

```
PS C:\Users\phamd\Desktop\robot ass\4.Using tags\Assignment> robot -d results -i Default_speed morse.robot
=====
Morse :: Example of morse transmitter test
=====
Whatever speed | PASS |
-----
Morse :: Example of morse transmitter test | PASS |
1 test, 1 passed, 0 failed
=====
```

```
PS C:\Users\phamd\Desktop\robot ass\4.Using tags\Assignment> robot -d results -i Speed_with_range morse.robot
=====
Morse :: Example of morse transmitter test
=====
Speed with range 10% | PASS |
-----
Morse :: Example of morse transmitter test | PASS |
1 test, 1 passed, 0 failed
=====
```

```
PS C:\Users\phamd\Desktop\robot ass\4.Using tags\Assignment> robot -d results -i Exactly_speed morse.robot
=====
Morse :: Example of morse transmitter test
=====
Expected speed is equal input speed | PASS |
-----
Morse :: Example of morse transmitter test | PASS |
1 test, 1 passed, 0 failed
=====
```