

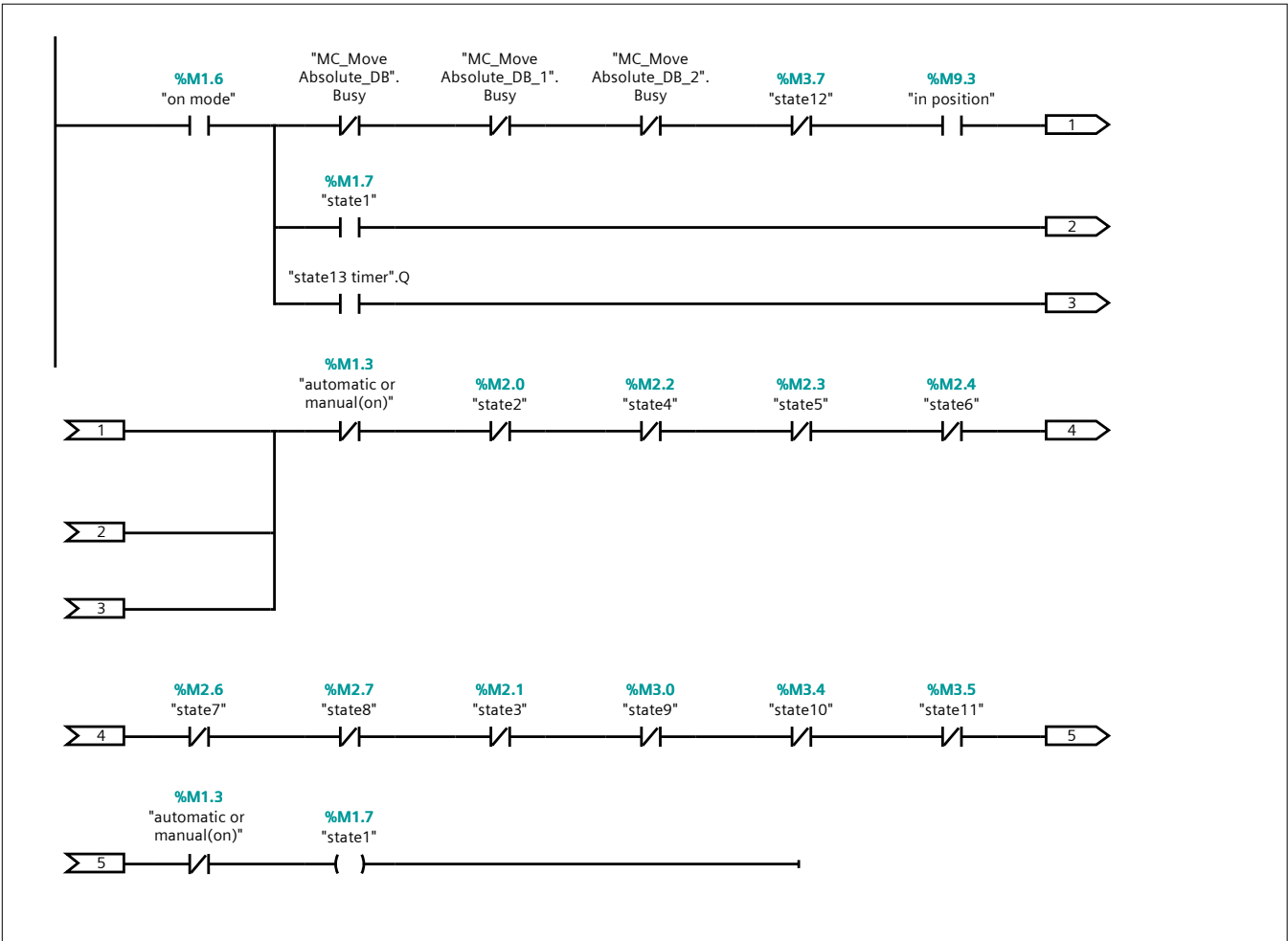
Change Position of Robot [FC6]

Change Position of Robot Properties

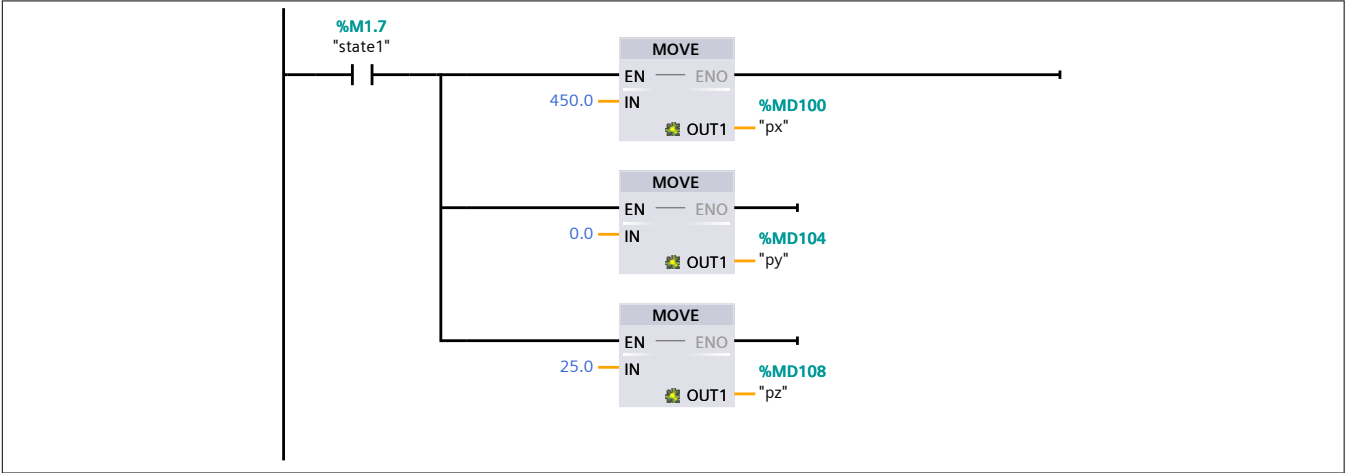
General					
Name	Change Position of Robot	Number	6	Type	FC
Language	LAD	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

Name	Data type	Default value	Comment
Input			
Output			
InOut			
Temp			
Constant			
▼ Return			
Change Position of Robot	Void		

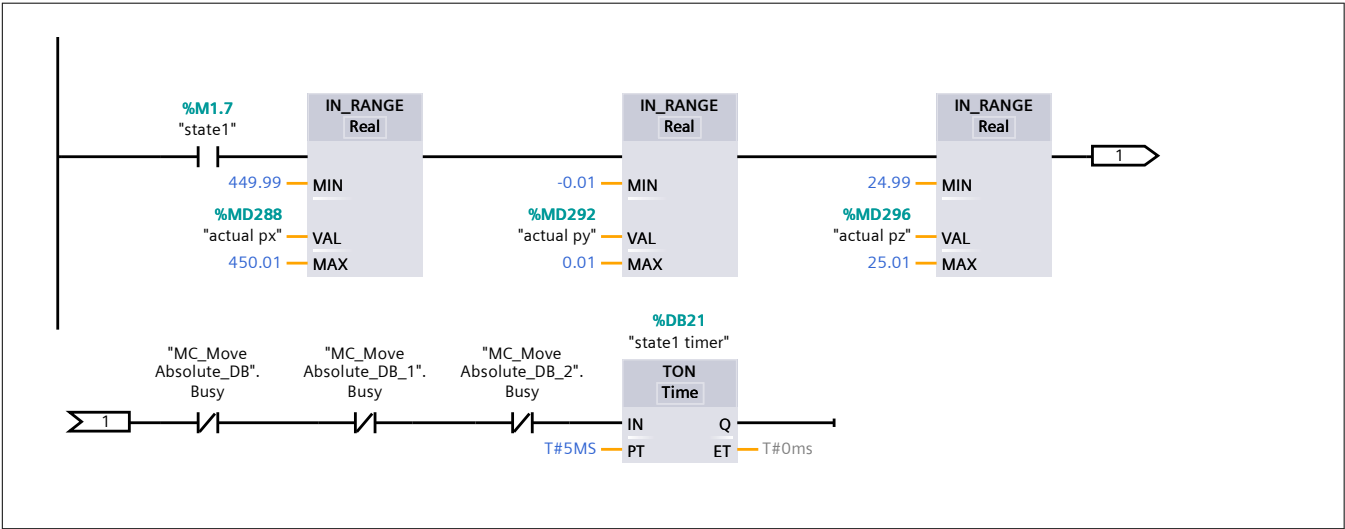
Network 1: STATE 1 ON



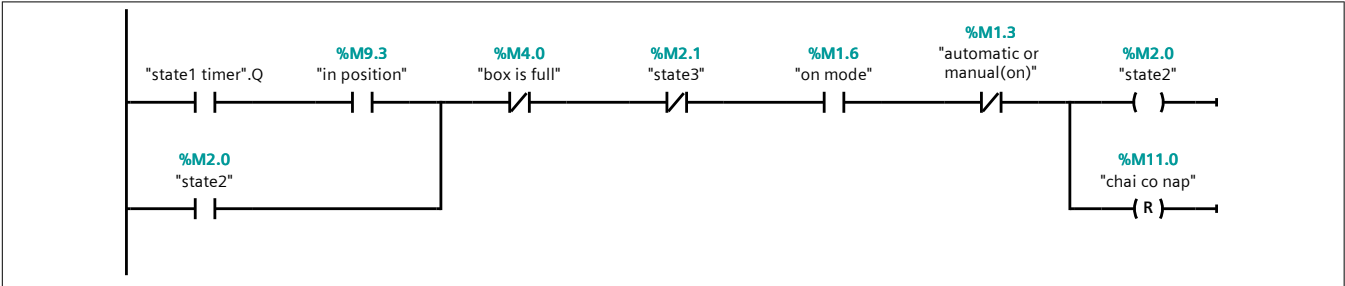
Network 2: Vi tri cua state1



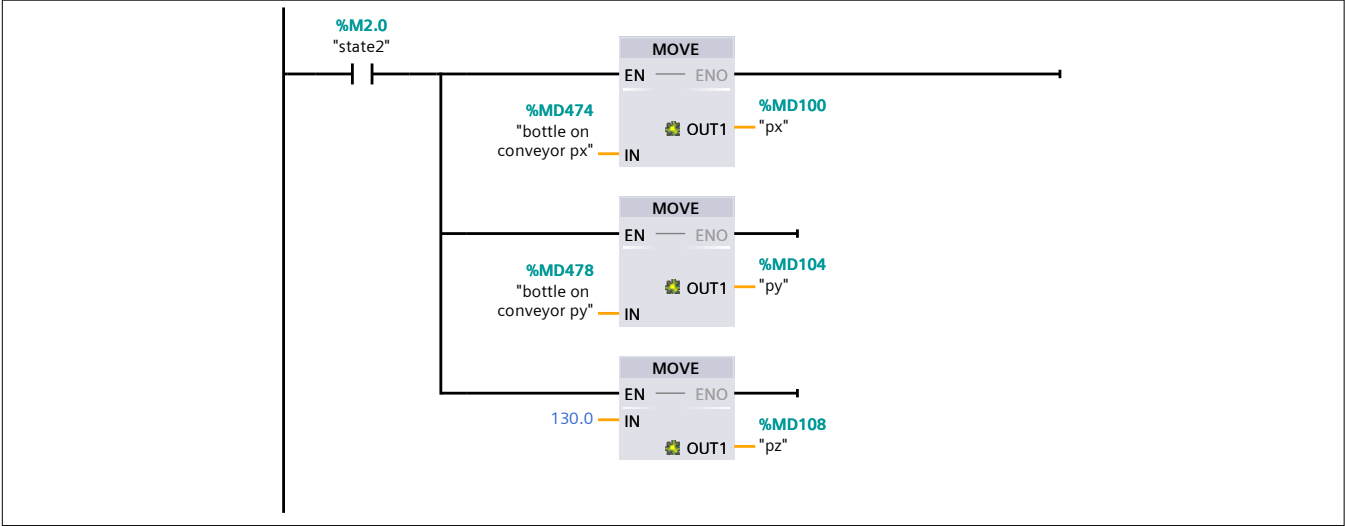
Network 3:



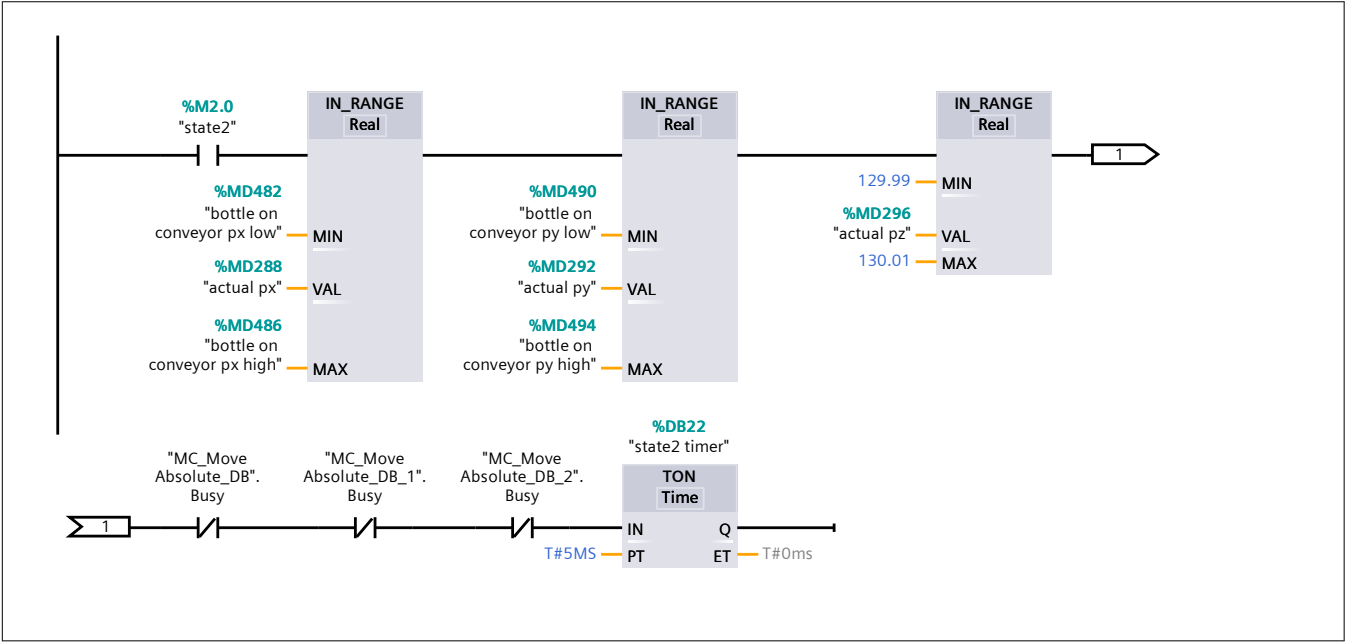
Network 4:



Network 5:



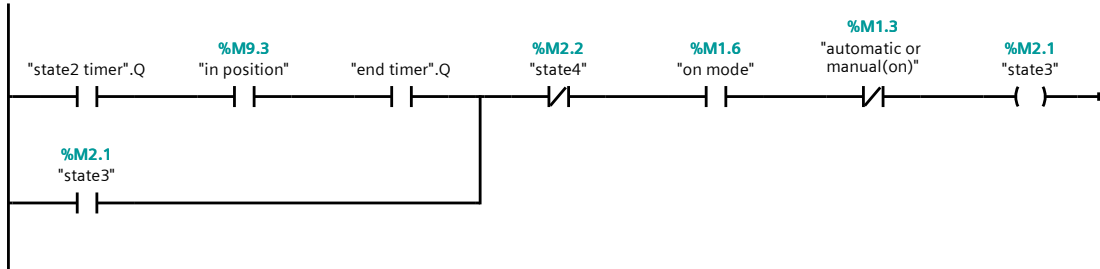
Network 6:



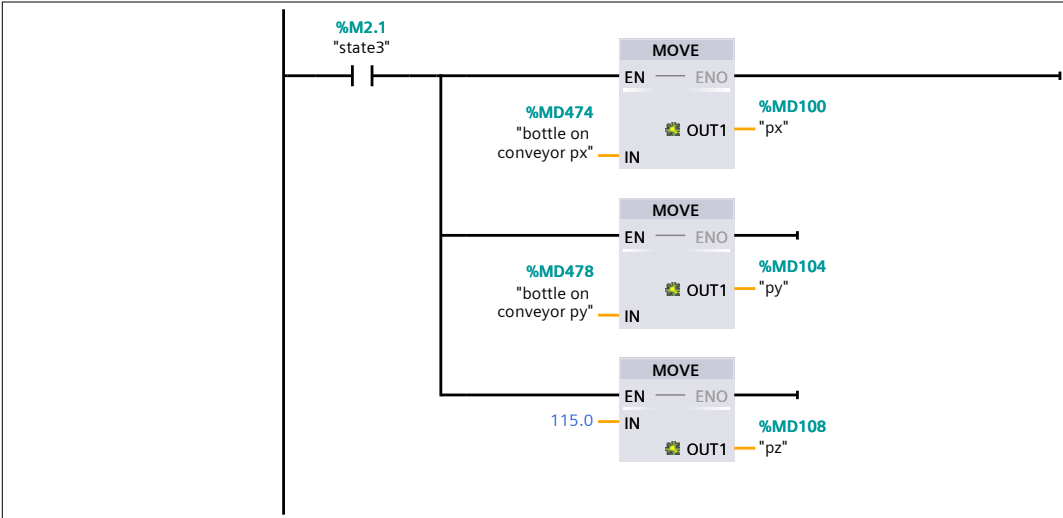
Network 7:



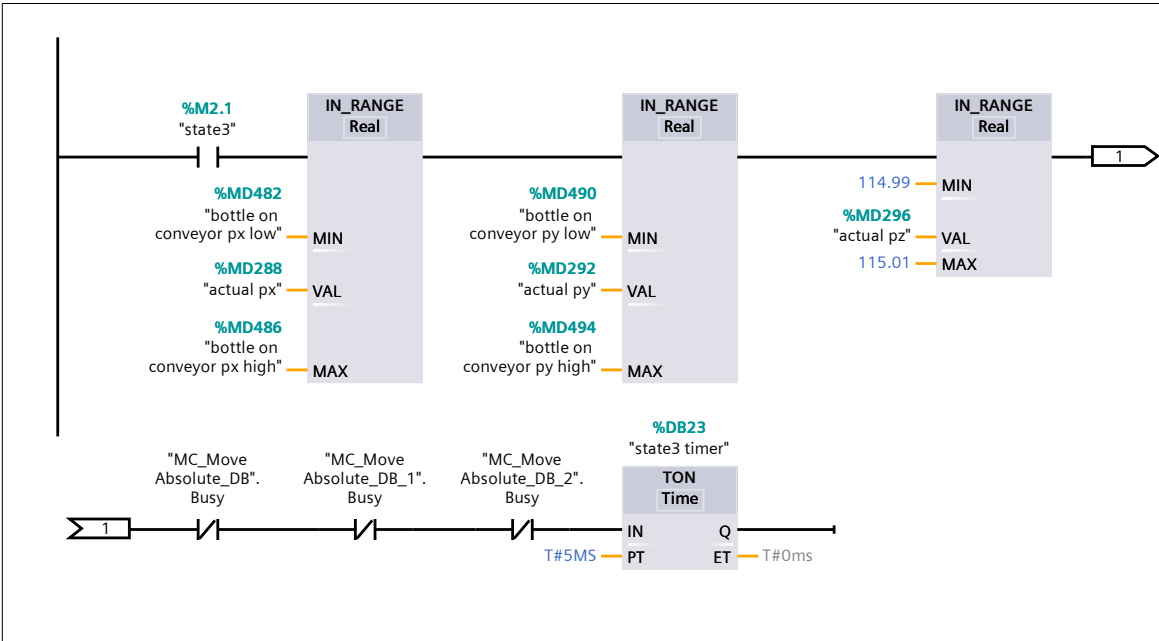
Network 8:



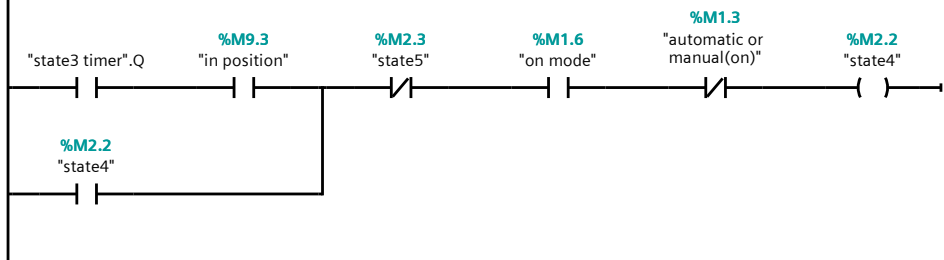
Network 9:



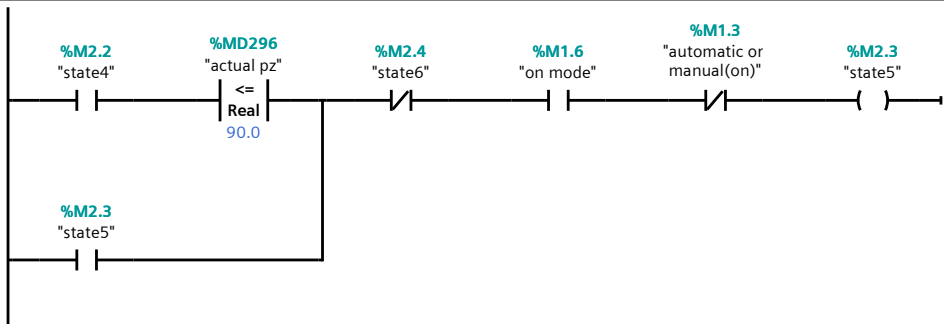
Network 10:



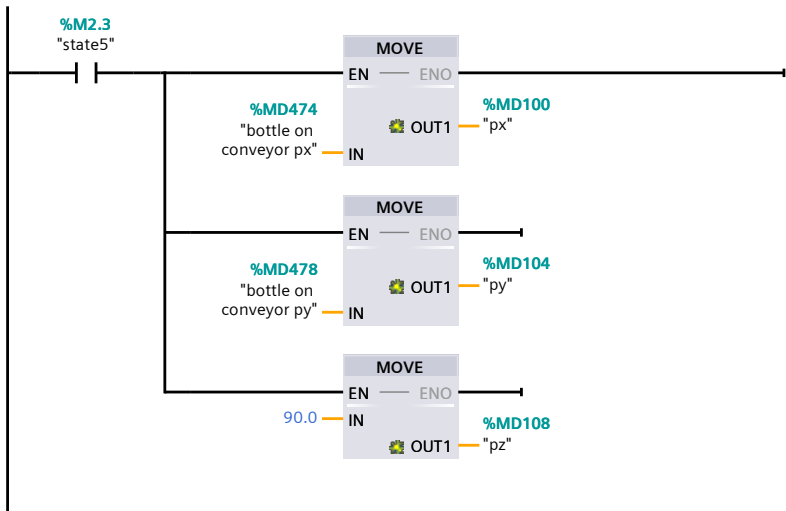
Network 11:



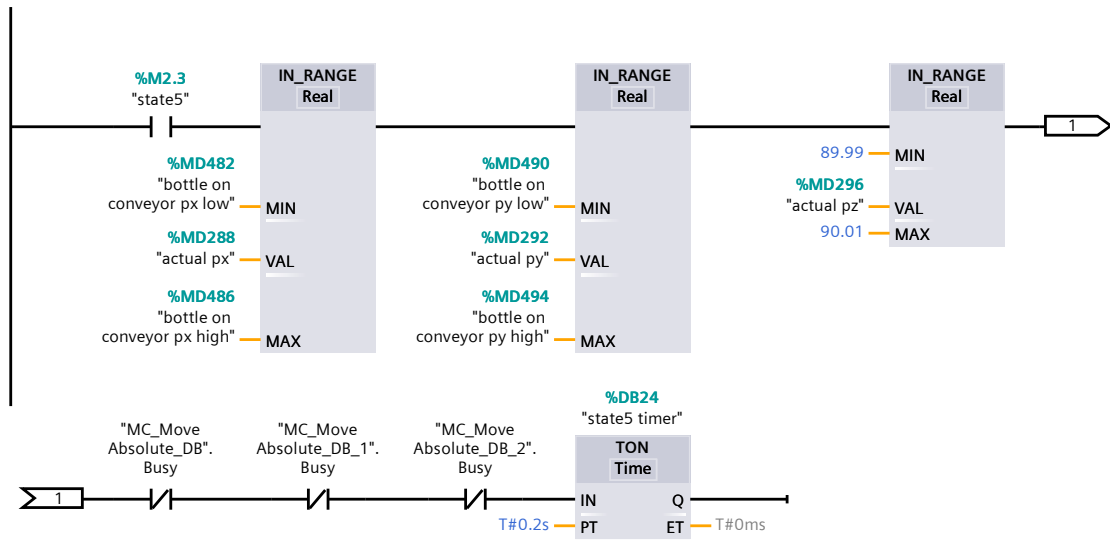
Network 12:



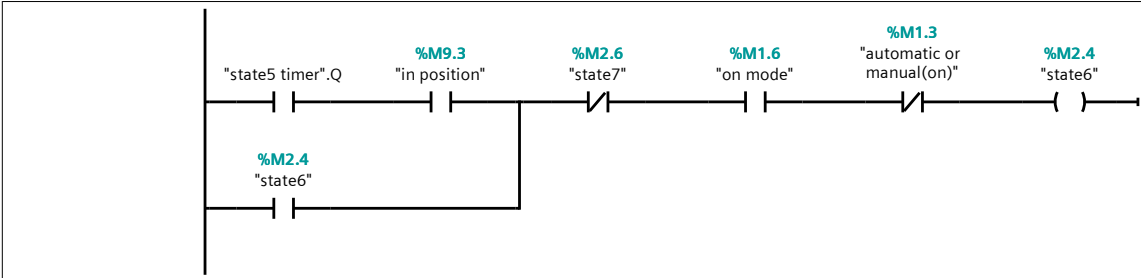
Network 13:



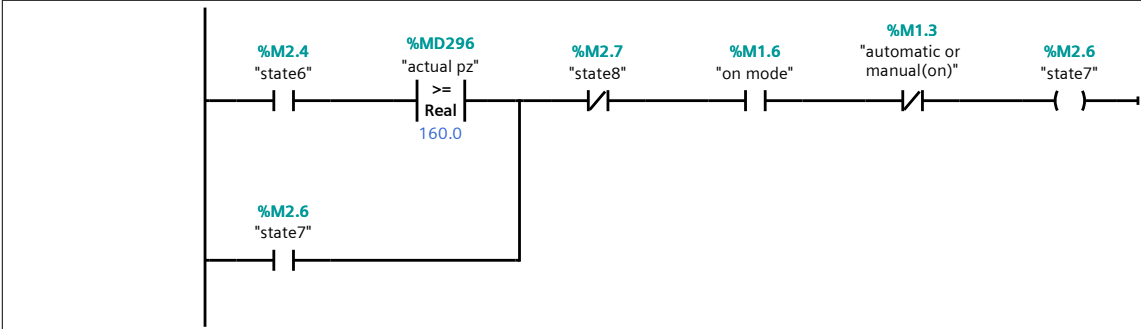
Network 14:



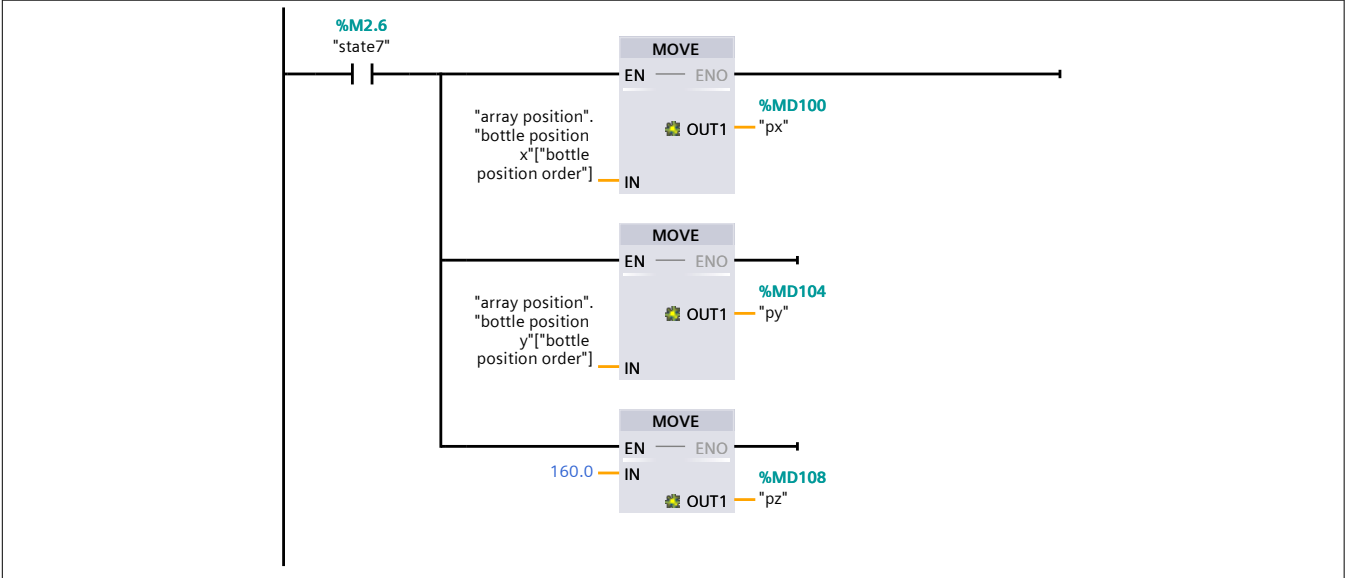
Network 15:



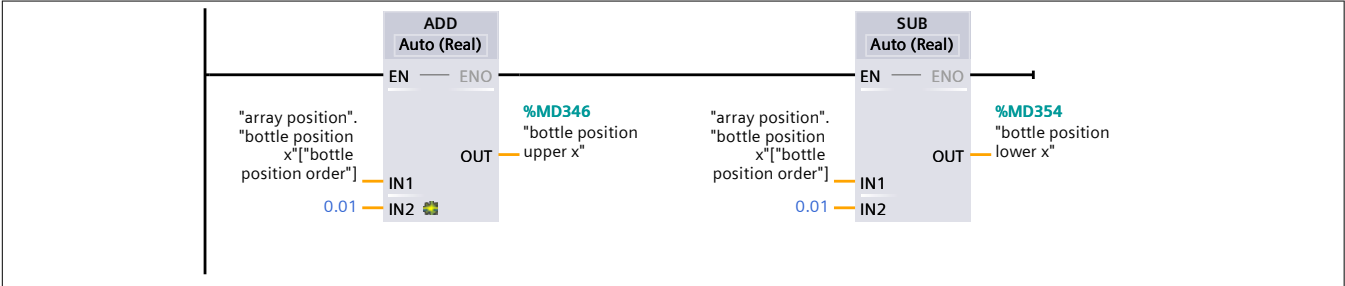
Network 16:



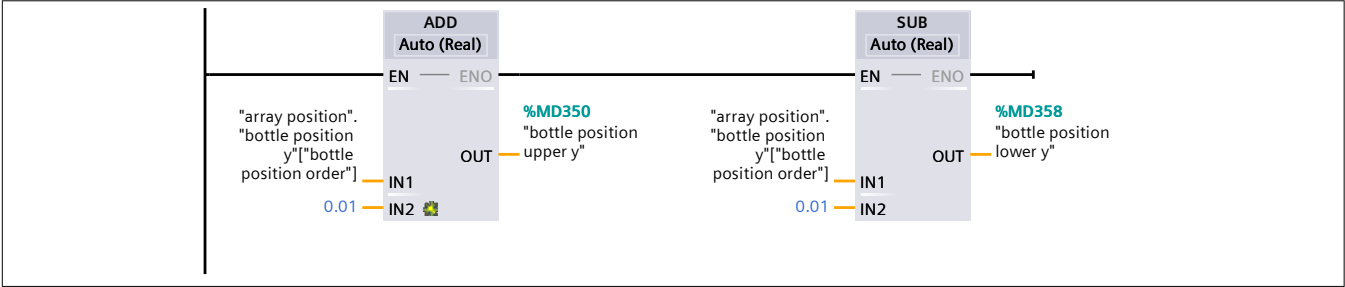
Network 17:



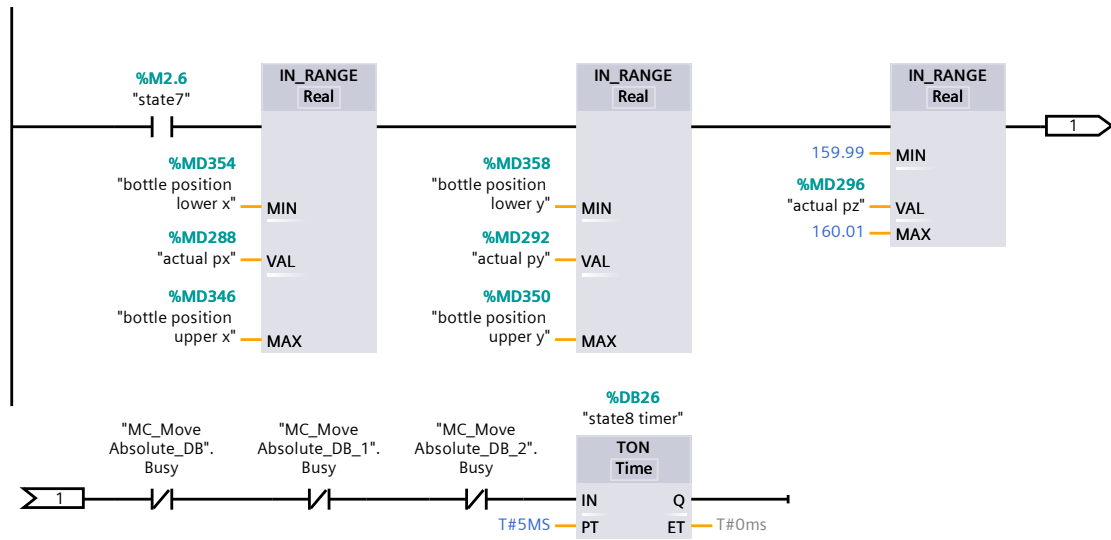
Network 18:



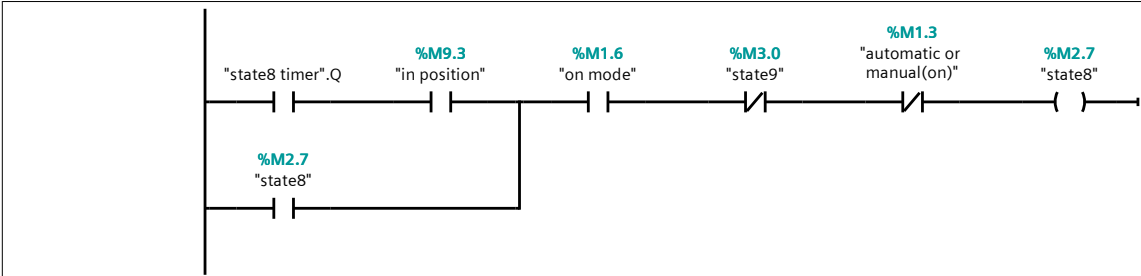
Network 19:



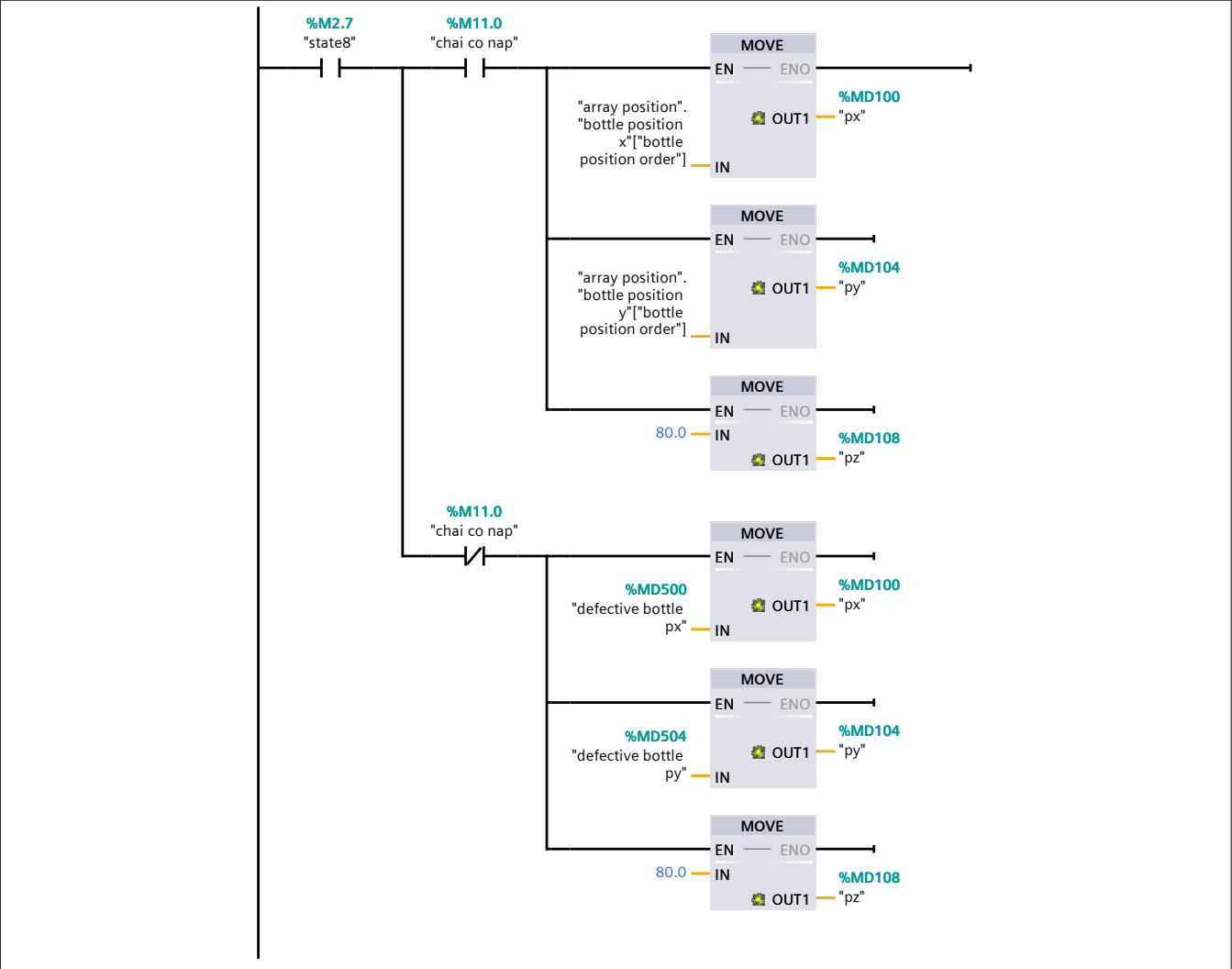
Network 20:



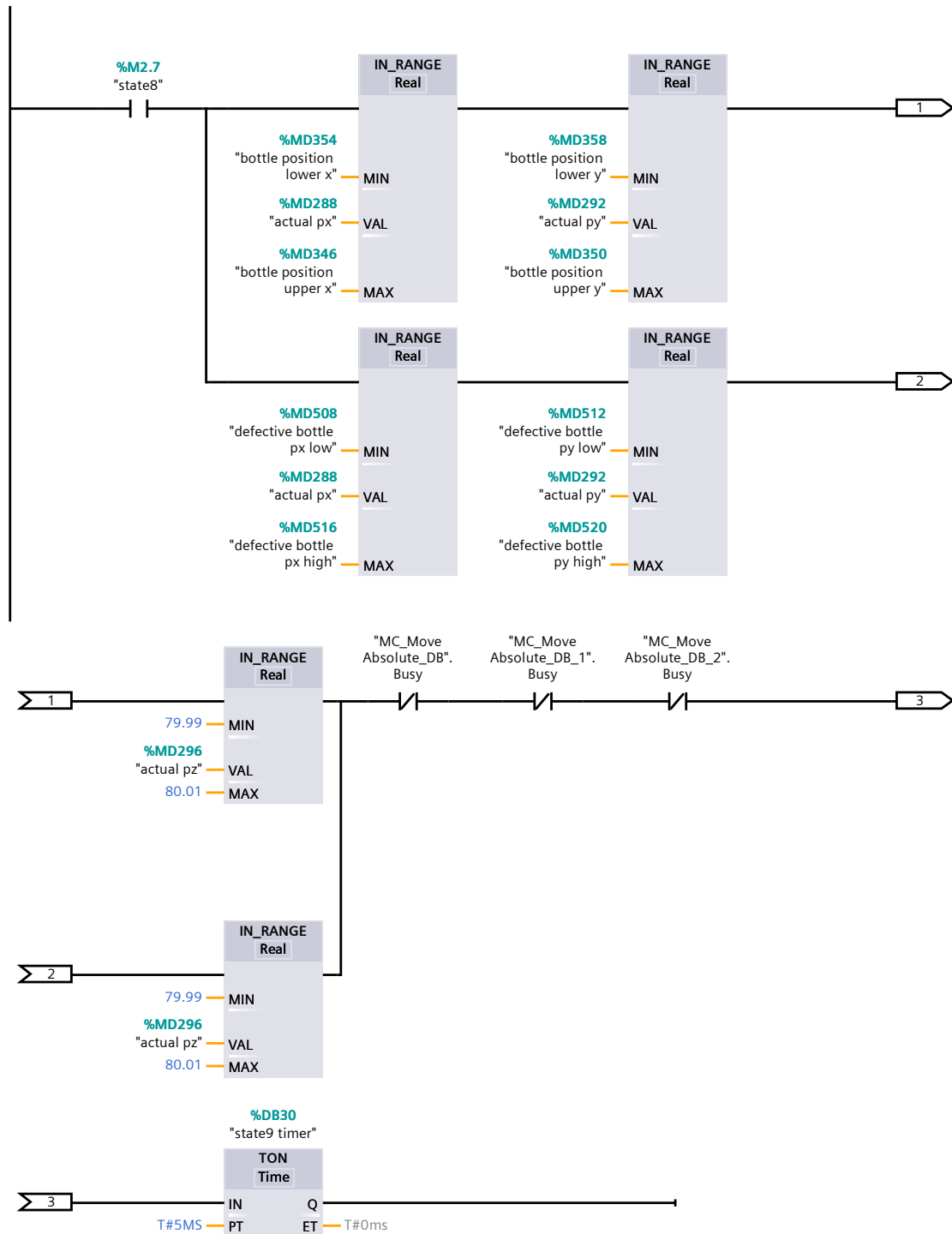
Network 21:



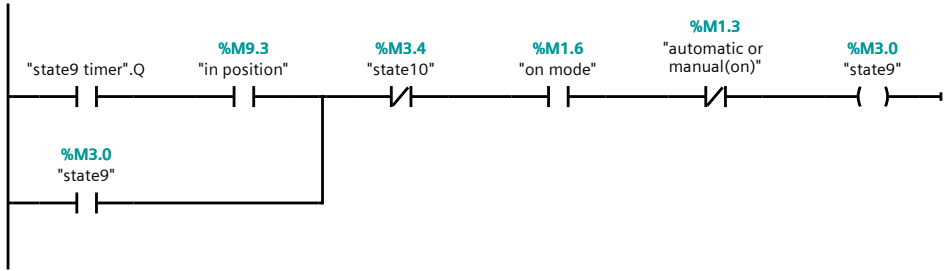
Network 22:



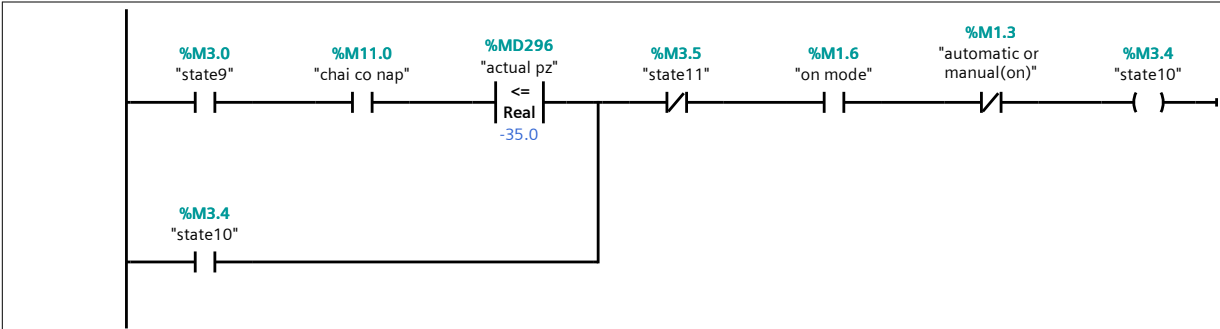
Network 23:



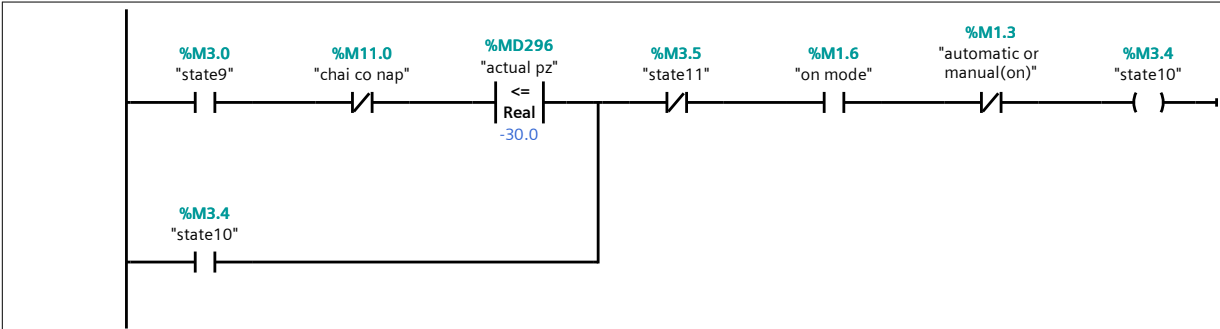
Network 24:



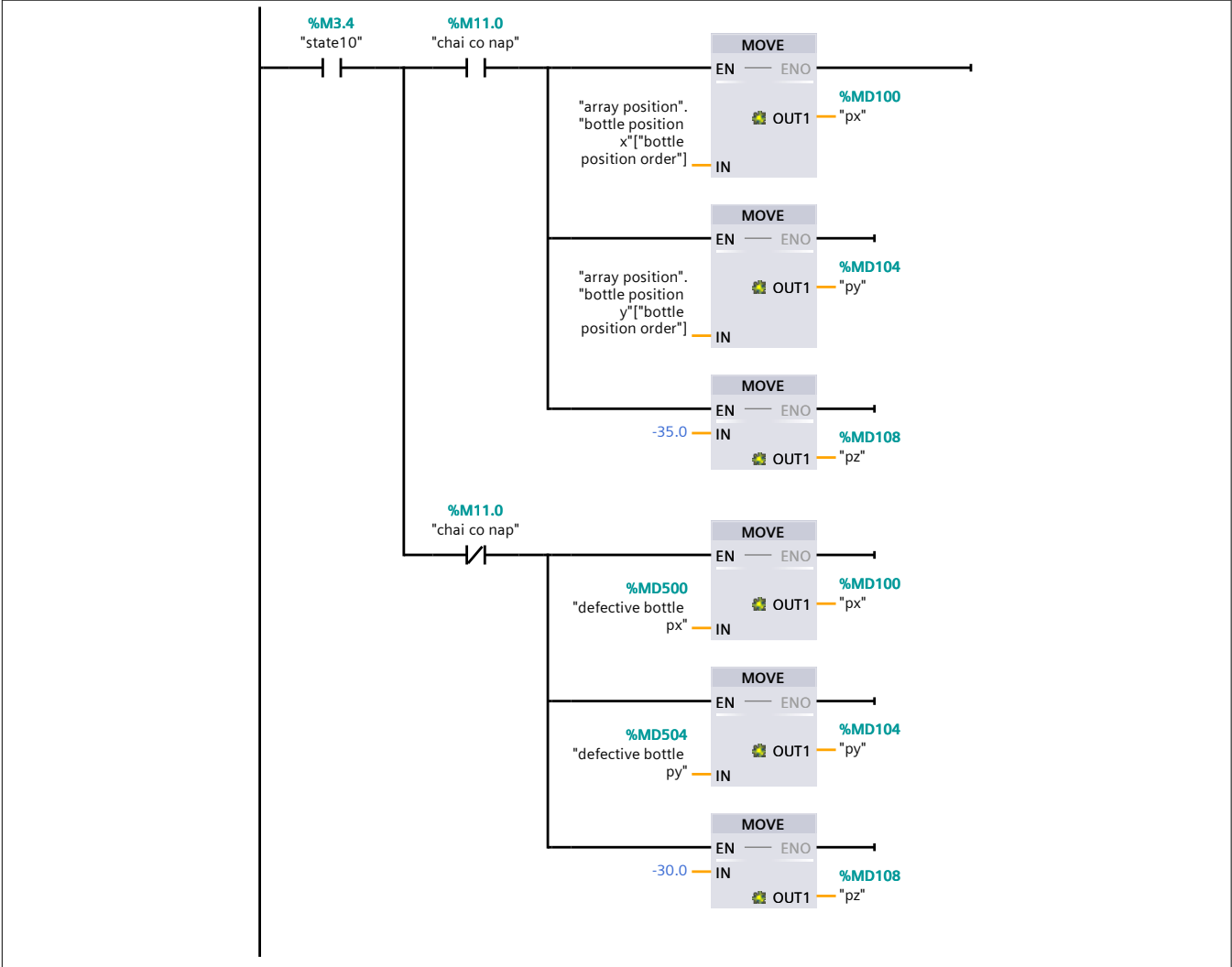
Network 25:



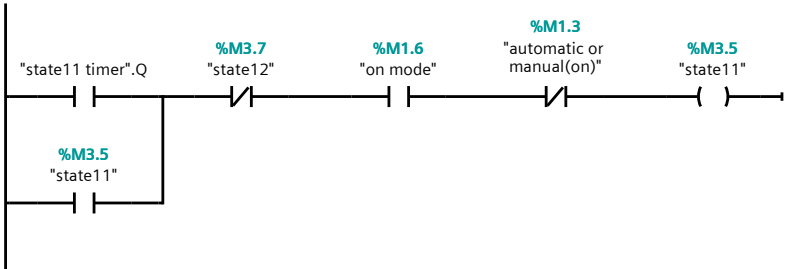
Network 26:



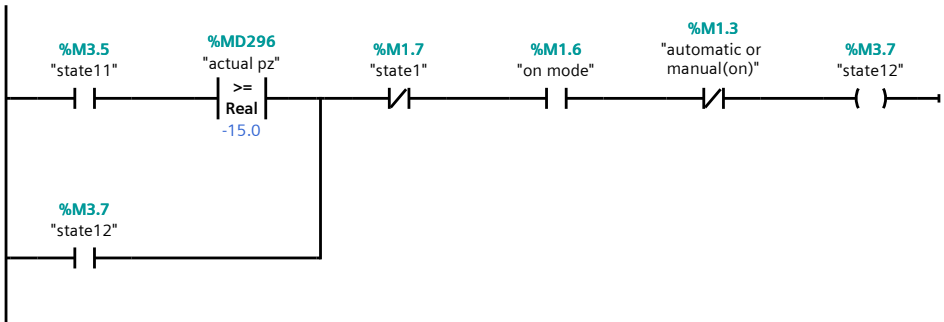
Network 27:



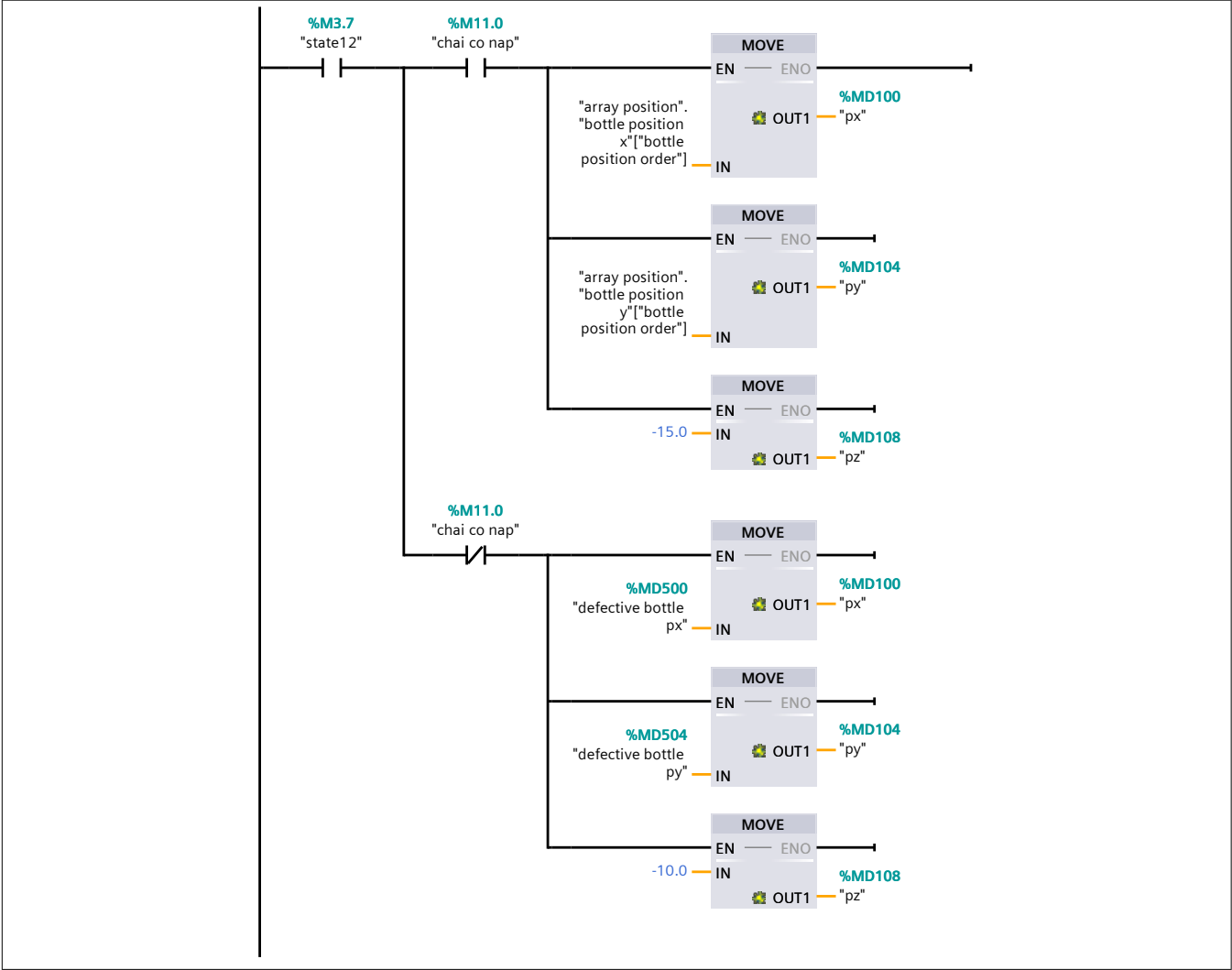
Network 28:



Network 30:



Network 31:



Network 32:

