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## Education

#### Texas A&M University, College Station

Aug. 2023 – May. 2025 (Expected)

Master of Science in Computer Science, GPA: 4.0/4.0

#### The Hong Kong University of Science and Technology

Sep. 2019 – Jun. 2023

B. Sc. in Data Science and Technology & Computer Science (Double-Major)

- Graduated with First Class Honors, GPA: 3.65/4.30
- 2022/23 CSE Best Final Year Project: Professor Samuel Chanson Best FYP Award

## Skills

- Programming Languages: Python, C++, CUDA, Java, Scala
- Tech Skills: PyTorch, Mitsuba Renderer, OptiX, OpenGL, TensorFlow

## Internship Experience

**Aurora** C++

Jun. 2024 – Aug. 2024

Software Engineer Intern, Synthetic World and Sensor Simulation Team

Mountain View, CA, USA

An accelerated light sampling algorithm to enhance sensor simulation efficiency

- Accelerated the rendering process for sensor simulation, crucial for efficiently generating edge cases to improve the robustness of autonomous driving systems.
- Implemented <u>Stochastic Lightcuts</u>, <u>organized in spatial cells</u> within a Bounding Volume Hierarchy, reducing rendering time by 55% in many-light scenarios, especially beneficial in night scene simulations.

### Capmi Technology JavaScript, TypeScript

Jun. 2022 – Aug. 2022

Software Developer Intern

Sha Tin, HKSAR

Two core features to enhance expressiveness of an Inertial Motion Capture product.

- Improved an Inertial Measurement Unit Sensor-to-Body Calibration Method for arbitrary orientation.
- Developed a Foot Rooted Kinematic Model algorithm for model translation on level ground and a *Kalman* Filter for reconstructing complex dynamic human motions including jumping, running, *etc*.

# Research Experience

Neural Path Guiding C++, Python, CUDA, Pytorch, OptiX, Mitsuba

Sep. 2023 – Ongoing

Aggie Graphics Group, advised by Professor Nima Kalantari

College Station, TX, USA

A neural formulation to encode target distributions for path guiding algorithms.

- Ported the <u>Neural Parametric Mixtures for Path Guiding</u> from the original C++ implementation (using OptiX and tiny-cuda-nn) to Python, utilizing Mitsuba3, tiny-cuda-nn, and Pytorch.
- Implemented RealNVP in CUDA C++, a core component of Neural Importance Sampling.

## **Projects**

# Real-time Vacancy Detection System (FYP) O Python, PyTorch

Sep. 2022 – May 2023

- Detecting occupancy status of 12+ parking spaces using one fisheye-camera in real-time.
- Accuracy more than 90% with pedestrian related noise filtering algorithm.

Graphics Projects O C++, OpenGL, WebGL2

Sep. 2022 – Dec. 2022

- Geometry: Implemented Laplacian smoothing methods and Laplacian mesh editing technique.
- **Rendering:** Implemented rendering of volumetric cloud using fractal noise and Ray Marching.

Game Project – Pixel Fantasy O C++, OpenGL

Feb. 2022 – May 2022

• An OpenGL-based game featuring a 3D ARPG with 2D Sprites without dependence on game engine.