

BÀI 2: CÁC THUẬT TOÁN TÌM KIẾM: BFS, DFS, VÀ UCS (tiếp theo)

I. MỤC TIÊU:

Sau khi thực hành xong bài này, sinh viên nắm được:

- Thuật toán tìm kiếm BFS, DFS trên cây tìm kiếm.
- Áp dụng các thuật toán này vào các bài toán thực tế.

II. TÓM TẮT LÝ THUYẾT:

1. Cấu trúc dữ liệu của các node trong cây tìm kiếm:

- State: trạng thái trong không gian trạng thái.
- Node: chứa 1 trạng thái, con trỏ tới predecessor, độ sâu, và chi phí đường đi, hành động.
- Depth: số bước dọc theo đường đi từ trạng thái ban đầu.
- Path Cost: chi phí đường đi từ trạng thái ban đầu tới node.
- Fringe: bộ nhớ lưu trữ các node mở rộng. Ví dụ, s là stack hoặc hàng đợi.

2. Các hàm thực thi:

- Make-Node(state): khởi tạo 1 node từ 1 trạng thái (state).
- Goal-Test(state): trả về true nếu state là trạng thái kết thúc.
- Successor-Fn(state): thực thi các hàm successor (mở rộng một tập các node mới với tất cả các hành động có thể áp dụng trong trạng thái).
- Cost(state, action): trả về chi phí thực thi hành động trong trạng thái.
- Insert(node, fringe): thêm 1 node mới vào fringe.
- Remove-First(fringe): trả về node đầu tiên từ fringe.

3. General Tree-Search Procedure:

```

function TREE-SEARCH(problem, fringe) returns a solution, or failure

fringe  $\leftarrow$  INSERT(MAKE-NODE(INITIAL-STATE[problem]), fringe)
loop do
    if EMPTY?(fringe) then return failure
    node  $\leftarrow$  REMOVE-FIRST(fringe)
    if GOAL-TEST[problem] applied to STATE[node] succeeds
        then return SOLUTION(node)
    fringe  $\leftarrow$  INSERT-ALL(EXPAND(node, problem), fringe)



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function EXPAND(node, problem) returns a set of nodes

successors  $\leftarrow$  the empty set
for each  $\langle$  action, result  $\rangle$  in SUCCESSOR-FN[problem](STATE[node]) do
    {
        s  $\leftarrow$  a new NODE
        STATE[s]  $\leftarrow$  result
        PARENT-NODE[s]  $\leftarrow$  node
        ACTION[s]  $\leftarrow$  action
        PATH-COST[s]  $\leftarrow$  PATH-COST[node] + STEP-COST(node, action, s)
        DEPTH[s]  $\leftarrow$  DEPTH[node] + 1
        add s to successors
    }
return successors

```

4. Thuật toán BFS:

5. Thuật toán DFS:

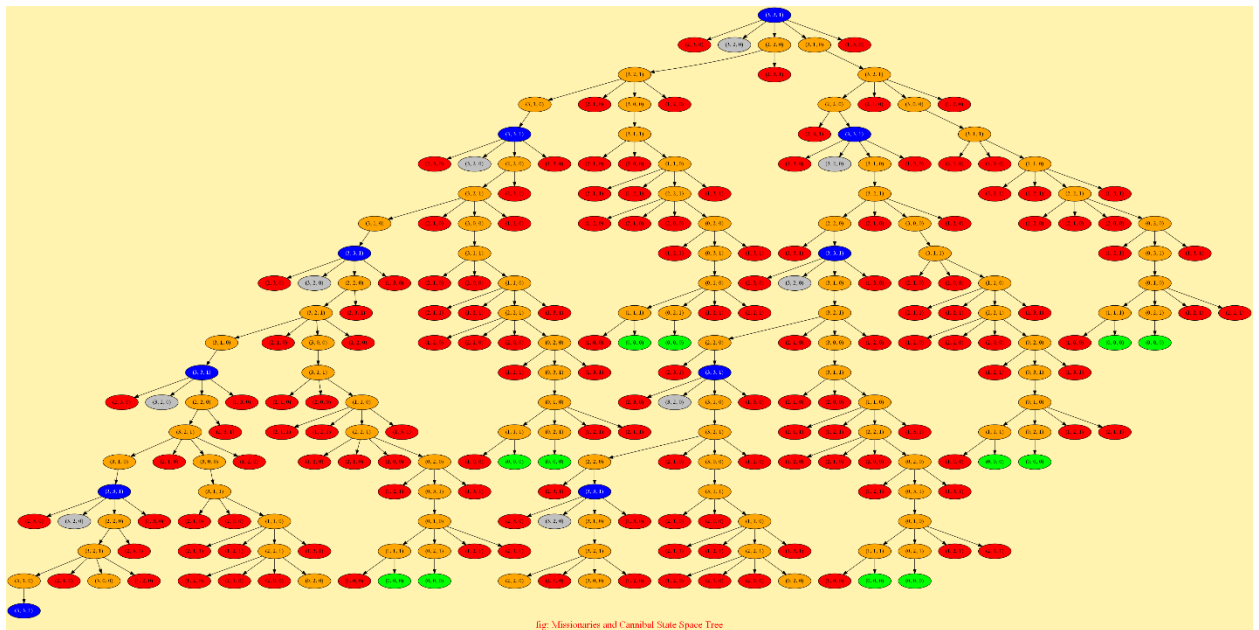
III. NỘI DUNG THỰC HÀNH:

1. Bài toán: Có 3 người truyền giáo và 3 con quỷ ở bờ bên trái của một con sông, cùng với con thuyền có thể chở được 1 hoặc 2 người. Nếu số quỷ nhiều hơn số người truyền giáo trong một bờ thì số quỷ sẽ ăn thịt số người truyền giáo. Tìm các để đưa tất cả qua bờ sông bên kia (bên phải) sao cho số người không ít hơn số quỷ ở cùng 1 bờ (bên trái hay bên phải), nghĩa là không ai bị ăn thịt.

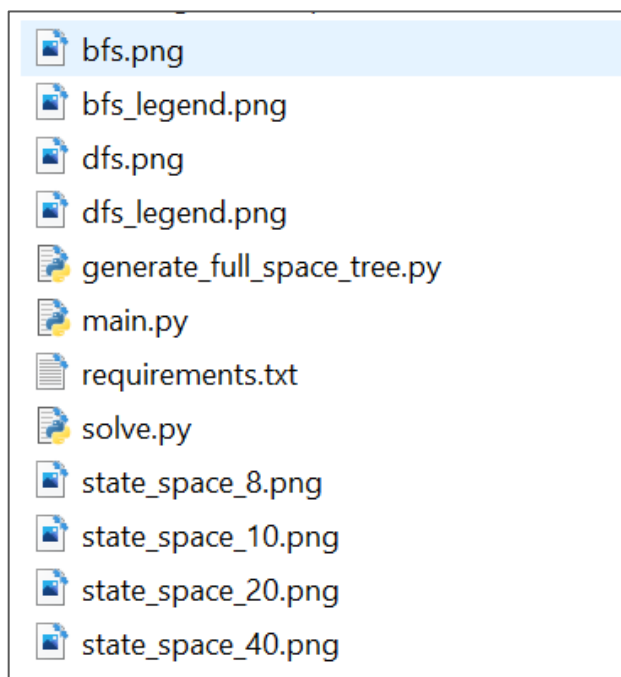
Gọi (*a*, *b*, *k*) với $0 \leq a, b \leq 3$, trong đó *a* là số người, *b* là số con quỷ ở bên bờ bên trái, *k*=1 nếu thuyền ở bờ bên trái và *k* = 0 nếu thuyền ở bờ bên phải. Khi đó, không gian trạng thái của bài toán được xác định như sau:

- Trạng thái ban đầu là (3, 3, 1).
- Thuyền chở qua sông 1 người, hoặc 1 con quỷ, hoặc 1 người và 1 con quỷ, hoặc 2 người, hoặc 2 con quỷ \Rightarrow các phép toán chuyển từ trạng thái này sang trạng thái khác là: (1, 0), (0, 1), (1, 1), (2, 0), (0, 2) (trong đó (*x*, *y*) là số người và số quỷ di chuyển từ bờ bên trái qua bờ bên phải hay ngược lại).
- Trạng thái kết thúc là (0, 0, 0).

2. Cây tìm kiếm (state_space_20.png):



3. Cài đặt:



```
generate_full_space_tree.py X
6 from collections import deque
7 import pydot
8 import argparse
9 import os
10
11 # Set it to bin folder of graphviz
12 os.environ["PATH"] += os.pathsep + 'C:/Program Files/Graphviz/bin'
13
14 options = [(1, 0), (0, 1), (1, 1), (0, 2), (2, 0)]
15 Parent = dict()
16 graph = pydot.Dot(graph_type='graph',strict=False, bgcolor="#fff3af", label="fig: Missionaries and Cannibal State Space Tree", fontcolor="red", fontsize="24", overlap="true")
17
18 # To track node
19 i = 0
20
21 arg = argparse.ArgumentParser()
22 arg.add_argument("-d", "--depth", required=False, help="MAximum depth upto which you want to generate Space State Tree")
23
24 args = vars(arg.parse_args())
25
26 max_depth = int(args.get("depth", 20))
27
28
29 def is_valid_move(number_missionaries, number_cannibals):
30     """
31     Checks if number constraints are satisfied
32     """
33     return (0 <= number_missionaries <= 3) and (0 <= number_cannibals <= 3)
34
35 def write_image(file_name="state_space"):
36     try:
37         graph.write_png(f"{file_name}_{max_depth}.png")
38     except Exception as e:
39         print("Error while writing file", e)
40     print(f"File {file_name}_{max_depth}.png successfully written.")
41
42 def draw_edge(number_missionaries, number_cannibals, side, depth_level, node_num):
43     u, v = None, None
44     if Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)] is not None:
45         u = pydot.Node(str(Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)]), label=str(Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)][3]))
46         graph.add_node(u)
47
48         v = pydot.Node(str((number_missionaries, number_cannibals, side, depth_level, node_num)), label=str((number_missionaries, number_cannibals, side)))
49         graph.add_node(v)
50
51         edge = pydot.Edge(str(Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)]), str((number_missionaries, number_cannibals, side, depth_level, node_num) ), dir='forward')
52         graph.add_edge(edge)
53     else:
```

```

54         # For start node
55         v = pydot.Node(str((number_missionaries, number_cannibals, side, depth_level, node_num)), label=str((number_missionaries, number_cannibals, side)))
56         graph.add_node(v)
57         return u, v
58
59     def is_start_state(number_missionaries, number_cannibals, side):
60         return (number_missionaries, number_cannibals, side) == (3, 3, 1)
61
62     def is_goal_state(number_missionaries, number_cannibals, side):
63         return (number_missionaries, number_cannibals, side) == (0, 0, 0)
64
65     def number_of_cannibals_exceeds(number_missionaries, number_cannibals):
66         number_missionaries_right = 3 - number_missionaries
67         number_cannibals_right = 3 - number_cannibals
68         return (number_missionaries > 0 and number_cannibals > number_missionaries) \
69             or (number_missionaries_right > 0 and number_cannibals_right > number_missionaries_right)
70
71     def generate():
72         global i
73         q = deque()
74         node_num = 0
75         q.append((3, 3, 1, 0, node_num))
76
77         Parent[(3, 3, 1, 0, node_num)] = None
78
79         while q:
80
81             number_missionaries, number_cannibals, side, depth_level, node_num = q.popleft()
82             # print(number_missionaries, number_cannibals)
83             # Draw Edge from u -> v
84             # Where u = Parent[v]
85             # and v = (number_missionaries, number_cannibals, side, depth_level)
86             u, v = draw_edge(number_missionaries, number_cannibals, side, depth_level, node_num)
87
88
89             if is_start_state(number_missionaries, number_cannibals, side):
90                 v.set_style("filled")
91                 v.set_fillcolor("blue")
92                 v.set_fontcolor("white")
93             elif is_goal_state(number_missionaries, number_cannibals, side):
94                 v.set_style("filled")
95                 v.set_fillcolor("green")
96                 continue
97             # return True
98             elif number_of_cannibals_exceeds(number_missionaries, number_cannibals):
99                 v.set_style("filled")
100                 v.set_fillcolor("red")

```

```

102         continue
103     else:
104         v.set_style("filled")
105         v.set_fillcolor("orange")
106
107     if depth_level == max_depth:
108         return True
109
110     op = -1 if side == 1 else 1
111
112     can_be_expanded = False
113
114     # i = node_num
115     for x, y in options:
116         next_m, next_c, next_s = number_missionaries + op * x, number_cannibals + op * y, int(not side)
117
118
119         if Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)] is None or (next_m, next_c, next_s) != Parent[(number_missionaries, number_cannibals, side, depth_level, node_num)][3]:
120             if is_valid_move(next_m, next_c):
121                 can_be_expanded = True
122                 i += 1
123                 q.append((next_m, next_c, next_s, depth_level + 1, i))
124
125                 # Keep track of parent
126                 Parent[(next_m, next_c, next_s, depth_level + 1, i)] = (number_missionaries, number_cannibals, side, depth_level, node_num)
127
128     if not can_be_expanded:
129         v.set_style("filled")
130         v.set_fillcolor("gray")
131     return False
132
133 if __name__ == "__main__":
134     if generate():
135         write_image()

```

solve.py

```
6 import os
7 import emoji
8 import pydot
9 import random
10 from collections import deque
11
12 # Set it to bin folder of graphviz
13 os.environ["PATH"] += os.pathsep + 'C:/Program Files/Graphviz/bin'
14
15 # Dictionaries to backtrack solution nodes
16 # Parent stores parent of (m, c, s)
17 # Move stores (x, y, side) i.e number of missionaries, cannibals to be moved from left to right or right to left for particular state
18 # node_list stores pydot.Node object for particular state (m, c, s) so that we can color the solution nodes
19 Parent, Move, node_list = dict(), dict(), dict()
20
21
22 class Solution():
23
24     def __init__(self):
25         # Start state (3M, 3C, Left)
26         # Goal State (0M, 0C, Right)
27         # Each state gives the number of missionaries and cannibals on the left side
28
29         self.start_state = (3, 3, 1)
30         self.goal_state = (0, 0, 0)
31         self.options = [(1, 0), (0, 1), (1, 1), (0, 2), (2, 0)]
32
33         self.boat_side = ["right", "left"]
34
35
36         self.graph = pydot.Dot(graph_type='graph', bgcolor="#fff3af", label="fig: Missionaries and Cannibal State Space Tree", fontcolor="red", fontsize="24")
37         self.visited = {}
38         self.solved = False
39
40     def is_valid_move(self, number_missionaries, number_cannibals):
41         """
42         Checks if number constraints are satisfied
43         """
44         return (0 <= number_missionaries <= 3) and (0 <= number_cannibals <= 3)
45
46     def is_goal_state(self, number_missionaries, number_cannibals, side):
47         return (number_missionaries, number_cannibals, side) == self.goal_state
48
49     def is_start_state(self, number_missionaries, number_cannibals, side):
50         return (number_missionaries, number_cannibals, side) == self.start_state
51
52     def number_of_cannibals_exceeds(self, number_missionaries, number_cannibals):
53         number_missionaries_right = 3 - number_missionaries
54         number_cannibals_right = 3 - number_cannibals
```

```

55     return (number_missionaries > 0 and number_cannibals > number_missionaries) \
56           or (number_missionaries_right > 0 and number_cannibals_right > number_missionaries_right)
57
58 def write_image(self, file_name="state_space.png"):
59     try:
60         self.graph.write_png(file_name)
61     except Exception as e:
62         print("Error while writing file", e)
63     print(f"File {file_name} successfully written.")
64
65 def solve(self, solve_method="dfs"):
66     self.visited = dict()
67     Parent[self.start_state] = None
68     Move[self.start_state] = None
69     node_list[self.start_state] = None
70
71     return self.dfs(*self.start_state, 0) if solve_method == "dfs" else self.bfs()
72
73 def draw_legend(self):
74     """
75     Utility method to draw legend on graph if legend flag is ON
76     """
77     graphlegend = pydot.Cluster(graph_name="legend", label="Legend", fontsize="20", color="gold",
78                                fontcolor="blue", style="filled", fillcolor="#f4f4f4")
79
80     node1 = pydot.Node("1", style="filled", fillcolor="blue", label="Start Node", fontcolor="white", width="2", fixedsize="true")
81     graphlegend.add_node(node1)
82
83     node2 = pydot.Node("2", style="filled", fillcolor="red", label="Killed Node", fontcolor="black", width="2", fixedsize="true")
84     graphlegend.add_node(node2)
85
86     node3 = pydot.Node("3", style="filled", fillcolor="yellow", label="Solution nodes", width="2", fixedsize="true")
87     graphlegend.add_node(node3)
88
89     node4 = pydot.Node("4", style="filled", fillcolor="gray", label="Can't be expanded", width="2", fixedsize="true")
90     graphlegend.add_node(node4)
91
92     node5 = pydot.Node("5", style="filled", fillcolor="green", label="Goal node", width="2", fixedsize="true")
93     graphlegend.add_node(node5)
94
95     node7 = pydot.Node("7", style="filled", fillcolor="gold", label="Node with child", width="2", fixedsize="true")
96     graphlegend.add_node(node7)
97
98
99
100 description = "Each node (m, c, s) represents a \nstate where 'm' is the number of\nmissionaries, 'n' the cannibals and 'n's' the side of the boat\n\"
101             \" where '1' represents the left \nside and '0' the right side \n\nOur objective is to reach goal state (0, 0, 0) \nfrom start state (3, 3, 1) by some \noperators = [(0, 1), (0, 2), (1, 0), (1, 1), (2, 0),]\n\n\"
102             \"each tuples (x, y) inside operators \nrepresents the number of missionaries and \ncannibals to be moved from left to right \nif c == 1 and viceversa\"

```



```

103
104 node6 = pydot.Node("6", style="filled", fillcolor="gold", label=description, shape="plaintext", fontsize="20", fontcolor="red")
105 graphlegend.add_node(node6)
106
107 self.graph.add_subgraph(graphlegend)
108
109 self.graph.add_edge(pydot.Edge(node1, node2, style="invis"))
110 self.graph.add_edge(pydot.Edge(node2, node3, style="invis"))
111 self.graph.add_edge(pydot.Edge(node3, node4, style="invis"))
112 self.graph.add_edge(pydot.Edge(node4, node5, style="invis"))
113 self.graph.add_edge(pydot.Edge(node5, node7, style="invis"))
114 self.graph.add_edge(pydot.Edge(node7, node6, style="invis"))
115
116 def draw(self, *, number_missionaries_left, number_cannibals_left, number_missionaries_right, number_cannibals_right):
117     """
118     Draw state on console using emojis
119     """
120     left_m = emoji.emojiize(f":old_man: " * number_missionaries_left)
121     left_c = emoji.emojiize(f":ogre: " * number_cannibals_left)
122     right_m = emoji.emojiize(f":old_man: " * number_missionaries_right)
123     right_c = emoji.emojiize(f":ogre: " * number_cannibals_right)
124
125     print('{}{}{}{}{}{}'.format(left_m, left_c + " " * (14 - len(left_m) - len(left_c)), "_" * 40, " " * (12 - len(right_m) - len(right_c)) + right_m, right_c))
126     print("")
127
128 def show_solution(self):
129     # Recursively start from Goal State
130     # And find parent until start state is reached
131
132     state = self.goal_state
133     path, steps, nodes = [], [], []
134
135     while state is not None:
136         path.append(state)
137         steps.append(Move[state])
138         nodes.append(node_list[state])
139
140         state = Parent[state]
141
142     steps, nodes = steps[::-1], nodes[::-1]
143
144     number_missionaries_left, number_cannibals_left = 3, 3
145     number_missionaries_right, number_cannibals_right = 0, 0
146
147     print("+" * 60)
148     self.draw(number_missionaries_left=number_missionaries_left, number_cannibals_left=number_cannibals_left, number_missionaries_right=number_missionaries_right, number_cannibals_right=number_cannibals_right)
149
150     for i, ((number_missionaries, number_cannibals, side), node) in enumerate(zip(steps[1:], nodes[1:])):

```

```

151
152     if node.get_label() != str(self.start_state):
153         node.set_style("filled")
154         node.set_fillcolor("yellow")
155
156     print(f"Step {i + 1}: Move {number_missionaries} missionaries and {number_cannibals} cannibals from {self.boat_side[side]} to {self.boat_side[int(not side)]}.")
157
158     op = -1 if side == 1 else 1
159
160     number_missionaries_left = number_missionaries_left + op * number_missionaries
161     number_cannibals_left = number_cannibals_left + op * number_cannibals
162
163     number_missionaries_right = number_missionaries_right - op * number_missionaries
164     number_cannibals_right = number_cannibals_right - op * number_cannibals
165
166     self.draw(number_missionaries_left=number_missionaries_left, number_cannibals_left=number_cannibals_left, number_missionaries_right=number_missionaries_right, number_cannibals_right=number_cannibals_right)
167
168     print("Congratulations!!! you have solved the problem")
169     print("*" * 60)
170
171     def draw_edge(self, number_missionaries, number_cannibals, side, depth_level):
172         u, v = None, None
173         if Parent[(number_missionaries, number_cannibals, side)] is not None:
174             u = pydot.Node(str(Parent[(number_missionaries, number_cannibals, side)] + (depth_level - 1, )), label=str(Parent[(number_missionaries, number_cannibals, side)]))
175             self.graph.add_node(u)
176
177             v = pydot.Node(str((number_missionaries, number_cannibals, side, depth_level)), label=str((number_missionaries, number_cannibals, side)))
178             self.graph.add_node(v)
179
180             edge = pydot.Edge(str(Parent[(number_missionaries, number_cannibals, side)] + (depth_level - 1, )), str((number_missionaries, number_cannibals, side, depth_level)), dir='forward')
181             self.graph.add_edge(edge)
182         else:
183             # For start node
184             v = pydot.Node(str((number_missionaries, number_cannibals, side, depth_level)), label=str((number_missionaries, number_cannibals, side)))
185             self.graph.add_node(v)
186         return u, v
187
188     def bfs(self):
189         q = deque()
190         q.append(self.start_state + (0, ))
191         self.visited[self.start_state] = True
192
193         while q:
194             number_missionaries, number_cannibals, side, depth_level = q.popleft()
195             # Draw Edge from u -> v
196             # Where u = Parent[v]
197             # and v = (number_missionaries, number_cannibals, side, depth_level)
198             u, v = self.draw_edge(number_missionaries, number_cannibals, side, depth_level)

```

```

201         if self.is_start_state(number_missionaries, number_cannibals, side):
202             v.set_style("filled")
203             v.set_fillcolor("blue")
204             v.set_fontcolor("white")
205         elif self.is_goal_state(number_missionaries, number_cannibals, side):
206             v.set_style("filled")
207             v.set_fillcolor("green")
208             return True
209         elif self.number_of_cannibals_exceeds(number_missionaries, number_cannibals):
210             v.set_style("filled")
211             v.set_fillcolor("red")
212             continue
213         else:
214             v.set_style("filled")
215             v.set_fillcolor("orange")
216
217         op = -1 if side == 1 else 1
218
219         can_be_expanded = False
220
221         for x, y in self.options:
222             next_m, next_c, next_s = number_missionaries + op * x, number_cannibals + op * y, int(not side)
223             if (next_m, next_c, next_s) not in self.visited:
224                 if self.is_valid_move(next_m, next_c):
225                     can_be_expanded = True
226                     self.visited[(next_m, next_c, next_s)] = True
227                     q.append((next_m, next_c, next_s, depth_level + 1))
228
229                     # Keep track of parent and corresponding move
230                     Parent[(next_m, next_c, next_s)] = (number_missionaries, number_cannibals, side)
231                     Move[(next_m, next_c, next_s)] = (x, y, side)
232                     node_list[(next_m, next_c, next_s)] = v
233
234             if not can_be_expanded:
235                 v.set_style("filled")
236                 v.set_fillcolor("gray")
237         return False
238
239     def dfs(self, number_missionaries, number_cannibals, side, depth_level):
240         self.visited[(number_missionaries, number_cannibals, side)] = True
241
242         # Draw Edge from u -> v
243         # Where u = Parent[v]
244         u, v = self.draw_edge(number_missionaries, number_cannibals, side, depth_level)

```

```

245
246
247     if self.is_start_state(number_missionaries, number_cannibals, side):
248         v.set_style("filled")
249         v.set_fillcolor("blue")
250     elif self.is_goal_state(number_missionaries, number_cannibals, side):
251         v.set_style("filled")
252         v.set_fillcolor("green")
253         return True
254     elif self.number_of_cannibals_exceeds(number_missionaries, number_cannibals):
255         v.set_style("filled")
256         v.set_fillcolor("red")
257         return False
258     else:
259         v.set_style("filled")
260         v.set_fillcolor("orange")
261
262     solution_found = False
263     operation = -1 if side == 1 else 1
264
265     can_be_expanded = False
266
267     for x, y in self.options:
268         next_m, next_c, next_s = number_missionaries + operation * x, number_cannibals + operation * y, int(not side)
269
270         if (next_m, next_c, next_s) not in self.visited:
271             if self.is_valid_move(next_m, next_c):
272                 can_be_expanded = True
273                 # Keep track of Parent state and corresponding move
274                 Parent[(next_m, next_c, next_s)] = (number_missionaries, number_cannibals, side)
275                 Move[(next_m, next_c, next_s)] = (x, y, side)
276                 node_list[(next_m, next_c, next_s)] = v
277
278                 solution_found = (solution_found or self.dfs(next_m, next_c, next_s, depth_level + 1))
279
280                 if solution_found:
281                     return True
282
283             if not can_be_expanded:
284                 v.set_style("filled")
285                 v.set_fillcolor("gray")
286
287     self.solved = solution_found
288     return solution_found

```

```

main.py
5 from solve import Solution
6 import argparse
7 import itertools
8
9 arg = argparse.ArgumentParser()
10 arg.add_argument("-m", "--method", required=False, help="Specify which method to use")
11 arg.add_argument("-l", "--legend", required=False, help="Specify if you want to display legend on graph")
12
13 args = vars(arg.parse_args())
14
15 solve_method = args.get("method", "bfs")
16 legend_flag = args.get("legend", False)
17
18
19 def main():
20     s = Solution()
21
22     if(s.solve(solve_method)):
23
24         # Display Solution on console
25         s.show_solution()
26
27         output_file_name = f"{solve_method}"
28         # Draw legend if legend_flag is set
29         if legend_flag:
30             if legend_flag[0].upper() == 'T' :
31                 output_file_name += "_legend.png"
32                 s.draw_legend()
33             else:
34                 output_file_name += ".png"
35         else:
36             output_file_name += ".png"
37
38         # Write State space tree
39         s.write_image(output_file_name)
40     else:
41         raise Exception("No solution found")
42
43 if __name__ == "__main__":
44     main()

```

- a. Cài đặt thư viện graphviz tải về từ link: <https://graphviz.org/download/> và đặt đường dẫn tới thư mục bin của graphviz đã cài đặt trên máy tính.

```
generate_full_space_tree.py
10
11 # Set it to bin folder of graphviz
12 os.environ["PATH"] += os.pathsep + 'C:/Program Files/Graphviz/bin'
```

```
solve.py
11
12 # Set it to bin folder of graphviz
13 os.environ["PATH"] += os.pathsep + 'C:/Program Files/Graphviz/bin'
```

- b. Cài đặt các yêu cầu trong file “requirements.txt”

```
requirements.txt - Notepad
File Edit Format View Help
emoji==0.5.4
pydot==1.4.1
pyparsing==2.4.5
```

pip install -r requirements.txt

```
C:\WINDOWS\system32\cmd.exe
Microsoft Windows [Version 10.0.19043.2006]
(c) Microsoft Corporation. All rights reserved.

C:\Users\Huynh>cd C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master

C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>pip install -r requirements.txt
Requirement already satisfied: emoji==0.5.4 in c:\users\huynh\appdata\local\programs\python\python37\lib\site-packages (
from -r requirements.txt (line 1)) (0.5.4)
Requirement already satisfied: pydot==1.4.1 in c:\users\huynh\appdata\local\programs\python\python37\lib\site-packages (
from -r requirements.txt (line 2)) (1.4.1)
Requirement already satisfied: pyparsing==2.4.5 in c:\users\huynh\appdata\local\programs\python\python37\lib\site-packag
es (from -r requirements.txt (line 3)) (2.4.5)

C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>
```

- c. Khởi tạo cây không gian trạng thái:

python generate_full_space_tree.py -d 8 (với d là độ sâu (depth=8))

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python generate_full_space_tree.py -d 8
File state_space_8.png successfully written.
```

python generate_full_space_tree.py -d 20 (depth = 20)

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python generate_full_space_tree.py -d 20
File state_space_20.png successfully written.
```

.....

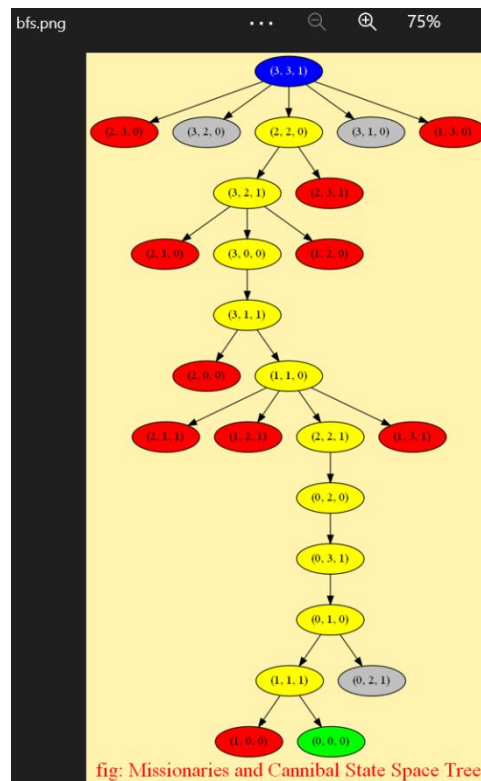
- d. Cây DFS:

- DFS:

python main.py -m dfs

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python main.py -m dfs
*****
? ? ? ? ? ?
Step 1: Move 1 missionaries and 1 cannibals from left to right.
? ? ? ? ? ?
Step 2: Move 1 missionaries and 0 cannibals from right to left.
? ? ? ? ? ?
Step 3: Move 0 missionaries and 2 cannibals from left to right.
? ? ? ? ? ?
Step 4: Move 0 missionaries and 1 cannibals from right to left.
? ? ? ? ? ?
Step 5: Move 2 missionaries and 0 cannibals from left to right.
? ? ? ? ? ?
Step 6: Move 1 missionaries and 1 cannibals from right to left.
? ? ? ? ? ?
Step 7: Move 2 missionaries and 0 cannibals from left to right.
? ? ? ? ? ?
Step 8: Move 0 missionaries and 1 cannibals from right to left.
? ? ? ? ? ?
Step 9: Move 0 missionaries and 2 cannibals from left to right.
? ? ? ? ? ?
Step 10: Move 1 missionaries and 0 cannibals from right to left.
? ? ? ? ? ?
Step 11: Move 1 missionaries and 1 cannibals from left to right.
? ? ? ? ? ?

Congratulations!!! you have solved the problem
*****
File dfs.png successfully written.
```

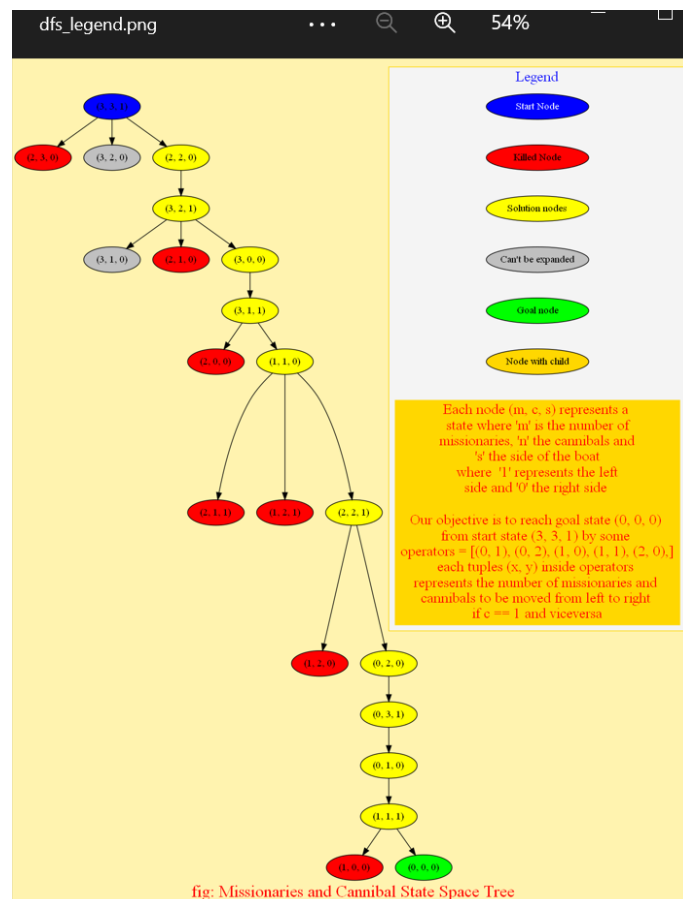


- DFS với legends:

python main.py -m dfs -l True

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python main.py -m dfs -l True
*****
Step 1: Move 1 missionaries and 1 cannibals from left to right.
Step 2: Move 1 missionaries and 0 cannibals from right to left.
Step 3: Move 0 missionaries and 2 cannibals from left to right.
Step 4: Move 0 missionaries and 1 cannibals from right to left.
Step 5: Move 2 missionaries and 0 cannibals from left to right.
Step 6: Move 1 missionaries and 1 cannibals from right to left.
Step 7: Move 2 missionaries and 0 cannibals from left to right.
Step 8: Move 0 missionaries and 1 cannibals from right to left.
Step 9: Move 0 missionaries and 2 cannibals from left to right.
Step 10: Move 1 missionaries and 0 cannibals from right to left.
Step 11: Move 1 missionaries and 1 cannibals from left to right.

Congratulations!!! you have solved the problem
*****
File dfs_legend.png successfully written.
```



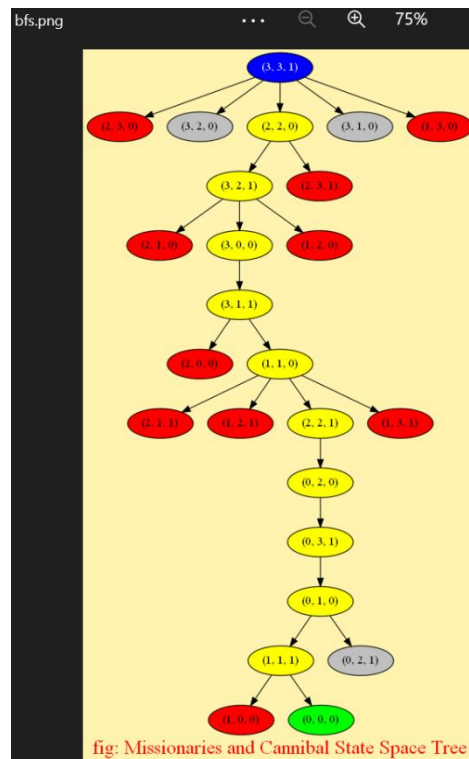
e. Cây BFS:

- BFS

python main.py -m bfs

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python main.py -m bfs
*****
Step 1: Move 1 missionaries and 1 cannibals from left to right.
Step 2: Move 1 missionaries and 0 cannibals from right to left.
Step 3: Move 0 missionaries and 2 cannibals from left to right.
Step 4: Move 0 missionaries and 1 cannibals from right to left.
Step 5: Move 2 missionaries and 0 cannibals from left to right.
Step 6: Move 1 missionaries and 1 cannibals from right to left.
Step 7: Move 2 missionaries and 0 cannibals from left to right.
Step 8: Move 0 missionaries and 1 cannibals from right to left.
Step 9: Move 0 missionaries and 2 cannibals from left to right.
Step 10: Move 1 missionaries and 0 cannibals from right to left.
Step 11: Move 1 missionaries and 1 cannibals from left to right.

Congratulation!!! you have solved the problem
*****
File bfs.png successfully written.
```

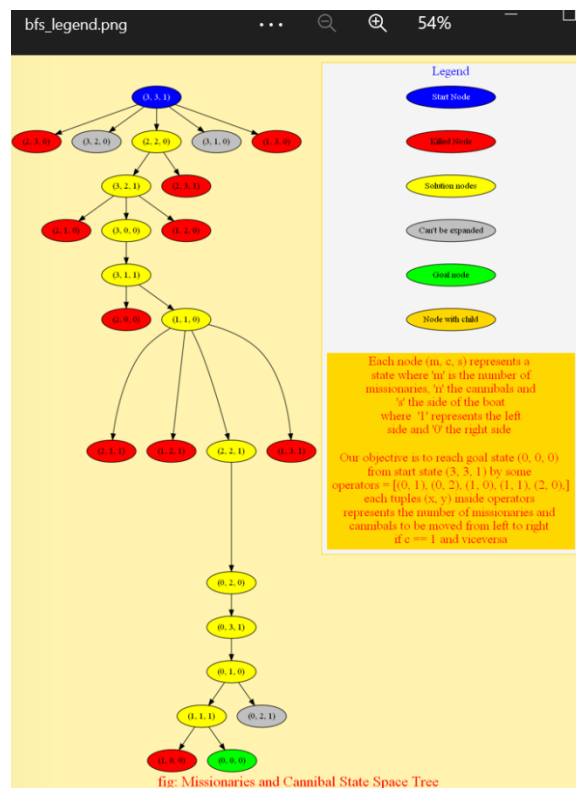


- BFS với legends

python main.py -m bfs -l True

```
C:\Users\Huynh\Desktop\Missionaries-and-Cannibals-Problem-master>python main.py -m bfs -l True
*****
[ ] [ ] [ ] [ ] [ ] [ ]
Step 1: Move 1 missionaries and 1 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 2: Move 1 missionaries and 0 cannibals from right to left.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 3: Move 0 missionaries and 2 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 4: Move 0 missionaries and 1 cannibals from right to left.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 5: Move 2 missionaries and 0 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 6: Move 1 missionaries and 1 cannibals from right to left.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 7: Move 2 missionaries and 0 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 8: Move 0 missionaries and 1 cannibals from right to left.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 9: Move 0 missionaries and 2 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 10: Move 1 missionaries and 0 cannibals from right to left.
[ ] [ ] [ ] [ ] [ ] [ ]
Step 11: Move 1 missionaries and 1 cannibals from left to right.
[ ] [ ] [ ] [ ] [ ] [ ]

Congratulations!!! you have solved the problem
*****
File bfs_legend.png successfully written.
```



4. Yêu cầu:

- Cài đặt và thực thi chương trình. Nếu chương trình bị báo lỗi thì lỗi ở dòng nào và sửa lại như thế nào?
- Viết báo cáo trình bày lại tất cả những gì em hiểu liên quan tới bài thực hành. Nhận xét?