

# Home assignment for Computer Network EDA387

Group 24

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**Problem** Consider an asynchronous computer network with a distributed but fair scheduler, i.e., not a central daemon. The network has  $n$  nodes, where  $n < N$  is a finite number that is unknown to the algorithm, and  $N$  is an upper bound on  $n$ , such that only the value of  $\lceil \log_2 N \rceil$  is known. The network is based on shared memory where each processor can write to a single register with up to  $O(\lceil \log_2 N \rceil)$  bits. Recall that each register can be divided into multiple fields, say, one field per neighbor. The processors do not have globally unique identifiers, and all nodes run the same program without the presence of a distinguished processor.

Your task is to design a self-stabilizing algorithm that operates within an asynchronous network with a graph topology, which we specify below. The algorithm is required to achieve an accurate node count. After a period of recovery from the occurrence of the last transient fault, each processor should output, using the operation `print(x)`, the total number  $x$  of nodes in the system.

Please present a comprehensive explanation of your solution along with your exact assumptions.

1. Provide a well-structured pseudo-code for your algorithm.
2. Define the set of legal executions.
3. Present a proof of correctness, complete with all necessary arguments to convincingly demonstrate the algorithm's accuracy and self-stabilization. If needed, separate between the convergence and the closure proofs.
4. What is the stabilization time of the proposed algorithm?
5. Does a self-stabilizing naming algorithm exist for the system described? If such an algorithm exists, provide a detailed description and proof of its correctness. If not, provide proof of the impossibility of the result.

## Question 1

Suppose the network topology is an oriented bidirectional path graph  $P_n$ . Specifically, each register is divided into two fields. That is, processor  $p_i$  can read its neighbors' registers,  $\text{left}_j$  or  $\text{right}_k$ , while writing/reading only to its own  $\text{left}_i$  and  $\text{right}_i$  fields in its register, where  $p_j$  and  $p_k$  are  $p_i$ 's neighbors.

The path is oriented from left to right in the sense that each node has a right and/or left neighbor. That is, starting from the leftmost node (which has no left neighbor, i.e.,  $\text{left}_i = \perp$ ) and taking exactly  $n$  hops to the right brings us to the rightmost node (which has no right neighbor, i.e.,  $\text{right}_i = \perp$ ).

*Proof.* Because of each processor has its own register, and in the register, it can be divided into fields, we will use this to store the important information as in the pseudo-code below.

```
00 do forever
01   if not hasLeft:
02       lefti := 0
03   else
04       lefti := min(leftj + 1, N)
05   if not hasRight:
06       righti := lefti + 1
07   else
08       righti := rightk
```

Let consider the left field in the register is for the relative distance from the processor to the leftmost, while the right field is for the number of the processors. In this problem, this code uses 2 floods to update the correct value for a processors. One from the leftmost, carries the relative distance from leftmost processor to  $P_i$ . The other comes from rightmost, carries the information about the total number of processors in this set.

- **Legal execution and legal configuration** each processor can update its *left* or *right* register through computing with the help of the neighbors, left and right. With leftmost's *left* and rightmost's *right*, these values are assigned. The legal configuration is that: each processor holds both the distance to the leftmost and the total number of processors. Under a fair scheduler, every processors will have chance to update these values.
- **Correctness** this algorithm will flood the value from the leftmost to the rightmost. Because it takes exactly  $n$  steps from leftmost to rightmost, at the end of block 01 – 04 (the left flood), each processor will know its relative distance to the leftmost, and this will remain unchanged (because the value is the same after the stabilization). As the same with block 05 – 08, the rightmost will assign the value of  $n$  and will flood it to the leftmost. Because these 2 processes begin from different directions and write to different fields, it is guarantee that the values are correct.

- **Lemma for left convergence** if a processor  $P_i$  has a value  $left_i$  after several asynchronous rounds. Because the leftmost always set its  $left$  to 0, it will be stabilized after at most  $n$  rounds. Hence, the complexity of this algorithm is  $O(n)$  for the left convergence.
- **Lemma for right convergence** because the rightmost keeps setting its  $right$  to the value of its  $left$ , if a register  $right_i$  has transient fault, it will eventually adopt the value  $n$  after at most  $n$  rounds. Same as left convergence, complexity is  $O(n)$ .
- **Time** at most  $n$  cycles, all these processors will be in the safe configuration state.

For the question: *Can a naming self-stabilization algorithm exist on such a system*

The answer is no without a distinguished node. As stated in "Self stabilization" (Angluin 1980, Dolev): "Naming in anonymous, symmetric networks without unique inputs is impossible."

And from this system (as in question 1):

- The network is anonymous, symmetric and deterministic.
- All nodes run identical code with no distinguishing information. (At fault, we even don't know the total nodes).
- The leftmost, and even the rightmost cannot be considered as a standout. Because they need data from each other to form the legal configuration.

But with an symmetry breaking algorithm (leader elective algorithm),

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