

# Review

February 20, 2023

## 1 Foundations (Section 2.1 - 2.4)

### 1. Ordinary differential Equations (ODEs)

ODEs are differential equations with respect to one variable.

### 2. Initial conditions

Suppose  $E \subset R^n$ ,  $(x_0, \mu_0) \in E$ . For any closed ball  $B \subset E$ ,  $\exists a > 0, \delta > 0$ , there is an initial condition  $(t_0, y_0, \mu_0) \in [-a, a] \times B(x_0, \delta) \times B(x_0, \delta)$ .

### 3. Initial value problems (IVP)

An IVP consists of a differential equation together with an initial condition  $(t_0, x_0) \in R \times E$ , such that:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= x_0\end{aligned}$$

We say that  $x(t)$  is a solution of this IVP on the interval  $I$  that satisfies:

$$t_0 \in I$$

$$x(t_0) = x_0$$

$x(t)$  is a solution of this IVP on  $I$

### 4. Continuity and the derivative for function $f : R^n \rightarrow R^n$

#### a. Definition of a continuous function

Suppose  $f : E \rightarrow R^n$ ,  $x \in E$ . We say that  $f$  is continuous at  $x$  if the following condition holds:  $\forall \epsilon > 0$ ,  $\exists \delta > 0$  if  $y \in E$  and  $|x - y| < \delta$ , then:

$$|f(x) - f(y)| < \epsilon$$

Furthermore,  $f$  is continuous on  $E$  if  $f$  is continuous at each point of  $E$

#### b. Differential function

Suppose  $E \subset R^n$ ,  $f : E \rightarrow R^n$  is continuous. We say  $f$  is differential at  $x_0$  if there is a linear transformation  $Df(x_0)$  such that:

$$\lim_{|h| \rightarrow 0} \frac{\|f(x_0 + h) - f(x_0) - Df(x_0)h\|}{\|h\|} = 0$$

In this case,  $Df(x_0)$  is the derivative of  $f$  at  $x_0$ . Furthermore, if  $f$  is differentiable at each point of  $E$ , then  $f$  is differentiable on  $E$ .

The derivative  $Df$  is given by  $n \times n$  Jacobian matrix

$$Df = \left[ \frac{\partial f_j}{\partial x_j} \right]$$

5.  $C^0(E), C^1(E)$

a.  $C^0(E)$

For any open set  $E \subset R^n$ , we let:

$$C(E) = \{f : E \rightarrow R^n, f \text{ is continuous on } E\}$$

b.  $C^1(E)$

For any open set  $E \subset R^n$ , we let:

$$C^1(E) = \{f : E \rightarrow R^n, f \text{ is differentiable on } E, \frac{\partial f_i}{\partial x_j} \text{ are continuous}\}$$

6. Locally Lipschitz

Suppose  $E \subset R^n$ ,  $f \in C^1(E)$ . For any closed ball  $B \subset E$ , there exists  $K \geq 0$ ,  $\forall x, y \in B$ , we have:

$$|f(x) - f(y)| \leq K|x - y|$$

7. Peano Theorem

Suppose  $E \subset R^n$ ,  $f : E \rightarrow R^n$  is continuous. For any initial condition  $(t_0, x_0) \in R \times E$ , the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= x_0\end{aligned}$$

has at least one solution  $x(t)$  on the interval  $I$  containing  $t_0$ .

8. Fundamental Theorem of Existence and Uniqueness

Suppose  $E \subset R^n$ ,  $f \in C^1(E)$ . For any initial condition  $(t_0, x_0) \in R \times E$ , there exists  $a > 0$ , the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= x_0\end{aligned}$$

has a unique solution  $x(t)$  on the interval of the form  $[t_0 - a, t_0 + a]$ .

9. Integral Equations

Suppose  $E \subset R^n$ ,  $f : E \rightarrow R^n$  is continuous. Consider IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= x_0\end{aligned}$$

has a solution  $x(t)$  on the interval containing  $t_0$  if and only if it satisfies:

$$x(t) = x_0 + \int_0^t f(x(s))ds$$

10. Successive approximations:

Apply the formula

$$u_{k+1} = x_0 + \int_0^t f(u_k(s))ds$$

to solve the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= x_0\end{aligned}$$

11. Dependence on initial conditions and parameters:

a. Dependence on initial conditions:

Suppose  $E \subset \mathbb{R}^n$ ,  $f \in C^1(E)$ ,  $x_0 \in E$ . Then  $\exists a > 0, \epsilon > 0$ .  $\forall y \in B(x_0, \epsilon)$ , the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= y\end{aligned}$$

has a unique solution  $u(t, y)$  on the interval containing  $t_0$ .

$u(t, y) \in C^1(G)$  where  $G = [-a, a] \times B(x_0, \epsilon)$ .

$\forall y \in B$ ,  $u(t, y)$  has twice continuously differentiable in  $t$ .

b. Dependence on parameters:

Suppose  $E \subset \mathbb{R}^{n+m}$ ,  $f \in C^1(E)$ ,  $(x_0, \mu_0) \in E$ . Then  $\exists a > 0, \epsilon > 0$ ,  $\forall y \in B(x_0, \epsilon)$  and  $\forall \mu \in B(\mu_0, \epsilon)$ , the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= y\end{aligned}$$

has a unique solution  $u(t, y, \mu)$  and  $u(t, y, \mu) \in C^1(G)$  where  $G = [-a, a] \times B(x_0, \epsilon) \times B(\mu_0, \epsilon)$

12. Gronwall's Inequality:

Suppose  $g(t)$  is continuous,  $g(t) \geq 0 \forall t \in [0, a]$ . It satisfies:

$$g(t) \leq C + K \int_0^t g(s) ds$$

We have:

$$g(t) \leq Ce^{Kt}$$

Proof:

Define  $G(t) = C + K \int_0^t g(s) ds$

$G(t) \geq g(t)$  and  $G(t) > 0 \forall t \in [0, a]$ .

By FTC, we have:

$$G'(t) = Kg(t)$$

Then,

$$\frac{d}{dt}(\ln G(t)) = \frac{G'(t)}{G(t)} = \frac{Kg(t)}{G(t)} \leq \frac{KG(t)}{G(t)} = K$$

Integrate both sides from 0 to  $t$ , we have:

$$\ln G(t) - \ln G(0) \leq Kt$$

then,  $\ln G(t) \leq \ln G(0) + Kt$

$\Rightarrow g(t) \leq G(t) \leq Ce^{Kt}$

13. Maximal interval of existence

a. Definition:

An IVP has a maximal interval of existence if there exists a solution  $x(t)$  this IVP on the interval  $J$  such that if  $y(t)$  is another solution on the interval  $I$ ,  $I \subset J$ , and  $x(t) = y(t), \forall t \in I$ .

b. Theorem:

Suppose  $E \subset \mathbb{R}^n$ ,  $f \in C^1(E)$ ,  $x_0 \in E$ . The IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= y\end{aligned}$$

has a maximal interval of existence  $J$ ,  $J$  is open.

14. Escape from the compact set

Suppose  $E \subset \mathbb{R}^n$ ,  $f \in C^1(E)$ ,  $x_0 \in E$ . Let  $(\alpha, \beta)$  is the maximal interval of existence of the IVP:

$$\begin{aligned}\dot{x} &= f(x) \\ x(t_0) &= y\end{aligned}$$

If  $\beta < \infty$ , there is any compact set  $K \subset E$ ,  $\forall t \in (\alpha, \beta)$ ,  $x(t) \notin K$ .

Corollary 1: If  $\beta < \infty$ , limit when  $t \rightarrow \beta -$  exists,  $x(t) \in K$  (compact set), then the limit point  $x_1 \in \partial E$ .

Corollary 2:  $K$  is compact, for all  $t \in (\alpha, \beta)$ ,  $x(t) \in K$ , then  $\beta = \infty$

## 2 Linear systems (Sections 1.1 - 1.5)

1. Linear system of equations

Let  $A$  be a  $nn$  matrix,  $x_0 \in \mathbb{R}^n$ :

$$\begin{aligned}\dot{x} &= Ax \\ x(0) &= x_0\end{aligned}$$

Since  $f(x) = Ax$  is linear, then the IVP is called a linear system of equations.

2. Fundamentals Theorem for Linear Systems

Let  $A$  be a  $n \times n$  matrix,  $x_0 \in \mathbb{R}^n$ :

$$\begin{aligned}\dot{x} &= Ax \\ x(0) &= x_0\end{aligned}$$

has a unique solution  $x(t) = e^{At}x_0, \forall t \in \mathbb{R}$