Python For Data Science *Cheat Sheet*

NumPy Basics

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NumPy

The **NumPy** library is the core library for scientific computing in Python. It provides a high-performance multidimensional array object, and tools for working with these arrays.

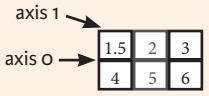
Use the following import convention:

```
>>> import numpy as np
```

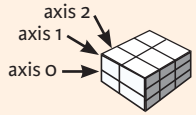
NumPy Arrays

1D array

2D array



3D array



Creating Arrays

```
>>> a = np.array([1,2,3])
>>> b = np.array([(1.5,2,3), (4,5,6)], dtype = float)
>>> c = np.array([[(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)]],
                 dtype = float)
```

Initial Placeholders

```
>>> np.zeros((3,4))                    Create an array of zeros
>>> np.ones((2,3,4),dtype=np.int16)    Create an array of ones
>>> d = np.arange(10,25,5)             Create an array of evenly
                                       spaced values (step value)
>>> np.linspace(0,2,9)                 Create an array of evenly
                                       spaced values (number of samples)
>>> e = np.full((2,2),7)               Create a constant array
>>> f = np.eye(2)                      Create a 2X2 identity matrix
>>> np.random.random((2,2))            Create an array with random values
>>> np.empty((3,2))                    Create an empty array
```

I/O

Saving & Loading On Disk

```
>>> np.save('my_array', a)
>>> np.savez('array.npz', a, b)
>>> np.load('my_array.npy')
```

Saving & Loading Text Files

```
>>> np.loadtxt("myfile.txt")
>>> np.genfromtxt("my_file.csv", delimiter=',')
>>> np.savetxt("myarray.txt", a, delimiter=" ")
```

Data Types

```
>>> np.int64       Signed 64-bit integer types
>>> np.float32     Standard double-precision floating point
>>> np.complex     Complex numbers represented by 128 floats
>>> np.bool        Boolean type storing TRUE and FALSE values
>>> np.object      Python object type
>>> np.string_     Fixed-length string type
>>> np.unicode_    Fixed-length unicode type
```

Inspecting Your Array

```
>>> a.shape             Array dimensions
>>> len(a)              Length of array
>>> b.ndim              Number of array dimensions
>>> e.size              Number of array elements
>>> b.dtype             Data type of array elements
>>> b.dtype.name        Name of data type
>>> b.astype(int)       Convert an array to a different type
```

Asking For Help

```
>>> np.info(np.ndarray.dtype)
```

Array Mathematics

Arithmetic Operations

```
>>> g = a - b                          Subtraction
  array([[-0.5,  0. ,  0. ],
         [-3. , -3. , -3. ]])
>>> np.subtract(a,b)                   Subtraction
>>> b + a                              Addition
  array([[ 2.5,  4. ,  6. ],
         [ 5. ,  7. ,  9. ]])
>>> np.add(b,a)                        Addition
>>> a / b                              Division
  array([[ 0.66666667,  1.        ,  1.        ],
         [ 0.25      ,  0.4       ,  0.5       ]])
>>> np.divide(a,b)                     Division
>>> a * b                              Multiplication
  array([[  1.5,   4. ,   9. ],
         [  4. ,  10. ,  18. ]])
>>> np.multiply(a,b)                   Multiplication
>>> np.exp(b)                          Exponentiation
>>> np.sqrt(b)                         Square root
>>> np.sin(a)                          Print sines of an array
>>> np.cos(b)                          Element-wise cosine
>>> np.log(a)                          Element-wise natural logarithm
>>> e.dot(f)                           Dot product
  array([[ 7.,  7.],
         [ 7.,  7.]])
```

Comparison

```
>>> a == b                             Element-wise comparison
  array([[False,  True,  True],
         [False, False, False]], dtype=bool)
>>> a < 2                              Element-wise comparison
  array([True, False, False], dtype=bool)
>>> np.array_equal(a, b)               Array-wise comparison
```

Aggregate Functions

```
>>> a.sum()                            Array-wise sum
>>> a.min()                            Array-wise minimum value
>>> b.max(axis=0)                      Maximum value of an array row
>>> b.cumsum(axis=1)                   Cumulative sum of the elements
>>> a.mean()                           Mean
>>> b.median()                         Median
>>> a.corrcoef()                       Correlation coefficient
>>> np.std(b)                          Standard deviation
```

Copying Arrays

```
>>> h = a.view()          Create a view of the array with the same data
>>> np.copy(a)            Create a copy of the array
>>> h = a.copy()          Create a deep copy of the array
```

Sorting Arrays

```
>>> a.sort()              Sort an array
>>> c.sort(axis=0)        Sort the elements of an array's axis
```

Subsetting, Slicing, Indexing

Also see Lists

Subsetting


```
>>> a[2]
  3
```

Select the element at the 2nd index


```
>>> b[1,2]
  6.0
```

Select the element at row 1 column 2 (equivalent to `b[1][2]`)

Slicing


```
>>> a[0:2]
  array([1, 2])
```

Select items at index 0 and 1


```
>>> b[0:2,1]
  array([ 2.,  5.])
```

Select items at rows 0 and 1 in column 1


```
>>> b[:1]
  array([[1.5, 2., 3.]])
```

Select all items at row 0 (equivalent to `b[0:1, :]`)

```
>>> c[1,...]
  array([[[ 3.,  2.,  1.],
          [ 4.,  5.,  6.]]])
```

Same as `[1,:,:]`

```
>>> a[ : :-1]
  array([3, 2, 1])
```

Reversed array `a`

Boolean Indexing


```
>>> a[a<2]
  array([1])
```

Select elements from `a` less than 2

Fancy Indexing

```
>>> b[[1, 0, 1, 0],[0, 1, 2, 0]]
  array([ 4. , 2. , 6. , 1.5])
```

Select elements $(1,0)$, $(0,1)$, $(1,2)$ and $(0,0)$

```
>>> b[[1, 0, 1, 0]][:,[0,1,2,0]]
  array([[ 4. , 5. , 6. , 4. ],
         [ 1.5, 2. , 3. , 1.5],
         [ 4. , 5. , 6. , 4. ],
         [ 1.5, 2. , 3. , 1.5]])
```

Select a subset of the matrix's rows and columns

Array Manipulation

Transposing Array

```
>>> i = np.transpose(b)        Permute array dimensions
>>> i.T                        Permute array dimensions
```

Changing Array Shape

```
>>> b.ravel()                  Flatten the array
>>> g.reshape(3,-2)            Reshape, but don't change data
```

Adding/Removing Elements

```
>>> h.resize((2,6))            Return a new array with shape (2,6)
>>> np.append(h,g)             Append items to an array
>>> np.insert(a, 1, 5)         Insert items in an array
>>> np.delete(a,[1])           Delete items from an array
```

Combining Arrays

```
>>> np.concatenate((a,d),axis=0)        Concatenate arrays
  array([ 1,  2,  3, 10, 15, 20])
>>> np.vstack((a,b))                    Stack arrays vertically (row-wise)
  array([[ 1. ,  2. ,  3. ],
         [ 1.5,  2. ,  3. ],
         [ 4. ,  5. ,  6. ]])
>>> np.r_[e,f]                          Stack arrays vertically (row-wise)
>>> np.hstack((e,f))                    Stack arrays horizontally (column-wise)
  array([[ 7.,  7.,  1.,  0.],
         [ 7.,  7.,  0.,  1.]])
>>> np.column_stack((a,d))              Create stacked column-wise arrays
  array([[ 1, 10],
         [ 2, 15],
         [ 3, 20]])
>>> np.c_[a,d]                          Create stacked column-wise arrays
```

Splitting Arrays

```
>>> np.hsplit(a,3)                      Split the array horizontally at the 3rd index
  [array([1]),array([2]),array([3])]
>>> np.vsplit(c,2)                      Split the array vertically at the 2nd index
[array([[[ 1.5,  2. ,  1. ],
         [ 4. ,  5. ,  6. ]]]),
 array([[[ 3.,  2.,  3.],
         [ 4.,  5.,  6.]]])]
```

Python For Data Science *Cheat Sheet*

SciPy - Linear Algebra

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SciPy

The **SciPy** library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.

Interacting With NumPy

Also see NumPy

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])
>>> c = np.array([[(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)]])
```

Index Tricks

```
>>> np.mgrid[0:5,0:5]          Create a dense meshgrid
>>> np.ogrid[0:2,0:2]          Create an open meshgrid
>>> np.r_[[3,[0]*5,-1:1:10j]   Stack arrays vertically (row-wise)
>>> np.c_[b,c]                 Create stacked column-wise arrays
```

Shape Manipulation

```
>>> np.transpose(b)            Permute array dimensions
>>> b.flatten()                Flatten the array
>>> np.hstack((b,c))           Stack arrays horizontally (column-wise)
>>> np.vstack((a,b))           Stack arrays vertically (row-wise)
>>> np.hsplit(c,2)             Split the array horizontally at the 2nd index
>>> np.vpslit(d,2)             Split the array vertically at the 2nd index
```

Polynomials

```
>>> from numpy import poly1d
>>> p = poly1d([3,4,5])        Create a polynomial object
```

Vectorizing Functions

```
>>> def myfunc(a):
        if a < 0:
          return a*2
        else:
          return a/2
>>> np.vectorize(myfunc)       Vectorize functions
```

Type Handling

```
>>> np.real(c)                 Return the real part of the array elements
>>> np.imag(c)                 Return the imaginary part of the array elements
>>> np.real_if_close(c,tol=1000)  Return a real array if complex parts close to 0
>>> np.cast['f'](np.pi)        Cast object to a data type
```

Other Useful Functions

```
>>> np.angle(b,deg=True)       Return the angle of the complex argument
>>> g = np.linspace(0,np.pi,num=5)  Create an array of evenly spaced values
                                    (number of samples)
>>> g [3:] += np.pi
>>> np.unwrap(g)               Unwrap
>>> np.logspace(0,10,3)        Create an array of evenly spaced values (log scale)
>>> np.select([c<4],[c*2])     Return values from a list of arrays depending on
                               conditions
>>> misc.factorial(a)          Factorial
>>> misc.comb(10,3,exact=True)  Combine N things taken at k time
>>> misc.central_diff_weights(3)  Weights for Np-point central derivative
>>> misc.derivative(myfunc,1.0)  Find the n-th derivative of a function at a point
```

Linear Algebra

Also see NumPy

You'll use the `linalg` and `sparse` modules. Note that `scipy.linalg` contains and expands on `numpy.linalg`.

```
>>> from scipy import linalg, sparse
```

Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))
>>> B = np.asmatrix(b)
>>> C = np.mat(np.random.random((10,5)))
>>> D = np.mat([[3,4], [5,6]])
```

Basic Matrix Routines

Inverse

```
>>> A.I                        Inverse
>>> linalg.inv(A)              Inverse
>>> A.T                        Tranpose matrix
>>> A.H                        Conjugate transposition
>>> np.trace(A)                Trace
```

Norm

```
>>> linalg.norm(A)             Frobenius norm
>>> linalg.norm(A,1)           L1 norm (max column sum)
>>> linalg.norm(A,np.inf)      L inf norm (max row sum)
```

Rank

```
>>> np.linalg.matrix_rank(C)   Matrix rank
```

Determinant

```
>>> linalg.det(A)              Determinant
```

Solving linear problems

```
>>> linalg.solve(A,b)          Solver for dense matrices
>>> E = np.mat(a).T            Solver for dense matrices
>>> linalg.lstsq(D,E)          Least-squares solution to linear matrix
                               equation
```

Generalized inverse

```
>>> linalg.pinv(C)             Compute the pseudo-inverse of a matrix
                               (least-squares solver)
>>> linalg.pinv2(C)            Compute the pseudo-inverse of a matrix
                               (SVD)
```

Creating Sparse Matrices

```
>>> F = np.eye(3, k=1)         Create a 2X2 identity matrix
>>> G = np.mat(np.identity(2)) Create a 2x2 identity matrix
>>> C[C > 0.5] = 0
>>> H = sparse.csr_matrix(C)   Compressed Sparse Row matrix
>>> I = sparse.csc_matrix(D)   Compressed Sparse Column matrix
>>> J = sparse.dok_matrix(A)   Dictionary Of Keys matrix
>>> E.todense()                Sparse matrix to full matrix
>>> sparse.isspmatrix_csc(A)   Identify sparse matrix
```

Sparse Matrix Routines

Inverse

```
>>> sparse.linalg.inv(I)       Inverse
```

Norm

```
>>> sparse.linalg.norm(I)      Norm
```

Solving linear problems

```
>>> sparse.linalg.spsolve(H,I)  Solver for sparse matrices
```

Sparse Matrix Functions

```
>>> sparse.linalg.expm(I)      Sparse matrix exponential
```

Matrix Functions

Addition

```
>>> np.add(A,D)                Addition
```

Subtraction

```
>>> np.subtract(A,D)           Subtraction
```

Division

```
>>> np.divide(A,D)             Division
```

Multiplication

```
>>> np.multiply(D,A)           Multiplication
>>> np.dot(A,D)                Dot product
>>> np.vdot(A,D)               Vector dot product
>>> np.inner(A,D)              Inner product
>>> np.outer(A,D)              Outer product
>>> np.tensordot(A,D)          Tensor dot product
>>> np.kron(A,D)               Kronecker product
```

Exponential Functions

```
>>> linalg.expm(A)             Matrix exponential
>>> linalg.expm2(A)            Matrix exponential (Taylor Series)
>>> linalg.expm3(D)            Matrix exponential (eigenvalue
                               decomposition)
```

Logarithm Function

```
>>> linalg.logm(A)             Matrix logarithm
```

Trigonometric Tunctions

```
>>> linalg.sinm(D)             Matrix sine
>>> linalg.cosm(D)             Matrix cosine
>>> linalg.tanm(A)             Matrix tangent
```

Hyperbolic Trigonometric Functions

```
>>> linalg.sinhm(D)            Hypberbolic matrix sine
>>> linalg.coshm(D)            Hyperbolic matrix cosine
>>> linalg.tanhm(A)            Hyperbolic matrix tangent
```

Matrix Sign Function

```
>>> np.sigm(A)                 Matrix sign function
```

Matrix Square Root

```
>>> linalg.sqrtm(A)            Matrix square root
```

Arbitrary Functions

```
>>> linalg.funm(A, lambda x: x*x)  Evaluate matrix function
```

Decompositions

Eigenvalues and Eigenvectors

```
>>> la, v = linalg.eig(A)      Solve ordinary or generalized
                               eigenvalue problem for square matrix
>>> l1, l2 = la                Unpack eigenvalues
>>> v[:,0]                     First eigenvector
>>> v[:,1]                     Second eigenvector
>>> linalg.eigvals(A)          Unpack eigenvalues
```

Singular Value Decomposition

```
>>> U,s,Vh = linalg.svd(B)     Singular Value Decomposition (SVD)
>>> M,N = B.shape
>>> Sig = linalg.diagsvd(s,M,N)  Construct sigma matrix in SVD
```

LU Decomposition

```
>>> P,L,U = linalg.lu(C)       LU Decomposition
```

Sparse Matrix Decompositions

```
>>> la, v = sparse.linalg.eigs(F,1)  Eigenvalues and eigenvectors
>>> sparse.linalg.svds(H, 2)         SVD
```

Asking For Help

```
>>> help(scipy.linalg.diagsvd)
>>> np.info(np.matrix)
```

Cheatography

Linear Algebra Using SymPy Cheat Sheet

by royqh1979 via cheatography.com/87753/cs/20231/

Import SymPy

```
import sympy as sp
```

Matrix Creation

normal Matrix	sp.**Matrix**([[1,2],[3,4]])
Matrix with all zeros	sp.**zeros**(4,5)
Matrix with all ones	sp.**ones**(4,5)
Square matrix with all zeros	sp.**zeros**(5)
Square matrix with all ones	sp.**ones**(5)
Identity matrix	sp.**eyes**(5)
Diagonal Matrix	sp.**diag**(1,2,3,4)
Generate element with func(i,j)	sp.**Matrix**(2,3,func)

Matrix Modification

Delete the i-th row	M.row_del(i)
Delete the j-th column	M.col_del(j)
Row join M1 and M2	M1.row_join(M2)
Column join M1 and M2	M1.col_join(M2)

Indexing(Slicing)

get the element in M at (i,j)	M[i,j]
get the i-th row in M	M.row(i)
get the i-th row in M	M[i,:]
get the j-th column in M	M.col(j)
get the j-th column in M	M[:,j]
get the i-th and the k-th rows	M[[i,k],:]
get the j-th and the k-th columns	M[:,[j,k]]
get rows from i to k	M[i:k,:]
get columns from j to k	M[:,j:k]
get sub-matrix (row i to k,col j to l)	M[i:k,j:l]

Note: All indices start from 0

Basic opertaions

Sum	A+B
Substraction	A-B
Matrix Multiply	A*B
Scalar Multiply	5*A
Elementwise product	sp.matrix_multiply_elementwise(A,B)
Transpose	A.T
Determinant	A.det()
Inverse	A.inv()
Condition Number	A.condition_number()
Row count	A.rows
Column count	A.cols
Trace	A.trace()

Elementary Row Operations

Replacement	m.row_op(i, **lambda** ele,col:ele+m.row(j)[col]*c)
Interchange	M.row_swap(i,j)
Scaling	m.row_op(i,**lambda** ele,col:ele*c)

Linear Equations

Echelon From	M.echelon_form()
Reduced Echelon Form	M.rref()
Solve AX=B (B can be a matrix)	x,freevars=A.gauss_jordan_solve(B)
least-square fit Ax=b	A.solve_least_squares(b)
solve Ax=b	A.solve(b)

Vector Space

Basis of column space	M.columnspace()
Basis of null space	M.nullspace()
Basis of row space	M.rowspace()
Rank	M.rank()

Eigenvalues amd Eigenvectors

Find the eigenvalues	M.eigenvals()
Find the eignevalues and the corresponding eigenspace	M.eigenvects()
Diagonalize a matrix	P, D = M.diagonalize()
test if the matrix is diagonalizable	M.is_diagonalizable
Calculate Jordan From	P, J = M.jordan_form()

Decomposition

LU Decomposition(PA=LU)	P,L,U=A.LUdecomposition()
QR Decomposition	Q,R=A.QRdecomposition()

Vector Operations

Create a column vector	v=sp.Matrix([1,2,3])
dot product	v1.dot(v2)
cross product	v1.cross(v2)
length of the vector	v.norm()
normalize of vector	v.normalize()
the projection of v1 on v2	v1.project(v2)
Gram-Schmidt orthogonalize	sp.GramSchmidt([v1,v2,v3])
Gram-Schmidt orthogonalize with normalization	sp.GramSchmidt([v1,v2,v3],True)
Singular values	M.singlular_values()

Block Matrix

Create a matrix by block	M=sp.Matrix([[A,B],[C,D]])

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Useful Links

SymPy Documentation

SymPy Tutorial

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