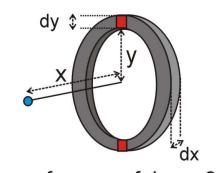


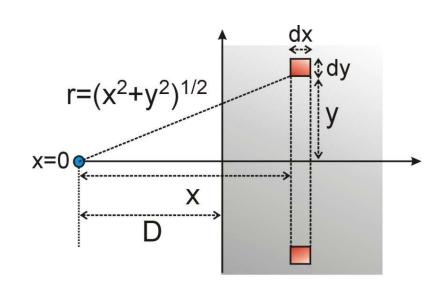
# Dispersion interactions - macroscopic bodies

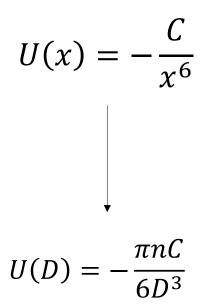
Force & function at the nanoscale

# **Detailed picture**



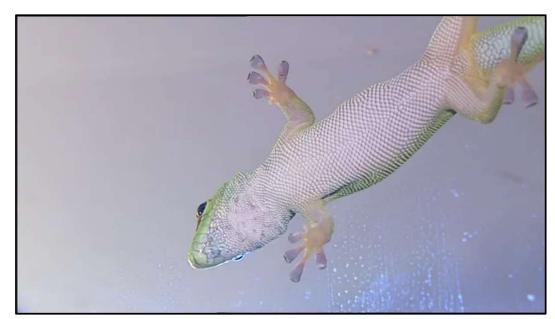
Circumference of ring =  $2\pi y$ Area of ring =  $2\pi y dy$ Volume of ring =  $2\pi y dy dx$ 







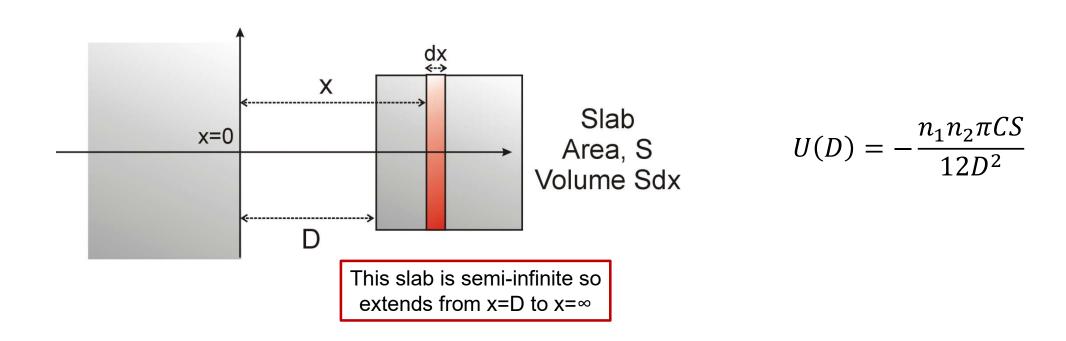
# Introduction





#### 5.1 The slab & surface

Derive an expression for the dispersion forces which act between a perfectly flat slab of area S and a semi-infinite solid if the number density of atoms in the solid and slab are n<sub>1</sub> and n<sub>2</sub> respectively.



#### **The Hamaker Constant**

We considered the interactions between 2 slabs. Later in the lecture we'll look at a sphere and a slab. Similar expressions exist for other geometries:

$$U(D) = -\frac{n_1 n_2 \pi CS}{12D^2} \qquad U(D) = -\frac{n_1 n_2 \pi^2 CR}{3D}$$

The Hamaker constant provides us with an easy way to quantify the strength of interaction between two materials which is geometry independent.

$$A_{12} = n_1 n_2 \pi^2 C$$
 Measured in J

### **Dispersion interactions and Hamaker constants**

We can rewrite our expressions for the dispersion interaction energy between two macroscopic bodies in terms of the Hamaker constant

Dispersion Interaction energy between a flat slab of area, S, and a semi-infinite solid

$$U(D) = -\frac{n_1 n_2 \pi CS}{12D^2} = -\frac{A_{12}S}{12\pi D^2}$$

Dispersion Interaction energy a semi-infinite solid

Dispersion Interaction energy between a sphere of radius, 
$$R$$
, and  $U(D) = -\frac{n_1 n_2 \pi^2 CR}{3D} = -\frac{A_{12}R}{3D}$ 

## **Dispersion Forces and Hamaker constants**

We can also write the forces in terms of the Hamaker constant

Dispersion force between a flat slab of area, S, and a semi-infinite solid

$$F(D) = -\frac{dU}{dD} = -\frac{A_{12}S}{6\pi D^3}$$

Dispersion force between a sphere of radius, *R*, and a semi-infinite solid

$$F(D) = -\frac{dU}{dD} = -\frac{A_{12}R}{3D^2}$$

So for a given geometry we can determine the strength of the dispersion interaction  $A_{12}$  between two materials by measuring forces

# **How big are Hamaker constant values?**

Values of A typically lie in the range  $10^{-21}$  to  $10^{-19}$  J (while  $kT_{300K} = 4.14 \times 10^{-21}$ J)

Medium	Dielectric Constant	Hamaker Constant (*10 <sup>-20</sup> J)
Liquid He	1.057	0.057
Alkanes	2	3
Benzene	2.28	5
Diamond	5.66	28.9
Silicon	11.6	18
Ethanol	26	4.2
Water	80	3.7

#### 5.2 Force between two surfaces

We've shown that the force between a perfectly flat slab and a semiinfinite solid surface is

$$F(D) = -\frac{A_{12}S}{6\pi D^3}$$

#### Question:

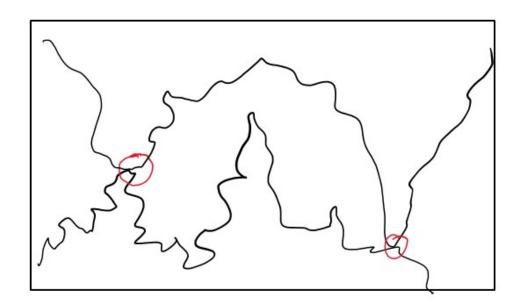
Imagine you place your hand flat on the wall. What is the force you would need to remove it?

Assuming your hand has an area of  $S=0.02m^2$  and  $A_{12}=10^{-21}$  J. What is the force between the slab and the surface at a separation of 0.3nm?

Does this seem reasonable? What's gone wrong?!

# **Surface Roughness**

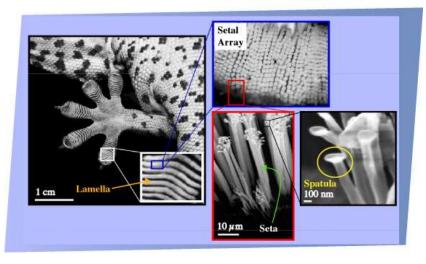
In reality all surfaces are, on the nanoscale, really rough, so that the area of "contact" between the surfaces is really small.





# Geckos and "Biomimicry"



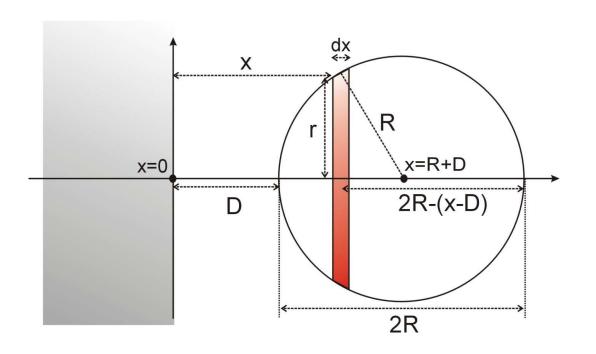






## 5.3 – The sphere and surface

Derive an expression for the dispersion forces which act between a sphere of radius R and a semi-infinite solid, for separations D>>R, if the number density of atoms in the solid and sphere are  $n_1$  and  $n_2$  respectively.

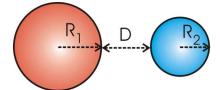


$$U(D) = -\frac{n_1 n_2 \pi^2 CR}{3D}$$

## Some other important geometries

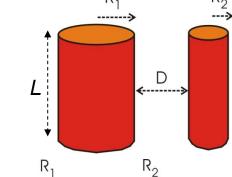
The geometry of the macroscopic bodies is important in determining the separation dependence of the dispersion interaction





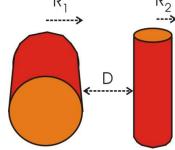
$$U(D) = -\frac{A_{12}}{3D} \frac{R_1 R_2}{R_1 + R_2}$$

**Parallel cylinders** 



$$U(D) = -\frac{A_{12}L}{12\sqrt{2}D^{3/2}} \left(\frac{R_1R_2}{R_1 + R_2}\right)^{1/2}$$

Perpendicular cylinders



$$U(D) = -\frac{A_{12}}{6D} \sqrt{R_1 R_2}$$

## How close do you have to get to feel dispersion interactions?

We can calculate the range of the interaction by comparing dispersion and thermal energies i.e.  $|U(D_{range})| \sim kT$ 

For a sphere of radius R and a solid surface we have

$$|U(D)| = \frac{A_{12}R}{3D_{range}} \approx kT$$
 Hence  $D_{range} \approx \frac{A_{12}R}{3kT}$ 

For values of T=300K, R=10 nm and  $A_{12}$ =10<sup>-19</sup>J

$$D_{range} \sim 10R = 100 \text{ nm}$$

$$D_{range}(atoms) \sim 0.3 nm$$

Ok for a Gecko but not your hand

## Summary of key results

Adding up dispersion interactions from individual atoms allows us to understand how macroscopic bodies interact.

The Hamaker constant provides a geometry independent way of characterising the strength of interaction between different materials

$$U(D) = -\frac{n_1 n_2 \pi CS}{12D^2}$$

Dispersion interactions between macroscopic bodies are much longer range and hence important. They are sufficiently strong to support the weight of a Gecko or ladybird....

... but maybe not if the surface spins too fast!

