

# Image Representation and Formation

Instructor

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# Outline

- ❖ What are (digital) images?
- ❖ What is image/video processing?
- ❖ What are basic components of image/video processing systems?
- ❖ Why should students study image/video processing?
- ❖ How do we represent digital images?
- ❖ How can we acquire digital images?
- ❖ Is there any tool/library for processing images?

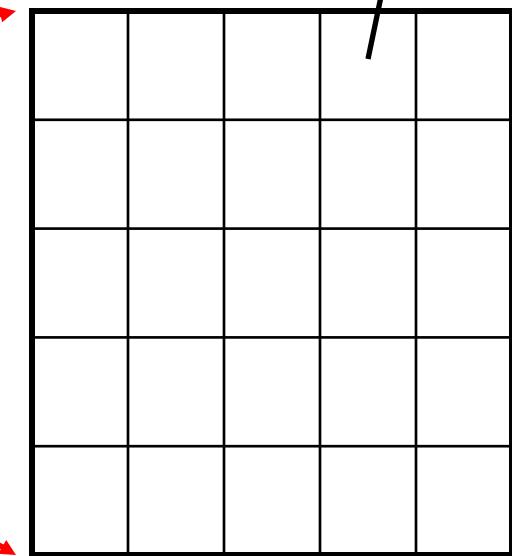
# Images: What are about?

- ❖ Images:
  - ✖ Rectangular shapes of shades or colors



# Digital Images: What are about?

- ❖ Digital Images:
  - ☞ **Space (rectangular shape): is digitalized into matrix of rectangular cells which is called pixels.**



# Digital Images: What are about?

## ❖ Digital Images:

 **Shades or colors: are digitalized into discrete sets.**

- ✓ Gray images: that set is [0,255]
- ✓ RGB Color images: each set for Red, Green, and Blue color, values in the sets range from 0 to 255.

# Image/Video Processing: What is about?

❖ Multi-kinds of processing tasks:

☞ **Simple: Scaling, rotating an image**

☞ **Others:**

✓ Enhancement:

- Obtain a better image from a bad image.

✓ Restoration

- Recover from damaged images.

✓ Compression

- Reduce the size of images with/without loss of the quality.

✓ Segmentation

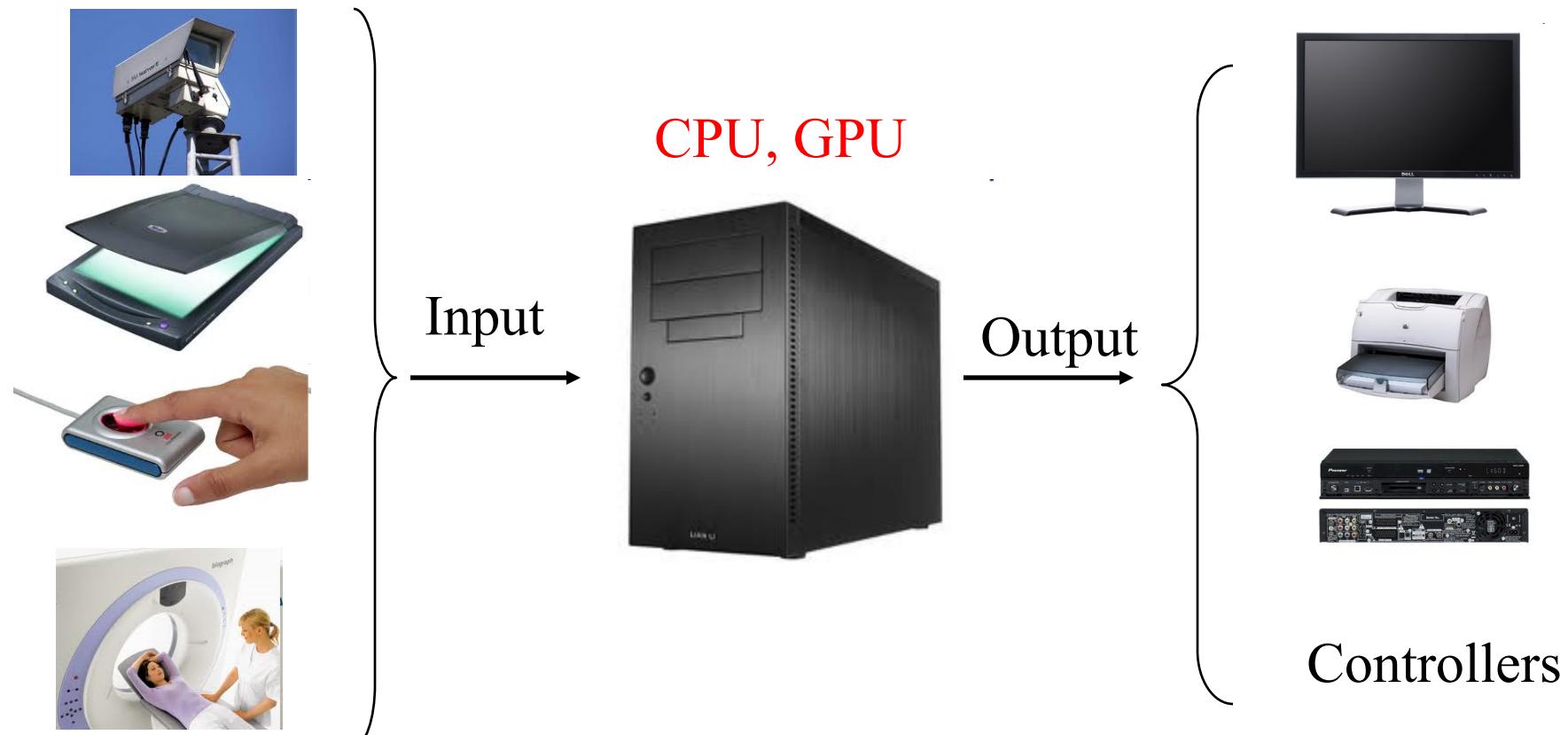
- Obtain interested objects from the whole image.

✓ Recognition

- Recognize, classify, or identify objects.

✓ ...

# Image/video processing systems: basic components



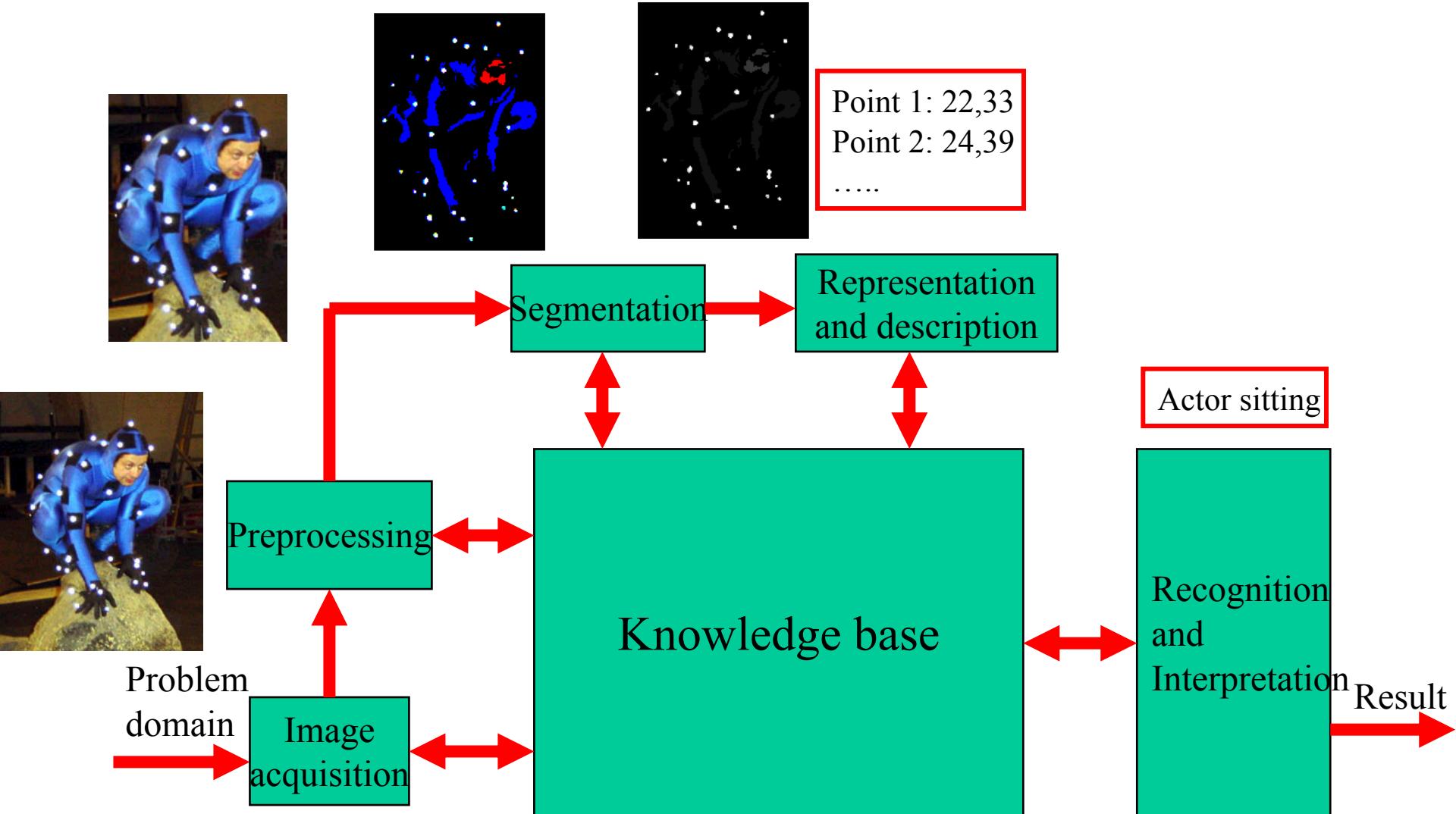
# Image/video processing systems: basic components

## ❖ Hardware:

- ☞ **PC: Host and run processing modules**
- ☞ **Input: cameras, scanner,...**
- ☞ **Output: Display, Recorder, other controller**

## ❖ Software:

- ☞ **Libraries**
- ☞ **Processing modules (typical: the following figure)**



# Why should students study image/video processing?

❖ Why should students study image/video processing?

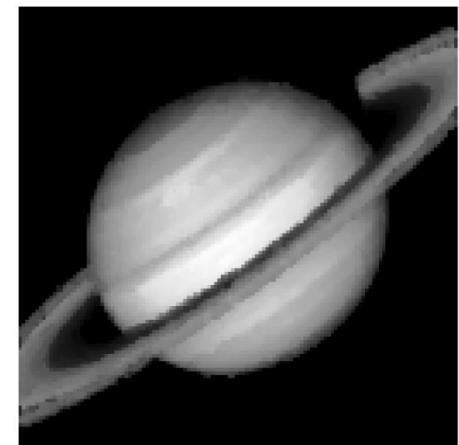
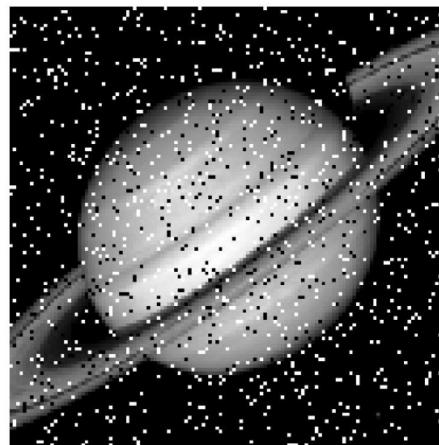
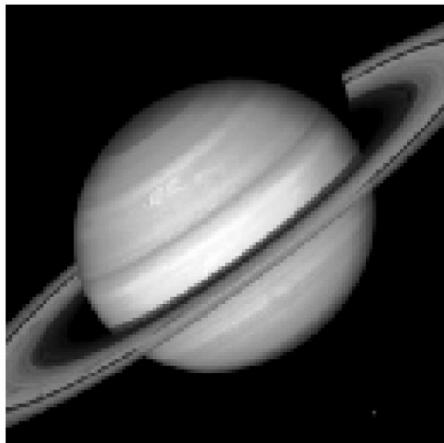
☞ **Usefulness/Applications**

☞ **Challenge**

☞ **Activeness**

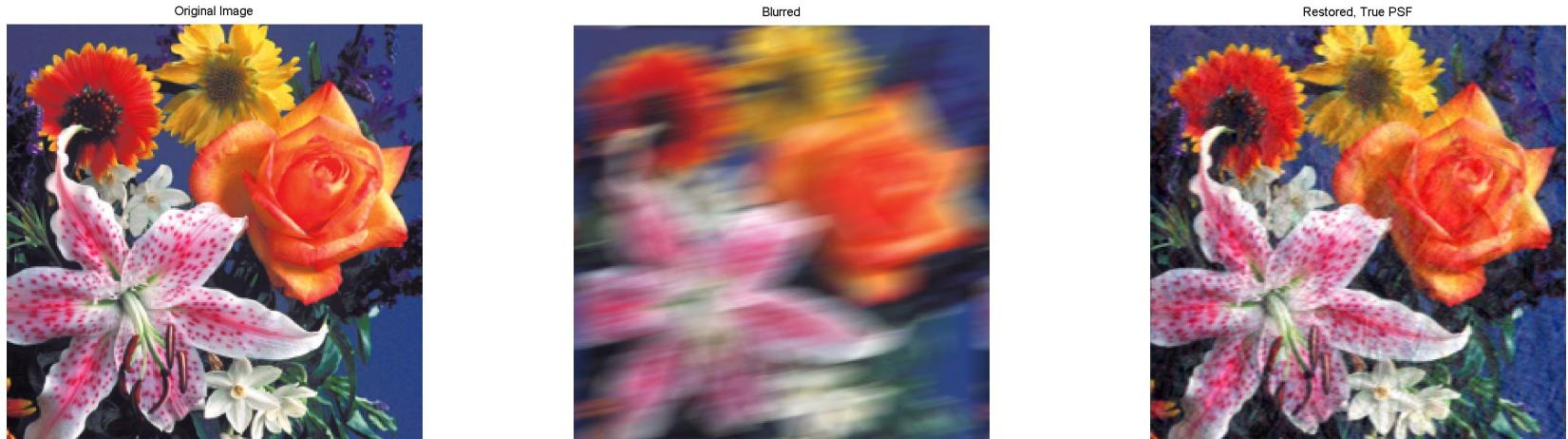
# Applications

# Examples: Image Correction



- ❖ Needed when image data is erroneous:
  - ☞ **Bad transmission**
  - ☞ **Bits are missing: *Salt & Pepper Noise***

# Image Deblurring: Motion Blur



- ❖ Can be used when a camera or object is moved during exposure

# Deblurring



- ❖ Can be used when the camera was not focused properly!!

# Image manipulation

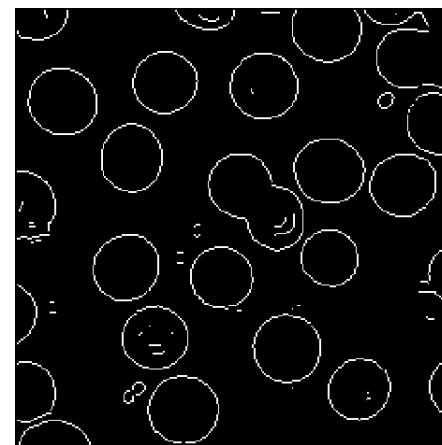
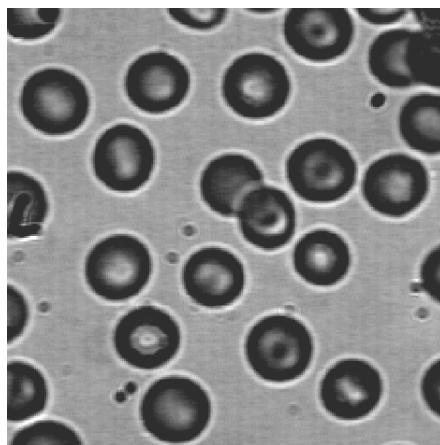
- ❖ Image improvement, e.g. too dark image



- ❖ Rotate + scale

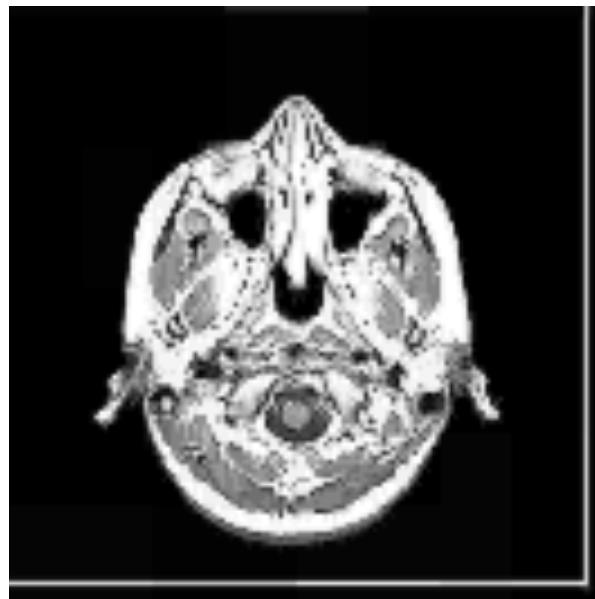


# Medical Image Processing



- ❖ Image Processing is widely used
- ❖ E.g. Analysis of microscopic images

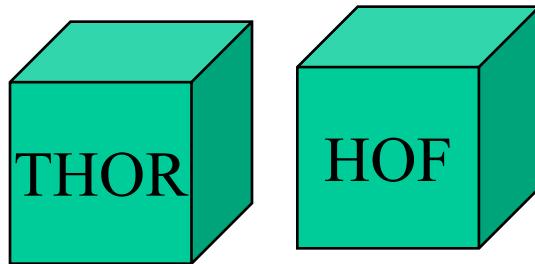
# Medical Image Processing



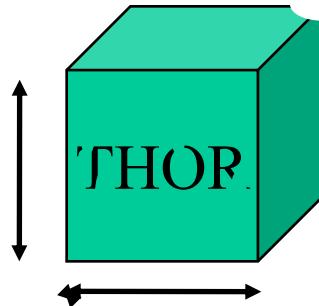
- ❖ MR/CT Imaging of a human body
- ❖ Use for Brain Surgery

# Machine vision applications

- ❖ Classification

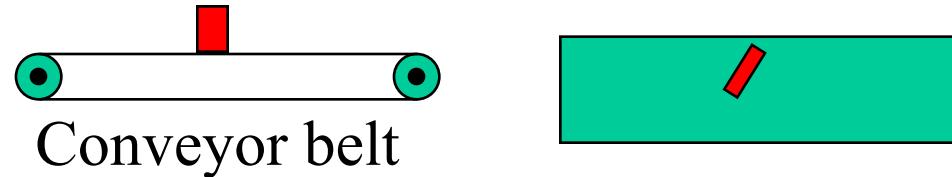


- ❖ Quality control



- ❖ Pose estimation

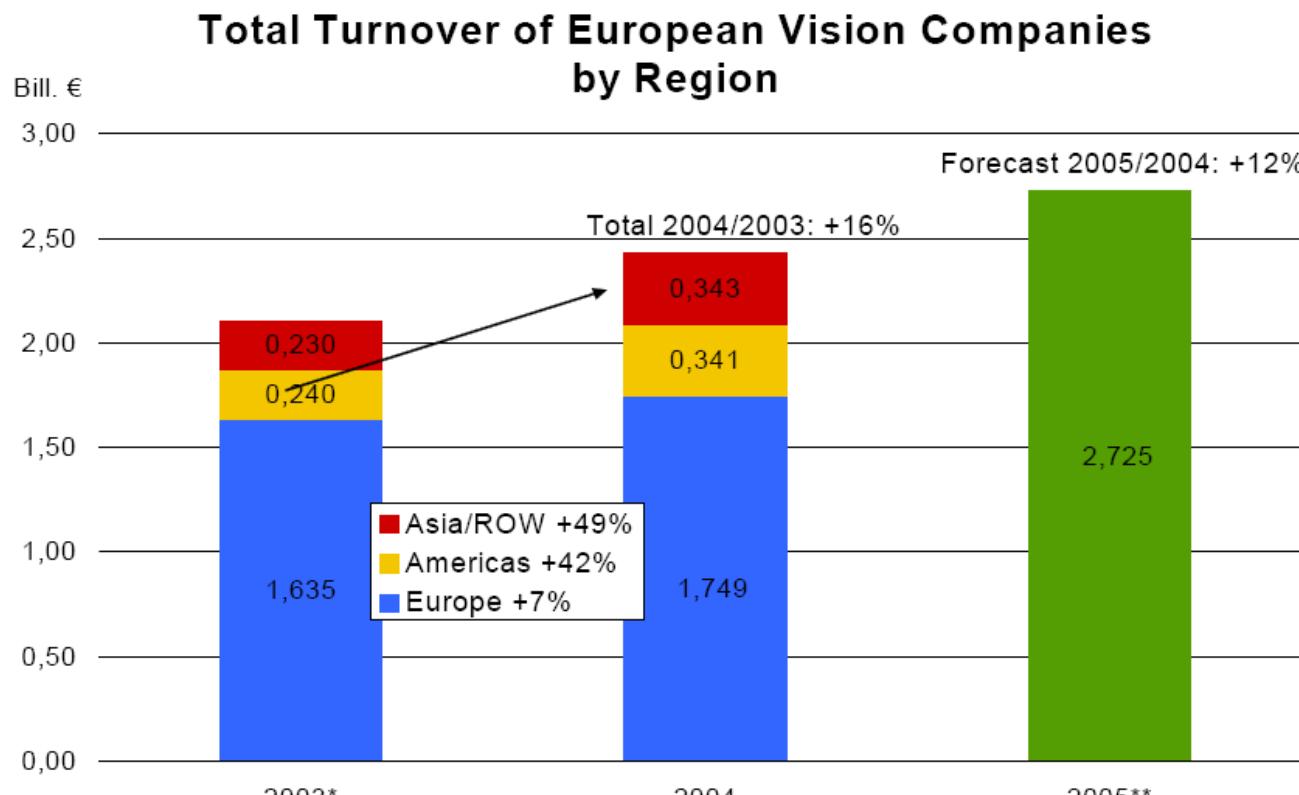
- ❖ **Pick and place applications**



- ❖ **Bin-picking**



# Machine vision

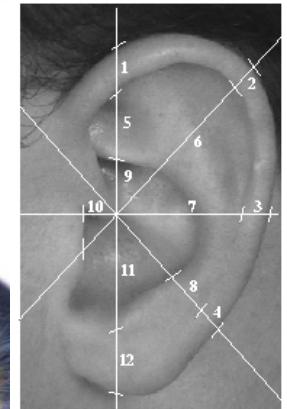
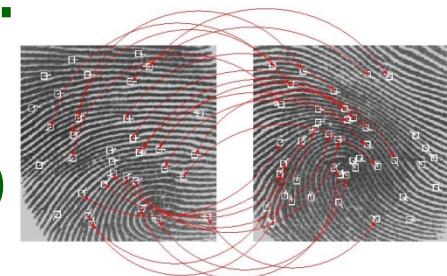


\* estimated total turnover of Europe

\*\*based on forecasts of 60 companies

# Biometrics

- ❖ Recognizing/verifying the identity of a person by analyzing one or more characteristics of the human body
- ❖ Characteristics:
  - ☞ **Fingerprint, eye (retina, iris), ear, face, heat profile, shape (3D face, hand), motion (gait, writing), ..**
- ❖ Applications:
  - ☞ **Verifying: Access control (bio-passports)**
  - ☞ **Recognizing, tracking: Surveillance**



# Chroma keying



# Analysis of Sport Motions



- ❖ Here: Analysis of motion of Sarah Hughes
- ❖ 3D Tracking of body parts
- ❖ Motion interpretation
- ❖ Action recognition

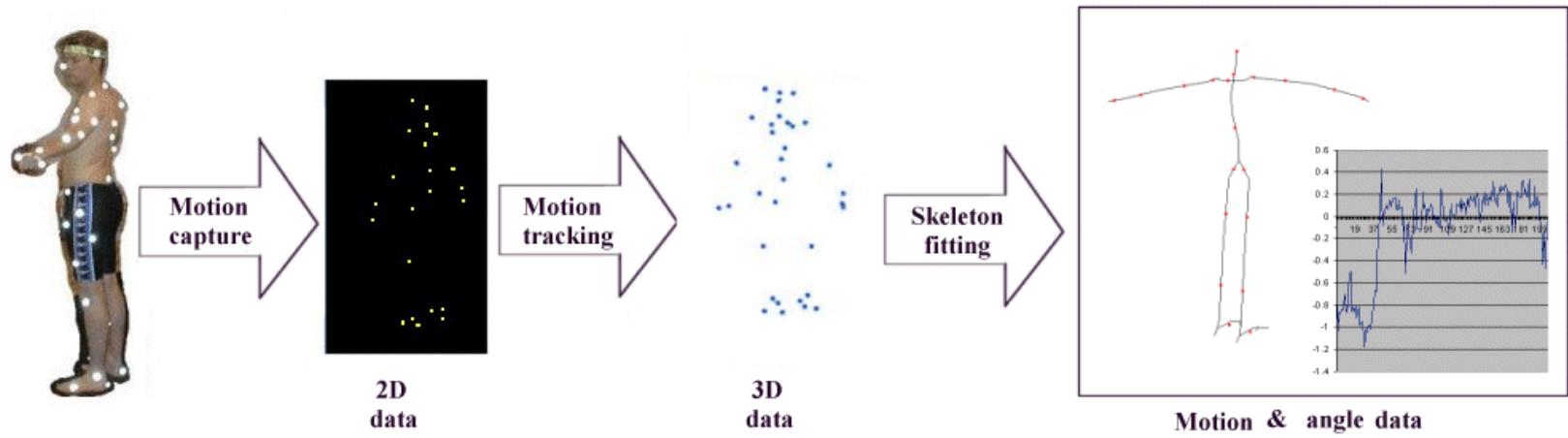
# Motion Capture

- ❖ Special effects
  - ☛ Advertising
  - ☛ Movies



Andy Serkis

# Motion Capture



# Challenges

# Image/Video Processing: Challenges

- ❖ Almost of processing tasks in image/video processing need further improvements for being done automatically, being done more efficiently, being realistic
  - ☞ **Enhancement:** We have many techniques, all of them can not results the same quality for every applications. They depend on many thresholds which affects the quality of the enhancement also.
  - ☞ **Compression:** How can we transmit in real-time a large amount of data from multiple cameras in the network to realize 3D applications?
  - ☞ **Analysis:**
    - ✓ How can we detect and analyze automatically the activities of humans in complex scenes like railway station, airport, etc ?
    - ✓ How can we detect and diagnose automatically diseases of human?

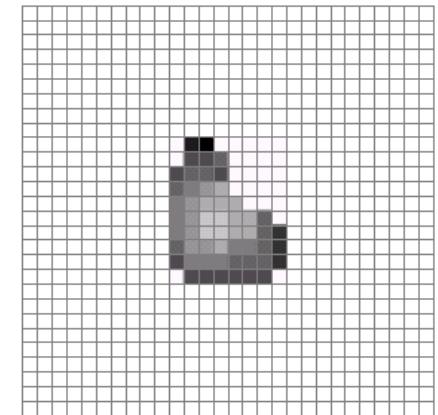
# Activeness

# Image/Video Processing: Activeness

- ❖ Many research groups around the world working on Image Processing and Computer Vision
- ❖ Many conferences and transactions organized for the field
  - ☞ ICIP: International Conference on Image Processing
  - ☞ CVPR: International Conference on Computer Vision and Pattern Recognition
  - ☞ IEEE Transactions on Image Processing
  - ☞ IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)
  - ☞ ...

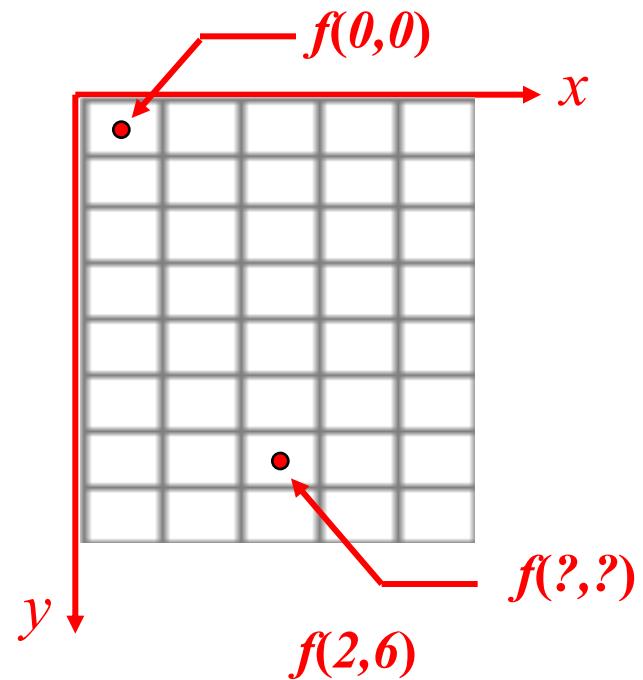
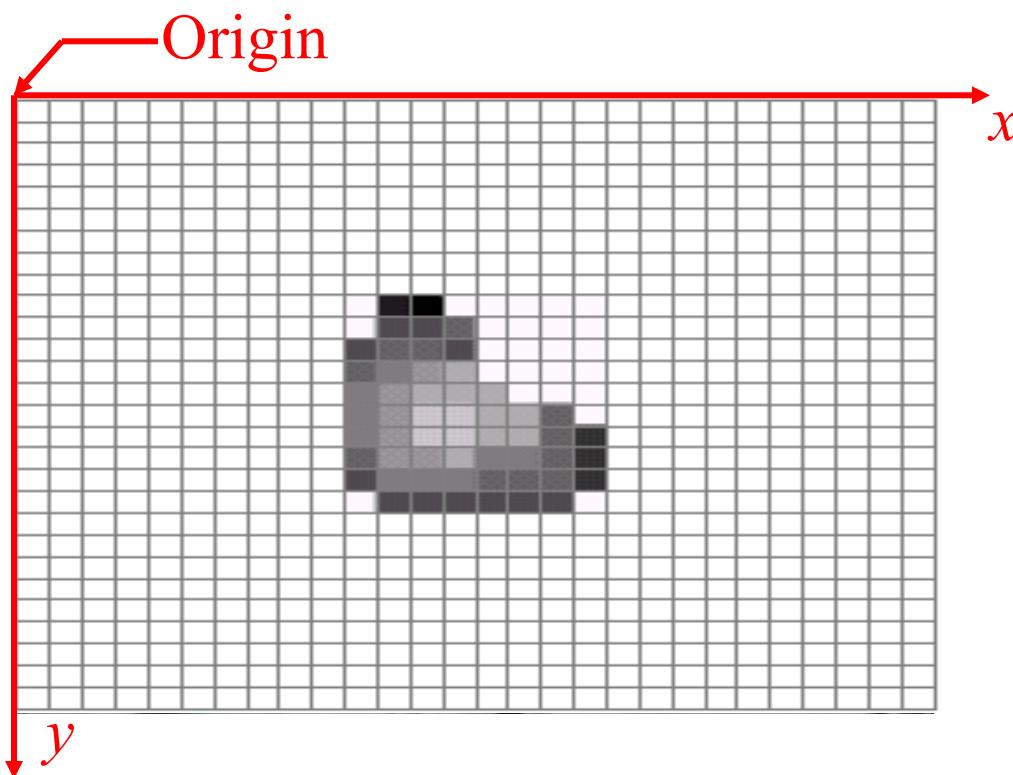
❖ How do we represent images?

# Digital Image Representation



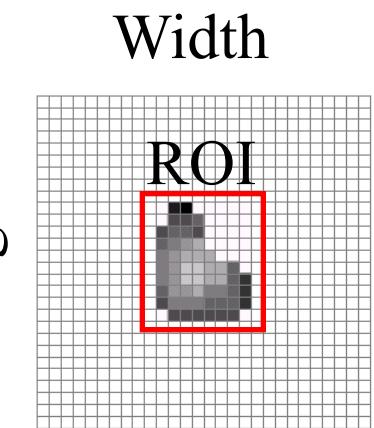
- ❖ Image is seen as a **discrete function  $f(x,y)$**  as opposed to a continuous function (show)
- ❖ x and y **cannot** take on any value!

# Discrete image coordinate system



# Digital Image Representation

- ❖ An image  $f(x,y)$  is represented as an *2D Array, matrix*
- ❖ Width =
  - ☞ **number of pixels in x-direction**
- ❖ Height =
  - ☞ **number of pixels in y-direction**
- ❖ Size (width  $\times$  height)
- ❖ ROI = region of interest
  - ☞ **To reduce the amount of data**



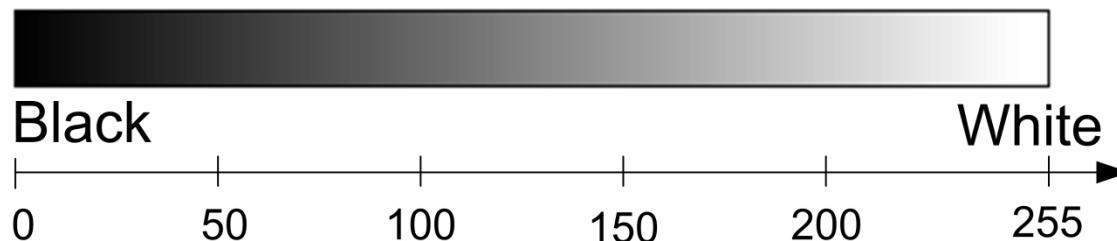
# Digital Image Representation

## ❖ Pixel representation:

### ⦿ **Gray images:**

- ✓ Pixel's values are on or inside of [0,255]
- ✓ Pixel's value = 0: black
- ✓ Pixel's value = 255: white

Shades of grey



# Digital Image Representation

202	134	112	122	...	112
209	133	112	126	...	102
223	151	94	108	...	106
233	166	109	115	...	126
...	...	...	...	...	...
132	138	147	131	...	95

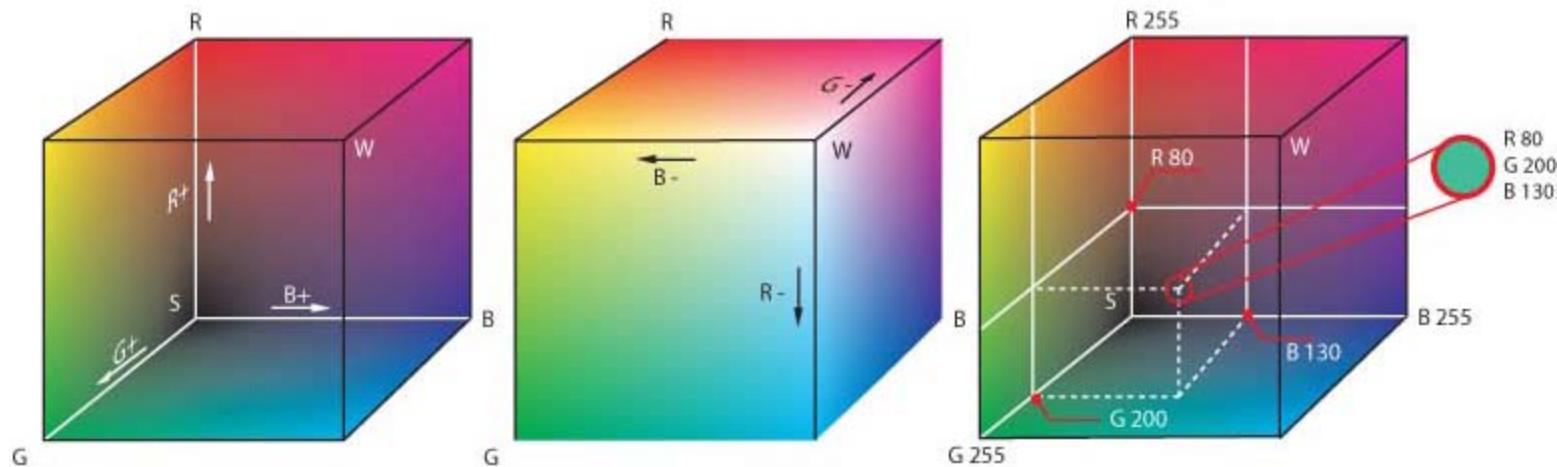


# Digital Image Representation

## ❖ Pixel representation:

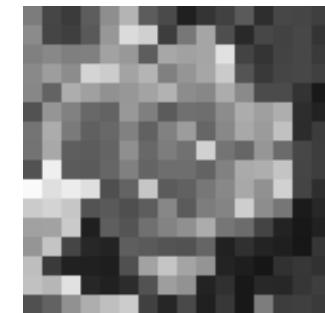
### ❖ Color images:

- ✓ A color = a combination of a red, a green, and a blue shade
- ✓ An pixel is represented by a triple [R,G,B].
- ✓ An image has 3 planes: R, G, and B-plane



# Spatial Image Resolution:

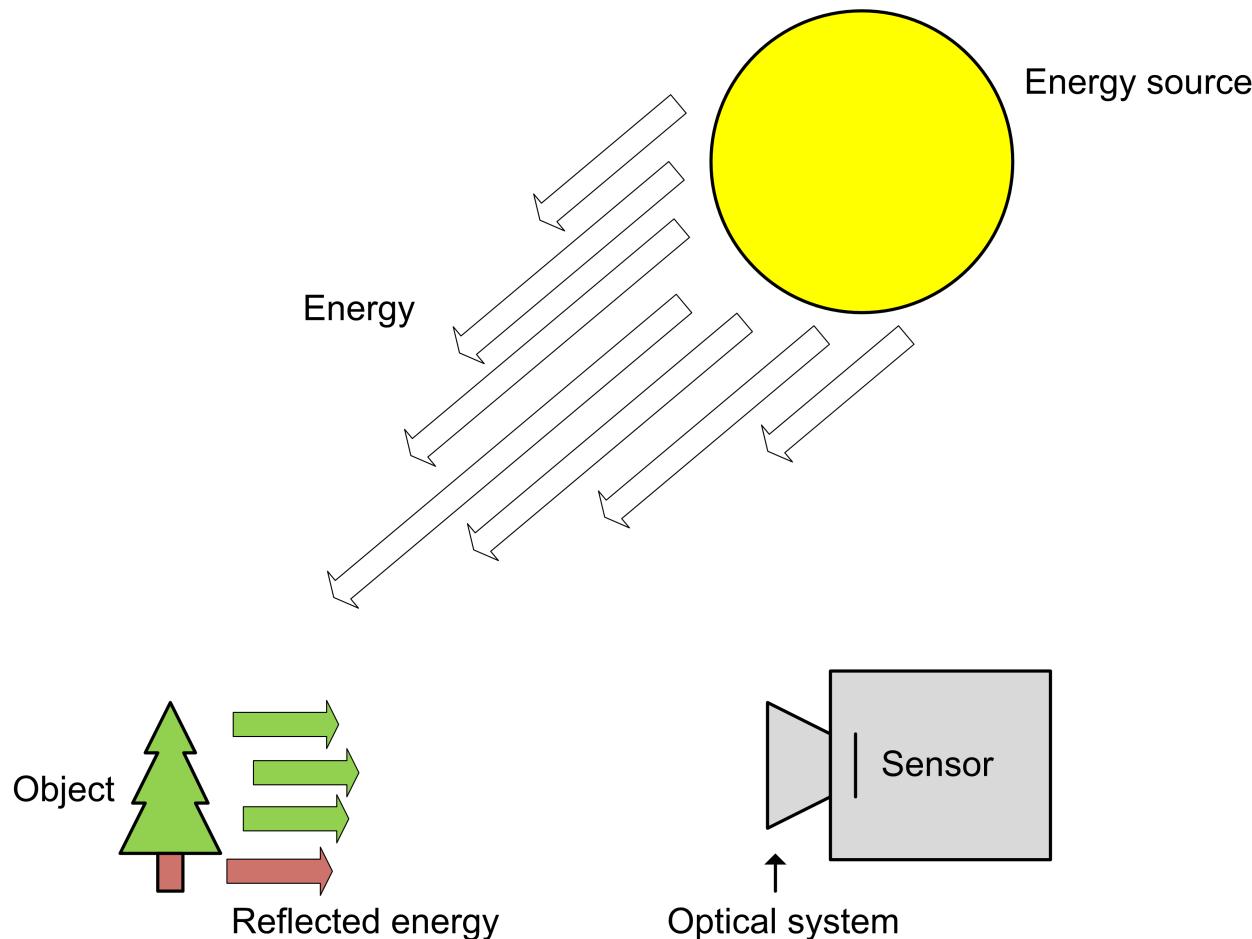
- ❖ Resolution
  - ☞ **The size of an area in a scene that is represented by one pixel in the image**
- ❖ Different Resolutions are possible (256x256....16x16)



- ❖ Lower resolution leads to data reduction!

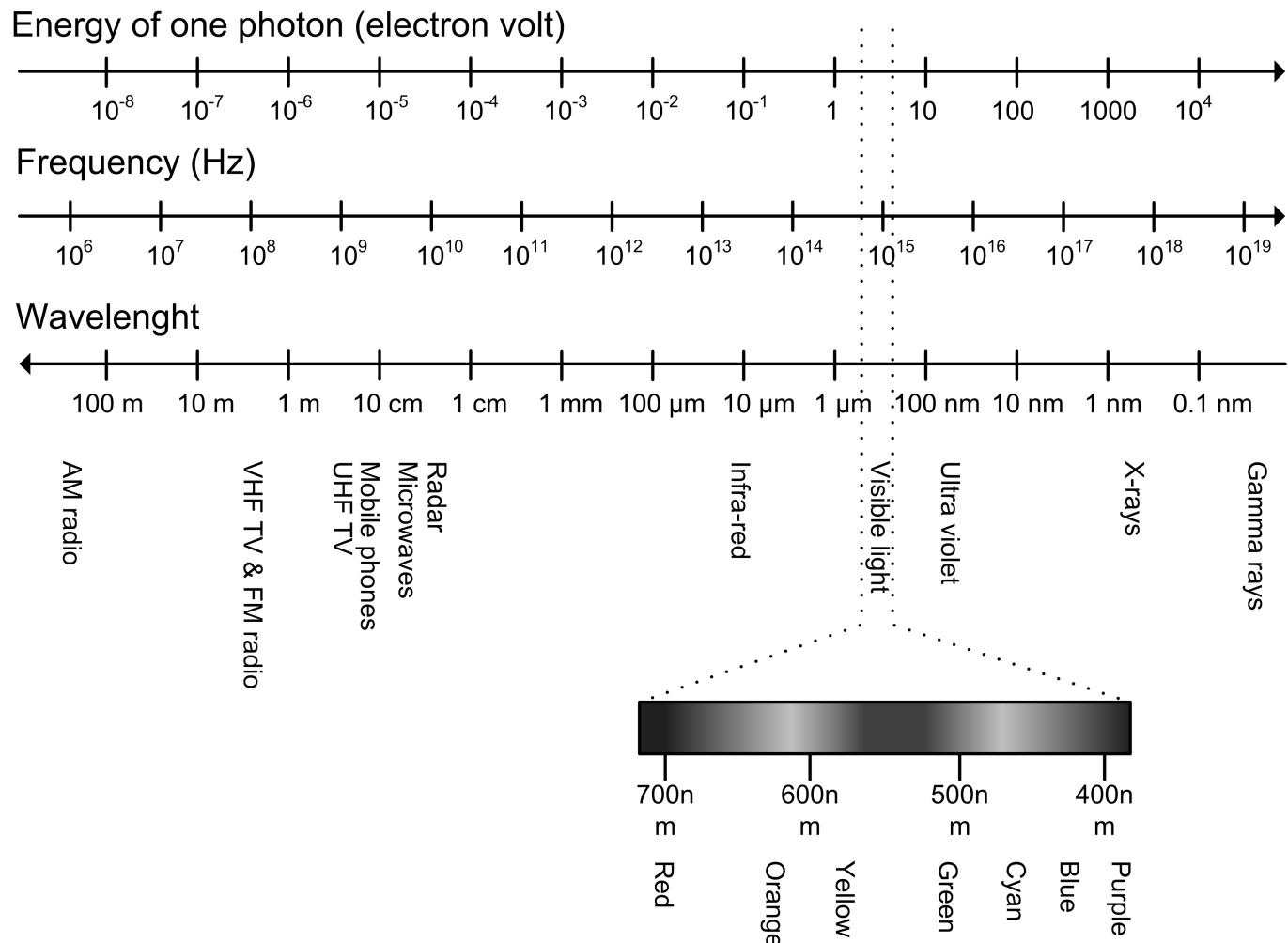
❖ How can we acquire images?

# Where does an image come from?



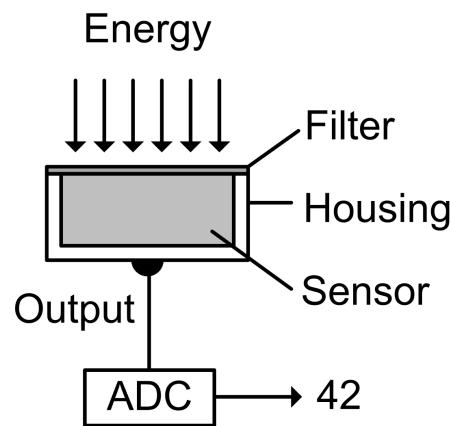
# Where does an image come from?

## Electromagnetic spectrum

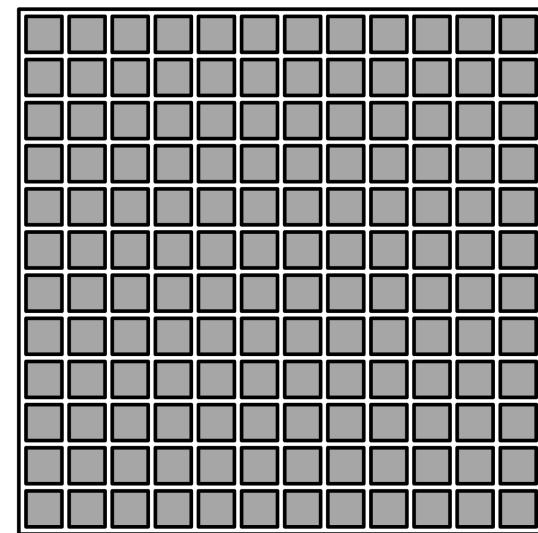


# Where does an image come from?

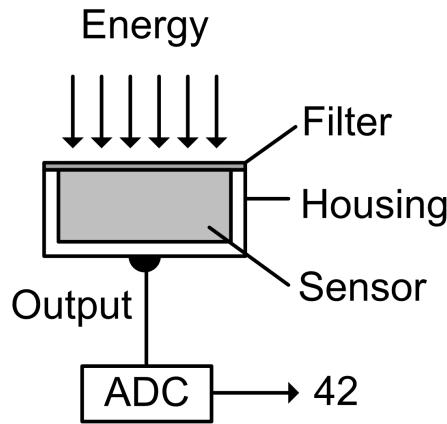
Single cell



Charged coupled device  
CCD-chip



# Where does an image come from?



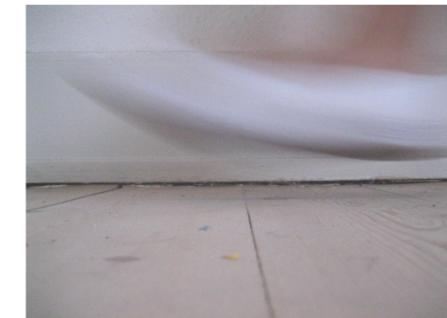
Correctly exposed



Over exposed



Under exposed



Motion blur

## ❖ Integration over time

### 🕒 Exposure time

✓ Shutter time

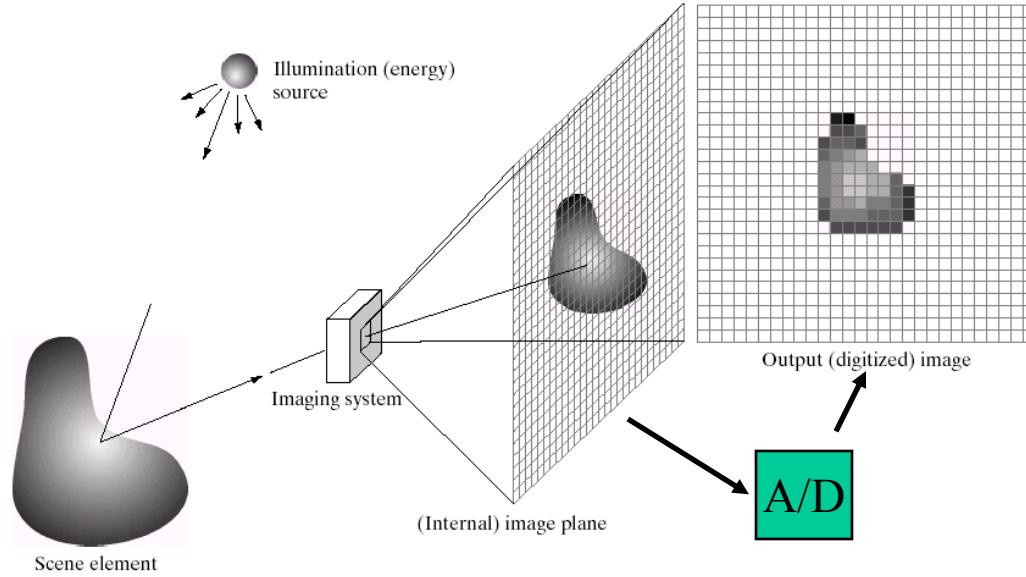
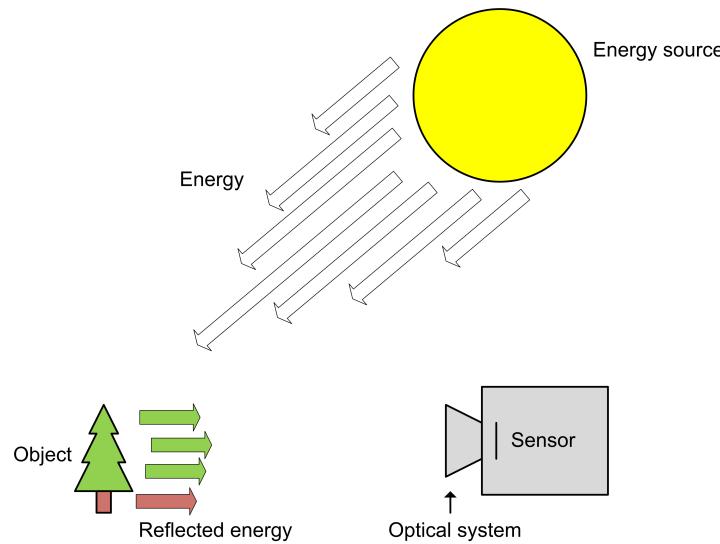
### 🕒 Motion blur

### 🕒 Maximum charge

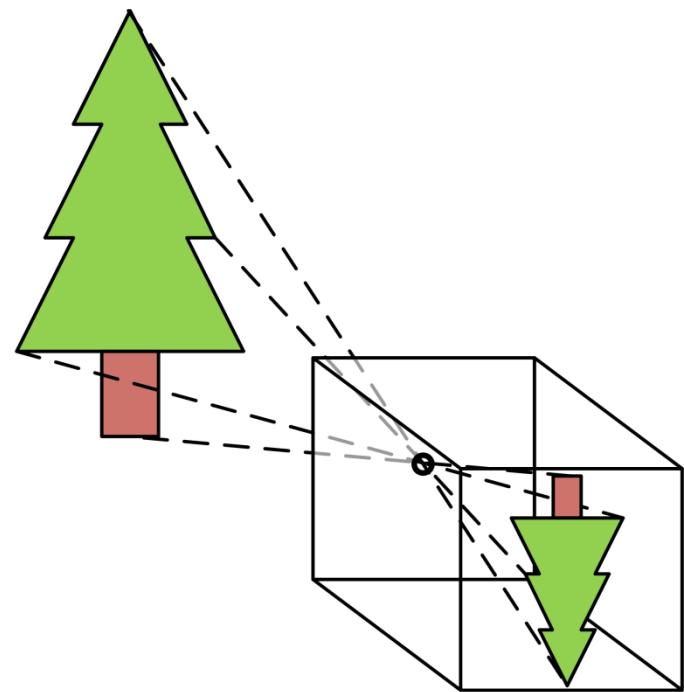
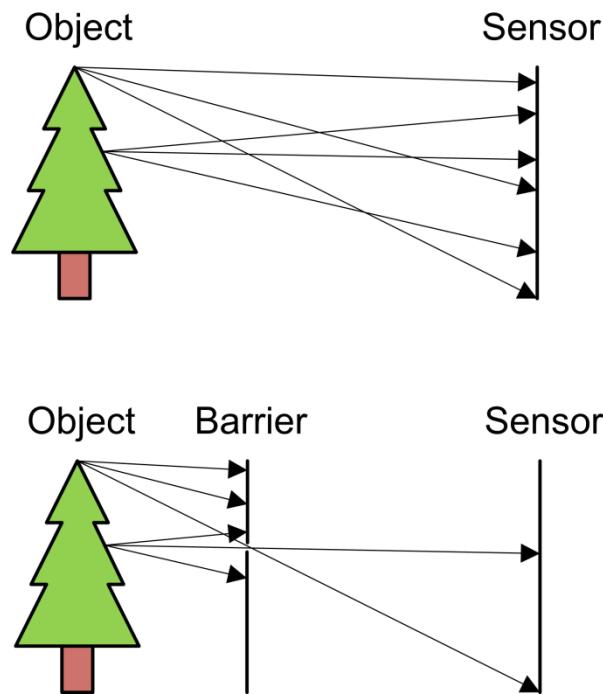
✓ Saturation

✓ Blooming

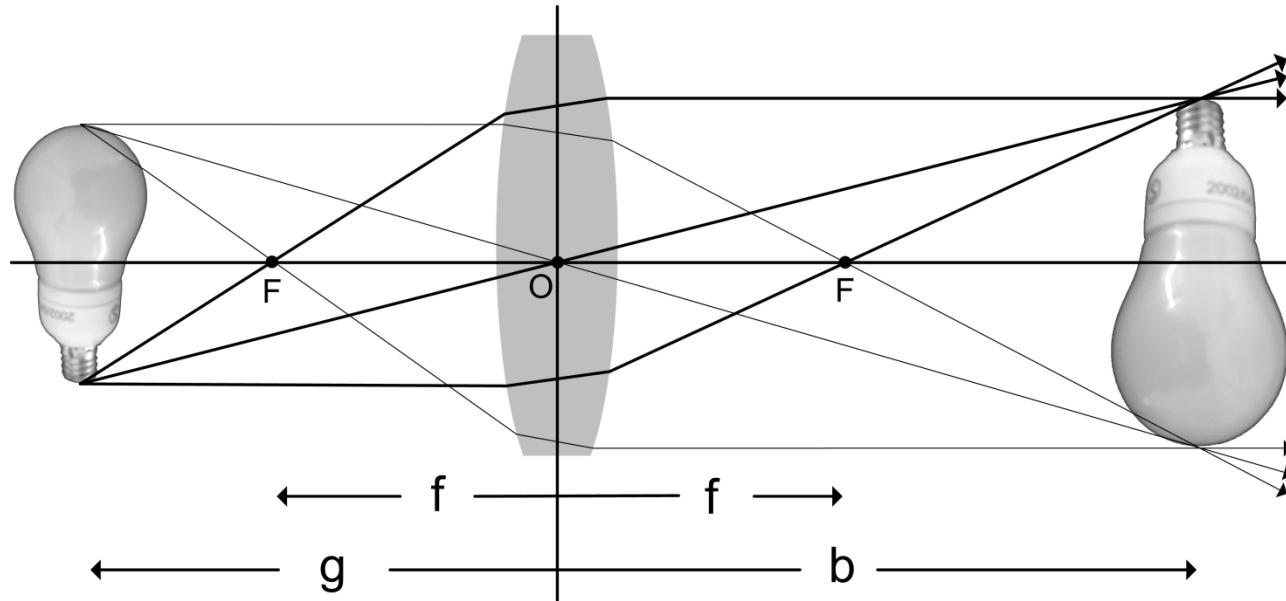
# Image formation - the lens



# The lens

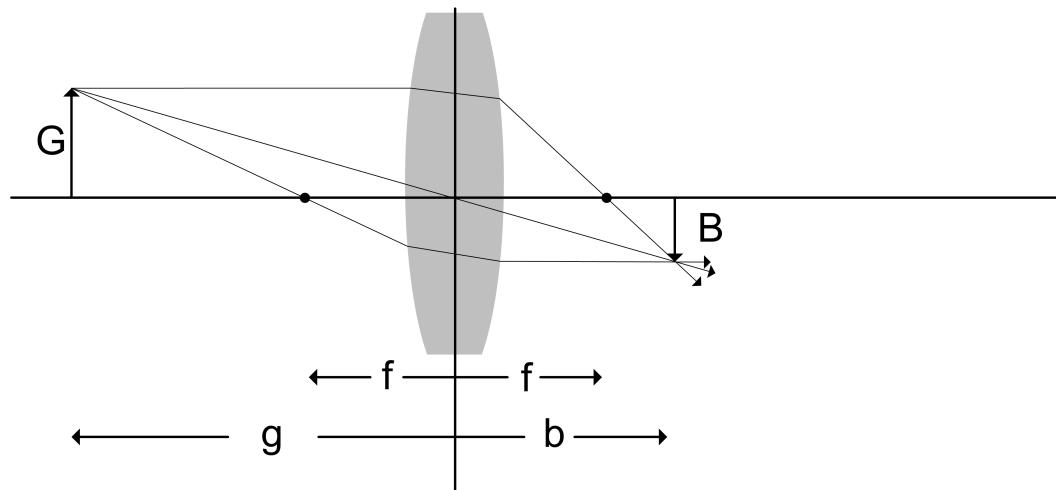


# The lens



- A lens focuses a bundle of rays to one point
- Parallel rays pass through a **focal point**  $F$  at a distance  $f$  beyond the plane of the lens.  $f$  is the focal length
- $O$  is the optical center
- $F$  and  $O$  span the optical axis/principal axis

# Focus



$$\frac{1}{g} + \frac{1}{b} = \frac{1}{f}$$

In focus



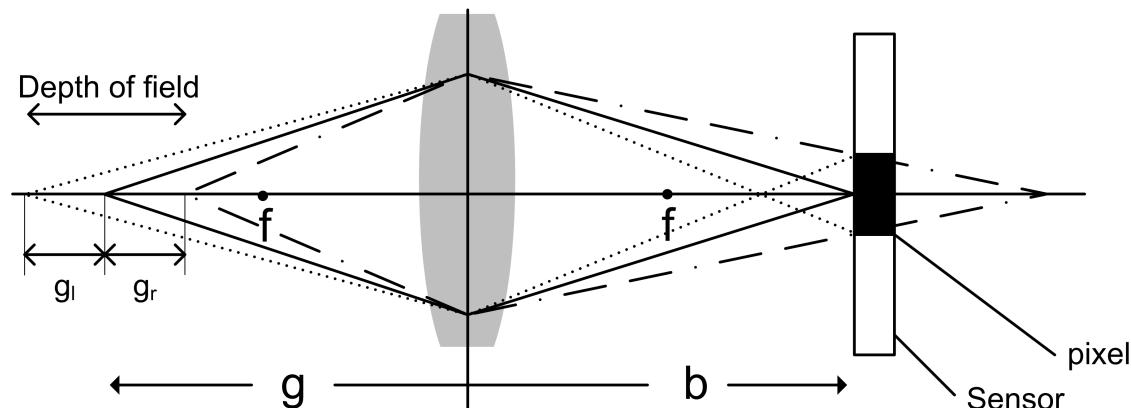
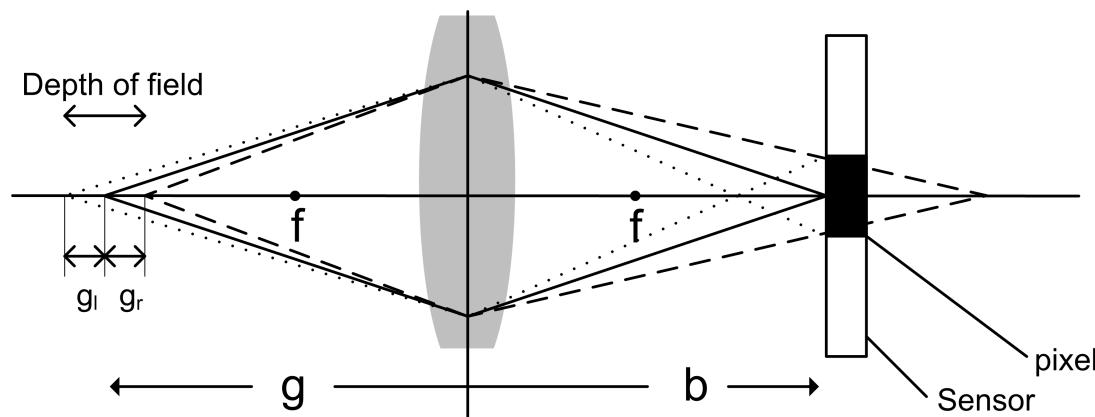
Not in focus



(vis på oh)

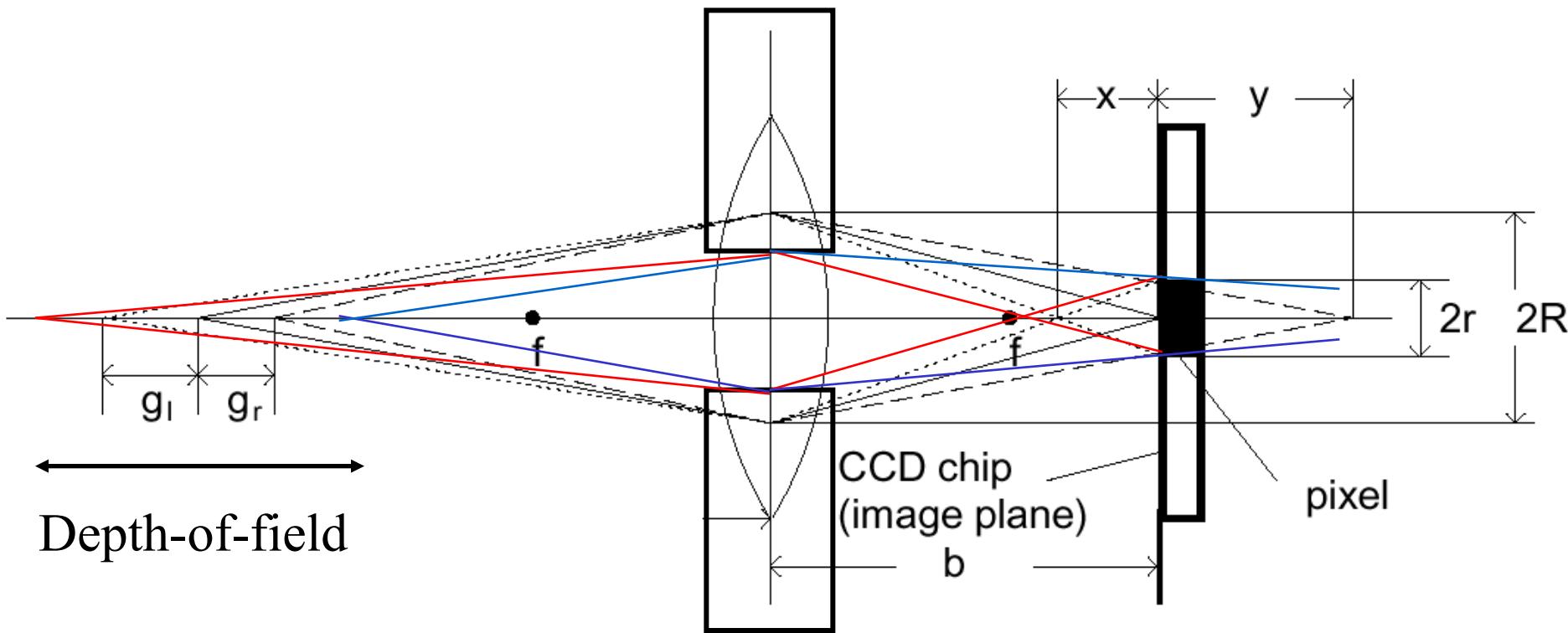
# Focus and depth-of-field

- Depth-of-field is the distance from the nearest to the farthest object in front of the camera that can be captured sharply in the result image, i.e., the blur does not exceed a certain value



$$\frac{1}{g} + \frac{1}{b} = \frac{1}{f}$$

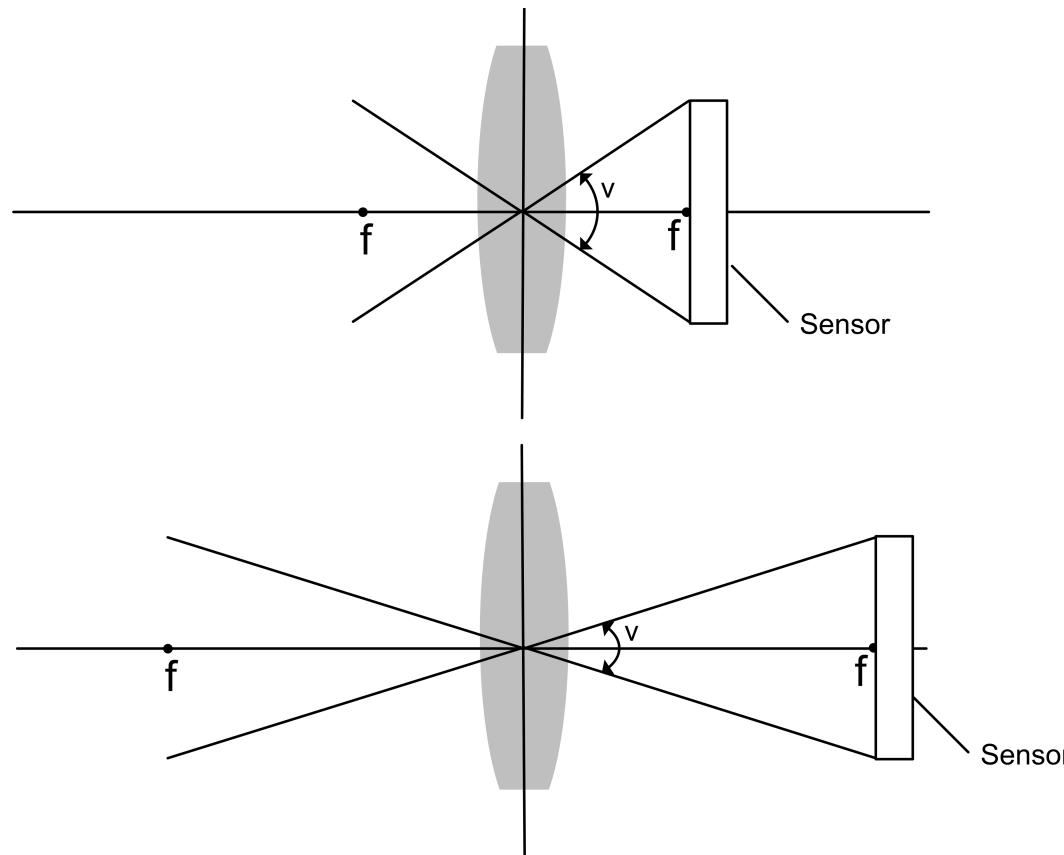
# Aperture



Depth-of-field

- The smaller aperture, the longer the depth of field.
- **Downside:** smaller aperture  $\Rightarrow$  less light enters the camera
  - $\Rightarrow$  increase exposure time
  - $\Rightarrow$  risk of blur due to motion

# Field-of-view

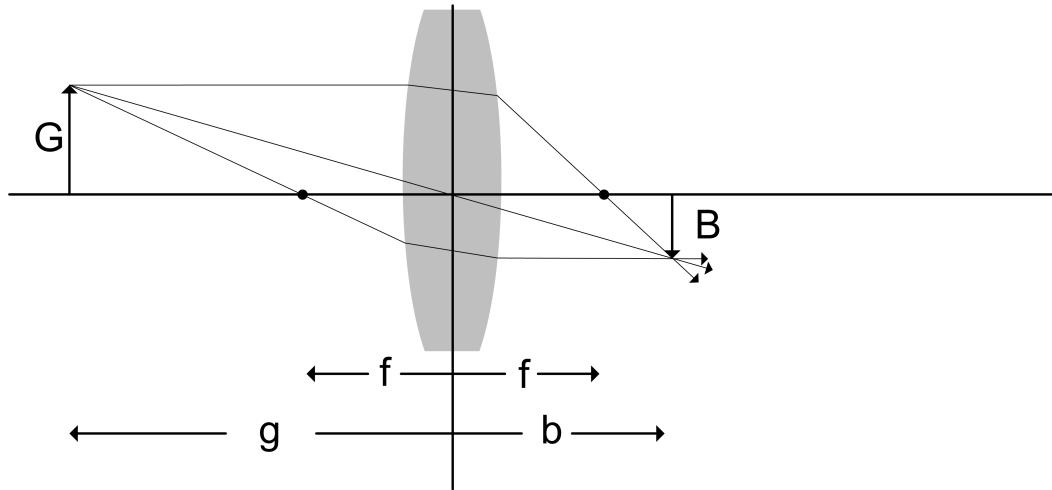


- Field-of-view,  $v$ , depends on size of the sensor and focal length
- "Fisheye" lens  $\Rightarrow$  small focal length and large field-of-view
- Horizontal FOV and Vertical FOV

# Zoom

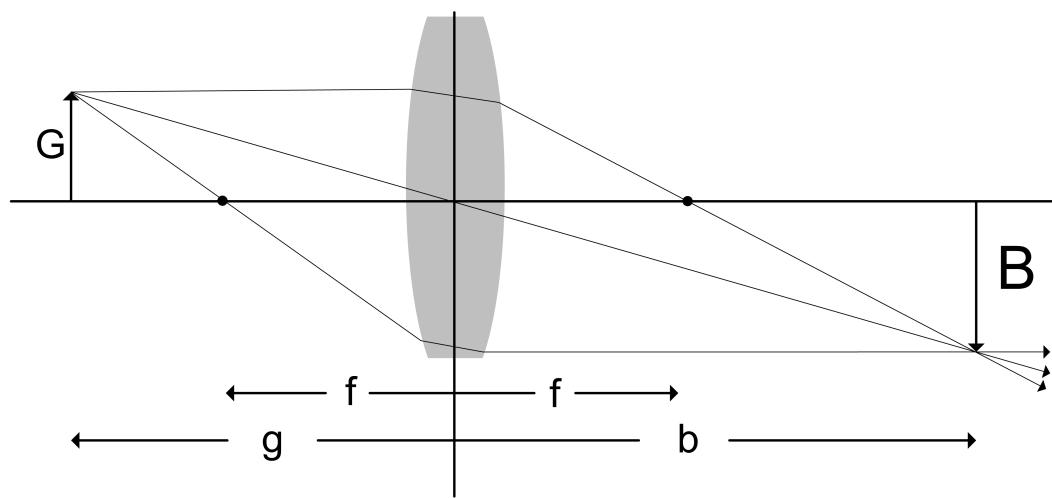
## ❖ Optical zoom

☞ **The optics (lens) is changed  $\Rightarrow$  focal length,  $f$ , is changed**



## ❖ Digital zoom

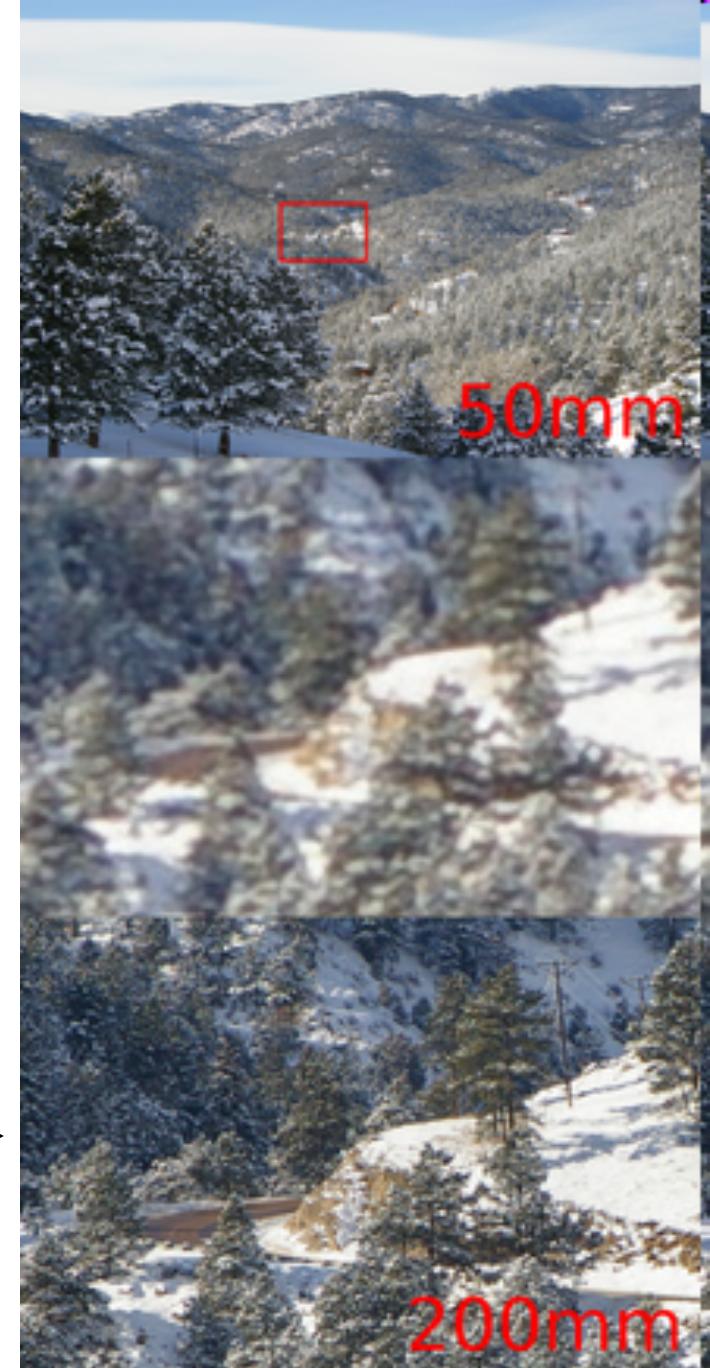
☞ **Interpolation**



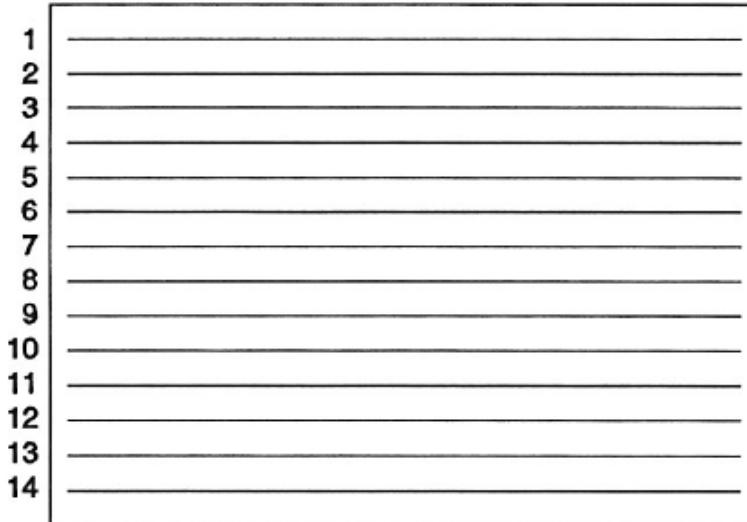
# Zoom

Digital Zoom →

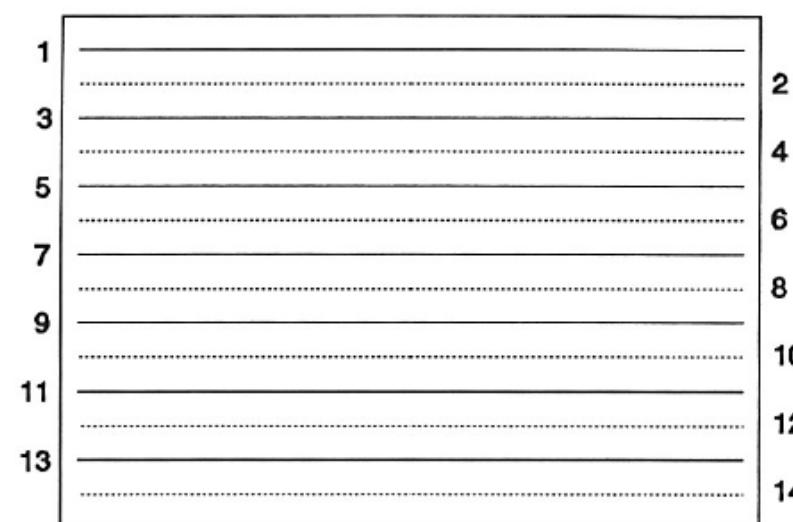
Optical Zoom →



# Progressive vs. Interlaced



Progressive



Interlaced

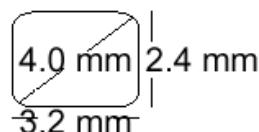


# Sensor Chip Formats

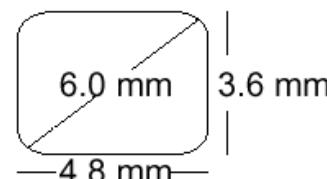
Number of Pixels  
from 500x500  
to 5000x5000

Pixel size  
from  $4\mu\text{m} \times 4 \mu\text{m}$   
to  $16 \mu\text{m} \times 16 \mu\text{m}$

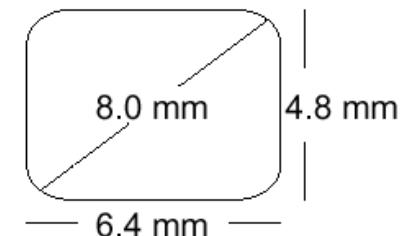
1/4" CCD - Chip



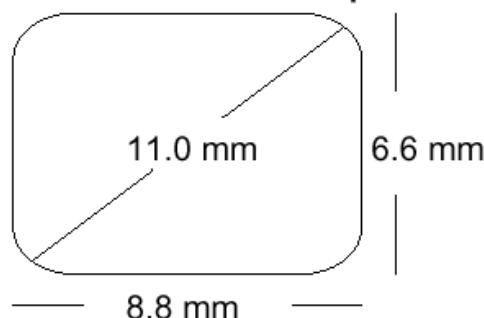
1/3" CCD - Chip



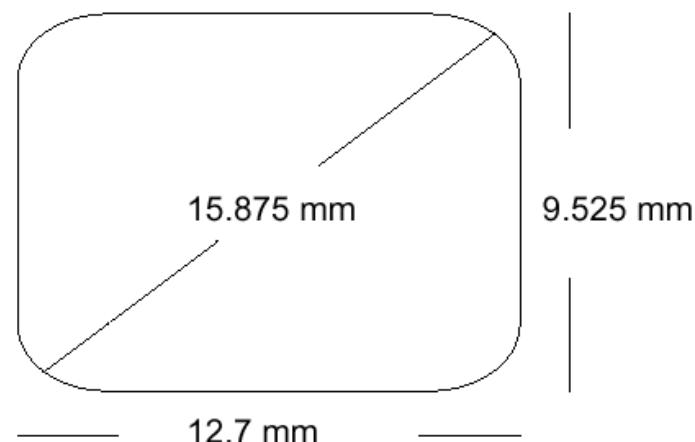
1/2" CCD - Chip



2/3" CCD - Chip



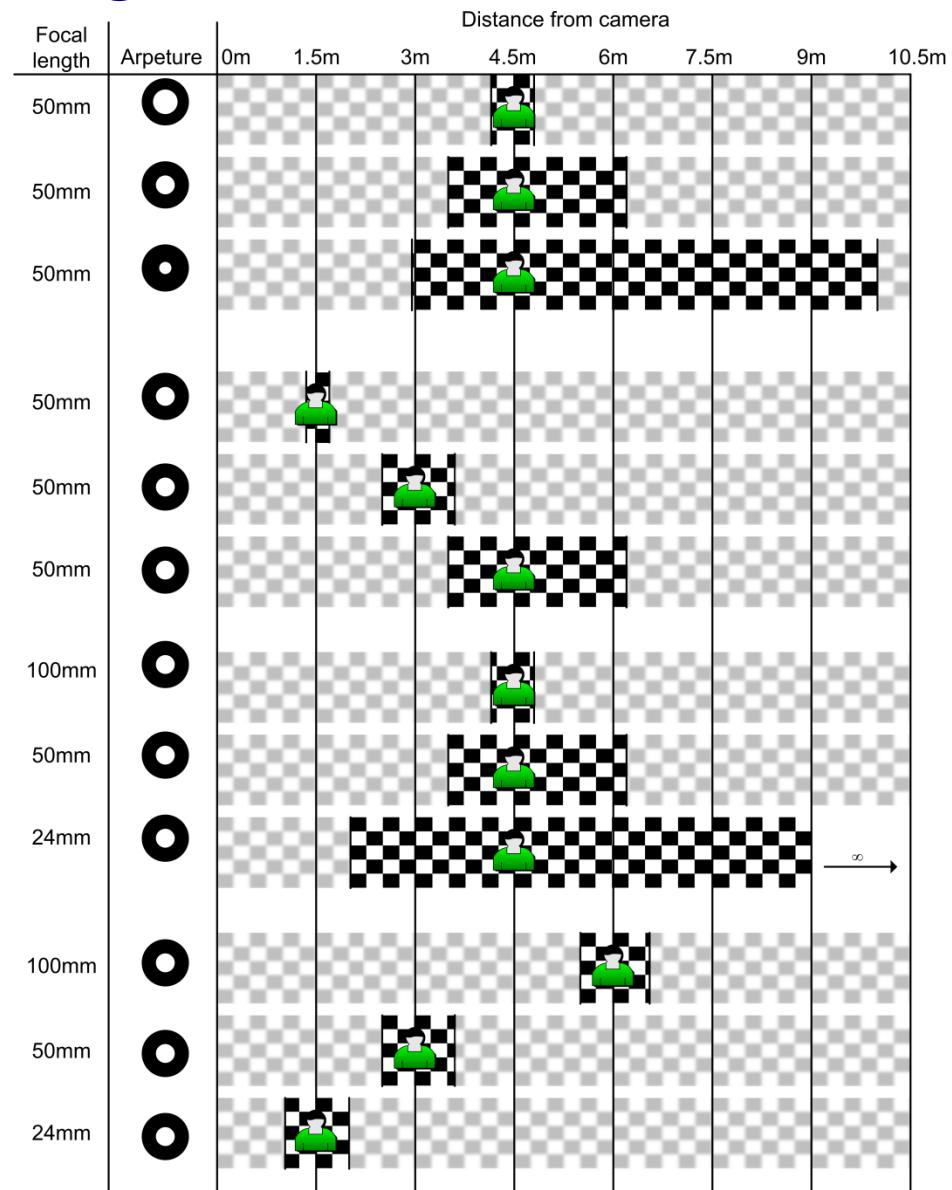
1" CCD - Chip



# A good image...

## ❖ Issues to consider:

- ☞ **Dist. to object**
- ☞ **Motion of object**
- ☞ **Zoom**
- ☞ **Focus**
- ☞ **Depth-of-fields**
- ☞ **Focal length**
- ☞ **Shutter**
- ☞ **Field-of-view**
- ☞ **Aperture (DK: blænde)**
- ☞ **Sensor (size and type)**



# Image file types

- ❖ image.jpg, image.tif, image.gif, image.png, image.ppm, ....
- ❖ Raw:
  - ☞ **No data is lost**
  - ☞ **Header + data (234 235 32 21...)**
  - ☞ **For example: image.pgm**
  - ☞ **The file can be viewed**
- ❖ Lossless compression:
  - ☞ **No data is lost, but the file cannot be viewed**
  - ☞ **For example: image.gif**
- ❖ Lossy compression:
  - ☞ **Better compression**
  - ☞ **Some data is lost (optimized from the HVS' point of view)**
  - ☞ **The file cannot be viewed**
  - ☞ **For example: image.jpg**



# Image file types

- ❖ Normally you don't care about the file type
  - ☞ **The application will take care of it for you:**
  - ☞ **For example: rotate**
    - ✓ Application
      - image.x => raw
      - Rotate the raw image
      - Rotated raw => rotated\_image.x
- ❖ But to write your own programs from scratch the images need to be in the raw format (without a header)

# Is there any tool/library for processing images?

- ❖ MATLAB

-  **Demonstrations**

- ✓ Image: Read, Write, Display, Simple Process

- ❖ OpenCV