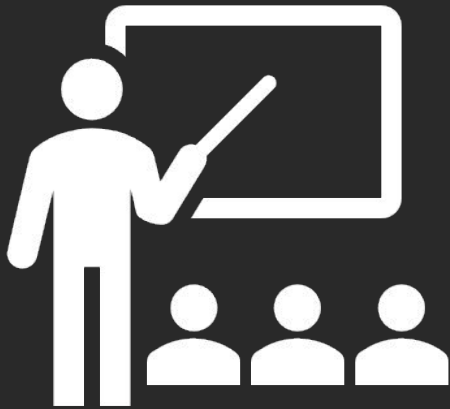


# Multithreading

# Game Plan



- Finishing Up Smart Pointers
- Announcements
- Multithreading

# Recap

# Problem: We can't guarantee this function will not have a memory leak.

```
string EvaluateSalaryAndReturnName(int idNumber) {  
    Employee* e = new Employee(idNumber);  
  
    if ( e.Title() == "CEO" || e.Salary() > 100000 ) {  
        cout << e.First() << " "  
             << e.Last() << " is overpaid" << endl;  
    }  
    auto result = e.First() + " " + e.Last();  
  
    delete e;  
    return result;  
}
```

How do we guarantee classes  
release their resources?

Regardless of exceptions!

# RAII!

Acquire resources in the constructor,  
release in the destructor.

Use a wrapper class that handles all the resource  
management for you!

We previously saw how to make file reading  
RAII compliant using filestreams:

# We previously saw how to make file reading RAII compliant using **filestreams**:

```
void printFile () {  
    ifstream input();  
    input.open("hamlet.txt");  
    string line;  
    while (getline(input, line)) {  
        cout << line << endl;  
    }  
    input.close();  
}
```



```
void printFile () {  
    ifstream input("hamlet.txt");  
    string line;  
    while (getline(input, line)) {  
        cout << line << endl;  
    }  
    // no close call needed!  
}  
// stream destructor  
// releases access to file
```



We previously saw how to make `locks`  
RAII compliant using `lock_guards`:

# We previously saw how to make **locks** RAII compliant using **lock\_guards**:

```
void cleanDatabase (mutex& databaseLock,  
                    map<int, int>& database) {  
    databaseLock.lock();  
    // other threads will not modify  
    database  
    // modify the database  
    // if exception thrown, mutex never  
    unlocked!  
    databaseLock.unlock();  
}
```



```
void cleanDatabase (mutex& databaseLock,  
                    map<int, int>& database) {  
    lock_guard<mutex>(databaseLock);  
    // other threads will not modify  
    database  
    // modify the database  
    // if exception thrown, that's fine!  
    // no release call needed  
}  
// lock_guard destructor  
// releases lock
```

We previously saw how to make **pointers**  
RAII compliant using **smart pointers**:

We previously saw how to make **pointers**  
RAII compliant using **smart pointers**:

```
void rawPtrFn () {  
    Node* n = new Node;  
    // do some stuff with n...  
    delete n;  
}
```



```
void rawPtrFn () {  
    std::unique_ptr<Node> n(new Node);  
    // do some stuff with n  
} // Freed!
```

# We previously saw how to make **pointers** RAII compliant using **smart pointers**:

```
void rawPtrFn () {  
    Node* n = new Node;  
    // do some stuff with n...  
    delete n;  
}
```



```
void rawPtrFn () {  
    std::unique_ptr<Node> n(new Node);  
    // do some stuff with n  
} // Freed!
```



```
void rawPtrFn () {  
    std::shared_ptr<Node> n(new Node);  
    // do some stuff with n  
} // Freed!
```

And we saw a better way to declare smart pointers:

# And we saw a better way to declare smart pointers:

```
std::unique_ptr<Node> n(new Node);    std::shared_ptr<Node> n(new Node);
```



```
std::unique_ptr<Node> n =  
    std::make_unique<Node>();
```



```
std::shared_ptr<Node> n =  
    std::make_shared<Node>();
```

# Today we'll learn why it's better!

```
std::unique_ptr<Node> n(new Node);    std::shared_ptr<Node> n(new Node);
```



```
std::unique_ptr<Node> n =  
    std::make_unique<Node>();
```



```
std::shared_ptr<Node> n =  
    std::make_shared<Node>();
```



But First...

...Multithreading!

# What is a thread?

# What is a thread?

Code is usually sequential.

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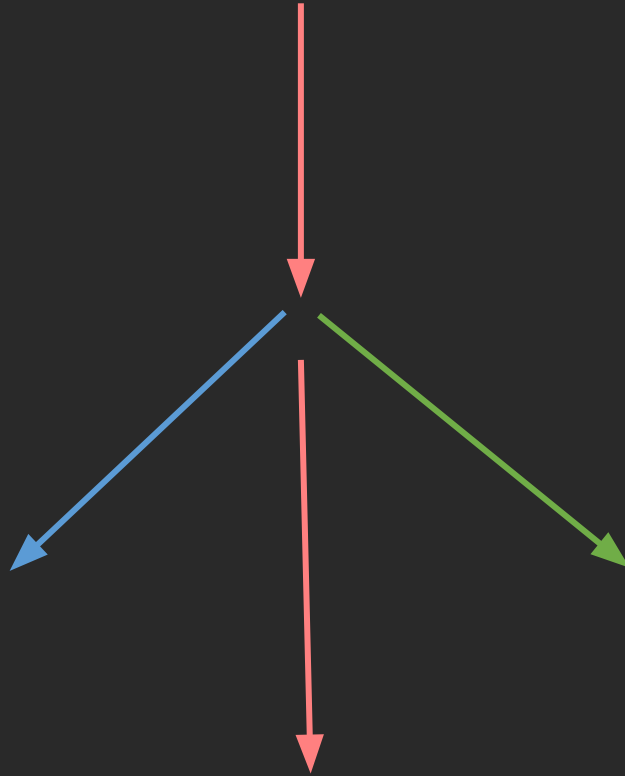
Threads are ways to parallelise execution.

# What is a thread?

# What is a thread?

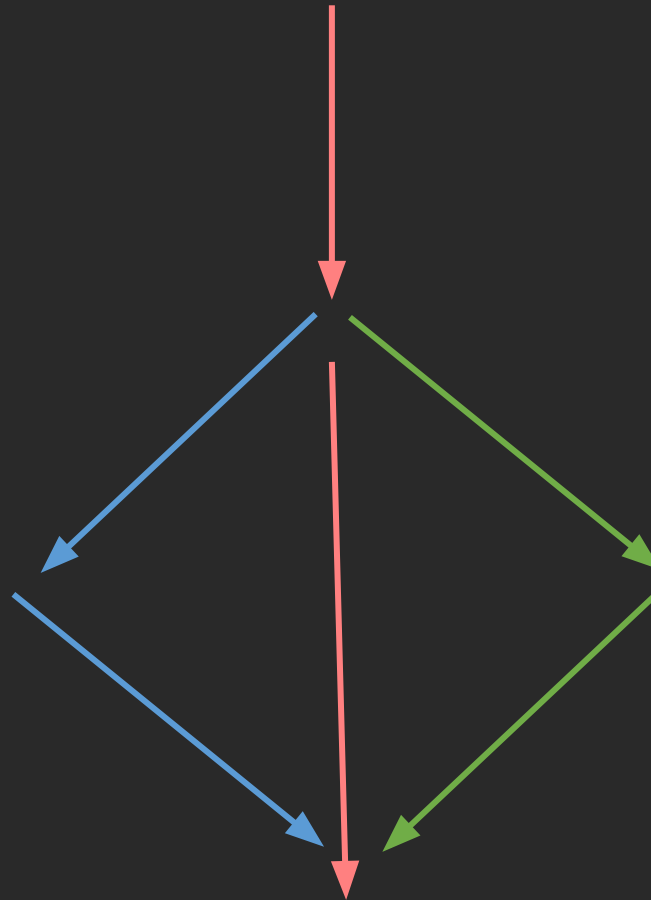


# What is a thread?

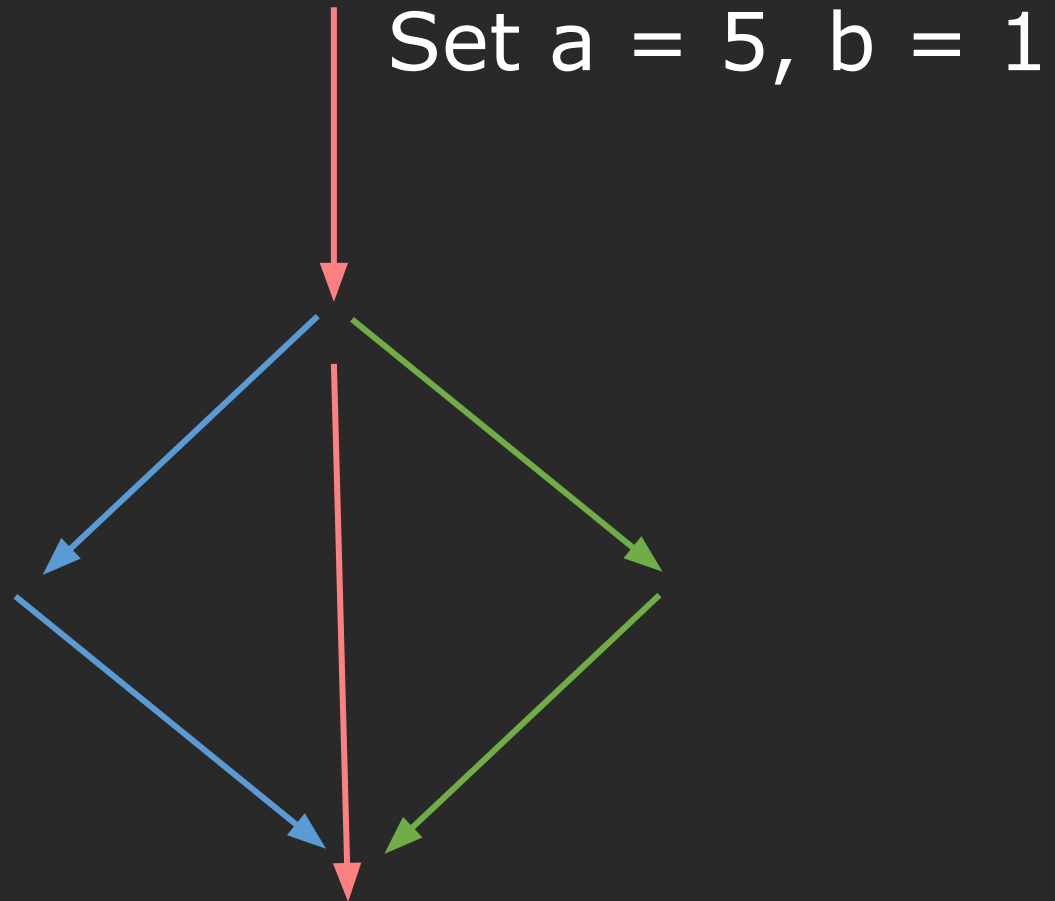




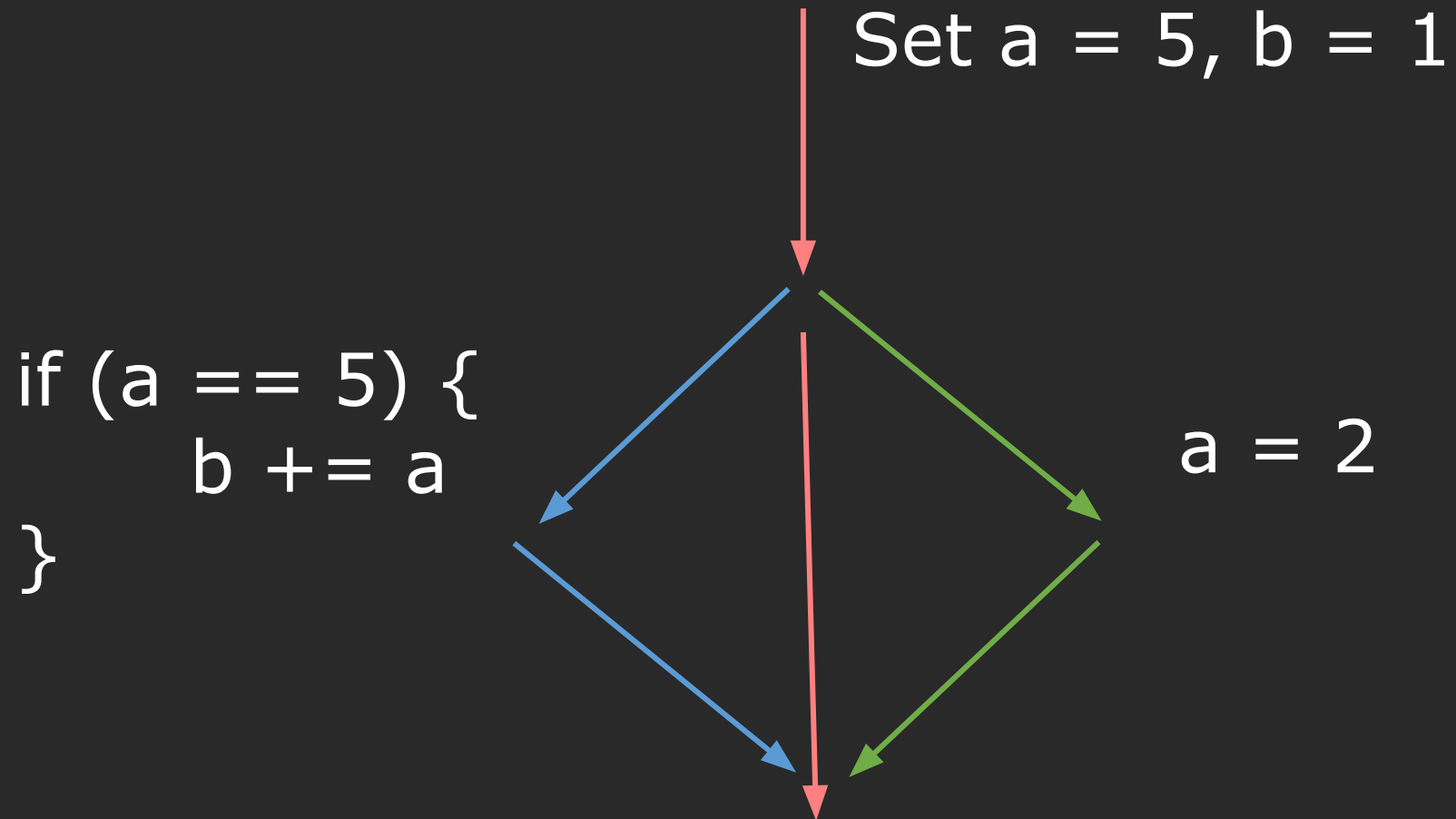
# What is a thread?



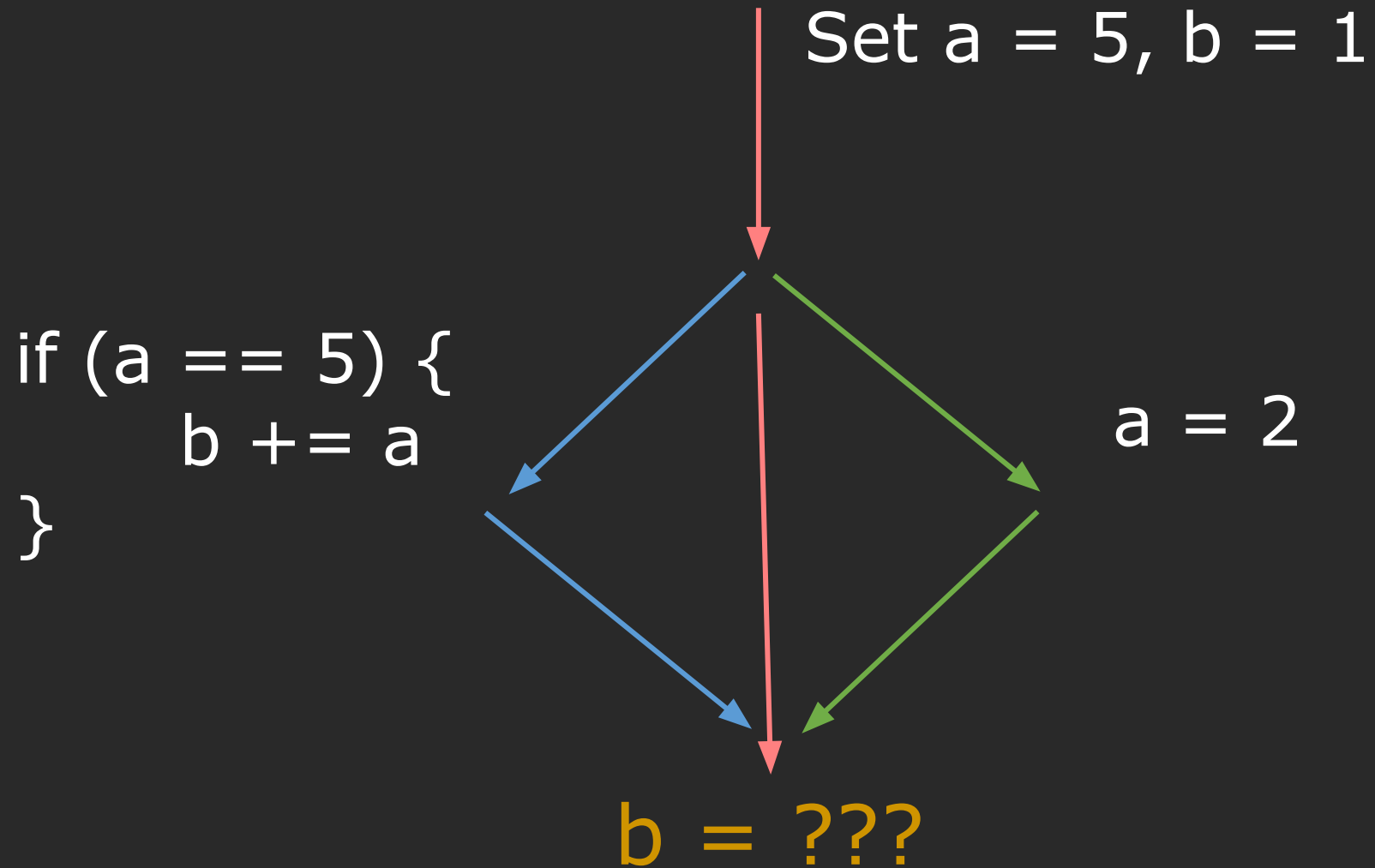
# What is a thread?



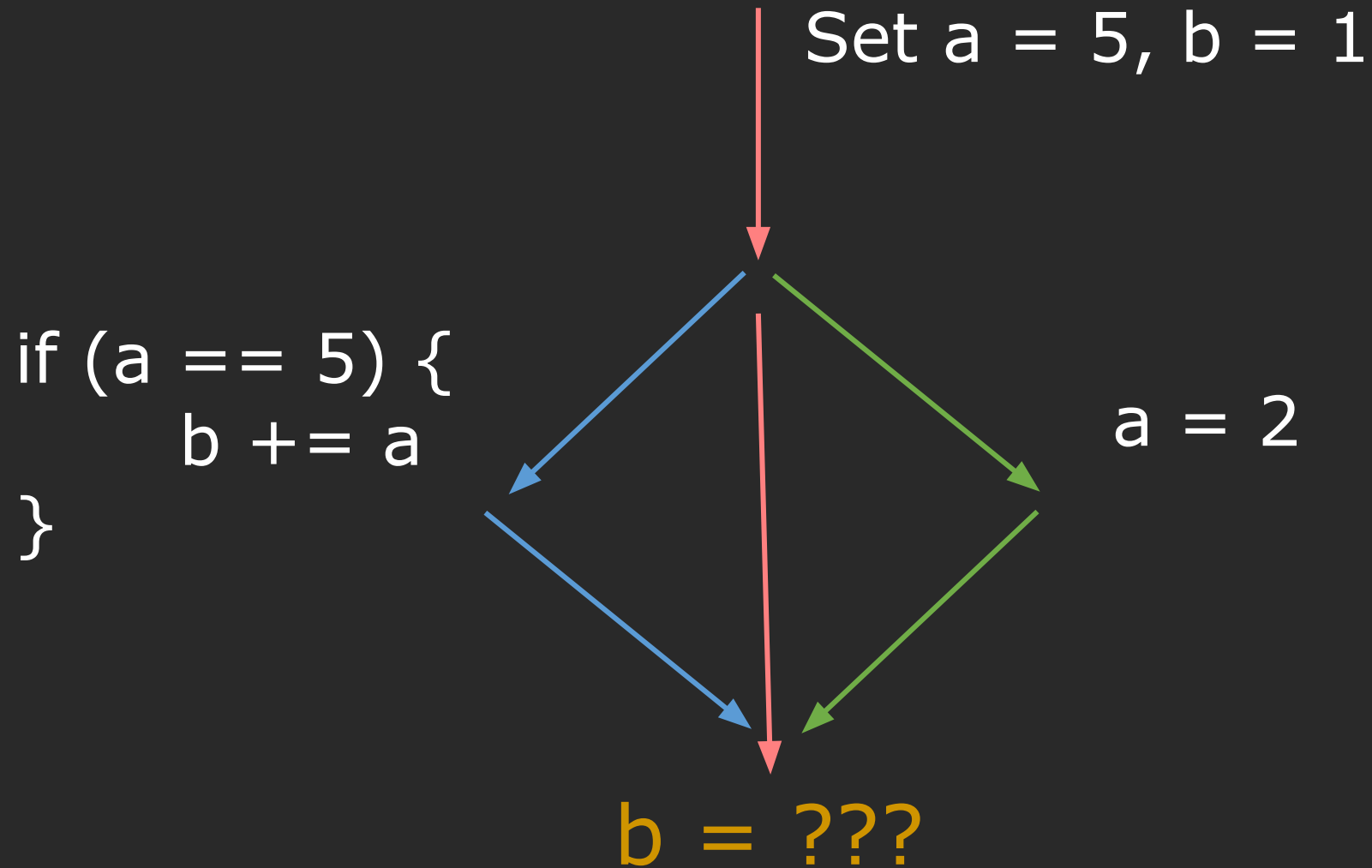
# What is a thread?



# What is a thread?



# This is known as a data race!



# We've already seen locks with RAII!

```
void cleanDatabase (mutex& databaseLock,  
                   map<int, int>& database) {  
    databaseLock.lock();  
    // other threads will not modify  
    database  
    // modify the database  
    // if exception thrown, mutex never  
    unlocked!  
    databaseLock.unlock();  
}
```



```
void cleanDatabase (mutex& databaseLock,  
                   map<int, int>& database) {  
    lock_guard<mutex>(databaseLock);  
    // other threads will not modify  
    database  
    // modify the database  
    // if exception thrown, that's fine!  
    // no release call needed  
}  
// lock_guard destructor  
// releases lock
```

# Return of the STL!



The screenshot shows a web browser window with the address bar displaying "cplusplus.com/reference/multithreading/". The page features the cplusplus.com logo and a search bar. A navigation menu on the left includes "C++", "Information", "Tutorials", "Reference", "Articles", and "Forum". The "Reference" section is expanded, showing a list of topics: "C library:", "Containers:", "Input/Output:", "Multi-threading:", and "Other:". The "Multi-threading:" section is further expanded, listing headers: "<atomic>", "<condition\_variable>", "<future>", "<mutex>", and "<thread>". The main content area is titled "library Multi-threading" and includes a warning icon. It states "Atomic and thread support" and "Support for atomics and threads:". Below this, a section titled "Headers" lists the following headers and their descriptions:

| Header               | Description                 |
|----------------------|-----------------------------|
| <atomic>             | Atomic (header)             |
| <thread>             | Thread (header)             |
| <mutex>              | Mutex (header)              |
| <condition_variable> | Condition variable (header) |
| <future>             | Future (header)             |

<http://www.cplusplus.com/reference/multithreading/>

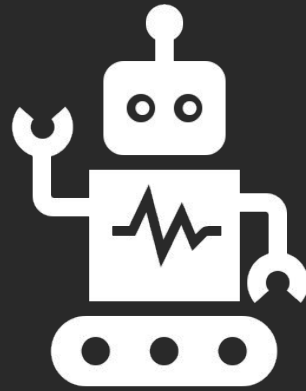
# Things to Take Away

- When do I need to use locks?
  - Internally synchronized: `mutex`, `condition_variable`, `<atomic>`
  - With any other type, you are responsible for synchronizing (i.e. making your code thread-safe)!
- 3 types of locks: normal, timed, recursive
- `std::lock_guard` vs. `std::unique_lock`
- Condition variables allow cross-thread communication
  - see CS 110



# Synchronization and Class Design

- In your class design, it's your responsibility to ensure that internal state is thread-safe!
- See [this link](#) for a fuller discussion on this topic!



# Example

## Multithreading in Action

Bad Dad Joke of the Day 1:

- What did the grape say when it was stepped on?
- Nothing, it just let out a little wine.

Creds: Jared

Bad Dad Joke of the Day 2:

- What do you call a dog that can do magic?
- A labracadabrador.

Creds: Nick

# 2-min stretch break!

Bad Dad Joke of the Day 1:

- What did the grape say when it was stepped on?
- Nothing, it just let out a little wine.

Creds: Jared

Bad Dad Joke of the Day 2:

- What do you call a dog that can do magic?
- A labracadabrador.

Creds: Nick

## 2-min stretch break!

Bad Dad Joke of the Day 3:

- Why aren't Koalas considered mammals?
- Because they do not meet the koala-ilifications!

Creds: Wilmer

Bad Dad Joke of the Day 4:

- I don't know any jokes about bad dads

Creds: Anton

# Announcements

# Announcements

- Reminder to fill out the form for final lecture!
  - Also, come to final lecture to be part of our EOQ screenshot!
- Assignment 2 grades are (almost all) out!
- Assignment 3 due this **Sunday**, 6/7, 11:59 pm
  - Hard deadline: Wednesday, 6/10, 11:59 pm
- **Assignment 3 has been revised!**

# Smart Pointer Creation

It's trickier than you might think!

# Recap: Smart Pointers

```
std::unique_ptr<T> up{new T};
```

```
std::shared_ptr<T> sp{new T};
```

```
std::weak_ptr<T> wp = sp;
```



# Recap: Smart Pointers

```
std::unique_ptr<T> up{new T};
```

```
std::shared_ptr<T> sp{new T};
```

# Recap: Smart Pointers

```
std::unique_ptr<T> up{new T};
```

```
std::unique_ptr<T> up = std::make_unique<T>();
```

```
std::shared_ptr<T> sp{new T};
```

# Recap: Smart Pointers

```
std::unique_ptr<T> up{new T};  
std::unique_ptr<T> up = std::make_unique<T>();  
  
std::shared_ptr<T> sp{new T};  
std::shared_ptr<T> sp = std::make_shared<T>();
```

# Which way is better?

```
std::unique_ptr<T> up{new T};
```

```
std::unique_ptr<T> up = std::make_unique<T>();
```

```
std::shared_ptr<T> sp{new T};
```

```
std::shared_ptr<T> sp = std::make_shared<T>();
```

# Rules of Function Calls

```
f ( expr1, expr2 );
```

## Rule #1:

Arguments to a function are evaluated before the function.  
Order is not guaranteed!

# Rules of Function Calls

```
f ( g (expr1) , h (expr2) ) ;
```

## Rule #2:

Each function is “atomic”.

Arguments may be interleaved otherwise.

# Rules of Function Calls

```
f( expr1, expr2 );  
f( g(expr1), h(expr2) );
```

## Rules:

Arguments to a function are evaluated before the function.  
Order is not guaranteed!

Each function is “atomic”.  
Arguments may be interleaved otherwise.

# Rules of Function Calls

```
f ( expr1, expr2 ) ;
```

## Rules:

Arguments to a function are evaluated before the function.

Order is not guaranteed!

Arguments may be interleaved otherwise.



# Rules of Function Calls

```
f( expr1, expr2 );
```

```
f( std::unique_ptr<T1>{ new T1 }, std::unique_ptr<T2>{ new T2 } );
```

## Rules:

Arguments to a function are evaluated before the function.

Order is not guaranteed!

Arguments may be interleaved otherwise.

# What might go wrong here?

```
f( expr1, expr2 );
```

```
f( std::unique_ptr<T1>{ new T1 }, std::unique_ptr<T2>{ new T2 } );
```

## Rules:

Arguments to a function are evaluated before the function.

Order is not guaranteed!

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# What might go wrong here?

```
f( expr1, expr2 );
```

```
f( std::unique_ptr<T1>{ new T1 }, std::unique_ptr<T2>{ new T2 } );
```

## Rules:

Arguments to a function are evaluated before the function.  
Order is not guaranteed!

Arguments may be interleaved otherwise.

# The Fix

```
f( g(expr1), h(expr2) );
```

```
f( std::make_unique<T1>(), std::make_unique<T2>() );
```

## Rules:

Arguments to a function are evaluated before the function.

Order is not guaranteed!

Arguments may be interleaved otherwise.

Each function is “atomic”.

# Aside

This rule is no longer true as of C++17:  
**Arguments may be interleaved otherwise.**

But we still prefer the wrapper functions -  
make\_shared has some performance benefits, etc.

# So... Which way is better?

```
std::unique_ptr<T> up{new T};
```

```
std::unique_ptr<T> up = std::make_unique<T>();
```

```
std::shared_ptr<T> sp{new T};
```

```
std::shared_ptr<T> sp = std::make_shared<T>();
```

So... Which way is better?

```
std::unique_ptr<T> up{new T};  
std::unique_ptr<T> up = std::make_unique<T>();
```

```
std::shared_ptr<T> sp{new T};  
std::shared_ptr<T> sp = std::make_shared<T>();
```

Always use `std::make_unique<T>()` and  
`std::make_shared<T>()`!

# So, to repeat a takeaway from last lecture:

**Guideline:** Don't use explicit **new**, **delete**, and owning **\*** pointers, except in rare cases encapsulated inside the implementation of a low-level data structure.

In **modern C++**, we almost never use  
**new** and **delete**!



# So, to repeat a takeaway from last lecture:

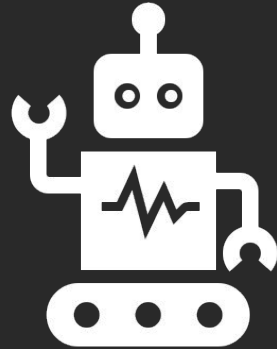
**Guideline:** *Don't use explicit **new**, **delete**, and owning \* pointers, except in rare cases encapsulated inside the implementation of a low-level data structure.*

## In **modern C++**, we almost never use **new** and **delete**!

You can read more about this here:

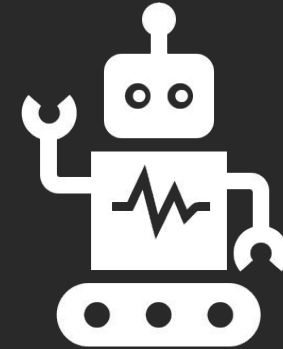
<https://herbsutter.com/2013/05/29/gotw-89-solution-smart-pointers/> . Overall, highly recommend Herb Sutter's GOTW blog!

If we have time... Last Example: you choose!



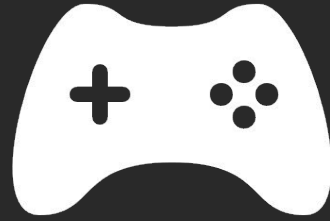
Smart Pointers:

Implementing a Shared  
Pointer!



Multithreading:

The Classic Ticket Agent  
Example



# Next time

Final Lecture