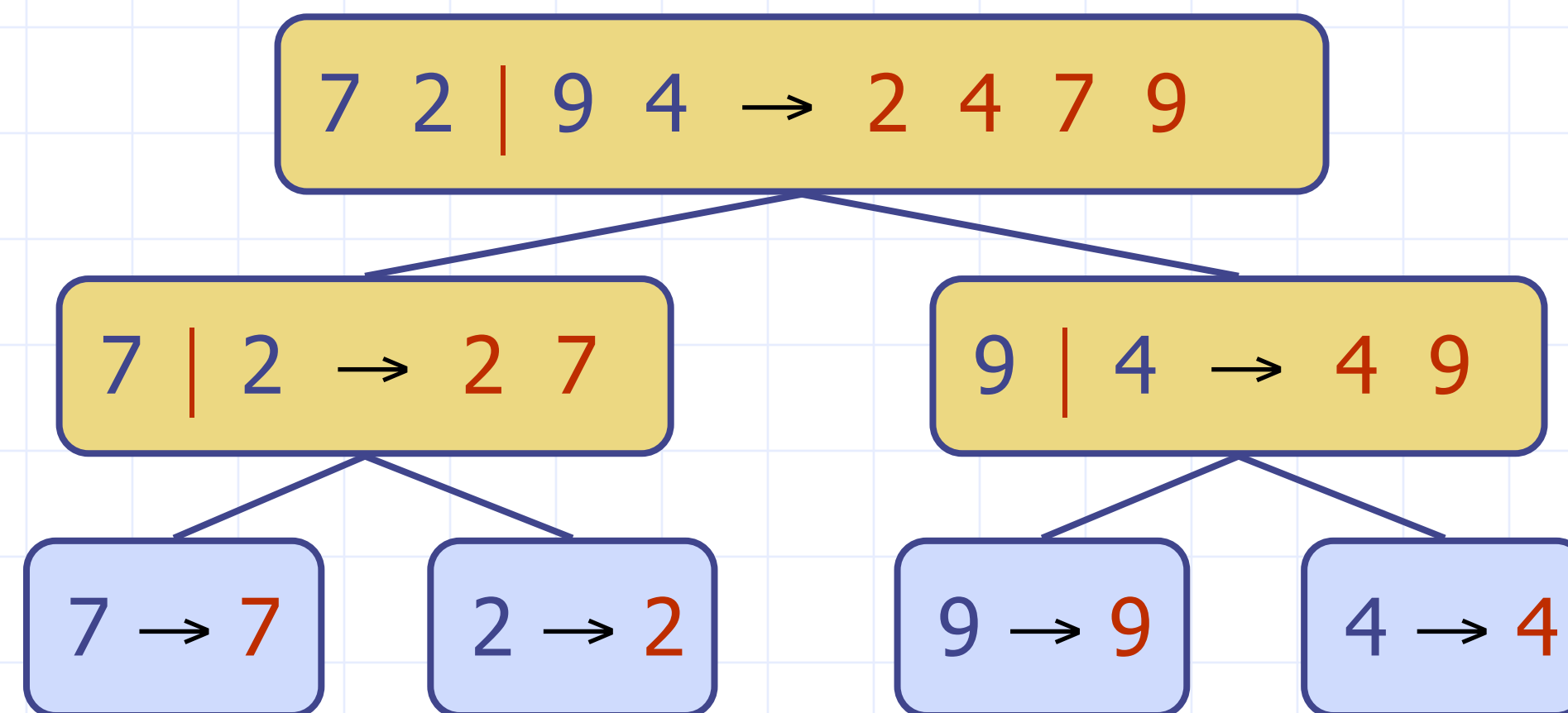


# Merge Sort & Quick Sort



# Merge-Sort

- Merge-sort on an input sequence  $S$  with  $n$  elements consists of three steps:
  - **Divide**: partition  $S$  into two sequences  $S_1$  and  $S_2$  of about  $n/2$  elements each
  - **Recursive step**: recursively sort  $S_1$  and  $S_2$
  - **Conquer**: merge  $S_1$  and  $S_2$  into a unique sorted sequence

**Algorithm** *mergeSort*( $S$ )

```
if  $S.size() \leq 1$ 
    return;
else
     $(S_1, S_2) \leftarrow partition(S, S.size()/2)$ 
    mergeSort( $S_1$ )
    mergeSort( $S_2$ )
     $S \leftarrow merge(S_1, S_2)$ 
```

- This is known as a **divide and conquer algorithm**.

# Merging Two Sorted Sequences

- The conquer step of merge-sort consists of merging two sorted sequences  $A$  and  $B$  into a sorted sequence  $S$  containing the union of the elements of  $A$  and  $B$
- Merging two sorted sequences, each with  $n/2$  elements and implemented by means of a doubly linked list, takes  $O(n)$  time

**Algorithm** *merge*( $A, B$ )

$S \leftarrow$  empty sequence

**while**  $!A.empty() \ \&\& \ !B.empty()$

**if**  $A.front() < B.front()$

$S.addBack(A.front()); A.eraseFront();$

**else**

$S.addBack(B.front()); B.eraseFront();$

**while**  $!A.empty()$

$S.addBack(A.front()); A.eraseFront();$

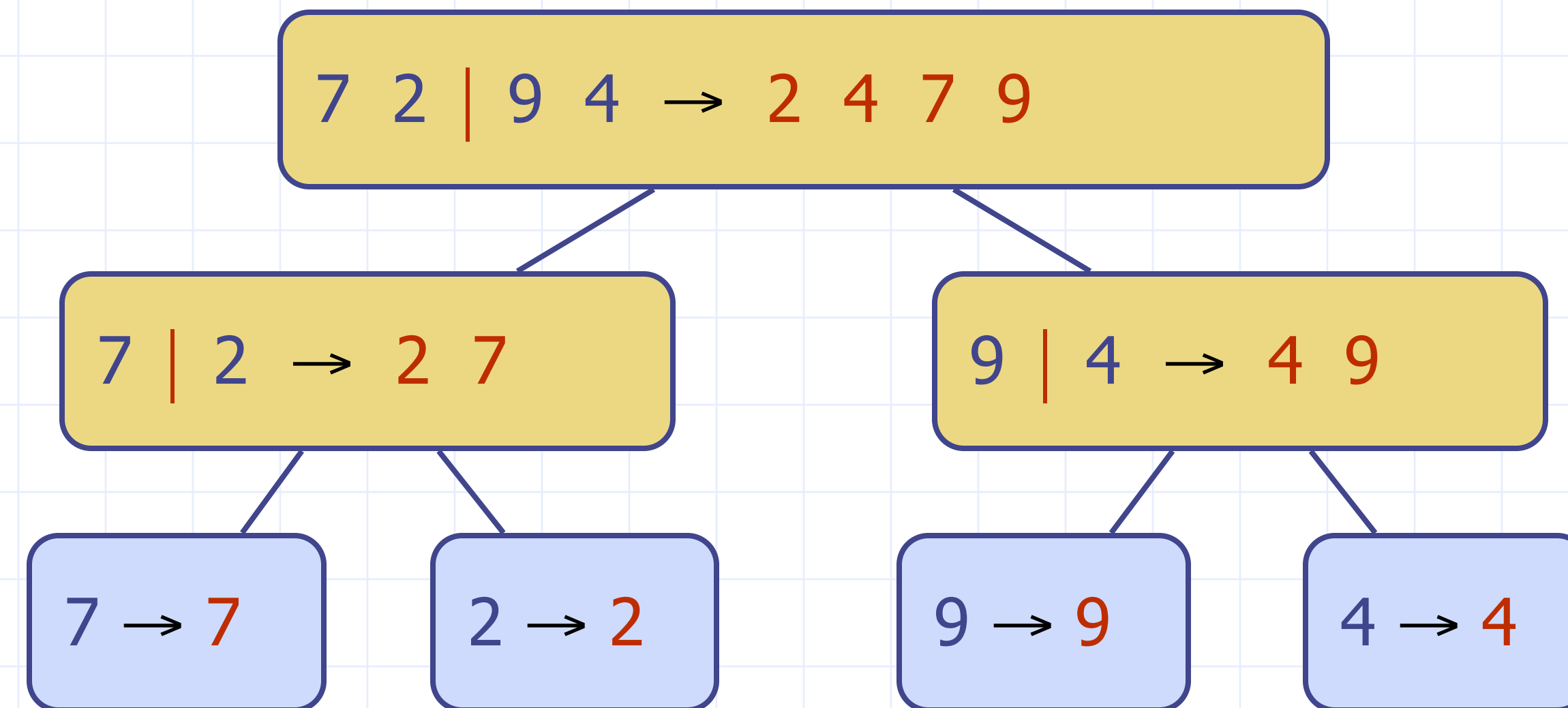
**while**  $!B.empty()$

$S.addBack(B.front()); B.eraseFront();$

**return**  $S$

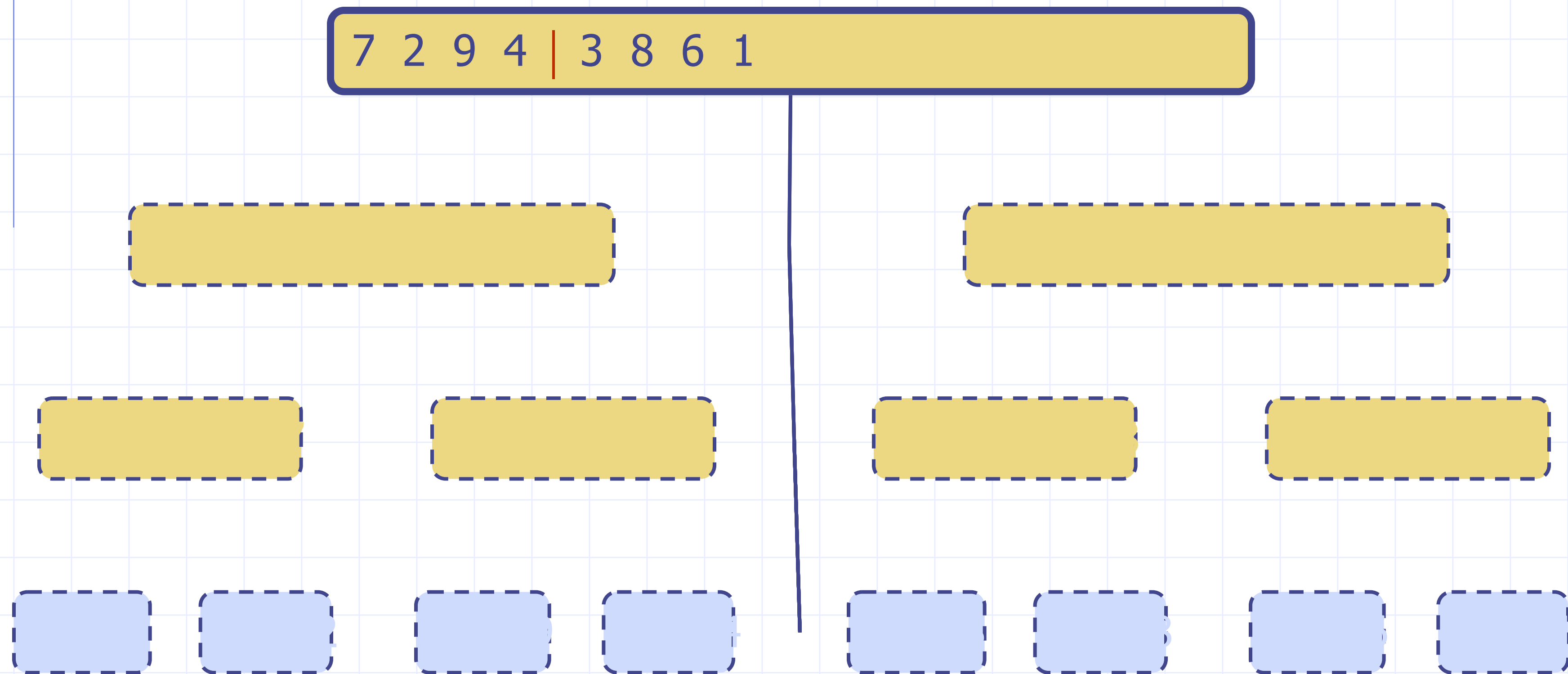
# Merge-Sort Tree

- An execution of merge-sort is depicted by a “binary tree”
  - each “node” represents a recursive call of merge-sort and stores
    - ◆ unsorted sequence before the execution and its partition
    - ◆ sorted sequence at the end of the execution



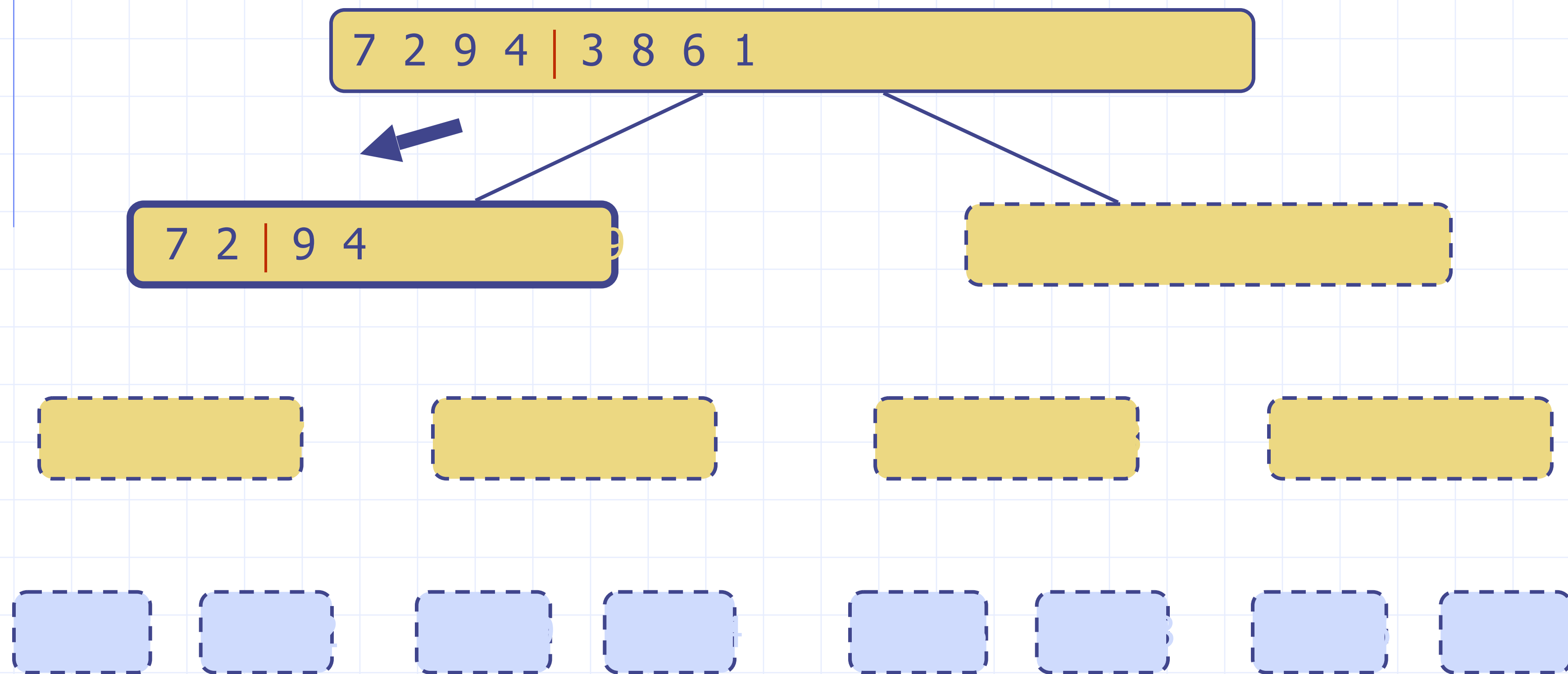
# Execution Example

- Partition - recursively



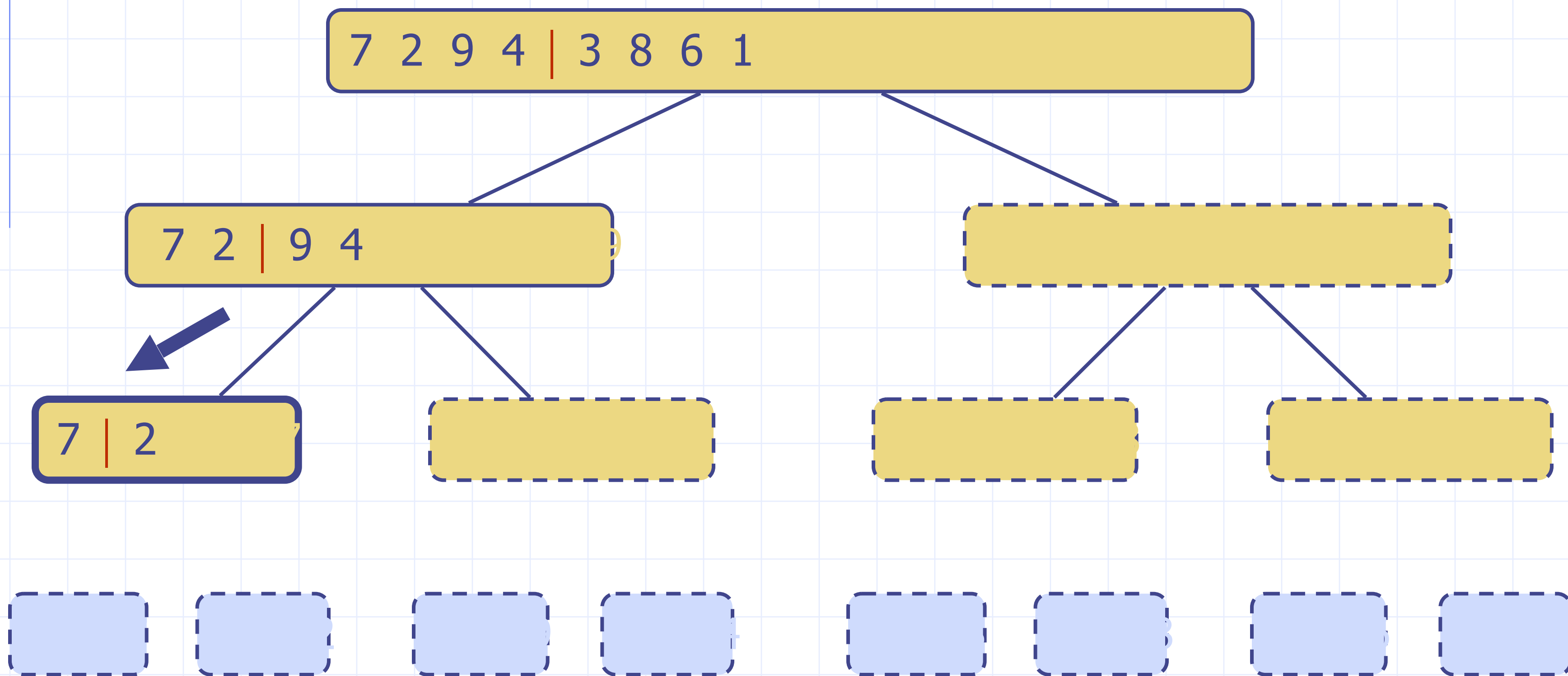
# Execution Example (cont.)

- Recursive call, partition



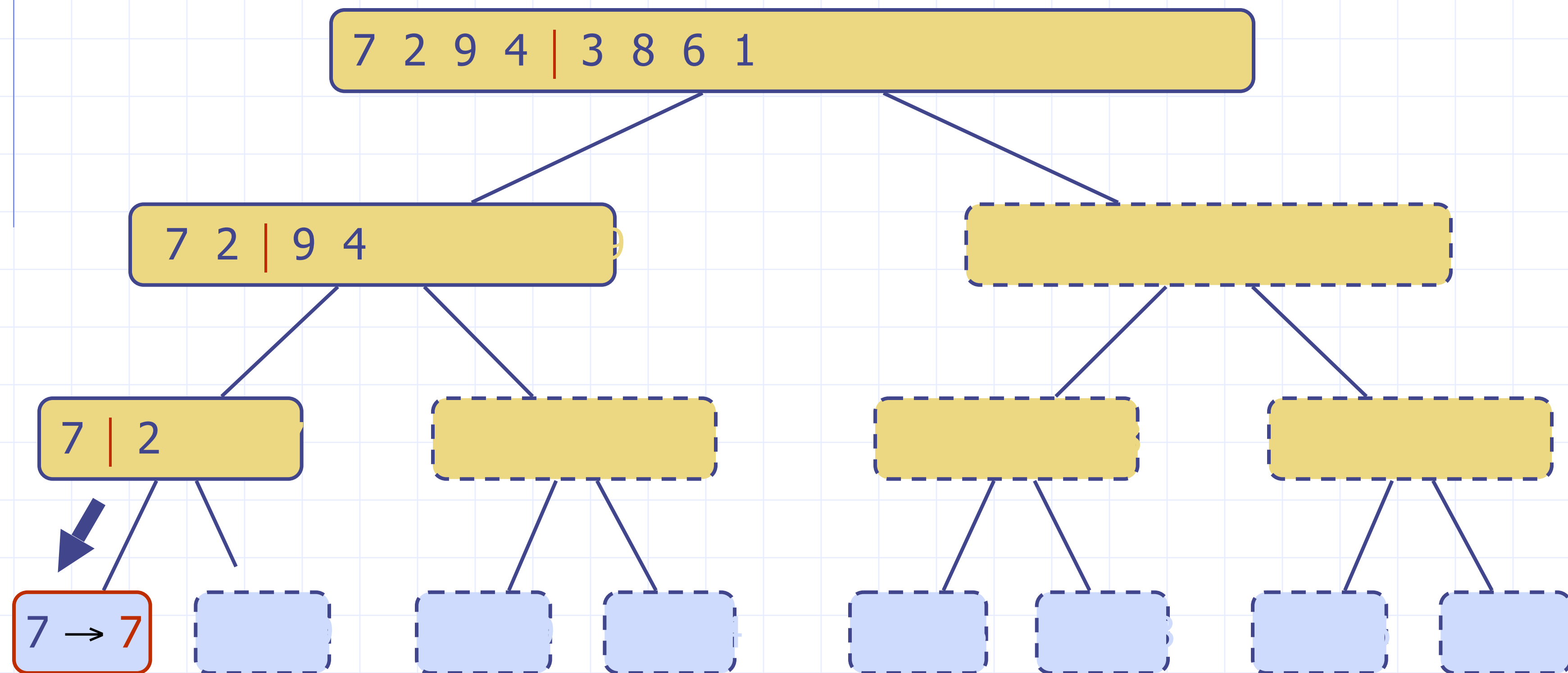
# Execution Example (cont.)

- Recursive call, partition



# Execution Example (cont.)

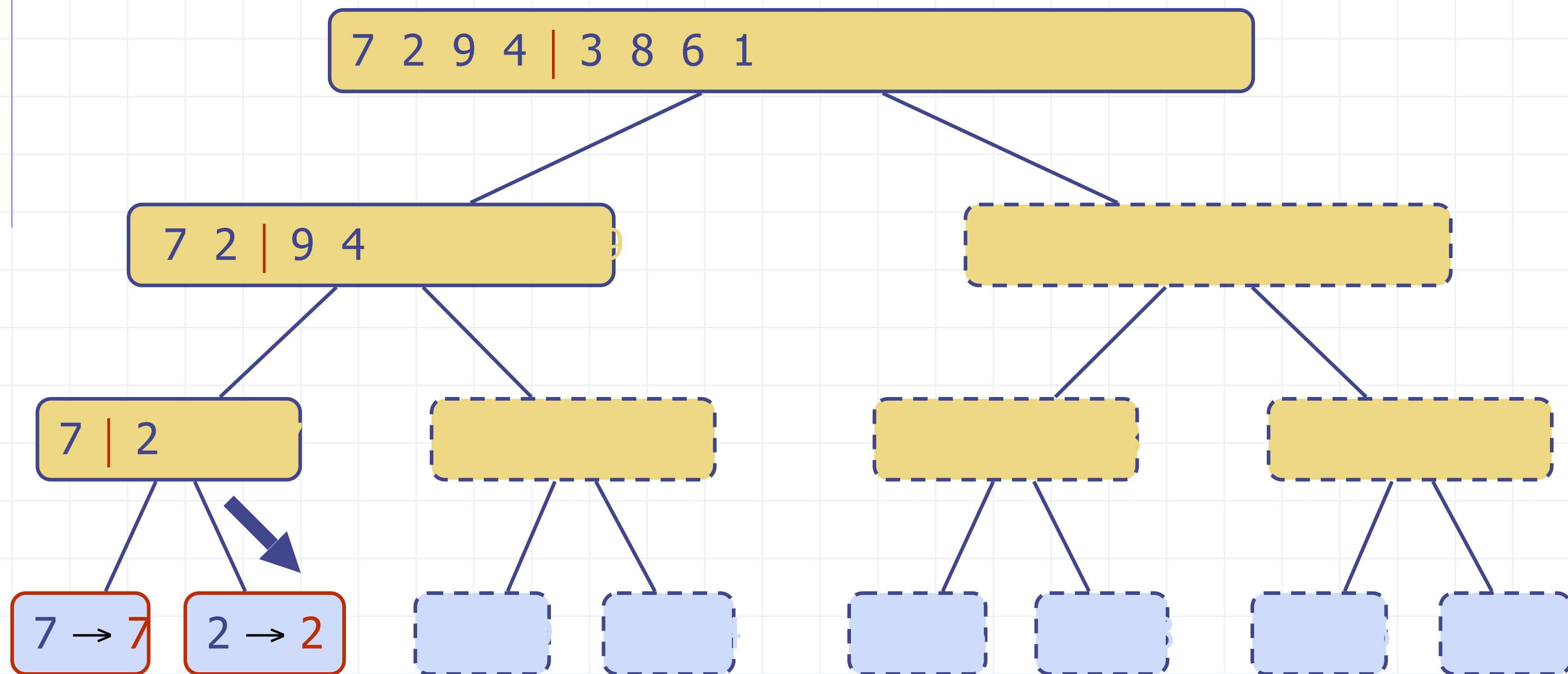
- Recursive call, base case





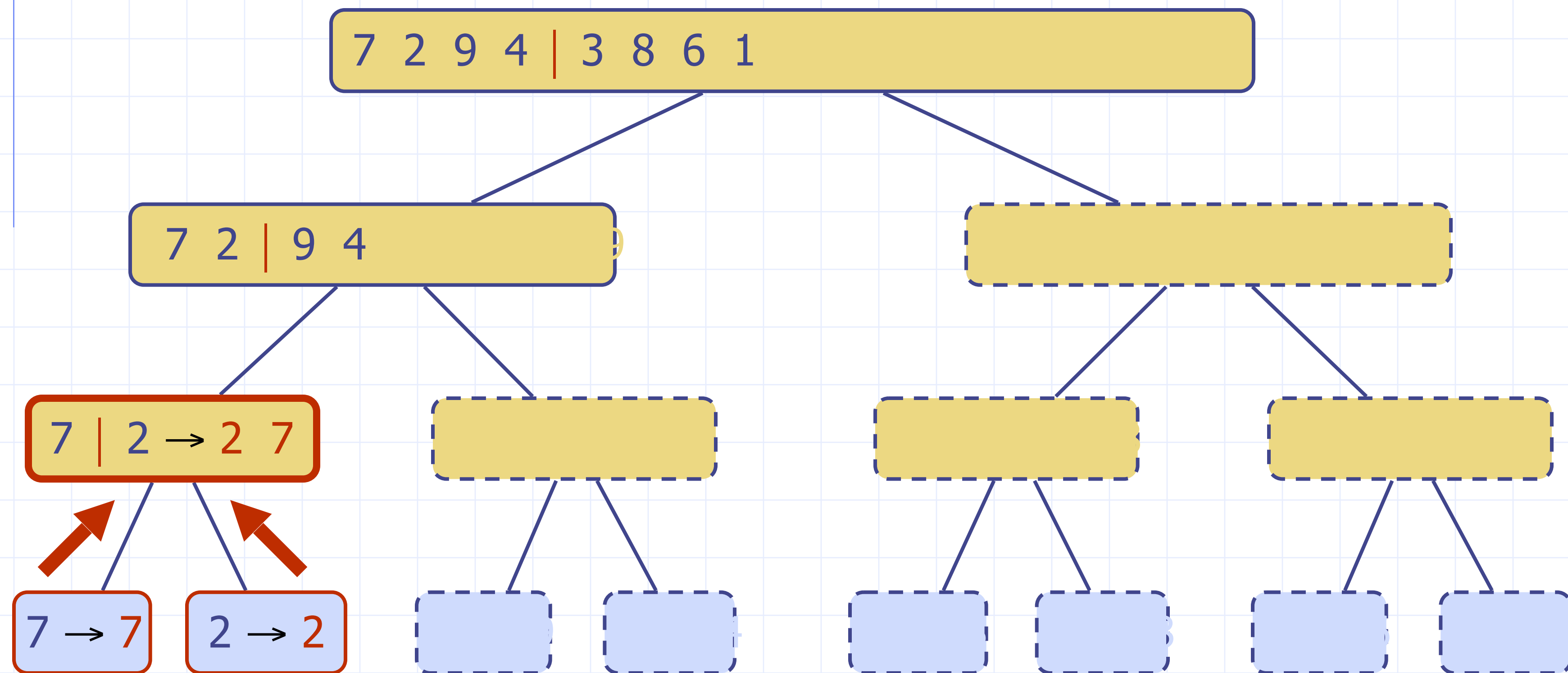
# Execution Example (cont.)

- Recursive call, base case



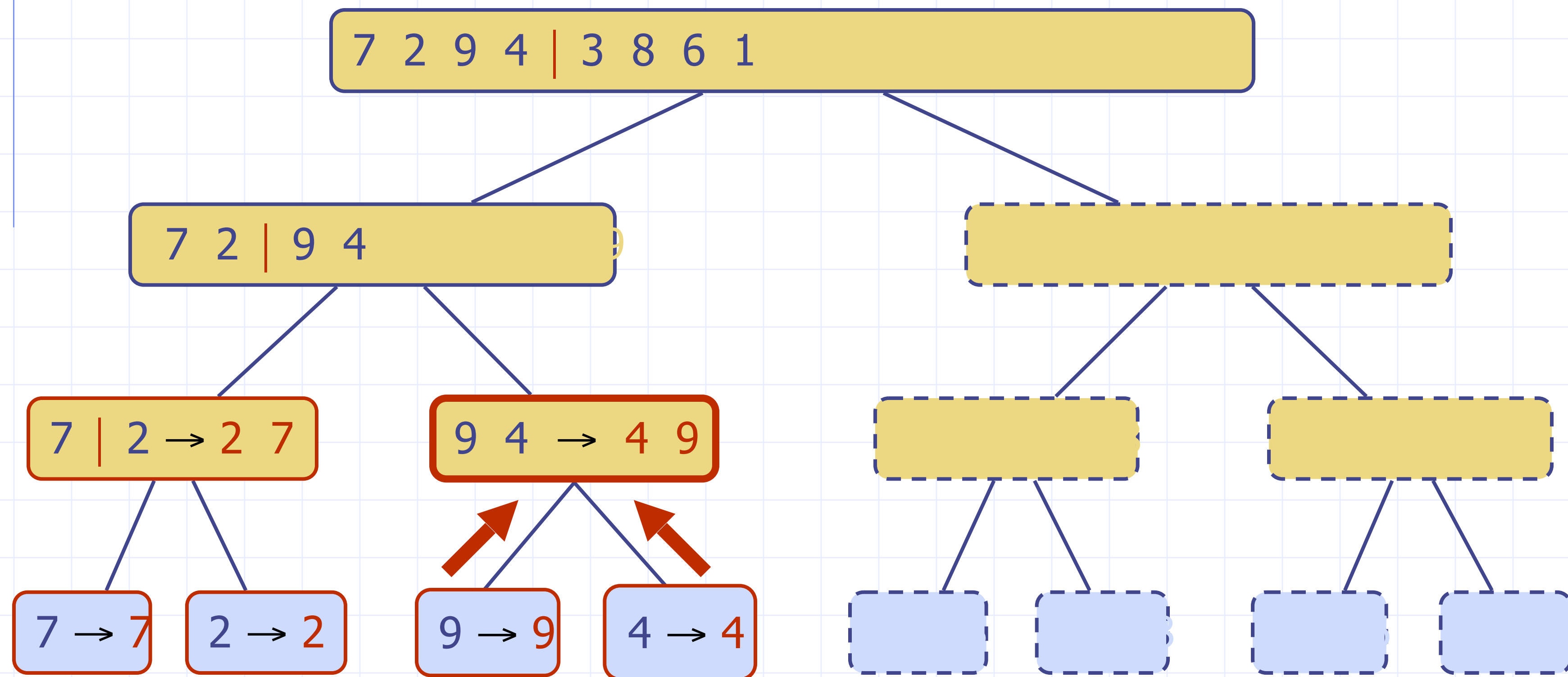
# Execution Example (cont.)

## ■ Merge



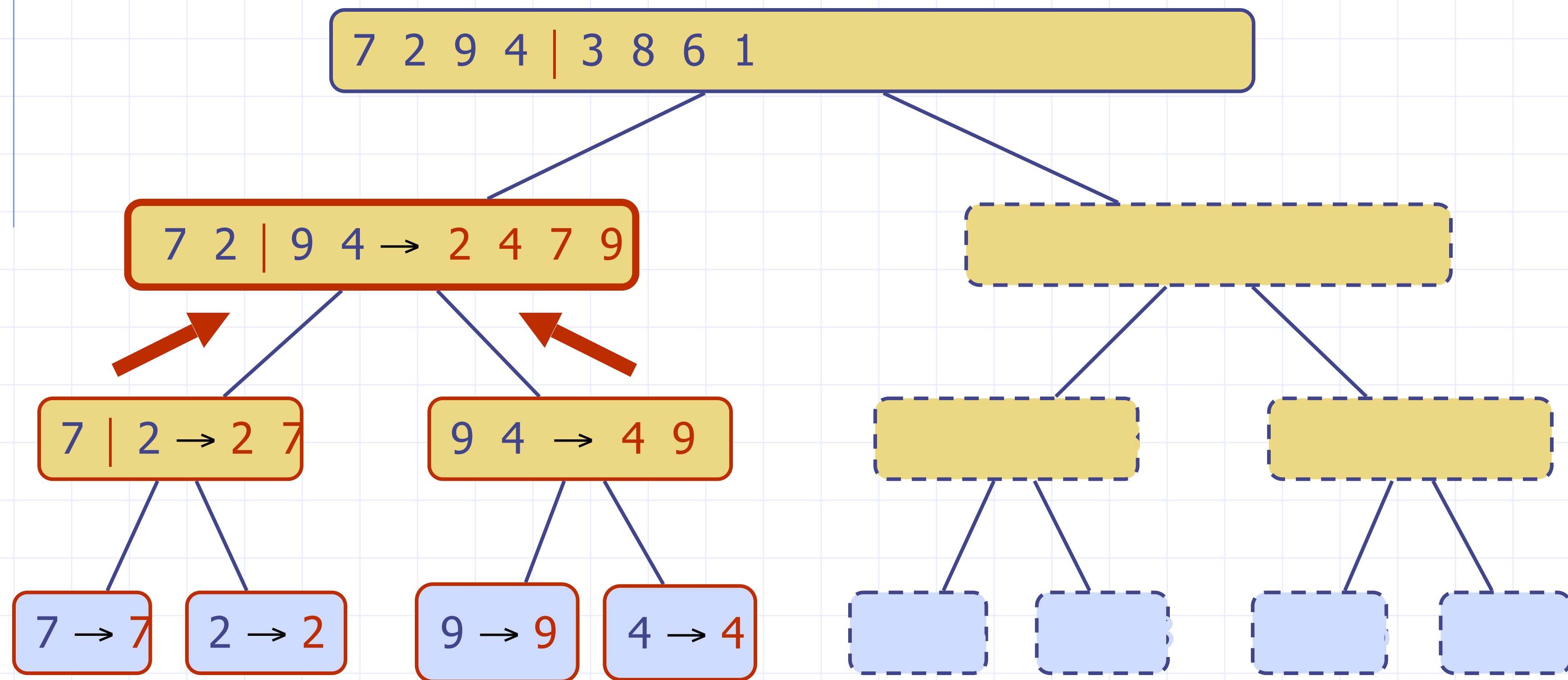
# Execution Example (cont.)

- Recursive call, ..., base case, merge



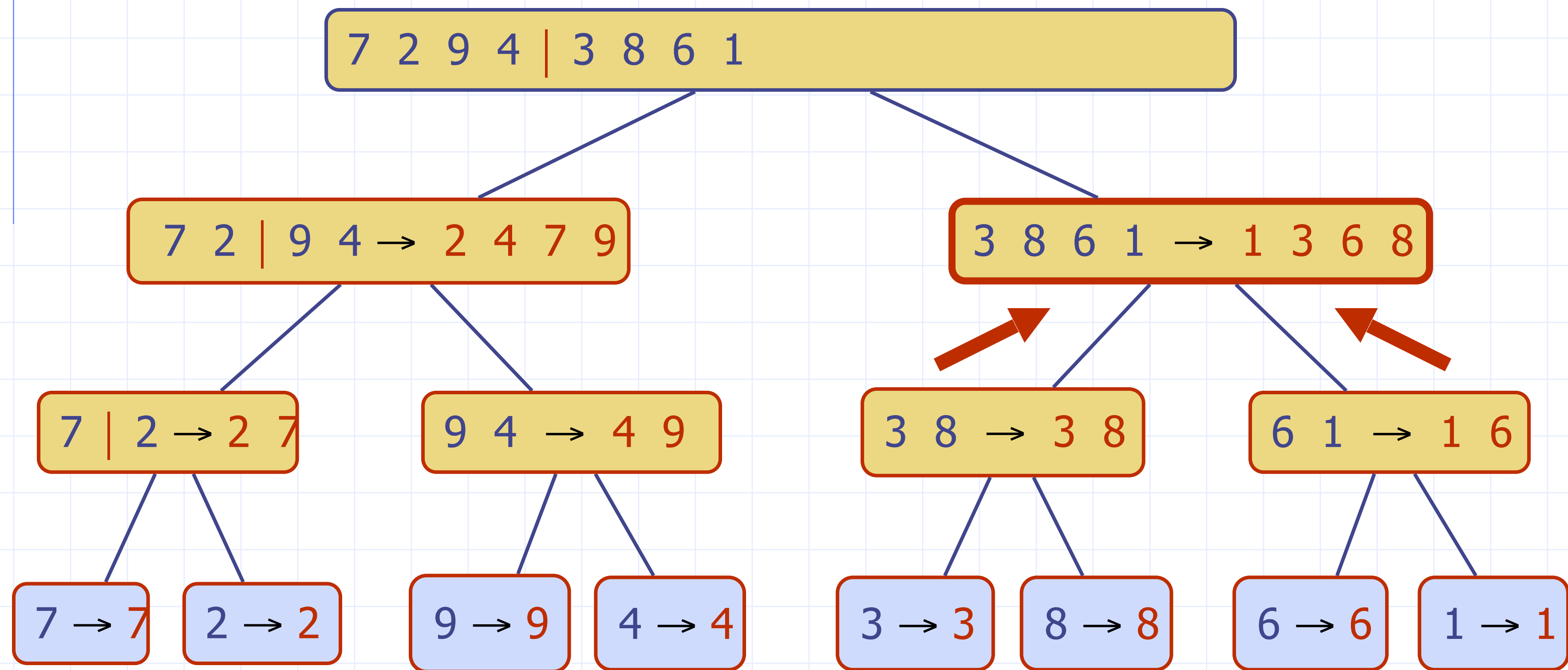
# Execution Example (cont.)

## ■ Merge



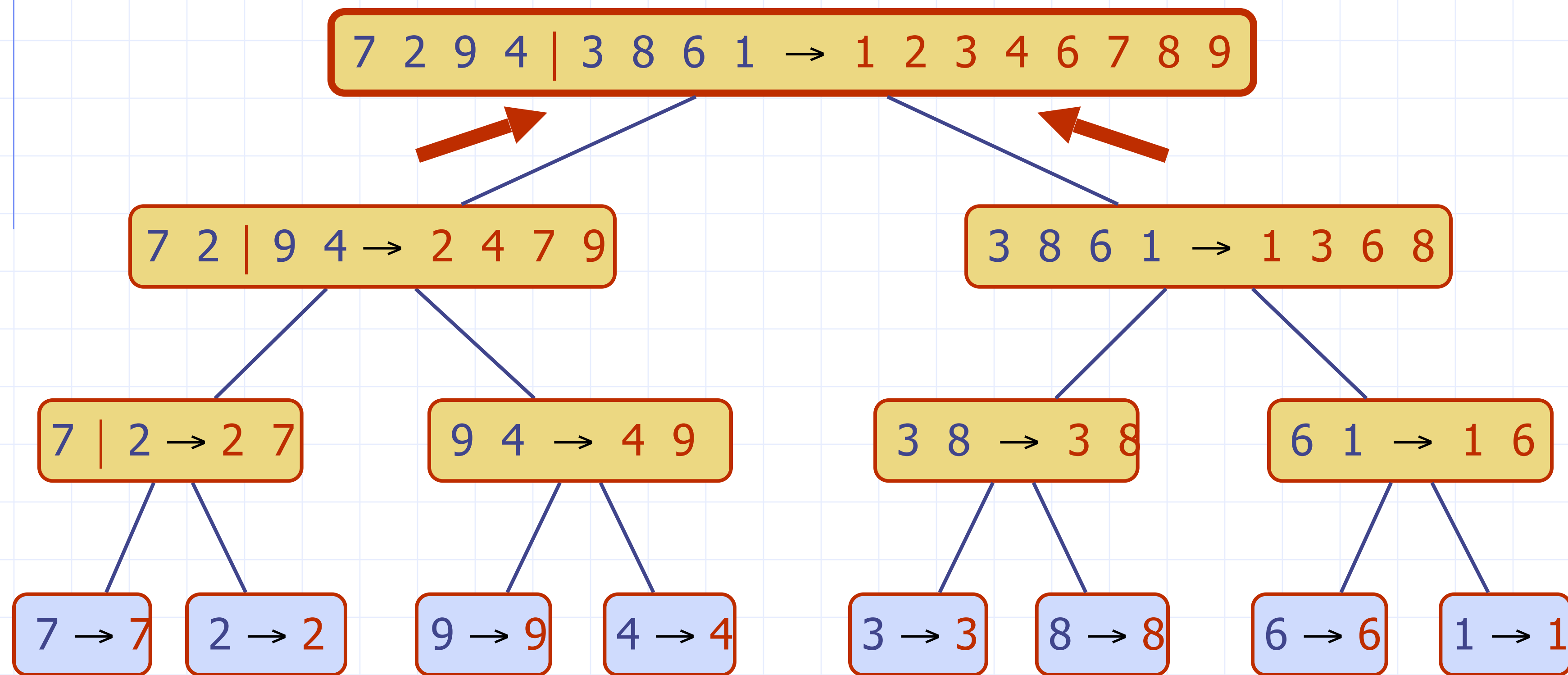
# Execution Example (cont.)

◆ Recursive call, ..., merge, merge



# Execution Example (cont.)

## ◆ Merge



# Analysis of Merge-Sort

- The height  $h$  of the merge-sort tree is  $O(\log n)$ 
  - at each recursive call we divide in half the sequence,
- The overall amount of work done at the nodes of depth  $i$  is  $O(n)$ 
  - we partition and merge  $2^i$  sequences of size  $n/2^i$
  - we make  $2^{i+1}$  recursive calls
- Thus, the total running time of merge-sort is  $O(n \log n)$

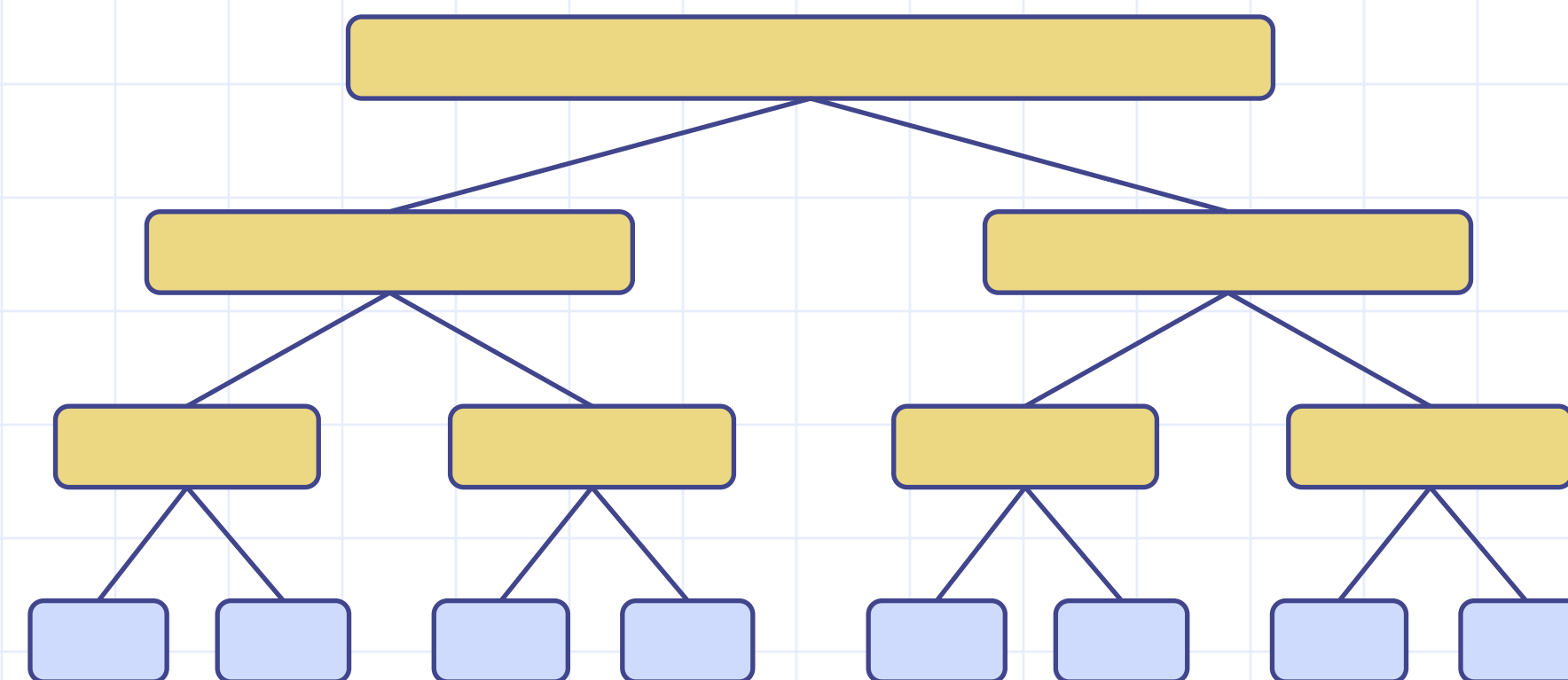
depth #seqs size

0 1  $n$

1 2  $n/2$

$i$   $2^i$   $n/2^i$

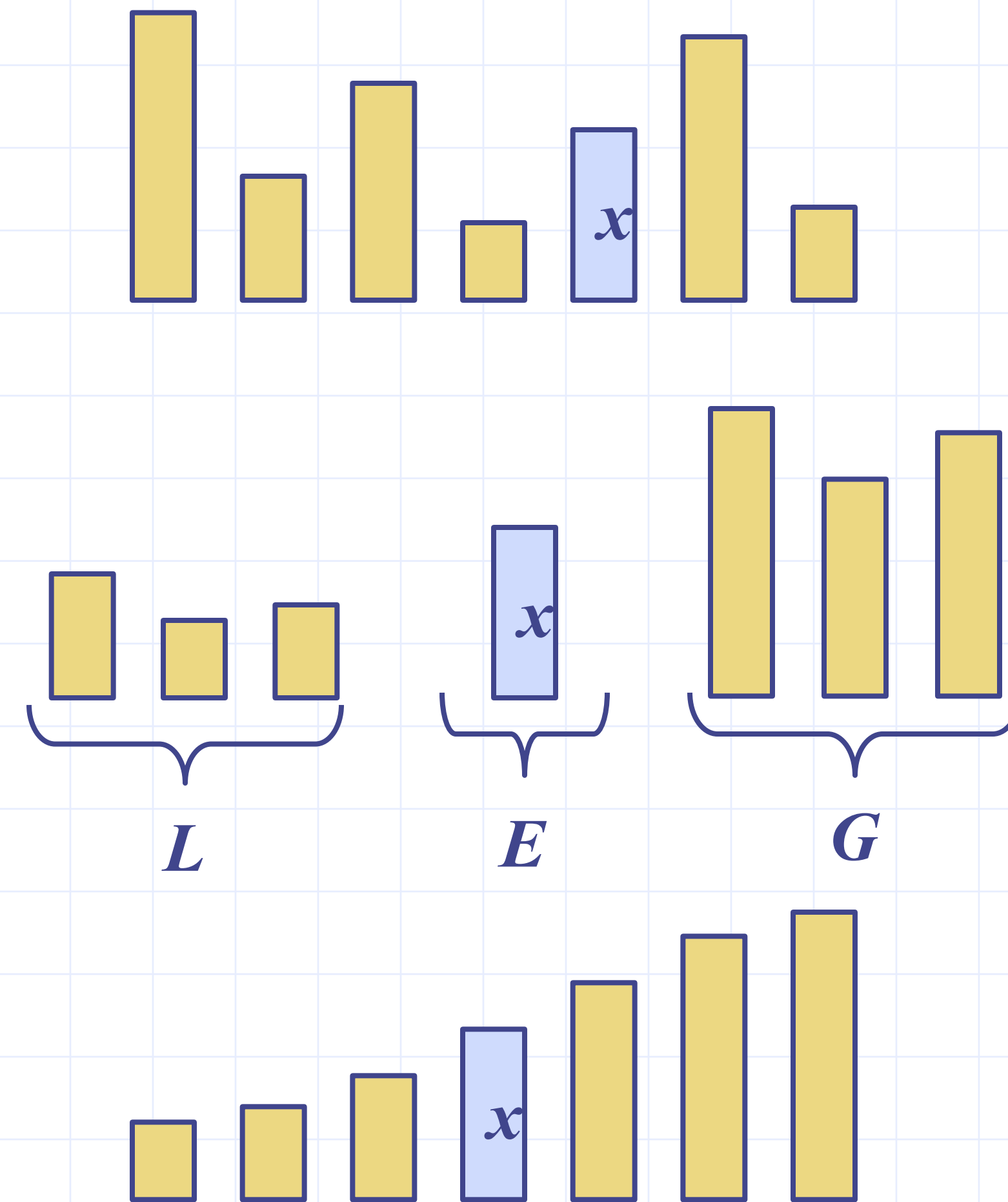
... ...



Merge Sort

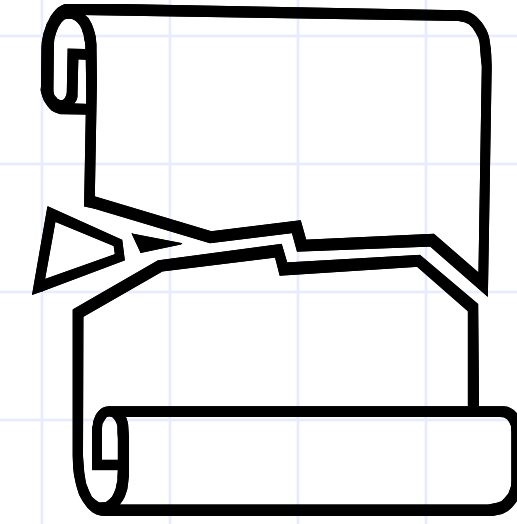
# Quick-Sort

- **Quick-sort** is a randomized sorting algorithm based on the divide-and-conquer paradigm:
  - **Divide**: pick a random element  $x$  (called **pivot**) and partition  $S$  into
    - $L$  : elements less than  $x$
    - $E$  : elements equal  $x$
    - $G$  : elements greater than  $x$
  - **Recurse**: sort  $L$  and  $G$
  - **Conquer**: join  $L$ ,  $E$  and  $G$ 
    - *this turns out to be trivial!*





# Partition



- Partition the input sequence as follows:
  - We remove, in turn, each element  $y$  from  $S$  and
  - We insert  $y$  into  $L$ ,  $E$  or  $G$ , depending on the result of the comparison with the pivot  $p$
- Each insertion and removal is at the beginning or at the end of a sequence, and hence takes  $O(1)$  time
- Thus, the partition step of quick-sort takes  $O(n)$  time

**Algorithm** *partition*( $S, p$ )

$L, E, G \leftarrow$  empty sequences

$x \leftarrow S.erase(p)$

**while**  $\neg S.empty()$

$y \leftarrow S.eraseFront()$

**if**  $y < x$

$L.insertBack(y)$

**else if**  $y = x$

$E.insertBack(y)$

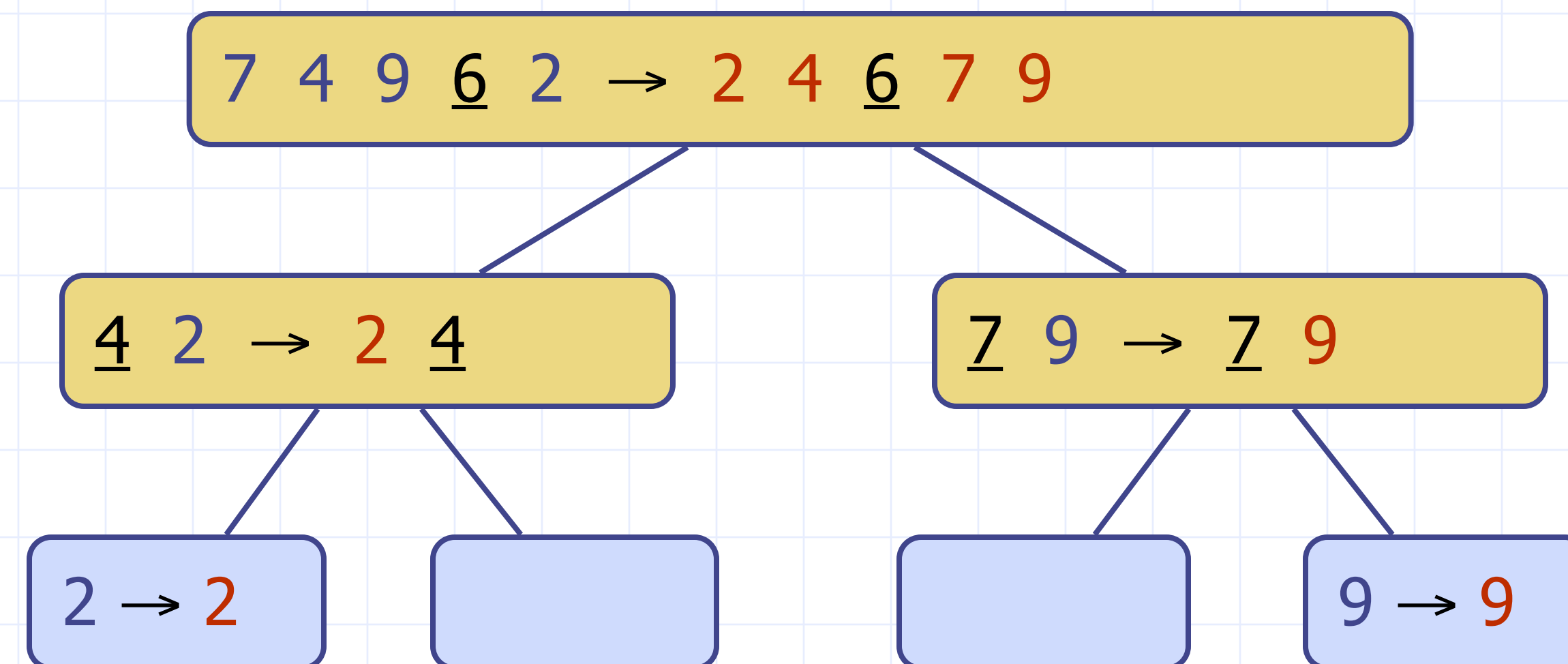
**else**  $\{ y > x \}$

$G.insertBack(y)$

**return**  $L, E, G$

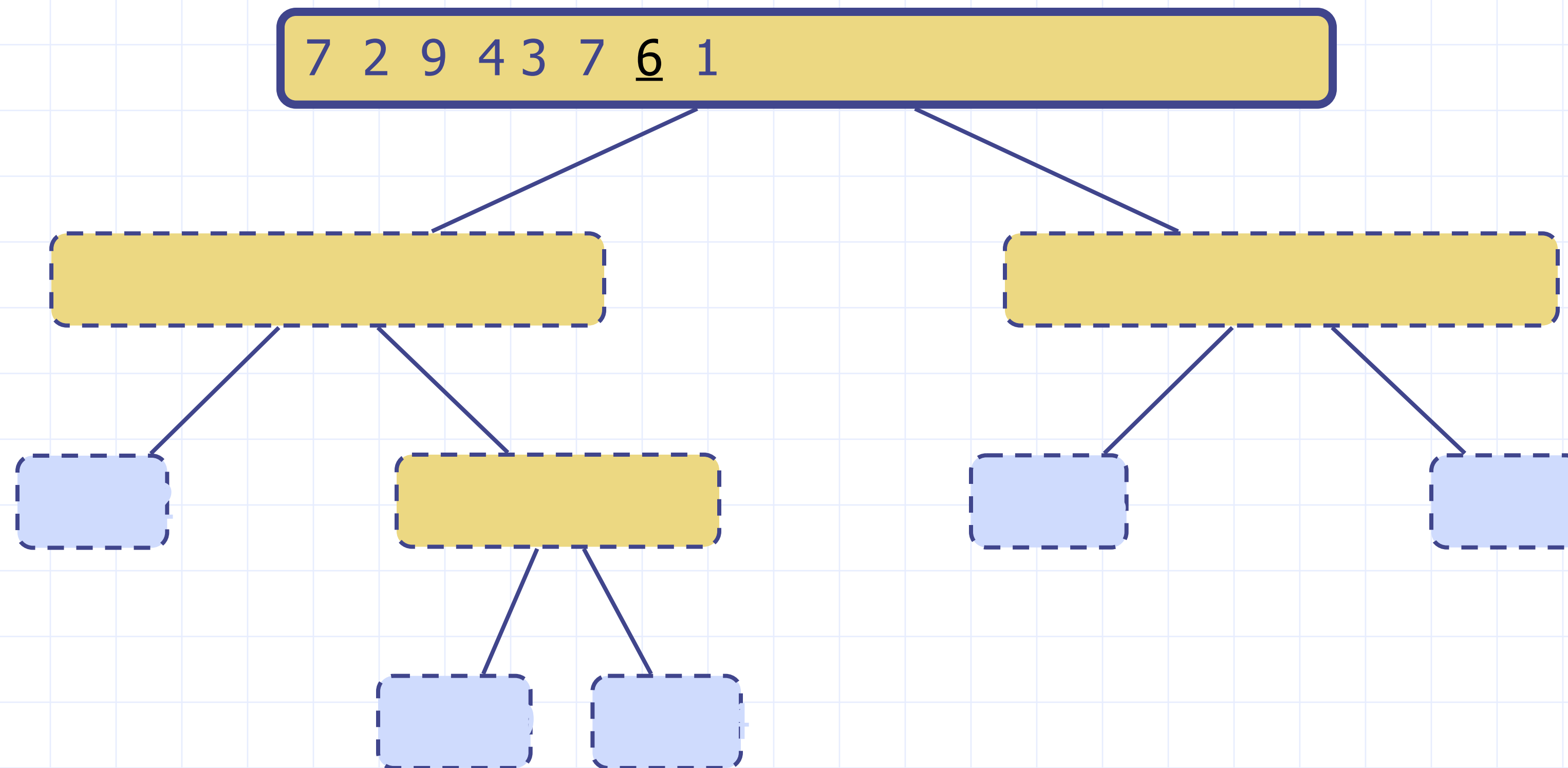
# Quick-Sort Tree

- An execution of quick-sort is depicted by a binary tree
  - Each node represents a recursive call of quick-sort and stores
    - Unsorted sequence before the execution and its pivot
    - Sorted sequence at the end of the execution
  - The root is the initial call
  - The leaves are calls on subsequences of size 0 or 1



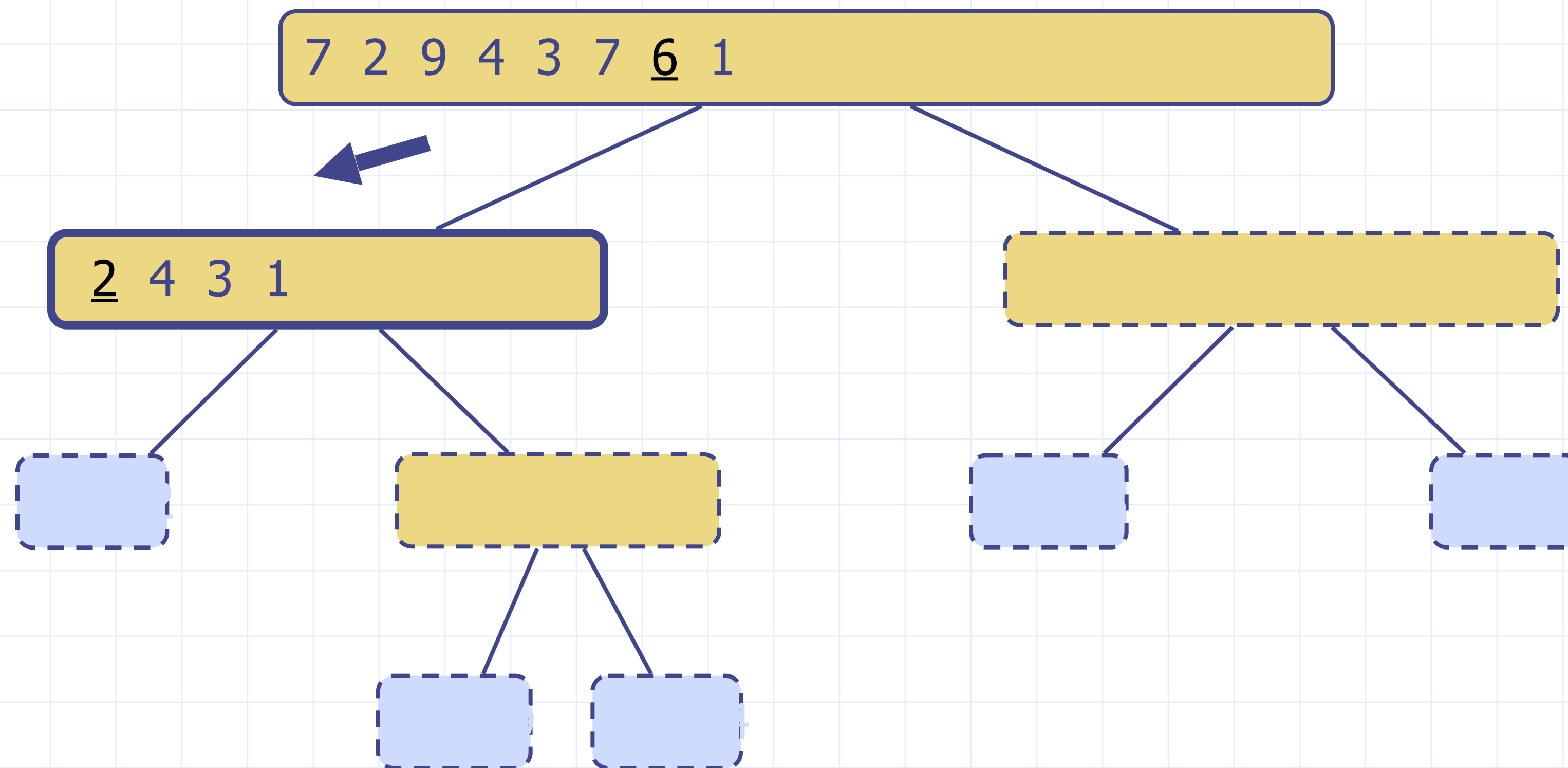
# Execution Example

- Pivot selection



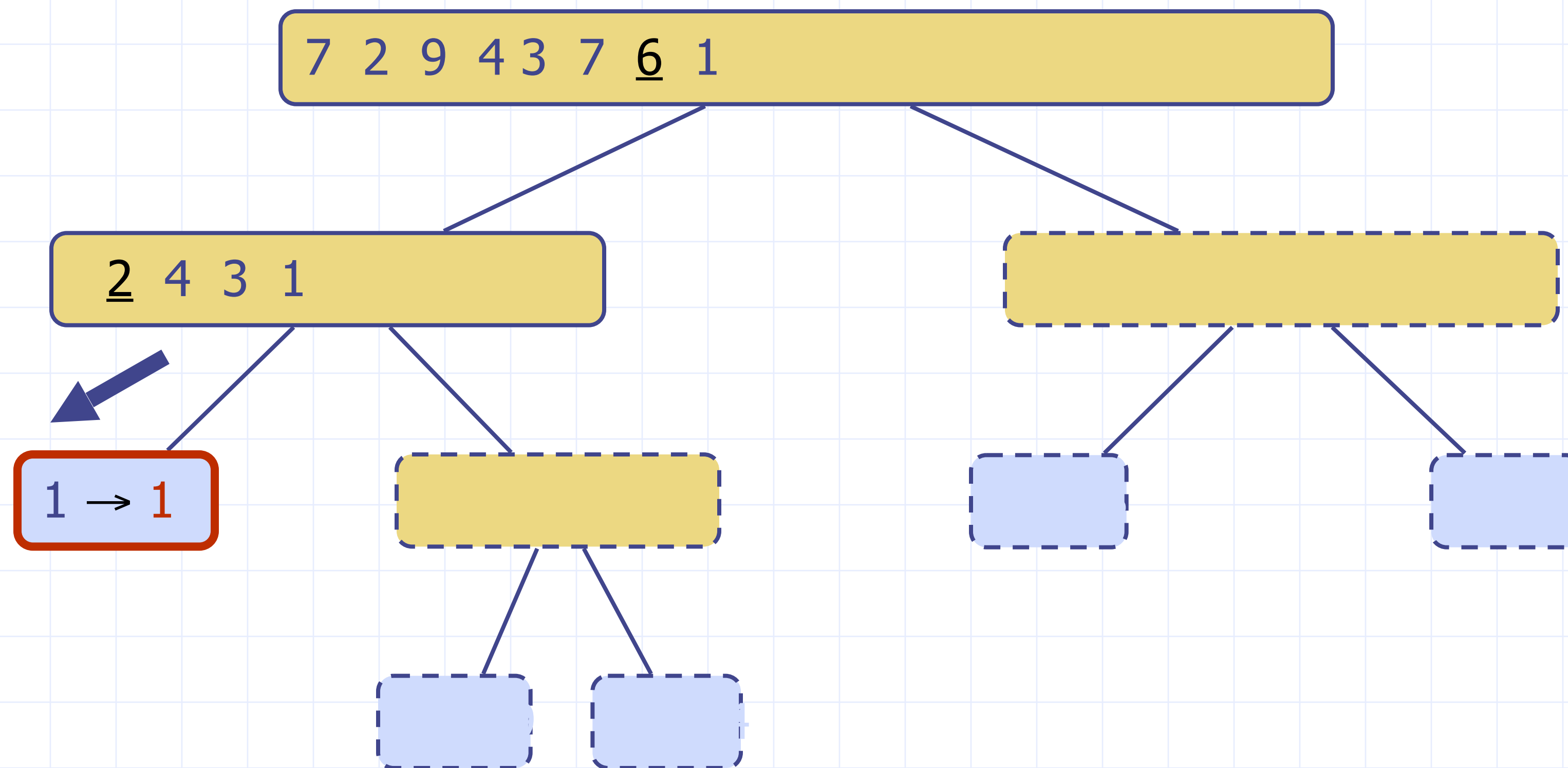
# Execution Example (cont.)

- Partition, recursive call, pivot selection



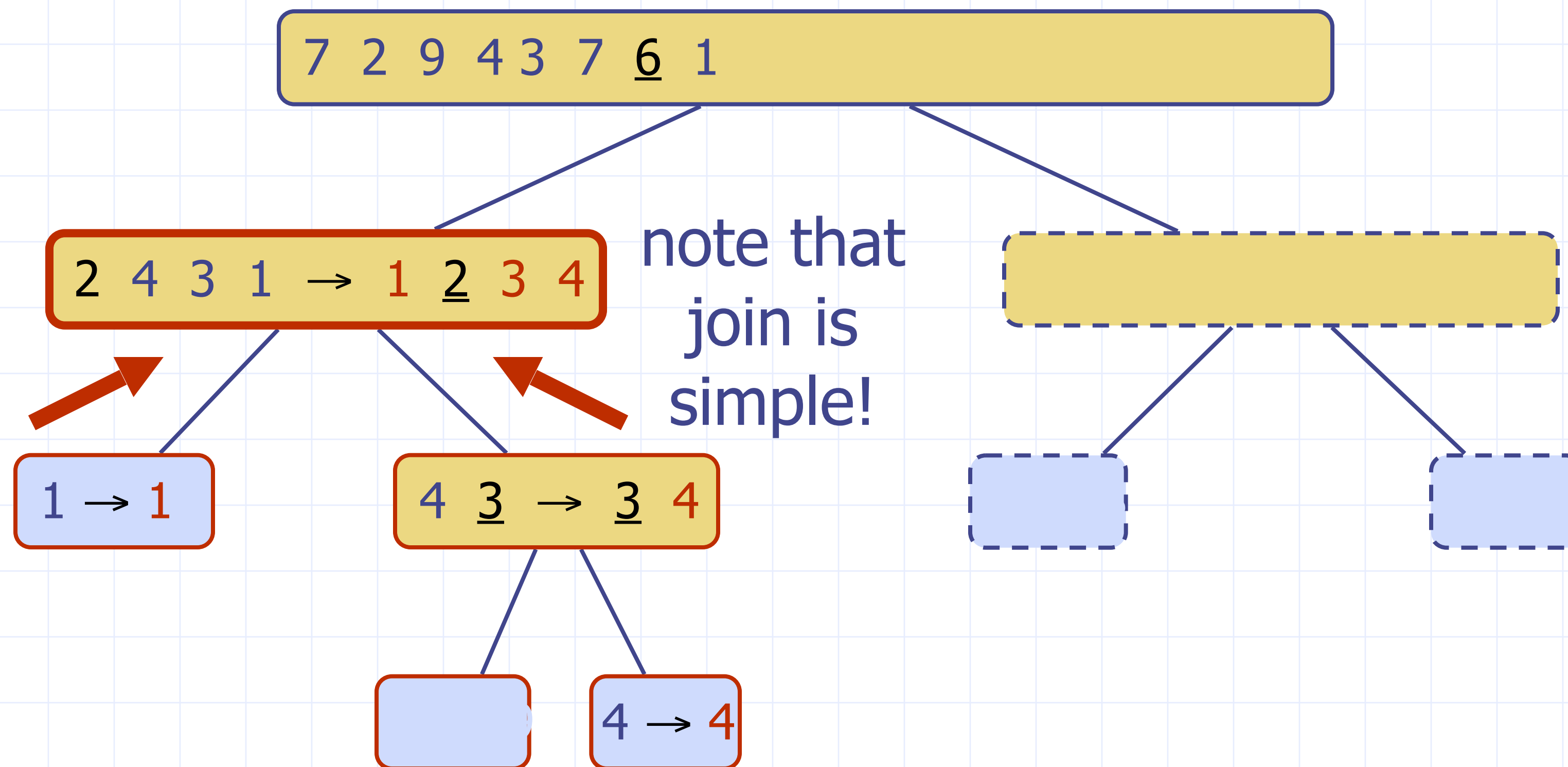
# Execution Example (cont.)

- Partition, recursive call, base case



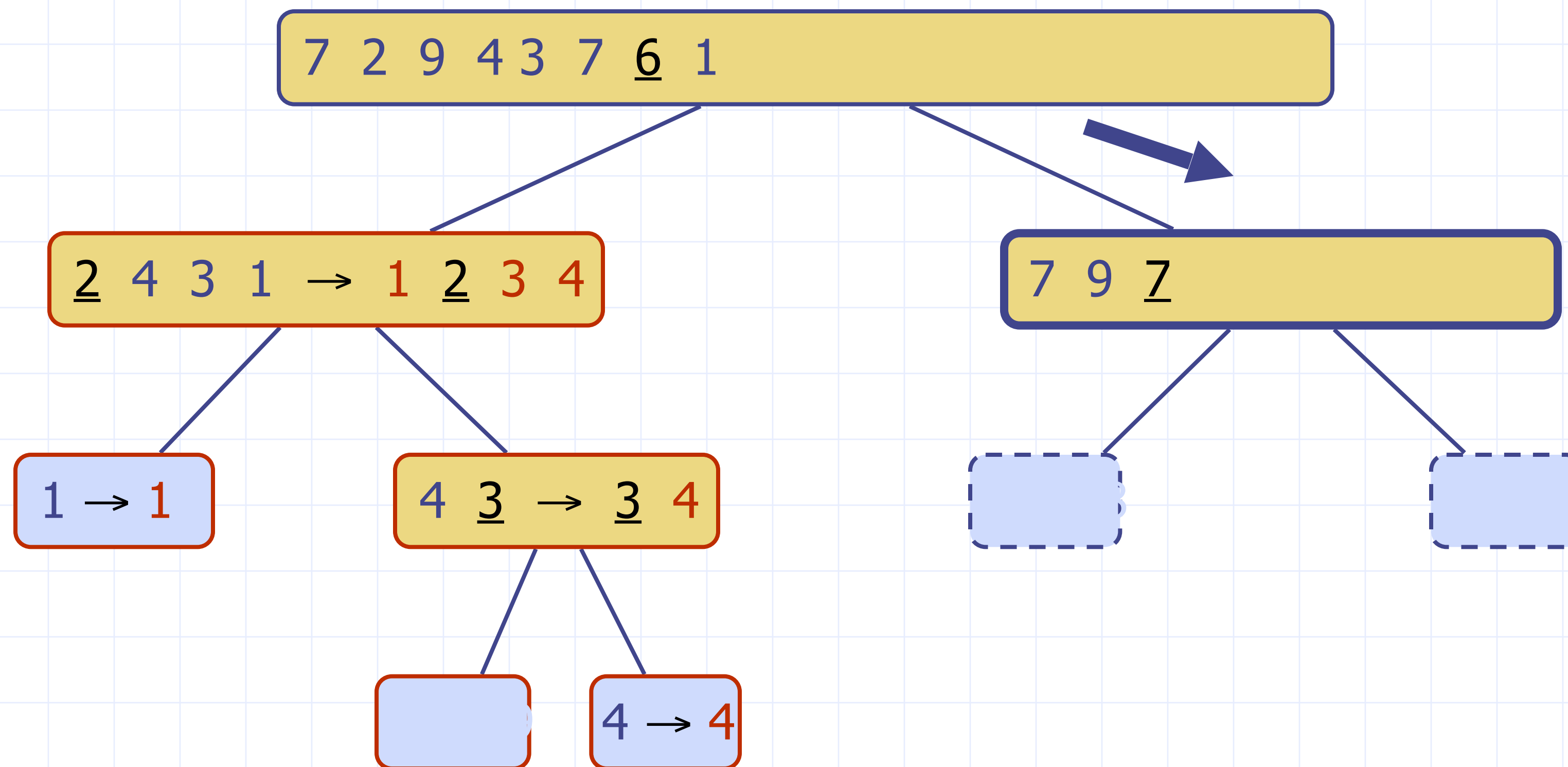
# Execution Example (cont.)

- Recursive call, ..., base case, join



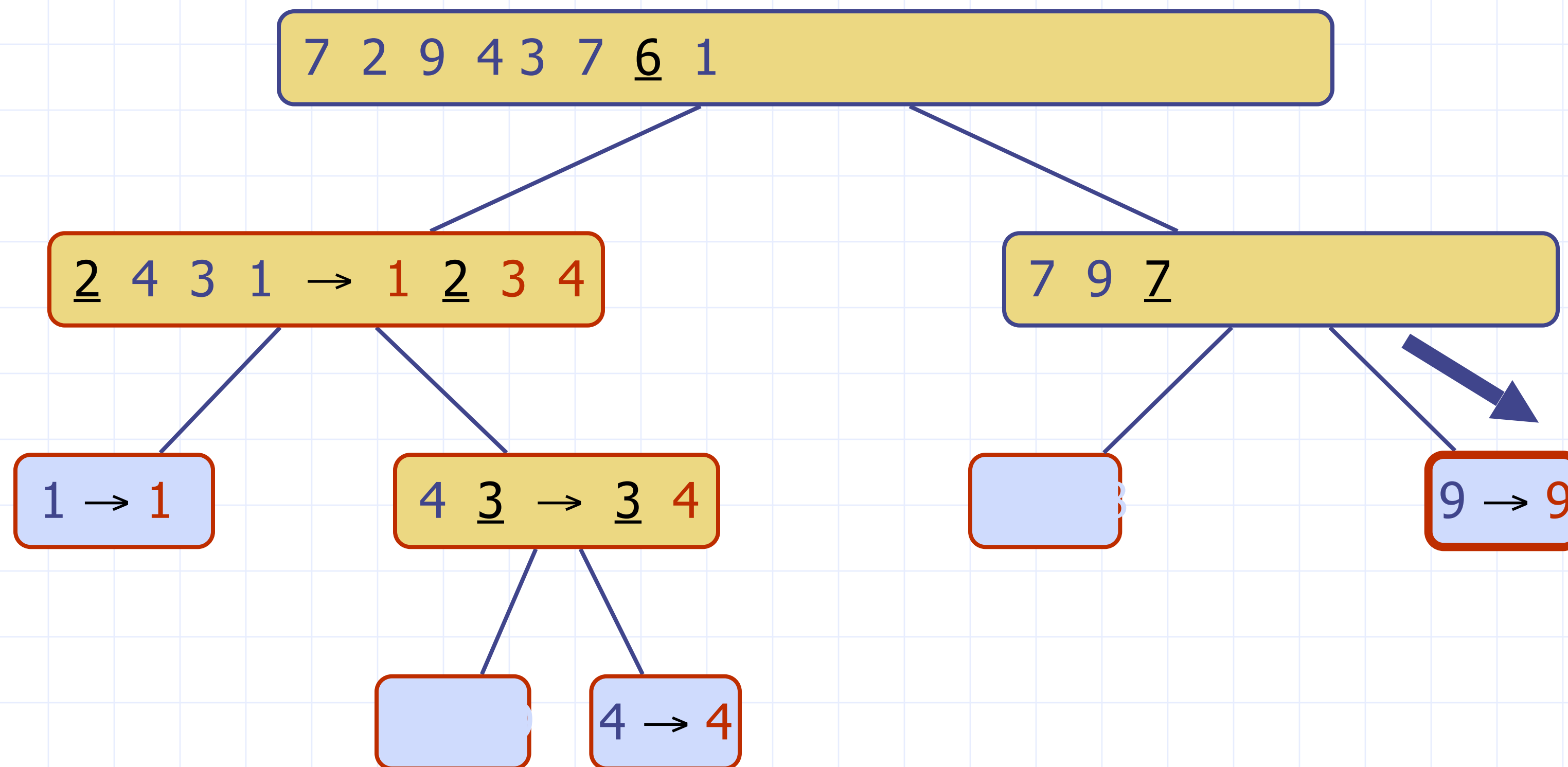
# Execution Example (cont.)

- Recursive call, pivot selection



# Execution Example (cont.)

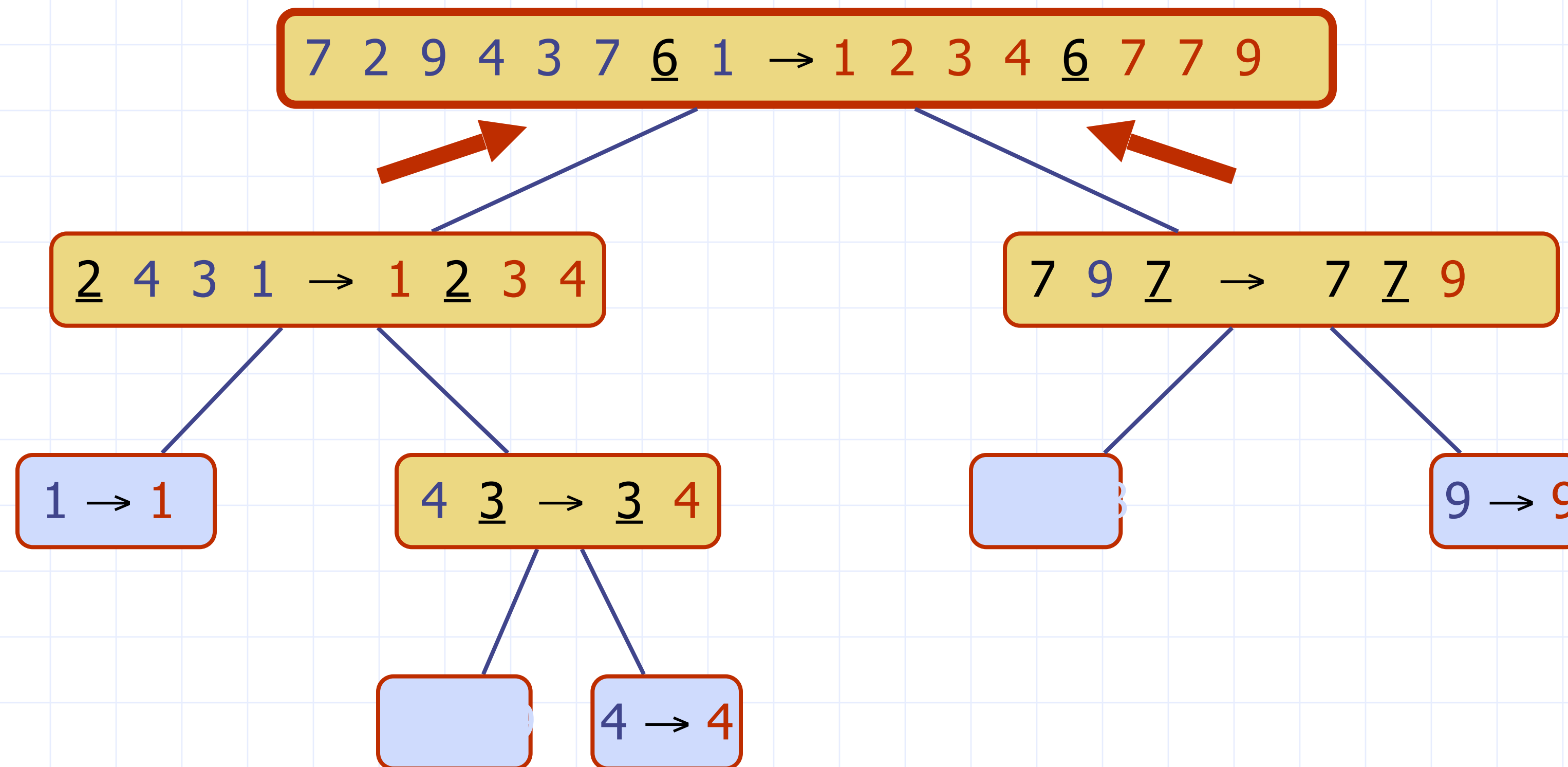
- Partition, ..., recursive call, base case





# Execution Example (cont.)

- Join, join ... again, these are easy here!



# Worst-case Running Time

- The worst case for quick-sort occurs when the pivot is the unique minimum or maximum element
- One of  $L$  and  $G$  has size  $n - 1$  and the other has size 0
- The running time is proportional to the sum

$$n + (n - 1) + \dots + 2 + 1$$

- Thus, the worst-case running time of quick-sort is  $O(n^2)$

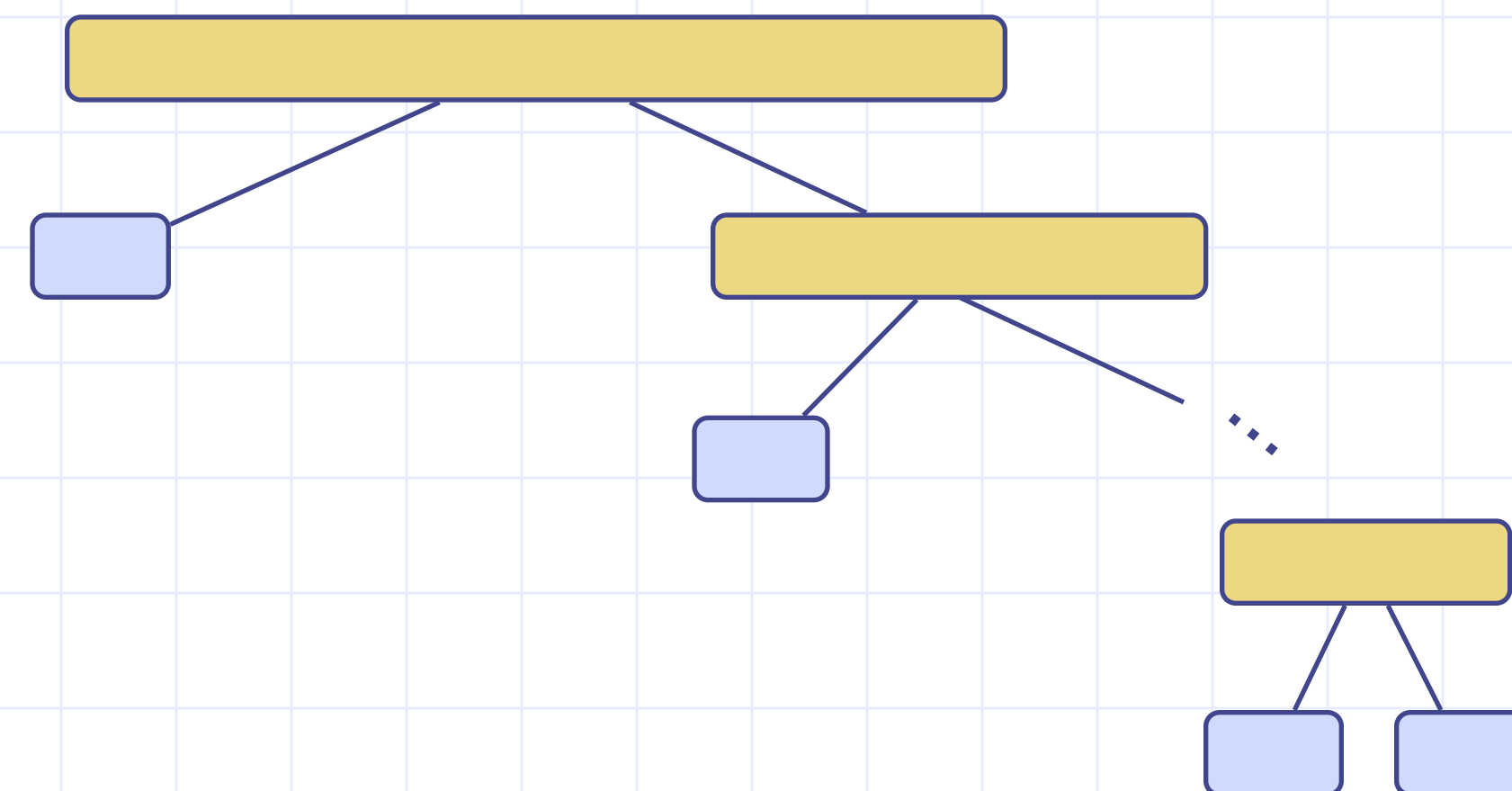
depth time

0  $n$

1  $n - 1$

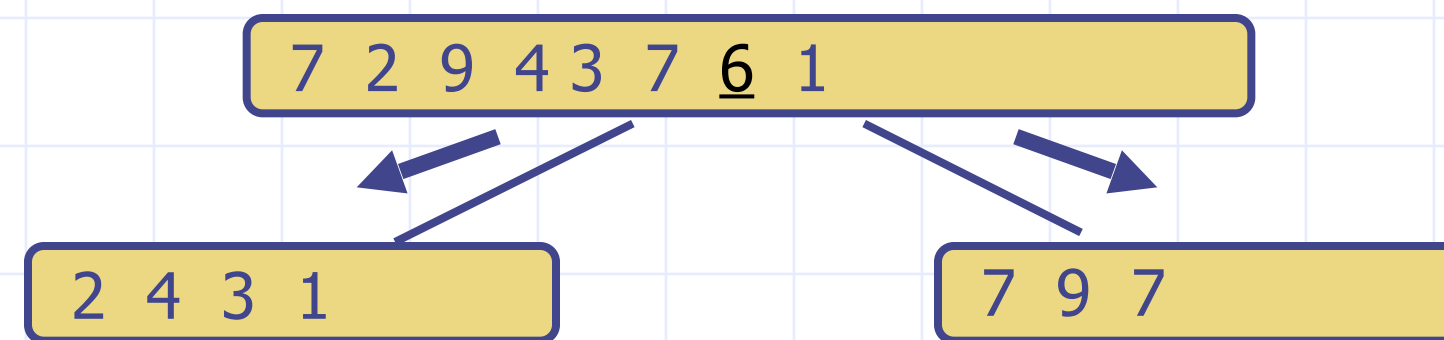
...

$n - 1$  1

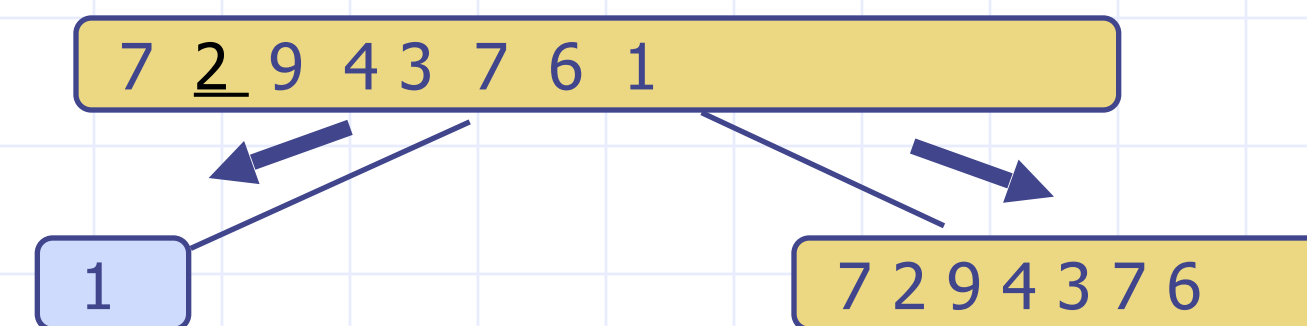


# Expected Running Time

- Consider a recursive call of quick-sort on a sequence of size  $s$ . Define:
  - **Good call:** the sizes of  $L$  and  $G$  are each less than  $3s/4$
  - **Bad call:** one of  $L$  and  $G$  has size greater than  $3s/4$

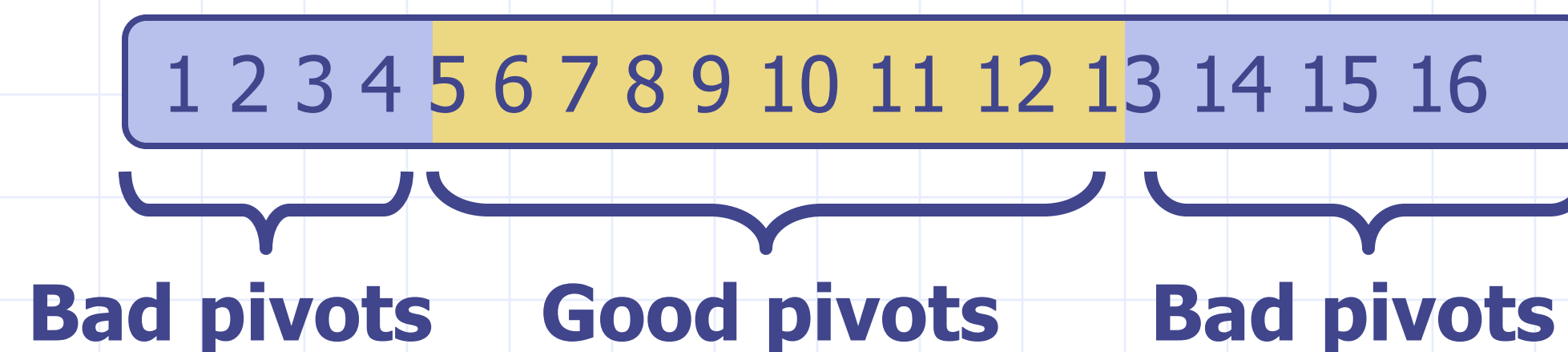


**Good call**



**Bad call**

- A call is **good** with probability  $1/2$ 
  - $1/2$  of the possible pivots cause good calls:



# Expected Running Time, Part 2

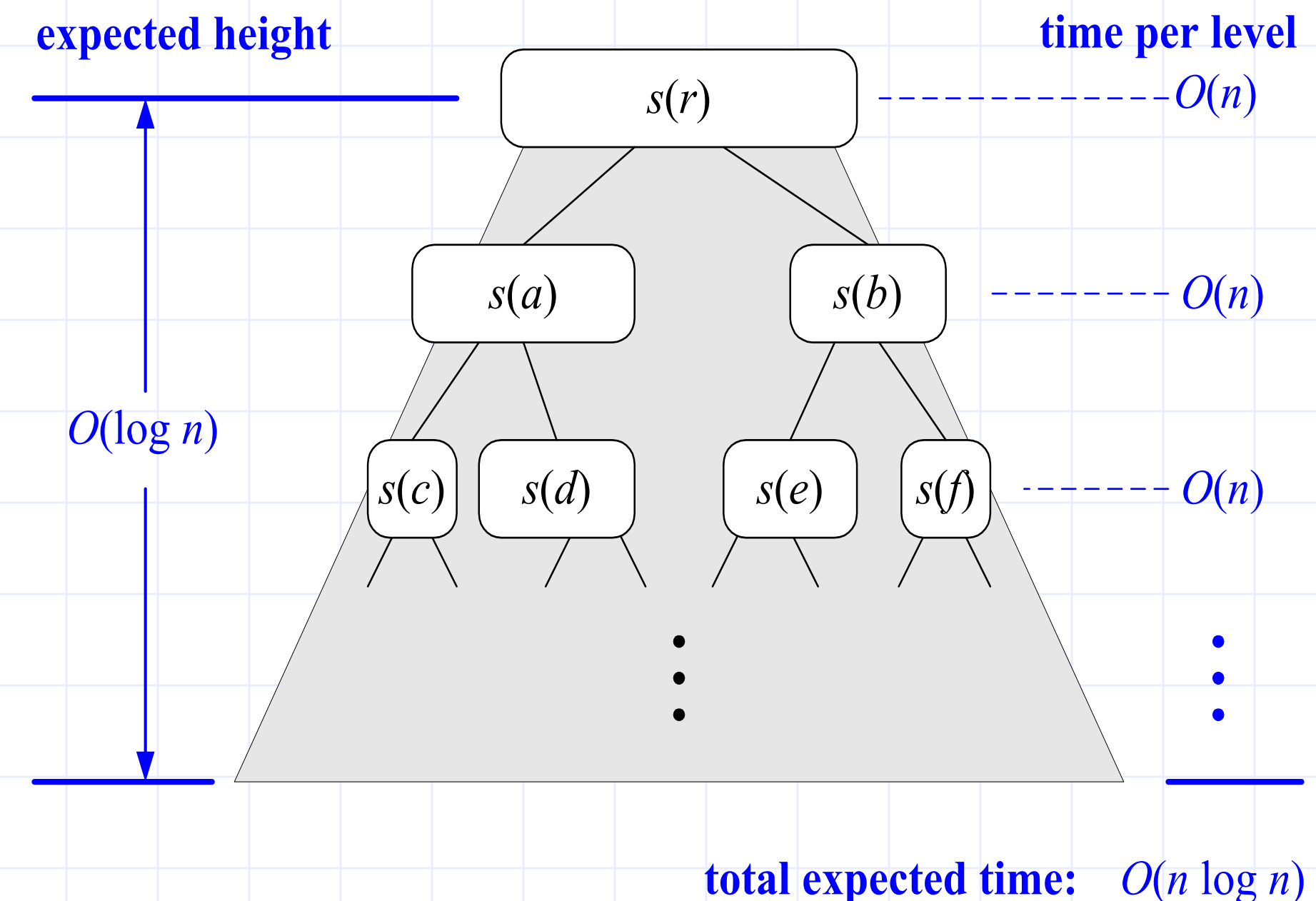
- For a node of depth  $i$ , we expect
  - $i/2$  ancestors are good calls
  - The size of the input sequence for the current call is at most  $(3/4)^{i/2}n$

- Therefore:

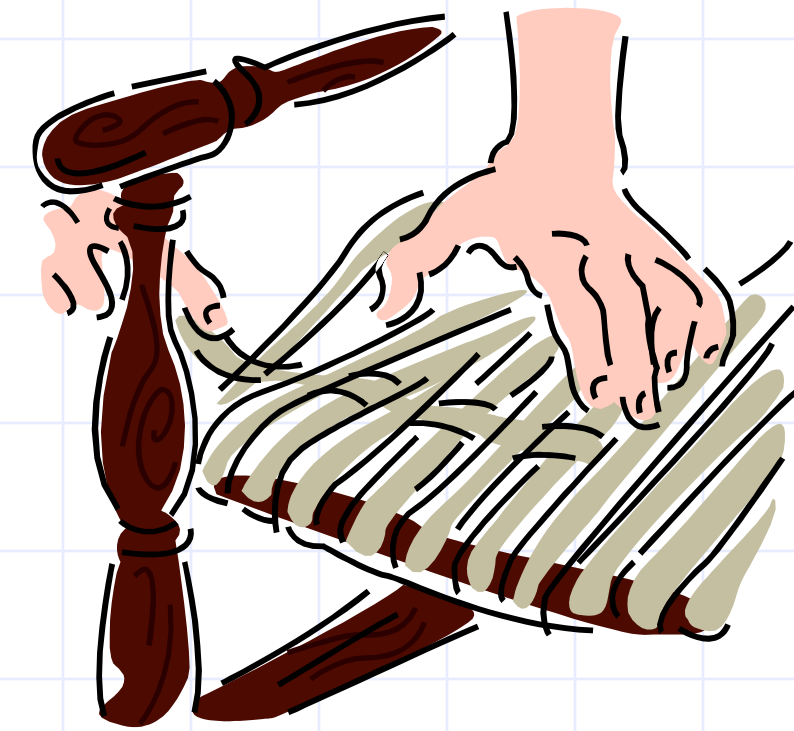
- For a node of depth  $2\log_{4/3}n$ , the expected input size is one

- The expected height of the quick-sort tree is  $O(\log n)$

- The amount of work done at the nodes of the same depth is  $O(n)$
- Thus, the expected running time of quick-sort is  $O(n \log n)$



# In-Place Quick-Sort



- Quick-sort can be implemented to run “in-place”
- In the partition step, we use replace operations to rearrange the elements of the input sequence such that:
  - the elements less than the pivot have index less than  $h$
  - the elements equal to the pivot have index between  $h$  and  $k$
  - the elements greater than the pivot have index greater than  $k$
- The recursive calls consider
  - elements with index less than  $h$
  - elements with index greater than  $k$

# Summary of Sorting Algorithms

| Algorithm                   | Time                                 | Notes  |
|-----------------------------|--------------------------------------|--|
| selection-sort              | $O(n^2)$                             | <ul style="list-style-type: none"><li>■ in-place</li><li>■ slow (good for small inputs)</li></ul>                            |
| bubble-sort                 | $O(n^2)$                             | <ul style="list-style-type: none"><li>■ in-place</li><li>■ slow (good for small inputs)</li></ul>                            |
| quick-sort                  | $O(n \log n)$<br><i>**expected**</i> | <ul style="list-style-type: none"><li>■ in-place, randomized</li><li>■ <u>usually</u> fast (good for large inputs)</li></ul> |
| merge-sort                  | $O(n \log n)$                        | <ul style="list-style-type: none"><li>■ needs extra storage</li><li>■ fast (good for huge inputs)</li></ul>                  |
| heap-sort<br>(next lecture) | $O(n \log n)$                        | <ul style="list-style-type: none"><li>■ in-place</li><li>■ fast (good for large inputs)</li></ul>                            |