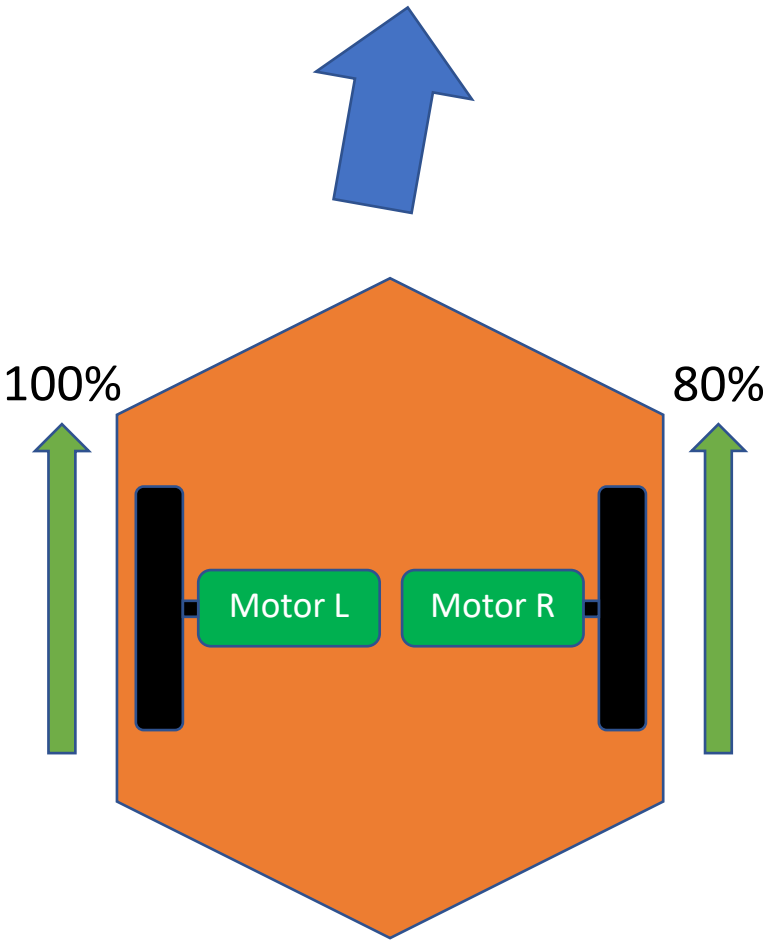
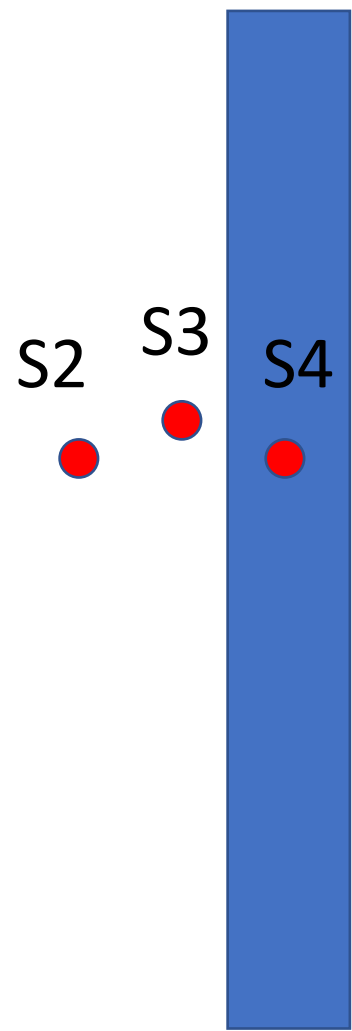


ค่าที่อ่านได้

S2	S3	S4
1	0	0

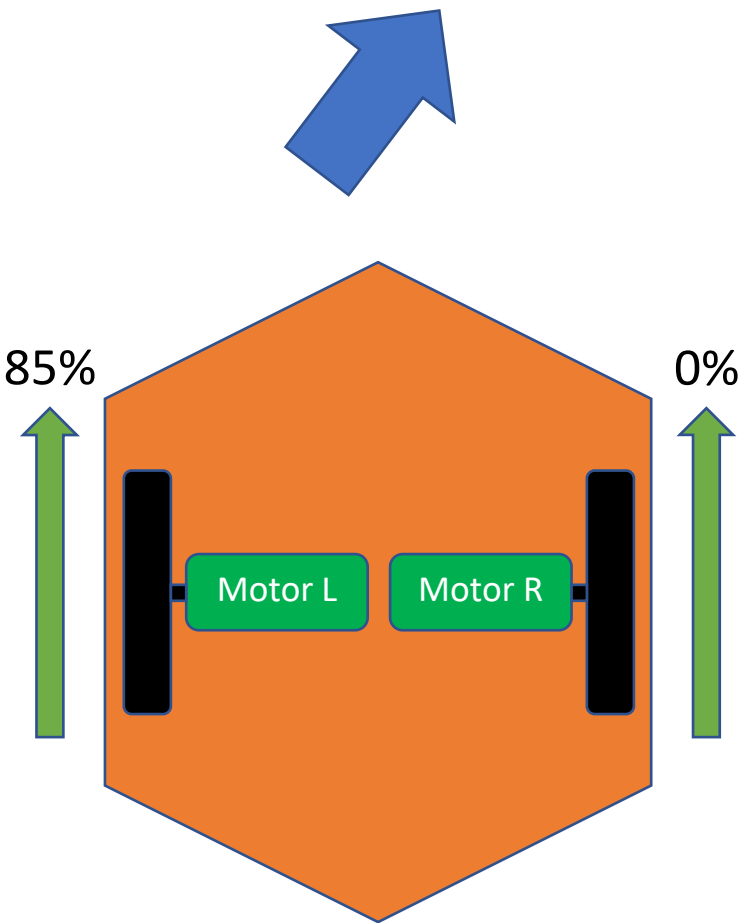


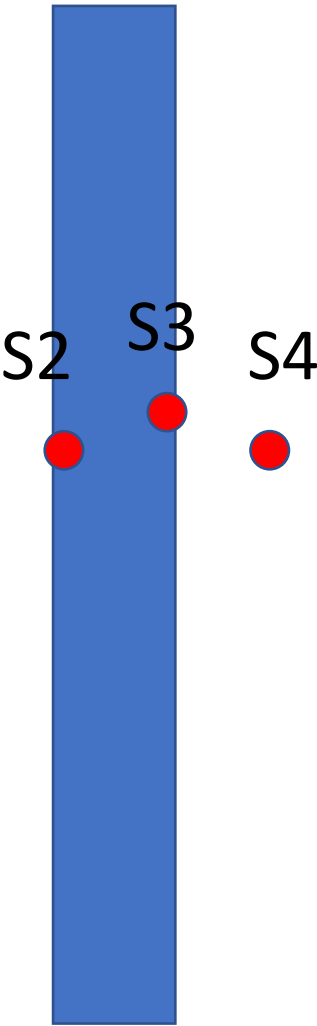
State 3



ค่าที่อ่านได้

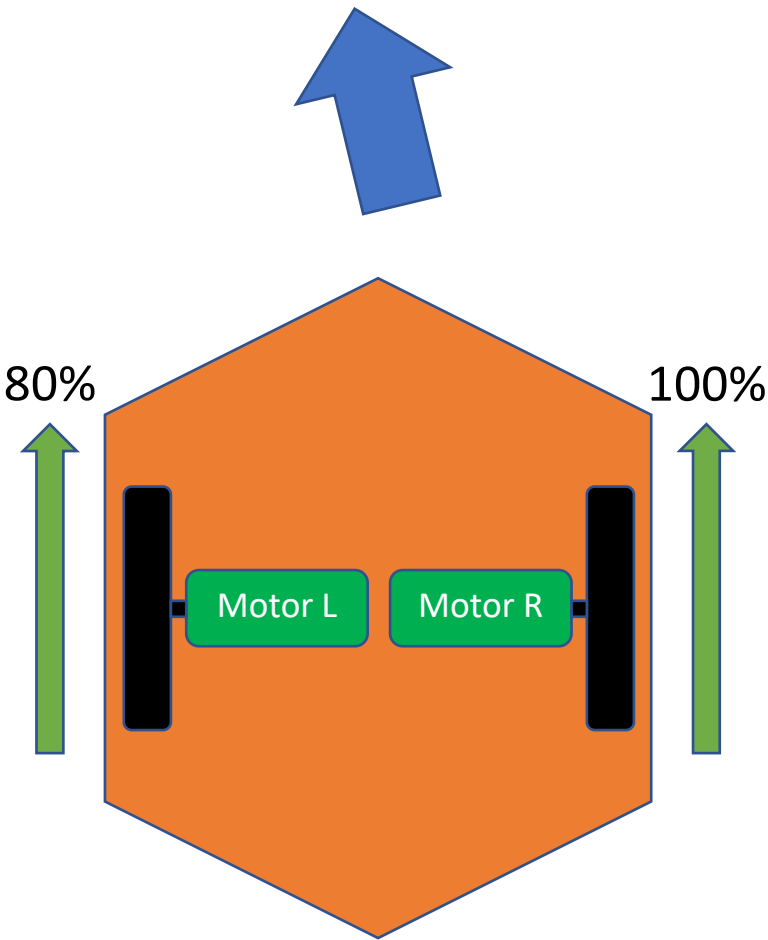
S2	S3	S4
1	1	0

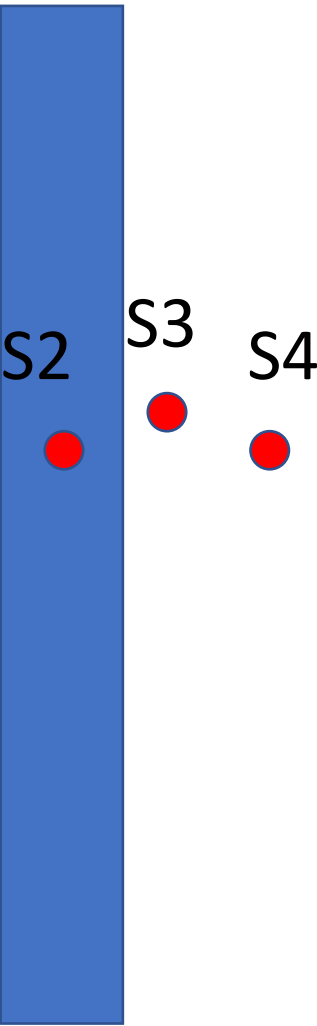




ค่าที่อ่านได้

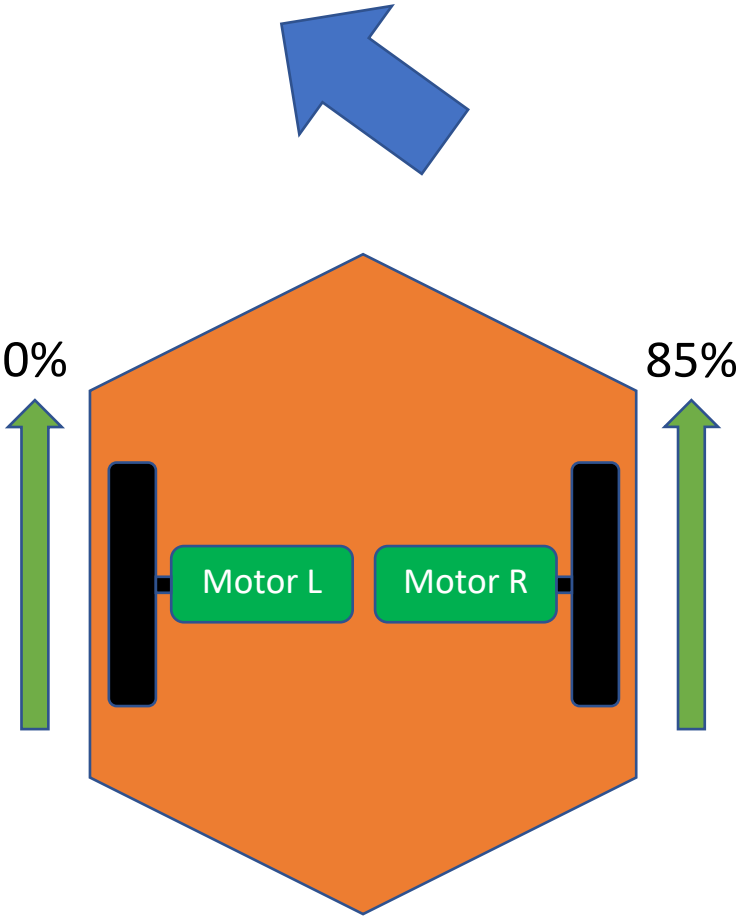
S2	S3	S4
0	0	1

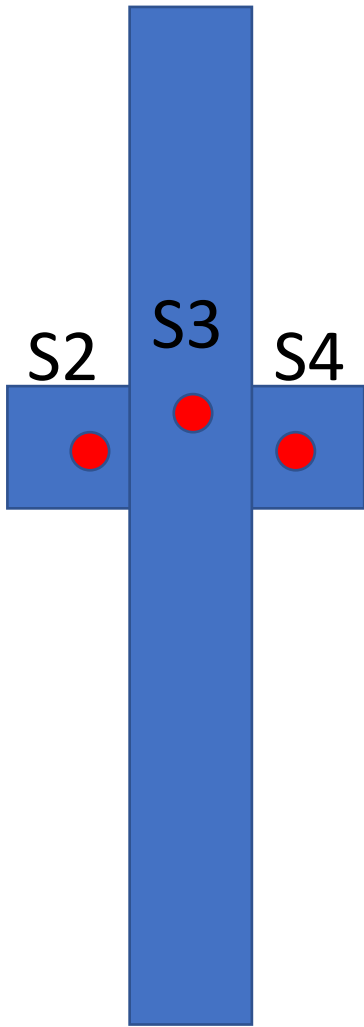




ค่าที่อ่านได้

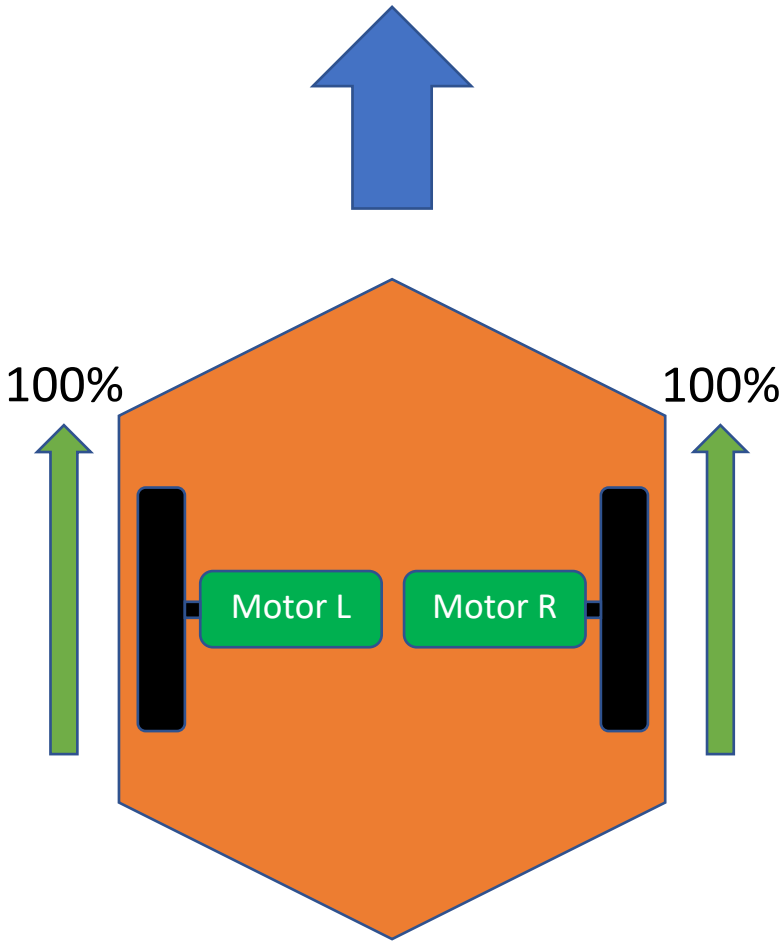
S2	S3	S4
0	1	1

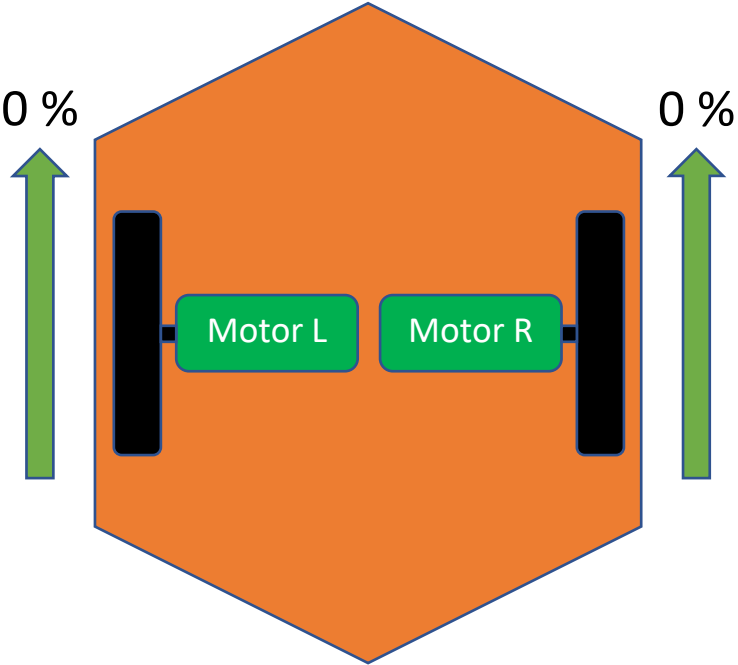
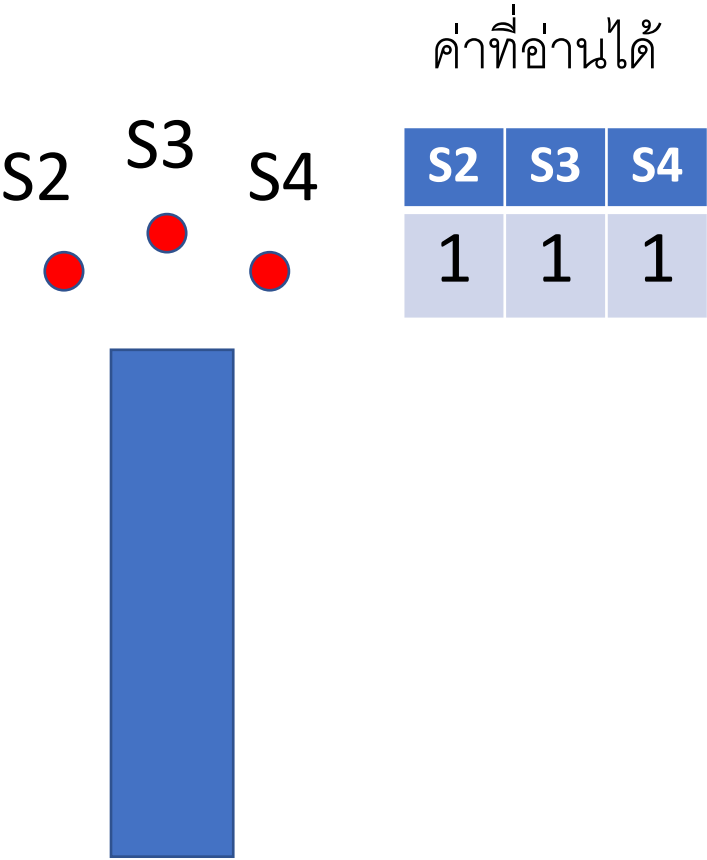


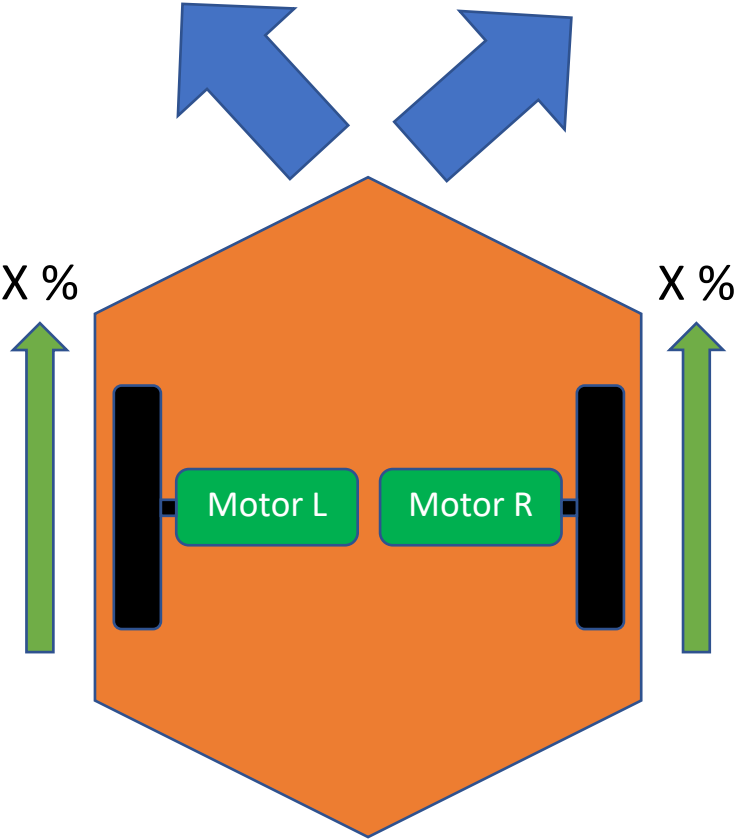
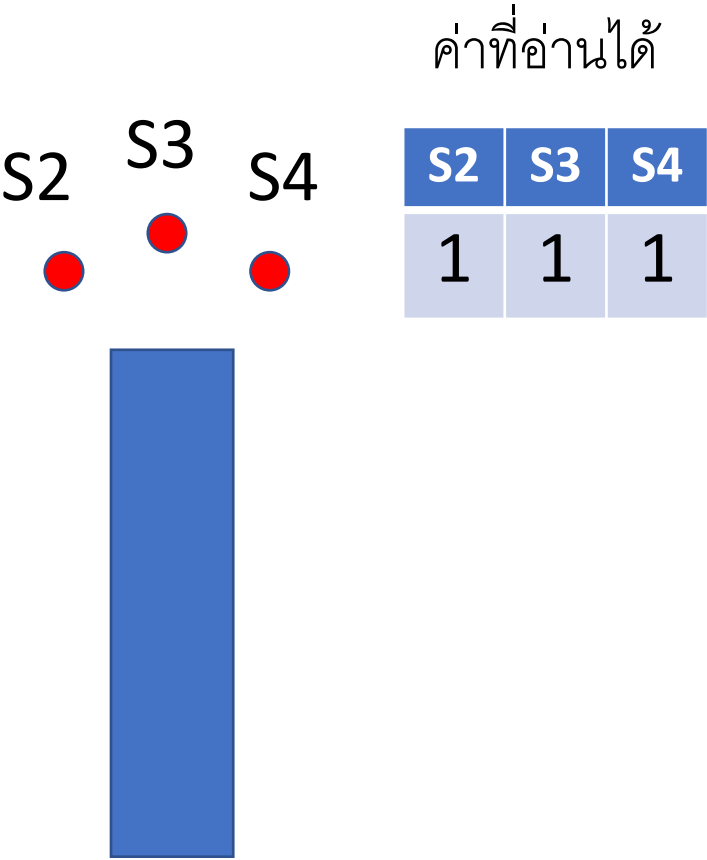


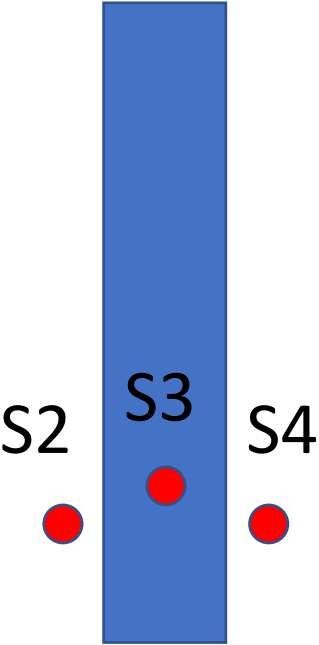
ค่าที่อ่านได้

S2	S3	S4
0	0	0



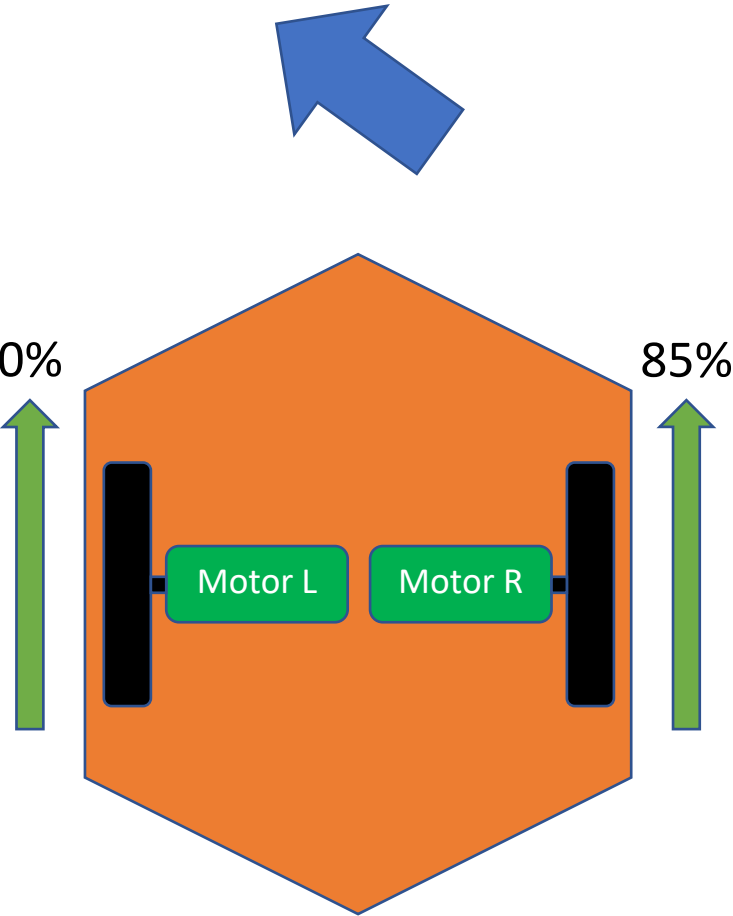






ค่าที่อ่านได้

S2	S3	S4
0	1	1

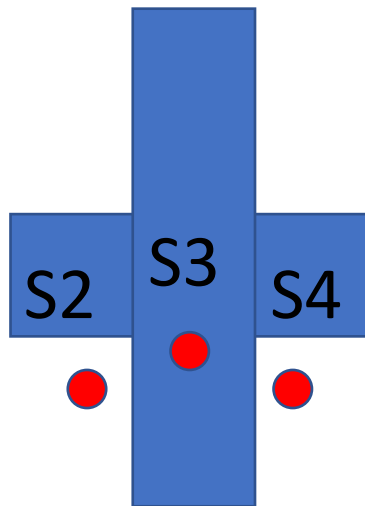




Step1

ค่าที่อ่านได้

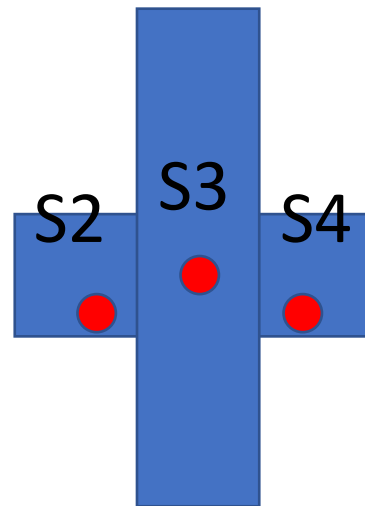
S2	S3	S4
1	0	1



Step2

ค่าที่อ่านได้

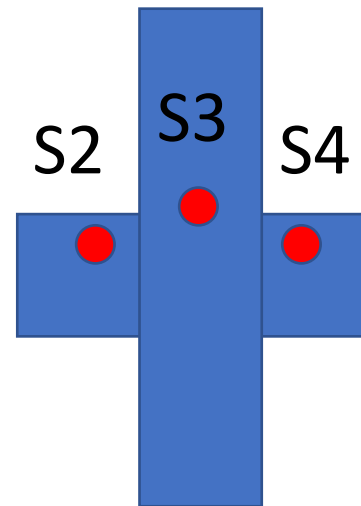
S2	S3	S4
0	0	0



Step3

ค่าที่อ่านได้

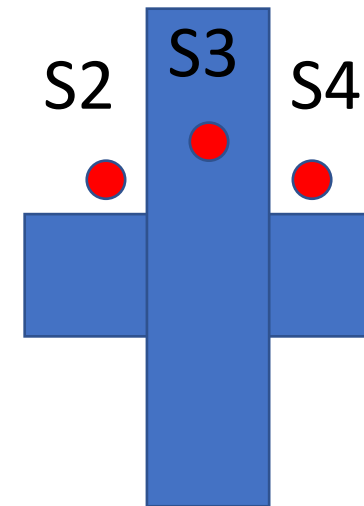
S2	S3	S4
0	0	0



Step4

ค่าที่อ่านได้

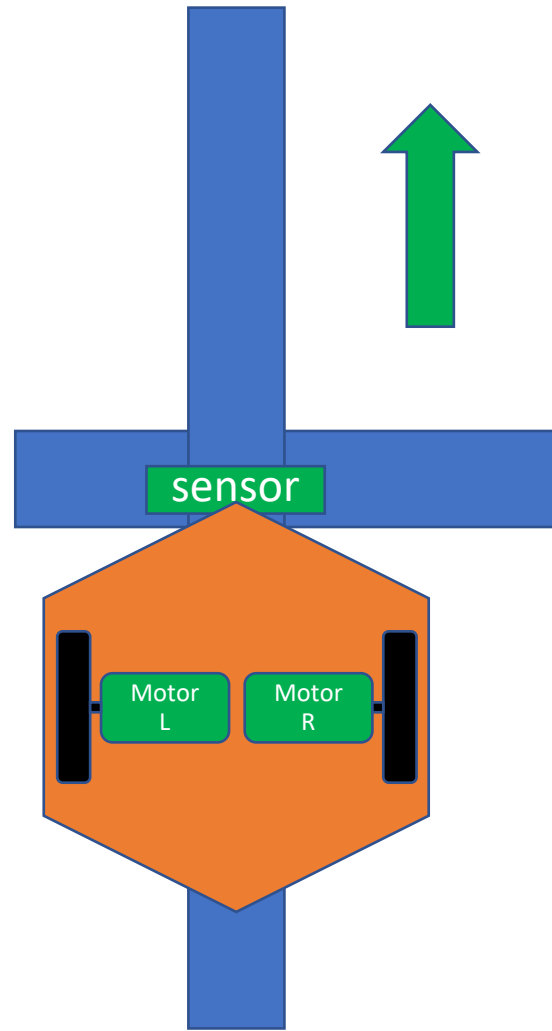
S2	S3	S4
1	0	1



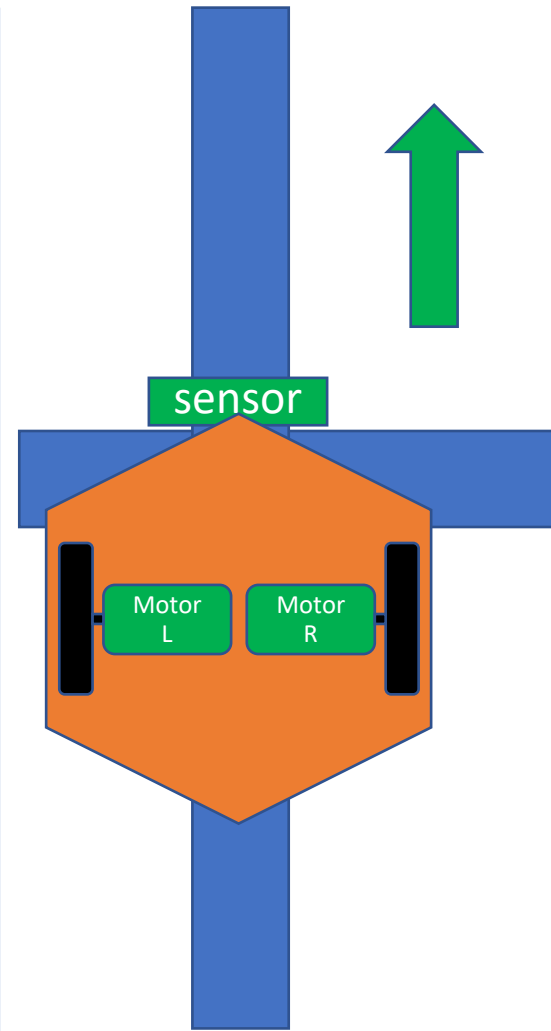
Line count ++



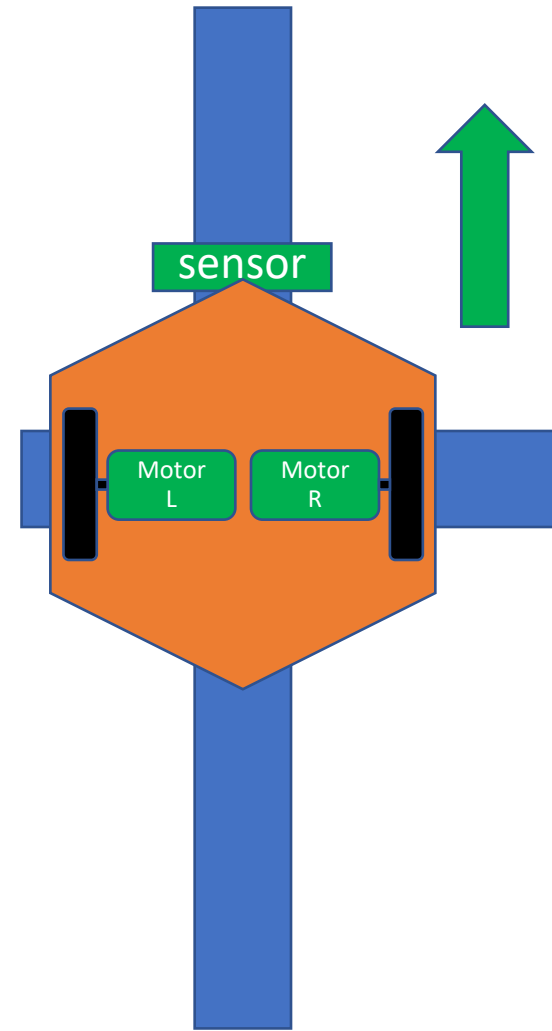
Step1



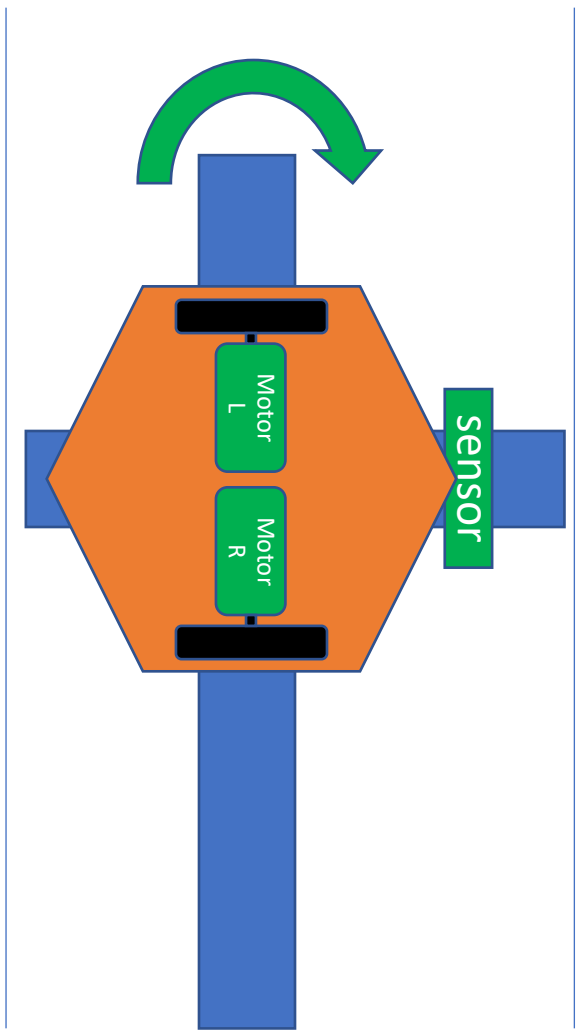
Step2



Step3

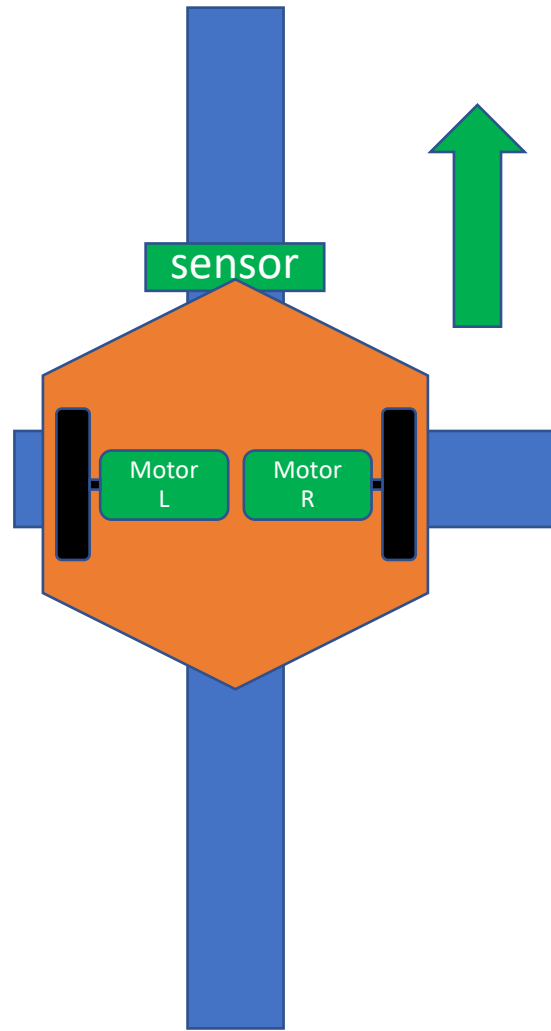


Step4

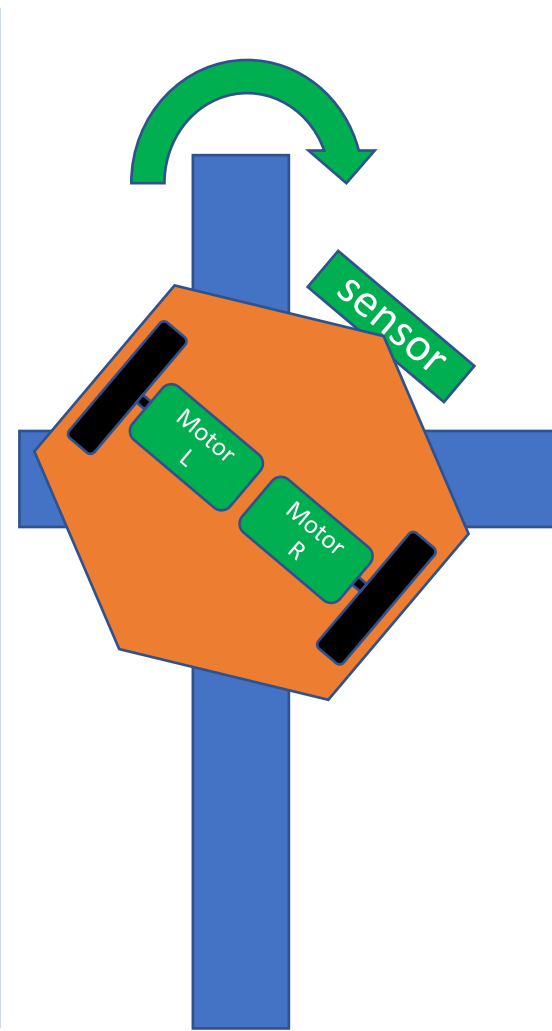




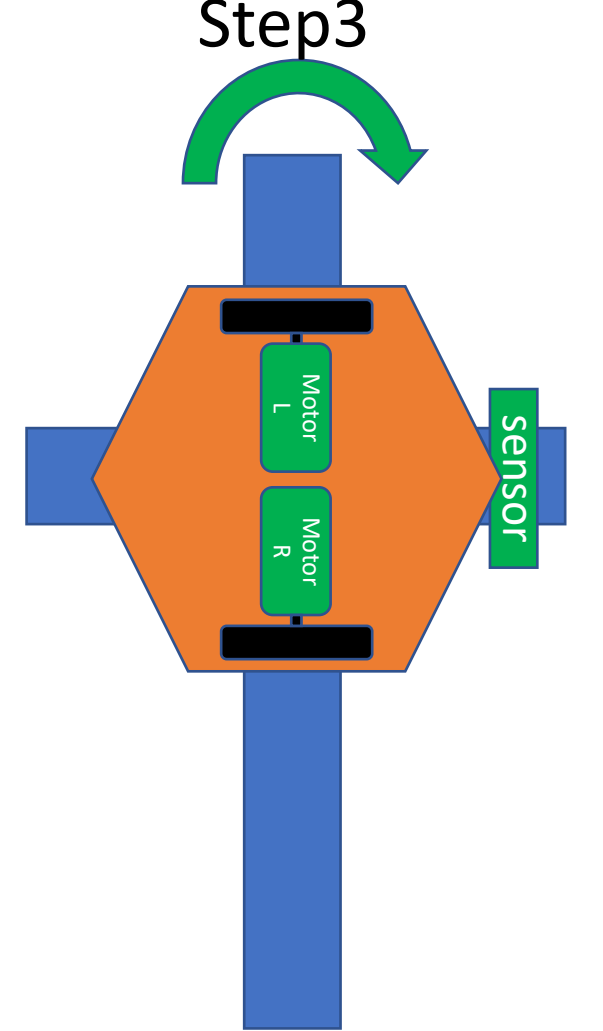
Step1



Step2



STEM Robotics
Step3

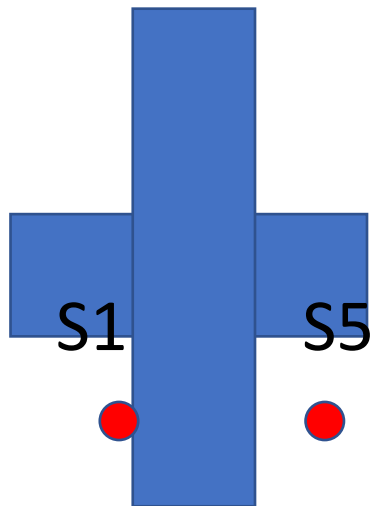




Step1

ค่าที่อ่านได้

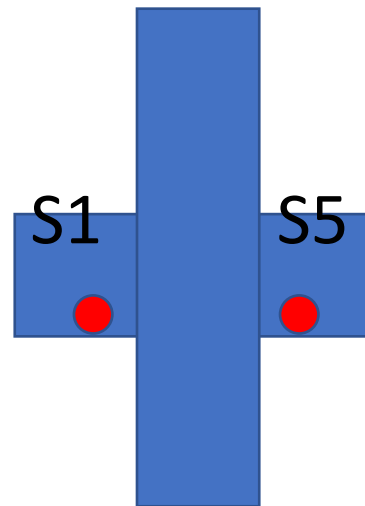
S1		S5
1		1



Step2

ค่าที่อ่านได้

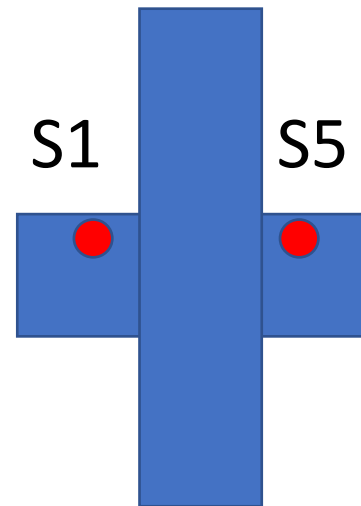
S1		S5
0		0



Step3

ค่าที่อ่านได้

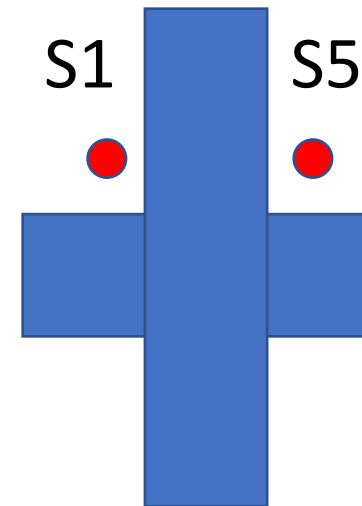
S1		S5
0		0



Step4

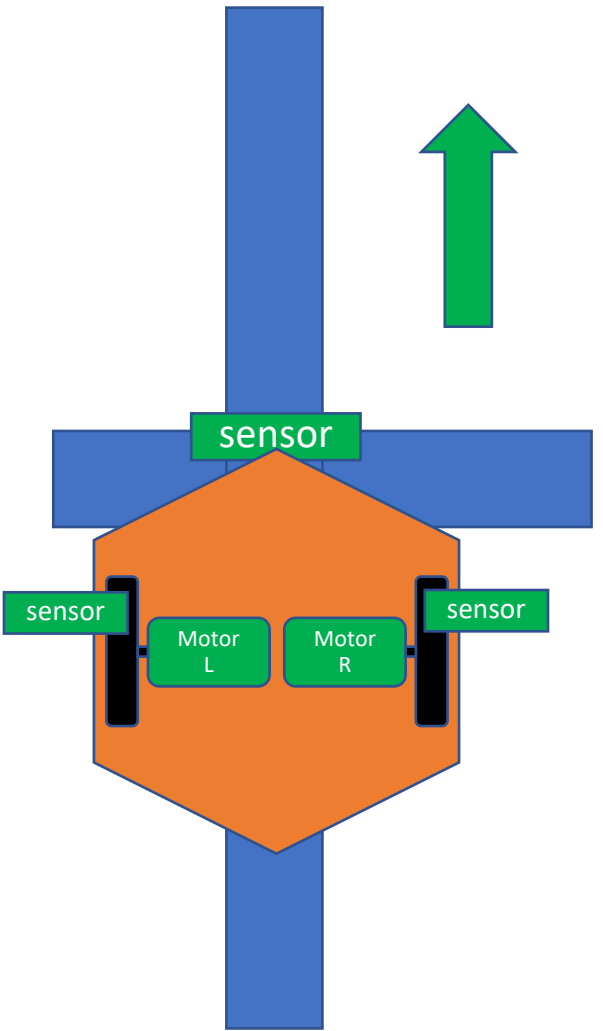
ค่าที่อ่านได้

S1		S5
1		1

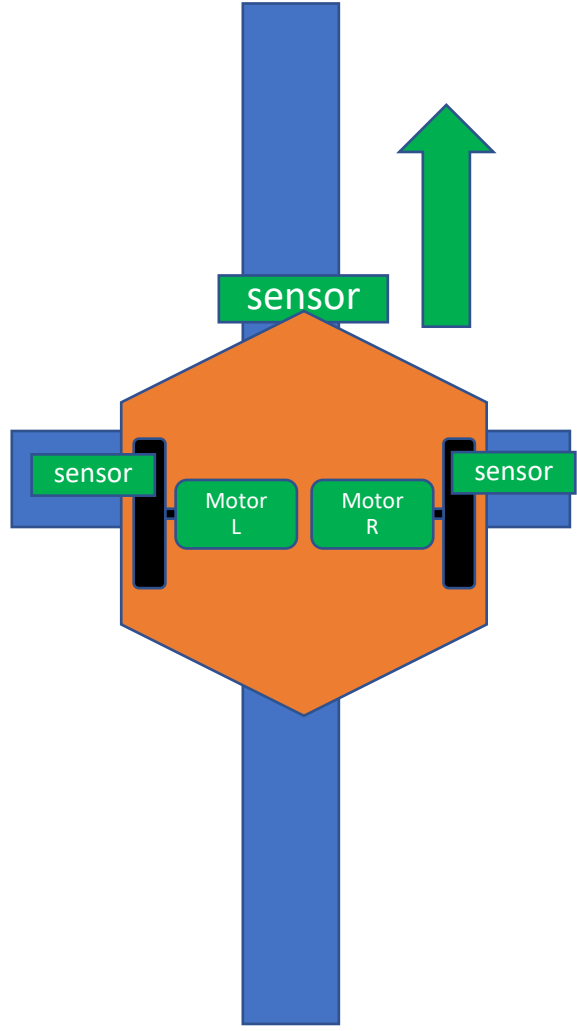


Line count ++

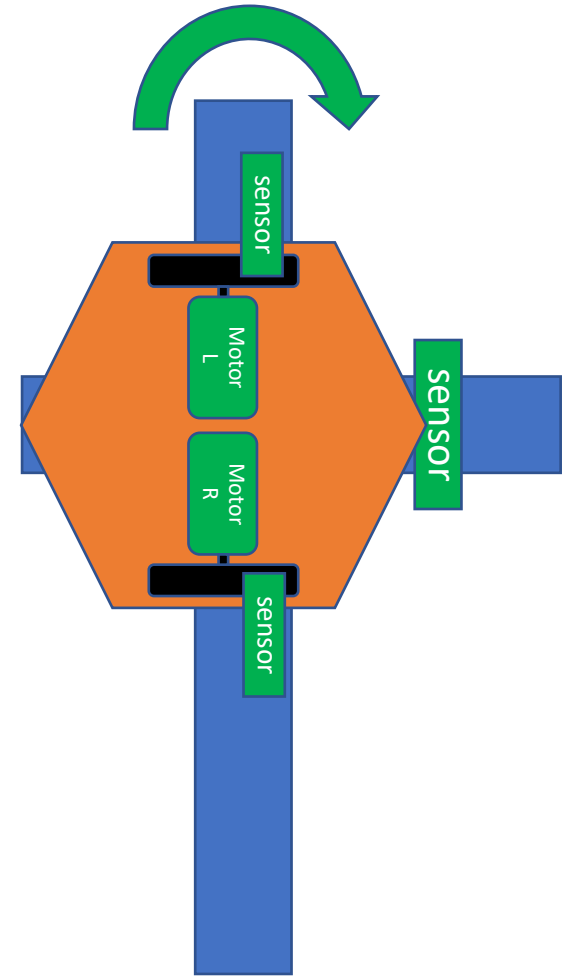
Step1



Step2



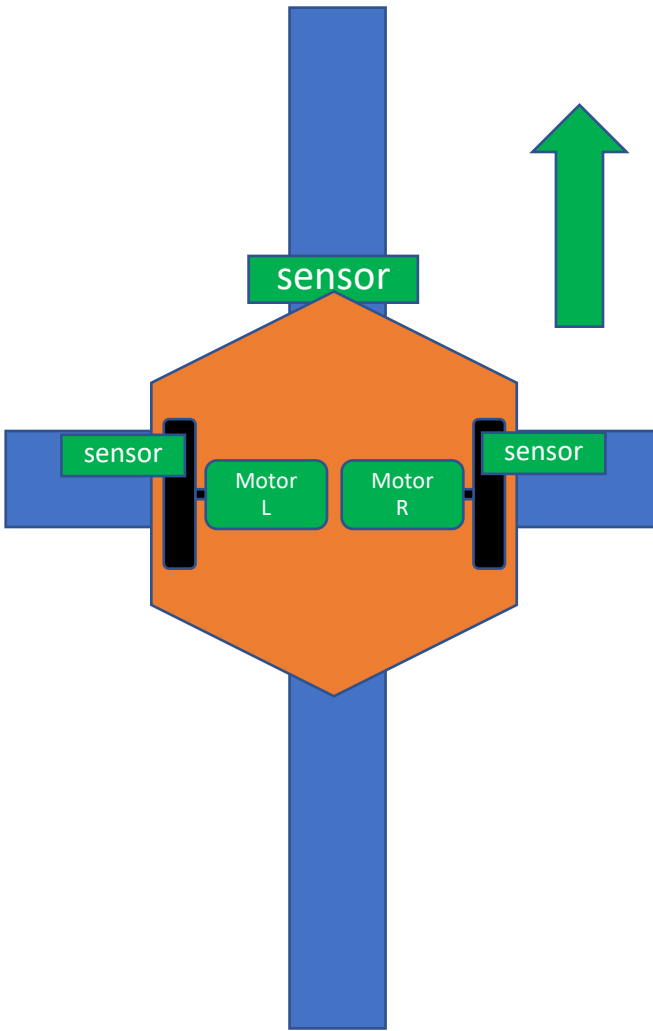
Step3



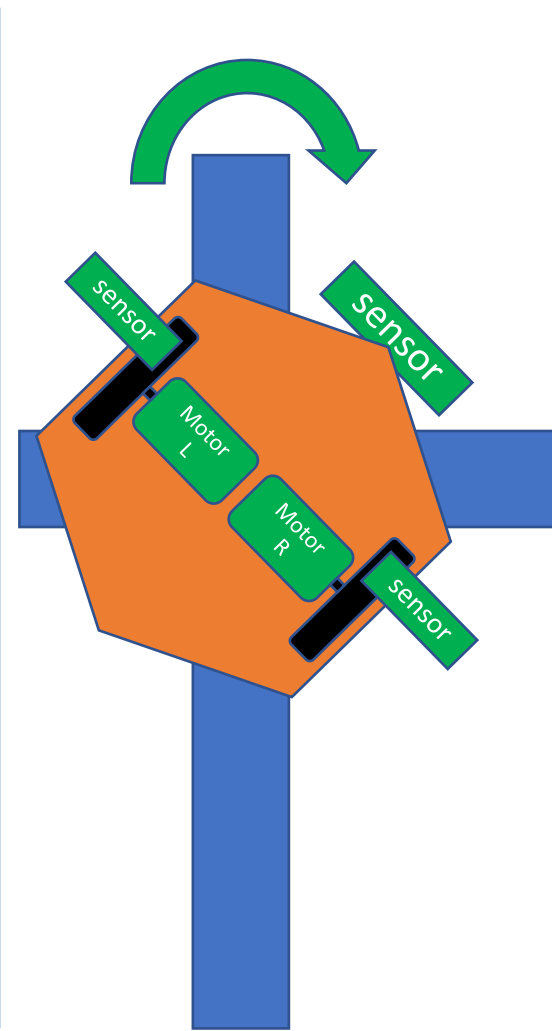
Step4



Step1



Step2



STEM Robotics
Step3

