaddr](#), [i2c_isr_state](#), [i2c_write](#), [i2c_read](#), [I2C Overview](#)

#use profile()

Syntax:	#use profile(options)
Elements:	<i>options</i> may be any of the following, comma separated:

	ICD	Default – configures code profiler to use the ICD connection.
	TIMER1	Optional. If specified, the code profiler run-time on the microcontroller will use the Timer1 peripheral as a timestamp for all profile events. If not specified the code profiler tool will use the PC clock, which may not be accurate for fast events.
	BAUD=x	Optional. If specified, will use a different baud rate between the microcontroller and the code profiler tool. This may be required on slow microcontrollers to attempt to use a slower baud rate.
Purpose:	Tell the compiler to add the code profiler run-time in the microcontroller and configure the link and clock.	
Examples:	#profile(ICD, TIMER1, baud=9600)	
Example Files:	ex_profile.c	
Also See:	#profile() , profileout() , Code Profile overview	

#use pwm()

Syntax:	#use pwm (options)	
Elements:	options are separated by commas and may be:	
	PWMx or CCPx	Selects the CCP to use, x being the module number to use.
	OUTPUT=PIN_xx	Selects the PWM pin to use, pin must be one of the CCP pins. If device has remappable pins compiler will assign specified pin to specified CCP module. If CCP module not specified it will assign remappable pin to first available module.
	TIMER=x	Selects timer to use with PWM module,

	FREQUENCY=x	<p>default if not specified is timer 2.</p> <p>Sets the period of PWM based off specified value, should not be used if PERIOD is already specified. If frequency can't be achieved exactly compiler will generate a message specifying the exact frequency and period of PWM. If neither FREQUENCY or PERIOD is specified, the period defaults to maximum possible period with maximum resolution and compiler will generate a message specifying the frequency and period of PWM, or if using same timer as previous stream instead of setting to maximum possible it will be set to the same as previous stream. If using same timer as previous stream and frequency is different compiler will generate an error.</p>
	PERIOD=x	<p>Sets the period of PWM, should not be used if FREQUENCY is already specified. If period can't be achieved exactly compiler will generate a message specifying the exact period and frequency of PWM. If neither PERIOD or FREQUENCY is specified, the period defaults to maximum possible period with maximum resolution and compiler will generate a message specifying the frequency and period of PWM, or if using same timer as previous stream instead of setting to maximum possible it will be set to the same as previous stream. If using same timer as previous stream and period is different compiler will generate an error.</p>
	BITS=x	<p>Sets the resolution of the the duty cycle, if period or frequency is specified will adjust the period to meet set resolution and will generate an message specifying the frequency and duty of PWM. If period or frequency not specified will set period to maximum possible for specified resolution and compiler will generate a message specifying the frequency and period of PWM, unless using same timer as previous then it will generate an error if resolution is different then previous stream. If not</p>

		specified then frequency, period or previous stream using same timer sets the resolution.
	DUTY=x	Selects the duty percentage of PWM, default if not specified is 50%.
	PWM_ON	Initialize the PWM in the ON state, default state if pwm_on or pwm_off is not specified.
	PWM_OFF	Initialize the PWM in the OFF state.
	STREAM=id	Associates a stream identifier with the PWM signal. The identifier may be used in functions like pwm_set_duty_percent().
Purpose:	<p>This directive tells the compiler to setup a PWM on the specified pin using the specified frequency, period, duty cycle and resolution. The #USE DELAY directive must appear before this directive can be used.</p> <p>This directive enables use of built-in functions such as set_pwm_duty_percent(), set_pwm_frequency(), set_pwm_period(), pwm_on() and pwm_off().</p>	
Examples:	None	
Also See:	pwm_on() , pwm_off() , pwm_set_frequency() , pwm_set_duty_percent() , pwm_set_duty()	

#use rs232

Syntax:	#USE RS232 (<i>options</i>)	
Elements:	Options are separated by commas and may be:	
	STREAM=id	Associates a stream identifier with this RS232 port. The identifier may then be used in functions like fputc.
	BAUD=x	Set baud rate to x
	XMIT=pin	Set transmit pin

RCV=pin	Set receive pin
FORCE_SW	Will generate software serial I/O routines even when the UART pins are specified.
BRGH1OK	Allow bad baud rates on chips that have baud rate problems.
ENABLE=pin	The specified pin will be high during transmit. This may be used to enable 485 transmit.
DEBUGGER	Indicates this stream is used to send/receive data through a CCS ICD unit. The default pin used is B3, use XMIT= and RCV= to change the pin used. Both should be the same pin.
RESTART_WDT	Will cause GETC() to clear the WDT as it waits for a character.
INVERT	Invert the polarity of the serial pins (normally not needed when level converter, such as the MAX232). May not be used with the internal UART.
PARITY=X	Where x is N, E, or O.
BITS =X	Where x is 5-9 (5-7 may not be used with the SCI).
FLOAT_HIGH	The line is not driven high. This is used for open collector outputs. Bit 6 in RS232_ERRORS is set if the pin is not high at the end of the bit time.
ERRORS	Used to cause the compiler to keep receive errors in the variable RS232_ERRORS and to reset errors when they occur, and RS232_BUFFER_ERRORS when transmit or RECEIVE_BUFFER are used.

SAMPLE_EARLY	A getc() normally samples data in the middle of a bit time. This option causes the sample to be at the start of a bit time. May not be used with the UART.
RETURN=pin	For FLOAT_HIGH and MULTI_MASTER this is the pin used to read the signal back. The default for FLOAT_HIGH is the XMIT pin and for MULTI_MASTER the RCV pin.
MULTI_MASTER	Uses the RETURN pin to determine if another master on the bus is transmitting at the same time. If a collision is detected bit 6 is set in RS232_ERRORS and all future PUTC's are ignored until bit 6 is cleared. The signal is checked at the start and end of a bit time. May not be used with the UART.
LONG_DATA	Makes getc() return an int16 and putc accept an int16. This is for 9 bit data formats.
DISABLE_INTS	Will cause interrupts to be disabled when the routines get or put a character. This prevents character distortion for software implemented I/O and prevents interaction between I/O in interrupt handlers and the main program when using the UART.
STOP=X	To set the number of stop bits (default is 1). This works for both UART and non-UART ports.
TIMEOUT=X	To set the time getc() waits for a byte in milliseconds. If no character comes in within this time the RS232_ERRORS is set to 0 as well as the return value from getc(). This

	works for both UART and non-UART ports.
SYNC_SLAVE	Makes the RS232 line a synchronous slave, making the receive pin a clock in, and the data pin the data in/out.
SYNC_MASTER	Makes the RS232 line a synchronous master, making the receive pin a clock out, and the data pin the data in/out.
SYNC_MASTER_CONT	Makes the RS232 line a synchronous master mode in continuous receive mode. The receive pin is set as a clock out, and the data pin is set as the data in/out.
UART1	Sets the XMIT= and RCV= to the chips first hardware UART.
UART2	Sets the XMIT= and RCV= to the chips second hardware UART.
NOINIT	No initialization of the UART peripheral is performed. Useful for dynamic control of the UART baud rate or initializing the peripheral manually at a later point in the program's run time. If this option is used, then <code>setup_uart()</code> needs to be used to initialize the peripheral. Using a serial routine (such as <code>getc()</code> or <code>putc()</code>) before the UART is initialized will cause undefined behavior.
ICD	Indicates this stream is used to send/receive data through a CCS ICD unit. The default transmit pin is the PIC's ICSPDAT/PGD pin and the default receive pin is the PIC's ICSPCLK/PGC pin. Use XMIT= and RCV= to change the pins used.
UART3	Sets the XMIT= and RCV= to the device's third hardware UART.
UART4	Sets the XMIT= and RCV= to the

	device's fourth hardware UART.
ICD	Indicates this stream uses the ICD in a special pass through mode to send/receive serial data to/from PC. The ICSP clock line is the PIC's receive pin, usually pin B6, and the ICSP data line is the PIC's transmit pin, usually pin B7.
MAX_ERROR=x	Specifies the max error percentage the compiler can set the RS232 baud rate from the specified baud before generating an error. Defaults to 3% if not specified.
Serial Buffer Options:	
RECEIVE_BUFFER=x	Size in bytes of UART circular receive buffer, default if not specified is zero. Uses an interrupt to receive data, supports RDA interrupt or external interrupts.
TRANSMIT_BUFFER=x	Size in bytes of UART circular transmit buffer, default if not specified is zero.
TXISR	If TRANSMIT_BUFFER is greater then zero specifies using TBE interrupt for transmitting data. Default is NOTXISR if TXISR or NOTXISR is not specified. TXISR option can only be used when using hardware UART.
NOTXISR	If TRANSMIT_BUFFER is greater then zero specifies to not use TBE interrupt for transmitting data. Default is NOTXISR if TXISR or NOTXISR is not specified and XMIT_BUFFER is greater then zero
Flow Control Options:	
RTS = PIN_xx	Pin to use for RTS flow control. When using FLOW_CONTROL_MODE this pin is driven to the active level when it is ready to receive more data. In SIMPLEX_MODE the pin is driven to the active level when it has data to transmit. FLOW_CONTROL_MODE can only be use when using RECEIVE_BUFFER

	RTS_LEVEL=x	Specifies the active level of the RTS pin, HIGH is active high and LOW is active low. Defaults to LOW if not specified.
	CTS = PIN_xx	Pin to use for CTS flow control. In both FLOW_CONTROL_MODE and SIMPLEX_MODE this pin is sampled to see if it clear to send data. If pin is at active level and there is data to send it will send next data byte.
	CTS_LEVEL=x	Specifies the active level of the CTS pin, HIGH is active high and LOW is active low. Default to LOW if not specified
	FLOW_CONTROL_MODE	Specifies how the RTS pin is used. For FLOW_CONTROL_MODE the RTS pin is driven to the active level when ready to receive data. Defaults to FLOW_CONTROL_MODE when neither FLOW_CONTROL_MODE or SIMPLEX_MODE is specified. If RTS pin is not specified then this option is not used.
	SIMPLEX_MODE	Specifies how the RTS pin is used. For SIMPLEX_MODE the RTS pin is driven to the active level when it has data to send. Defaults to FLOW_CONTROL_MODE when neither FLOW_CONTROL_MODE or SIMPLEX_MODE is specified. If RTS pin is not specified then this option is not used.
Purpose:	<p>This directive tells the compiler the baud rate and pins used for serial I/O. This directive takes effect until another RS232 directive is encountered. The #USE DELAY directive must appear before this directive can be used. This directive enables use of built-in functions such as GETC, PUTC, and PRINTF. The functions created with this directive are exported when using multiple compilation units. To access the correct function use the stream identifier.</p> <p>When using parts with built-in SCI and the SCI pins are specified, the SCI will be used. If a baud rate cannot be achieved within 3% of the desired value using the current clock rate, an error will be generated.</p>	

The definition of the RS232_ERRORS is as follows:

No UART:

- Bit 7 is 9th bit for 9 bit data mode (get and put).
- Bit 6 set to one indicates a put failed in float high mode.

With a UART:

- Used only by get:
- Copy of RCSTA register except:
- Bit 0 is used to indicate a parity error.

The definition of the RS232_BUFFER_ERRORS variable is as follows:

- Bit 0 UART Receive overrun error occurred.
- Bit 1 Receive Buffer overflowed.
- Bit 2 Transmit Buffer overflowed.

Warning:

The PIC UART will shut down on overflow (3 characters received by the hardware with a GETC() call). The "ERRORS" option prevents the shutdown by detecting the condition and resetting the UART.

Examples:

```
#use rs232 (baud=9600, xmit=PIN_A2,rcv=PIN_A3)
```

Example Files:

[ex_cust.c](#)

Also See:

[getc\(\)](#), [putc\(\)](#), [printf\(\)](#), [setup_uart\(\)](#), [RS232 I/O overview](#), [kbhit\(\)](#), [puts\(\)](#), [putc_send\(\)](#), [rcv_buffer_bytes\(\)](#), [tx_buffer_bytes\(\)](#), [rcv_buffer_full\(\)](#), [tx_buffer_full\(\)](#), [tx_buffer_available\(\)](#)

#use rtos

(The RTOS is only included with the PCW and PCWH packages.)

The CCS Real Time Operating System (RTOS) allows a PIC micro controller to run regularly scheduled tasks without the need for interrupts. This is accomplished by a function (RTOS_RUN()) that acts as a dispatcher. When a task is scheduled to run, the dispatch function gives control of the processor to that task. When the task is done executing or does not need the processor anymore, control of the processor is returned to the dispatch function which then will give control of the processor to the next task that is

scheduled to execute at the appropriate time. This process is called cooperative multi-tasking.

Syntax:	#USE RTOS (options)	
Elements:	options are separated by comma and may be:	
	timer=X	Where x is 0-4 specifying the timer used by the RTOS.
	minor_cycle=time	Where time is a number followed by s, ms, us, ns. This is the longest time any task will run. Each task's execution rate must be a multiple of this time. The compiler can calculate this if it is not specified.
	statistics	Maintain min, max, and total time used by each task.
Purpose:	This directive tells the compiler which timer on the PIC to use for monitoring and when to grant control to a task. Changes to the specified timer's prescaler will effect the rate at which tasks are executed.	
	This directive can also be used to specify the longest time that a task will ever take to execute with the minor_cycle option. This simply forces all task execution rates to be a multiple of the minor_cycle before the project will compile successfully. If the this option is not specified the compiler will use a minor_cycle value that is the smallest possible factor of the execution rates of the RTOS tasks.	
	If the statistics option is specified then the compiler will keep track of the minimum processor time taken by one execution of each task, the maximum processor time taken by one execution of each task, and the total processor time used by each task.	
	When linking multiple compilation units, this directive must appear exactly the same in each compilation unit.	
Examples:	#use rtos(timer=0, minor_cycle=20ms)	
Also See:	#TASK	

#use spi

Syntax:	#USE SPI (<i>options</i>)																																																					
Elements:	<i>Options</i> are separated by commas and may be:																																																					
	<table> <tr> <td>MASTER</td><td>Set the device as the master. (default)</td></tr> <tr> <td>SLAVE</td><td>Set the device as the slave.</td></tr> <tr> <td>BAUD=n</td><td>Target bits per second, default is as fast as possible.</td></tr> <tr> <td>CLOCK_HIGH=n</td><td>High time of clock in us (not needed if BAUD= is used). (default=0)</td></tr> <tr> <td>CLOCK_LOW=n</td><td>Low time of clock in us (not needed if BAUD= is used). (default=0)</td></tr> <tr> <td>DI=pin</td><td>Optional pin for incoming data.</td></tr> <tr> <td>DO=pin</td><td>Optional pin for outgoing data.</td></tr> <tr> <td>CLK=pin</td><td>Clock pin.</td></tr> <tr> <td>MODE=n</td><td>The mode to put the SPI bus.</td></tr> <tr> <td>ENABLE=pin</td><td>Optional pin to be active during data transfer.</td></tr> <tr> <td>LOAD=pin</td><td>Optional pin to be pulsed active after data is transferred.</td></tr> <tr> <td>DIAGNOSTIC=pin</td><td>Optional pin to the set high when data is sampled.</td></tr> <tr> <td>SAMPLE_RISE</td><td>Sample on rising edge.</td></tr> <tr> <td>SAMPLE_FALL</td><td>Sample on falling edge (default).</td></tr> <tr> <td>BITS=n</td><td>Max number of bits in a transfer. (default=32)</td></tr> <tr> <td>SAMPLE_COUNT=n</td><td>Number of samples to take (uses majority vote). (default=1)</td></tr> <tr> <td>LOAD_ACTIVE=n</td><td>Active state for LOAD pin (0, 1).</td></tr> <tr> <td>ENABLE_ACTIVE=n</td><td>Active state for ENABLE pin (0, 1). (default=0)</td></tr> <tr> <td>IDLE=n</td><td>Inactive state for CLK pin (0, 1). (default=0)</td></tr> <tr> <td>ENABLE_DELAY=n</td><td>Time in us to delay after ENABLE is activated. (default=0)</td></tr> <tr> <td>DATA_HOLD=n</td><td>Time between data change and clock change</td></tr> <tr> <td>LSB_FIRST</td><td>LSB is sent first.</td></tr> <tr> <td>MSB_FIRST</td><td>MSB is sent first. (default)</td></tr> <tr> <td>STREAM=id</td><td>Specify a stream name for this protocol.</td></tr> <tr> <td>SPI1</td><td>Use the hardware pins for SPI Port 1</td></tr> <tr> <td>SPI2</td><td>Use the hardware pins for SPI Port 2</td></tr> <tr> <td>FORCE_SW</td><td>Use a software implementation even when</td></tr> </table>	MASTER	Set the device as the master. (default)	SLAVE	Set the device as the slave.	BAUD=n	Target bits per second, default is as fast as possible.	CLOCK_HIGH=n	High time of clock in us (not needed if BAUD= is used). (default=0)	CLOCK_LOW=n	Low time of clock in us (not needed if BAUD= is used). (default=0)	DI=pin	Optional pin for incoming data.	DO=pin	Optional pin for outgoing data.	CLK=pin	Clock pin.	MODE=n	The mode to put the SPI bus.	ENABLE=pin	Optional pin to be active during data transfer.	LOAD=pin	Optional pin to be pulsed active after data is transferred.	DIAGNOSTIC=pin	Optional pin to the set high when data is sampled.	SAMPLE_RISE	Sample on rising edge.	SAMPLE_FALL	Sample on falling edge (default).	BITS=n	Max number of bits in a transfer. (default=32)	SAMPLE_COUNT=n	Number of samples to take (uses majority vote). (default=1)	LOAD_ACTIVE=n	Active state for LOAD pin (0, 1).	ENABLE_ACTIVE=n	Active state for ENABLE pin (0, 1). (default=0)	IDLE=n	Inactive state for CLK pin (0, 1). (default=0)	ENABLE_DELAY=n	Time in us to delay after ENABLE is activated. (default=0)	DATA_HOLD=n	Time between data change and clock change	LSB_FIRST	LSB is sent first.	MSB_FIRST	MSB is sent first. (default)	STREAM=id	Specify a stream name for this protocol.	SPI1	Use the hardware pins for SPI Port 1	SPI2	Use the hardware pins for SPI Port 2	FORCE_SW
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	hardware pins are specified
FORCE_HW	Use the pic hardware SPI.
NOINIT	Do not initialize the hardware SPI Port

Purpose:	<p>The SPI library contains functions to implement an SPI bus. After setting all of the proper parameters in #USE SPI, the spi_xfer() function can be used to both transfer and receive data on the SPI bus.</p> <p>The SPI1 and SPI2 options will use the SPI hardware onboard the PIC. The most common pins present on hardware SPI are: DI, DO, and CLK. These pins don't need to be assigned values through the options; the compiler will automatically assign hardware-specific values to these pins. Consult your PIC's data sheet as to where the pins for hardware SPI are. If hardware SPI is not used, then software SPI will be used. Software SPI is much slower than hardware SPI, but software SPI can use any pins to transfer and receive data other than just the pins tied to the PIC's hardware SPI pins.</p> <p>The MODE option is more or less a quick way to specify how the stream is going to sample data. MODE=0 sets IDLE=0 and SAMPLE_RISE. MODE=1 sets IDLE=0 and SAMPLE_FALL. MODE=2 sets IDLE=1 and SAMPLE_FALL. MODE=3 sets IDLE=1 and SAMPLE_RISE. There are only these 4 MODEs.</p> <p>SPI cannot use the same pins for DI and DO. If needed, specify two streams: one to send data and another to receive data.</p> <p>The pins must be specified with DI, DO, CLK or SPIx, all other options are defaulted as indicated above.</p> <pre>#use spi(DI=PIN_B1, DO=PIN_B0, CLK=PIN_B2, ENABLE=PIN_B4, BITS=16) // uses software SPI</pre>
Examples:	<pre>#use spi(FORCE_HW, BITS=16, stream=SPI_STREAM) // uses hardware SPI and gives this stream the name SPI_STREAM</pre>
Example Files:	None
Also See:	spi_xfer()

#use standard_io

Syntax:	#USE STANDARD_IO (<i>port</i>)
Elements:	<i>port</i> is A, B, C, D, E, F, G, H, J or ALL
Purpose:	<p>This directive affects how the compiler will generate code for input and output instructions that follow. This directive takes effect until another #USE XXX_IO directive is encountered. The standard method of doing I/O will cause the compiler to generate code to make an I/O pin either input or output every time it is used. On the 5X processors this requires one byte of RAM for every port set to standard I/O.</p> <p>Standard_io is the default I/O method for all ports.</p> <p>When linking multiple compilation units be aware this directive only applies to the current compilation unit.</p>
Examples:	<code>#use standard_io(A)</code>
Example Files:	ex_cust.c
Also See:	#USE FAST_IO , #USE FIXED_IO , General Purpose I/O

#use timer

Syntax:	#USE TIMER (options)
Elements:	<p>TIMER=x Sets the timer to use as the tick timer. x is a valid timer that the PIC has. Default value is 1 for Timer 1.</p> <p>TICK=xx Sets the desired time for 1 tick. xx can be used with ns(nanoseconds), us (microseconds), ms (milliseconds), or s (seconds). If the desired tick time can't be achieved it will set the time to closest achievable time and will generate a warning specifying the exact tick time. The default value is 1us.</p>

BITS=x

Sets the variable size used by the `get_ticks()` and `set_ticks()` functions for returning and setting the tick time. `x` can be 8 for 8 bits, 16 for 16 bits or 32 for 32bits. The default is 32 for 32 bits.

ISR

Uses the timer's interrupt to increment the upper bits of the tick timer. This mode requires the the global interrupt be enabled in the main program.

NOISR

The `get_ticks()` function increments the upper bits of the tick timer. This requires that the `get_ticks()` function be called more often then the timer's overflow rate. NOISR is the default mode of operation.

STREAM=id

Associates a stream identifier with the tick timer. The identifier may be used in functions like `get_ticks()`.

DEFINE=id

Creates a define named `id` which specifies the number of ticks that will occur in one second. Default define name if not specified is `TICKS_PER_SECOND`. Define name must start with an ASCII letter 'A' to 'Z', an ASCII letter 'a' to 'z' or an ASCII underscore ('_').

COUNTER or COUNTER=x

Sets up specified timer as a counter instead of timer. `x` specifies the prescalar to setup counter with, default is 1 if `x` is not specified. The function `get_ticks()` will return the current count and the function `set_ticks()` can be used to set count to a specific starting value or to clear counter.

Purpose:

This directive creates a tick timer using one of the PIC's timers. The tick timer is initialized to zero at program start. This directive also creates the define `TICKS_PER_SECOND` as a floating point number, which specifies that number of ticks that will occur in one second.

Examples:

```
#USE TIMER (TIMER=1, TICK=1ms, BITS=16, NOISR)

unsigned int16 tick_difference(unsigned int16 current,
unsigned int16 previous) {
    return(current - previous);
}

void main(void) {
```

```

        unsigned int16 current_tick, previous_tick;
        current_tick = previous_tick = get_ticks();
        while(TRUE) {
            current_tick = get_ticks();
            if(tick_difference(current_tick, previous_tick) >
1000) {
                output_toggle(PIN_B0);
                previous_tick = current_tick;
            }
        }
    }
}

```

Example Files: None

Also See: [get_ticks\(\)](#), [set_ticks\(\)](#)

#use touchpad

Syntax: **#USE TOUCHPAD (options)**

Elements:

RANGE=x

Sets the oscillator charge/discharge current range. If x is L, current is nominally 0.1 microamps. If x is M, current is nominally 1.2 microamps. If x is H, current is nominally 18 microamps. Default value is H (18 microamps).

THRESHOLD=x

x is a number between 1-100 and represents the percent reduction in the nominal frequency that will generate a valid key press in software. Default value is 6%.

SCANTIME=xxMS

xx is the number of milliseconds used by the microprocessor to scan for one key press. If utilizing multiple touch pads, each pad will use xx milliseconds to scan for one key press. Default is 32ms.

PIN=char

If a valid key press is determined on "PIN", the software will return the character "char" in the function touchpad_getc(). (Example: PIN_B0='A')

	<p>SOURCETIME=xxus (CTMU only) xx is thenumber of microseconds each pin is sampled for by ADC during each scan time period. Default is 10us.</p>
Purpose:	<p>This directive will tell the compiler to initialize and activate the Capacitive Sensing Module (CSM)or Charge Time Measurement Unit (CTMU) on the microcontroller. The compiler requires use of the TIMER0 and TIMER1 modules for CSM and Timer1 ADC modules for CTMU, and global interrupts must still be activated in the main program in order for the CSM or CTMU to begin normal operation. For most applications, a higher RANGE, lower THRESHOLD, and higher SCANTIME will result better key press detection. Multiple PIN's may be declared in "options", but they must be valid pins used by the CSM or CTMU. The user may also generate a TIMER0 ISR with TIMER0's interrupt occuring every SCANTIME milliseconds. In this case, the CSM's or CTMU's ISR will be executed first.</p>
Examples:	<pre>#USE TOUCHPAD (THRESHOLD=5, PIN D5='5', PIN B0='C') void main(void) { char c; enable_interrupts(GLOBAL); while(1){ c = TOUCHPAD GETC(); //will wait until a pin is detected //if PIN_B0 is pressed, c will } //if PIN_B0 is pressed, c will have 'C' } //if PIN D5 is pressed, c will have '5'</pre>
Example Files:	None
Also See:	touchpad_state() , touchpad_getc() , touchpad_hit()

#warning

Syntax:	#WARNING <i>text</i>
Elements:	<i>text</i> is optional and may be any text

Purpose:

Forces the compiler to generate a warning at the location this directive appears in the file. The text may include macros that will be expanded for the display. This may be used to see the macro expansion. The command may also be used to alert the user to an invalid compile time situation.

To prevent the warning from being counted as a warning, use this syntax: `#warning/information text`

Examples:

```
#if BUFFER_SIZE < 32
#warning Buffer Overflow may occur
#endif
```

Example Files:

[ex_psp.c](#)

Also See:

[#ERROR](#)

#word

Syntax:

#WORD *id* = *x*

Elements:

id is a valid C identifier,

x is a C variable or a constant

Purpose:

If the *id* is already known as a C variable then this will locate the variable at address *x*. In this case the variable type does not change from the original definition. If the *id* is not known a new C variable is created and placed at address *x* with the type `int16`

Warning: In both cases memory at *x* is not exclusive to this variable. Other variables may be located at the same location. In fact when *x* is a variable, then *id* and *x* share the same memory location.

Examples:

```
#word data = 0x0800

struct {
    int lowerByte : 8;
    int upperByte : 8;
```

	<pre>} control_word; #word control_word = 0x85 ... control_word.upperByte = 0x42;</pre>
Example Files:	None
Also See:	#bit , #byte , #locate , #reserve , Named Registers , Type Specifiers , Type Qualifiers , Enumerated Types , Structures & Unions , Typedef

#zero_ram

Syntax:	#ZERO_RAM
Elements:	None
Purpose:	This directive zero's out all of the internal registers that may be used to hold variables before program execution begins.
Examples:	<pre>#zero_ram void main() { } </pre>
Example Files:	ex_cust.c
Also See:	None

BUILT-IN FUNCTIONS

BUILT-IN FUNCTIONS

The CCS compiler provides a lot of built-in functions to access and use the PIC microcontroller's peripherals. This makes it very easy for the users to configure and use the peripherals without going into in depth details of the registers associated with the functionality. The functions categorized by the peripherals associated with them are listed on the next page. Click on the function name to get a complete description and parameter and return value descriptions.

abs()

Syntax:	value = abs(x)
Parameters:	x is a signed 8, 16, or 32 bit int or a float
Returns:	Same type as the parameter.
Function:	Computes the absolute value of a number.
Availability:	All devices
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>signed int target, actual; ... error = abs(target-actual);</pre>
Example Files:	None
Also See:	labs()

sin()
atan()

cos()
sinh()

tan()
cosh()

asin()
tanh()

acos()
atan2()

Syntax:

val = sin (rad)
val = cos (rad)
val = tan (rad)
rad = asin (val)
rad1 = acos (val)
rad = atan (val)
rad2=atan2(val, val)
result=sinh(value)
result=cosh(value)
result=tanh(value)

Parameters:

rad is a float representing an angle in Radians -2pi to 2pi.
val is a float with the range -1.0 to 1.0.
Value is a float

rad is a float representing an angle in Radians -pi/2 to pi/2

val is a float with the range -1.0 to 1.0.

Returns:

rad1 is a float representing an angle in Radians 0 to pi

rad2 is a float representing an angle in Radians -pi to pi
Result is a float

Function:

These functions perform basic Trigonometric functions.	
sin	returns the sine value of the parameter (measured in radians)
cos	returns the cosine value of the parameter (measured in radians)
tan	returns the tangent value of the parameter (measured in radians)
asin	returns the arc sine value in the range [-pi/2,+pi/2] radians
acos	returns the arc cosine value in the range[0,pi] radians
atan	returns the arc tangent value in the range [-pi/2,+pi/2] radians
atan2	returns the arc tangent of y/x in the range [-pi,+pi] radians
sinh	returns the hyperbolic sine of x
cosh	returns the hyperbolic cosine of x
tanh	returns the hyperbolic tangent of x

Note on error handling:

If "errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.

Domain error occurs in the following cases:

asin: when the argument not in the range[-1,+1]

acos: when the argument not in the range[-1,+1]

atan2: when both arguments are zero

Range error occur in the following cases:

cosh: when the argument is too large

sinh: when the argument is too large

Availability: All devices

Requires: #INCLUDE <math.h>

Examples:

```
float phase;
// Output one sine wave
for(phase=0; phase<2*3.141596; phase+=0.01)
    set_analog_voltage( sin(phase)+1 );
```

Example Files: [ex_tank.c](#)

Also See: [log\(\)](#), [log10\(\)](#), [exp\(\)](#), [pow\(\)](#), [sqrt\(\)](#)

adc_done()

Syntax: value = adc_done();

Parameters: None
channel is an optional parameter for specifying the channel to check if the conversion is done. If not specified will use channel specified in the last call to set_adc_channel(), read_adc() or adc_done(). Only available for dsPIC33EPxxGSxxx family.

Returns: A short int. TRUE if the A/D converter is done with conversion, FALSE if it

	is still busy.
Function:	Can be polled to determine if the A/D has valid data.
Availability:	Only available on devices with built in analog to digital converters
Requires:	None
Examples:	<pre>int16 value; setup_adc_ports(sAN0 sAN1, VSS_VDD); setup_adc(ADC_CLOCK_DIV_4 ADC_TAD_MUL_8); set_adc_channel(0); read_adc(ADC_START_ONLY); int1 done = adc_done(); while(!done) { done = adc_done(); } value = read_adc(ADC_READ_ONLY); printf("A/C value = %IX\n\r", value); }</pre>
Example Files:	None
Also See:	setup_adc() , set_adc_channel() , setup_adc_ports() , read_adc() , ADC Overview

adc_read()

Syntax:	result=adc_read(register)
Parameters:	register - ADC register to read: <ul style="list-style-type: none">• ADC_RESULT• ADC_ACCUMULATOR• ADC_FILTER
Returns:	int8 or in16 read from the specified register. Return size depends on which register is being read. For example, ADC_RESULT register is 16 bits and ADC_COUNT register is 8-bits.
Function:	Reads one of the Analog-to-Digital Converter with Computation (ADC2)

	Module registers
Availability:	All devices with an ADC2 Module
Requires:	Constants defined in the device's .h file
Examples:	<code>FilteredResult=adc_read(ADC_FILTER);</code>
Also See:	ADC Overview , setup_adc() , setup_adc_ports() , set_adc_channel() , read_adc() , #DEVICE , adc_write() , adc_status() , set_adc_trigger()

adc_status()

Syntax:	status=adc_status()
Parameters:	None
Returns:	int8 value of the ADSTAT register
Function:	Read the current value of the ADSTAT register of the Analog-to-Digital Converter with Computation (ADC2) Module.
Availability:	All devices with an ADC2 Module
Requires:	Nothing
Examples:	<code>while((adc_status() & ADC_UPDATING)==0);</code> <code>Average=adc_read(ADC_FILTER);</code>
Also See:	ADC Overview , setup_adc() , setup_adc_ports() , set_adc_channel() , read_adc() , #DEVICE , adc_read() , adc_write() , set_adc_trigger()

adc_write()

Syntax:	adc_write (register, value)
Parameters:	register - ADC register to write: <ul style="list-style-type: none"> • ADC_REPEAT • ADC_SET_POINT • ADC_LOWER_THRESHOLD • ADC_UPPER_THRESHOLD
Returns:	undefined
Function:	Write one of the Analog-to-Digital Converter with Computation (ADC2) Module registers.
Availability:	All devices with an ADC2 Module
Requires:	Constants defined in the device's .h file
Examples:	<code>adc_write(ADC_SET_POINT, 300);</code>
Also See:	ADC Overview , setup_adc() , setup_adc_ports() , set_adc_channel() , read_adc() , #DEVICE , adc_read() , adc_status() , set_adc_trigger()

assert()

Syntax:	assert (<i>condition</i>);
Parameters:	<i>condition</i> is any relational expression
Returns:	Nothing
Function:	This function tests the condition and if FALSE will generate an error message on STDERR (by default the first USE RS232 in the program). The error message will include the file and line of the assert(). No code is generated for the assert() if you #define NODEBUG. In this way you may include asserts in your code for testing and quickly eliminate them from the final program.

Availability:	All devices
Requires:	assert.h and #USE RS232
Examples:	<pre>assert(number_of_entries<TABLE_SIZE); // If number_of_entries is >= TABLE_SIZE then // the following is output at the RS232: // Assertion failed, file myfile.c, line 56</pre>
Example Files:	None
Also See:	#USE RS232 , RS232 I/O Overview

atoe

Syntax:	atoe (string);
Parameters:	<i>string</i> is a pointer to a null terminated string of characters.
Returns:	Result is a floating point number
Function:	Converts the string passed to the function into a floating point representation. If the result cannot be represented, the behavior is undefined. This function also handles E format numbers
Availability:	All devices
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>char string [10]; float32 x; strcpy (string, "12E3"); x = atoe(string); // x is now 12000.00</pre>
Example Files:	None
Also See:	atoi() , atol() , atoi32() , atof() , printf()

atof()

Syntax:	result = atof (string)
Parameters:	string is a pointer to a null terminated string of characters.
Returns:	Result is a floating point number
Function:	Converts the string passed to the function into a floating point representation. If the result cannot be represented, the behavior is undefined.
Availability:	All devices
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>char string [10]; float x; strcpy (string, "123.456"); x = atof(string); // x is now 123.456</pre>
Example Files:	ex_tank.c
Also See:	atoi() , atol() , atoi32() , printf()

pin_select()

Syntax:	pin_select(peripheral_pin, pin, [unlock],[lock])
Parameters:	<p>peripheral_pin – a constant string specifying which peripheral pin to map the specified pin to. Refer to #pin_select for all available strings. Using “NULL” for the peripheral_pin parameter will unassign the output peripheral pin that is currently assigned to the pin passed for the pin parameter.</p>

pin – the pin to map to the specified peripheral pin. Refer to device's header file for pin defines. If the `peripheral_pin` parameter is an input, passing `FALSE` for the `pin` parameter will unassign the pin that is currently assigned to that peripheral pin.

unlock – optional parameter specifying whether to perform an unlock sequence before writing the `RPINRx` or `RPORx` register register determined by `peripheral_pin` and `pin` options. Default is `TRUE` if not specified. The unlock sequence must be performed to allow writes to the `RPINRx` and `RPORx` registers. This option allows calling `pin_select()` multiple times without performing an unlock sequence each time.

lock – optional parameter specifying whether to perform a lock sequence after writing the `RPINRx` or `RPORx` registers. Default is `TRUE` if not specified. Although not necessary it is a good idea to lock the `RPINRx` and `RPORx` registers from writes after all pins have been mapped. This option allows calling `pin_select()` multiple times without performing a lock sequence each time.

Returns: Nothing.

Availability: On device with remappable peripheral pins.

Requires: Pin defines in device's header file.

Examples:

```
pin_select("U2TX",PIN_B0);

//Maps PIN_B0 to U2TX //peripheral pin, performs
unlock //and lock sequences.

pin_select("U2TX",PIN_B0,TRUE,FALSE);

//Maps PIN_B0 to U2TX //peripheral pin and performs
//unlock sequence.

pin_select("U2RX",PIN_B1,FALSE,TRUE);

//Maps PIN_B1 to U2RX //peripheral pin and performs
lock //sequence.
```

Example Files: None.

Also See: `#pin_select`

atoi() atol() atoi32()

Syntax:	ival = atoi (<i>string</i>) or lvalue = atol (<i>string</i>) or i32value = atoi32 (<i>string</i>)
Parameters:	string is a pointer to a null terminated string of characters.
Returns:	ival is an 8 bit int. lvalue is a 16 bit int. i32value is a 32 bit int.
Function:	Converts the string passed to the function into an int representation. Accepts both decimal and hexadecimal argument. If the result cannot be represented, the behavior is undefined.
Availability:	All devices
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>char string[10]; int x; strcpy(string, "123"); x = atoi(string); // x is now 123</pre>
Example Files:	input.c
Also See:	printf()

at_clear_interrupts()

Syntax:	at_clear_interrupts (interrupts);
Parameters:	interrupts - an 8-bit constant specifying which AT interrupts to disable. The constants are defined in the device's header file as:

- AT_PHASE_INTERRUPT
- AT_MISSING_PULSE_INTERRUPT
- AT_PERIOD_INTERRUPT
- AT_CC3_INTERRUPT
- AT_CC2_INTERRUPT
- AT_CC1_INTERRUPT

Returns: Nothing

Function:

To disable the Angular Timer interrupt flags. More than one interrupt can be cleared at a time by or'ing multiple constants together in a single call, or calling function multiple times for each interrupt to clear.

Availability:

All devices with an AT module.

Requires:

Constants defined in the device's header file

Examples:

```
#INT-AT1
voidl_isr(void)
[
    if(at_interrupt_active(AT_PERIOD_INTERRUPT))
    [
        handle_period_interrupt();
        at_clear_interrupts(AT_PERIOD_INTERRUPT);
    ]
    if(at_interrupt_active(AT_PHASE_INTERRUPT);
    [
        handle_phase_interrupt();
        at_clear_interrupts(AT_PHASE_INTERRUPT);
    ]
]
```

Example Files:

None

Also See:

[at_set_resolution\(\)](#), [at_get_resolution\(\)](#),
[at_set_missing_pulse_delay\(\)](#), [at_get_missing_pulse_delay\(\)](#),
[at_get_period\(\)](#), [at_get_phase_counter\(\)](#), [at_set_set_point\(\)](#),
[at_get_set_point\(\)](#), [at_get_set_point_error\(\)](#), [at_enable_interrupts\(\)](#),
[at_disable_interrupts\(\)](#), [at_interrupt_active\(\)](#), [at_setup_cc\(\)](#),
[at_set_compare_time\(\)](#), [at_get_capture\(\)](#), [at_get_status\(\)](#), [setup_at\(\)](#)

at_disable_interrupts()

Syntax:	at_disable_interrupts (interrupts);
Parameters:	<p>interrupts - an 8-bit constant specifying which AT interrupts to disable. The constants are defined in the device's header file as:</p> <ul style="list-style-type: none">· AT_PHASE_INTERRUPT· AT_MISSING_PULSE_INTERRUPT· AT_PERIOD_INTERRUPT· AT_CC3_INTERRUPT· AT_CC2_INTERRUPT· AT_CC1_INTERRUPT
Returns:	Nothing
Function:	To disable the Angular Timer interrupts. More than one interrupt can be disabled at a time by or'ing multiple constants together in a single call, or calling function multiple times for each interrupt to be disabled.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's header file
Examples:	<pre>at_disable_interrupts(AT_PHASE_INTERRUPT); at_disable_interrupts(AT_PERIOD_INTERRUPT AT_CC1_INTERRUPT);</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_enable_interrupts()

Syntax:	at_enable_interrupts(interrupts);
Parameters:	<p>interrupts - an 8-bit constant specifying which AT interrupts to enable. The constants are defined in the device's header file as:</p> <ul style="list-style-type: none"> • AT_PHASE_INTERRUPT • AT_MISSING_PULSE_INTERRUPT • AT_PERIOD_INTERRUPT • AT_CC3_INTERRUPT • AT_CC2_INTERRUPT • AT_CC1_INTERRUPT
Returns:	Nothing
Function:	To enable the Angular Timer interrupts. More than one interrupt can be enabled at a time by or'ing multiple constants together in a single call, or calling function multiple times for each interrupt to be enabled.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's header file
Examples:	<pre>at_enable_interrupts(AT_PHASE_INTERRUPT); at_enable_interrupts(AT_PERIOD_INTERRUPT AT_CC1_INTERRUPT);</pre>
Example Files:	None
Also See:	<pre>setup_at(), at_set_resolution(), at_get_resolution(), at_set_missing_pulse_delay(), at_get_missing_pulse_delay(), at_get_phase_counter(), at_set_set_point(), at_get_set_point(), at_get_set_point(), at_get_set_point_error(), at_disable_interrupts(), at_clear_interrupts(), at_interrupt_active(), at_setup_cc(), at_set_compare_time(), at_get_capture(), at_get_status()</pre>

at_get_capture()

Syntax:	result=at_get_capture(which);;
Parameters:	which - an 8-bit constant specifying which AT Capture/Compare module to get the capture time from, can be 1, 2 or 3.
Returns:	A 16-bit integer
Function:	To get one of the Angular Timer Capture/Compare modules capture time.
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<pre>result1=at_get_capture(1); result2=at_get_capture(2);</pre>
Example Files:	None
Also See:	setup_at(), at_set_resolution(), at_get_resolution(), at_set_missing_pulse_delay(), at_get_missing_pulse_delay(), at_get_phase_counter(), at_set_set_point(), at_get_set_point(), at_get_set_point(), at_get_set_point_error(), at_enable_interrupts(), at_disable_interrupts(), at_clear_interrupts(), at_interrupt_active(), at_setup_cc(), at_set_compare_time(), at_get_status()

at_get_missing_pulse_delay()

Syntax:	result=at_get_missing_pulse_delay();
Parameters:	None.
Returns:	A 16-bit integer
Function:	To setup the Angular Timer Missing Pulse Delay
Availability:	All devices with an AT module.

Requires:	Nothing
Examples:	<code>result=at_get_missing_pulse_delay();</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_get_period()

Syntax:	<code>result=at_get_period();</code>
Parameters:	None.
Returns:	A 16-bit integer. The MSB of the returned value specifies whether the period counter rolled over one or more times. 1 - counter rolled over at least once, 0 - value returned is valid.
Function:	To get Angular Timer Measured Period
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<code>result=at_get_period();</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() ,

[at_setup_cc\(\)](#), [at_set_compare_time\(\)](#), [at_get_capture\(\)](#),
[at_get_status\(\)](#), [setup_at\(\)](#)

at_get_phase_counter()

Syntax:	result=at_get_phase_counter();
Parameters:	None.
Returns:	A 16-bit integer.
Function:	To get the Angular Timer Phase Counter
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<code>result=at_get_phase_counter();</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_get_resolution()

Syntax:	result=at_get_resolution();
Parameters:	None

Returns:	A 16-bit integer
Function:	To setup the Angular Timer Resolution
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<pre>result=at_get_resolution();</pre>
Example Files:	None
Also See:	at_set_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_get_set_point()

Syntax:	result=at_get_set_point();
Parameters:	None
Returns:	A 16-bit integer
Function:	To get the Angular Timer Set Point
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<pre>result=at_get_set_point();</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() ,

[at_get_period\(\)](#), [at_get_phase_counter\(\)](#), [at_set_set_point\(\)](#),
[at_get_set_point_error\(\)](#), [at_enable_interrupts\(\)](#),
[at_disable_interrupts\(\)](#), [at_clear_interrupts\(\)](#), [at_interrupt_active\(\)](#),
[at_setup_cc\(\)](#), [at_set_compare_time\(\)](#), [at_get_capture\(\)](#),
[at_get_status\(\)](#), [setup_at\(\)](#)

at_get_set_point_error()

Syntax: `result=at_get_set_point_error();`

Parameters: None

Returns: A 16-bit integer

Function: To get the Angular Timer Set Point Error, the error of the measured period value compared to the threshold setting.

Availability: All devices with an AT module.

Requires: Nothing

Examples: `result=at_get_set_point_error();`

Example Files: None

Also See: [at_set_resolution\(\)](#), [at_get_resolution\(\)](#),
[at_set_missing_pulse_delay\(\)](#), [at_get_missing_pulse_delay\(\)](#),
[at_get_period\(\)](#), [at_get_phase_counter\(\)](#), [at_set_set_point\(\)](#),
[at_get_set_point\(\)](#), [at_enable_interrupts\(\)](#), [at_disable_interrupts\(\)](#),
[at_clear_interrupts\(\)](#), [at_interrupt_active\(\)](#), [at_setup_cc\(\)](#),
[at_set_compare_time\(\)](#), [at_get_capture\(\)](#), [at_get_status\(\)](#), [setup_at\(\)](#)

at_get_status()

Syntax:	result=at_get_status();
Parameters:	None
Returns:	An 8-bit integer. The possible results are defined in the device's header file as: <ul style="list-style-type: none"> · AT_STATUS_PERIOD_AND_PHASE_VALID · AT_STATUS_PERIOD_LESS_THAN_PREVIOUS
Function:	To get the status of the Angular Timer module.
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<pre>if ((at_get_status() & AT_STATUS_PERIOD_AND_PHASE_VALID) == AT_STATUS_PERIOD_AND_PHASE_VALID [Period=at_get_period(); Phase=at_get_phase();])</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , setup_at()

at_interrupt_active()

Syntax:	result=at_interrupt_active(interrupt);
Parameters:	interrupts - an 8-bit constant specifying which AT interrupts to check if its flag is set. The constants are defined in the device's header file as:

	<ul style="list-style-type: none">• AT_PHASE_INTERRUPT• AT_MISSING_PULSE_INTERRUPT• AT_PERIOD_INTERRUPT• AT_CC3_INTERRUPT• AT_CC2_INTERRUPT• AT_CC1_INTERRUPT
Returns:	TRUE if the specified AT interrupt's flag is set, interrupt is active, or FALSE if the flag is clear, interrupt is not active.
Function:	To check if the specified Angular Timer interrupt flag is set.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's header file
Examples:	<pre>#INT-AT1 voidl_isr(void) [if(at_interrupt_active(AT_PERIOD_INTERRUPT)) [handle_period_interrupt(); at_clear_interrupts(AT_PERIOD_INTERRUPT);] if(at_interrupt_active(AT_PHASE_INTERRUPT)) [handle_phase_interrupt(); at_clear_interrupts(AT_PHASE_INTERRUPT);]]</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_set_compare_time()

Syntax:	at_set_compare_time (which, compare_time);
Parameters:	<p>which - an 8-bit constant specifying which AT Capture/Compare module to set the compare time for, can be 1, 2, or 3.</p> <p>compare_time - a 16-bit constant or variable specifying the value to trigger an interrupt/output pulse.</p>
Returns:	Nothing
Function:	To set one of the Angular Timer Capture/Compare module's compare time.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's header file
Examples:	<pre>at_set_compare_time(1, 0x1FF); at_set_compare_time(3, compare_time);</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_get_capture() , at_get_status() , setup_at()

at_set_missing_pulse_delay()

Syntax:	at_set_missing_pulse_delay (pulse_delay);
Parameters:	pulse_delay - a signed 16-bit constant or variable to set the missing pulse delay.
Returns:	Nothing

Function:	To setup the Angular Timer Missing Pulse Delay
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<code>at_set_missing_pulse_delay(pulse_delay);</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_set_resolution()

Syntax:	<code>at_set_resolution(resolution);</code>
Parameters:	resolution - a 16-bit constant or variable to set the resolution.
Returns:	Nothing
Function:	To setup the Angular Timer Resolution
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<code>at_set_resolution(resolution);</code>
Example Files:	None
Also See:	at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() ,

[at_get_phase_counter\(\)](#), [at_set_set_point\(\)](#), [at_get_set_point\(\)](#),
[at_get_set_point_error\(\)](#), [at_enable_interrupts\(\)](#),
[at_disable_interrupts\(\)](#), [at_clear_interrupts\(\)](#), [at_interrupt_active\(\)](#),
[at_setup_cc\(\)](#), [at_set_compare_time\(\)](#), [at_get_capture\(\)](#),
[at_get_status\(\)](#), [setup_at\(\)](#)

at_set_set_point()

Syntax:	<code>at_set_set_point(set_point);</code>
Parameters:	set_point - a 16-bit constant or variable to set the set point. The set point determines the threshold setting that the period is compared against for error calculation.
Returns:	Nothing
Function:	To get the Angular Timer Set Point
Availability:	All devices with an AT module.
Requires:	Nothing
Examples:	<code>at_set_set_point(set_point);</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

at_setup_cc()

Syntax:	at_setup_cc (which, settings);
Parameters:	<p>which - an 8-bit constant specifying which AT Capture/Compare to setup, can be 1, 2 or 3.</p> <p>settings - a 16-bit constant specifying how to setup the specified AT Capture/Compare module. See the device's header file for all options. Some of the typical options include:</p> <ul style="list-style-type: none">· AT_CC_ENABLED· AT_CC_DISABLED· AT_CC_CAPTURE_MODE· AT_CC_COMPARE_MODE· AT_CAPTURE_FALLING_EDGE· AT_CAPTURE_RISING_EDGE
Returns:	Nothing
Function:	To setup one of the Angular Timer Capture/Compare modules to the specified settings.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's header file
Examples:	<pre>at_setup_cc(1,AT_CC_ENABLED AT_CC_CAPTURE_MODE AT_CAPTURE_FALLING_EDGE AT_CAPTURE_INPUT_ATCAP); at_setup_cc(2,AT_CC_ENABLED AT_CC_CAPTURE_MODE AT_CC_ACTIVE_HIGH);</pre>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_set_compare_time() , at_get_capture() , at_get_status() , setup_at()

bit_clear()

Syntax:	bit_clear (<i>var</i> , <i>bit</i>)
Parameters:	var may be a any bit variable (any lvalue) bit is a number 0- 31 representing a bit number, 0 is the least significant bit.
Returns:	undefined
Function:	Simply clears the specified bit (0-7, 0-15 or 0-31) in the given variable. The least significant bit is 0. This function is the similar to: var &= ~(1<<bit);
Availability:	All devices
Requires:	Nothing
Examples:	<pre>int x; x=5; bit_clear(x,2); // x is now 1</pre>
Example Files:	ex_patg.c
Also See:	bit_set() , bit_test()

bit_set()

Syntax:	bit_set (<i>var</i> , <i>bit</i>)
Parameters:	var may be a 8,16 or 32 bit variable (any lvalue) bit is a number 0- 31 representing a bit number, 0 is the least significant bit.
Returns:	Undefined
Function:	Sets the specified bit (0-7, 0-15 or 0-31) in the given variable. The least significant bit is 0. This function is the similar to: var = (1<<bit);
Availability:	All devices

Requires:	Nothing
Examples:	<pre>int x; x=5; bit_set(x,3); // x is now 13</pre>
Example Files:	ex_patg.c
Also See:	bit_clear() , bit_test()

bit_test()

Syntax:	value = bit_test (var, bit)
Parameters:	var may be a 8,16 or 32 bit variable (any lvalue) bit is a number 0- 31 representing a bit number, 0 is the least significant bit.
Returns:	0 or 1
Function:	Tests the specified bit (0-7,0-15 or 0-31) in the given variable. The least significant bit is 0. This function is much more efficient than, but otherwise similar to: (var & (1<<bit)) != 0)
Availability:	All devices
Requires:	Nothing
Examples:	<pre>if(bit_test(x,3) !bit_test (x,1)){ //either bit 3 is 1 or bit 1 is 0 } if(data!=0) for(i=31;!bit_test(data, i);i--) ; // i now has the most significant bit in data // that is set to a 1</pre>
Example Files:	ex_patg.c

Also See: [bit_clear\(\)](#), [bit_set\(\)](#)

brownout_enable()

Syntax: `brownout_enable (value)`

Parameters: `value` – TRUE or FALSE

Returns: undefined

Function: Enable or disable the software controlled brownout. Brownout will cause the PIC to reset if the power voltage goes below a specific set-point.

Availability: This function is only available on PICs with a software controlled brownout. This may also require a specific configuration bit/fuse to be set for the brownout to be software controlled.

Requires: Nothing

Examples: `brownout_enable(TRUE);`

Example Files: None

Also See: [restart_cause\(\)](#)

bsearch()

Syntax: `ip = bsearch (&key, base, num, width, compare)`

Parameters:
key: Object to search for
base: Pointer to array of search data
num: Number of elements in search data
width: Width of elements in search data
compare: Function that compares two elements in search data

Returns: bsearch returns a pointer to an occurrence of key in the array pointed

	to by base. If key is not found, the function returns NULL. If the array is not in order or contains duplicate records with identical keys, the result is unpredictable.
Function:	Performs a binary search of a sorted array
Availability:	All devices
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>int nums[5]={1,2,3,4,5}; int compar(const void *arg1,const void *arg2); void main() { int *ip, key; key = 3; ip = bsearch(&key, nums, 5, sizeof(int), compar); } int compar(const void *arg1,const void *arg2) { if (* (int *) arg1 < (* (int *) arg2) return -1 else if (* (int *) arg1 == (* (int *) arg2) return 0 else return 1; }</pre>
Example Files:	None
Also See:	qsort()

calloc()

Syntax:	ptr=calloc(<i>nmem</i>, <i>size</i>)
Parameters:	<i>nmem</i> is an integer representing the number of member objects <i>size</i> is the number of bytes to be allocated for each one of them.
Returns:	A pointer to the allocated memory, if any. Returns null otherwise.
Function:	The calloc function allocates space for an array of nmem objects whose size is specified by size. The space is initialized to all bits zero.
Availability:	All devices
Requires:	#INCLUDE <stdlibm.h>

Examples:

```
int * iptr;
iptr=calloc(5,10);
// iptr will point to a block of memory of
// 50 bytes all initialized to 0.
```

Example Files:

None

Also See:[realloc\(\)](#), [free\(\)](#), [malloc\(\)](#)

ceil()

Syntax:**result = ceil (value)****Parameters:****value** is a float**Returns:**

A float

Function:

Computes the smallest integer value greater than the argument. CEIL(12.67) is 13.00.

Availability:

All devices

Requires:

#INCLUDE<math.h>

Examples:

```
// Calculate cost based on weight rounded
// up to the next pound

cost = ceil( weight ) * DollarsPerPound;
```

Example Files:

None

Also See:[floor\(\)](#)

clc1_setup_gate()
clc3_setup_gate()

clc2_setup_gate()
clc4_setup_gate()

Syntax:	<code>clc1_setup_gate(gate, mode);</code> <code>clc2_setup_gate(gate, mode);</code> <code>clc3_setup_gate(gate, mode);</code> <code>clc4_setup_gate(gate, mode);</code>
Parameters:	<p>gate – selects which data gate of the Configurable Logic Cell (CLC) module to setup, value can be 1 to 4.</p> <p>mode – the mode to setup the specified data gate of the CLC module into. The options are:</p> <div>CLC_GATE_AND CLC_GATE_NAND CLC_GATE_NOR CLC_GATE_OR CLC_GATE_CLEAR CLC_GATE_SET</div>
Returns:	Undefined
Function:	Sets the logic function performed on the inputs for the specified data gate.
Availability:	On devices with a CLC module.
Returns:	Undefined.
Examples:	<code>clc1_setup_gate(1, CLC_GATE_AND);</code> <code>clc1_setup_gate(2, CLC_GATE_NAND);</code> <code>clc1_setup_gate(3, CLC_GATE_CLEAR);</code> <code>clc1_setup_gate(4, CLC_GATE_SET);</code>
Example Files:	None
Also See:	setup_clcx() , clcx_setup_input()

clear_interrupt()

Syntax:	<code>clear_interrupt(<i>level</i>)</code>
Parameters:	level - a constant defined in the devices.h file
Returns:	undefined
Function:	Clears the interrupt flag for the given level. This function is designed for use with a specific interrupt, thus eliminating the GLOBAL level as a possible parameter. Some chips that have interrupt on change for individual pins allow the pin to be specified like INT_RA1.
Availability:	All devices
Requires:	Nothing
Examples:	<code>clear_interrupt(int_timer1);</code>
Example Files:	None
Also See:	enable_interrupts() , #INT , Interrupts Overview disable_interrupts() , interrupt_active()

clear_pwm1_interrupt() clear_pwm2_interrupt() clear_pwm3_interrupt() clear_pwm4_interrupt() clear_pwm5_interrupt() clear_pwm6_interrupt()

Syntax:	<code>clear_pwm1_interrupt (<i>interrupt</i>)</code> <code>clear_pwm2_interrupt (<i>interrupt</i>)</code> <code>clear_pwm3_interrupt (<i>interrupt</i>)</code> <code>clear_pwm4_interrupt (<i>interrupt</i>)</code> <code>clear_pwm5_interrupt (<i>interrupt</i>)</code>
---------	--

clear_pwm6_interrupt (<i>interrupt</i>)	
Parameters:	<p><i>interrupt</i> - 8-bit constant or variable. Constants are defined in the device's header file as:</p> <ul style="list-style-type: none">• PWM_PERIOD_INTERRUPT• PWM_DUTY_INTERRUPT• PWM_PHASE_INTERRUPT• PWM_OFFSET_INTERRUPT
Returns:	undefined.
Function:	Clears one of the above PWM interrupts, multiple interrupts can be cleared by or'ing multiple options together.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre>clear_pwm1_interrupt(PWM_PERIOD_INTERRUPT); clear_pwm1_interrupt(PWM_PERIOD_INTERRUPT PWM_DUTY_INTERRUPT);</pre>
Example Files:	setup_pwm() , set_pwm_duty() , set_pwm_phase() , set_pwm_period() , set_pwm_offset() , enable_pwm_interrupt() , disable_pwm_interrupt() , pwm_interrupt_active()
Also See:	

cog_status()

Syntax:	value=cog_status();
Parameters:	None
Returns:	value - the status of the COG module
Function:	To determine if a shutdown event occurred on the Complementary Output Generator (COG) module.
Availability:	All devices with a COG module.
Examples:	<pre>if (cog_status() == COG_AUTO_SHUTDOWN) cog_restart();</pre>

Example Files:	None
Also See:	setup_cog() , set_cog_dead_band() , set_cog_blanking() , set_cog_phase() , cog_restart()

cog_restart()

Syntax:	cog_restart();
Parameters:	None
Returns:	Nothing
Function:	To restart the Complementary Output Generator (COG) module after an auto-shutdown event occurs, when not using auto-restart option of module.
Availability:	All devices with a COG module.
Examples:	<pre>if (cog_status() == COG_AUTO_SHUTDOWN) cog_restart();</pre>
Example Files:	None
Also See:	setup_cog() , set_cog_dead_band() , set_cog_blanking() , set_cog_phase() , cog_status()

crc_calc() crc_calc8() crc_calc16()

Syntax:	<pre>Result = crc_calc (data,[width]); Result = crc_calc(ptr,len,[width]); Result = crc_calc8(data,[width]); Result = crc_calc8(ptr,len,[width]); Result = crc_calc16(data,[width]); Result = crc_calc16(ptr,len,[width]);</pre> <div>//same as crc_calc() //same as crc_calc()</div>
Parameters:	<p>data- This is one double word, word or byte that needs to be processed when using <code>crc_calc16()</code>, or <code>crc_calc8()</code></p> <p>ptr- is a pointer to one or more double words, words or bytes of data</p>

	<p>len- number of double words, words or bytes to process for function calls <code>crc_calc16()</code>, or <code>crc_calc8()</code></p> <p>width- optional parameter used to specify the input data bit width to use with the functions <code>crc_calc16()</code>, and <code>crc_calc8()</code> If not specified, it defaults to the width of the return value of the function, 8-bit for <code>crc_calc8()</code>, 16-bit for <code>crc_calc16()</code> For devices with a 16-bit for CRC the input data bit width is the same as the return bit width, <code>crc_calc16()</code> and 8-bit <code>crc_calc8()</code>.</p>
Returns:	Returns the result of the final CRC calculation.
Function:	This will process one data double word, word or byte or len double words, words or bytes of data using the CRC engine.
Availability:	Only the devices with built in CRC module.
Requires:	Nothing
Examples:	<pre>int16 data[8]; Result = crc_calc(data,8);</pre>
Example Files:	None
Also See:	<code>setup_crc()</code> ; crc_init()

crc_init(mode)

Syntax:	<code>crc_init (data);</code>
Parameters:	data - This will setup the initial value used by write CRC shift register. Most commonly, this register is set to 0x0000 for start of a new CRC calculation.
Returns:	undefined
Function:	Configures the CRCWDAT register with the initial value used for CRC calculations.
Availability:	Only the devices with built in CRC module.

Requires:	Nothing
Examples:	<pre>crc_init (); // Starts the CRC accumulator out at 0 crc_init(0xFEEE); // Starts the CRC accumulator out at 0xFEEE</pre>
Example Files:	None
Also See:	setup_crc(), crc_calc() , crc_calc8()

cwg_status()

Syntax:	value = cwg_status();
Parameters:	None
Returns:	the status of the CWG module
Function:	To determine if a shutdown event occurred causing the module to auto-shutdown
Availability:	On devices with a CWG module.
Examples:	<pre>if(cwg_status() == CWG_AUTO_SHUTDOWN) cwg_restart();</pre>
Example Files:	None
Also See:	setup_cwg() , cwg_restart()

cwg_restart()

Syntax:	cwg_restart();
Parameters:	None
Returns:	Nothing

Function:	To restart the CWG module after an auto-shutdown event occurs, when not using auto-raster option of module.
Availability:	On devices with a CWG module.
Examples:	<pre>if(cwg_status() == CWG_AUTO_SHUTDOWN) cwg_restart();</pre>
Example Files:	None
Also See:	setup_cwg() , cwg_status()

dac_write()

Syntax:	dac_write (value)
Parameters:	Value: 8-bit integer value to be written to the DAC module
Returns:	undefined
Function:	This function will write a 8-bit integer to the specified DAC channel.
Availability:	Only available on devices with built in digital to analog converters.
Requires:	Nothing
Examples:	<pre>int i = 0; setup_dac(DAC_VDD DAC_OUTPUT); while(1){ i++; dac_write(i); }</pre>
Also See:	setup_dac() , DAC Overview , see header file for device selected

delay_cycles()

Syntax:	delay_cycles (count)
Parameters:	count - a constant 1-255
Returns:	undefined
Function:	Creates code to perform a delay of the specified number of instruction clocks (1-255). An instruction clock is equal to four oscillator clocks. The delay time may be longer than requested if an interrupt is serviced during the delay. The time spent in the ISR does not count toward the delay time.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>delay_cycles(1); // Same as a NOP delay_cycles(25); // At 20 mhz a 5us delay</pre>
Example Files:	ex_cust.c
Also See:	delay_us() , delay_ms()

delay_ms()

Syntax:	delay_ms (time)
Parameters:	time - a variable 0-65535(int16) or a constant 0-65535 Note: Previous compiler versions ignored the upper byte of an int16, now the upper byte affects the time.
Returns:	undefined
Function:	This function will create code to perform a delay of the specified length. Time is specified in milliseconds. This function works by executing a precise number of instructions to cause the requested

	<p>delay. It does not use any timers. If interrupts are enabled the time spent in an interrupt routine is not counted toward the time.</p> <p>The delay time may be longer than requested if an interrupt is serviced during the delay. The time spent in the ISR does not count toward the delay time.</p>
Availability:	All devices
Requires:	<code>#USE DELAY</code>
	<pre>#use delay (clock=20000000) delay_ms(2);</pre>
Examples:	<pre>void delay_seconds(int n) { for (;n!=0; n- -) delay_ms(1000); }</pre>
Example Files:	ex_sqw.c
Also See:	delay_us() , delay_cycles() , #USE DELAY

delay_us()

Syntax:	<code>delay_us (time)</code>
	time - a variable 0-65535(int16) or a constant 0-65535
Parameters:	Note: Previous compiler versions ignored the upper byte of an int16, now the upper byte affects the time.
Returns:	undefined
Function:	Creates code to perform a delay of the specified length. Time is specified in microseconds. Shorter delays will be INLINE code and longer delays and variable delays are calls to a function. This function works by executing a precise number of instructions to cause the requested delay. It does not use any timers. If interrupts are enabled the time spent in an interrupt routine is not counted toward the time.

The delay time may be longer than requested if an interrupt is serviced during the delay. The time spent in the ISR does not count toward the delay time.

Availability: All devices

Requires: `#USE DELAY`

```
#use delay(clock=20000000)
```

Examples:

```
do {
  output_high(PIN_B0);
  delay_us(duty);
  output_low(PIN_B0);
  delay_us(period-duty);
} while(TRUE);
```

Example Files: [ex_sqw.c](#)

Also See: [delay_ms\(\)](#), [delay_cycles\(\)](#), [#USE DELAY](#)

disable_interrupts()

Syntax: `disable_interrupts (level)`

Parameters: *level* - a constant defined in the devices .h file

Returns: undefined

Function:

Disables the interrupt at the given level. The GLOBAL level will not disable any of the specific interrupts but will prevent any of the specific interrupts, previously enabled to be active. Valid specific levels are the same as are used in `#INT_xxx` and are listed in the devices .h file. GLOBAL will also disable the peripheral interrupts on devices that have it. Note that it is not necessary to disable interrupts inside an interrupt service routine since interrupts are automatically disabled. Some chips that have interrupt on change for individual pins allow the pin to be specified like `INT_RA1`.

Availability: Device with interrupts (PCM and PCH)

Requires: Should have a `#INT_xxxx`, constants are defined in the devices .h

file.

Examples:

```
disable_interrupts(GLOBAL); // all interrupts OFF
disable_interrupts(INT_RDA); // RS232 OFF

enable_interrupts(ADC_DONE);
enable_interrupts(RB_CHANGE);
// these enable the interrupts
// but since the GLOBAL is disabled they
// are not activated until the following
// statement:
enable_interrupts(GLOBAL);
```

Example Files:

[ex_sisr.c](#), [ex_stwt.c](#)

Also See:

[enable_interrupts\(\)](#), [clear_interrupt\(\)](#), [#INT_xxxx](#), [Interrupts Overview](#), [interrupt_active\(\)](#)

disable_pwm1_interrupt()
disable_pwm2_interrupt()
disable_pwm3_interrupt()
disable_pwm4_interrupt()
disable_pwm5_interrupt()
disable_pwm6_interrupt()

Syntax:

```
disable_pwm1_interrupt (interrupt)
disable_pwm2_interrupt (interrupt)
disable_pwm3_interrupt (interrupt)
disable_pwm4_interrupt (interrupt)
disable_pwm5_interrupt (interrupt)
disable_pwm6_interrupt (interrupt)
```

Parameters:

interrupt - 8-bit constant or variable. Constants are defined in the device's header file as:

- PWM_PERIOD_INTERRUPT
- PWM_DUTY_INTERRUPT

	<ul style="list-style-type: none"> • PWM_PHASE_INTERRUPT • PWM_OFFSET_INTERRUPT
Returns:	undefined.
Function:	Disables one of the above PWM interrupts, multiple interrupts can be disabled by or'ing multiple options together.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre>disable_pwm1_interrupt(PWM_PERIOD_INTERRUPT); disable_pwm1_interrupt(PWM_PERIOD_INTERRUPT PWM_DUTY_INTERRUPT);</pre>
Example Files:	setup_pwm() , set_pwm_duty() , set_pwm_phase() , set_pwm_period() , set_pwm_offset() , enable_pwm_interrupt() , clear_pwm_interrupt() , pwm_interrupt_active()
Also See:	

div() ldiv()

Syntax:	idiv=div(<i>num</i>, <i>denom</i>) ldiv =ldiv(<i>lnum</i>, <i>ldenom</i>)
Parameters:	<p><i>num</i> and <i>denom</i> are signed integers. <i>num</i> is the numerator and <i>denom</i> is the denominator. <i>lnum</i> and <i>ldenom</i> are signed longs <i>lnum</i> is the numerator and <i>ldenom</i> is the denominator.</p>
Returns:	idiv is a structure of type div_t and ldiv is a structure of type ldiv_t. The div function returns a structure of type div_t, comprising of both the quotient and the remainder. The ldiv function returns a structure of type ldiv_t, comprising of both the quotient and the remainder.
Function:	The div and ldiv function computes the quotient and remainder of the division of the numerator by the denominator. If the division is inexact, the resulting quotient is the integer or long of lesser

	magnitude that is the nearest to the algebraic quotient. If the result cannot be represented, the behavior is undefined; otherwise <code>quot*denom(lidenom)+rem</code> shall equal <code>num(lnum)</code> .
Availability:	All devices.
Requires:	<code>#INCLUDE <STDLIB.H></code>
Examples:	<pre>div_t idiv; ldiv_t ldiv; idiv=div(3,2); //idiv will contain quot=1 and rem=1 ldiv=ldiv(300,250); //ldiv will contain ldiv.quot=1 and ldiv.rem=50</pre>
Example Files:	None
Also See:	None

enable_interrupts()

Syntax:	enable_interrupts (level)
Parameters:	level is a constant defined in the devices *.h file.
Returns:	undefined.
Function:	<p>This function enables the interrupt at the given level. An interrupt procedure should have been defined for the indicated interrupt.</p> <p>The GLOBAL level will not enable any of the specific interrupts, but will allow any of the specified interrupts previously enabled to become active. Some chips that have an interrupt on change for individual pins all the pin to be specified, such as INT_RA1. For interrupts that use edge detection to trigger, it can be setup in the <code>enable_interrupts()</code> function without making a separate call to the <code>set_int_edge()</code> function.</p> <p>Enabling interrupts does not clear the interrupt flag if there was a pending interrupt prior to the call. Use the <code>clear_interrupt()</code> function to clear pending interrupts before the call to <code>enable_interrupts()</code> to discard the prior interrupts.</p>

Availability:	Devices with interrupts.
Requires:	Should have a #INT_XXXX to define the ISR, and constants are defined in the devices *.h file.
Examples:	<pre>enable_interrupts(GLOBAL); enable_interrupts(INT_TIMER0); enable_interrupts(INT_EXT_H2L);</pre>
Example Files:	ex_sisr.c , ex_stwt.c
Also See:	disable_interrupts() , clear_interrupt() , ext_int_edge() , #INT xxxx , Interrupts Overview , interrupt_active()

enable_pwm1_interrupt()
enable_pwm2_interrupt()
enable_pwm3_interrupt()
enable_pwm4_interrupt()
enable_pwm5_interrupt()
enable_pwm6_interrupt()

Syntax:	<pre>enable_pwm1_interrupt (interrupt) enable_pwm2_interrupt (interrupt) enable_pwm3_interrupt (interrupt) enable_pwm4_interrupt (interrupt) enable_pwm5_interrupt (interrupt) enable_pwm6_interrupt (interrupt)</pre>
Parameters:	<p><i>interrupt</i> - 8-bit constant or variable. Constants are defined in the device's header file as:</p> <ul style="list-style-type: none"> • PWM_PERIOD_INTERRUPT • PWM_DUTY_INTERRUPT • PWM_PHASE_INTERRUPT • PWM_OFFSET_INTERRUPT
Returns:	undefined.
Function:	Enables one of the above PWM interrupts, multiple interrupts can be

	enabled by or'ing multiple options together. For the interrupt to occur, the overall PWMx interrupt still needs to be enabled and an interrupt service routine still needs to be created.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre>enable_pwm1_interrupt(PWM_PERIOD_INTERRUPT); enable_pwm1_interrupt(PWM_PERIOD_INTERRUPT PWM_DUTY_INTERRUPT);</pre>
Example Files:	setup_pwm() , set_pwm_duty() , set_pwm_phase() , set_pwm_period() , set_pwm_offset() , disable_pwm_interrupt() , clear_pwm_interrupt() , pwm_interrupt_active()
Also See:	

erase_eeprom()

Syntax:	erase_eeprom (address);
Parameters:	address is 8 bits on PCB parts.
Returns:	undefined
Function:	This will erase a row of the EEPROM or Flash Data Memory.
Availability:	PCB devices with EEPROM like the 12F519
Requires:	Nothing
Examples:	<pre>erase_eeprom(0); // erase the first row of the EEPROM (8 bytes)</pre>
Example Files:	None
Also See:	write_program_eeprom() , write_program_memory() , Program Eeprom Overview

erase_program_eeprom()

Syntax:	erase_program_eeprom (address);
Parameters:	address is 16 bits on PCM parts and 32 bits on PCH parts . The least significant bits may be ignored.
Returns:	undefined
Function:	Erases FLASH_ERASE_SIZE bytes to 0xFFFF in program memory. FLASH_ERASE_SIZE varies depending on the part. For example, if it is 64 bytes then the least significant 6 bits of address is ignored. See write_program_memory() for more information on program memory access.
Availability:	Only devices that allow writes to program memory.
Requires:	Nothing
Examples:	<pre>for (i=0x1000; i<=0x1fff; i+=getenv("FLASH_ERASE_SIZE")) erase_program_memory(i);</pre>
Example Files:	None
Also See:	write_program_eeprom() , write_program_memory() , Program Eeprom Overview

exp()

Syntax:	result = exp (value)
Parameters:	value is a float
Returns:	A float
Function:	Computes the exponential function of the argument. This is e to the power of value where e is the base of natural logarithms. exp(1) is 2.7182818. Note on error handling:

	<p>If "errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.</p> <p>Range error occur in the following case:</p> <ul style="list-style-type: none">• exp: when the argument is too large
Availability:	All devices
Requires:	#INCLUDE <math.h>
Examples:	<pre>// Calculate x to the power of y x_power_y = exp(y * log(x));</pre>
Example Files:	None
Also See:	pow() , log() , log10()

ext_int_edge()

Syntax:	ext_int_edge (<i>source</i> , <i>edge</i>)
Parameters:	<p>source is a constant 0,1 or 2 for the PIC18XXX and 0 otherwise. Source is optional and defaults to 0.</p> <p>edge is a constant H_TO_L or L_TO_H representing "high to low" and "low to high"</p>
Returns:	undefined
Function:	Determines when the external interrupt is acted upon. The edge may be L_TO_H or H_TO_L to specify the rising or falling edge.
Availability:	Only devices with interrupts (PCM and PCH)
Requires:	Constants are in the devices .h file
Examples:	<pre>ext_int_edge(2, L_TO_H); // Set up PIC18 EXT2 ext_int edge(H TO L); // Sets up EXT</pre>

Example Files: [ex_wakeup.c](#)

Also See: [#INT_EXT](#), [enable_interrupts\(\)](#), [disable_interrupts\(\)](#), [Interrupts Overview](#)

fabs()

Syntax: **result=fabs (value)**

Parameters: **value** is a float

Returns: result is a float

Function: The fabs function computes the absolute value of a float

Availability: All devices.

Requires: #INCLUDE <math.h>

Examples:

```
float result;
result=fabs(-40.0)
// result is 40.0
```

Example Files: None

Also See: [abs\(\)](#), [labs\(\)](#)

floor()

Syntax: **result = floor (value)**

Parameters: **value** is a float

Returns: result is a float

Function: Computes the greatest integer value not greater than the argument. Floor (12.67) is 12.00.

Availability:	All devices.
Requires:	#INCLUDE <math.h>
Examples:	// Find the fractional part of a value frac = value - floor(value);
Example Files:	None
Also See:	ceil()

fmod()

Syntax:	result= fmod (val1, val2)
Parameters:	val1 is a float val2 is a float
Returns:	result is a float
Function:	Returns the floating point remainder of val1/val2. Returns the value val1 - i*val2 for some integer "i" such that, if val2 is nonzero, the result has the same sign as val1 and magnitude less than the magnitude of val2.
Availability:	All devices.
Requires:	#INCLUDE <math.h>
Examples:	float result; result=fmod(3,2); // result is 1
Example Files:	None
Also See:	None

free()

Syntax:	free(ptr)
Parameters:	ptr is a pointer earlier returned by the calloc, malloc or realloc.
Returns:	No value
Function:	The free function causes the space pointed to by the ptr to be deallocated, that is made available for further allocation. If ptr is a null pointer, no action occurs. If the ptr does not match a pointer earlier returned by the calloc, malloc or realloc, or if the space has been deallocated by a call to free or realloc function, the behavior is undefined.
Availability:	All devices.
Requires:	#INCLUDE <stdlibm.h>
Examples:	<pre>int * iptr; iptr=malloc(10); free(iptr) // iptr will be deallocated</pre>
Example Files:	None
Also See:	realloc() , malloc() , calloc()

frexp()

Syntax:	result=frexp (value, &exp);
Parameters:	value is a float exp is a signed int.
Returns:	result is a float
Function:	The frexp function breaks a floating point number into a normalized fraction and an integral power of 2. It stores the integer in the signed int object exp. The result is in the interval [1/2 to 1) or zero, such that

	value is result times 2 raised to power exp. If value is zero then both parts are zero.
Availability:	All devices.
Requires:	#INCLUDE <math.h>
Examples:	<pre>float result; signed int exp; result=frexp(.5,&exp); // result is .5 and exp is 0</pre>
Example Files:	None
Also See:	ldexp() , exp() , log() , log10() , modf()

scanf()

Syntax:	scanf (cstring); scanf (cstring, values...) fscanf (stream, cstring, values...)
Parameters:	cstring is a constant string. values is a list of variables separated by commas. stream is a stream identifier.
Returns:	0 if a failure occurred, otherwise it returns the number of conversion specifiers that were read in, plus the number of constant strings read in.
Function:	<p>Reads in a string of characters from the standard RS-232 pins and formats the string according to the format specifiers. The format specifier character (%) used within the string indicates that a conversion specification is to be done and the value is to be saved into the corresponding argument variable. A %% will input a single %.</p> <p>Formatting rules for the format specifier as follows:</p> <p>If fscanf() is used, then the specified stream is used, where scanf() defaults to STDIN (the last USE RS232).</p>

Format:

The format takes the generic form %nt. **n** is an option and may be 1-99 specifying the field width, the number of characters to be inputted. **t** is the type and maybe one of the following:

c	Matches a sequence of characters of the number specified by the field width (1 if no field width is specified). The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence.
s	Matches a sequence of non-white space characters. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a terminating null character, which will be added automatically.
u	Matches an unsigned decimal integer. The corresponding argument shall be a pointer to an unsigned integer.
Lu	Matches a long unsigned decimal integer. The corresponding argument shall be a pointer to a long unsigned integer.
d	Matches a signed decimal integer. The corresponding argument shall be a pointer to a signed integer.
Ld	Matches a long signed decimal integer. The corresponding argument shall be a pointer to a long signed integer.
o	Matches a signed or unsigned octal integer. The corresponding argument shall be a pointer to a signed or unsigned integer.
Lo	Matches a long signed or unsigned octal integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
x or X	Matches a hexadecimal integer. The corresponding argument shall be a pointer to a signed or unsigned integer.

Lx or LX	Matches a long hexadecimal integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
i	Matches a signed or unsigned integer. The corresponding argument shall be a pointer to a signed or unsigned integer.
Li	Matches a long signed or unsigned integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
f,g or e	Matches a floating point number in decimal or exponential format. The corresponding argument shall be a pointer to a float.
[<p>Matches a non-empty sequence of characters from a set of expected characters. The sequence of characters included in the set are made up of all character following the left bracket ([) up to the matching right bracket (]). Unless the first character after the left bracket is a ^, in which case the set of characters contain all characters that do not appear between the brackets. If a - character is in the set and is not the first or second, where the first is a ^, nor the last character, then the set includes all characters from the character before the - to the character after the -.</p> <p>For example, %[a-z] would include all characters from a to z in the set and %[^a-z] would exclude all characters from a to z from the set. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a terminating null character, which will be added automatically.</p>
n	<p>Assigns the number of characters read thus far by the call to scanf() to the corresponding argument. The corresponding argument shall be a pointer to an unsigned integer.</p> <p>An optional assignment-suppressing character (*) can be used after the format specifier to indicate that the conversion specification is to be done, but not saved into a corresponding variable. In this case,</p>

no corresponding argument variable should be passed to the `scanf()` function.

A string composed of ordinary non-white space characters is executed by reading the next character of the string. If one of the inputted characters differs from the string, the function fails and exits. If a white-space character precedes the ordinary non-white space characters, then white-space characters are first read in until a non-white space character is read.

White-space characters are skipped, except for the conversion specifiers `['', c or n]`, unless a white-space character precedes the `[''` or `c` specifiers.

Availability: All Devices

Requires: #USE RS232

Examples:

```
char name[2-];
unsigned int8 number;
signed int32 time;

if (scanf("%u%s%d", &number, name, &time))
    printf("\r\nName: %s, Number: %u, Time: %ld", name, number, time);
```

Example Files: None

Also See: [RS232 I/O Overview](#), [getc\(\)](#), [putc\(\)](#), [printf\(\)](#)

get_capture()

Syntax: value = get_capture(x)

Parameters: x defines which ccp module to read from.

Returns: A 16-bit timer value.

Function: This function obtains the last capture time from the indicated CCP

	module
Availability:	Only available on devices with Input Capture modules
Requires:	None
Examples:	
Example Files:	ex_ccpmp.c
Also See:	setup_ccpx()

get_capture_event()

Syntax:	result = get_capture_event([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE CAPTURE.
Returns:	TRUE if a capture event occurred, FALSE otherwise.
Function:	To determine if a capture event occurred.
Availability:	All devices.
Requires:	#USE CAPTURE
Examples:	#USE CAPTURE(INPUT=PIN_C2,CAPTURE_RISING,TIMER=1,FASTEST) if(get_capture_event()) result = get_capture_time();
Example Files:	None
Also See:	#use_capture , get_capture_time()

get_capture_time()

Syntax:	result = get_capture_time([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE CAPTURE.

Returns:	An int16 value representing the last capture time.
Function:	To get the last capture time.
Availability:	All devices.
Requires:	#USE CAPTURE
Examples:	<pre>#USE CAPTURE (INPUT=PIN_C2,CAPTURE_RISING,TIMER=1,FASTEST) result = get_capture_time();</pre>
Example Files:	None
Also See:	#use capture , get_capture_event()

get_capture32()

Syntax:	result = get_capture32(x,[wait]);
Parameters:	<p>x is 1-16 and defines which input capture result buffer modules to read from.</p> <p>wait is an optional parameter specifying if the compiler should read the oldest result in the bugger or the next result to enter the buffer.</p>
Returns:	A 32-bit timer value
Function:	<p>If wait is true, the current capture values in the result buffer are cleared, and the next result to be sent to the buffer is returned. If wait is false, the default setting, the first value currently in the buffer is returned. However, the buffer will only hold four results while waiting for them to be read, so if get_capture32 is not being called for every capture event. When wait is false, the buffer will fill with old capture values and any new results will be lost.</p>
Availability:	Only devices with a 32-bit Input Capture module
Requires:	Nothing
Examples:	<pre>setup_timer2(TMR_INTERNAL TMR_DIV_BY_1 TMR_32_BIT);</pre>

```
setup_capture(1,CAPTURE_FE | CAPTURE_TIMER2 |
CAPTURE_32_BIT);
while(TRUE) {
    timerValue=get_capture32(1,TRUE);
    printf("Capture 1 occurred at: %LU", timerValue);
}
```

Example Files:	None
Also See:	setup_capture(), setup_compare(), get_capture() , Input Capture Overview

get_hspwm_capture()

Syntax:	result=get_hspwm_capture(unit);
Parameters:	unit - The High Speed PWM unit to set.
Returns:	Unsigned in16 value representing the capture PWM time base value.
Function:	Gets the captured PWM time base value from the leading edge detection on the current-limit input.
Availability:	Only on devices with a built-in High Speed PWM module (dsPIC33FJxxGSxxx, dsPIC33EPxxxMUxxx, dsPIC33EPxxxMCxxx, and dsPIC33EVxxxGMxxx devices)
Requires:	None
Examples:	<code>result=get_hspwm_capture(1);</code>
Example Files:	None
Also See:	setup_hspwm_unit() , set_hspwm_phase() , set_hspwm_duty() , set_hspwm_event() , setup_hspwm_blanking() , setup_hspwm_trigger() , set_hspwm_override() , setup_hspwm_chop_clock() , setup_hspwm_unit_chop_clock() , setup_hspwm() , setup_hspwm_secondary()

get_nco_accumulator()

Syntax:	<code>value =get_nco_accumulator();</code>
Parameters:	none
Returns:	current value of accumulator.
Availability:	On devices with a NCO module.
Examples:	<code>value = get_nco_accumulator();</code>
Example Files:	None
Also See:	setup_nco() , set_nco_inc_value() , get_nco_inc_value()

get_nco_inc_value()

Syntax:	<code>value =get_nco_inc_value();</code>
Parameters:	None
Returns:	- current value set in increment registers.
Availability:	On devices with a NCO module.
Examples:	<code>value = get_nco_inc_value();</code>
Example Files:	None
Also See:	setup_nco() , set_nco_inc_value() , get_nco_accumulator()

get_ticks()

Syntax:	value = get_ticks([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE TIMER.
Returns:	– a 8, 16 or 32 bit integer. (int8, int16 or int32)
Function:	Returns the current tick value of the tick timer. The size returned depends on the size of the tick timer.
Availability:	All devices.
Requires:	#USE TIMER(options) #USE TIMER (TIMER=1, TICK=1ms, BITS=16, NOISR)
Examples:	<pre>void main(void) { unsigned int16 current_tick; current_tick = get_ticks(); }</pre>
Example Files:	None
Also See:	#USE TIMER , set_ticks()

get_timerA()

Syntax:	value=get_timerA();
Parameters:	none
Returns:	The current value of the timer as an int8
Function:	Returns the current value of the timer. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2, ...).
Availability:	This function is only available on devices with Timer A hardware.
Requires:	Nothing

Examples:	<pre>set_timerA(0); while(timerA < 200);</pre>
Example Files:	none
Also See:	set_timerA() , setup_timer_A() , TimerA Overview

get_timerB()

Syntax:	value=get_timerB();
Parameters:	none
Returns:	The current value of the timer as an int8
Function:	Returns the current value of the timer. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2, ...).
Availability:	This function is only available on devices with Timer B hardware.
Requires:	Nothing
Examples:	<pre>set_timerB(0); while(timerB < 200);</pre>
Example Files:	none
Also See:	set_timerB() , setup_timer_B() , TimerB Overview

get_timerx()

Syntax:	<pre>value=get_timer0() Same as: value=get_rtcc() value=get_timer1() value=get_timer2() value=get_timer3() value=get_timer4() value=get_timer5() value=get_timer6()</pre>
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	<code>value=get_timer7()</code> <code>value=get_timer8()</code> <code>value=get_timer10()</code> <code>value=get_timer12()</code>
Parameters:	None
Returns:	Timers 1, 3, 5 and 7 return a 16 bit int. Timers 2, 4, 6, 8, 10 and 12 return an 8 bit int. Timer 0 (AKA RTCC) returns a 8 bit int except on the PIC18XXX where it returns a 16 bit int.
Function:	Returns the count value of a real time clock/counter. RTCC and Timer0 are the same. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2...).
Availability:	Timer 0 - All devices Timers 1 & 2 - Most but not all PCM devices Timer 3, 5 and 7 - Some PIC18 and Enhanced PIC16 devices Timer 4,6,8,10 and 12- Some PIC18 and Enhanced PIC16 devices
Requires:	Nothing
Examples:	<code>set_timer0(0);</code> <code>while (get_timer0() < 200) ;</code>
Example Files:	ex_stwt.c
Also See:	set_timerx() , Timer0 Overview , Timer1 Overview , Timer2 Overview , Timer5 Overview

get_tris_x()

Syntax:	<code>value = get_tris_A();</code> <code>value = get_tris_B();</code> <code>value = get_tris_C();</code> <code>value = get_tris_D();</code> <code>value = get_tris_E();</code> <code>value = get_tris_F();</code> <code>value = get_tris_G();</code> <code>value = get_tris_H();</code>
---------	--

	value = get_tris_J(); value = get_tris_K()
Parameters:	None
Returns:	int16, the value of TRIS register
Function:	Returns the value of the TRIS register of port A, B, C, D, E, F, G, H, J, or K.
Availability:	All devices.
Requires:	Nothing
Examples:	<code>tris_a = GET_TRIS_A();</code>
Example Files:	None
Also See:	input() , output_low() , output_high()

getc() getch() getchar() fgetc()

Syntax:	value = getc() value = fgetc(<i>stream</i>) value=getch() value=getchar()
Parameters:	<i>stream</i> is a stream identifier (a constant byte)
Returns:	An 8 bit character
Function:	<p>This function waits for a character to come in over the RS232 RCV pin and returns the character. If you do not want to hang forever waiting for an incoming character use kbhit() to test for a character available. If a built-in USART is used the hardware can buffer 3 characters otherwise GETC must be active while the character is being received by the PIC®.</p> <p>If fgetc() is used then the specified stream is used where getc() defaults to STDIN (the last USE RS232).</p>
Availability:	All devices

Requires:	#USE RS232
Examples:	<pre>printf("Continue (Y,N)?"); do { answer=getch(); }while(answer!='Y' && answer!='N'); #use rs232 (baud=9600,xmit=pin_c6, rcv=pin_c7,stream=HOSTPC) #use rs232 (baud=1200,xmit=pin_b1, rcv=pin_b0,stream=GPS) #use rs232 (baud=9600,xmit=pin_b3, stream=DEBUG) ... while(TRUE) { c=fgetc(GPS); fputc(c,HOSTPC); if(c==13) fprintf(DEBUG,"Got a CR\r\n"); }</pre>
Example Files:	ex_stwt.c
Also See:	putc() , kbhit() , printf() , #USE RS232 , input.c , RS232 I/O Overview

getenv()

Syntax:	value = getenv (cstring);				
Parameters:	cstring is a constant string with a recognized keyword				
Returns:	A constant number, a constant string or 0				
Function:	<p>This function obtains information about the execution environment. The following are recognized keywords. This function returns a constant 0 if the keyword is not understood.</p> <table><tr><td>FUSE_SET:ffff</td><td>Returns 1 if fuse ffff is enabled</td></tr><tr><td>FUSE_VALID:ffff</td><td>Returns 1 if fuse ffff is valid</td></tr></table>	FUSE_SET:ffff	Returns 1 if fuse ffff is enabled	FUSE_VALID:ffff	Returns 1 if fuse ffff is valid
FUSE_SET:ffff	Returns 1 if fuse ffff is enabled				
FUSE_VALID:ffff	Returns 1 if fuse ffff is valid				

INT:iiii	Returns 1 if the interrupt iiii is valid
ID	Returns the device ID (set by #ID)
DEVICE	Returns the device name string (like "PIC16C74")
CLOCK	Returns the MPU FOSC
VERSION	Returns the compiler version as a float
VERSION_STRING	Returns the compiler version as a string
PROGRAM_MEMORY	Returns the size of memory for code (in words)
STACK	Returns the stack size
SCRATCH	Returns the start of the compiler scratch area
DATA_EEPROM	Returns the number of bytes of data EEPROM
EEPROM_ADDRESS	Returns the address of the start of EEPROM. 0 if not supported by the device.
READ_PROGRAM	Returns a 1 if the code memory can be read
ADC_CHANNELS	Returns the number of A/D channels
ADC_RESOLUTION	Returns the number of bits returned from READ_ADC()
ICD	Returns a 1 if this is being compiled for a ICD
SPI	Returns a 1 if the device has SPI
USB	Returns a 1 if the device has USB
CAN	Returns a 1 if the device has CAN

I2C_SLAVE	Returns a 1 if the device has I2C slave H/W
I2C_MASTER	Returns a 1 if the device has I2C master H/W
PSP	Returns a 1 if the device has PSP
COMP	Returns a 1 if the device has a comparator
VREF	Returns a 1 if the device has a voltage reference
LCD	Returns a 1 if the device has direct LCD H/W
UART	Returns the number of H/W UARTs
AUART	Returns 1 if the device has an ADV UART
CCPx	Returns a 1 if the device has CCP number x
TIMERx	Returns a 1 if the device has TIMER number x
FLASH_WRITE_SIZE	Smallest number of bytes that can be written to FLASH
FLASH_ERASE_SIZE	Smallest number of bytes that can be erased in FLASH
BYTES_PER_ADDRESS	Returns the number of bytes at an address location
BITS_PER_INSTRUCTION	Returns the size of an instruction in bits
RAM	Returns the number of RAM bytes available for your device.

SFR:name	Returns the address of the specified special file register. The output format can be used with the preprocessor command #bit. name must match SFR denomination of your target PIC (example: STATUS, INTCON, TXREG, RCREG, etc)
BIT:name	Returns the bit address of the specified special file register bit. The output format will be in "address:bit", which can be used with the preprocessor command #byte. name must match SFR.bit denomination of your target PIC (example: C, Z, GIE, TMR0IF, etc)
SFR_VALID:name	Returns TRUE if the specified special file register name is valid and exists for your target PIC (example: getenv("SFR_VALID:INTCON"))
BIT_VALID:name	Returns TRUE if the specified special file register bit is valid and exists for your target PIC (example: getenv("BIT_VALID:TMR0IF"))
PIN:PB	Returns 1 if PB is a valid I/O PIN (like A2)
UARTx_RX	Returns UARTxPin (like PINxC7)
UARTx_TX	Returns UARTxPin (like PINxC6)
SPIx_DI	Returns SPIxDI Pin
SPIxDO	Returns SPIxDO Pin
SPIxCLK	Returns SPIxCLK Pin

ETHERNET	Returns 1 if device supports Ethernet
QEI	Returns 1 if device has QEI
DAC	Returns 1 if device has a D/A Converter
DSP	Returns 1 if device supports DSP instructions
DCI	Returns 1 if device has a DCI module
DMA	Returns 1 if device supports DMA
CRC	Returns 1 if device has a CRC module
CWG	Returns 1 if device has a CWG module
NCO	Returns 1 if device has a NCO module
CLC	Returns 1 if device has a CLC module
DSM	Returns 1 if device has a DSM module
OPAMP	Returns 1 if device has op amps
RTC	Returns 1 if device has a Real Time Clock
CAP_SENSE	Returns 1 if device has a CSM cap sense module and 2 if it has a CTMU module
EXTERNAL_MEMORY	Returns 1 if device supports external program memory
INSTRUCTION_CLOCK	Returns the MPU instruction clock
ENH16	Returns 1 for Enhanced 16 devices

Availability:

All devices

Requires:	Nothing
Examples:	<pre>#IF getenv("VERSION")<3.050 #ERROR Compiler version too old #endif for(i=0;i<getenv("DATA_EEPROM");i++) write_eeprom(i,0); #if getenv("FUSE_VALID:BROWNOUT") #FUSE BROWNOUT #endif byte status_reg=GETENV("SFR:STATUS") bit carry_flag=GETENV("BIT:C")</pre>
Example Files:	None
Also See:	None

gets()

fgets()

Syntax:	gets (<i>string</i>) value = fgets (<i>string</i> , <i>stream</i>)
Parameters:	string is a pointer to an array of characters. Stream is a stream identifier (a constant byte)
Returns:	undefined
Function:	Reads characters (using getc()) into the string until a RETURN (value 13) is encountered. The string is terminated with a 0. Note that INPUT.C has a more versatile get_string function. If fgets() is used then the specified stream is used where gets() defaults to STDIN (the last USE RS232).
Availability:	All devices

Requires:	<code>#USE RS232</code>
Examples:	<pre>char string[30]; printf("Password: "); gets(string); if(strcmp(string, password)) printf("OK");</pre>
Example Files:	None
Also See:	getc() , get_string in input.c

goto_address()

Syntax:	goto_address(location);
Parameters:	location is a ROM address, 16 or 32 bit int.
Returns:	Nothing
Function:	This function jumps to the address specified by location. Jumps outside of the current function should be done only with great caution. This is not a normally used function except in very special situations.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>#define LOAD_REQUEST PIN_B1 #define LOADER 0x1f00 if(input(LOAD_REQUEST)) goto_address(LOADER);</pre>
Example Files:	setjmp.h
Also See:	label_address()

high_speed_adc_done()

Syntax:	value = high_speed_adc_done([pair]);
Parameters:	pair – Optional parameter that determines which ADC pair's ready flag to check. If not used all ready flags are checked.
Returns:	An int16. If pair is used 1 will be return if ADC is done with conversion, 0 will be return if still busy. If pair isn't use it will return a bit map of which conversion are ready to be read. For example a return value of 0x0041 means that ADC pair 6, AN12 and AN13, and ADC pair 0, AN0 and AN1, are ready to be read.
Function:	Can be polled to determine if the ADC has valid data to be read.
Availability:	Only on dsPIC33FJxxGSxxx devices.
Requires:	None
Examples:	<pre>int16 result[2] setup_high_speed_adc_pair(1, INDIVIDUAL_SOFTWARE_TRIGGER); setup_high_speed_adc(ADC_CLOCK_DIV_4); read_high_speed_adc(1, ADC_START_ONLY); while(!high_speed_adc_done(1)); read_high_speed_adc(1, ADC_READ_ONLY, result); printf("AN2 value = %LX, AN3 value = %LX\n\r",result[0],result[1]);</pre>
Example Files:	None
Also See:	setup_high_speed_adc() , setup_high_speed_adc_pair() , read_high_speed_adc()

i2c_init()

Syntax:	i2c_init([stream],baud);
Parameters:	stream – optional parameter specifying the stream defined in #USE I2C.

	baud – if baud is 0, I2C peripheral will be disable. If baud is 1, I2C peripheral is initialized and enabled with baud rate specified in #USE I2C directive. If baud is > 1 then I2C peripheral is initialized and enabled to specified baud rate.
Returns:	Nothing
Function:	To initialize I2C peripheral at run time to specified baud rate.
Availability:	All devices.
Requires:	#USE I2C
Examples:	#USE I2C(MASTER,I2C1, FAST,NOINIT) i2c_init(TRUE); //initialize and enable I2C peripheral to baud rate specified in // #USE I2C i2c_init(500000); //initialize and enable I2C peripheral to a baud rate of 500 //KBPS
Example Files:	None
Also See:	i2c_poll() , i2c_speed() , i2c_slaveaddr() , i2c_isr_state() , i2c_write() , i2c_read() , USE_I2C() , I2C()

i2c_isr_state()

Syntax:	state = i2c_isr_state(); state = i2c_isr_state(stream);
Parameters:	None
Returns:	state is an 8 bit int 0 - Address match received with R/W bit clear, perform i2c_read() to read the I2C address. 1-0x7F - Master has written data; i2c_read() will immediately return the data 0x80 - Address match received with R/W bit set; perform i2c_read() to read the I2C address, and use i2c_write() to pre-load the transmit buffer for the next transaction (next I2C read performed by master will read this byte). 0x81-0xFF - Transmission completed and acknowledged; respond with i2c_write() to pre-load the transmit buffer for the next transaction (the next I2C read performed by master will read this byte).

Function:	<p>Returns the state of I2C communications in I2C slave mode after an SSP interrupt. The return value increments with each byte received or sent.</p> <p>If 0x00 or 0x80 is returned, an <code>i2c_read()</code> needs to be performed to read the I2C address that was sent (it will match the address configured by <code>#USE I2C</code> so this value can be ignored)</p>
Availability:	Devices with i2c hardware
Requires:	<code>#USE I2C</code>
Examples:	<pre>#INT_SSP void i2c_isr() { state = i2c_isr_state(); if(state== 0) i2c_read(); i2c_read(); if(state == 0x80) i2c_read(2); if(state >= 0x80) i2c_write(send_buffer[state - 0x80]); else if(state > 0) rcv_buffer[state - 1] = i2c_read(); }</pre>
Example Files:	ex_slave.c
Also See:	i2c_poll , i2c_speed , i2c_start , i2c_stop , i2c_slaveaddr , i2c_write , i2c_read , #USE I2C , I2C Overview

i2c_poll()

Syntax:	i2c_poll() i2c_poll(stream)
Parameters:	stream (optional)- specify the stream defined in <code>#USE I2C</code>
Returns:	1 (TRUE) or 0 (FALSE)
Function:	<p>The <code>I2C_POLL()</code> function should only be used when the built-in SSP is used. This function returns TRUE if the hardware has a received byte in the buffer. When a TRUE is returned, a call to <code>I2C_READ()</code> will immediately return the byte that was received.</p>

Availability:	Devices with built in I2C
Requires:	#USE I2C
Examples:	<pre>if(i2c_poll()) buffer [index]=i2c_read();//read data</pre>
Example Files:	None
Also See:	i2c_speed , i2c_start , i2c_stop , i2c_slaveaddr , i2c_isr_state , i2c_write , i2c_read , #USE I2C , I2C Overview

i2c_read()

Syntax:	<pre>data = i2c_read(); data = i2c_read(ack); data = i2c_read(stream, ack);</pre>
Parameters:	<p>ack -Optional, defaults to 1. 0 indicates do not ack. 1 indicates to ack. 2 slave only, indicates to not release clock at end of read. Use when i2c_isr_state () returns 0x80. stream - specify the stream defined in #USE I2C</p>
Returns:	data - 8 bit int
Function:	Reads a byte over the I2C interface. In master mode this function will generate the clock and in slave mode it will wait for the clock. There is no timeout for the slave, use i2c_poll() to prevent a lockup. Use restart_wdt() in the #USE I2C to strobe the watch-dog timer in the slave mode while waiting.
Availability:	All devices.
Requires:	#USE I2C
Examples:	<pre>i2c_start(); i2c_write(0x1); data1 = i2c_read(TRUE); data2 = i2c_read(FALSE);</pre>

```
i2c_stop();
```

Example Files: [ex_extee.c](#) with [2416.c](#)

Also See: [i2c_poll](#), [i2c_speed](#), [i2c_start](#), [i2c_stop](#), [i2c_slaveaddr](#), [i2c_isr_state](#), [i2c_write](#), [#USE I2C](#), [I2C Overview](#)

i2c_slaveaddr()

Syntax: **I2C_SlaveAddr**(addr);
I2C_SlaveAddr(stream, addr);

Parameters: **addr** = 8 bit device address
stream(optional) - specifies the stream used in #USE I2C

Returns: Nothing

Function: This functions sets the address for the I2C interface in slave mode.

Availability: Devices with built in I2C

Requires: #USE I2C

Examples: `i2c_SlaveAddr(0x08);`
`i2c_SlaveAddr(i2cStream1, 0x08);`

Example Files: [ex_slave.c](#)

Also See: [i2c_poll](#), [i2c_speed](#), [i2c_start](#), [i2c_stop](#), [i2c_isr_state](#), [i2c_write](#), [i2c_read](#), [#USE I2C](#), [I2C Overview](#)

i2c_speed()

Syntax: **i2c_speed** (*baud*)
i2c_speed (stream, *baud*)

Parameters:	baud is the number of bits per second. stream - specify the stream defined in #USE I2C
Returns:	Nothing.
Function:	This function changes the I2c bit rate at run time. This only works if the hardware I2C module is being used.
Availability:	All devices.
Requires:	#USE I2C
Examples:	<code>I2C_Speed (400000);</code>
Example Files:	none
Also See:	i2c_poll , i2c_start , i2c_stop , i2c_slaveaddr , i2c_isr_state , i2c_write , i2c_read , #USE I2C , I2C Overview

i2c_start()

Syntax:	i2c_start() i2c_start(stream) i2c_start(stream, restart)
Parameters:	stream: specify the stream defined in #USE I2C restart: 2 – new restart is forced instead of start 1 – normal start is performed 0 (or not specified) – restart is done only if the compiler last encountered a I2C_START and no I2C_STOP
Returns:	undefined
Function:	Issues a start condition when in the I2C master mode. After the start condition the clock is held low until I2C_WRITE() is called. If another I2C_start is called in the same function before an i2c_stop is called, then a special restart condition is issued. Note that specific I2C protocol depends on the slave device. The I2C_START function will now accept an optional parameter. If 1 the compiler assumes the bus is in the stopped state. If 2 the compiler treats this I2C_START as a restart. If no parameter is passed a 2 is

	used only if the compiler compiled a I2C_START last with no I2C_STOP since.
Availability:	All devices.
Requires:	#USE I2C
Examples:	<pre> i2c_start(); i2c_write(0xa0); // Device address i2c_write(address); // Data to device i2c_start(); // Restart i2c_write(0xa1); // to change data direction data=i2c_read(0); // Now read from slave i2c_stop(); </pre>
Example Files:	ex_extee.c with 2416.c
Also See:	i2c_poll , i2c_speed , i2c_stop , i2c_slaveaddr , i2c_isr_state , i2c_write , i2c_read , #USE I2C , I2C Overview

i2c_stop()

Syntax:	i2c_stop() i2c_stop(stream)
Parameters:	stream: (optional) specify stream defined in #USE I2C
Returns:	undefined
Function:	Issues a stop condition when in the I2C master mode.
Availability:	All devices.
Requires:	#USE I2C
Examples:	<pre> i2c_start(); // Start condition i2c_write(0xa0); // Device address i2c_write(5); // Device command i2c_write(12); // Device data i2c_stop(); // Stop condition </pre>

Example Files:	ex_extee.c with 2416.c
Also See:	i2c_poll , i2c_speed , i2c_start , i2c_slaveaddr , i2c_isr_state , i2c_write , i2c_read , #USE I2C , I2C Overview

i2c_write()

Syntax:	i2c_write (<i>data</i>) i2c_write (stream , <i>data</i>)
Parameters:	data is an 8 bit int stream - specify the stream defined in #USE I2C
Returns:	This function returns the ACK Bit. 0 means ACK, 1 means NO ACK, 2 means there was a collision if in Multi_Master Mode. This does not return an ACK if using i2c in slave mode.
Function:	Sends a single byte over the I2C interface. In master mode this function will generate a clock with the data and in slave mode it will wait for the clock from the master. No automatic timeout is provided in this function. This function returns the ACK bit. The LSB of the first write after a start determines the direction of data transfer (0 is master to slave). Note that specific I2C protocol depends on the slave device.
Availability:	All devices.
Requires:	#USE I2C
Examples:	<pre>long cmd; ... i2c_start(); // Start condition i2c_write(0xa0); // Device address i2c_write(cmd); // Low byte of command i2c_write(cmd>>8); // High byte of command i2c_stop(); // Stop condition</pre>
Example Files:	ex_extee.c with 2416.c
Also See:	i2c_poll , i2c_speed , i2c_start , i2c_stop , i2c_slaveaddr , i2c_isr_state , i2c_read , #USE I2C , I2C Overview

input()

Syntax:	value = input (pin)
Parameters:	<p>Pin to read. Pins are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #define PIN_A3 43 .</p> <p>The PIN could also be a variable. The variable must have a value equal to one of the constants (like PIN_A1) to work properly. The tristate register is updated unless the FAST_IO mode is set on port A. note that doing I/O with a variable instead of a constant will take much longer time.</p>
Returns:	0 (or FALSE) if the pin is low, 1 (or TRUE) if the pin is high
Function:	This function returns the state of the indicated pin. The method of I/O is dependent on the last USE *_IO directive. By default with standard I/O before the input is done the data direction is set to input.
Availability:	All devices.
Requires:	Pin constants are defined in the devices .h file
Examples:	<pre>while (!input(PIN_B1)); // waits for B1 to go high if(input(PIN_A0)) printf("A0 is now high\r\n"); int16 i=PIN_B1; while(!i); //waits for B1 to go high</pre>
Example Files:	ex_pulse.c
Also See:	input_x() , output_low() , output_high() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

input_change_x()

Syntax:	<pre>value = input_change_a(); value = input_change_b(); value = input_change_c(); value = input_change_d(); value = input_change_e(); value = input_change_f(); value = input_change_g(); value = input_change_h(); value = input_change_j(); value = input_change_k();</pre>
Parameters:	None
Returns:	An 8-bit or 16-bit int representing the changes on the port.
Function:	This function reads the level of the pins on the port and compares them to the results the last time the input_change_x() function was called. A 1 is returned if the value has changed, 0 if the value is unchanged.
Availability:	All devices.
Requires:	None
Examples:	<pre>pin_check = input_change_b();</pre>
Example Files:	None
Also See:	input() , input_x() , output_x() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

input_state()

Syntax:	<pre>value = input_state(pin)</pre>
Parameters:	<i>pin</i> to read. Pins are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: <code>#define PIN_A3</code>

	43 .
Returns:	Bit specifying whether pin is high or low. A 1 indicates the pin is high and a 0 indicates it is low.
Function:	This function reads the level of a pin without changing the direction of the pin as INPUT() does.
Availability:	All devices.
Requires:	Nothing
Examples:	<pre>level = input_state(pin_A3); printf("level: %d", level);</pre>
Example Files:	None
Also See:	input() , set_tris_x() , output_low() , output_high() , General Purpose I/O

input_x()

Syntax:	<pre>value = input_a() value = input_b() value = input_c() value = input_d() value = input_e() value = input_f() value = input_g() value = input_h() value = input_j() value = input_k()</pre>
Parameters:	None
Returns:	An 8 bit int representing the port input data.
Function:	Inputs an entire byte from a port. The direction register is changed

	in accordance with the last specified <code>#USE *_IO</code> directive. By default with standard I/O before the input is done the data direction is set to input.
Availability:	All devices.
Requires:	Nothing
Examples:	<code>data = input_b();</code>
Example Files:	ex_psp.c
Also See:	input() , output_x() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO

interrupt_active()

Syntax:	interrupt_active (interrupt)
Parameters:	Interrupt – constant specifying the interrupt
Returns:	Boolean value
Function:	The function checks the interrupt flag of the specified interrupt and returns true in case the flag is set.
Availability:	Device with interrupts
Requires:	Should have a <code>#INT_xxxx</code> , Constants are defined in the devices .h file.
Examples:	<code>interrupt_active(INT_TIMER0);</code> <code>interrupt_active(INT_TIMER1);</code>
Example Files:	None
Also See:	disable_interrupts() , #INT , Interrupts Overview clear_interrupt , enable_interrupts()

isalnum(char)
isdigit(char)
isspace(char)
isprint(x)

isalpha(char)
isgraph(x)
isupper(char)
ispunct(x)

iscntrl(x)
islower(char)
isxdigit(char)

Syntax:

value = isalnum(*datac*)
value = isalpha(*datac*)
value = isdigit(*datac*)
value = islower(*datac*)
value = isspace(*datac*)
value = isupper(*datac*)
value = isxdigit(*datac*)
value = iscntrl(*datac*)
value = isgraph(*datac*)
value = isprint(*datac*)
value = punct(*datac*)

Parameters:

datac is a 8 bit character

Returns:

0 (or FALSE) if *datac* dose not match the criteria, 1 (or TRUE) if *datac* does match the criteria.

Function:

Tests a character to see if it meets specific criteria as follows:	
isalnum(x)	X is 0..9, 'A'..'Z', or 'a'..'z'
isalpha(x)	X is 'A'..'Z' or 'a'..'z'
isdigit(x)	X is '0'..'9'
islower(x)	X is 'a'..'z'
isupper(x)	X is 'A'..'Z'
isspace(x)	X is a space
isxdigit(x)	X is '0'..'9', 'A'..'F', or 'a'..'f'
iscntrl(x)	X is less than a space
isgraph(x)	X is greater than a space
isprint(x)	X is greater than or equal to a space
ispunct(x)	X is greater than a space and not a letter or number

Availability:

All devices.

Requires:

#INCLUDE <ctype.h>

Examples:

```
char id[20];
...
if(isalpha(id[0])) {
    valid_id=TRUE;
    for (i=1;i<strlen(id);i++)
        valid_id=valid_id && isalnum(id[i]);
} else
    valid_id=FALSE;
```

Example Files: [ex_str.c](#)

Also See: [isamong\(\)](#)

isamong()

Syntax: **result = isamong (value, cstring)**

Parameters: **value** is a character
cstring is a constant sting

Returns: 0 (or FALSE) if value is not in cstring
1 (or TRUE) if value is in cstring

Function: Returns TRUE if a character is one of the characters in a constant string.

Availability: All devices

Requires: Nothing

Examples:

```
char x= 'x';
...
if ( isamong ( x,
    "0123456789ABCDEFGHIJKLMNOPQRSTUVWXYZ" ) )
    printf ("The character is valid");
```

Example Files: `#INCLUDE <ctype.h>`

Also See: [isalnum\(\)](#), [isalpha\(\)](#), [isdigit\(\)](#), [isspace\(\)](#), [islower\(\)](#), [isupper\(\)](#), [isxdigit\(\)](#)

itoa()

Syntax:	<code>string = itoa(i32value, i8base, string)</code>
Parameters:	i32value is a 32 bit int i8base is a 8 bit int string is a pointer to a null terminated string of characters
Returns:	string is a pointer to a null terminated string of characters
Function:	Converts the signed int32 to a string according to the provided base and returns the converted value if any. If the result cannot be represented, the function will return 0.
Availability:	All devices
Requires:	<code>#INCLUDE <stdlib.h></code>
Examples:	<pre>int32 x=1234; char string[5]; itoa(x,10, string); // string is now "1234"</pre>
Example Files:	None
Also See:	None

jump_to_isr()

Syntax:	<code>jump_to_isr (address)</code>
Parameters:	address is a valid program memory address
Returns:	No value
Function:	The <code>jump_to_isr</code> function is used when the location of the interrupt service routines are not at the default location in program memory. When an interrupt occurs, program execution will jump to the default location and then jump to the specified address.

Availability:	All devices
Requires:	Nothing
Examples:	<pre>int_global void global_isr(void) { jump_to_isr(isr_address); }</pre>
Example Files:	ex_bootloader.c
Also See:	#BUILD

kbhit()

Syntax:	value = kbhit() value = kbhit (stream)
Parameters:	stream is the stream id assigned to an available RS232 port. If the stream parameter is not included, the function uses the primary stream used by getc().
Returns:	0 (or FALSE) if getc() will need to wait for a character to come in, 1 (or TRUE) if a character is ready for getc()
Function:	If the RS232 is under software control this function returns TRUE if the start bit of a character is being sent on the RS232 RCV pin. If the RS232 is hardware this function returns TRUE if a character has been received and is waiting in the hardware buffer for getc() to read. This function may be used to poll for data without stopping and waiting for the data to appear. Note that in the case of software RS232 this function should be called at least 10 times the bit rate to ensure incoming data is not lost.
Availability:	All devices.
Requires:	#USE RS232
Examples:	<pre>char timed_getc() { long timeout; timeout_error=FALSE;</pre>

```

        timeout=0;
        while(!kbhit() && (++timeout<50000)) // 1/2
                                                    // second
            delay_us(10);
        if(kbhit())
            return(getc());
        else {
            timeout_error=TRUE;
            return(0);
        }
    }

```

Example Files: [ex_tgetc.c](#)

Also See: [getc\(\)](#), [#USE RS232](#), [RS232 I/O Overview](#)

label_address()

Syntax: **value = label_address(*label*);**

Parameters: *label* is a C label anywhere in the function

Returns: A 16 bit int in PCB,PCM and a 32 bit int for PCH, PCD

Function: This function obtains the address in ROM of the next instruction after the label. This is not a normally used function except in very special situations.

Availability: All devices.

Requires: Nothing

Examples:

```

start:
    a = (b+c)<<2;
end:
printf("It takes %lu ROM locations.\r\n",
    label_address(end)-label_address(start));

```

Example Files: [setjmp.h](#)

Also See: [goto_address\(\)](#)

labs()

Syntax:	result = labs (value)
Parameters:	value is a 16 bit signed long int
Returns:	A 16 bit signed long int
Function:	Computes the absolute value of a long integer.
Availability:	All devices.
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>if(labs(target_value - actual_value) > 500) printf("Error is over 500 points\r\n");</pre>
Example Files:	None
Also See:	abs()

lcd_contrast()

Syntax:	lcd_contrast (contrast)
Parameters:	contrast is used to set the internal contrast control resistance ladder.
Returns:	undefined.
Function:	This function controls the contrast of the LCD segments with a value passed in between 0 and 7. A value of 0 will produce the minimum contrast, 7 will produce the maximum contrast.
Availability:	Only on select devices with built-in LCD Driver Module hardware.
Requires:	None.
Examples:	<pre>lcd_contrast(0); // Minimum Contrast lcd_contrast(7); // Maximum Contrast</pre>

Example Files:	None.
Also See:	lcd_load() , lcd_symbol() , setup_lcd() , Internal LCD Overview

lcd_load()

Syntax:	lcd_load (<i>buffer_pointer</i> , <i>offset</i> , <i>length</i>);
Parameters:	buffer_pointer points to the user data to send to the LCD, offset is the offset into the LCD segment memory to write the data, length is the number of bytes to transfer to the LCD segment memory.
Returns:	undefined.
Function:	This function will load length bytes from buffer_pointer into the LCD segment memory beginning at offset . The <code>lcd_symbol()</code> function provides as easier way to write data to the segment memory.
Availability:	Only on devices with built-in LCD Driver Module hardware.
Requires	Constants are defined in the devices *.h file.
Examples:	<code>lcd_load(buffer, 0, 16);</code>
Example Files:	ex_92lcd.c
Also See:	lcd_symbol() , setup_lcd() , lcd_contrast() , Internal LCD Overview

lcd_symbol()

Syntax:	lcd_symbol (<i>symbol</i> , <i>bX_addr</i>);
Parameters:	symbol is a 8 bit or 16 bit constant. bX_addr is a bit address representing the segment location to be used for bit X of the specified symbol. 1-16 segments could be specified.

Returns:	undefined
Function:	This function loads the bits for the symbol into the segment data registers for the LCD with each bit address specified. If bit X in symbol is set, the segment at bX_addr is set, otherwise it is cleared. The bX_addr is a bit address into the LCD RAM.
Availability:	Only on devices with built-in LCD Driver Module hardware.
Requires	Constants are defined in the devices *.h file.
Examples:	<pre>byte CONST DIGIT_MAP[10] = {0xFC, 0x60, 0xDA, 0xF2, 0x66, 0xB6, 0xBE, 0xE0, 0xFE, 0xE6}; #define DIGIT1 COM1+20, COM1+18, COM2+18, COM3+20, COM2+28, COM1+28, COM2+20, COM3+18 for(i = 0; i <= 9; i++) { lcd_symbol(DIGIT_MAP[i], DIGIT1); delay_ms(1000); }</pre>
Example Files:	ex_92lcd.c
Also See:	setup_lcd() , lcd_load() , lcd_contrast() , Internal LCD Overview

ldexp()

Syntax:	result= ldexp (value, exp);
Parameters:	value is float exp is a signed int.
Returns:	result is a float with value result times 2 raised to power exp.
Function:	The ldexp function multiplies a floating-point number by an integral power of 2.
Availability:	All devices.
Requires:	#INCLUDE <math.h>

Examples:

```
float result;
result=ldexp(.5,0);
// result is .5
```

Example Files:

None

Also See:
[frexp\(\)](#), [exp\(\)](#), [log\(\)](#), [log10\(\)](#), [modf\(\)](#)

log()

Syntax:**result = log (value)****Parameters:****value** is a float**Returns:**

A float

Function:

Computes the natural logarithm of the float x. If the argument is less than or equal to zero or too large, the behavior is undefined.

Note on error handling:

"errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.

Domain error occurs in the following cases:

- log: when the argument is negative

Availability:

All devices

Requires:

#INCLUDE <math.h>

Examples:

lnx = log(x);

Example Files:

None

Also See:
[log10\(\)](#), [exp\(\)](#), [pow\(\)](#)

log10()

Syntax:	result = log10 (value)
Parameters:	value is a float
Returns:	A float
Function:	<p>Computes the base-ten logarithm of the float x. If the argument is less than or equal to zero or too large, the behavior is undefined.</p> <p>Note on error handling: If "errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.</p> <p>Domain error occurs in the following cases:</p> <ul style="list-style-type: none">• log10: when the argument is negative
Availability:	All devices
Requires:	#INCLUDE <math.h>
Examples:	<pre>db = log10(read_adc()*(5.0/255)) *10;</pre>
Example Files:	None
Also See:	log() , exp() , pow()

longjmp()

Syntax:	longjmp (env, val)
Parameters:	<p>env: The data object that will be restored by this function</p> <p>val: The value that the function setjmp will return. If val is 0 then the function setjmp will return 1 instead.</p>
Returns:	After longjmp is completed, program execution continues as if the corresponding invocation of the setjmp function had just returned the value specified by val.

Function:	Performs the non-local transfer of control.
Availability:	All devices
Requires:	#INCLUDE <setjmp.h>
Examples:	<code>longjmp(jmpbuf, 1);</code>
Example Files:	None
Also See:	setjmp()

make8()

Syntax:	i8 = MAKE8(<i>var</i>, <i>offset</i>)
Parameters:	<i>var</i> is a 16 or 32 bit integer. <i>offset</i> is a byte offset of 0,1,2 or 3.
Returns:	An 8 bit integer
Function:	Extracts the byte at offset from var. Same as: <code>i8 = (((var >> (offset*8)) & 0xff)</code> except it is done with a single byte move.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>int32 x; int y; y = make8(x,3); // Gets MSB of x</pre>
Example Files:	None
Also See:	make16() , make32()

make16()

Syntax:	i16 = MAKE16(<i>varhigh</i>, <i>varlow</i>)
Parameters:	<i>varhigh</i> and <i>varlow</i> are 8 bit integers.
Returns:	A 16 bit integer
Function:	Makes a 16 bit number out of two 8 bit numbers. If either parameter is 16 or 32 bits only the lsb is used. Same as: i16 = (int16)(varhigh&0xff)*0x100+(varlow&0xff) except it is done with two byte moves.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>long x; int hi,lo; x = make16(hi,lo);</pre>
Example Files:	ltc1298.c
Also See:	make8() , make32()

make32()

Syntax:	i32 = MAKE32(<i>var1</i>, <i>var2</i>, <i>var3</i>, <i>var4</i>)
Parameters:	<i>var1-4</i> are a 8 or 16 bit integers. <i>var2-4</i> are optional.
Returns:	A 32 bit integer
Function:	Makes a 32 bit number out of any combination of 8 and 16 bit numbers. Note that the number of parameters may be 1 to 4. The msb is first. If the total bits provided is less than 32 then zeros are added at the msb.
Availability:	All devices

Requires:	Nothing
Examples:	<pre>int32 x; int y; long z; x = make32(1,2,3,4); // x is 0x01020304 y=0x12; z=0x4321; x = make32(y,z); // x is 0x00124321 x = make32(y,y,z); // x is 0x12124321</pre>
Example Files:	ex_freqc.c
Also See:	make8() , make16()

malloc()

Syntax:	ptr=malloc(size)
Parameters:	size is an integer representing the number of bytes to be allocated.
Returns:	A pointer to the allocated memory, if any. Returns null otherwise.
Function:	The malloc function allocates space for an object whose size is specified by size and whose value is indeterminate.
Availability:	All devices
Requires:	#INCLUDE <stdlibm.h>
Examples:	<pre>int * iptr; iptr=malloc(10); // iptr will point to a block of memory of 10 bytes.</pre>
Example Files:	None
Also See:	realloc() , free() , calloc()

memcpy()

memmove()

Syntax:	memcpy (<i>destination, source, n</i>) memmove (<i>destination, source, n</i>)
Parameters:	destination is a pointer to the destination memory. source is a pointer to the source memory., n is the number of bytes to transfer
Returns:	undefined
Function:	Copies n bytes from source to destination in RAM. Be aware that array names are pointers where other variable names and structure names are not (and therefore need a & before them). Memmove performs a safe copy (overlapping objects doesn't cause a problem). Copying takes place as if the n characters from the source are first copied into a temporary array of n characters that doesn't overlap the destination and source objects. Then the n characters from the temporary array are copied to destination.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>memcpy(&structA, &structB, sizeof (structA)); memcpy(arrayA,arrayB,sizeof (arrayA)); memcpy(&structA, &databyte, 1); char a[20]="hello"; memmove(a,a+2,5); // a is now "llo"</pre>
Example Files:	None
Also See:	strcpy() , memset()

memset()

Syntax:	memset (<i>destination</i> , <i>value</i> , <i>n</i>)
Parameters:	<p><i>destination</i> is a pointer to memory. <i>value</i> is a 8 bit int <i>n</i> is a 16 bit int.</p> <p>On PCB and PCM parts n can only be 1-255.</p>
Returns:	undefined
Function:	Sets n number of bytes, starting at destination, to value. Be aware that array names are pointers where other variable names and structure names are not (and therefore need a & before them).
Availability:	All devices
Requires:	Nothing
Examples:	<pre>memset(arrayA, 0, sizeof(arrayA)); memset(arrayB, '?', sizeof(arrayB)); memset(&structA, 0xFF, sizeof(structA));</pre>
Example Files:	None
Also See:	memcpy()

modf()

Syntax:	result= modf (<i>value</i> , & <i>integral</i>)
Parameters:	<p><i>value</i> is a float <i>integral</i> is a float</p>
Returns:	result is a float
Function:	The modf function breaks the argument value into integral and fractional parts, each of which has the same sign as the argument. It stores the integral part as a float in the object integral.

Availability:	All devices
Requires:	#INCLUDE <math.h>
Examples:	<pre>float result, integral; result=modf(123.987,&integral); // result is .987 and integral is 123.0000</pre>
Example Files:	None
Also See:	None

_mul()

Syntax:	prod=_mul(<i>val1</i>, <i>val2</i>);
Parameters:	<i>val1</i> and <i>val2</i> are both 8-bit or 16-bit integers
Returns:	A 16-bit integer if both parameters are 8-bit integers, or a 32-bit integer if both parameters are 16-bit integers.
Function:	Performs an optimized multiplication. By accepting a different type than it returns, this function avoids the overhead of converting the parameters to a larger type.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>int a=50, b=100; long int c; c = _mul(a, b); //c holds 5000</pre>
Example Files:	None
Also See:	None

nargs()

Syntax:	void foo(char * str, int count, ...)
Parameters:	The function can take variable parameters. The user can use stdarg library to create functions that take variable parameters.
Returns:	Function dependent.
Function:	<p>The stdarg library allows the user to create functions that supports variable arguments.</p> <p>The function that will accept a variable number of arguments must have at least one actual, known parameters, and it may have more. The number of arguments is often passed to the function in one of its actual parameters. If the variable-length argument list can involve more that one type, the type information is generally passed as well. Before processing can begin, the function creates a special argument pointer of type va_list.</p>
Availability:	All devices
Requires:	#INCLUDE <stdarg.h>
Examples:	<pre>int foo(int num, ...) { int sum = 0; int i; va_list argptr; // create special argument pointer va_start(argptr,num); // initialize argptr for(i=0; i<num; i++) sum = sum + va_arg(argptr, int); va_end(argptr); // end variable processing return sum; } void main() { int total; total = foo(2,4,6,9,10,2); }</pre>
Example Files:	None
Also See:	va_start() , va_end() , va_arg()

offsetof() offsetofbit()

Syntax:	value = offsetof(<i>sttype</i>, <i>field</i>); value = offsetofbit(<i>sttype</i>, <i>field</i>);
Parameters:	<i>sttype</i> is a structure type name. <i>Field</i> is a field from the above structure
Returns:	An 8 bit byte
Function:	These functions return an offset into a structure for the indicated field. offsetof returns the offset in bytes and offsetofbit returns the offset in bits.
Availability:	All devices
Requires:	#INCLUDE <stddef.h>
Examples:	<pre>struct time_structure { int hour, min, sec; int zone : 4; int1 daylight_savings; } x = offsetof(time_structure, sec); // x will be 2 x = offsetofbit(time_structure, sec); // x will be 16 x = offsetof (time_structure, daylight_savings); // x will be 3 x = offsetofbit(time_structure, daylight_savings); // x will be 28</pre>
Example Files:	None
Also See:	None

output_x()

Syntax:	<code>output_a (value)</code> <code>output_b (value)</code> <code>output_c (value)</code> <code>output_d (value)</code> <code>output_e (value)</code> <code>output_f (value)</code> <code>output_g (value)</code> <code>output_h (value)</code> <code>output_j (value)</code> <code>output_k (value)</code>
Parameters:	<i>value</i> is a 8 bit int
Returns:	undefined
Function:	Output an entire byte to a port. The direction register is changed in accordance with the last specified <code>#USE *_IO</code> directive.
Availability:	All devices, however not all devices have all ports (A-E)
Requires:	Nothing
Examples:	<code>OUTPUT_B(0xf0);</code>
Example Files:	ex_patg.c
Also See:	input() , output_low() , output_high() , output_float() , output_bit() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

output_bit()

Syntax:	<code>output_bit (pin, value)</code>
Parameters:	<i>Pins</i> are defined in the devices .h file. The actual number is a bit address. For example, port a (byte 5) bit 3 would have a value of $5*8+3$ or 43 . This is defined as follows: <code>#define PIN_A3 43</code> . The PIN could also be a variable. The variable must have a value equal

	to one of the constants (like PIN_A1) to work properly. The tristate register is updated unless the FAST_IO mode is set on port A. Note that doing I/O with a variable instead of a constant will take much longer time. Value is a 1 or a 0.
Returns:	undefined
Function:	Outputs the specified value (0 or 1) to the specified I/O pin. The method of setting the direction register is determined by the last #USE *_IO directive.
Availability:	All devices.
Requires:	Pin constants are defined in the devices .h file
Examples:	<pre> output_bit(PIN_B0, 0); // Same as output_low(pin_B0); output_bit(PIN_B0,input(PIN_B1)); // Make pin B0 the same as B1 output_bit(PIN_B0,shift_left(&data,1,input(PIN_B1))); // Output the MSB of data to // B0 and at the same time // shift B1 into the LSB of data int16 i=PIN_B0; ouput_bit(i,shift_left(&data,1,input(PIN_B1))); //same as above example, but //uses a variable instead of a constant </pre>
Example Files:	ex_extee.c with 9356.c
Also See:	input() , output_low() , output_high() , output_float() , output_x() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

output_drive()

Syntax:	output_drive(pin)
Parameters:	<i>Pins</i> are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #DEFINE PIN_A3 43 .
Returns:	undefined
Function:	Sets the specified pin to the output mode.
Availability:	All devices.
Requires:	Pin constants are defined in the devices.h file.
Examples:	<pre>output_drive(pin_A0); // sets pin_A0 to output its value output_bit(pin_B0, input(pin_A0)) // makes B0 the same as A0</pre>
Example Files:	None
Also See:	input() , output_low() , output_high() , output_bit() , output_x() , output_float()

output_float()

Syntax:	output_float (pin)
Parameters:	<i>Pins</i> are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #DEFINE PIN_A3 43 . The PIN could also be a variable to identify the pin. The variable must have a value equal to one of the constants (like PIN_A1) to work properly. Note that doing I/O with a variable instead of a constant will take much longer time.
Returns:	undefined

Function:	Sets the specified pin to the input mode. This will allow the pin to float high to represent a high on an open collector type of connection.
Availability:	All devices.
Requires:	Pin constants are defined in the devices .h file
Examples:	<pre>if((data & 0x80)==0) output_low(pin_A0); else output_float(pin_A0);</pre>
Example Files:	None
Also See:	input() , output_low() , output_high() , output_bit() , output_x() , output_drive() , #USE FIXED_IO , #USE FAST_IO , #USE STANDARD_IO , General Purpose I/O

output_high()

Syntax:	output_high (pin)
Parameters:	<i>Pin</i> to write to. Pins are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #DEFINE PIN_A3 43 . The PIN could also be a variable. The variable must have a value equal to one of the constants (like PIN_A1) to work properly. The tristate register is updated unless the FAST_IO mode is set on port A. Note that doing I/O with a variable instead of a constant will take much longer time.
Returns:	undefined
Function:	Sets a given pin to the high state. The method of I/O used is dependent on the last USE *_IO directive.
Availability:	All devices.
Requires:	Pin constants are defined in the devices .h file
Examples:	output_high(PIN_A0);


```
Int16 i=PIN_A1;
output_low(PIN_A1);
```

Example Files: [ex_sqw.c](#)

Also See:

[input\(\)](#), [output_low\(\)](#), [output_float\(\)](#), [output_bit\(\)](#), [output_x\(\)](#), [#USE FIXED_IO](#), [#USE FAST_IO](#), [#USE STANDARD_IO](#), [General Purpose I/O](#)

output_low()

Syntax: `output_low (pin)`

Parameters:

Pins are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #DEFINE PIN_A3 43 . The PIN could also be a variable. The variable must have a value equal to one of the constants (like PIN_A1) to work properly. The tristate register is updated unless the FAST_IO mode is set on port A. Note that doing I/O with a variable instead of a constant will take much longer time.

Returns: undefined

Function:

Sets a given pin to the ground state. The method of I/O used is dependent on the last USE *_IO directive.

Availability:

All devices.

Requires:

Pin constants are defined in the devices .h file

Examples:

```
output_low(PIN_A0);

Int16i=PIN_A1;
output_low(PIN_A1);
```

Example Files: [ex_sqw.c](#)

Also See:

[input\(\)](#), [output_high\(\)](#), [output_float\(\)](#), [output_bit\(\)](#), [output_x\(\)](#), [#USE FIXED_IO](#), [#USE FAST_IO](#), [#USE STANDARD_IO](#), [General Purpose I/O](#)

output_toggle()

Syntax:	output_toggle(<i>pin</i>)
Parameters:	Pins are defined in the devices .h file. The actual value is a bit address. For example, port a (byte 5) bit 3 would have a value of 5*8+3 or 43 . This is defined as follows: #DEFINE PIN_A3 43 .
Returns:	Undefined
Function:	Toggles the high/low state of the specified pin.
Availability:	All devices.
Requires:	Pin constants are defined in the devices .h file
Examples:	<code>output_toggle(PIN_B4);</code>
Example Files:	None
Also See:	Input() , output_high() , output_low() , output_bit() , output_x()

perror()

Syntax:	perror(<i>string</i>);
Parameters:	<i>string</i> is a constant string or array of characters (null terminated).
Returns:	Nothing
Function:	This function prints out to STDERR the supplied string and a description of the last system error (usually a math error).
Availability:	All devices.
Requires:	#USE RS232, #INCLUDE <errno.h>
Examples:	<pre> x = sin(y); if(errno!=0) perror("Problem in find_area"); </pre>

Example Files:	None
Also See:	RS232 I/O Overview

pid_busy()

Syntax:	result = pid_busy();
Parameters:	None
Returns:	TRUE if PID module is busy or FALSE if PID module is not busy.
Function:	To check if the PID module is busy with a calculation.
Availability:	All devices with a PID module.
Requires:	Nothing
Examples:	<pre>pid_get_result(PID_START_ONLY, ADCResult); while(pid_busy()); pid_get_result(PID_READ_ONLY, &PIDResult);</pre>
Example Files:	None
Also See:	setup_pid() , pid_write() , pid_get_result() , pid_read()

pid_get_result()

Syntax:	pid_get_result(set_point, input, &output);	//Start and Read
	pid_get_result(mode, set_point, input);	//Start Only
	pid_get_result(mode, &output)	//Read Only
	pid_get_result(mode, set_point, input, &output);	
Parameters:	mode- constant parameter specifying whether to only start the calculation, only read the result, or start the calculation and read	

	<p>the result. The options are defined in the device's header file as:</p> <ul style="list-style-type: none">· PID_START_READ· PID_READ_ONLY· PID_START_ONLY <p>set_point - a 16-bit variable or constant representing the set point of the control system, the value the input from the control system is compared against to determine the error in the system.</p> <p>input - a 16-bit variable or constant representing the input from the control system.</p> <p>output - a structure that the output of the PID module will be saved to. Either pass the address of the structure as the parameter, or a pointer to the structure as the parameter.</p>
Returns:	Nothing
Function:	To pass the set point and input from the control system to the PID module, start the PID calculation and get the result of the PID calculation. The PID calculation starts, automatically when the input is written to the PID module's input registers.
Availability:	All devices with a PID module.
Requires:	Constants are defined in the device's .h file.
Examples:	<pre>pid_get_result(SetPoint, ADCResult, &PIDOutput); //Start and Read pid_get_result(PID_START_ONLY, SetPoint, ADCResult); //Start Only pid_get_result(PID_READ_ONLY, &PIDResult); //Read Only</pre>
Example Files:	None
Also See:	setup_pid() , pid_read() , pid_write() , pid_busy()

pid_read()

Syntax:	pid_read (register, &output);
Parameters:	<p>register- constant specifying which PID registers to read. The registers that can be written are defined in the device's header file as:</p> <ul style="list-style-type: none"> · PID_ADDR_ACCUMULATOR · PID_ADDR_OUTPUT · PID_ADDR_Z1 · PID_ADDR_Z2 · PID_ADDR_K1 · PID_ADDR_K2 · PID_ADDR_K3 <p>output -a 16-bit variable, 32-bit variable or structure that specified PID registers value will be saved to. The size depends on the registers that are being read. Either pass the address of the variable or structure as the parameter, or a pointer to the variable or structure as the parameter.</p>
Returns:	Nothing
Function:	To read the current value of the Accumulator, Output, Z1, Z2, Set Point, K1, K2 or K3 PID registers. If the PID is busy with a calculation the function will wait for module to finish calculation before reading the specified register.
Availability:	All devices with a PID module.
Requires:	Constants are defined in the device's .h file.
Examples:	<code>pid_read(PID_ADDR_Z1, &value_z1);</code>
Example Files:	None
Also See:	setup_pid() , pid_write() , pid_get_result() , pid_busy()

pid_write()

Syntax:	pid_write (register, &input);
Parameters:	<p>register- constant specifying which PID registers to write. The registers that can be written are defined in the device's header file as:</p> <ul style="list-style-type: none"> · PID_ADDR_ACCUMULATOR · PID_ADDR_OUTPUT · PID_ADDR_Z1 · PID_ADDR_Z2 · PID_ADDR_Z3 · PID_ADDR_K1 · PID_ADDR_K2 · PID_ADDR_K3 <p>input -a 16-bit variable, 32-bit variable or structure that contains the data to be written. The size depends on the registers that are being written. Either pass the address of the variable or structure as the parameter, or a pointer to the variable or structure as the parameter.</p>
Returns:	Nothing
Function:	To write a new value for the Accumulator, Output, Z1, Z2, Set Point, K1, K2 or K3 PID registers. If the PID is busy with a calculation the function will wait for module to finish the calculation before writing the specified register.
Availability:	All devices with a PID module.
Requires:	Constants are defined in the device's .h file.
Examples:	<code>pid_write(PID_ADDR_Z1, &value_z1);</code>
Example Files:	None
Also See:	setup_pid() , pid_read() , pid_get_result() , pid_busy()

pll_locked()

Syntax:	result=pll_locked();
Parameters:	None
Returns:	A short int. TRUE if the PLL is locked/ready, FALSE if PLL is not locked/ready
Function:	This function allows testing the PLL Ready Flag bit to determined if the PLL is stable and running.
Availability:	Devices with a Phase Locked Loop (PLL). Not all devices have a PLL Ready Flag, for those devices the pll_locked() function will always return TRUE.
Requires:	Nothing.
Examples:	while(!pll_locked());
Example Files:	None
Also See:	#use delay

port_x_pullups ()

Syntax:	port_a_pullups (value) port_b_pullups (value) port_d_pullups (value) port_e_pullups (value) port_j_pullups (value) port_x_pullups (upmask) port_x_pullups (upmask, downmask)
Parameters:	value is TRUE or FALSE on most parts, some parts that allow pullups to be specified on individual pins permit an 8 bit int here, one bit for each port pin. upmask for ports that permit pullups to be specified on a pin basis. This mask indicates what pins should have pullups activated. A 1 indicates the pullups is on. downmask for ports that permit pulldowns to be specified on a pin

	basis. This mask indicates what pins should have pulldowns activated. A 1 indicates the pulldowns is on.
Returns:	undefined
Function:	Sets the input pullups. TRUE will activate, and a FALSE will deactivate.
Availability:	Only 14 and 16 bit devices (PCM and PCH). (Note: use SETUP_COUNTERS on PCB parts).
Requires:	Nothing
Examples:	<code>port_a_pullups(FALSE);</code>
Example Files:	ex_lcdkb.c , kbd.c
Also See:	input() , input_x() , output_float()

pow() pwr()

Syntax:	f = pow (x,y) f = pwr (x,y)
Parameters:	x and y are of type float
Returns:	A float
Function:	<p>Calculates X to the Y power.</p> <p>Note on error handling: If "errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.</p> <p>Range error occurs in the following case:</p> <ul style="list-style-type: none">• pow: when the argument X is negative
Availability:	All Devices

Requires:	#INCLUDE <math.h>
Examples:	area = pow (size,3.0);
Example Files:	None
Also See:	None

printf()

fprintf()

Syntax:	printf (<i>string</i>) or printf (<i>cstring</i> , <i>values...</i>) or printf (<i>fname</i> , <i>cstring</i> , <i>values...</i>) fprintf (<i>stream</i> , <i>cstring</i> , <i>values...</i>)
Parameters:	<p>String is a constant string or an array of characters null terminated.</p> <p>C String is a constant string. Note that format specifiers cannot be used in RAM strings.</p> <p>Values is a list of variables separated by commas, <i>fname</i> is a function name to be used for outputting (default is <code>putc</code> is none is specified).</p> <p>Stream is a stream identifier (a constant byte).</p>
Returns:	undefined
Function:	<p>Outputs a string of characters to either the standard RS-232 pins (first two forms) or to a specified function. Formatting is in accordance with the string argument. When variables are used this string must be a constant. The % character is used within the string to indicate a variable value is to be formatted and output. Longs in the printf may be 16 or 32 bit. A %% will output a single %. Formatting rules for the % follows.</p> <p>See the Expressions > Constants and Trigraph sections of this manual for other escape character that may be part of the string.</p>

If `fprintf()` is used then the specified stream is used where `printf()` defaults to `STDOUT` (the last USE RS232).

Format:

The format takes the generic form `%nt`. `n` is optional and may be 1-9 to specify how many characters are to be outputted, or 01-09 to indicate leading zeros, or 1.1 to 9.9 for floating point and `%w` output. `t` is the type and may be one of the following:

c	Character
s	String or character
u	Unsigned int
d	Signed int
Lu	Long unsigned int
Ld	Long signed int
x	Hex int (lower case)
X	Hex int (upper case)
Lx	Hex long int (lower case)
LX	Hex long int (upper case)
f	Float with truncated decimal
g	Float with rounded decimal
e	Float in exponential format
w	Unsigned int with decimal place inserted. Specify two numbers for <code>n</code> . The first is a total field width. The second is the desired number of decimal places.

Example formats:

Specifier	Value=0x12	Value=0xfe
%03u	018	254
%u	18	254
%2u	18	*
%5	18	254
%d	18	-2
%x	12	fe
%X	12	FE
%4X	0012	00FE
%3.1w	1.8	25.4

* Result is undefined - Assume garbage.

Availability:

All Devices

Requires:

#USE RS232 (unless `fname` is used)

Examples:

byte `x, y, z;`

```
printf("HiThere");  
printf("RTCCValue=>%2x\n\r",get_rtcc());  
printf("%2u %X %4X\n\r",x,y,z);  
printf(LCD_PUTC, "n=%u",n);
```

Example Files: [ex_admm.c](#), [ex_lcdkb.c](#)

Also See: [atoi\(\)](#), [puts\(\)](#), [putc\(\)](#), [getc\(\)](#) (for a stream example), [RS232 I/O Overview](#)

profileout()

Syntax:	profileout(string); profileout(string, value); profileout(value);
Parameters:	string is any constant string, and value can be any constant or variable integer. Despite the length of string the user specifies here, the code profile run-time will actually only send a one or two byte identifier tag to the code profile tool to keep transmission and execution time to a minimum.
Returns:	Undefined
Function:	<p>Typically the code profiler will log and display function entry and exits, to show the call sequence and profile the execution time of the functions. By using profileout(), the user can add any message or display any variable in the code profile tool. Most messages sent by profileout() are displayed in the 'Data Messages' and 'Call Sequence' screens of the code profile tool.</p> <p>If a profileout(string) is used and the first word of string is "START", the code profile tool will then measure the time it takes until it sees the same profileout(string) where the "START" is replaced with "STOP". This measurement is then displayed in the 'Statistics' screen of the code profile tool, using string as the</p>

	name (without "START" or "STOP")
Availability:	Any device.
Requires:	#use profile() used somewhere in the project source code. // send a simple string. profileout("This is a text string"); // send a variable with a string identifier. profileout("RemoteSensor=", adc); // just send a variable. profileout(adc);
Examples:	// time how long a block of code takes to execute. // this will be displayed in the 'Statistics' of the // Code Profile tool. profileout("start my algorithm"); /* code goes here */ profileout("stop my algorithm");
Example Files:	ex_profile.c
Also See:	#use profile() , #profile , Code Profile overview

psmc_blanking()

Syntax:	psmc_blanking (<i>unit, rising_edge, rise_time, falling_edge, fall_time</i>);
Parameters:	<p><i>unit</i> is the PSMC unit number 1-4</p> <p><i>rising_edge</i> are the events that are ignored after the signal activates.</p> <p><i>rise_time</i> is the time in ticks (0-255) that the above events are ignored.</p> <p><i>falling_edge</i> are the events that are ignored after the signal goes inactive.</p> <p><i>fall_time</i> is the time in ticks (0-255) that the above events are ignored.</p> <p>Events:</p>

- PSMC_EVENT_C1OUT
- PSMC_EVENT_C2OUT
- PSMC_EVENT_C3OUT
- PSMC_EVENT_C4OUT
- PSMC_EVENT_IN_PIN

Returns: undefined

Function:

This function is used when system noise can cause an incorrect trigger from one of the specified events. This function allows for ignoring these events for a period of time around either edge of the signal. See `setup_psmc()` for a definition of a tick.

Pass a 0 or FALSE for the events to disable blanking for an edge.

Availability: All devices equipped with PSMC module.

Requires:

Examples:

Example Files:

None

Also See:

[setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#),
[psmc_modulation\(\)](#),
[psmc_shutdown\(\)](#), [psmc_duty\(\)](#), [psmc_freq_adjust\(\)](#), [psmc_pins\(\)](#)

psmc_deadband()

Syntax: `psmc_deadband(unit, rising_edge, falling_edge);`

Parameters:

unit is the PSMC unit number 1-4

rising_edge is the deadband time in ticks after the signal goes active. If this function is not called, 0 is used.

falling_edge is the deadband time in ticks after the signal goes inactive. If this function is not called, 0 is used.

Returns: undefined

Function: This function sets the deadband time values. Deadbands are a gap in time where both sides of a complementary signal are forced to be inactive. The time values are in ticks. See `setup_psmc()` for a definition of a tick.

Availability: All devices equipped with PSMC module.

Requires: undefined

Examples:

```
// 5 tick deadband when the signal goes active.
psmc_deadband(1, 5, 0);
```

Example Files: None

Also See: [setup_psmc\(\)](#), [psmc_sync\(\)](#), [psmc_blanking\(\)](#), [psmc_modulation\(\)](#), [psmc_shutdown\(\)](#), [psmc_duty\(\)](#), [psmc_freq_adjust\(\)](#), [psmc_pins\(\)](#)

psmc_duty()

Syntax: `psmc_pins(unit, pins_used, pins_active_low);`

Parameters: *unit* is the PSMC unit number 1-4
fall_time is the time in ticks that the signal goes inactive (after the start of the period) assuming the event PSMC_EVENT_TIME has been specified in the setup_psmc().

Returns: Undefined

Function: This function changes the fall time (within the period) for the active signal. This can be used to change the duty of the active pulse. Note that the time is NOT a percentage nor is it the time the signal is active. It is the time from the start of the period that the signal will go inactive. If the rise_time was set to 0, then this time is the total time the signal will be active.

Availability: All devices equipped with PSMC module.

Requires:

Examples:

```
// For a 10khz PWM, based on Fosc divided by 1
// the following sets the duty from
// 0% to 100% baed on the ADC reading
while(TRUE) {
    psmc_duty(1, (read_adc()*(int16)10)/25)*
        (getenv("CLOCK")/1000000));
}
```

Example Files: None

Also See: [setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#), [psmc_blanking\(\)](#), [psmc_modulation\(\)](#), [psmc_shutdown\(\)](#), [psmc_freq_adjust\(\)](#), [psmc_pins\(\)](#)

psmc_freq_adjust()

Syntax: `psmc_freq_adjust(unit, freq_adjust);`

Parameters: *unit* is the PSMC unit number 1-4
freq_adjust is the time in tick/16 increments to add to the period.
The value may be 0-15.

Returns: Undefined

Function: This function adds a fraction of a tick to the period time for some modes of operation.

Availability: All devices equipped with PSMC module.

Requires:

Examples:

Example Files: None

Also See: [setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#), [psmc_blanking\(\)](#), [psmc_modulation\(\)](#), [psmc_shutdown\(\)](#), [psmc_dutyt\(\)](#), [psmc_pins\(\)](#)

psmc_modulation()

Syntax:	<code>psmc_modulation(<i>unit</i>, <i>options</i>);</code>
Parameters:	<p><i>unit</i> is the PSMC unit number 1-4</p> <p><i>Options</i> may be one of the following:</p> <ul style="list-style-type: none">• PSMC_MOD_OFF• PSMC_MOD_ACTIVE• PSMC_MOD_INACTIVE• PSMC_MOD_C1OUT• PSMC_MOD_C2OUT• PSMC_MOD_C3OUT• PSMC_MOD_C4OUT• PSMC_MOD_CCP1• PSMC_MOD_CCP2• PSMC_MOD_IN_PIN <p>The following may be OR'ed with the above</p> <ul style="list-style-type: none">• PSMC_MOD_INVERT• PSMC_MOD_NOT_BDF• PSMC_MOD_NOT_ACE
Returns:	undefined
Function:	<p>This function allows some source to control if the PWM is running or not. The active/inactive are used for software to control the modulation. The other sources are hardware controlled modulation. There are also options to invert the inputs, and to ignore some of the PWM outputs for the purpose of modulation.</p>
Availability:	All devices equipped with PSMC module.
Requires:	
Example Files:	None

Also See: [setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#), [psmc_blanking\(\)](#), [psmc_shutdown\(\)](#), [psmc_duty\(\)](#), [psmc_freq_adjust\(\)](#), [psmc_pins\(\)](#)

psmc_pins()

Syntax: `psmc_pins(unit, pins_used, pins_active_low);`

Parameters:

unit is the PSMC unit number 1-4

used_pins is the any combination of the following or'ed together:

- PSMC_A
- PSMC_B
- PSMC_C
- PSMC_D
- PSMC_E
- PSMC_F
- PSMC_ON_NEXT_PERIOD

If the last constant is used, all the changes made take effect on the next period (as opposed to immediate)

pins_active_low is an optional parameter. When used it lists the same pins from above as the pins that should have an inverted polarity.

Returns: Undefined

Function: This function identified the pins allocated to the PSMC unit, the polarity of those pins and it enables the PSMC unit. The tri-state register for each pin is set to the output state.

Availability: All devices equipped with PSMC module.

Requires:

Examples:

```
// Simple PWM, 10khz out on pin C0 assuming a 20mhz crystal
// Duty is initially set to 25%
setup_psmc(1, PSMC) SINGLE,
    PSMC_EVENT_TIME | PSMC_SOURCE_FOSC, us(100,
    PSMC_EVENT_TIME, 0,
    PSMC_EVENT_TIME, us(25));

psmc_pins(1, PSMC_A);
```

Example Files:

None

Also See:

[setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#), [psmc_blanking\(\)](#),
[psmc_modulation\(\)](#), [psmc_shutdown\(\)](#), [psmc_duty\(\)](#),
[psmc_freq_adjust\(\)](#)

psmc_shutdown()

Syntax:

psmc_shutdown(*unit, options, source, pins_high*);
psmc_shutdown(*unit, command*);

Parameters:

unit is the PSMC unit number 1-4

Options may be one of the following:

- PSMC_SHUTDOWN_OFF
- PSMC_SHUTDOWN_NORMAL
- PSMC_SHUTDOWN_AUTO_RESTART

command may be one of the following:

- PSMC_SHUTDOWN_RESTART
- PSMC_SHUTDOWN_FORCE
- PSMC_SHUTDOWN_CHECK

source may be any of the following or'ed together:

- PSMC_SHUTDOWN_C1OUT
- PSMC_SHUTDOWN_C2OUT
- PSMC_SHUTDOWN_C3OUT
- PSMC_SHUTDOWN_C4OUT
- PSMC_SHUTDOWN_IN_PIN

	<p><i>pins_high</i> is any combination of the following or'ed together:</p> <ul style="list-style-type: none">• PSMC_A• PSMC_B• PSMC_C• PSMC_D• PSMC_E• PSMC_F
Returns:	Non-zero if the unit is now in shutdown.
Function:	<p>This function implements a shutdown capability. when any of the listed events activate the PSMC unit will shutdown and the output pins are driver low unless they are listed in the pins that will be driven high.</p> <p>The auto restart option will restart when the condition goes inactive, otherwise a call with the restart command must be used. Software can force a shutdown with the force command.</p>
Availability:	All devices equipped with PSMC module.
Requires:	
Examples:	
Example Files:	None
Also See:	setup_psmc() , psmc_deadband() , psmc_sync() , psmc_blanking() , psmc_modulation() , psmc_duty() , psmc_freq_adjust() , psmc_pins()

psmc_sync()

Syntax: `psmc_sync(slave_unit, master_unit, options);`

Parameters:

slave_unit is the PSMC unit number 1-4 to be controlled.

master_unit is the PSMC unit number 1-4 to be synchronized to

Options may be:

- PSMC_SOURCE_IS_PHASE
- PSMC_SOURCE_IS_PERIOD
- PSMC_DISCONNECT

The following may be OR'ed with the above:

- PSMC_INVERT_DUTY
- PSMC_INVET_PERIOD

Returns: undefined

Function: This function allows one PSMC unit (the slave) to be synchronized (the outputs) with another PSMC unit (the master).

Availability: All devices equipped with PSMC module.

Requires:

Examples:

Example Files: None

Also See: [setup_psmc\(\)](#), [psmc_deadband\(\)](#), [psmc_sync\(\)](#), [psmc_modulation\(\)](#), [psmc_shutdown\(\)](#), [psmc_duty\(\)](#), [psmc_freq_adjust\(\)](#), [psmc_pins\(\)](#)

psp_output_full()

psp_input_full()

psp_overflow()

Syntax:	<div>result = psp_output_full()</div> <div>result = psp_input_full()</div> <div>result = psp_overflow()</div> <div>result = psp_error();</div> <div>result = psp_timeout();</div> <div>//EPMP only</div> <div>//EPMP only</div>
Parameters:	None
Returns:	A 0 (FALSE) or 1 (TRUE)
Function:	These functions check the Parallel Slave Port (PSP) for the indicated conditions and return TRUE or FALSE.
Availability:	This function is only available on devices with PSP hardware on chips.
Requires:	Nothing
Examples:	<pre>while (psp_output_full()) ; psp_data = command; while(!psp_input_full()) ; if (psp_overflow()) error = TRUE; else data = psp_data;</pre>
Example Files:	ex_psp.c
Also See:	setup_psp() , PSP Overview

putc()

putchar()

fputc()

Syntax:	<div>putc(<i>cdata</i>)</div> <div>putchar(<i>cdata</i>)</div> <div>fputc(<i>cdata</i>, <i>stream</i>)</div>
---------	--

Parameters:	<i>cdata</i> is a 8 bit character. <i>Stream</i> is a stream identifier (a constant byte)
Returns:	undefined
Function:	<p>This function sends a character over the RS232 XMIT pin. A #USE RS232 must appear before this call to determine the baud rate and pin used. The #USE RS232 remains in effect until another is encountered in the file.</p> <p>If fputc() is used then the specified stream is used where putc() defaults to STDOUT (the last USE RS232).</p>
Availability:	All devices
Requires:	#USE RS232
Examples:	<pre>putc('*'); for(i=0; i<10; i++) putc(buffer[i]); putc(13);</pre>
Example Files:	ex_tgetc.c
Also See:	getc() , printf() , #USE RS232 , RS232 I/O Overview

putc_send(); fputc_send();

Syntax:	putc_send(); fputc_send(stream);
Parameters:	stream – parameter specifying the stream defined in #USE RS232.
Returns:	Nothing
Function:	<p>Function used to transmit bytes loaded in transmit buffer over RS232. Depending on the options used in #USE RS232 controls if function is available and how it works.</p> <p>If using hardware UARTx with NOTXISR option it will check if</p>

	<p>currently transmitting. If not transmitting it will then check for data in transmit buffer. If there is data in transmit buffer it will load next byte from transmit buffer into the hardware TX buffer, unless using CTS flow control option. In that case it will first check to see if CTS line is at its active state before loading next byte from transmit buffer into the hardware TX buffer.</p> <p>If using hardware UARTx with TXISR option, function only available if using CTS flow control option, it will test to see if the TBEx interrupt is enabled. If not enabled it will then test for data in transmit buffer to send. If there is data to send it will then test the CTS flow control line and if at its active state it will enable the TBEx interrupt. When using the TXISR mode the TBEx interrupt takes care off moving data from the transmit buffer into the hardware TX buffer.</p> <p>If using software RS232, only useful if using CTS flow control, it will check if there is data in transmit buffer to send. If there is data it will then check the CTS flow control line, and if at its active state it will clock out the next data byte.</p>
Availability:	All devices
Requires:	#USE RS232 #USE_RS232(UART1,BAUD=9600,TRANSMIT_BUFFER=50,NO TXISR)
Examples:	printf("Testing Transmit Buffer"); while(TRUE){ putc_send(); }
Example Files:	None
Also See:	_USE_RS232() , RCV_BUFFER_FULL() , TX_BUFFER_FULL() , TX_BUFFER_BYTES() , GET() , PUTC() RINTF() , SETUP_UART() , PUTC()_SEND

puts()

fputs()

Syntax:	puts (<i>string</i>). fputs (<i>string</i> , <i>stream</i>)
Parameters:	string is a constant string or a character array (null-terminated). Stream is a stream identifier (a constant byte)
Returns:	undefined
Function:	Sends each character in the string out the RS232 pin using putc(). After the string is sent a CARRIAGE-RETURN (13) and LINE-FEED (10) are sent. In general printf() is more useful than puts(). If fputs() is used then the specified stream is used where puts() defaults to STDOUT (the last USE RS232)
Availability:	All devices
Requires:	#USE RS232
Examples:	<pre>puts (" ----- "); puts (" HI "); puts (" ----- ");</pre>
Example Files:	None
Also See:	printf() , gets() , RS232 I/O Overview

pwm_off()

Syntax:	pwm_off ([<i>stream</i>]);
Parameters:	stream – optional parameter specifying the stream defined in #USE PWM.
Returns:	Nothing.
Function:	To turn off the PWM signal.
Availability:	All devices.

Requires:	#USE PWM
Examples:	<pre>#USE PWM(OUTPUT=PIN_C2, FREQUENCY=10kHz, DUTY=25) while(TRUE){ if(kbhit()){ c = getc(); if(c=='F') pwm_off(); } }</pre>
Example Files:	None
Also See:	#use_pwm , pwm_on() , pwm_set_duty_percent() , pwm_set_duty() , pwm_set_frequency()

pwm_on()

Syntax:	pwm_on([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE PWM.
Returns:	Nothing.
Function:	To turn on the PWM signal.
Availability:	All devices.
Requires:	#USE PWM
Examples:	<pre>#USE_PWM(OUTPUT=PIN_C2, FREQUENCY=10kHz, DUTY=25) while (TRUE) { if(kbhit()) { c = getc(); if(c=='O') pwm_on(); } }</pre>
Example Files:	None
Also See:	#use_pwm , pwm_off() , pwm_set_duty_percent() , pwm_set_duty() , pwm_set_frequency()

pwm_set_duty()

Syntax:	pwm_set_duty([stream],duty);
Parameters:	stream – optional parameter specifying the stream defined in #USE PWM. duty – an int16 constant or variable specifying the new PWM high time.
Returns:	Nothing.
Function:	To change the duty cycle of the PWM signal. The duty cycle percentage depends on the period of the PWM signal. This function is faster than pwm_set_duty_percent(), but requires you to know what the period of the PWM signal is.
Availability:	All devices.
Requires:	#USE PWM
Examples:	#USE PWM(OUTPUT=PIN_C2, FREQUENCY=10kHz, DUTY=25)
Example Files:	None
Also See:	#use_pwm , pwm_on() , pwm_off() , pwm_set_frequency() , pwm_set_duty_percent()

pwm_set_duty_percent

Syntax:	pwm_set_duty_percent([stream]), percent
Parameters:	stream – optional parameter specifying the stream defined in #USE PWM. percent - an int16 constant or variable ranging from 0 to 1000 specifying the new PWM duty cycle, D is 0% and 1000 is 100.0%.
Returns:	Nothing.
Function:	To change the duty cycle of the PWM signal. Duty cycle percentage is based off the current frequency/period of the PWM signal.
Availability:	All devices.
Requires:	#USE PWM

Examples:

```
#USE PWM(OUTPUT=PIN_C2, FREQUENCY=10kHz, DUTY=25)
pwm_set_duty_percent(500); //set PWM duty cycle to 50%
```

Example Files:

None

Also See:

[#use_pwm](#), [pwm_on\(\)](#), [pwm_off\(\)](#),
[pwm_set_frequency\(\)](#), [pwm_set_duty\(\)](#)

pwm_set_frequency

Syntax:

pwm_set_frequency([stream],frequency);

Parameters:

stream – optional parameter specifying the stream defined in #USE PWM.

frequency – an int32 constant or variable specifying the new PWM frequency.

Returns:

Nothing.

Function:

To change the frequency of the PWM signal.
 Warning this may change the resolution of the PWM signal.

Availability:

All devices.

Requires:

#USE PWM

Examples:

```
#USE PWM(OUTPUT=PIN_C2, FREQUENCY=10kHz, DUTY=25)
pwm_set_frequency(1000); //set PWM frequency to 1kHz
```

Example Files:

None

Also See:

[#use_pwm](#), [pwm_on\(\)](#), [pwm_off\(\)](#),
[pwm_set_duty_percent](#), [pwm_set_duty\(\)](#)

[pwm1_interrupt_active\(\)](#)
[pwm2_interrupt_active\(\)](#)
[pwm3_interrupt_active\(\)](#)
[pwm4_interrupt_active\(\)](#)
[pwm5_interrupt_active\(\)](#)
[pwm6_interrupt_active\(\)](#)

Syntax:	<pre> result_pwm1_interrupt_active (interrupt) result_pwm2_interrupt_active (interrupt) result_pwm3_interrupt_active (interrupt) result_pwm4_interrupt_active (interrupt) result_pwm5_interrupt_active (interrupt) result_pwm6_interrupt_active (interrupt) </pre>
Parameters:	<p><i>interrupt</i> - 8-bit constant or variable. Constants are defined in the device's header file as:</p> <ul style="list-style-type: none"> • PWM_PERIOD_INTERRUPT • PWM_DUTY_INTERRUPT • PWM_PHASE_INTERRUPT • PWM_OFFSET_INTERRUPT
Returns:	TRUE if interrupt is active. FALSE if interrupt is not active.
Function:	Tests to see if one of the above PWM interrupts is active, interrupt flag is set.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre> if (pwm1_interrupt_active(PWM_PERIOD_INTERRUPT)) clear_pwm1_interrupt(PWM_PERIOD_INTERRUPT); </pre>
Example Files:	
Also See:	setup_pwm() , set_pwm_duty() , set_pwm_phase() , set_pwm_period() , set_pwm_offset() , enable_pwm_interrupt() , clear_pwm_interrupt() , disable_pwm_interrupt()

qei_get_count()

Syntax:	value = qei_get_count([type]);
Parameters:	<p>type - Optional parameter to specify which counter to get, defaults to position counter. Defined in devices .h file as:</p> <p>QEI_GET_POSITION_COUNT QEI_GET_VELOCITY_COUNT</p>
Returns:	The 16-bit value of the position counter or velocity counter.
Function:	Reads the current 16-bit value of the position or velocity counter.
Availability:	Devices that have the QEI module.
Requires:	Nothing.
Examples:	<pre>value = qei_get_counter(QEI_GET_POSITION_COUNT); value = qei_get_counter(); value = qei_get_counter(QEI_GET_VELOCITY_COUNT);</pre>
Example Files:	None
Also See:	setup_qei() , qei_set_count() , qei_status() .

qei_set_count()

Syntax:	qei_set_count(value);
Parameters:	value - The 16-bit value of the position counter.
Returns:	void
Function:	Write a 16-bit value to the position counter.
Availability:	Devices that have the QEI module.
Requires:	Nothing.

Examples:	<code>qei_set_counter(value);</code>
Example Files:	None
Also See:	setup_qei() , qei_get_count() , qei_status() .

qei_status()

Syntax:	<code>status = qei_status();</code>
Parameters:	None
Returns:	The status of the QEI module.
Function:	Returns the status of the QEI module.
Availability:	Devices that have the QEI module.
Requires:	Nothing.
Examples:	<code>status = qei_status();</code>
Example Files:	None
Also See:	setup_qei() , qei_set_count() , qei_get_count() .

qsort()

Syntax:	<code>qsort (base, num, width, compare)</code>
Parameters:	base: Pointer to array of sort data num: Number of elements width: Width of elements compare: Function that compares two elements
Returns:	None

Function:	Performs the shell-metzner sort (not the quick sort algorithm). The contents of the array are sorted into ascending order according to a comparison function pointed to by compare.
Availability:	All devices
Requires:	<code>#INCLUDE <stdlib.h></code>
Examples:	<pre>int nums[5]={ 2,3,1,5,4}; int compar(void *arg1,void *arg2); void main() { qsort (nums, 5, sizeof(int), compar); } int compar(void *arg1,void *arg2) { if (* (int *) arg1 < (* (int *) arg2) return -1 else if (* (int *) arg1 == (* (int *) arg2) return 0 else return 1; }</pre>
Example Files:	ex_qsort.c
Also See:	bsearch()

rand()

Syntax:	<code>re=rand()</code>
Parameters:	None
Returns:	A pseudo-random integer.
Function:	The rand function returns a sequence of pseudo-random integers in the range of 0 to RAND_MAX.

Availability:	All devices
Requires:	#INCLUDE <STDLIB.H>
Examples:	<pre>int I; I=rand();</pre>
Example Files:	None
Also See:	srand()

rcv_buffer_bytes()

Syntax:	value = rcv_buffer_bytes([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE RS232.
Returns:	Number of bytes in receive buffer that still need to be retrieved.
Function:	Function to determine the number of bytes in receive buffer that still need to be retrieved.
Availability:	All devices
Requires:	#USE RS232
Examples:	<pre>#USE_RS232(UART1,BAUD=9600,RECEIVE_BUF FER=100) void main(void) { char c; if(rcv_buffer_bytes() > 10) c = getc(); }</pre>
Example Files:	None

Also See:	_USE_RS232() , RCV_BUFFER_FULL() , TX_BUFFER_FULL() , TX_BUFFER_BYTES() , GETC() , PUTC() , PRINTF() , SETUP_UART() , PUTC_SEND()
------------------	---

rcv_buffer_full()

Syntax:	value = rcv_buffer_full([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE RS232.
Returns:	TRUE if receive buffer is full, FALSE otherwise.
Function:	Function to test if the receive buffer is full.
Availability:	All devices
Requires:	#USE RS232 #USE_RS232(UART1,BAUD=9600,RECEIVE_BUFFER=100)
Examples:	<pre>void main(void) { char c; if(rcv_buffer_full()) c = getc(); }</pre>
Example Files:	None
Also See:	_USE_RS232() , RCV_BUFFER_BYTES() , TX_BUFFER_BYTES() , TX_BUFFER_FULL() , GETC() , PUTC() , PRINTF() , SETUP_UART() , PUTC_SEND()

read_adc()

Syntax:	value = read_adc ([mode])
Parameters:	mode is an optional parameter. If used the values may be: ADC_START_AND_READ (continually takes readings, this is the default) ADC_START_ONLY (starts the conversion and returns) ADC_READ_ONLY (reads last conversion result)

Returns:	Either a 8 or 16 bit int depending on #DEVICE ADC= directive.																														
Function:	<div><p>This function will read the digital value from the analog to digital converter. Calls to setup_adc(), setup_adc_ports() and set_adc_channel() should be made sometime before this function is called. The range of the return value depends on number of bits in the chips A/D converter and the setting in the #DEVICE ADC= directive as follows:</p><table><tr><th>#DEVICE</th><th>8 bit</th><th>10 bit</th><th>11 bit</th><th>12 bit</th><th>16 bit</th></tr><tr><td>ADC=8</td><td>00-FF</td><td>00-FF</td><td>00-FF</td><td>00-FF</td><td>00-FF</td></tr><tr><td>ADC=10</td><td>x</td><td>0-3FF</td><td>x</td><td>0-3FF</td><td>x</td></tr><tr><td>ADC=11</td><td>x</td><td>x</td><td>0-7FF</td><td>x</td><td>x</td></tr><tr><td>ADC=16</td><td>0FF-00</td><td>0-FFC0</td><td>0-FFEO</td><td>0-FFF0</td><td>0-FFFF</td></tr></table><p>Note: x is not defined</p></div>	#DEVICE	8 bit	10 bit	11 bit	12 bit	16 bit	ADC=8	00-FF	00-FF	00-FF	00-FF	00-FF	ADC=10	x	0-3FF	x	0-3FF	x	ADC=11	x	x	0-7FF	x	x	ADC=16	0FF-00	0-FFC0	0-FFEO	0-FFF0	0-FFFF
#DEVICE	8 bit	10 bit	11 bit	12 bit	16 bit																										
ADC=8	00-FF	00-FF	00-FF	00-FF	00-FF																										
ADC=10	x	0-3FF	x	0-3FF	x																										
ADC=11	x	x	0-7FF	x	x																										
ADC=16	0FF-00	0-FFC0	0-FFEO	0-FFF0	0-FFFF																										
Availability:	This function is only available on devices with A/D hardware.																														
Requires:	Pin constants are defined in the devices .h file.																														
Examples:	<pre>setup_adc(ADC_CLOCK_INTERNAL); setup_adc_ports(ALL_ANALOG); set_adc_channel(1); while (input(PIN_B0)) { delay_ms(5000); value = read_adc(); printf("A/D value = %2x\n\r", value); } read_adc(ADC_START_ONLY); sleep(); value=read_adc(ADC_READ_ONLY);</pre>																														
Example Files:	ex_admm.c , ex_14kad.c																														
Also See:	setup_adc() , set_adc_channel() , setup_adc_ports() , #DEVICE , ADC Overview																														

read_bank()

Syntax:	value = read_bank (bank, offset)
Parameters:	bank is the physical RAM bank 1-3 (depending on the device) offset is the offset into user RAM for that bank (starts at 0),
Returns:	8 bit int
Function:	Read a data byte from the user RAM area of the specified memory bank. This function may be used on some devices where full RAM access by auto variables is not efficient. For example, setting the pointer size to 5 bits on the PIC16C57 chip will generate the most efficient ROM code. However, auto variables can not be above 1Fh. Instead of going to 8 bit pointers, you can save ROM by using this function to read from the hard-to-reach banks. In this case, the bank may be 1-3 and the offset may be 0-15.
Availability:	All devices but only useful on PCB parts with memory over 1Fh and PCM parts with memory over FFh.
Requires:	Nothing
Examples:	<pre>// See write_bank() example to see // how we got the data // Moves data from buffer to LCD i=0; do { c=read_bank(1,i++); if(c!=0x13) lcd_putc(c); } while (c!=0x13);</pre>
Example Files:	ex_psp.c
Also See:	write_bank() , and the "Common Questions and Answers" section for more information.

read_calibration()

Syntax:	value = read_calibration (n)
Parameters:	n is an offset into calibration memory beginning at 0
Returns:	An 8 bit byte
Function:	The read_calibration function reads location "n" of the 14000-calibration memory.
Availability:	This function is only available on the PIC14000.
Requires:	Nothing
Examples:	fin = read_calibration(16);
Example Files:	ex_14kad.c with 14kcal.c
Also See:	None

read_configuration_memory()

Syntax:	read_configuration_memory([offset], ramPtr, n)
Parameters:	ramPtr is the destination pointer for the read results count is an 8 bit integer offset is an optional parameter specifying the offset into configuration memory to start reading from, offset defaults to zero if not used.
Returns:	undefined
Function:	For PIC18-Reads n bytes of configuration memory and saves the values to ramPtr . For Enhanced16 devices function reads User ID, Device ID and configuration memory regions.
Availability:	All PIC18 Flash and Enhanced16 devices

Requires:	Nothing
Examples:	<pre>int data[6]; read_configuration_memory(data,6);</pre>
Example Files:	None
Also See:	write_configuration_memory() , read_program_memory() , Configuration Memory Overview .

read_eeprom()

value = read_eeprom (address)

Syntax:

Parameters:	address is an 8 bit or 16 bit int depending on the part
Returns:	An 8 bit int
Function:	Reads a byte from the specified data EEPROM address. The address begins at 0 and the range depends on the part.
Availability:	This command is only for parts with built-in EEPROMS
Requires:	Nothing
Examples:	<pre>#define LAST_VOLUME 10 volume = read_EEPROM (LAST_VOLUME);</pre>
Example Files:	None
Also See:	write_eeprom() , Data Eeprom Overview

read_extended_ram()

Syntax:	<code>read_extended_ram(page,address,data,count);</code>
Parameters:	<p>page – the page in extended RAM to read from</p> <p>address – the address on the selected page to start reading from</p> <p>data – pointer to the variable to return the data to</p> <p>count – the number of bytes to read (0-32768)</p>
Returns:	Undefined
Function:	To read data from the extended RAM of the PIC.
Availability:	On devices with more then 30K of RAM.
Requires:	Nothing
Examples:	<pre>unsigned int8 data[8]; read_extended_ram(1,0x0000,data,8);</pre>
Example Files:	None
Also See:	read_extended_ram() , Extended RAM Overview

read_program_memory() read_external_memory()

Syntax:	<code>READ_PROGRAM_MEMORY (address, dataptr, count);</code> <code>READ_EXTERNAL_MEMORY (address, dataptr, count);</code>
Parameters:	<p>address is 16 bits on PCM parts and 32 bits on PCH parts . The least significant bit should always be 0 in PCM.</p> <p>dataptr is a pointer to one or more bytes.</p> <p>count is a 8 bit integer on PIC16 and 16-bit for PIC18</p>
Returns:	undefined

Function:	Reads count bytes from program memory at address to RAM at dataptr . Both of these functions operate exactly the same.
Availability:	Only devices that allow reads from program memory.
Requires:	Nothing
Examples:	<pre>char buffer[64]; read_external_memory(0x40000, buffer, 64);</pre>
Example Files:	None
Also See:	write_program_memory() , External memory overview , Program Eeprom Overview

read_program_eeprom()

Syntax:	value = read_program_eeprom (address)
Parameters:	address is 16 bits on PCM parts and 32 bits on PCH parts
Returns:	16 bits
Function:	Reads data from the program memory.
Availability:	Only devices that allow reads from program memory.
Requires:	Nothing
Examples:	<pre>checksum = 0; for(i=0;i<8196;i++) checksum^=read_program_eeprom(i); printf("Checksum is %2X\r\n",checksum);</pre>
Example Files:	None
Also See:	write_program_eeprom() , write_eeprom() , read_eeprom() , Program Eeprom Overview

read_rom_memory()

Syntax:	READ_ROM_MEMORY (<i>address</i> , <i>dataptr</i> , <i>count</i>);
Parameters:	<i>address</i> is 32 bits. The least significant bit should always be 0. <i>dataptr</i> is a pointer to one or more bytes. <i>count</i> is a 16 bit integer
Returns:	undefined
Function:	Reads <i>count</i> bytes from program memory at <i>address</i> to <i>dataptr</i> . Due to the 24 bit program instruction size on the PCD devices, three bytes are read from each address location.
Availability:	Only devices that allow reads from program memory.
Requires:	Nothing
Examples:	<pre>char buffer[64]; read_program_memory(0x40000, buffer, 64);</pre>
Example Files:	None
Also See:	write_program_eeprom() , write_eeprom() , read_eeprom() , Program eeprom overview

read_sd_adc()

Syntax:	value = read_sd_adc();
Parameters:	None
Returns:	A signed 32 bit int.
Function:	To poll the SDRDY bit and if set return the signed 32 bit value stored in the SD1RESH and SD1RESL registers, and clear the

	SDRDY bit. The result returned depends on settings made with the <code>setup_sd_adc()</code> function, but will always be a signed int32 value with the most significant bits being meaningful. Refer to Section 66, 16-bit Sigma-Delta A/D Converter, of the PIC24F Family Reference Manual for more information on the module and the result format.
Availability:	Only devices with a Sigma-Delta Analog to Digital Converter (SD ADC) module.
Examples:	<code>value = read_sd_adc()</code>
Example Files:	None
Also See:	setup_sd_adc() , set_sd_adc_calibration() , set_sd_adc_channel()

realloc()

Syntax:	realloc (<i>ptr</i> , <i>size</i>)
Parameters:	<i>ptr</i> is a null pointer or a pointer previously returned by <code>calloc</code> or <code>malloc</code> or <code>realloc</code> function, <i>size</i> is an integer representing the number of bytes to be allocated.
Returns:	A pointer to the possibly moved allocated memory, if any. Returns null otherwise.
Function:	The <code>realloc</code> function changes the size of the object pointed to by the <i>ptr</i> to the size specified by the <i>size</i> . The contents of the object shall be unchanged up to the lesser of new and old sizes. If the new size is larger, the value of the newly allocated space is indeterminate. If <i>ptr</i> is a null pointer, the <code>realloc</code> function behaves like <code>malloc</code> function for the specified size. If the <i>ptr</i> does not match a pointer earlier returned by the <code>calloc</code> , <code>malloc</code> or <code>realloc</code> , or if the space has been deallocated by a call to <code>free</code> or <code>realloc</code> function, the behavior is undefined. If the space cannot be allocated, the object pointed to by <i>ptr</i> is unchanged. If <i>size</i> is zero and the <i>ptr</i> is not a null pointer, the object is to be freed.
Availability:	All devices
Requires:	<code>#INCLUDE <stdlib.h></code>

Examples:	<pre>int * iptr; iptr=malloc(10); realloc(iptr,20) // iptr will point to a block of memory of 20 bytes, if available.</pre>
Example Files:	None
Also See:	malloc() , free() , calloc()

release_io()

Syntax:	release_io();
Parameters:	none
Returns:	nothing
Function:	The function releases the I/O pins after the device wakes up from deep sleep, allowing the state of the I/O pins to change
Availability:	Devices with a deep sleep module.
Requires:	Nothing
Examples:	<pre>unsigned int16 restart; restart = restart_cause(); if(restart == RTC_FROM_DS) release_io();</pre>
Example Files:	None
Also See:	sleep()

reset_cpu()

Syntax:	reset_cpu()
Parameters:	None
Returns:	This function never returns
Function:	This is a general purpose device reset. It will jump to location 0 on PCB and PCM parts and also reset the registers to power-up state on the PIC18XXX.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>if (checksum!=0) reset_cpu();</pre>
Example Files:	None
Also See:	None

restart_cause()

Syntax:	value = restart_cause()
Parameters:	None
Returns:	A value indicating the cause of the last processor reset. The actual values are device dependent. See the device .h file for specific values for a specific device. Some example values are: WDT_FROM_SLEEP, WDT_TIMEOUT, MCLR_FROM_SLEEP and NORMAL_POWER_UP.
Function:	Returns the cause of the last processor reset.
Availability:	All devices
Requires:	Constants are defined in the devices .h file.

Examples:

```
switch ( restart_cause() ) {
    case WDT_FROM_SLEEP:
    case WDT_TIMEOUT:
        handle_error();
}
```

Example Files:

[ex_wdt.c](#)

Also See:

[restart_wdt\(\)](#), [reset_cpu\(\)](#)

restart_wdt()

Syntax:

restart_wdt()

Parameters:

None

Returns:

undefined

Function:

Restarts the watchdog timer. If the watchdog timer is enabled, this must be called periodically to prevent the processor from resetting.

The watchdog timer is used to cause a hardware reset if the software appears to be stuck.

The timer must be enabled, the timeout time set and software must periodically restart the timer. These are done differently on the PCB/PCM and PCH parts as follows:

	PCB/PCM	PCH
Enable/Disable	#fuses	setup_wdt()
Timeout time	setup_wdt()	#fuses
restart	restart_wdt()	restart_wdt()

Availability:

All devices

Requires:

#FUSES

Examples:

```
#fuses WDT // PCB/PCM example
// See setup_wdt for a
```

```
// PIC18 example
main() {
    setup_wdt(WDT_2304MS);
    while (TRUE) {
        restart_wdt();
        perform_activity();
    }
}
```

Example Files:	ex_wdt.c
Also See:	#FUSES , setup_wdt() , WDT or Watch Dog Timer Overview

rotate_left()

Syntax:	rotate_left (<i>address</i> , <i>bytes</i>)
Parameters:	address is a pointer to memory bytes is a count of the number of bytes to work with.
Returns:	undefined
Function:	Rotates a bit through an array or structure. The address may be an array identifier or an address to a byte or structure (such as &data). Bit 0 of the lowest BYTE in RAM is considered the LSB.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>x = 0x86; rotate_left(&x, 1); // x is now 0x0d</pre>
Example Files:	None
Also See:	rotate_right() , shift_left() , shift_right()

rotate_right()

Syntax:	rotate_right (address, bytes)
Parameters:	address is a pointer to memory, bytes is a count of the number of bytes to work with.
Returns:	undefined
Function:	Rotates a bit through an array or structure. The address may be an array identifier or an address to a byte or structure (such as &data). Bit 0 of the lowest BYTE in RAM is considered the LSB.
Availability:	All devices
Requires:	Nothing
Examples:	<pre> struct { int cell_1 : 4; int cell_2 : 4; int cell_3 : 4; int cell_4 : 4; } cells; rotate_right(&cells, 2); rotate_right(&cells, 2); rotate_right(&cells, 2); rotate_right(&cells, 2); // cell_1->4, 2->1, 3->2 and 4-> 3 </pre>
Example Files:	None
Also See:	rotate_left() , shift_left() , shift_right()

rtc_alarm_read()

Syntax:	rtc_alarm_read(&datetime);
Parameters:	datetime - A structure that will contain the values to be written to the alarm in the RTCC module. Structure used in read and write functions are defined in the

	device header file as <code>rtc_time_t</code>
Returns:	void
Function:	Reads the date and time from the alarm in the RTCC module to structure <i>datetime</i> .
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<code>rtc_alarm_read(&datetime);</code>
Example Files:	None
Also See:	rtc_read() , rtc_alarm_read() , rtc_alarm_write() , setup_rtc_alarm() , rtc_write() , setup_rtc()

rtc_alarm_write()

Syntax:	<code>rtc_alarm_write(&datetime);</code>
Parameters:	<i>datetime</i> - A structure that will contain the values to be written to the alarm in the RTCC module. Structure used in read and write functions are defined in the device header file as <code>rtc_time_t</code> .
Returns:	void
Function:	Writes the date and time to the alarm in the RTCC module as specified in the structure date time.
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<code>rtc_alarm_write(&datetime);</code>
Example Files:	None

Also See: [rtc_read\(\)](#), [rtc_alarm_read\(\)](#), [rtc_alarm_write\(\)](#), [setup_rtc_alarm\(\)](#), [rtc_write\(\)](#), [setup_rtc\(\)](#)

rtc_read()

Syntax:	<code>rtc_read(&datetime);</code>
Parameters:	<p><i>datetime</i>- A structure that will contain the values returned by the RTCC module.</p> <p>Structure used in read and write functions are defined in the device header file as <code>rtc_time_t</code>.</p>
Returns:	void
Function:	Reads the current value of Time and Date from the RTCC module and stores the structure date time.
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<code>rtc_read(&datetime);</code>
Example Files:	ex_rtcc.c
Also See:	rtc_read() , rtc_alarm_read() , rtc_alarm_write() , setup_rtc_alarm() , rtc_write() , setup_rtc()

rtc_write()

Syntax:	<code>rtc_write(&datetime);</code>
Parameters:	<p><i>datetime</i>- A structure that will contain the values to be written to the RTCC module.</p> <p>Structure used in read and write functions are defined in the device header file as <code>rtc_time_t</code>.</p>

Returns:	void
Function:	Writes the date and time to the RTCC module as specified in the structure date time.
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<code>rtc_write(&datetime);</code>
Example Files:	ex_rtcc.c
Also See:	rtc_read() , rtc_alarm_read() , rtc_alarm_write() , setup_rtc_alarm() , rtc_write() , setup_rtc()

rtos_await()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_await (<i>expre</i>)
Parameters:	<i>expre</i> is a logical expression.
Returns:	None
Function:	This function can only be used in an RTOS task. This function waits for <i>expre</i> to be true before continuing execution of the rest of the code of the RTOS task. This function allows other tasks to execute while the task waits for <i>expre</i> to be true.
Availability:	All devices
Requires:	#USE RTOS
Examples:	<code>rtos_await(kbhit());</code>
Also See:	None

rtos_disable()

The RTOS is only included in the PCW, PCWH, and PCWHD software packages.

Syntax:	rtos_disable (<i>task</i>)
Parameters:	<i>task</i> is the identifier of a function that is being used as an RTOS task.
Returns:	None
Function:	This function disables a task which causes the task to not execute until enabled by rtos_enable(). All tasks are enabled by default.
Availability:	All devices
Requires:	#USE RTOS
Examples:	rtos_disable(toggle_green)
Also See:	rtos_enable()

rtos_enable()

The RTOS is only included in the PCW, PCWH, and PCWHD software packages.

Syntax:	rtos_enable (<i>task</i>)
Parameters:	<i>task</i> is the identifier of a function that is being used as an RTOS task.
Returns:	None
Function:	This function enables a task to execute at it's specified rate.
Availability:	All devices
Requires:	#USE RTOS

Examples:	<code>rtos_enable(toggle_green);</code>
Also See:	rtos_disable()

rtos_msg_poll()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	<code>i = rtos_msg_poll()</code>
Parameters:	None
Returns:	An integer that specifies how many messages are in the queue.
Function:	This function can only be used inside an RTOS task. This function returns the number of messages that are in the queue for the task that the <code>rtos_msg_poll()</code> function is used in.
Availability:	All devices
Requires:	<code>#USE RTOS</code>
Examples:	<code>if(rtos_msg_poll())</code>
Also See:	<code>rtos msg send()</code> , <code>rtos msg read()</code>

rtos_overrun()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	<code>rtos_overrun([task])</code>
Parameters:	<i>task</i> is an optional parameter that is the identifier of a function that is being used as an RTOS task
Returns:	A 0 (FALSE) or 1 (TRUE)

Function:	This function returns TRUE if the specified task took more time to execute than it was allocated. If no task was specified, then it returns TRUE if any task ran over it's allotted execution time.
Availability:	All devices
Requires:	#USE RTOS(statistics)
Examples:	<code>rtos_overshoot()</code>
Also See:	None

rtos_run()

The RTOS is only included in the PCW, PCWH, and PCWHD software packages.

Syntax:	rtos_run()
Parameters:	None
Returns:	None
Function:	This function begins the execution of all enabled RTOS tasks. This function controls the execution of the RTOS tasks at the allocated rate for each task. This function will return only when <code>rtos_terminate()</code> is called.
Availability:	All devices
Requires:	#USE RTOS
Examples:	<code>rtos_run()</code>
Also See:	rtos_terminate()

rtos_signal()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_signal (<i>sem</i>)
Parameters:	sem is a global variable that represents the current availability of a shared system resource (a semaphore).
Returns:	None
Function:	This function can only be used by an RTOS task. This function increments sem to let waiting tasks know that a shared resource is available for use.
Availability:	All devices
Requires:	#USE RTOS
Examples:	<code>rtos_signal(uart_use)</code>
Also See:	rtos_wait()

rtos_stats()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_stats (<i>task</i> ,& <i>stat</i>)
Parameters:	task is the identifier of a function that is being used as an RTOS task. stat is a structure containing the following: struct rtos_stas_struct { unsigned int32 task_total_ticks; //number of ticks the task has //used

	<pre> unsigned int16 task_min_ticks; //the minimum number of ticks //used unsigned int16 task_max_ticks; //the maximum number of ticks //used unsigned int16 hns_per_tick; //us = (ticks*hns_per_tick)/10 }; Returns: Undefined</pre>
Function:	This function returns the statistic data for a specified <i>task</i> .
Availability:	All devices
Requires:	#USE RTOS(statistics)
Examples:	<code>rtos_stats(echo, &stats)</code>
Also See:	None

rtos_terminate()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_terminate()
Parameters:	None
Returns:	None
Function:	This function ends the execution of all RTOS tasks. The execution of the program will continue with the first line of code after the <code>rtos_run()</code> call in the program. (This function causes <code>rtos_run()</code> to return.)
Availability:	All devices
Requires:	#USE RTOS

Examples:	<code>rtos_terminate()</code>
Also See:	rtos_run()

rtos_wait()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_wait (sem)
Parameters:	sem is a global variable that represents the current availability of a shared system resource (a semaphore).
Returns:	None
Function:	This function can only be used by an RTOS task. This function waits for sem to be greater than 0 (shared resource is available), then decrements sem to claim usage of the shared resource and continues the execution of the rest of the code the RTOS task. This function allows other tasks to execute while the task waits for the shared resource to be available.
Availability:	All devices
Requires:	#USE RTOS
Examples:	<code>rtos_wait (uart_use)</code>
Also See:	rtos signal()

rtos_yield()

The RTOS is only included in the PCW, PCWH and PCWHD software packages.

Syntax:	rtos_yield()
Parameters:	None
Returns:	None
Function:	This function can only be used in an RTOS task. This function stops the execution of the current task and returns control of the processor to rtos_run(). When the next task executes, it will start it's execution on the line of code after the rtos_yield().
Availability:	All devices
Requires:	#USE RTOS
Examples:	<pre>void yield(void) { printf("Yielding...\r\n"); rtos_yield(); printf("Executing code after yield\r\n"); }</pre>
Also See:	None

set_adc_channel()

Syntax:	set_adc_channel (chan [,neg]))
Parameters:	<p>chan is the channel number to select. Channel numbers start at 0 and are labeled in the data sheet AN0, AN1. For devices with a differential ADC it sets the positive channel to use.</p> <p>neg is optional and is used for devices with a differential ADC only. It sets the negative channel to use, channel numbers can be 0 to 6</p>

	or VSS. If no parameter is used the negative channel will be set to VSS by default.
Returns:	undefined
Function:	Specifies the channel to use for the next read_adc() call. Be aware that you must wait a short time after changing the channel before you can get a valid read. The time varies depending on the impedance of the input source. In general 10us is good for most applications. You need not change the channel before every read if the channel does not change.
Availability:	This function is only available on devices with A/D hardware.
Requires:	Nothing
Examples:	<pre>set_adc_channel(2); delay_us(10); value = read_adc();</pre>
Example Files:	ex_admm.c
Also See:	read_adc() , setup_adc() , setup_adc_ports() , ADC Overview

set_adc_trigger()

Syntax:	set_adc_trigger (trigger)
Parameters:	<p><i>trigger</i> - ADC trigger source. Constants defined in device's header, see the device's .h file for all options. Some typical options include:</p> <ul style="list-style-type: none">• ADC_TRIGGER_DISABLED• ADC_TRIGGER_ADACT_PIN• ADC_TRIGGER_TIMER1• ADC_TRIGGER_CCP1
Returns:	undefined
Function:	Sets the Auto-Conversion trigger source for the Analog-to-Digital Converter with Computation (ADC2) Module.

Availability:	All devices with an ADC2 Module
Requires:	Constants defined in the device's .h file
Examples:	<code>set_adc_trigger(ADC_TRIGGER_TIMER1);</code>
Also See:	ADC Overview , setup_adc() , setup_adc_ports() , set_adc_channel() , read_adc() , #DEVICE , adc_read() , adc_write() , adc_status()

set_analog_pins()

Syntax:	set_analog_pins (pin, pin, pin, ...)
Parameters:	<p>pin - pin to set as an analog pin. Pins are defined in the device's .h file. The actual value is a bit address. For example, bit 3 of port A at address 5, would have a value of $5*8+3$ or 43. This is defined as follows:</p> <pre>#define PIN_A3 43</pre>
Returns:	undefined
Function:	<p>To set which pins are analog and digital. Usage of function depends on method device has for setting pins to analog or digital. For devices with ANSELx, x being the port letter, registers the function is used as described above. For all other devices the function works the same as <code>setup_adc_ports()</code> function.</p> <p>Refer to the setup_adc_ports() page for documentation on how to use.</p>
Availability:	On all devices with an Analog to Digital Converter
Requires:	Nothing
Examples:	<code>set_analog_pins(PIN_A0, PIN_A1, PIN_E1, PIN_B0, PIN_B5);</code>
Example Files:	
Also See:	setup_adc_reference() , set_adc_channel() , read_adc() , setup_adc() , setup_adc_ports() , ADC Overview

scanf()

Syntax:	<code>scanf(cstring);</code> <code>scanf(cstring, values...)</code> <code>fscanf(stream, cstring, values...)</code>				
Parameters:	<p>cstring is a constant string.</p> <p>values is a list of variables separated by commas.</p> <p>stream is a stream identifier.</p>				
Returns:	0 if a failure occurred, otherwise it returns the number of conversion specifiers that were read in, plus the number of constant strings read in.				
Function:	<p>Reads in a string of characters from the standard RS-232 pins and formats the string according to the format specifiers. The format specifier character (%) used within the string indicates that a conversion specification is to be done and the value is to be saved into the corresponding argument variable. A %% will input a single %. Formatting rules for the format specifier as follows:</p> <p>If fscanf() is used, then the specified stream is used, where scanf() defaults to STDIN (the last USE RS232).</p> <p>Format: The format takes the generic form %nt. n is an option and may be 1-99 specifying the field width, the number of characters to be inputted. t is the type and maybe one of the following:</p> <table><tr><td>c</td><td>Matches a sequence of characters of the number specified by the field width (1 if no field width is specified). The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence.</td></tr><tr><td>s</td><td>Matches a sequence of non-white space characters. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a</td></tr></table>	c	Matches a sequence of characters of the number specified by the field width (1 if no field width is specified). The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence.	s	Matches a sequence of non-white space characters. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a
c	Matches a sequence of characters of the number specified by the field width (1 if no field width is specified). The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence.				
s	Matches a sequence of non-white space characters. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a				

	terminating null character, which will be added automatically.
u	Matches an unsigned decimal integer. The corresponding argument shall be a pointer to an unsigned integer.
Lu	Matches a long unsigned decimal integer. The corresponding argument shall be a pointer to a long unsigned integer.
d	Matches a signed decimal integer. The corresponding argument shall be a pointer to a signed integer.
Ld	Matches a long signed decimal integer. The corresponding argument shall be a pointer to a long signed integer.
o	Matches a signed or unsigned octal integer. The corresponding argument shall be a pointer to a signed or unsigned integer.
Lo	Matches a long signed or unsigned octal integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
x or X	Matches a hexadecimal integer. The corresponding argument shall be a pointer to a signed or unsigned integer.
Lx or LX	Matches a long hexadecimal integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
i	Matches a signed or unsigned integer. The corresponding argument shall be a pointer to a signed or unsigned integer.
Li	Matches a long signed or unsigned integer. The corresponding argument shall be a pointer to a long signed or unsigned integer.
f,g or e	Matches a floating point number in decimal or exponential format. The corresponding

argument shall be a pointer to a float.

[Matches a non-empty sequence of characters from a set of expected characters. The sequence of characters included in the set are made up of all character following the left bracket ([) up to the matching right bracket (]). Unless the first character after the left bracket is a ^, in which case the set of characters contain all characters that do not appear between the brackets. If a - character is in the set and is not the first or second, where the first is a ^, nor the last character, then the set includes all characters from the character before the - to the character after the -.

For example, %[a-z] would include all characters from **a** to **z** in the set and %[^a-z] would exclude all characters from **a** to **z** from the set. The corresponding argument shall be a pointer to the initial character of an array long enough to accept the sequence and a terminating null character, which will be added automatically.

n Assigns the number of characters read thus far by the call to scanf() to the corresponding argument. The corresponding argument shall be a pointer to an unsigned integer.

An optional assignment-suppressing character (*) can be used after the format specifier to indicate that the conversion specification is to be done, but not saved into a corresponding variable. In this case, no corresponding argument variable should be passed to the scanf() function.

A string composed of ordinary non-white space characters is executed by reading the next character of the string. If one of the inputted characters differs from the string, the function fails and exits. If a white-space character precedes the ordinary non-white space characters, then white-space characters are first read in until a non-white space character is read.

White-space characters are skipped, except for the

	conversion specifiers [, c or n , unless a white-space character precedes the [or c specifiers.
Availability:	All Devices
Requires:	#USE RS232
Examples:	<pre>char name[2-]; unsigned int8 number; signed int32 time; if (scanf("%u%s%ld", &number, name, &time)) printf("\r\nName: %s, Number: %u, Time: %ld", name, number, time);</pre>
Example Files:	None
Also See:	RS232 I/O Overview , getc() , putc() , printf()

set_cog_blanking()

Syntax:	set_cog_blanking(falling_time, rising_time);
Parameters:	falling time - sets the falling edge blanking time. rising time - sets the rising edge blanking time.
Returns:	Nothing
Function:	To set the falling and rising edge blanking times on the Complementary Output Generator (COG) module. The time is based off the source clock of the COG module, the times are either a 4-bit or 6-bit value, depending on the device, refer to the device's datasheet for the correct width.
Availability:	All devices with a COG module.
Examples:	<pre>set_cog_blanking(10,10);</pre>
Example Files:	None

Also See:	setup_cog() , set_cog_phase() , set_cog_dead_band() , cog_status() , cog_restart()
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set_cog_dead_band()

Syntax:	set_cog_dead_band(falling_time, rising_time);
Parameters:	falling time - sets the falling edge dead-band time. rising time - sets the rising edge dead-band time.
Returns:	Nothing
Function:	To set the falling and rising edge dead-band times on the Complementary Output Generator (COG) module. The time is based off the source clock of the COG module, the times are either a 4-bit or 6-bit value, depending on the device, refer to the device's datasheet for the correct width.
Availability:	All devices with a COG module.
Examples:	<code>set_cog_dead_band(16,32);</code>
Example Files:	None
Also See:	setup_cog() , set_cog_phase() , set_cog_blanking() , cog_status() , cog_restart()

set_cog_phase()

Syntax:	<code>set_cog_phase(rising_time);</code> <code>set_cog_phase(falling_time, rising_time);</code>
Parameters:	falling time - sets the falling edge phase time. rising time - sets the rising edge phase time.
Returns:	Nothing
Function:	To set the falling and rising edge phase times on the Complementary Output Generator (COG) module. The time is based off the source clock of the COG module, the times are either a 4-bit or 6-bit value, depending on the device. Some devices only have a rising edge delay, refer to the device's datasheet.
Availability:	All devices with a COG module.
Examples:	<code>set_cog_phase(10,10);</code>
Example Files:	None
Also See:	setup_cog() , set_cog_dead_band() , set_cog_blanking() , cog_status() , cog_restart()

set_compare_time()

Syntax:	<code>set_compare_time(x, ocr, [ocrs])</code>
Parameters:	x is 1-16 and defines which output compare module to set time for ocr is the compare time for the primary compare register. ocrs is the optional compare time for the secondary register. Used for dual compare mode.

Returns:	None
Function:	This function sets the compare value for the output compare module. If the output compare module is to perform only a single compare than the ocrs register is not used. If the output compare module is using double compare to generate an output pulse, the ocr signifies the start of the pulse and ocrs defines the pulse termination time.
Availability:	Only available on devices with output compare modules.
Requires:	Nothing
Examples:	<pre>// Pin OC1 will be set when timer 2 is equal to 0xF000 setup_timer2(TMR_INTERNAL TIMER_DIV_BY_8); setup_compare_time(1, 0xF000); setup_compare(1, COMPARE_SET_ON_MATCH COMPARE_TIMER2);</pre>
Example Files:	None
Also See:	get_capture(), setup_compare(), Output Compare, PWM Overview

set_dedicated_adc_channel()

Syntax:	set_dedicated_adc_channel (core,channel, [differential]);
Parameters:	<p>core - the dedicated ADC core to setup</p> <p>channel - the channel assigned to the specified ADC core. Channels are defined in the device's .h file as follows:</p> <ul style="list-style-type: none">• ADC_CHANNEL_AN0• ADC_CHANNEL_AN7• ADC_CHANNEL_PGA1• ADC_CHANNEL_AN0ALT• ADC_CHANNEL_AN1• ADC_CHANNEL_AN18• ADC_CHANNEL_PGA2• ADC_CHANNEL_AN1ALT

- ADC_CHANNEL_AN2
- ADC_CHANNEL_AN11
- ADC_CHANNEL_VREF_BAND_GAP
- ADC_CHANNEL_AN3
- ADC_CHANNEL_AN15

Not all of the above defines can be used with all the dedicated ADC cores. Refer to the device's header for which can be used with each dedicated ADC core.

differential - optional parameter to specify if channel is differential or single-ended. TRUE is differential and FALSE is single-ended.

Returns:	Undefined
Function:	Sets the channel that will be assigned to the specified dedicated ADC core. Function does not set the channel that will be read with the next call to read_adc(), use set_adc_channel() or read_adc() functions to set the channel that will be read.
Availability:	On the dsPIC33EPxxGSxxx family of devices.
Requires:	Nothing.
Examples:	setup_dedicated_adc_channel(0,ADC_CHANNEL_AN0);
Example Files:	None
Also See:	setup_adc() , setup_adc_ports() , set_adc_channel() , read_adc() , adc_done() , setup_dedicated_adc() , ADC Overview

set_input_level_x()

Syntax:	<code>set_input_level_a(value)</code> <code>set_input_level_b(value)</code> <code>set_input_level_v(value)</code> <code>set_input_level_d(value)</code> <code>set_input_level_e(value)</code>
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	set_input_level_f(value) set_input_level_g(value) set_input_level_h(value) set_input_level_j(value) set_input_level_k(value) set_input_level_l(value)
Parameters:	value is an 8-bit int with each bit representing a bit of the I/O port.
Returns:	undefined
Function:	These functions allow the I/O port Input Level Control (INLVLx) registers to be set. Each bit in the value represents one pin. A 1 sets the corresponding pin's input level to Schmitt Trigger (ST) level, and a 0 sets the corresponding pin's input level to TTL level.
Availability:	All devices with ODC registers, however not all devices have all I/O ports and not all devices port's have a corresponding ODC register.
Requires:	Nothing
Examples:	<pre>set_input_level_a(0x0); //sets PIN_A0 input level to ST and all other //PORTA pins to TTL level</pre>
Example Files:	None
Also See:	output_high() , output_low() , output_bit() , output_x() , General Purpose I/O

set_nco_inc_value()

Syntax:	set_nco_inc_value(value);
Parameters:	value- value to set the NCO increment registers
Returns :	Undefined
Function:	Sets the value that the NCO's accumulator will be incremented by on each clock pulse. The increment registers are double buffered so the new value won't be applied until the accumulator rolls-over.
Availability:	On devices with a NCO module.
Example	<pre>set_nco_inc_value(inc_value); //sets the new</pre>

es:	increment value
Example Files:	None
Also See:	setup_nco() , get_nco_accumulator() , get_nco_inc_value()

set_open_drain_x(value)

Syntax:	<code>set_open_drain_a(value)</code> <code>set_open_drain_b(value)</code> <code>set_open_drain_c(value)</code> <code>set_open_drain_d(value)</code> <code>set_open_drain_e(value)</code> <code>set_open_drain_f(value)</code> <code>set_open_drain_g(value)</code> <code>set_open_drain_h(value)</code> <code>set_open_drain_j(value)</code> <code>set_open_drain_k(value)</code>
Parameters:	value – is an 8-bit int with each bit representing a bit of the I/O port.
Returns:	Nothing
Function	These functions allow the I/O port Open-Drain Control (ODCONx) registers to be set. Each bit in the value represents one pin. A 1 sets the corresponding pin to act as an open-drain output, and a 0 sets the corresponding pin to act as a digital output.
Availability	Nothing.
Examples:	<pre>set open drain a(0x01); //makes PIN A0 an open- drain output. set_open_drain_b(0x001); //enables open-drain output on PIN-B0 //disable on all other port B pins.</pre>
Also See	output_high() , output_low() , output_bit() , output_x() , General Purpose I/O

set_power_pwm_override()

Syntax:	set_power_pwm_override(<i>pwm</i> , <i>override</i> , <i>value</i>)
Parameters:	<i>pwm</i> is a constant between 0 and 7 <i>Override</i> is true or false <i>Value</i> is 0 or 1
Returns:	undefined
Function:	<i>pwm</i> selects which module will be affected. Override determines whether the output is to be determined by the OVDCONS register or the PDC registers. When override is false, the PDC registers determine the output. When override is true, the output is determined by the value stored in OVDCONS. value determines if pin is driven to it's active staet or if pin will be inactive. I will be driven to its active state, 0 pin will be inactive.
Availability:	All devices equipped with PWM.
Requires:	None
Examples:	<pre>set_power_pwm_override(1, true, 1); //PWM1 will be //overridden to active //state set_power_pwm_override(1, false, 0); //PMW1 will not be //overridden</pre>
Example Files:	None
Also See:	setup_power_pwm() , setup_power_pwm_pins() , set_power_pwmX_duty()

set_power_pwmX_duty()

Syntax:	set_power_pwmX_duty(<i>duty</i>)
Parameters:	<i>X</i> is 0, 2, 4, or 6

	Duty is an integer between 0 and 16383.
Returns:	undefined
Function:	Stores the value of duty into the appropriate PDCXL/H register. This duty value is the amount of time that the PWM output is in the active state.
Availability:	All devices equipped with PWM.
Requires:	None
Examples:	<code>set_power_pwm_x_duty(4000);</code>
Example Files:	None
Also See:	setup_power_pwm() , setup_power_pwm_pins() , set_power_pwm_override()

set_pwm1_duty()

set_pwm3_duty()

set_pwm5_duty()

set_pwm2_duty()

set_pwm4_duty()

Syntax:	<code>set_pwm1_duty (value)</code> <code>set_pwm2_duty (value)</code> <code>set_pwm3_duty (value)</code> <code>set_pwm4_duty (value)</code> <code>set_pwm5_duty (value)</code>
Parameters:	value may be an 8 or 16 bit constant or variable.
Returns:	undefined
Function:	Writes the 10-bit value to the PWM to set the duty. An 8-bit value may be used if the most significant bits are not required. The 10 bit value is then used to determine the duty cycle of the PWM signal as follows: <ul style="list-style-type: none">□ $\text{duty cycle} = \text{value} / [4 * (\text{PR2} + 1)]$

	<p>If an 8-bit value is used, the duty cycle of the PWM signal is determined as follows:</p> <ul style="list-style-type: none">• $\text{duty cycle} = \text{value} / (\text{PR2} + 1)$ <p>Where PR2 is the maximum value timer 2 will count to before toggling the output pin.</p>
Availability:	This function is only available on devices with CCP/PWM hardware.
Requires:	None
Examples:	<pre>// For a 20 mhz clock, 1.2 khz frequency, // t2DIV set to 16, PR2 set to 200 // the following sets the duty to 50% (or 416 us). long duty; duty = 408; // [408/(4*(200+1))]=0.5=50% set_pwm1_duty(duty);</pre>
Example Files:	ex_pwm.c
Also See:	setup_ccpX() , set_ccpX_compare_time() , set_timer_period_ccpX() , set_timer_ccpX() , get_timer_ccpX() , get_capture_ccpX() , get_captures32_ccpX()

set_pwm1_offset()	set_pwm2_offset()
set_pwm3_offset()	set_pwm4_offset()
set_pwm5_offset()	set_pwm6_offset()

Syntax:	<pre>set_pwm1_offset (value) set_pwm2_offset (value) set_pwm3_offset (value) set_pwm4_offset (value) set_pwm5_offset (value) set_pwm6_offset (value)</pre>
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Parameters:	<i>value</i> - 16-bit constant or variable.
Returns:	undefined.
Function:	Writes the 16-bit to the PWM to set the offset. The offset is used to adjust the waveform of a slave PWM module relative to the waveform of a master PWM module.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre>set_pwm1_offset(0x0100); set_pwm1_offset(offset);</pre>
Example Files:	setup_pwm() , set_pwm_duty() , set_pwm_period() , clear_pwm_interrupt() , set_pwm_phase() , enable_pwm_interrupt() , disable_pwm_interrupt() , pwm_interrupt_active()
Also See:	

[set_pwm1_period\(\)](#) [set_pwm2_period\(\)](#)
[set_pwm3_period\(\)](#) [set_pwm4_period\(\)](#)
[set_pwm5_period\(\)](#) [set_pwm6_period\(\)](#)

Syntax:	<pre>set_pwm1_period (value) set_pwm2_period (value) set_pwm3_period (value) set_pwm4_period (value) set_pwm5_period (value) set_pwm6_period (value)</pre>
Parameters:	<i>value</i> - 16-bit constant or variable.
Returns:	undefined.
Function:	Writes the 16-bit to the PWM to set the period. When the PWM module is set-up for standard mode it sets the period of the PWM

	signal. When set-up for set on match mode, it sets the maximum value at which the phase match can occur. When in toggle on match and center aligned modes it sets the maximum value the PWMxTMR will count to, the actual period of PWM signal will be twice what the period was set to.
Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<pre>set_pwm1_period(0x8000); set_pwm1_period(period);</pre>
Example Files:	setup_pwm() , set_pwm_duty() , set_pwm_phase() , clear_pwm_interrupt() , set_pwm_offset() , enable_pwm_interrupt() , disable_pwm_interrupt() , pwm_interrupt_active()
Also See:	

[set_pwm1_phase\(\)](#)
[set_pwm3_phase\(\)](#)
[set_pwm5_phase\(\)](#)

[set_pwm2_phase\(\)](#)
[set_pwm4_phase\(\)](#)
[set_pwm6_phase\(\)](#)

Syntax:	<pre>set_pwm1_phase (value) set_pwm2_phase (value) set_pwm3_phase (value) set_pwm4_phase (value) set_pwm5_phase (value) set_pwm6_phase (value)</pre>
Parameters:	value - 16-bit constant or variable.
Returns:	undefined.
Function:	Writes the 16-bit to the PWM to set the phase. When the PWM module is set-up for standard mode the phaes specifies the start of the duty cycle, when in set on match mode it specifies when the output goes high, and when in toggle on match mode it specifies when the output toggles. Phase is not used when in center aligned mode.

Availability:	Devices with a 16-bit PWM module.
Requires:	Nothing
Examples:	<code>set_pwm1_phase(0);</code> <code>set_pwm1_phase(phase);</code>
Example Files:	<code>setup_pwm()</code> , <code>set_pwm_duty()</code> , <code>set_pwm_period()</code> , <code>clear_pwm_interrupt()</code> ,
Also See:	<code>set_pwm_offset()</code> , <code>enable_pwm_interrupt()</code> , <code>disable_pwm_interrupt()</code> , <code>pwm_interrupt_active()</code>

set_open_drain_x()

Syntax:	<code>set_open_drain_a(value)</code> <code>set_open_drain_b(value)</code> <code>set_open_drain_v(value)</code> <code>set_open_drain_d(value)</code> <code>set_open_drain_e(value)</code> <code>set_open_drain_f(value)</code> <code>set_open_drain_g(value)</code> <code>set_open_drain_h(value)</code> <code>set_open_drain_j(value)</code> <code>set_open_drain_k(value)</code>
Parameters:	value is an 16-bit int with each bit representing a bit of the I/O port.
Returns:	undefined
Function:	These functions allow the I/O port Open-Drain Control (ODC) registers to be set. Each bit in the value represents one pin. A 1 sets the corresponding pin to act as an open-drain output, and a 0 sets the corresponding pin to act as a digital output.
Availability:	All devices with ODC registers, however not all devices have all I/O ports and not all devices port's have a corresponding ODC register.
Requires:	Nothing

Examples:	<code>set_open_drain_a(0x0001);</code> <code>//makes PIN_A0 an open-drain output</code>
Example Files:	None
Also See:	output_high() , output_low() , output_bit() , output_x() , General Purpose I/O

set_rtcc()

set_timer2()

set_timer5()

set_timer0()

set_timer3()

set_timer1()

set_timer4()

Syntax:	<code>set_timer0(value)</code> or <code>set_rtcc (value)</code> <code>set_timer1(value)</code> <code>set_timer2(value)</code> <code>set_timer3(value)</code> <code>set_timer4(value)</code> <code>set_timer5(value)</code>
Parameters:	Timers 1 & 5 get a 16 bit int. Timer 2 and 4 gets an 8 bit int. Timer 0 (AKA RTCC) gets an 8 bit int except on the PIC18XXX where it needs a 16 bit int. Timer 3 is 8 bit on PIC16 and 16 bit on PIC18
Returns:	undefined
Function:	Sets the count value of a real time clock/counter. RTCC and Timer0 are the same. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2...)
Availability:	Timer 0 - All devices Timers 1 & 2 - Most but not all PCM devices Timer 3 - Only PIC18XXX and some pick devices Timer 4 - Some PCH devices Timer 5 - Only PIC18XX31
Requires:	Nothing

Examples:

```
// 20 mhz clock, no prescaler, set timer 0
// to overflow in 35us

set_timer0(81);           // 256-(.000035/(4/20000000))
```

Example Files:

[ex_patg.c](#)

Also See:

[set_timer1\(\)](#), [get_timerX\(\)](#) [Timer0 Overview](#), [Timer1Overview](#), [Timer2 Overview](#), [Timer5 Overview](#)

set_ticks()

Syntax: `set_ticks([stream],value);`

Parameters:

stream – optional parameter specifying the stream defined in `#USE TIMER`

value – a 8, 16 or 32 bit integer, specifying the new value of the tick timer. (int8, int16 or int32)

Returns:

void

Function:

Sets the new value of the tick timer. Size passed depends on the size of the tick timer.

Availability:

All devices.

Requires:

`#USE TIMER(options)`

```
#USE TIMER(TIMER=1,TICK=1ms,BITS=16,NOISR)
```

Examples:

```
void main(void) {
    unsigned int16 value = 0x1000;

    set_ticks(value);
}
```

Example Files:

None

Also See:

[#USE TIMER](#), [get_ticks\(\)](#)

setup_sd_adc_calibration()

Syntax:	<code>setup_sd_adc_calibration(model);</code>
Parameters:	<p><i>mode</i>- selects whether to enable or disable calibration mode for the SD ADC module. The following defines are made in the device's <i>.h</i> file:</p> <ul style="list-style-type: none">1 SDADC_START_CALIBRATION_MODE2 SDADC_END_CALIBRATION_MODE
Returns:	Nothing
Function:	To enable or disable calibration mode on the Sigma-Delta Analog to Digital Converter (SD ADC) module. This can be used to determine the offset error of the module, which then can be subtracted from future readings.
Availability:	Only devices with a SD ADC module.
Examples:	<pre>signed int 32 result, calibration; set_sd_adc_calibration(SDADC_START_CALIBRATION_MODE); calibration = read_sd_adc(); set_sd_adc_calibration(SDADC_END_CALIBRATION_MODE); result = read_sd_adc() - calibration;</pre>
Example Files:	None
Also See:	setup_sd_adc() , read_sd_adc() , set_sd_adc_channel()

set_sd_adc_channel()

Syntax:	<code>setup_sd_adc(channel);</code>
Parameters:	<p><i>channel</i>- sets the SD ADC channel to read. Channel can be 0 to read the difference between CH0+ and CH0-, 1 to read the difference between CH1+ and CH1-, or one of the following:</p> <ul style="list-style-type: none">1 SDADC_CH1SE_SVSS2 SDADC_REFERENCE

Returns:	Nothing
Function:	To select the channel that the Sigma-Delta Analog to Digital Converter (SD ADC) performs the conversion on.
Availability:	Only devices with a SD ADC module.
Examples:	<code>set_sd_adc_channel(0);</code>
Example Files:	None
Also See:	setup_sd_adc() , read_sd_adc() , set_sd_adc_calibration()

set_timerA()

Syntax:	set_timerA(value);
Parameters:	An 8 bit integer. Specifying the new value of the timer. (int8)
Returns:	undefined
Function:	Sets the current value of the timer. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2, ...).
Availability:	This function is only available on devices with Timer A hardware.
Requires:	Nothing
Examples:	<pre>// 20 mhz clock, no prescaler, set timer A // to overflow in 35us set_timerA(81); // 256-(.000035/(4/20000000))</pre>
Example Files:	none
Also See:	get_timerA() , setup_timer_A() , TimerA Overview

set_timerB()

Syntax:	set_timerB (value);
Parameters:	An 8 bit integer. Specifying the new value of the timer. (int8)
Returns:	undefined
Function:	Sets the current value of the timer. All timers count up. When a timer reaches the maximum value it will flip over to 0 and continue counting (254, 255, 0, 1, 2, ...).
Availability:	This function is only available on devices with Timer B hardware.
Requires:	Nothing
Examples:	<pre>// 20 mhz clock, no prescaler, set timer B // to overflow in 35us set_timerB(81); // 256-(.000035/(4/20000000))</pre>
Example Files:	none
Also See:	get_timerB() , setup_timer_B() , TimerB Overview

set_tris_x()

Syntax:	set_tris_a (value) set_tris_b (value) set_tris_c (value) set_tris_d (value) set_tris_e (value) set_tris_f (value) set_tris_g (value) set_tris_h (value) set_tris_j (value) set_tris_k (value)
Parameters:	value is an 8 bit int with each bit representing a bit of the I/O port.
Returns:	undefined

Function:	<p>These functions allow the I/O port direction (TRI-State) registers to be set. This must be used with FAST_IO and when I/O ports are accessed as memory such as when a # BYTE directive is used to access an I/O port. Using the default standard I/O the built in functions set the I/O direction automatically.</p> <p>Each bit in the value represents one pin. A 1 indicates the pin is input and a 0 indicates it is output.</p>
Availability:	All devices (however not all devices have all I/O ports)
Requires:	Nothing
Examples:	<pre>SET_TRIS_B(0x0F); // B7,B6,B5,B4 are outputs // B3,B2,B1,B0 are inputs</pre>
Example Files:	lcd.c
Also See:	#USE FAST_IO , #USE FIXED_IO , #USE STANDARD_IO , General Purpose I/O

set_uart_speed()

Syntax:	set_uart_speed (<i>baud</i> , [<i>stream</i> , <i>clock</i>])
Parameters:	<p><i>baud</i> is a constant representing the number of bits per second.</p> <p><i>stream</i> is an optional stream identifier.</p> <p><i>clock</i> is an optional parameter to indicate what the current clock is if it is different from the #use delay value</p>
Returns:	undefined
Function:	Changes the baud rate of the built-in hardware RS232 serial port at run-time.
Availability:	This function is only available on devices with a built in UART.
Requires:	#USE RS232

Examples:	<pre>// Set baud rate based on setting // of pins B0 and B1 switch(input_b() & 3) { case 0 : set_uart_speed(2400); break; case 1 : set_uart_speed(4800); break; case 2 : set_uart_speed(9600); break; case 3 : set_uart_speed(19200); break; }</pre>
Example Files:	loader.c
Also See:	#USE RS232 , putc() , getc() , setup_uart() , RS232 I/O Overview ,

setjmp()

Syntax:	result = setjmp (env)
Parameters:	env: The data object that will receive the current environment
Returns:	If the return is from a direct invocation, this function returns 0. If the return is from a call to the longjmp function, the setjmp function returns a nonzero value and it's the same value passed to the longjmp function.
Function:	Stores information on the current calling context in a data object of type jmp_buf and which marks where you want control to pass on a corresponding longjmp call.
Availability:	All devices
Requires:	#INCLUDE <setjmp.h>
Examples:	<pre>result = setjmp(jmpbuf);</pre>
Example Files:	None
Also See:	longjmp()

setup_adc(mode)

Syntax:	setup_adc (<i>mode</i> , [<i>ADCRS</i>], [<i>ADRPT</i>]); setup_adc2 (<i>mode</i>);
Parameters:	<p>mode- Analog to digital mode. The valid options vary depending on the device. See the devices .h file for all options. Some typical options include:</p> <ul style="list-style-type: none"> • ADC_OFF • ADC_CLOCK_INTERNAL • ADC_CLOCK_DIV_32 <p>ADCRS - For devices with an analog-to-digital converter with computation (ADC2) module only. Optional parameter used set how much the accumulated value is divided by (2^{ADCRS}) in Accumulate, Average and Parst Average modes, and the cut-off frequency in low-pass filter mode.</p> <p>ADRPT - For devices with an ADC2 module only. Optional parameter used to set the number of samples to be done before performing a threshold comparison in Average, Bust Average and low-pass filter modes.</p>
Returns:	undefined
Function:	Configures the analog to digital converter.
Availability:	Only the devices with built in analog to digital converter.
Requires:	Constants are defined in the devices .h file.
Examples:	<pre> setup_adc_ports(ALL_ANALOG); setup_adc(ADC_CLOCK_INTERNAL); set_adc_channel(0); value = read_adc(); setup_adc(ADC_OFF); </pre>
Example Files:	ex_admm.c
Also See:	setup_adc_ports() , set_adc_channel() , read_adc() , #DEVICE , ADC Overview , see header file for device selected

setup_adc_ports()

Syntax:	setup_adc_ports (value) setup_adc_ports (ports, reference)]
Parameters:	<p>value - a constant defined in the device's .h file</p> <p>ports - is a constant specifying the ADC pins to use</p> <p>reference - is an optional constant specifying the ADC reference to use. By default, the reference voltage are Vss and Vdd</p>
Returns:	undefined
Function:	<p>Sets up the ADC pins to be analog, digital, or a combination and the voltage reference to use when computing the ADC value. The allowed analog pin combinations vary depending on the chip and are defined by using the bitwise OR to concatenate selected pins together. Check the device include file for a complete list of available pins and reference voltage settings. The constants ALL_ANALOG and NO_ANALOGS are valid for all chips.</p> <p>Some other example pin definitions are:</p> <ul style="list-style-type: none">• sAN1 sAN2 - AN1 and AN2 are analog, remaining pins are digital• sAN0 sAN3 - AN0 and AN3 are analog, remaining pins are digital
Availability:	<p>This function is only available on devices with A/D hardware.</p> <p>This function is only available on devices with built-in A/D converters.</p>
Requires:	Constants are defined in the device's .h file.
Examples:	<pre>// All pins analog (that can be) setup_adc_ports(ALL_ANALOG); // Pins A0, A1, and A3 are analog and all others are digital. // The +5V is used as a reference. setup_adc_ports(RA0_RA1_RA3_ANALOG); // Pins A0 and A1 are analog. Pin RA3 is use for the reference voltage // and all other pins are digital.</pre>

```
setup_adc_ports(A0_RA1_ANALOGRA3_REF);

// Set all ADC pins to analog mode.

setup_adc_ports(ALL_ANALOG);

// Pins AN0, AN1, and AN3 are analog and all other pins
are digital.

setup_adc_ports(sAN0|sAN1|sAN3);

// Pins AN0 and AN1 are analog. The VrefL pin and Vdd
are used for
// voltage references.

setup_adc_ports(sAN0|sAN1, VREF_VDD);
```

Example Files: [ex_admm.c](#)

Also See: [#USE RS232](#), [putc\(\)](#), [getc\(\)](#), [setup_uart\(\)](#), [RS232 I/O Overview](#),

setup_adc_reference()

Syntax:	setup_adc_reference(reference)
Parameters:	reference - the voltage reference to set the ADC. The valid options depend on the device, see the device's .h file for all options. Typical options include: <ul style="list-style-type: none">• VSS_VDD• VSS_VREF• VREF_VREF• VREF_VDD
Returns:	undefined
Function:	To set the positive and negative voltage reference for the Analog to Digital Converter (ADC) uses.
Availability:	Only on devices with an ADC and has ANSELx, x being the port letter, registers for setting which pins are analog or digital.

Requires:	Nothing
Examples:	<code>set_adc_reference(VSS_VREF);</code>
Example Files:	
Also See:	set_analog_pins() , set_adc_channel() , read_adc() , setup_adc() , setup_adc_ports() , ADC Overview

setup_at()

Syntax:	<code>setup_at(settings);</code>
Parameters:	settings - the setup of the AT module. See the device's header file for all options. Some typical options include: <ul style="list-style-type: none">· AT_ENABLED· AT_DISABLED· AT_MULTI_PULSE_MODE· AT_SINGLE_PULSE_MODE
Returns:	Nothing
Function:	To setup the Angular Timer (AT) module.
Availability:	All devices with an AT module.
Requires:	Constants defined in the device's .h file
Examples:	<code>setup_at(AT_ENABLED AT_MULTI_PULSE_MODE AT_INPUT_ATIN);</code>
Example Files:	None
Also See:	at_set_resolution() , at_get_resolution() , at_set_missing_pulse_delay() , at_get_missing_pulse_delay() , at_get_period() , at_get_phase_counter() , at_set_set_point() , at_get_set_point() , at_get_set_point_error() , at_enable_interrupts() , at_disable_interrupts() , at_clear_interrupts() , at_interrupt_active() , at_setup_cc() , at_set_compare_time() , at_get_capture() , at_get_status()

setup_ccp1()

setup_ccp3()

setup_ccp5()

setup_ccp2()

setup_ccp4()

setup_ccp6()

Syntax:

setup_ccp1 (mode) or setup_ccp1 (mode, pwm)

setup_ccp2 (mode) or setup_ccp2 (mode, pwm)

setup_ccp3 (mode) or setup_ccp3 (mode, pwm)

setup_ccp5 (mode) or setup_ccp5 (mode, pwm)

setup_ccp6 (mode) or setup_ccp6 (mode, pwm)

mode

 is a constant. Valid constants are defined in the devices .h file and refer to devices .h file for all options, some options are as follows:

Disable the CCP:

CCP_OFF

Set CCP to capture mode:

CCP_CAPTURE_FE	Capture on falling edge
CCP_CAPTURE_RE	Capture on rising edge
CCP_CAPTURE_DIV_4	Capture after 4 pulses
CCP_CAPTURE_DIV_16	Capture after 16 pulses

Set CCP to compare mode:

CCP_COMPARE_SET_ON_MATCH	Output high on compare
CCP_COMPARE_CLR_ON_MATCH	Output low on compare
CCP_COMPARE_INT	interrupt on compare
CCP_COMPARE_RESET_TIMER	Reset timer on compare

Set CCP to PWM mode:

CCP_PWM	Enable Pulse Width Modulator
---------	------------------------------

Constants used for ECCP modules are as follows:

CCP_PWM_H_H
CCP_PWM_H_L

CCP_PWM_L_H	
CCP_PWM_L_L	
CCP_PWM_FULL_BRIDGE	
CCP_PWM_FULL_BRIDGE_REV	
CCP_PWM_HALF_BRIDGE	
CCP_SHUTDOWN_ON_COMP1	shutdown on Comparator 1 change
CCP_SHUTDOWN_ON_COMP2	shutdown on Comparator 2 change
CCP_SHUTDOWN_ON_COMP	Either Comp. 1 or 2 change
CCP_SHUTDOWN_ON_INT0	VIL on INT pin
CCP_SHUTDOWN_ON_COMP1_INT0	VIL on INT pin or Comparator 1 change
CCP_SHUTDOWN_ON_COMP2_INT0	VIL on INT pin or Comparator 2 change
CCP_SHUTDOWN_ON_COMP_INT0	VIL on INT pin or Comparator 1 or 2 change
CCP_SHUTDOWN_AC_L	Drive pins A and C high
CCP_SHUTDOWN_AC_H	Drive pins A and C low
CCP_SHUTDOWN_AC_F	Drive pins A and C tri-state
CCP_SHUTDOWN_BD_L	Drive pins B and D high
CCP_SHUTDOWN_BD_H	Drive pins B and D low
CCP_SHUTDOWN_BD_F	Drive pins B and D tri-state
CCP_SHUTDOWN_RESTART	the device restart after a shutdown event
CCP_DELAY	use the dead-band delay

pwm parameter is an optional parameter for chips that includes ECCP module. This parameter allows setting the shutdown time. The value may be 0-255.

Returns: Undefined

Function:	Initialize the CCP. The CCP counters may be accessed using the long variables CCP_1 and CCP_2. The CCP operates in 3 modes. In capture mode it will copy the timer 1 count value to CCP_x when the input pin event occurs. In compare mode it will trigger an action when timer 1 and CCP_x are equal. In PWM mode it will generate a square wave. The PCW wizard will help to set the correct mode and timer settings for a particular application.
Availability:	This function is only available on devices with CCP hardware.
Requires:	Constants are defined in the devices .h file.
Examples:	<code>setup_ccp1(CCP_CAPTURE_RE);</code>
Example Files:	ex_pwm.c , ex_ccmp.c , ex_ccp1s.c
Also See:	set_pwmX_duty() , set_ccpX_compare_time() , set_timer_period_ccpX() , set_timer_ccpX() , get_timer_ccpX() , get_capture_ccpX() , get_captures32_ccpX()

setup_clc1() setup_clc3()

setup_clc2() setup_clc4()

Syntax:	<code>setup_clc1(mode);</code> <code>setup_clc2(mode);</code> <code>setup_clc3(mode);</code> <code>setup_clc4(mode);</code>
Parameters:	mode – The mode to setup the Configurable Logic Cell (CLC) module into. See the device's .h file for all options. Some typical options include: CLC_ENABLED CLC_OUTPUT CLC_MODE_AND_OR CLC_MODE_OR_XOR
Returns:	Undefined.

Function:	Sets up the CLC module to performed the specified logic. Please refer to the device datasheet to determine what each input to the CLC module does for the select logic function
Availability:	On devices with a CLC module.
Return s:	Undefined.
Examples:	<code>setup_clc1(CLC_ENABLED CLC_MODE_AND_OR);</code>
Example Files:	None
Also See:	clcx_setup_gate() , clcx_setup_input()

setup_comparator()

Syntax:	setup_comparator (mode)
Parameters:	<p>mode is a constant. Valid constants are in the devices .h file refer to devices .h file for valid options. Some typical options are as follows:</p> <p>A0_A3_A1_A2 A0_A2_A1_A2 NC_NC_A1_A2 NC_NC_NC_NC A0_VR_A1_VR A3_VR_A2_VR A0_A2_A1_A2_OUT_ON_A3_A4 A3_A2_A1_A2</p>
Returns:	undefined
Function:	Sets the analog comparator module. The above constants have four parts representing the inputs: C1-, C1+, C2-, C2+
Availability:	This function is only available on devices with an analog comparator.
Requires	Constants are defined in the devices .h file.
Examples:	<code>// Sets up two independent comparators (C1 and C2),</code>

```
// C1 uses A0 and A3 as inputs (- and +), and C2
// uses A1 and A2 as inputs
setup_comparator(A0_A3_A1_A2);
```

Example Files: [ex_comp.c](#)

Also See: [Analog Comparator overview](#)

setup_counters()

Syntax: **setup_counters** (*rtcc_state*, *ps_state*)

Parameters:

rtcc_state may be one of the constants defined in the devices .h file. For example: RTCC_INTERNAL, RTCC_EXT_L_TO_H or RTCC_EXT_H_TO_L

ps_state may be one of the constants defined in the devices .h file.

For example: RTCC_DIV_2, RTCC_DIV_4, RTCC_DIV_8, RTCC_DIV_16, RTCC_DIV_32, RTCC_DIV_64, RTCC_DIV_128, RTCC_DIV_256, WDT_18MS, WDT_36MS, WDT_72MS, WDT_144MS, WDT_288MS, WDT_576MS, WDT_1152MS, WDT_2304MS

Returns: undefined

Function:

Sets up the RTCC or WDT. The *rtcc_state* determines what drives the RTCC. The PS state sets a prescaler for either the RTCC or WDT. The prescaler will lengthen the cycle of the indicated counter. If the RTCC prescaler is set the WDT will be set to WDT_18MS. If the WDT prescaler is set the RTCC is set to RTCC_DIV_1.

This function is provided for compatibility with older versions. `setup_timer_0` and `setup_WDT` are the recommended replacements when possible. For PCB devices if an external RTCC clock is used and a WDT prescaler is used then this function must be used.

Availability: All devices

Requires: Constants are defined in the devices .h file.

Examples:	<code>setup_counters (RTCC_INTERNAL, WDT_2304MS);</code>
Example Files:	None
Also See:	setup_wdt() , setup_timer_0() , see header file for device selected

setup_cog()

Syntax:	setup_cog(mode, [shutdown]); setup_cog(mode, [shutdown], [sterring]);
----------------	--

Parameters:	<p>mode- the setup of the COG module. See the device's .h file for all options. Some typical options include:</p> <ul style="list-style-type: none">• COG_ENABLED• COG_DISABLED• COG_CLOCK_HFINTOSC• COG_CLOCK_FOSC <p>shutdown- the setup for the auto-shutdown feature of COG module. See the device's .h file for all the options. Some typical options include:</p> <ul style="list-style-type: none">• COG_AUTO_RESTART• COG_SHUTDOWN_ON_C1OUT• COG_SHUTDOWN_ON_C2OUT <p>steering- optional parameter for steering the PWM signal to COG output pins and/or selecting the COG pins static level. Used when COG is set for steered PWM or synchronous steered PWM modes. Not available on all devices, see the device's .h file if available and for all options. Some typical options include:</p> <ul style="list-style-type: none">• COG_PULSE_STEERING_A• COG_PULSE_STEERING_B• COG_PULSE_STEERING_C• COG_PULSE_STEERING_D
--------------------	---

Returns:	undefined
Function:	Sets up the Complementary Output Generator (COG) module, the auto-shutdown feature of the module and if available steers the signal to the different output pins.
Availability:	All devices with a COG module.
Examples:	<pre>setup_cog(COG_ENABLED COG_PWM COG_FALLING_SOURCE_PWM3 COG_RISING_SOURCE_PWM3, COG_NO_AUTO_SHUTDOWN, COG_PULSE_STEERING_A COG_PULSE_STEERING_B);</pre>
Example Files:	None
Also See:	set_cog_dead_band() , set_cog_phase() , set_cog_blanking() , cog_status() , cog_restart()

setup_crc()

Syntax:	setup_crc (polynomial terms)
Parameters:	<p>polynomial- This will setup the actual polynomial in the CRC engine. The power of each term is passed separated by a comma. 0 is allowed, but ignored. The following define is added to the device's header file to enable little-endian shift direction:</p> <pre>CRC_LITTLE_ENDIAN</pre>
Returns:	Nothing
Function:	Configures the CRC engine register with the polynomial.
Availability:	Only devices with a built-in CRC module.
Examples:	<pre>setup_crc(12, 5); // CRC Polynomial is x¹²+x⁵+1</pre>

	<pre>setup_crc(16, 15, 3, 1); // CRC Polynomial is x¹⁶+x¹⁵+x³+x¹+1</pre>
Example Files:	None
Also See:	crc_init(), crc_calc(), crc_calc8()

setup_cwg()

Syntax:	setup_cwg (mode,shutdown,dead_time_rising,dead_time_falling)
Parameters:	<p>mode- the setup of the CWG module. See the device's .h file for all options. Some typical options include:</p> <ul style="list-style-type: none">• CWG_ENABLED• CWG_DISABLED• CWG_OUTPUT_B• CWG_OUTPUT_A <p>shutdown- the setup for the auto-shutdown feature of CWG module. See the device's .h file for all the options. Some typical options include:</p> <p>CWG_AUTO_RESTART CWG_SHUTDOWN_ON)COMP1 CWG_SHUTDOWN_ON_FLT CWG_SHUTDOWN_ON_CLC2</p> <p>dead_time_rising- value specifying the dead time between A and B on the rising edge. (0-63)</p> <p>dead_time_falling- value specifying the dead time between A and B on the falling edge. (0-63)</p>
Returns:	undefined
Function:	Sets up the CWG module, the auto-shutdown feature of module and the rising

	and falling dead times of the module.
Availability:	All devices with a CWG module.
Examples:	<pre>setup_cwg(CWG_ENABLED CWG_OUTPUT_A CWG_OUTPUT_B CWG_INPUT_PWM1,CWG_SHUTDOWN_ON_FLT,60,30);</pre>
Example Files:	None
Also See:	cwg_status() , cwg_restart()

setup_dac()

Syntax:	setup_dac(mode);
Parameters:	<p>mode- The valid options vary depending on the device. See the devices .h file for all options. Some typical options include:</p> <ul style="list-style-type: none"> · DAC_OUTPUT
Returns:	undefined
Function:	Configures the DAC including reference voltage.
Availability:	Only the devices with built in digital to analog converter.
Requires:	Constants are defined in the devices .h file.
Examples:	<pre>setup_dac(DAC_VDD DAC_OUTPUT); dac_write(value);</pre>
Example Files:	None
Also See:	dac_write() , DAC Overview , See header file for device selected

setup_external_memory()

Syntax:	SETUP_EXTERNAL_MEMORY(<i>mode</i>);
Parameters:	<i>mode</i> is one or more constants from the device header file OR'ed together.
Returns:	undefined
Function:	Sets the mode of the external memory bus.
Availability:	Only devices that allow external memory.
Requires:	Constants are defined in the device.h file
Examples:	<pre>setup_external_memory(EXTMEM_WORD_WRITE EXTMEM_WAIT_0); setup_external_memory(EXTMEM_DISABLE);</pre>
Example Files:	None
Also See:	WRITE PROGRAM EEPROM() , WRITE PROGRAM MEMORY() , External Memory Overview

setup_lcd()

Syntax:	setup_lcd (mode, prescale, [<i>segments0_31</i>],[segments32_47]);
Parameters:	<p><i>Mode</i> may be any of the following constants to enable the LCD and may be or'ed with other constants in the devices *.h file:</p> <ul style="list-style-type: none">• LCD_DISABLED, LCD_STATIC, LCD_MUX12, LCD_MUX13, LCD_MUX14 <p>See the devices .h file for other device specific options.</p> <p><i>Prescale</i> may be 1-16 for the LCD clock.</p> <p><i>Segments0-31</i> may be any of the following constants or'ed together when using the PIC16C92X series of chips:</p> <ul style="list-style-type: none">• SEG0_4, SEG5_8, SEG9_11, SEG12_15,

	SEG16_19, SEG20_26, SEG27_28, SEG29_31 ALL_LCD_PINS
	<p>When using the PIC16F/LF1xxx or PIC18F/LFxxxx series of chips, each of the segments are enabled individually. A value of 1 will enable the segment, 0 will disable it and use the pin for normal I/O operation.</p> <p>Segments 32-47 when using a chip with more than 32 segments, this enables segments 32-47. A value 1 will enable the segment, 0 will disable it. Bit 0 corresponds to segment 32 and bit 15 corresponds to segment 47.</p>
Returns:	undefined.
Function:	This function is used to initialize the LCD Driver Module on the PIC16C92X and PIC16F/LF193X series of chips.
Availability:	Only on devices with built-in LCD Driver Module hardware.
Requires	Constants are defined in the devices *.h file.
Examples:	<pre> · setup_lcd(LCD_MUX14 LCD_STOP_ON_SLEEP, 2, ALL_LCD_PINS); // PIC16C92X · setup_lcd(LCD_MUX13 LCD_REF_ENABLED LCD_B_HIGH_POWER, 0, 0xFF0429); // PIC16F/LF193X - Enables Segments 0, 3, 5, 10, 16, 17, 18, 19, 20, 21, 22, 23 </pre>
Example Files:	ex_92lcd.c
Also See:	lcd_symbol() , lcd_load() , lcd_contrast() , Internal LCD Overview

setup_low_volt_detect()

Syntax:	setup_low_volt_detect(mode)
Parameters:	<p>mode may be one of the constants defined in the devices .h file.</p> <p>LVD_LVDIN, LVD_45, LVD_42, LVD_40, LVD_38, LVD_36, LVD_35, LVD_33, LVD_30, LVD_28, LVD_27, LVD_25, LVD_23, LVD_21, LVD_19</p>

	One of the following may be or'ed(via) with the above if high voltage detect is also available in the device LVD_TRIGGER_BELOW, LVD_TRIGGER_ABOVE
Returns:	undefined
Function:	This function controls the high/low voltage detect module in the device. The mode constants specifies the voltage trip point and a direction of change from that point (available only if high voltage detect module is included in the device). If the device experiences a change past the trip point in the specified direction the interrupt flag is set and if the interrupt is enabled the execution branches to the interrupt service routine.
Availability:	This function is only available with devices that have the high/low voltage detect module.
Requires	Constants are defined in the devices.h file.
Examples:	<pre>setup_low_volt_detect(LVD_TRIGGER_BELOW LVD_36);</pre> <p>This would trigger the interrupt when the voltage is below 3.6 volts</p>

setup_nco()

Syntax:	setup_nco(settings,inc_value)
Parameters:	<p>settings- setup of the NCO module. See the device's .h file for all options. Some typical options include:</p> <ul style="list-style-type: none">· NCO_ENABLE· NCO_OUTPUT· NCO_PULSE_FREQ_MODE· NCO_FIXED_DUTY_MODE <p>inc_value- value to increment the NCO 20 bit accumulator by.</p>
Returns:	Undefined
Function:	Sets up the NCO module and sets the value to increment the 20-bit accumulator by.

Availability:	On devices with a NCO module.
Examples:	<code>setup_nco(NCO_ENABLED NCO_OUTPUT NCO_FIXED_DUTY_MODE NCO_CLOCK_FOSC, 8192);</code>
Example Files:	None
Also See:	get_nco_accumulator() , set_nco_inc_value() , get_nco_inc_value()

setup_opamp1() setup_opamp2() setup_opamp3()

Syntax:	<code>setup_opamp1(mode)</code> <code>setup_opamp2(mode)</code> <code>setup_opamp3(mode)</code>
Parameters:	<p>mode - The mode of the operation amplifier. See the devices .h file for all options. Some typical options include:</p> <ul style="list-style-type: none"> • OPAMP_ENABLED • OPAMP_DISABLED
Returns:	undefined
Function:	Enables or Disables the internal operational amplifier peripheral of certain PICmicros.
Availability:	Only parts with a built-in operational amplifier (for example, PIC16F785).
Requires:	Only parts with a built-in operational amplifier (for example, PIC16F785).
Examples:	<pre>setup_opamp1(OPAMP_ENABLED); setup_opamp2(OPAMP_DISABLED); setup_opamp3(OPAMP_ENABLED OPAMP_I_TO_OUTPUT);</pre>
Example Files:	None
Also See:	None

setup_pid()

Syntax:	setup_pid([mode],[K1],[K2],[K3]);
Parameters:	<p>mode- the setup of the PID module. The options for setting up the module are defined in the device's header file as:</p> <ul style="list-style-type: none"> · PID_MODE_PID · PID_MODE_SIGNED_ADD_MULTIPLY_WITH_ACCUMULATION · PID_MODE_SIGNED_ADD_MULTIPLY · PID_MODE_UNSIGNED_ADD_MULTIPLY_WITH_ACCUMULATION · PID_MODE_UNSIGNED_ADD_MULTIPLY · PID_OUTPUT_LEFT_JUSTIFIED · PID_OUTPUT_RIGHT_JUSTIFIED <p>K1 - optional parameter specifying the K1 coefficient, defaults to zero if not specified. The K1 coefficient is used in the PID and ADD_MULTIPLY modes. When in PID mode the K1 coefficient can be calculated with the following formula:</p> <ul style="list-style-type: none"> · $K1 = Kp + Ki * T + Kd/T$ <p>When in one of the ADD_MULTIPLY modes K1 is the multiple value.</p> <p>K2 - optional parameter specifying the K2 coefficient, defaults to zero if not specified. The K2 coefficient is used in the PID mode only and is calculated with the following formula:</p> <ul style="list-style-type: none"> · $K2 = -(Kp + 2Kd/T)$ <p>K3 - optional parameter specifying the K3 coefficient, defaults to zero if not specified. The K3 coefficient is used in the PID mode, only and is calculated with the following formula:</p> <ul style="list-style-type: none"> · $K3 = Kd/T$ <p>T is the sampling period in the above formulas.</p>
Returns:	Nothing
Function:	To setup the Proportional Integral Derivative (PID) module, and to set the input coefficients (K1, K2 and K3).
Availability:	All devices with a PID module.
Requires:	Constants are defined in the device's .h file.
Examples:	<pre>setup_pid(PID_MODE_PID, 10, -3, 50);</pre>

Syntax:	setup_pmp(options,address_mask);
Options:	<p>options- The mode of the Parallel Master Port that allows to set the Master Port mode, read-write strobe options and other functionality of the PMPort module. See the device's .h file for all options. Some typical options include:</p> <ul style="list-style-type: none"> • PAR_PSP_AUTO_INC • PAR_CONTINUE_IN_IDLE • PAR_INTR_ON_RW //Interrupt on read write • PAR_INC_ADDR //Increment address by 1 every
Parameters:	<ul style="list-style-type: none"> • PAR_MASTER_MODE_1 //read/write cycle • PAR_WAIT_4 //Master Mode 1 • PAR_WAIT_4 //4 Tcy Wait for data hold after • PAR_STROBE // strobe
address_mask:	address_mask- this allows the user to setup the address enable register with a 16-bit value. This value determines which address lines are active from the available 16 address lines PMA0:PMA15.
Returns:	Undefined.
Function:	Configures various options in the PMP module. The options are present in the device's .h file and they are used to setup the module. The PMP module is highly configurable and this function allows users to setup configurations like the Slave module, Interrupt options, address increment/decrement options, Address enable bits, and various strobe and delay options.
Availability:	Only the devices with a built-in Parallel Master Port module.
Requires:	Constants are defined in the device's .h file.

Examples:

```
setup_psp(PAR_ENABLE|address
PAR_MASTER_MODE_1|PAR_STOP_IN_IDLE,0x00FF);
```

//Sets up Master mode with
//lines PMA0:PMA7

Example Files:

None

Also See:

[setup_pmp\(\)](#), [pmp_address\(\)](#), [pmp_read\(\)](#), [psp_read\(\)](#), [psp_write\(\)](#), [pmp_write\(\)](#), [psp_output_full\(\)](#), [psp_input_full\(\)](#), [psp_overflow\(\)](#), [pmp_output_full\(\)](#), [pmp_input_full\(\)](#), [pmp_overflow\(\)](#)
See header file for device selected

setup_psmc()

Syntax:

setup_psmc(*unit, mode, period, period_time, rising_edge, rise_time, falling_edge, fall_time*);

Parameters:

unit is the PSMC unit number 1-4

mode is one of:

- PSMC_SINGLE
- PSMC_PUSH_PULL
- PSMC_BRIDGE_PUSH_PULL
- PSMC_PULSE_SKIPPING
- PSMC_ECCP_BRIDGE_REVERSE
- PSMC_ECCP_BRIDGE_FORWARD
- PSMC_VARIABLE_FREQ
- PSMC_3_PHASE

For complementary outputs use a or bar (!) and PSMC_COMPLEMENTARY

Normally the module is not started until the psmc_pins() call is made. To enable immediately or in PSMC_ENABLE_NOW.

period has three parts or'ed together. The clock source, the clock divisor and the events that can cause the period to start.

Sources:

- PSMC_SOURCE_FOSC
- PSMC_SOURCE_64MHZ
- PSMC_SOURCE_CLK_PIN

Divisors:

- PSMC_DIV_1
- PSMC_DIV_2
- PSMC_DIV_4
- PSMC_DIV_8

Events:

- Use any of the events listed below.

period_time is the duration the period lasts in ticks. A tick is the above clock source divided by the divisor.

rising_edge is any of the following events to trigger when the signal goes active.

rise_time is the time in ticks that the signal goes active (after the start of the period) if the event is PSMC_EVENT_TIME, otherwise unused.

falling_edge is any of the following events to trigger when the signal goes inactive.

fall_time is the time in ticks that the signal goes inactive (after the start of the period) if the event is PSMC_EVENT_TIME, otherwise unused.

Events:

- PSMC_EVENT_TIME
- PSMC_EVENT_C1OUT
- PSMC_EVENT_C2OUT
- PSMC_EVENT_C3OUT
- PSMC_EVENT_C4OUT
- PSMC_EVENT_PIN_PIN

Returns: undefined

Function:

Initializes a PSMC unit with the primary characteristics such as the type of PWM, the period, duty and various advanced triggers. Normally this call does not start the PSMC. It is expected all the setup functions be called and the psmc_pins() be called last to start the PSMC module.

	These two calls are all that are required for a simple PWM. The other functions may be used for advanced settings and to dynamically change the signal.
Availability:	All devices equipped with PSMC module.
Requires:	None
Examples:	<pre>// Simple PWM, 10khz out on pin C0 assuming a 20mhz crystal // Duty is initially set to 25% setup_psmc(1, PSMC_SINGLE, PSMC_EVENT_TIME PSMC_SOURCE_FOSC, us(100), PSMC_EVENT_TIME, 0, PSMC_EVENT_TIME, us(25)); psmc_pins(1, PSMC_A);</pre>
Example Files:	None
Also See:	psmc_deadband() , psmc_sync() , psmc_blanking() , psmc_modulation() , psmc_shutdown() , psmc_duty() , psmc_freq_adjust() , psmc_pins()

setup_power_pwm()

Syntax:	setup_power_pwm (<i>modes</i> , <i>postscale</i> , <i>time_base</i> , <i>period</i> , <i>compare</i> , <i>compare_postscale</i> , <i>dead_time</i>)
Parameters:	<p>modes values may be up to one from each group of the following:</p> <p>PWM_CLOCK_DIV_4, PWM_CLOCK_DIV_16, PWM_CLOCK_DIV_64, PWM_CLOCK_DIV_128</p> <p>PWM_DISABLED, PWM_FREE_RUN, PWM_SINGLE_SHOT, PWM_UP_DOWN, PWM_UP_DOWN_INT</p> <p>PWM_OVERRIDE_SYNC</p> <p>PWM_UP_TRIGGER,</p> <p>PWM_DOWN_TRIGGER PWM_UPDATE_DISABLE, PWM_UPDATE_ENABLE</p> <p>PWM_DEAD_CLOCK_DIV_2, PWM_DEAD_CLOCK_DIV_4,</p>

PWM_DEAD_CLOCK_DIV_8,
PWM_DEAD_CLOCK_DIV_16

postscale is an integer between 1 and 16. This value sets the PWM time base output postscale.

time_base is an integer between 0 and 65535. This is the initial value of the PWM base

period is an integer between 0 and 4095. The PWM time base is incremented until it reaches this number.

compare is an integer between 0 and 255. This is the value that the PWM time base is compared to, to determine if a special event should be triggered.

compare_postscale is an integer between 1 and 16. This postscaler affects compare, the special events trigger.

dead_time is an integer between 0 and 63. This value specifies the length of an off period that should be inserted between the going off of a pin and the going on of it is a complementary pin.

Returns:	undefined
Function:	Initializes and configures the motor control Pulse Width Modulation (PWM) module.
Availability:	All devices equipped with motor control or power PWM module.
Requires:	None
Examples:	<pre>setup_power_pwm(PWM_CLOCK_DIV_4 PWM_FREE_RUN PWM_DEAD_CLOCK_DIV_4, 1, 10000, 1000, 0, 1, 0);</pre>
Example Files:	None
Also See:	set_power_pwm_override() , setup_power_pwm_pins() , set_power_pwmX_duty()

setup_power_pwm_pins()

Syntax:	setup_power_pwm_pins(module0,module1,module2,module3)
Parameters:	For each module (two pins) specify: PWM_PINS_DISABLED, PWM_ODD_ON, PWM_BOTH_ON, PWM_COMPLEMENTARY
Returns:	undefined
Function:	Configures the pins of the Pulse Width Modulation (PWM) device.
Availability:	All devices equipped with a power control PWM.
Requires:	None
Examples:	<pre>setup_power_pwm_pins(PWM_PINS_DISABLED, PWM_PINS_DISABLED, PWM_PINS_DISABLED, PWM_PINS_DISABLED); setup_power_pwm_pins(PWM_COMPLEMENTARY, PWM_COMPLEMENTARY, PWM_PINS_DISABLED, PWM_PINS_DISABLED);</pre>
Example Files:	None
Also See:	setup_power_pwm() , set_power_pwm_override() , set_power_pwmX_duty()

setup_psp(option,address_mask)

Syntax:	setup_psp (options,address_mask); setup_psp(options);
Parameters:	<p>Option- The mode of the Parallel slave port. This allows to set the slave port mode, read-write strobe options and other functionality of the PMP/EPMP module. See the devices .h file for all options. Some typical options include:</p> <ul style="list-style-type: none">· PAR_PSP_AUTO_INC· PAR_CONTINUE_IN_IDLE

	<ul style="list-style-type: none">• PAR_INTR_ON_RW //Interrupt on read write• PAR_INC_ADDR //Increment address by 1 every //read/write cycle• PAR_WAITE4 //4 Tcy Wait for data hold after //strobe <p>address_mask- This allows the user to setup the address enable register with a 16 bit or 32 bit (EPMP) value. This value determines which address lines are active from the available 16 address lines PMA0: PMA15 or 32 address lines PMA0:PMA31 (EPMP only).</p>
Returns:	Undefined.
Function:	Configures various options in the PMP/EPMP module. The options are present in the device.h file and they are used to setup the module. The PMP/EPMP module is highly configurable and this function allows users to setup configurations like the Slave mode, Interrupt options, address increment/decrement options, Address enable bits and various strobe and delay options.
Availability:	Only the devices with a built in Parallel Port module or Enhanced Parallel Master Port module.
Requires:	Constants are defined in the devices .h file.
Examples:	<pre>setup_psp(PAR_PSP_AUTO_INC //Sets up legacy slave PAR_STOP_IN_IDLE,0x00FF); //mode with //read and write buffers //auto increment.</pre>
Example Files:	None
Also See:	psp_output_full() , psp_input_full() , psp_overflow() , See header file for device selected.

setup_pwm1() setup_pwm2()

setup_pwm3() setup_pwm4()

Syntax:	<pre>setup_pwm1(settings); setup_pwm2(settings); setup_pwm3(settings); setup_pwm4(settings);</pre>
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Parameters:	settings- setup of the PWM module. See the device's .h file for all options. Some typical options include: <ul style="list-style-type: none">· PWM_ENABLED· PWM_OUTPUT· PWM_ACTIVE_LOW
Returns:	Undefined
Function:	Sets up the PWM module.
Availability:	On devices with a PWM module.
Examples:	<code>setup_pwm1(PWM_ENABLED PWM_OUTPUT);</code>
Example Files:	None
Also See:	set_pwm_duty()

setup_qei()

Syntax:	setup_qei(<i>options</i>, <i>filter</i>, <i>maxcount</i>);
Parameters:	<p><i>Options</i>- The mode of the QEI module. See the devices .h file for all options</p> <p>Some common options are:</p> <ul style="list-style-type: none">· QEI_MODE_X2· QEI_MODE_X4 <p><i>filter</i> - This parameter is optional, the user can enable the digital filters and specify the clock divisor.</p> <p><i>maxcount</i> - Specifies the value at which to reset the position counter.</p>
Returns:	void
Function:	Configures the Quadrature Encoder Interface. Various settings

	like mode and filters can be setup.
Availability:	Devices that have the QEI module.
Requires:	Nothing.
Examples:	<pre>setup_qei(QEI_MODE_X2 QEI_RESET_WHEN_MAXCOUNT, QEI_FILTER_ENABLE_QEA QEI_FILTER_DIV_2,0x1000);</pre>
Example Files:	None
Also See:	qei_set_count() , qei_get_count() , qei_status()

setup_rtc()

Syntax:	setup_rtc() (<i>options, calibration</i>);
Parameters:	<p>Options- The mode of the RTCC module. See the devices .h file for all options</p> <p>Calibration- This parameter is optional and the user can specify an 8 bit value that will get written to the calibration configuration register.</p>
Returns:	void
Function:	Configures the Real Time Clock and Calendar module. The module requires an external 32.768 kHz clock crystal for operation.
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<pre>setup_rtc(RTC_ENABLE RTC_OUTPUT_SECONDS, 0x00); // Enable RTCC module with seconds clock and no calibration</pre>
Example Files:	None
Also See:	rtc_read() , rtc_alarm_read() , rtc_alarm_write() , setup_rtc_alarm() , rtc_write() , setup_rtc()

setup_rtc_alarm()

Syntax:	<code>setup_rtc_alarm(<i>options</i>, <i>mask</i>, <i>repeat</i>);</code>
Parameters:	<p><i>options</i>- The mode of the RTCC module. See the devices .h file for all options</p> <p><i>mask</i>- specifies the alarm mask bits for the alarm configuration.</p> <p><i>repeat</i>- Specifies the number of times the alarm will repeat. It can have a max value of 255.</p>
Returns:	void
Function:	Configures the alarm of the RTCC module.
Availability:	Devices that have the RTCC module.
Requires:	Nothing.
Examples:	<code>setup_rtc_alarm(RTC_ALARM_ENABLE, RTC_ALARM_HOUR, 3);</code>
Example Files:	None
Also See:	rtc_read() , rtc_alarm_read() , rtc_alarm_write() , setup_rtc_alarm() , rtc_write() , setup_rtc()

setup_smtx()

Syntax:	<code>setup_smt1(mode,[period]);</code> <code>setup_smt2(mode,[period]);</code>
Parameters:	<p><i>mode</i> - The setup of the SMT module. See the device's .h file for all aoptions. Some typical options include:</p> <p>SMT_ENABLED SMT_MODE_TIMER SMT_MODE_GATED_TIMER SMT_MODE_PERIOD_DUTY_CYCLE_ACQ</p>

	period - Optional parameter for specifying the overflow value of the SMT timer, defaults to maximum value if not specified.
Returns:	Nothing
Function:	Configures the Signal Measurement Timer (SMT) module.
Availability:	Only devices with a built-in SMT module.
Examples:	<pre>setup_smt1(SMT_ENABLED SMT_MODE_PERIOD_DUTY_CYCLE_ACQ SMT_REPEAT_DATA_ACQ_MODE SMT_CLK_FOSC);</pre>
Example Files:	None
Also See:	smtx_status() , smtx_start() , smtx_stop() , smtx_update() , smtx_reset_timer() , smtx_read() , smtx_write()

setup_spi()

setup_spi2()

Syntax:	setup_spi (<i>mode</i>) setup_spi2 (<i>mode</i>)
Parameters:	<p>mode may be:</p> <ul style="list-style-type: none">• SPI_MASTER, SPI_SLAVE, SPI_SS_DISABLED• SPI_L_TO_H, SPI_H_TO_L• SPI_CLK_DIV_4, SPI_CLK_DIV_16,• SPI_CLK_DIV_64, SPI_CLK_T2• SPI_SAMPLE_AT_END, SPI_XMIT_L_TO_H• Constants from each group may be or'ed together with .
Returns:	undefined
Function:	Initializes the Serial Port Interface (SPI). This is used for 2 or 3 wire serial devices that follow a common clock/data protocol.
Also See:	spi_write() , spi_read() , spi_data_is_in() , SPI Overview

setup_timer_A()

Syntax:	setup_timer_A (mode);
Parameters:	<i>mode</i> values may be: <ul style="list-style-type: none">· TA_OFF, TA_INTERNAL, TA_EXT_H_TO_L, TA_EXT_L_TO_H· TA_DIV_1, TA_DIV_2, TA_DIV_4, TA_DIV_8, TA_DIV_16, TA_DIV_32, TA_DIV_64, TA_DIV_128, TA_DIV_256· constants from different groups may be or'ed together with .
Returns:	undefined
Function:	sets up Timer A.
Availability:	This function is only available on devices with Timer A hardware.
Requires:	Constants are defined in the device's .h file.
Examples:	<pre>setup_timer_A(TA_OFF); setup_timer_A(TA_INTERNAL TA_DIV_256); setup_timer_A(TA_EXT_L_TO_H TA_DIV_1);</pre>
Example Files:	none
Also See:	get_timerA() , set_timerA() , TimerA Overview

setup_timer_B()

Syntax:	setup_timer_B (mode);
Parameters:	<i>mode</i> values may be: <ul style="list-style-type: none">· TB_OFF, TB_INTERNAL, TB_EXT_H_TO_L, TB_EXT_L_TO_H· TB_DIV_1, TB_DIV_2, TB_DIV_4, TB_DIV_8, TB_DIV_16, TB_DIV_32, TB_DIV_64, TB_DIV_128, TB_DIV_256· constants from different groups may be or'ed together with .
Returns:	undefined

Function:	sets up Timer B
Availability:	This function is only available on devices with Timer B hardware.
Requires:	Constants are defined in device's .h file.
Examples:	<pre>setup_timer_B(TB_OFF); setup_timer_B(TB_INTERNAL TB_DIV_256); setup_timer_B(TA_EXT_L_TO_H TB_DIV_1);</pre>
Example Files:	none
Also See:	get_timerB() , set_timerB() , TimerB Overview

setup_timer_0()

Syntax:	setup_timer_0 (<i>mode</i>)
Parameters:	<p><i>mode</i> may be one or two of the constants defined in the devices .h file. RTCC_INTERNAL, RTCC_EXT_L_TO_H or RTCC_EXT_H_TO_L</p> <p>RTCC_DIV_2, RTCC_DIV_4, RTCC_DIV_8, RTCC_DIV_16, RTCC_DIV_32, RTCC_DIV_64, RTCC_DIV_128, RTCC_DIV_256</p> <p>PIC18XXX only: RTCC_OFF, RTCC_8_BIT</p> <p>One constant may be used from each group or'ed together with the operator.</p>
Returns:	undefined
Function:	Sets up the timer 0 (aka RTCC).
Warning:	On older PIC16 devices, set-up of the prescaler may undo the WDT prescaler.
Availability:	All devices.
Requires:	Constants are defined in the devices .h file.

Examples:	<code>setup_timer_0 (RTCC_DIV_2 RTCC_EXT_L_TO_H);</code>
Example Files:	
Also See:	get_timer0() , set_timer0() , setup_counters()

setup_timer_1()

Syntax:	<code>setup_timer_1 (mode)</code>
Parameters:	<p><i>mode</i> values may be:</p> <ul style="list-style-type: none">• T1_DISABLED, T1_INTERNAL, T1_EXTERNAL, T1_EXTERNAL_SYNC• T1_CLK_OUT• T1_DIV_BY_1, T1_DIV_BY_2, T1_DIV_BY_4, T1_DIV_BY_8• constants from different groups may be or'ed together with .
Returns:	undefined
Function:	<p>Initializes timer 1. The timer value may be read and written to using SET_TIMER1() and GET_TIMER1(). Timer 1 is a 16 bit timer.</p> <p>With an internal clock at 20mhz and with the T1_DIV_BY_8 mode, the timer will increment every 1.6us. It will overflow every 104.8576ms.</p>
Availability:	This function is only available on devices with timer 1 hardware.
Requires:	Constants are defined in the devices .h file.
Examples:	<pre>setup_timer_1 (T1_DISABLED); setup_timer_1 (T1_INTERNAL T1_DIV_BY_4); setup_timer_1 (T1_INTERNAL T1_DIV_BY_8);</pre>
Example Files:	
Also See:	get_timer1() , set_timer1() , Timer1 Overview

setup_timer_2()

Syntax:	setup_timer_2 (mode, period, postscale)
Parameters:	<p>mode may be one of:</p> <ul style="list-style-type: none">• T2_DISABLED• T2_DIV_BY_1, T2_DIV_BY_4, T2_DIV_BY_16 <p>Period is a int 0-255 that determines when the clock value is reset</p> <p>Postscale is a number 1-16 that determines how many timer overflows before an interrupt: (1 means once, 2 means twice, an so on)</p>
Returns:	undefined
Function:	<p>Initializes timer 2. The mode specifies the clock divisor (from the oscillator clock).</p> <p>The timer value may be read and written to using GET_TIMER2() and SET_TIMER2().</p> <p>2 is a 8-bit counter/timer.</p>
Availability:	This function is only available on devices with timer 2 hardware.
Requires:	Constants are defined in the devices .h file.
Examples:	<pre>setup_timer_2 (T2_DIV_BY_4, 0xc0, 2) //at 20mhz, the timer will //increment every 800ns //will overflow every 154.4us, //and will interrupt every 308.us</pre>
Example Files:	
Also See:	get_timer2() , set_timer2() , Timer2 Overview

setup_timer_3()

Syntax:	setup_timer_3 (mode)
Parameters:	<p>Mode may be one of the following constants from each group or'ed (via) together:</p> <ul style="list-style-type: none">• T3_DISABLED, T3_INTERNAL, T3_EXTERNAL, T3_EXTERNAL_SYNC• T3_DIV_BY_1, T3_DIV_BY_2, T3_DIV_BY_4, T3_DIV_BY_8
Returns:	undefined
Function:	Initializes timer 3 or 4.The mode specifies the clock divisor (from the oscillator clock). The timer value may be read and written to using GET_TIMER3() and SET_TIMER3(). Timer 3 is a 16 bit counter/timer.
Availability:	This function is only available on devices with timer 3 hardware.
Requires:	Constants are defined in the devices .h file.
Examples:	setup_timer_3 (T3_INTERNAL T3_DIV_BY_2);
Example Files:	None
Also See:	get_timer3() , set_timer3()

setup_timer_4()

Syntax:	setup_timer_4 (mode, period, postscale)
Parameters:	<p>mode may be one of:</p> <ul style="list-style-type: none">• T4_DISABLED, T4_DIV_BY_1, T4_DIV_BY_4, T4_DIV_BY_16 <p>period is a int 0-255 that determines when the clock value is reset,</p> <p>postscale is a number 1-16 that determines how many timer overflows</p>

	before an interrupt: (1 means once, 2 means twice, and so on).
Returns:	undefined
Function:	Initializes timer 4. The mode specifies the clock divisor (from the oscillator clock). The timer value may be read and written to using GET_TIMER4() and SET_TIMER4(). Timer 4 is a 8 bit counter/timer.
Availability:	This function is only available on devices with timer 4 hardware.
Requires:	Constants are defined in the devices .h file
Examples:	<pre>setup_timer_4 (T4_DIV_BY_4, 0xc0, 2); // At 20mhz, the timer will increment every 800ns, // will overflow every 153.6us, // and will interrupt every 307.2us.</pre>
Example Files:	
Also See:	get_timer4() , set_timer4()

setup_timer_5()

Syntax:	setup_timer_5 (mode)
Parameters:	<p>mode may be one or two of the constants defined in the devices .h file.</p> <p>T5_DISABLED, T5_INTERNAL, T5_EXTERNAL, or EXTERNAL_SYNC</p> <p>T5_DIV_BY_1, T5_DIV_BY_2, T5_DIV_BY_4, T5_DIV_BY_8</p> <p>T5_ONE_SHOT, T5_DISABLE_SE_RESET, or T5_ENABLE_DURING_SLEEP</p>
Returns:	undefined
Function:	Initializes timer 5. The mode specifies the clock divisor (from the

	oscillator clock). The timer value may be read and written to using GET_TIMER5() and SET_TIMER5(). Timer 5 is a 16 bit counter/timer.
Availability:	This function is only available on devices with timer 5 hardware.
Requires:	Constants are defined in the devices .h file.
Examples:	<code>setup_timer_5 (T5_INTERNAL T5_DIV_BY_2);</code>
Example Files:	None
Also See:	get_timer5() , set_timer5() , Timer5 Overview

setup_uart()

Syntax:	<code>setup_uart(baud, stream)</code> <code>setup_uart(baud)</code> <code>setup_uart(baud, stream, clock)</code>
Parameters:	<p>baud is a constant representing the number of bits per second. A one or zero may also be passed to control the on/off status.</p> <p>Stream is an optional stream identifier.</p> <p><i>Chips with the advanced UART may also use the following constants:</i></p> <p>UART_ADDRESS UART only accepts data with 9th bit=1</p> <p>UART_DATA UART accepts all data</p> <p><i>Chips with the EUART H/W may use the following constants:</i></p> <p>UART_AUTODETECT Waits for 0x55 character and sets the UART baud rate to match.</p> <p>UART_AUTODETECT_NOWAIT Same as above function, except returns before 0x55 is received. KBHIT() will be true when the match is made. A call to GETC() will clear the character.</p> <p>UART_WAKEUP_ON_RDA Wakes PIC up out of sleep when RCV goes from high to low</p> <p>clock - If specified this is the clock rate this function should assume. The default comes from the #USE_DELAY.</p>
Returns:	undefined

Function:	Very similar to SET_UART_SPEED. If 1 is passed as a parameter, the UART is turned on, and if 0 is passed, UART is turned off. If a BAUD rate is passed to it, the UART is also turned on, if not already on.
Availability:	This function is only available on devices with a built in UART.
Requires:	#USE RS232
Examples:	<pre>setup_uart(9600); setup_uart(9600, rsOut);</pre>
Example Files:	None
Also See:	#USE RS232 , putc() , getc() , RS232 I/O Overview

setup_vref()

Syntax:	setup_vref (<i>mode</i> <i>value</i>)
Parameters:	<p>mode may be one of the following constants:</p> <ul style="list-style-type: none"> • FALSE (off) • VREF_LOW for $VDD \times \text{VALUE} / 24$ • VREF_HIGH for $VDD \times \text{VALUE} / 32 + VDD / 4$ • any may be or'ed with VREF_A2. <p>value is an int 0-15.</p>
Also See:	Voltage Reference Overview

setup_wdt()

Syntax:	setup_wdt (<i>mode</i>)
Parameters:	Constants like: WDT_18MS, WDT_36MS, WDT_72MS, WDT_144MS, WDT_288MS, WDT_576MS, WDT_1152MS,

	WDT_2304MS For some parts: WDT_ON, WDT_OFF .
Warning:	On older PIC16 devices, set-up of the prescaler may undo the timer0 prescaler.
Also See:	#FUSES , restart_wdt() , WDT or Watch Dog Timer Overview Internal Oscillator Overview

setup_zdc()

Syntax:	setup_zdc(mode);
Parameters:	mode - the setup of the ZDC module. The options for setting up the module include: <ul style="list-style-type: none">• ZCD_ENABLED• ZCD_DISABLED• ZCD_INVERTED• ZCD_INT_L_TO_H• ZCD_INT_H_TO_L
Returns:	Nothing
Function:	To set-up the Zero_Cross Detection (ZCD) module.
Availability:	All devices with a ZCD module.
Examples:	<code>setup_zcd(ZCD_ENABLE ZCD_INT_H_TO_L);</code>
Example Files:	None
Also See:	zcd_status()

shift_left()

Syntax:	shift_left (<i>address</i> , <i>bytes</i> , <i>value</i>)
Parameters:	address is a pointer to memory. bytes is a count of the number of bytes to work with value is a 0 to 1 to be shifted in.
Returns:	0 or 1 for the bit shifted out
Function:	Shifts a bit into an array or structure. The address may be an array identifier or an address to a structure (such as &data). Bit 0 of the lowest byte in RAM is treated as the LSB.
Availability:	All devices
Requires:	Nothing
Examples:	<pre> byte buffer[3]; for(i=0; i<=24; ++i){ // Wait for clock high while (!input(PIN_A2)); shift_left(buffer,3,input(PIN_A3)); // Wait for clock low while (input(PIN_A2)); } // reads 24 bits from pin A3,each bit is read // on a low to high on pin A2 </pre>
Example Files:	ex_extee.c , 9356.c
Also See:	shift_right() , rotate_right() , rotate_left() ,

shift_right()

Syntax:	shift_right (<i>address</i> , <i>bytes</i> , <i>value</i>)
Parameters:	address is a pointer to memory bytes is a count of the number of bytes to work with value is a 0 to 1 to be shifted in.

Returns:	0 or 1 for the bit shifted out
Function:	Shifts a bit into an array or structure. The address may be an array identifier or an address to a structure (such as &data). Bit 0 of the lowest byte in RAM is treated as the LSB.
Availability:	All devices
Requires:	Nothing
Examples:	<pre>// reads 16 bits from pin A1, each bit is read // on a low to high on pin A2 struct { byte time; byte command : 4; byte source : 4;} msg; for(i=0; i<=16; ++i) { while(!input(PIN_A2)); shift_right(&msg,3,input(PIN_A1)); while (input(PIN_A2)) ;} // This shifts 8 bits out PIN_A0, LSB first. for(i=0;i<8;++i) output_bit(PIN_A0,shift_right(&data,1,0));</pre>
Example Files:	ex_extee.c , 9356.c
Also See:	shift_left() , rotate_right() , rotate_left() ,

sleep()

Syntax:	sleep(mode)
Parameters:	mode - for most chips this is not used. Check the device header for special options on some chips.
Returns:	Undefined
Function:	Issues a SLEEP instruction. Details are device dependent. However, in general the part will enter low power mode and halt program execution until woken by specific external

	events. Depending on the cause of the wake up execution may continue after the sleep instruction. The compiler inserts a sleep() after the last statement in main().
Availability:	All devices
Requires:	Nothing
Examples:	<code>SLEEP();</code>
Example Files:	ex_wakeup.c
Also See:	reset_cpu()

sleep_ulpwu()

Syntax:	sleep_ulpwu(<i>time</i>)
Parameters:	<i>time</i> specifies how long, in us, to charge the capacitor on the ultra-low power wakeup pin (by outputting a high on PIN_B0).
Returns:	undefined
Function:	Charges the ultra-low power wake-up capacitor on PIN_B0 for time microseconds, and then puts the PIC to sleep. The PIC will then wake-up on an 'Interrupt-on-Change' after the charge on the cap is lost.
Availability:	Ultra Low Power Wake-Up support on the PIC (example, PIC124F32KA302)
Requires:	#USE DELAY
Examples:	<pre> while(TRUE) { if (input(PIN_A1)) //do something else sleep_ulpwu(10); //cap will be charged for 10us, //then goto sleep } </pre>

Example Files:	None
Also See:	#USE_DELAY

smtx_read()

Syntax:	value_smt1_read (which); value_smt2_read (which);
Parameters:	which - Specifies which SMT registers to read. The following defines have been made in the device's header file to select which registers are read: SMT_CAPTURED_PERIOD_REG SMT_CAPTURED_PULSE_WIDTH_REG SMT_TMR_REG SMT_PERIOD_REG
Returns:	32-bit value
Function:	To read the Capture Period Registers, Capture Pulse Width Registers, Timer Registers or Period Registers of the Signal Measurement Timer module.
Availability:	Only devices with a built-in SMT module.
Examples:	unsigned int32 Period; Period = smt1_read(SMT_CAPTURED_PERIOD_REG);
Example Files:	None
Also See:	smtx_status() , smtx_start() , smtx_stop() , smtx_update() , smtx_reset_timer() , setup_SMTx() , smtx_write()

smtx_reset_timer()

Syntax:	smt1_reset_timer(); smt2_reset_timer();
Parameters:	None
Returns:	Nothing
Function:	To manually reset the Timer Register of the Signal Measurement Timer module.
Availability:	Only devices with a built-in SMT module.
Examples:	<code>smt1_reset_timer();</code>
Example Files:	None
Also See:	setup_smtx() , stmx_start() , smx_stop() , smx_update() , smx_status() , smx_read() , smx_write()

smtx_start()

Syntax:	smt1_start(); smt2_start();
Parameters:	None
Returns:	Nothing
Function:	To have the Signal Measurement Timer (SMT) module start acquiring data.
Availability:	Only devices with a built-in SMT module.
Examples:	<code>smt1_start();</code>
Example Files:	None
Also See:	smx_status() , setup_smtx() , smx_stop() , smx_update() , smx_reset_timer() , smx_read() , smx_write()

smtx_status()

Syntax:	value = smt1_status(); value = smt2_status();
Parameters:	None
Returns:	The status of the SMT module.
Function:	To return the status of the Signal Measurement Timer (SMT) module.
Availability:	Only devices with a built-in SMT module.
Examples:	<code>status = smt1_status();</code>
Example Files:	None
Also See:	setup_smtx() , stmx_start() , smtx_stop() , smtx_update() , smtx_reset_timer() , smtx_read() , smtx_write()

smtx_stop()

Syntax:	smt1_stop(); smt2_stop();
Parameters:	None
Returns:	Nothing
Function:	Configures the Signal Measurement Timer (SMT) module.
Availability:	Only devices with a built-in SMT module.
Examples:	<code>smt1_stop()</code>
Example Files:	None
Also See:	smtx_status() , stmx_start() , setup_smtx() , smtx_update() , smtx_reset_timer() , smtx_read() , smtx_write()

smtx_write()

Syntax:	smt1_write (which,value); smt2_write (which,value);
Parameters:	<p>which - Specifies which SMT registers to write. The following defines have been made in the device's header file to select which registers are written:</p> <p style="padding-left: 40px;">SMT_TMR_REG SMT_PERIOD_REG</p> <p>value - The 24-bit value to set the specified registers.</p>
Returns:	Nothing
Function:	To write the Timer Registers or Period Registers of the Signal Measurement Timer (SMT) module
Availability:	Only devices with a built-in SMT module.
Examples:	<code>smt1_write(SMT_PERIOD_REG, 0x100000000);</code>
Example Files:	None
Also See:	smtx_status() , smtx_start() , setup_smtx() , smtx_update() , smtx_reset_timer() , smtx_read() , setup_smtx()

smtx_update()

Syntax:	smt1_update (which); smt2_update (which);
Parameters:	<p>which - Specifies which capture registers to manually update. The following defines have been made in the device's header file to select which registers are updated:</p> <p style="padding-left: 40px;">SMT_CAPTURED_PERIOD_REG SMT_CAPTURED_PULSE_WIDTH_REG</p>
Returns:	Nothing

Function:	To manually update the Capture Period Registers or the Capture Pulse Width Registers of the Signal Measurement Timer module.
Availability:	Only devices with a built-in SMT module.
Examples:	<code>smt1_update(SMT_CAPTURED_PERIOD_REG);</code>
Example Files:	None
Also See:	setup_smtx() , stmx_start() , smxtx_stop() , smxtx_status() , smxtx_reset_timer() , smxtx_read() , smxtx_write()

`spi_data_is_in()` `spi_data_is_in2()`

Syntax:	<code>result = spi_data_is_in()</code> <code>result = spi_data_is_in2()</code>
Parameters:	None
Returns:	0 (FALSE) or 1 (TRUE)
Function:	Returns TRUE if data has been received over the SPI.
Availability:	This function is only available on devices with SPI hardware.
Requires:	Nothing
Examples:	<pre>(!spi_data_is_in() && input(PIN_B2)); if(spi_data_is_in()) data = spi_read();</pre>
Example Files:	None
Also See:	spi_read() , spi_write() , SPI Overview

spi_init()

Syntax:	spi_init(baud); spi_init(stream,baud);
Parameters:	stream – is the SPI stream to use as defined in the STREAM=name option in #USE SPI. band - the band rate to initialize the SPI module to. If FALSE it will disable the SPI module, if TRUE it will enable the SPI module to the band rate specified in #use SPI.
Returns:	Nothing.
Function:	Initializes the SPI module to the settings specified in #USE SPI.
Availability:	This function is only available on devices with SPI hardware.
Requires:	#USE SPI
Examples:	<pre>#use spi (MATER, SPI1, baud=1000000, mode=0, stream=SPI1_MODE0) spi_init(SPI1_MODE0, TRUE); //initialize and enable SPI1 to setting in #USE SPI spi_init(FALSE); //disable SPI1 spi_init(250000); //initialize and enable SPI1 to a baud rate of 250K</pre>
Example Files:	None
Also See:	#USE SPI, spi_xfer(), spi_xfer_in(), spi_prewrite(), spi_speed()

spi_prewrite(data);

Syntax:	spi_prewrite(data); spi_prewrite(stream, data);
Parameters:	stream – is the SPI stream to use as defined in the STREAM=name option in #USE SPI. data - the variable or constant to transfer via SPI
Returns:	Nothing.

Function:	Writes data into the SPI buffer without waiting for transfer to be completed. Can be used in conjunction with <code>spi_xfer()</code> with no parameters to transfer more then 8 bits for PCM and PCH device, or more then 8 bits or 16 bits (XFER16 option) for PCD. Function is useful when using the SSP or SSP2 interrupt service routines for PCM and PCH device, or the SPIx interrupt service routines for PCD device.
Availability:	This function is only available on devices with SPI hardware.
Requires:	#USE SPI, and the option SLAVE is used in #USE SPI to setup PIC as a SPI slave device
Examples:	<code>spi_prewrite(data_out);</code>
Example Files:	<code>ex_spi_slave.c</code>
Also See:	#USE SPI , spi_xfer() , spi_xfer_in() , spi_init() , spi_speed()

spi_read() spi_read2()

Syntax:	<code>value = spi_read ([data])</code> <code>value = spi_read2 ([data])</code>
Parameters:	data – optional parameter and if included is an 8 bit int.
Returns:	An 8 bit int
Function:	<p>Return a value read by the SPI. If a value is passed to the <code>spi_read()</code> the data will be clocked out and the data received will be returned. If no data is ready, <code>spi_read()</code> will wait for the data is a SLAVE or return the last DATA clocked in from <code>spi_write()</code>.</p> <p>If this device is the MASTER then either do a <code>spi_write(data)</code> followed by a <code>spi_read()</code> or do a <code>spi_read(data)</code>. These both do the same thing and will generate a clock. If there is no data to send just do a <code>spi_read(0)</code> to get the clock.</p> <p>If this device is a SLAVE then either call <code>spi_read()</code> to wait for the clock and data or use <code>_spi_data_is_in()</code> to determine if data is ready.</p>
Availability:	This function is only available on devices with SPI hardware.

Requires:	Nothing
Examples:	<code>data_in = spi_read(out_data);</code>
Example Files:	ex_spi.c
Also See:	spi_write() , spi_data_is_in() , SPI Overview

spi_read2_16() spi_read3_16() spi_read4_16()

Syntax:	<pre>value = spi_read_16([data]); value = spi_read2_16([data]); value = spi_read3_16([data]); value = spi_read4_16([data]);</pre>
Parameters:	data – optional parameter and if included is a 16 bit int
Returns:	A 16 bit int
Function:	<p>Return a value read by the SPI. If a value is passed to the spi_read_16() the data will be clocked out and the data received will be returned. If no data is ready, spi_read_16() will wait for the data is a SLAVE or return the last DATA clocked in from spi_write_16(). If this device is the MASTER then either do a spi_write_16(data) followed by a spi_read_16() or do a spi_read_16(data). These both do the same thing and will generate a clock. If there is no data to send just do a spi_read_16(0) to get the clock.</p> <p>If this device is a slave then either call spi_read_16() to wait for the clock and data or use spi_data_is_in() to determine if data is ready.</p>
Availability:	This function is only available on devices with SPI hardware.
Requires:	NThat the option SPI_MODE_16B be used in setup_spi() function, or that the option XFER16 be used in #use SPI(
Examples:	<code>data_in = spi_read_16(out_data);</code>
Example Files:	None

Also See:	<code>spi_read()</code> , <code>spi_write()</code> , <code>spi_write_16()</code> , <code>spi_data_is_in()</code> , SPI Overview
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spi_speed

Syntax:	<code>spi_speed(baud);</code> <code>spi_speed(stream,baud);</code> <code>spi_speed(stream,baud,clock);</code>
Parameters:	stream – is the SPI stream to use as defined in the STREAM=name option in #USE SPI. band - the band rate to set the SPI module to clock - the current clock rate to calculate the band rate with. If not specified it uses the value specified in #use delay ().
Returns:	Nothing.
Function:	Sets the SPI module's baud rate to the specified value.
Availability:	This function is only available on devices with SPI hardware.
Requires:	#USE SPI
Examples:	<code>spi_speed(250000);</code> <code>spi_speed(SPI1_MODE0, 250000);</code> <code>spi_speed(SPI1_MODE0, 125000, 8000000);</code>
Example Files:	None
Also See:	#USE SPI, <code>spi_xfer()</code> , <code>spi_xfer_in()</code> , <code>spi_prewrite()</code> , <code>spi_init()</code>

spi_write()

spi_write2()

Syntax:	<code>spi_write([wait],value);</code> <code>spi_write2([wait],value);</code>
Parameters:	value is an 8 bit int wait - an optional parameter specifying whether the function will wait

	for the SPI transfer to complete before exiting. Default is TRUE if not specified.
Returns:	Nothing
Function:	Sends a byte out the SPI interface. This will cause 8 clocks to be generated. This function will write the value out to the SPI. At the same time data is clocked out data is clocked in and stored in a receive buffer. <code>spi_read()</code> may be used to read the buffer.
Availability:	This function is only available on devices with SPI hardware.
Requires:	Nothing
Examples:	<pre>spi_write(data_out); data_in = spi_read();</pre>
Example Files:	ex_spi.c
Also See:	spi_read() , spi_data_is_in() , SPI Overview , spi_write_16() , spi_read_16()

spi_xfer()

Syntax:	<pre>spi_xfer(data) spi_xfer(stream, data) spi_xfer(stream, data, bits) result = spi_xfer(data) result = spi_xfer(stream, data) result = spi_xfer(stream, data, bits)</pre>
Parameters:	<p><i>data</i> is the variable or constant to transfer via SPI. The pin used to transfer <i>data</i> is defined in the DO=pin option in #use spi.</p> <p><i>stream</i> is the SPI stream to use as defined in the STREAM=name option in #USE SPI.</p> <p><i>bits</i> is how many bits of data will be transferred.</p>
Returns:	The data read in from the SPI. The pin used to transfer result is defined in the DI=pin option in #USE SPI.

Function:	Transfers data to and reads data from an SPI device.
Availability:	All devices with SPI support.
Requires:	<code>#USE SPI</code>
Examples:	<pre>int i = 34; spi_xfer(i); // transfers the number 34 via SPI int trans = 34, res; res = spi_xfer(trans); // transfers the number 34 via SPI // also reads the number coming in from SPI</pre>
Example Files:	None
Also See:	<u>#USE SPI</u>

SPI_XFER_IN()

Syntax:	<pre>value = spi_xfer_in(); value = spi_xfer_in(bits); value = spi_xfer_in(stream,bits);</pre>
Parameters:	<p>stream – is the SPI stream to use as defined in the <code>STREAM=name</code> option in <code>#USE SPI</code>.</p> <p>bits – is how many bits of data to be received.</p>
Returns:	The data read in from the SPI
Function:	Reads data from the SPI, without writing data into the transmit buffer first.
Availability:	This function is only available on devices with SPI hardware.
Requires:	<code>#USE SPI</code> , and the option <code>SLAVE</code> is used in <code>#USE SPI</code> to setup PIC as a SPI slave device.
Examples:	<pre>data_in = spi_xfer_in();</pre>
Example Files:	ex_spi_slave.c
Also See:	<code>#USE SPI</code> , <code>spi_xfer()</code> , <code>spi_prewrite()</code> , <code>spi_init()</code> , <code>spi_speed()</code>

sprintf()

Syntax:	sprintf(string, cstring, values...); bytes=sprintf(string, cstring, values...)
Parameters:	string is an array of characters. cstring is a constant string or an array of characters null terminated. Values are a list of variables separated by commas. Note that format specifiers do not work in ram band strings.
Returns:	Bytes is the number of bytes written to string.
Function:	This function operates like printf() except that the output is placed into the specified string. The output string will be terminated with a null. No checking is done to ensure the string is large enough for the data. See printf() for details on formatting.
Availability:	All devices.
Requires:	Nothing
Examples:	<pre>char mystring[20]; long mylong; mylong=1234; sprintf(mystring, "<%lu>", mylong); // mystring now has: // < 1 2 3 4 > \0</pre>
Example Files:	None
Also See:	printf()

sqrt()

Syntax:	result = sqrt (value)
Parameters:	value is a float
Returns:	A float

Function:	<p>Computes the non-negative square root of the float value x. If the argument is negative, the behavior is undefined.</p> <p>Note on error handling: If "errno.h" is included then the domain and range errors are stored in the errno variable. The user can check the errno to see if an error has occurred and print the error using the perror function.</p> <p>Domain error occurs in the following cases: sqrt: when the argument is negative</p>
Availability:	All devices.
Requires:	#INCLUDE <math.h>
Examples:	<pre>distance = sqrt(pow((x1-x2),2)+pow((y1-y2),2));</pre>
Example Files:	None
Also See:	None

rand()

Syntax:	rand(<i>n</i>)
Parameters:	<i>n</i> is the seed for a new sequence of pseudo-random numbers to be returned by subsequent calls to rand.
Returns:	No value.
Function:	<p>The rand() function uses the argument as a seed for a new sequence of pseudo-random numbers to be returned by subsequent calls to rand. If rand() is then called with same seed value, the sequence of random numbers shall be repeated. If rand is called before any call to srand() have been made, the same sequence shall be generated as when srand() is first called with a seed value of 1.</p>
Availability:	All devices.
Requires:	#INCLUDE <STDLIB.H>

Examples:	<code>srand(10);</code> <code>I=rand();</code>
Example Files:	None
Also See:	rand()

STANDARD STRING FUNCTIONS()

memchr()

strchr()

strcspn()

strlen()

strncmp()

strrchr()

memcmp()

strcmp()

strerror()

strlwr()

strncpy()

strspn()

strcat()

strcoll()

stricmp()

strncat()

strpbrk()

strstr()

strxfrm()

Syntax:	ptr=strcat (s1, s2)	Concatenate s2 onto s1
	ptr=strchr (s1, c)	Find c in s1 and return &s1[i]
	ptr=strrchr (s1, c)	Same but search in reverse
	cresult=strcmp (s1, s2)	Compare s1 to s2
	ireresult=strncmp (s1, s2, n)	Compare s1 to s2 (n bytes)
	ireresult=stricmp (s1, s2)	Compare and ignore case
	ptr=strncpy (s1, s2, n)	Copy up to n characters s2->s1
	ireresult=strcspn (s1, s2)	Count of initial chars in s1 not in s2
	ireresult=strspn (s1, s2)	Count of initial chars in s1 also in s2
	ireresult=strlen (s1)	Number of characters in s1
	ptr=strlwr (s1)	Convert string to lower case
	ptr=strpbrk (s1, s2)	Search s1 for first char also in s2
	ptr=strstr (s1, s2)	Search for s2 in s1
	ptr=strncat(s1,s2, n)	Concatenates up to n bytes of s2 onto s1
	ireresult=strcoll(s1,s2)	Compares s1 to s2, both interpreted as appropriate to the current locale.

	<div><div><div>res=strxfrm(s1,s2,n)</div><div>irestult=memcmp(m1,m2,n)</div><div>ptr=memchr(m1,c,n)</div><div>ptr=strerror(ernnum)</div></div><div><div>Transforms maximum of n characters of s2 and places them in s1, such that strcmp(s1,s2) will give the same result as strcoll(s1,s2)</div><div>Compare m1 to m2 (n bytes)</div><div>Find c in first n characters of m1 and return &m1[i]</div><div>Maps the error number in ernnum to an error message string. The parameters 'ernnum' is an unsigned 8 bit int. Returns a pointer to the string.</div></div></div>
Parameters:	<div><div>s1 and s2 are pointers to an array of characters (or the name of an array). Note that s1 and s2 MAY NOT BE A CONSTANT (like "hi").</div><div>n is a count of the maximum number of character to operate on.</div><div>c is a 8 bit character</div><div>m1 and m2 are pointers to memory.</div></div>
Returns:	<div><div>ptr is a copy of the s1 pointer</div><div>irestult is an 8 bit int</div><div>result is -1 (less than), 0 (equal) or 1 (greater than)</div><div>res is an integer.</div></div>
Function:	Functions are identified above.
Availability:	All devices.
Requires:	#include <string.h>
Examples:	<div><div>char string1[10], string2[10];</div><div>strcpy(string1,"hi ");</div><div>strcpy(string2,"there");</div><div>strcat(string1,string2);</div><div>printf("Length is %u\r\n", strlen(string1));</div><div>// Will print 8</div></div>
Example Files:	ex_str.c
Also See:	strcpy() , strtok()

strcpy() strcpy()

Syntax:	strcpy (<i>dest</i> , <i>src</i>) strcpy (<i>dest</i> , <i>src</i>)
Parameters:	dest is a pointer to a RAM array of characters. src may be either a pointer to a RAM array of characters or it may be a constant string.
Returns:	undefined
Function:	Copies a constant or RAM string to a RAM string. Strings are terminated with a 0.
Availability:	All devices.
Requires:	Nothing
Examples:	<pre>char string[10], string2[10]; . . . strcpy (string, "Hi There"); strcpy(string2,string);</pre>
Example Files:	ex_str.c
Also See:	strxxx()

strtod()

Syntax:	result=strtod (<i>nptr</i> ,& <i>endptr</i>)
Parameters:	nptr and endptr are strings
Returns:	result is a float. returns the converted value in result, if any. If no conversion could be

	performed, zero is returned.
Function:	The strtod function converts the initial portion of the string pointed to by nptr to a float representation. The part of the string after conversion is stored in the object pointed to endptr, provided that endptr is not a null pointer. If nptr is empty or does not have the expected form, no conversion is performed and the value of nptr is stored in the object pointed to by endptr, provided endptr is not a null pointer.
Availability:	All devices.
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>float result; char str[12]="123.45hello"; char *ptr; result=strtod(str,&ptr); //result is 123.45 and ptr is "hello"</pre>
Example Files:	None
Also See:	strtol() , strtoul()

strtok()

Syntax:	ptr = strtok(s1, s2)
Parameters:	s1 and s2 are pointers to an array of characters (or the name of an array). Note that s1 and s2 MAY NOT BE A CONSTANT (like "hi"). s1 may be 0 to indicate a continue operation.
Returns:	ptr points to a character in s1 or is 0
Function:	<p>Finds next token in s1 delimited by a character from separator string s2 (which can be different from call to call), and returns pointer to it.</p> <p>First call starts at beginning of s1 searching for the first character NOT contained in s2 and returns null if there is none are found.</p> <p>If none are found, it is the start of first token (return value). Function then searches from there for a character contained in s2.</p>

If none are found, current token extends to the end of s1, and subsequent searches for a token will return null.

If one is found, it is overwritten by '\0', which terminates current token. Function saves pointer to following character from which next search will start.

Each subsequent call, with 0 as first argument, starts searching from the saved pointer.

Availability: All devices.

Requires: #INCLUDE <string.h>

Examples:

```
char string[30], term[3], *ptr;

strcpy(string, "one,two,three;");
strcpy(term, ",;");

ptr = strtok(string, term);
while(ptr!=0) {
    puts(ptr);
    ptr = strtok(0, term);
}

// Prints:
one
two
three
```

Example Files: [ex_str.c](#)

Also See: [strxxx\(\)](#), [strcpy\(\)](#)

strtol()

Syntax: **result=**[**strtol**](#)(*nptr*,& *endptr*, *base*)

Parameters: *nptr* and *endptr* are strings and **base** is an integer

Returns: result is a signed long int.

	returns the converted value in result , if any. If no conversion could be performed, zero is returned.
Function:	The strtol function converts the initial portion of the string pointed to by nptr to a signed long int representation in some radix determined by the value of base. The part of the string after conversion is stored in the object pointed to endptr, provided that endptr is not a null pointer. If nptr is empty or does not have the expected form, no conversion is performed and the value of nptr is stored in the object pointed to by endptr, provided endptr is not a null pointer.
Availability:	All devices.
Requires:	#INCLUDE <stdlib.h>
Examples:	<pre>signed long result; char str[9]="123hello"; char *ptr; result=strtol(str,&ptr,10); //result is 123 and ptr is "hello"</pre>
Example Files:	None
Also See:	strtod() , strtoul()

strtoul()

Syntax:	result=strtoul(<i>nptr</i>,<i>endptr</i>, <i>base</i>)
Parameters:	<i>nptr</i> and <i>endptr</i> are strings pointers and <i>base</i> is an integer 2-36.
Returns:	result is an unsigned long int. returns the converted value in result , if any. If no conversion could be performed, zero is returned.

Function:	The strtoul function converts the initial portion of the string pointed to by nptr to a long int representation in some radix determined by the value of base. The part of the string after conversion is stored in the object pointed to endptr, provided that endptr is not a null pointer. If nptr is empty or does not have the expected form, no conversion is performed and the value of nptr is stored in the object pointed to by endptr, provided endptr is not a null pointer.
Availability:	All devices.
Requires:	STDLIB.H must be included
Examples:	<pre> long result; char str[9]="123hello"; char *ptr; result=strtoul(str,&ptr,10); //result is 123 and ptr is "hello" </pre>
Example Files:	None
Also See:	strtol() , strtod()

swap()

Syntax:	swap (Ivalue)
Parameters:	Ivalue is a byte variable
Returns:	undefined - WARNING: this function does not return the result
Function:	Swaps the upper nibble with the lower nibble of the specified byte. This is the same as: byte = (byte << 4) (byte >> 4);
Availability:	All devices.
Requires:	Nothing

Examples:	<pre>x=0x45; swap(x); //x now is 0x54</pre>
Example Files:	None
Also See:	rotate_right() , rotate_left()

tolower() toupper()

Syntax:	result = tolower (cvalue) result = toupper (cvalue)
Parameters:	cvalue is a character
Returns:	An 8 bit character
Function:	These functions change the case of letters in the alphabet. TOLOWER(X) will return 'a'..'z' for X in 'A'..'Z' and all other characters are unchanged. TOUPPER(X) will return 'A'..'Z' for X in 'a'..'z' and all other characters are unchanged.
Availability:	All devices.
Requires:	Nothing
Examples:	<pre>switch(toupper(getc())) { case 'R' : read_cmd(); break; case 'W' : write_cmd(); break; case 'Q' : done=TRUE; break; }</pre>
Example Files:	ex_str.c
Also See:	None

touchpad_getc()

Syntax:	input = TOUCHPAD_GETC();
Parameters:	None
Returns:	char (returns corresponding ASCII number if "input" declared as int)
Function:	<p>Actively waits for firmware to signal that a pre-declared Capacitive Sensing Module (CSM) or charge time measurement unit (CTMU) pin is active, then stores the pre-declared character value of that pin in "input".</p> <p>Note: Until a CSM or CTMU pin is read by firmware as active, this instruction will cause the microcontroller to stall.</p>
Availability:	All PIC's with a CSM or CTMU Module
Requires:	#USE TOUCHPAD (options) <pre>//When the pad connected to PIN_B0 is activated, store the letter 'A' #USE TOUCHPAD (PIN_B0='A') void main(void){ char c; enable_interrupts(GLOBAL); c = TOUCHPAD_GETC(); //will wait until one of declared pins is detected //if PIN_B0 is pressed, c will get value 'A' }</pre>
Examples:	
Example Files:	None
Also See:	#USE TOUCHPAD , touchpad_state()

touchpad_hit()

Syntax:	value = TOUCHPAD_HIT()
Parameters:	None
Returns:	TRUE or FALSE
Function:	Returns TRUE if a Capacitive Sensing Module (CSM) or Charge Time Measurement Unit (CTMU) key has been pressed. If TRUE, then a call to touchpad_getc() will not cause the program to wait for a key press.
Availability:	All PIC's with a CSM or CTMU Module
Requires:	#USE TOUCHPAD (options) // When the pad connected to PIN_B0 is activated, store the letter 'A' #USE TOUCHPAD (PIN_B0='A') void main(void){ char c; enable_interrupts(GLOBAL); while (TRUE) { if (TOUCHPAD_HIT()) //wait until key on PIN_B0 is pressed c = TOUCHPAD_GETC(); //get key that was pressed } }
Examples:	
Example Files:	None
Also See:	#USE TOUCHPAD () , touchpad_state() , touchpad_getc()

touchpad_state()

Syntax:	TOUCHPAD_STATE (state);
Parameters:	state is a literal 0, 1, or 2.

Returns:	None
Function:	<p>Sets the current state of the touchpad connected to the Capacitive Sensing Module (CSM). The state can be one of the following three values:</p> <p>0 : Normal state 1 : Calibrates, then enters normal state 2 : Test mode, data from each key is collected in the int16 array TOUCHDATA</p> <p>Note: If the state is set to 1 while a key is being pressed, the touchpad will not calibrate properly.</p>
Availability:	All PIC's with a CSM Module
Requires:	#USE TOUCHPAD (options)
Examples:	<pre>#USE TOUCHPAD (THRESHOLD=5, PIN_D5='5', PIN_B0='C') void main(void){ char c; TOUCHPAD_STATE(1); //calibrates, then enters normal state enable_interrupts(GLOBAL); while(1){ c = TOUCHPAD_GETC(); //will wait until one of declared pins is detected } //if PIN_B0 is pressed, c will get value 'C' } //if PIN_D5 is pressed, c will get value '5'</pre>
Example Files:	None
Also See:	#USE TOUCHPAD , touchpad_getc() , touchpad_hit()

tx_buffer_available()

Syntax:	value = tx_buffer_available([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE RS232.
Returns:	Number of bytes that can still be put into transmit buffer
Function:	Function to determine the number of bytes that can still be put into transmit buffer before it overflows. Transmit buffer is implemented has a circular buffer, so be sure to check to make sure there is room for at least one more then what is actually needed.
Availability:	All devices
Requires:	#USE RS232 #USE_RS232 (UART1,BAUD=9600,TRANSMIT_BUFFER=50) void main(void) { unsigned int8 Count = 0; while(TRUE) { if(tx_buffer_available()>13) printf("/r/nCount=%3u",Count++) ; } }
Examples:	
Example Files:	None
Also See:	USE_RS232() , rcv() , TX_BUFFER_FULL() , RCV_BUFFER_BYTES() , GET() , PUTC() , PRINTF() , SETUP_UART() , PUTC_SEND()

tx_buffer_bytes()

Syntax:	value = tx_buffer_bytes([stream]);
Parameters:	stream – optional parameter specifying the stream defined in #USE RS232.
Returns:	Number of bytes in transmit buffer that still need to be sent.
Function:	Function to determine the number of bytes in transmit buffer that still need to be sent.
Availability:	All devices
Requires:	#USE RS232
Examples:	<pre>#USE_RS232(UART1,BAUD=9600,TRANSMIT_BUFFER=50) void main(void) { char string[] = "Hello"; if(tx_buffer_bytes() <= 45) printf("%s",string); }</pre>
Example Files:	None
Also See:	<u>USE_RS232()</u> , <u>RCV_BUFFER_FULL()</u> , <u>TX_BUFFER_FULL()</u> , <u>RCV_BUFFER_BYTES()</u> , <u>GET()</u> , <u>PUTC()</u> , <u>PRINTF()</u> , <u>SETUP_UART()</u> , <u>PUTC_SEND()</u>

tx_buffer_full()

Syntax:	value = tx_buffer_full([stream])
Parameters:	stream – optional parameter specifying the stream defined in #USE RS232
Returns:	TRUE if transmit buffer is full, FALSE otherwise.

Function:	Function to determine if there is room in transmit buffer for another character.
Availability:	All devices
Requires:	#USE RS232
Examples:	<pre>#USE_RS232(UART1,BAUD=9600,TRANSMIT_BUFFER=50) void main(void) { char c; if(!tx_buffer_full()) putc(c); }</pre>
Example Files:	None
Also See:	_USE_RS232() , RCV_BUFFER_FULL() , TX_BUFFER_FULL() , RCV_BUFFER_BYTES() , GETC() , PUTC() , PRINTF() , SETUP_UART() , PUTC_SEND()

va_arg()

Syntax:	va_arg (argptr, type)
Parameters:	argptr is a special argument pointer of type va_list type – This is data type like int or char.
Returns:	The first call to va_arg after va_start return the value of the parameters after that specified by the last parameter. Successive invocations return the values of the remaining arguments in succession.
Function:	The function will return the next argument every time it is called.
Availability:	All devices.
Requires:	#INCLUDE <stdarg.h>
Examples:	<pre>int foo(int num, ...)</pre>

```
{
int sum = 0;
int i;
va_list argptr; // create special argument pointer
va_start(argptr,num); // initialize argptr
for(i=0; i<num; i++)
    sum = sum + va_arg(argptr, int);
va_end(argptr); // end variable processing
return sum;
}
```

Example Files:	None
Also See:	nargs() , va_end() , va_start()

va_end()

Syntax:	va_end(argptr)
Parameters:	argptr is a special argument pointer of type va_list.
Returns:	None
Function:	A call to the macro will end variable processing. This will facillitate a normal return from the function whose variable argument list was referred to by the expansion of va_start().
Availability:	All devices.
Requires:	#INCLUDE <stdarg.h>
Examples:	<pre>int foo(int num, ...) { int sum = 0; int i; va_list argptr; // create special argument pointer va_start(argptr,num); // initialize argptr for(i=0; i<num; i++) sum = sum + va_arg(argptr, int); va_end(argptr); // end variable processing return sum; }</pre>

Example Files:	None
Also See:	nargs() , va_start() , va_arg()

va_start

Syntax:	va_start (argptr, variable)
Parameters:	argptr is a special argument pointer of type va_list variable – The second parameter to va_start() is the name of the last parameter before the variable-argument list.
Returns:	None
Function:	The function will initialize the argptr using a call to the macro va_start().
Availability:	All devices.
Requires:	#INCLUDE <stdarg.h>
Examples:	<pre>int foo(int num, ...) { int sum = 0; int i; va_list argptr; // create special argument pointer va_start(argptr,num); // initialize argptr for(i=0; i<num; i++) sum = sum + va_arg(argptr, int); va_end(argptr); // end variable processing return sum; }</pre>
Example Files:	None
Also See:	nargs() , va_start() , va_arg()

write_bank()

Syntax:	write_bank (<i>bank, offset, value</i>)
Parameters:	<p>bank is the physical RAM bank 1-3 (depending on the device)</p> <p>offset is the offset into user RAM for that bank (starts at 0)</p> <p>value is the 8 bit data to write</p>
Returns:	undefined
Function:	Write a data byte to the user RAM area of the specified memory bank. This function may be used on some devices where full RAM access by auto variables is not efficient. For example on the PIC16C57 chip setting the pointer size to 5 bits will generate the most efficient ROM code however auto variables can not be above 1Fh. Instead of going to 8 bit pointers you can save ROM by using this function to write to the hard to reach banks. In this case the bank may be 1-3 and the offset may be 0-15.
Availability:	All devices but only useful on PCB parts with memory over 1Fh and PCM parts with memory over FFh.
Requires:	Nothing
Examples:	<pre>i=0; // Uses bank 1 as a RS232 buffer do { c=getc(); write_bank(1,i++,c); } while (c!=0x13);</pre>
Example Files:	ex_psp.c
Also See:	See the "Common Questions and Answers" section for more information.

write_configuration_memory()

Syntax:	write_configuration_memory ([offset], dataptr,count)
Parameters:	dataptr : pointer to one or more bytes

	count: a 8 bit integer offset is an optional parameter specifying the offset into configuration memory to start writing to, offset defaults to zero if not used.
Returns:	undefined
Function:	For PIC18 devices-Erases all fuses and writes count bytes from the dataptr to the configuration memory. For Enhanced16 devices - erases and write User ID memory.
Availability:	All PIC18 Flash and Enhanced16 devices
Requires:	Nothing
Examples:	<pre>int data[6]; write_configuration_memory(data, 6)</pre>
Example Files:	None
Also See:	write_program_memory() , Configuration Memory Overview

write_eeprom()

Syntax:	write_eeprom (<i>address</i> , <i>value</i>)
Parameters:	address is a (8 bit or 16 bit depending on the part) int, the range is device dependent value is an 8 bit int
Returns:	undefined
Function:	<p>Write a byte to the specified data EEPROM address. This function may take several milliseconds to execute. This works only on devices with EEPROM built into the core of the device.</p> <p>For devices with external EEPROM or with a separate EEPROM in the same package (like the 12CE671) see EX_EXTEE.c with CE51X.c, CE61X.c or CE67X.c.</p> <p>In order to allow interrupts to occur while using the write operation,</p>

	use the #DEVICE option <code>WRITE_EEPROM = NOINT</code> . This will allow interrupts to occur while the <code>write_eeprom()</code> operations is polling the done bit to check if the write operations has completed. Can be used as long as no EEPROM operations are performed during an ISR.
Availability:	This function is only available on devices with supporting hardware on chip.
Requires:	Nothing
Examples:	<pre>#define LAST_VOLUME 10 // Location in EEPROM volume++; write_eeprom(LAST_VOLUME, volume);</pre>
Example Files:	ex_intee.c , ex_extee.c , ce51x.c , ce62x.c , ce67x.c
Also See:	read_eeprom() , write_program_eeprom() , read_program_eeprom() , data Eeprom Overview

write_external_memory()

Syntax:	write_external_memory(<i>address</i>, <i>dataptr</i>, <i>count</i>)
Parameters:	address is 16 bits on PCM parts and 32 bits on PCH parts dataptr is a pointer to one or more bytes count is a 8 bit integer
Returns:	undefined
Function:	Writes count bytes to program memory from dataptr to address. Unlike <code>write_program_eeprom()</code> and <code>read_program_eeprom()</code> this function does not use any special EEPROM/FLASH write algorithm. The data is simply copied from register address space to program memory address space. This is useful for external RAM or to implement an algorithm for external flash.
Availability:	Only PCH devices.
Requires:	Nothing

Examples:

```
for(i=0x1000;i<=0x1fff;i++) {  
    value=read_adc();  
    write_external_memory(i, value, 2);  
    delay_ms(1000);  
}
```

Example Files: [ex_load.c](#), [loader.c](#)

Also See: [write_program_eeprom\(\)](#), [erase_program_eeprom\(\)](#), [Program Eeprom Overview](#)

write_extended_ram()

Syntax: `write_extended_ram (page,address,data,count);`

Parameters:

page – the page in extended RAM to write to
address – the address on the selected page to start writing to
data – pointer to the data to be written
count – the number of bytes to write (0-32768)

Returns: undefined

Function: To write data to the extended RAM of the PIC.

Availability: On devices with more then 30K of RAM.

Requires: Nothing

Examples:

```
unsigned int8 data[8] =  
{0x01,0x02,0x03,0x04,0x05,0x06,0x07,0x08};  
  
write_extended_ram(1,0x0000,data,8);
```

Example Files: None

Also See: [read_extended_ram\(\)](#), [Extended RAM Overview](#)

write_program_eeprom()

Syntax:	write_program_eeprom (<i>address, data</i>)
Parameters:	address is 16 bits on PCM parts and 32 bits on PCH parts, data is 16 bits. The least significant bit should always be 0 in PCH.
Returns:	undefined
Function:	Writes to the specified program EEPROM area. See our write_program_memory() for more information on this function.
Availability:	Only devices that allow writes to program memory.
Requires:	Nothing
Examples:	<code>write_program_eeprom(0,0x2800);</code> <code>//disables program</code>
Example Files:	ex_load.c , loader.c
Also See:	read_program_eeprom() , read_eeprom() , write_eeprom() , write_program_memory() , erase_program_eeprom() , Program Eeprom Overview

write_program_memory()

Syntax:	write_program_memory (<i>address, dataptr, count</i>);
Parameters:	address is 16 bits on PCM parts and 32 bits on PCH parts . dataptr is a pointer to one or more bytes count is a 8 bit integer on PIC16 and 16-bit for PIC18
Returns:	undefined
Function:	Writes count bytes to program memory from dataptr to address. This function is most effective when count is a multiple of FLASH_WRITE_SIZE. Whenever this function is about to write to a

	location that is a multiple of FLASH_ERASE_SIZE then an erase is performed on the whole block.
Availability:	Only devices that allow writes to program memory.
Requires:	Nothing
Examples:	<pre>for(i=0x1000;i<=0x1fff;i++) { value=read_adc(); write_program_memory(i, value, 2); delay_ms(1000); }</pre>
Example Files:	loader.c
Also See:	write_program_eeprom , erase_program_eeprom , Program Eeprom Overview
Additional Notes:	<p>Clarification about the functions to write to program memory:</p> <p>In order to get the desired results while using write_program_memory(), the block of memory being written to needs to first be read in order to save any other variables currently stored there, then erased to clear all values in the block before the new values can be written. This is because the write_program_memory() function does not save any values in memory and will only erase the block if the first location is written to. If this process is not followed, when new values are written to the block, they will appear as garbage values.</p> <p>For chips where getenv("FLASH_ERASE_SIZE") > getenv("FLASH_WRITE_SIZE")</p> <p>write_program_eeprom() - Writes 2 bytes, does not erase (use erase_program_eeprom())</p> <p>write_program_memory() - Writes any number of bytes, will erase a block whenever the first (lowest) byte in a block is written to. If the first address is not the start of a block that block is not erased.</p> <p>erase_program_eeprom() - Will erase a block. The lowest address bits are not used.</p> <p>For chips where</p>

```
getenv("FLASH_ERASE_SIZE") = getenv("FLASH_WRITE_SIZE")
```

`write_program_eeprom()` - Writes 2 bytes, no erase is needed.

`write_program_memory()` - Writes any number of bytes, bytes outside the range of the write block are not changed. No erase is needed.

`erase_program_eeprom()` - Not available

zdc_status()

Syntax: `value=zcd_status()`

Parameters: *None*

`value` - the status of the ZCD module. The following defines are made in the device's header file and are as follows:

Returns:

- `ZCD_IS_SINKING`
- `ZCD_IS_SOURCING`

Function:

To determine if the Zero-Cross Detection (ZCD) module is currently sinking or sourcing current. If the ZCD module is setup to have the output polarity inverted, the value return will be reversed.

Availability: All devices with a ZCD module.

Examples: `value=zcd_status() :`

Example Files: *None*

Also See: [setup_zcd\(\)](#)

STANDARD C INCLUDE FILES

errno.h

errno.h	
EDOM	Domain error value
ERANGE	Range error value
errno	error value

float.h

float.h	
FLT_RADIX:	Radix of the exponent representation
FLT_MANT_DIG:	Number of base digits in the floating point significant
FLT_DIG:	Number of decimal digits, q, such that any floating point number with q decimal digits can be rounded into a floating point number with p radix b digits and back again without change to the q decimal digits.
FLT_MIN_EXP:	Minimum negative integer such that FLT_RADIX raised to that power minus 1 is a normalized floating-point number.
FLT_MIN_10_EXP:	Minimum negative integer such that 10 raised to that power is in the range of normalized floating-point numbers.
FLT_MAX_EXP:	Maximum negative integer such that FLT_RADIX raised to that power minus 1 is a representable finite floating-point number.
FLT_MAX_10_EXP:	Maximum negative integer such that 10 raised to that power is in the range representable finite floating-point numbers.
FLT_MAX:	Maximum representable finite floating point number.
FLT_EPSILON:	The difference between 1 and the least value greater than 1 that is representable in the given floating point type.
FLT_MIN:	Minimum normalized positive floating point number
DBL_MANT_DIG:	Number of base digits in the floating point significant
DBL_DIG:	Number of decimal digits, q, such that any floating point number

	with q decimal digits can be rounded into a floating point number with p radix b digits and back again without change to the q decimal digits.
DBL_MIN_EXP:	Minimum negative integer such that FLT_RADIX raised to that power minus 1 is a normalized floating point number.
DBL_MIN_10_EXP:	Minimum negative integer such that 10 raised to that power is in the range of normalized floating point numbers.
DBL_MAX_EXP:	Maximum negative integer such that FLT_RADIX raised to that power minus 1 is a representable finite floating point number.
DBL_MAX_10_EXP:	Maximum negative integer such that 10 raised to that power is in the range of representable finite floating point numbers.
DBL_MAX:	Maximum representable finite floating point number.
DBL_EPSILON:	The difference between 1 and the least value greater than 1 that is representable in the given floating point type.
DBL_MIN:	Minimum normalized positive floating point number.
LDBL_MANT_DIG:	Number of base digits in the floating point significant
LDBL_DIG:	Number of decimal digits, q, such that any floating point number with q decimal digits can be rounded into a floating point number with p radix b digits and back again without change to the q decimal digits.
LDBL_MIN_EXP:	Minimum negative integer such that FLT_RADIX raised to that power minus 1 is a normalized floating-point number.
LDBL_MIN_10_EXP:	Minimum negative integer such that 10 raised to that power is in the range of normalized floating-point numbers.
LDBL_MAX_EXP:	Maximum negative integer such that FLT_RADIX raised to that power minus 1 is a representable finite floating-point number.
LDBL_MAX_10_EXP:	Maximum negative integer such that 10 raised to that power is in the range of representable finite floating-point numbers.
LDBL_MAX:	Maximum representable finite floating point number.
LDBL_EPSILON:	The difference between 1 and the least value greater than 1 that is representable in the given floating point type.
LDBL_MIN:	Minimum normalized positive floating point number.

limits.h

limits.h	
CHAR_BIT:	Number of bits for the smallest object that is not a bit_field.
SCHAR_MIN:	Minimum value for an object of type signed char
SCHAR_MAX:	Maximum value for an object of type signed char
UCHAR_MAX:	Maximum value for an object of type unsigned char

CHAR_MIN:	Minimum value for an object of type char(unsigned)
CHAR_MAX:	Maximum value for an object of type char(unsigned)
MB_LEN_MAX:	Maximum number of bytes in a multibyte character.
SHRT_MIN:	Minimum value for an object of type short int
SHRT_MAX:	Maximum value for an object of type short int
USHRT_MAX:	Maximum value for an object of type unsigned short int
INT_MIN:	Minimum value for an object of type signed int
INT_MAX:	Maximum value for an object of type signed int
UINT_MAX:	Maximum value for an object of type unsigned int
LONG_MIN:	Minimum value for an object of type signed long int
LONG_MAX:	Maximum value for an object of type signed long int
ULONG_MAX:	Maximum value for an object of type unsigned long int

locale.h

locale.h	
locale.h	(Localization not supported)
lconv	localization structure
SETLOCALE()	returns null
LOCALCONV()	returns clocale

setjmp.h

setjmp.h	
jmp_buf:	An array used by the following functions
setjmp:	Marks a return point for the next longjmp
longjmp:	Jumps to the last marked point

stddef.h

stddef.h	
ptrdiff_t:	The basic type of a pointer

size_t:	The type of the sizeof operator (int)
wchar_t	The type of the largest character set supported (char) (8 bits)
NULL	A null pointer (0)

stdio.h

stdio.h	
stderr	The standard error s stream (USE RS232 specified as stream or the first USE RS232)
stdout	The standard output stream (USE RS232 specified as stream last USE RS232)
stdin	The standard input s stream (USE RS232 specified as stream last USE RS232)

stdlib.h

stdlib.h	
div_t	structure type that contains two signed integers (quot and rem).
ldiv_t	structure type that contains two signed longs (quot and rem)
EXIT_FAILURE	returns 1
EXIT_SUCCESS	returns 0
RAND_MAX-	
MBCUR_MAX-	1
SYSTEM()	Returns 0(not supported)
Multibyte character and	Multibyte characters not supported
string functions:	
MBLEN()	Returns the length of the string.
MBTOWC()	Returns 1.
WCTOMB()	Returns 1.
MBSTOWCS()	Returns length of string.
WBSTOMBS()	Returns length of string.

Stdlib.h functions included just for compliance with ANSI C.

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