

Posterior mean model distance

DP

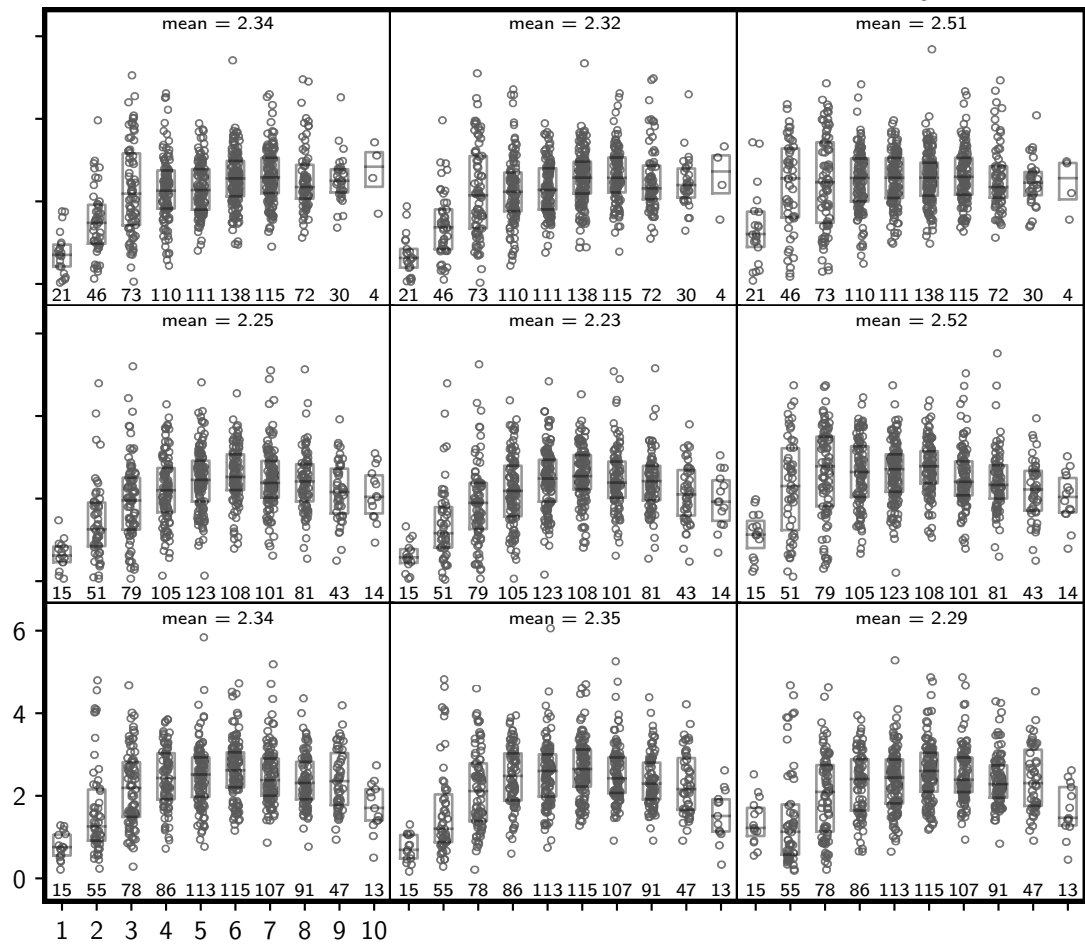
PYP

WU

DP

PYP

WU



True number of events