

Quantisation

Efficient implementation of convolutional neural networks

Philip Leong

Computer Engineering Lab
The University of Sydney

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Australia



Australia and Europe Area size comparison

Darwin to Perth 4396km • Perth to Adelaide 2707km • Adelaide to Melbourne 726km

Melbourne to Sydney 887km • Sydney to Brisbane 972km • Brisbane to Cairns 1748km



Population: 24M (2016)
Europe: 741M (2016)
Hong Kong: 7M (2016)
Area 1/25th Tasmania

Outline

1 Introduction

Number Systems

Convolutional Neural Networks

Integer Quantisation

SYQ: Low Precision DNN Training

FINN: A Binarised Neural Network

2 Tutorial

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Introduction

- There are several degrees of freedom to explore when optimising DNNs
 - NN architecture (SqueezeNet, MobileNet)
 - Compression (SVD, Deep Compression, Circulant)
 - Quantization (FP16, TF-Lite, FINN, DoReFa-Net)
- This talk: quantisation

Unsigned Numbers

$$\begin{aligned}U &= (u_{W-1} u_{W-2} \dots u_0), u_i \in \{0, 1\} \\&= \sum_{i=0}^{W-1} u_i 2^i\end{aligned}$$

- U is a W -bit unsigned integer
- Range $[0, 2^W)$

Two's Complement Numbers

$$\begin{aligned} X &= (x_{W-1}x_{W-2}\dots x_0), x_i \in \{0, 1\} \\ &= -x_{W-1}2^{W-1} + \sum_{i=0}^{W-2} x_i 2^i \end{aligned}$$

- X is a W -bit signed integer
- Range $[-2^{W-1}, 2^{W-1})$

Two's Complement Fractions

$$\begin{aligned} Y &= (\overbrace{y_{W-1} \dots y_F}^{\text{I-bit integer}} \overbrace{y_{F-1} \dots x_0}^{\text{F-bit fraction}}), y_i \in \{0, 1\} \\ &= 2^{-F} \times (-x_{W-1} 2^{W-1} + \sum_{i=0}^{W-2} x_i 2^i) \end{aligned}$$

- Y is a W -bit signed fraction with F -bit fraction
- Are two's complement numbers scaled by 2^{-F}
- Notation used: (I, F) (with $I + F = W$)
 - $(W, 0)$ same as two's complement integers
 - $(1, W-1)$ has range $[-1, 1]$ and multiplication never overflows

Dynamic Fixed Point [CBD14]

$$D = (-1)^S \cdot 2^{-F} \sum_{i=0}^{W-2} x_i 2^i$$

- D is dynamic fixed point number with sign bit S , fractional length F , W is word length
- Sign-magnitude fraction with F being shared within a group
- Allows number format to be adapted to different network segments e.g. layer inputs, weights and outputs can have different F

Operations on Two's Complement Fractions

- Addition and subtraction same as two's complement
- Multiplication
 - An (I,F) multiplication gives a (2I,2F) result, need to discard F bits
 - For (1,3)

$$\begin{aligned}0.75 \times 0.75 &= 0.110 \times 0.110 \\&= 00.100100 \quad \text{in (2I,2F) format} \\&\approx 0.100 \quad \text{in (I,F) format (truncated)}\end{aligned}$$

- Integer part controls range
- Fractional part controls spacing between numbers

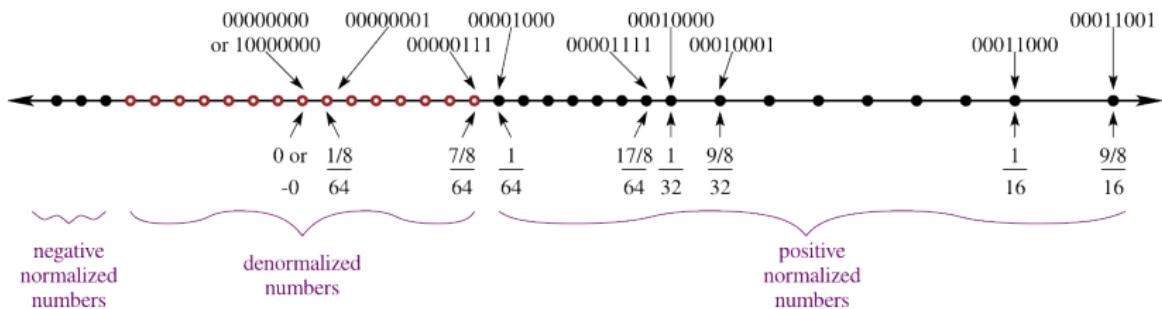
Floating Point 1

$$Z = (\overbrace{a_0}^A \overbrace{b_{J-1} \dots b_0}^B \overbrace{c_{F-1} \dots c_0}^C), (a_i, b_i c_i) \in \{0, 1\}$$

- Treating A, B and C as unsigned integers
 - The sign bit is $S = \begin{cases} +1 & \text{if } a_0 = 0 \\ -1, & \text{otherwise} \end{cases}$
 - The exponent is stored in a biased representation with $E = B - (2^{J-1} - 1)$
 - For normalised numbers, $B \neq 0$, and M is a positive (1,F) two's complement fraction $M = 1 + C2^{-F}$
 - For denormalised numbers $B = 0$ and there is no implicit 1 in the positive (0,F) two's complement fraction $M = C2^{-F}$

Floating Point 2

$$Z = \begin{cases} S \times 2^E \times M & \text{if } (0 < B < 2^J - 1) \\ S \times 2^E \times (M - 1) & \text{if } (B = 0) \\ S \times \infty & \text{if } (B = 2^J - 1 \text{ and } C = 0) \\ \text{NaN} & \text{if } (B = 2^J - 1 \text{ and } C \neq 0) \end{cases}$$



Operations on Floating Point Numbers

- Much larger resource utilisation
- Longer latency
- We will focus on fixed point

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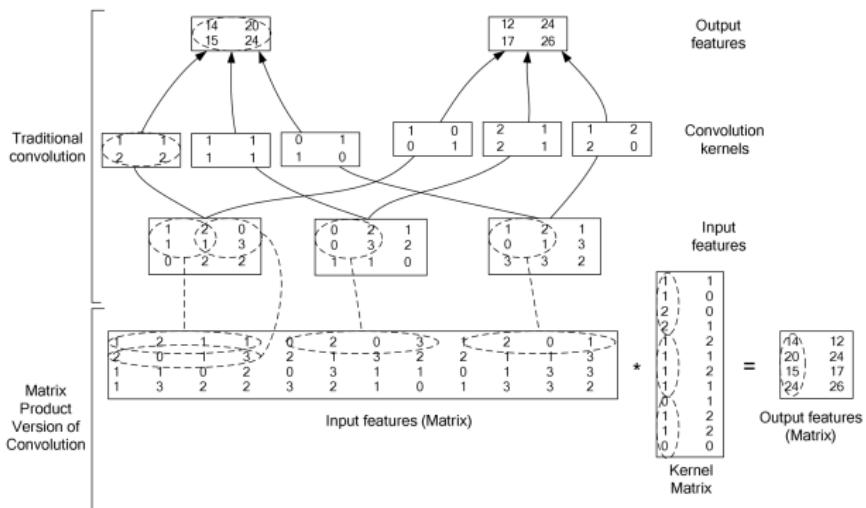
SYQ: Low Precision DNN Training

FINN: A Binarised Neural Network

2 Tutorial

Convolution Layer as MM

- Convolution layers converted to GEMM [CPS06]
- Efficient BLAS libraries can be exploited



DNN Computation

Computational problem in DNNs is to compute a number of dot products

$$h = g(\mathbf{w}^T \mathbf{x}) \quad (1)$$

where

- g is an element-wise nonlinear activation function
- $\mathbf{x} \in \mathbb{R}^{i.w.h}$ is the input vector
- $\mathbf{w} \in \mathbb{R}^{i.w.h}$ is the weight vector

Arithmetic Intensity

- Computation of a DNN layer is MV multiplication
- For MV multiply is $O(1)$, for MM is $O(b)$ where b is block size
- Efficient CPU/GPU implementations use batch size $\gg 1$ (process a number of inputs together)
- For latency-critical applications (e.g. object detection for self-driving car), we want a batch size of 1
- **Make sure comparisons are at the same batch size!**

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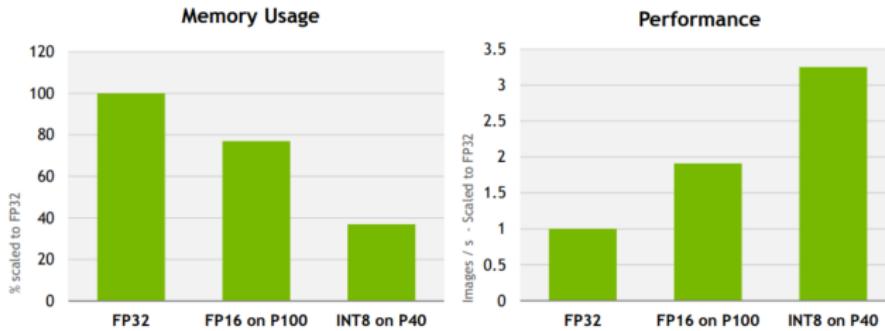
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2 Tutorial

Role of Wordlength on Performance

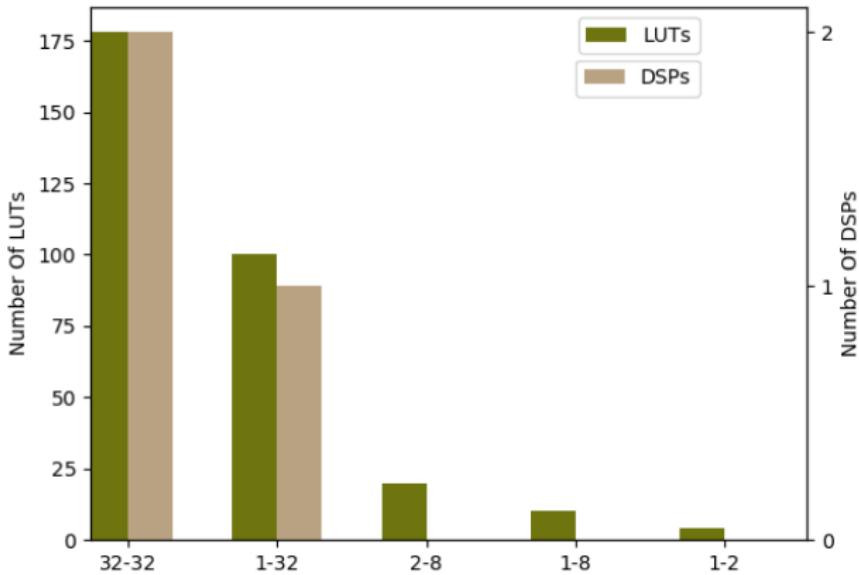
- CPU/GPU
 - Floating point performance comparable to fixed
 - Integer data types usually vectorisable hence faster
 - Nvidia offers FP64, FP32 and FP16 (> Tegra X1 and Pascal)
- FPGA
 - Datapath is flexible
 - No floating point unit so fixed point normally preferred



ResNet50 Model, Batch Size = 128, TensorRT 2.1 RC pre-release

Role of Wordlength on Resources

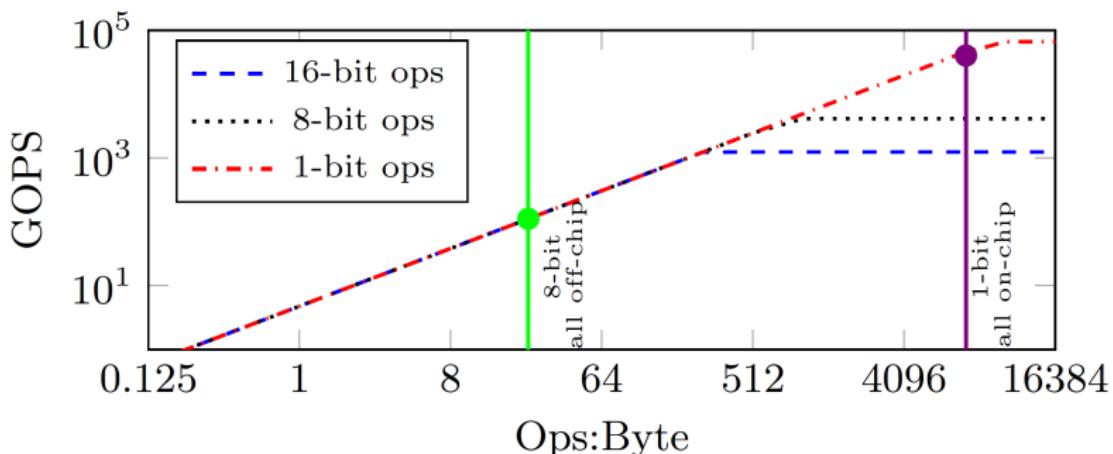
- X axis is bitwidth (weight-activation) and Y axis Number of LUTs/DSPs for MAC
- For k -bits, area is $\mathcal{O}(k^2)$



Roofline Model

Roofline model for Xilinx ZU19EG

- X axis is computational intensity (ops to perform / byte fetch), Y axis is performance
- Diagonal parts show memory-bandwidth limited space
- Horizontal parts show computation limited space
- Actually this is a better metric to optimise than say GOPs/s
- **Low precision extremely advantageous for performance**



Integer Quantization [Jac+18]

A way to map numbers $r \in \mathbb{R}$ to unsigned integers $q \in \mathbb{U}+$ is via an affine transformation

$$r = S(q - Z) \tag{2}$$

- $\mathbb{U}+$ is the set of unsigned W-bit integers
- S, Z are the quantisation parameters
 - $S \in \mathbb{R}+$ represents a scaling constant
 - $Z \in \mathbb{U}+$ represents a zero-point

Integer MM [Jac+18]

- $N \times N$ MM defined as

$$r_3^{(i,k)} = \sum_{j=1}^N r_1^{(i,j)} r_2^{(j,k)}, \quad (3)$$

substituting $r = S(q - Z)$ (2) and rewriting we get

$$q_3^{(i,k)} = Z_3 + M \left(NZ_1 Z_2 - Z_1 a_2^{(k)} - Z_2 \bar{a}_1^{(i)} + \sum_{j=1}^N q_1^{(i,j)} q_2^{(j,k)} \right) \quad (4)$$

- Multiplication with $M = \frac{S_1 S_2}{S_3}$ is implemented in (high-precision) two's complement fixed point
- $a_2^{(k)}$ and $\bar{a}_1^{(i)}$ together only take $2N^2$ additions
- Sum in (4) takes $2N^3$ and is a standard integer MAC
- CPU implementation uses uint8, accumulated as int32

Quantisation Range [Jac+18]

For each layer, quantisation parameterised by (a,b,n):

$$\text{clamp}(r; a, b) = \min(\max(x, a), b)$$

$$s(a, b, n) = \frac{b - a}{n - 1}$$

$$q(r; a, b, n) = \text{rnd}\left(\frac{\text{clamp}(r; a, b) - a}{s(a, b, n)}\right)s(a, b, n) + a \quad (5)$$

where $r \in \mathbb{R}$ is number to be quantised, $[a, b]$ is quantisation range, n is number of quantisation levels and $\text{rnd}()$ rounds to nearest integer

Figure from [Jac+18] (with permission)

Training Algorithm [Jac+18]

- 1 Create training graph of the floating-point model
- 2 Insert quantisation operations for integer computation in inference path using (5)
- 3 Train with quantised inference but floating-point backpropagation until convergence
- 4 Use weights thus obtained for low-precision inference

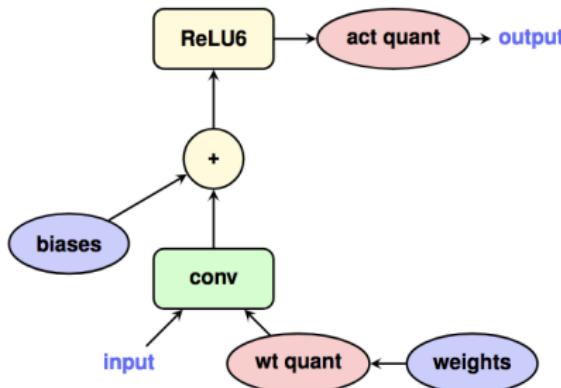


Figure from [Jac+18] (with permission)

Accuracy vs Precision [Jac+18]

ResNet50 on ImageNet, comparison with other approaches

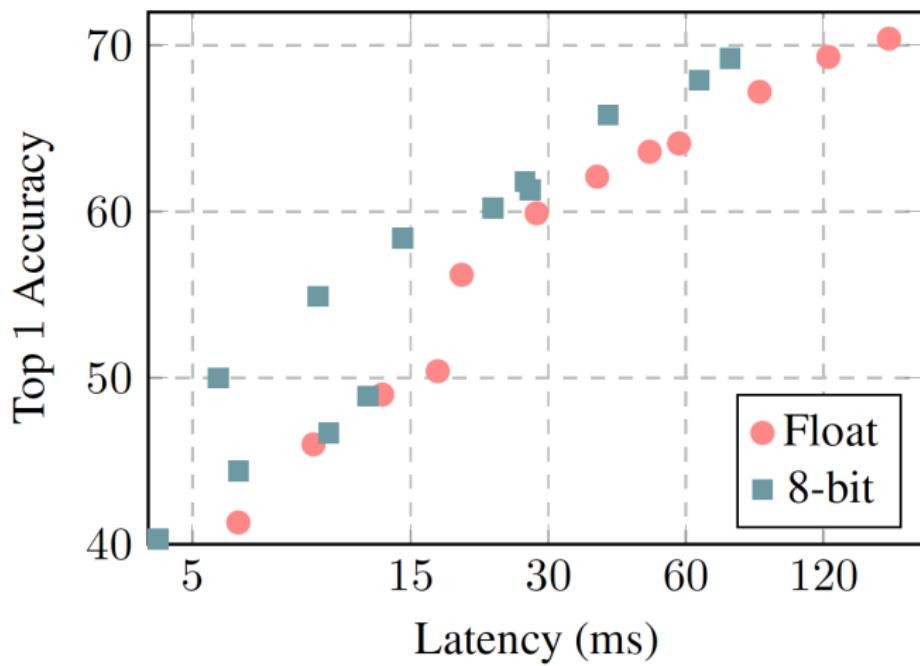
| Scheme | BWN | TWN | INQ | FGQ | Ours |
|-----------------|---------|---------|---------|-------|-------|
| Weight bits | 1 | 2 | 5 | 2 | 8 |
| Activation bits | float32 | float32 | float32 | 8 | 8 |
| Accuracy | 68.7% | 72.5% | 74.8% | 70.8% | 74.9% |

Table 4.2: ResNet on ImageNet: Accuracy under various quantization schemes, including binary weight networks (BWN [21, 15]), ternary weight networks (TWN [21, 22]), incremental network quantization (INQ [33]) and fine-grained quantization (FGQ [26])

Figure from [Jac+18] (with permission)

Accuracy vs Latency [Jac+18]

ImageNet classifier on Google Pixel 2 (Qualcomm Snapdragon 835 big cores)



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Symmetric Quantisation (SYQ) [Far+18]

- To compute quantised weights from FP weights

$$\mathbf{Q}_I = \text{sign}(\mathbf{W}_I) \odot \mathbf{M}_I \quad (6)$$

with,

$$M_{I,i,j} = \begin{cases} 1 & \text{if } |W_{I,i,j}| \geq \eta_I \\ 0 & \text{if } -\eta_I < W_{I,i,j} < \eta_I \end{cases} \quad (7)$$

$$\text{sign}(x) = \begin{cases} 1 & \text{if } x \geq 0 \\ -1 & \text{otherwise} \end{cases} \quad (8)$$

where \mathbf{M} represents a masking matrix, η is the quantization threshold hyperparameter (0 for binarised)

Symmetric Quantisation (SYQ) [Far+18]

- Make approximation $W_I \approx \alpha_I Q_I$, $Q_I \in \mathcal{C}$
- \mathcal{C} is the codebook, $\mathcal{C} \in \{C_1, C_2, \dots\}$ e.g. $\mathcal{C} = \{-1, +1\}$ for binary, $\mathcal{C} = \{-1, 0, +1\}$ for ternary
- A diagonal matrix α_I is defined by the vector $\alpha_I = [\alpha_I^1, \dots, \alpha_I^m]$:

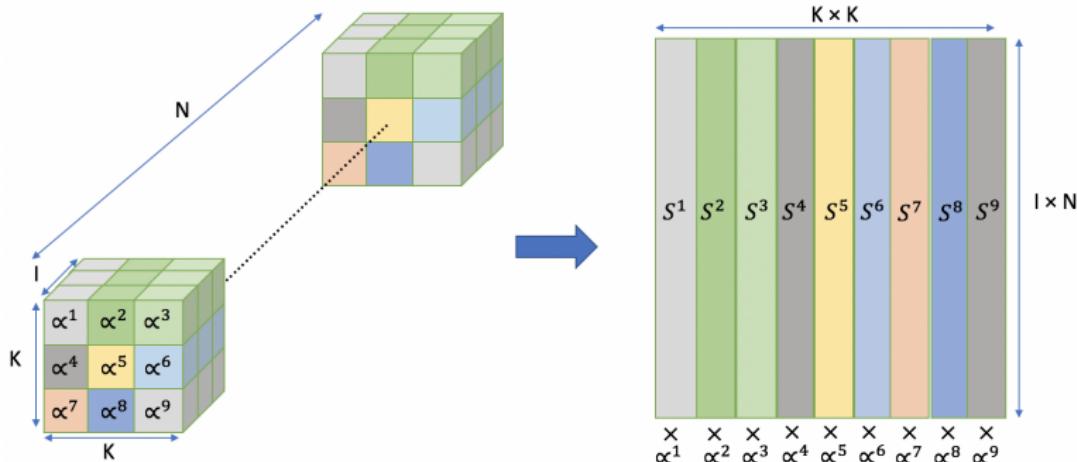
$$\alpha = \text{diag}(\alpha) := \begin{bmatrix} \alpha^1 & 0 & .. & 0 & 0 \\ 0 & \alpha^2 & .. & : & 0 \\ : & : & .. & \alpha^{m-1} & : \\ 0 & 0 & .. & 0 & \alpha^m \end{bmatrix}$$

- Train by solving

$$\alpha_I^* = \operatorname{argmin}_{\alpha} E(\alpha, \mathbf{Q}) \quad \text{s.t.} \quad \alpha \geq 0, \quad Q_{I,i,j} \in \mathcal{C}$$

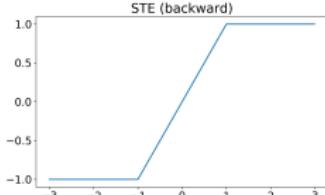
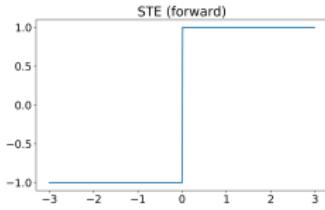
Subgroups

- Finer-grained quantisation improves weight approximation
- Pixel-wise shown, layer-wise has similar accuracy



Dealing with Non-differentiable Functions

- Recall (6) $\mathbf{Q}_I = \text{sign}(\mathbf{W}_I) \odot \mathbf{M}_I$
- This step function has a derivative which is zero everywhere: *vanishing gradients* problem
- Address via a straight through estimator (STE)
- Consider $q = \text{sign}(r)$ and $g_r \approx \frac{\partial C}{\partial q}$ then $\frac{\partial C}{\partial r} \approx g_q \mathbf{1}_{|r| \leq 1}$



Results for 8-bit activations

| Model | | Bin | Tern | FP32 | Reference |
|--------------|-------|-------------|-------------|-------------|------------------|
| AlexNet | Top-1 | 56.6 | 58.1 | 56.6 | 57.1 |
| | Top-5 | 79.4 | 80.8 | 80.2 | 80.2 |
| VGG | Top-1 | 66.2 | 68.7 | 69.4 | - |
| | Top-5 | 87.0 | 88.5 | 89.1 | - |
| ResNet-18 | Top-1 | 62.9 | 67.7 | 69.1 | 69.6 |
| | Top-5 | 84.6 | 87.8 | 89.0 | 89.2 |
| ResNet-34 | Top-1 | 67.0 | 70.8 | 71.3 | 73.3 |
| | Top-5 | 87.6 | 89.8 | 89.1 | 91.3 |
| ResNet-50 | Top-1 | 70.6 | 72.3 | 76.0 | 76.0 |
| | Top-5 | 89.6 | 90.9 | 93.0 | 93.0 |

- Our ResNet and AlexNet reference results are obtained from <https://github.com/facebook/fb.resnet.torch> and <https://github.com/BVLC/caffe>

Alexnet Comparison

| Model | Weights | Act. | Top-1 | Top-5 |
|---------------------|----------------|-------------|--------------|--------------|
| DoReFa-Net [Zho+16] | 1 | 2 | 49.8 | - |
| QNN [Hub+16] | 1 | 2 | 51.0 | 73.7 |
| HWGQ [Cai+17] | 1 | 2 | 52.7 | 76.3 |
| SYQ | 1 | 2 | 55.2 | 78.4 |
| DoReFa-Net [Zho+16] | 1 | 4 | 53.0 | - |
| SYQ | 1 | 4 | 56.2 | 79.4 |
| BWN [Ras+16] | 1 | 32 | 56.8 | 79.4 |
| SYQ | 1 | 8 | 56.6 | 79.4 |
| SYQ | 2 | 2 | 55.7 | 79.1 |
| FGQ [Mel+17] | 2 | 8 | 49.04 | - |
| TTQ [Zhu+16] | 2 | 32 | 57.5 | 79.7 |
| SYQ | 2 | 8 | 58.1 | 80.8 |

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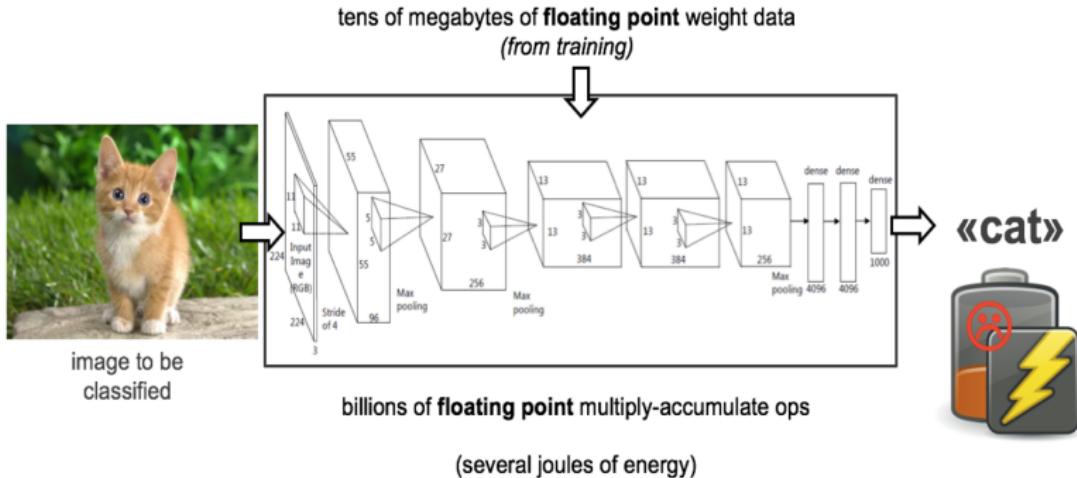
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Inference with Convolutional Neural Networks

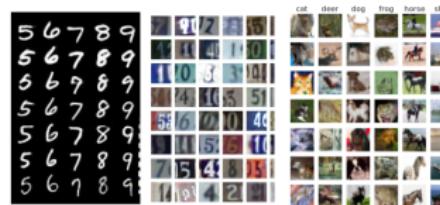
Slides from Yaman Umuroglu et. al., "FINN: A framework for fast, scalable binarized neural network inference," FPGA'17



Binarized Neural Networks

- › The extreme case of quantization
 - Permit only two values: +1 and -1
 - Binary weights, binary activations
 - Trained from scratch, not truncated FP

- › Courbariaux and Hubara et al. (NIPS 2016)
 - Competitive results on three smaller benchmarks
 - Open source training flow
 - Standard “deep learning” layers
 - Convolutions, max pooling, batch norm, fully connected...



| | MNIST | SVHN | CIFAR-10 |
|------------------------------|-------|--------|----------|
| Binary weights & activations | 0.96% | 2.53% | 10.15% |
| FP weights & activations | 0.94% | 1.69% | 7.62% |
| BNN accuracy loss | -0.2% | -0.84% | -2.53% |

% classification error (lower is better)

Advantages of BNNs

Vivado HLS estimates on Xilinx UltraScale+ MPSoC ZU19EG

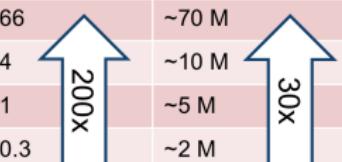
› Much smaller datapaths

- Multiply becomes XNOR, addition becomes popcount
- No DSPs needed, everything in LUTs
- Lower cost per op = more ops every cycle

› Much smaller weights

- Large networks can fit entirely into on-chip memory (OCM)
- More bandwidth, less energy compared to off-chip

| Precision | Peak TOPS | On-chip weights |
|-----------|-----------|-----------------|
| 1b | ~66 | ~70 M |
| 8b | ~4 | ~10 M |
| 16b | ~1 | ~5 M |
| 32b | ~0.3 | ~2 M |



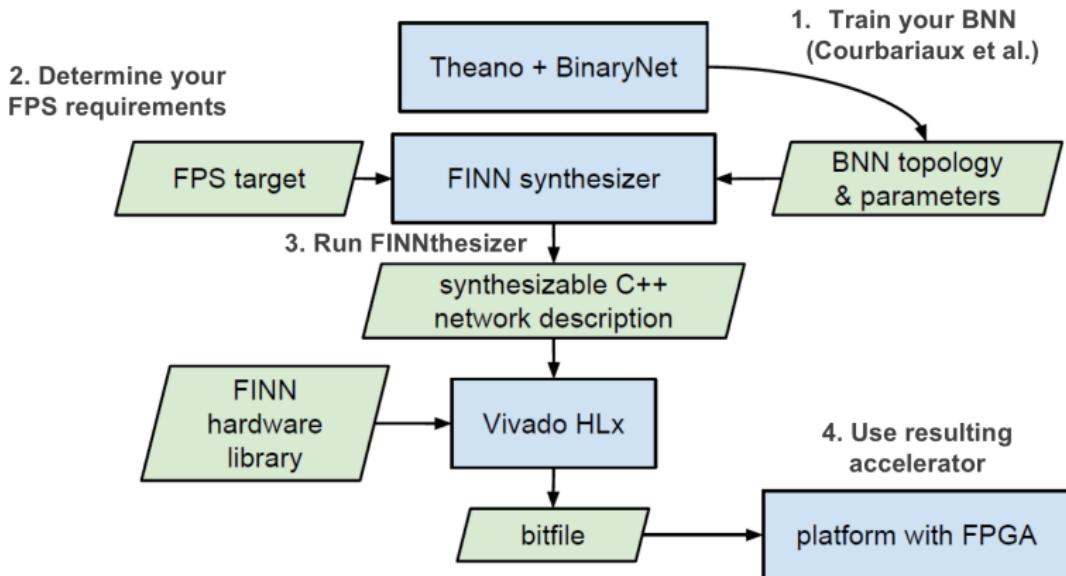
The table shows performance metrics for different precision levels. As precision decreases, peak TOPS increase significantly (200x for 16b vs 1b) while on-chip weight requirements decrease (30x for 16b vs 32b).

› fast inference with large BNNs

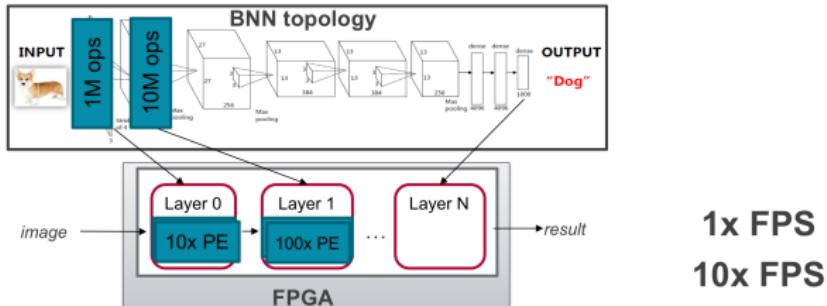
Design Flow

- One size does not fit all - Generate tailored hardware for network and use-case
- Stay on-chip - Higher energy efficiency and bandwidth
- Support portability and rapid exploration - Vivado HLS (High-Level Synthesis)
- Simplify with BNN-specific optimizations - Exploit compile time optimizations to simplify hardware, e.g. batchnorm and activation => thresholding

Design Flow



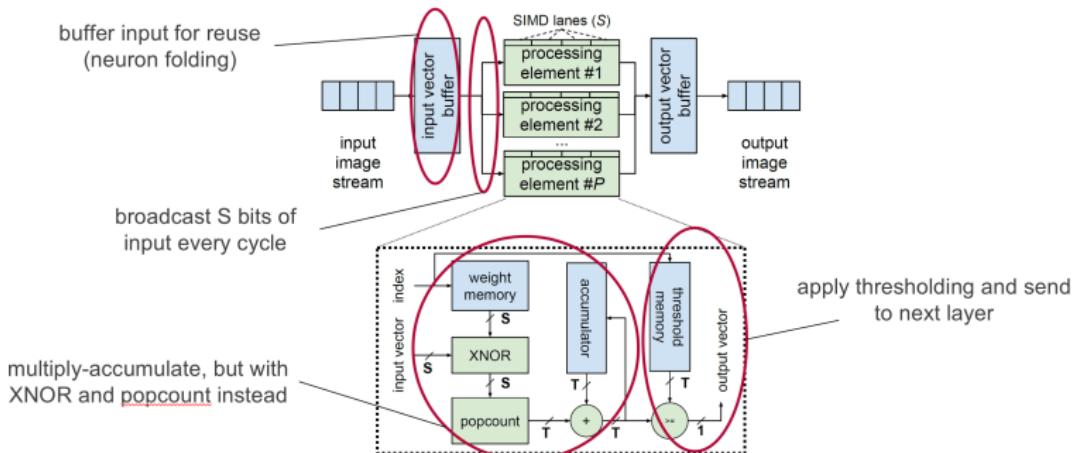
Heterogeneous Streaming Architecture



- One hardware layer per BNN layer, parameters built into bitstream
 - Both inter- and intra-layer parallelism
- Heterogeneous: Avoid “one-size-fits-all” penalties
 - Allocate compute resources according to FPS and network requirements
- Streaming: Maximize throughput, minimize latency
 - Overlapping computation and communication, batch size = 1

Matrix-Vector Threshold Unit (MVTU)

- Core computational element of FINN, tiled matrix-vector multiply
- Computes a (P) row $\times (S)$ column chunk of matrix every cycle, per-layer configurable tile size

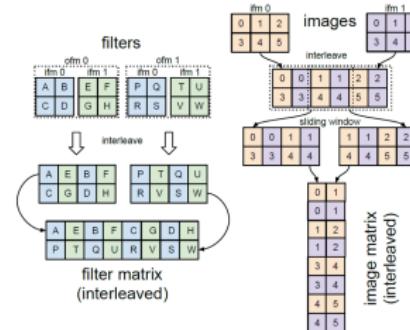
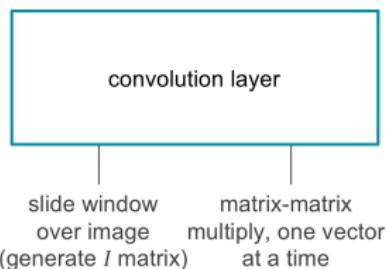


Convolutional Layers

► Lower convolutions to matrix-matrix multiplication, $W \cdot I$

- W : filter matrix (generated offline)
- I : image matrix (generated on-the-fly)

► Two components:



Performance

FINN

Prior Work

| | Accuracy | FPS | Power (chip) | Power (wall) | kFPS / Watt (chip) | kFPS / Watt (wall) | Precision |
|-----------------------|----------|---------|--------------|--------------|--------------------|--------------------|-----------|
| MNIST, SFC-max | 95.8% | 12.3 M | 7.3 W | 21.2 W | 1693 | 583 | 1 |
| MNIST, LFC-max | 98.4% | 1.5 M | 8.8 W | 22.6 W | 177 | 269 | 1 |
| CIFAR-10, CNV-max | 80.1% | 21.9 k | 3.6 W | 11.7 W | 6 | 2 | 1 |
| SVHN, CNV-max | 94.9% | 21.9 k | 3.6 W | 11.7 W | 6 | 2 | 1 |
| | | | | | | | |
| MNIST, Alemdar et al. | 97.8% | 255.1 k | 0.3 W | - | 806 | - | 2 |
| CIFAR-10, TrueNorth | 83.4% | 1.2 k | 0.2 W | - | 6 | - | 1 |
| SVHN, TrueNorth | 96.7% | 2.5 k | 0.3 W | - | 10 | - | 1 |

Max accuracy loss: ~3%

10 – 100x better performance

CIFAR-10/SVHN energy efficiency comparable to TrueNorth ASIC

Summary

- Reducing precision
 - Significantly reduce computational costs in DNNs
 - Data may now fit entirely on chip, avoiding external memory accesses
 - Computations greatly simplified
 - Key dimension for optimisation in CPU/GPU/FPGA implementations
- Convolutional layer can be computed as a MM
- Still an active research topic

Tutorial Question 1

- 1 Download VM (quantisation_usyd.ova) from
<https://bluemountain.eee.hku.hk/papaa2018/>

- 2 Import to Virtualbox, and inside VM do

```
git clone https://gitlab.com/phwl/syq-cifar10.git
```

- 3 Derive Equation (4) from (3) and (2)

Tutorial Question 2

- 1 Cifar10 is a *very small* neural network benchmark¹. Test precision with SYQ using:

```
cd syq-cifar10/src  
python cifar10_eval.py
```

(this can run during training)

- 2 The code provided performs binary quantisation. Modify the code to determine precision for binary, ternary and floating-point (use the checkpoint files provided to initialise your training).

```
python cifar10_train.py
```

¹

https://www.tensorflow.org/tutorials/images/deep_cnn

References I

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