



## KR 6 R900-2



## Technical data

| Maximum reach                 | 901 mm          |
|-------------------------------|-----------------|
| Maximum payload               | 6.7 kg          |
| Pose repeatability (ISO 9283) | ± 0.02 mm       |
| Number of axes                | 6               |
| Mounting position             | Floor;          |
|                               | Ceiling;        |
|                               | Wall;           |
|                               | Desired angle   |
| Footprint                     | 208 mm x 208 mm |
| Weight                        | approx. 55 kg   |

#### Axis data

| Motion range               |                |
|----------------------------|----------------|
| A1                         | ±170 °         |
| A2<br>A3<br>A4<br>A5<br>A6 | -190 ° / 45 °  |
| A3                         | -120 ° / 156 ° |
| A4                         | ±185 °         |
| A5                         | ±120 °         |
| A6                         | ±350 °         |

## Operating conditions

| Ambient temperature during opera- | 0 °C to 45 °C (273 K to 318 K) |
|-----------------------------------|--------------------------------|
| tion                              |                                |

## **Protection rating**

| Protection rating (IEC 60529)       | IP65 / IP67 |
|-------------------------------------|-------------|
| Protection rating, robot wrist (IEC | IP65 / IP67 |
| 60529)                              |             |

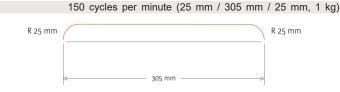
## Controller

| Controller | KR C5 micro;  |
|------------|---------------|
|            | KR C4 compact |

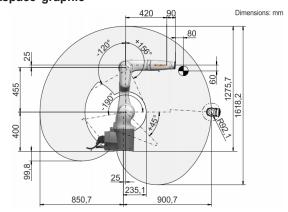
#### Certificates

ESD requirements IEC61340-5-1; ANSI/ESD S20.20

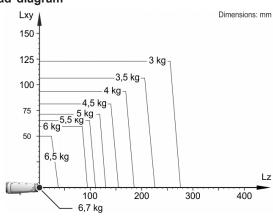
# Cycle time



## Workspace graphic



## Payload diagram



The KR 6 R900-2 is designed for a rated payload of 3 kg in order to optimize the dynamic performance of the robot. The maximum payload of 6.7 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

# Mounting flange

