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<https://github.com/physicell-training/ws2021>

Session 9: Contact and Pressure in PhysiCell



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Goals

- Mechanical Pressure
- Example: pressure-based proliferation (function only)
- Testing for cell contact
- Cell ingestion
- Example: Predator rule (function only)



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Mechanical Pressure (Compression)

- **Mechanical pressure** is the total force on a cell's surface, divided by its surface area.
- For the i^{th} cell with surface area S_i , we can create a "pressure" p_i based on the interaction potentials ψ of neighboring cells (with indices in N_i):

$$p_i = \frac{1}{S_i} \sum_{j \in N_i} -\nabla \psi(x_i, x_j)$$

- In PhysiCell, we calculate this as ***nondimensionaled*** `cell.state.simple_pressure`
 - Normalized for confluence in 3D:
 - ♦ pressure = 1 in 3-D confluence (12 neighbors of similar size)
 - ♦ pressure = 0.5 in 2-D confluence (6 neighbors of similar size)
 - ♦ eliminates the need for calculating surface area since we don't model cell morphology

Note: A ***confluent tissue*** is one with no gaps.
The cells' volumes are "squeezed" into the areas that render as white triangles.

Example: Pressure-dependent phenotype

```
void pressure_phenotype( Cell* pCell, Phenotype& phenotype , double dt )
{
    // get my cell definition
    static Cell_Definition* pCD = find_cell_definition( pCell->type );

    // exit early if dead
    if( phenotype.death.dead == true )
    {
        pCell->functions.update_phenotype = NULL;
        return;
    }

    // compare my pressure to the threshold
    // allow cycling if pressure is below threshold.
    if( pCell->state.simple_pressure < pCell->custom_data["pressure_threshold"] )
    {
        phenotype.cycle.data.transition_rate(0,1) = pCD->phenotype.cycle.data.transition_rate(0,1);
        pCell->custom_data["arrested"] = 0;
    }
    else
    {
        phenotype.cycle.data.transition_rate(0,1) = 0;
        pCell->custom_data["arrested"] = 1;
    }
    return;
}
```

Sample result

```
// Set number of cells to 500.  
// Set simulation domain to [-250,250]^2  
// output SVG every 15 minutes
```

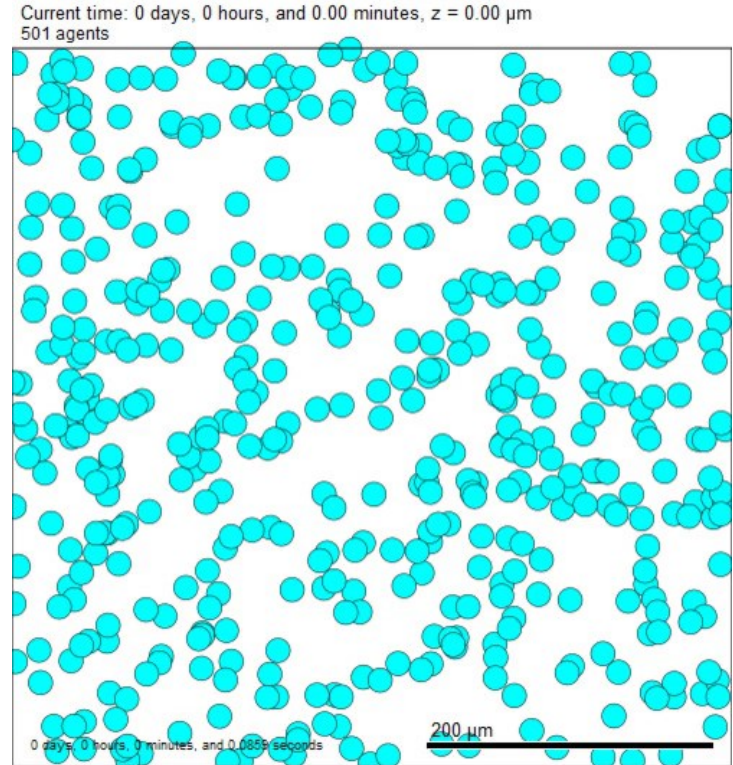
```
make  
./project  
make jpeg  
make movie
```

Other details:

Flow cytometry model (separated):

$$\begin{array}{ll} \frac{1}{r_{01}} = 30 \text{ min} & \frac{1}{r_{12}} = 90 \text{ min} \\ \frac{1}{r_{23}} = 120 \text{ min} & \frac{1}{r_{30}} = 30 \text{ min} \end{array}$$

- Pressure-arrested cell
- Non-arrested, not cycling
- Non-arrested, actively cycling
- Apoptotic



Example: Mechanofeedback & chemical communication

- Suppose:
 - Cycling cells secrete a diffusible signal s
 - Cell's down-regulate cycle entry if $p > 0.5$ or if $s > s_{\text{stop}}$
- Here's the expected behavior:
 - Apoptosis events reduce pressure on 6 neighbors (in 2D)
 - All 6 neighbors could proliferate to fill the gap opened by the 1 dead cell
 - Stochastically, once cell "chooses" to divide first
 - This cell secretes s to prevent the other 5 from dividing.

Pressure + Signal phenotype

```
// etc etc etc etc

static int nSignal = microenvironment.find_density_index( "signal" );

// if cycling, secrete signal
if( phenotype.cycle.data.current_phase_index > 0 )
{ phenotype.secretion.secretion_rates[nSignal] = 1; }
else
{ phenotype.secretion.secretion_rates[nSignal] = 0; }

// compare my signal to the threshold (store result in signal_arrested)
if( pCell->nearest_density_vector()[nSignal] < pCell->custom_data["signal_threshold"] )
{ pCell->custom_data["signal_arrested"] = 0; }
else
{ pCell->custom_data["signal_arrested"] = 1; }

// compare my pressure to the threshold (store result in pressure_arrested)
if( pCell->state.simple_pressure < pCell->custom_data["pressure_threshold"] )
{ pCell->custom_data["pressure_arrested"] = 0; }
else
{ pCell->custom_data["pressure_arrested"] = 1; }

// if either condition holds, arrest cycle entry
if( pCell->custom_data["pressure_arrested"] > 0.5 && pCell->custom_data["signal_stop"] > 0.5 )
{ phenotype.cycle.data.transition_rate(0,1) = 0; }
else
{ phenotype.cycle.data.transition_rate(0,1) = pCD->phenotype.cycle.data.transition_rate(0,1); }

return;
}
```

Sample result

```
// Set number of cells to 1400.  
// Set simulation domain to [-250,250]^2  
// set SVG output interval to 3 minutes  
// set max time to 3000 minutes
```

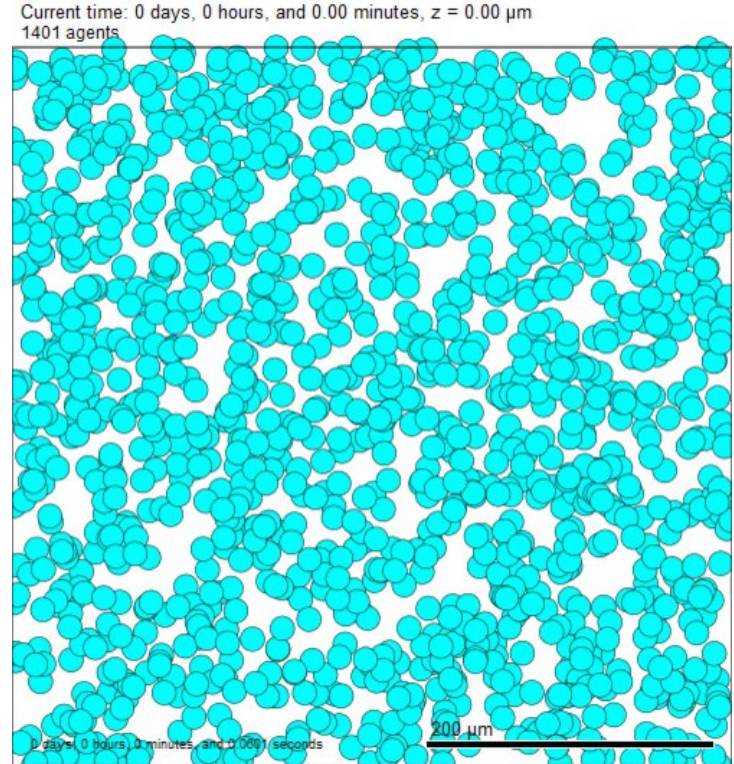
```
make  
./project  
make jpeg  
make movie
```

Other details:

Flow cytometry model (separated):

$$\begin{array}{ll} \frac{1}{r_{01}} = 30 \text{ min} & \frac{1}{r_{12}} = 90 \text{ min} \\ \frac{1}{r_{23}} = 120 \text{ min} & \frac{1}{r_{30}} = 30 \text{ min} \end{array}$$

- Signal-arrested cell
- Signal & Pressure-arrested cell
- Pressure-arrested cell
- Non-arrested, not cycling
- Non-arrested, actively cycling
- Apoptotic



Testing for Contact

- As of PhysiCell 1.8.0, each cell actively tracks a vector of Cell pointers **pCell->state.neighbors**:
 - Interaction potential records all cells with non-zero adhesion/repulsion
 - Updated every mechanics time step
 - **Note:** Requires that you use the default cell velocity function

Testing for contact (backup methods)

- In addition, the Cell class has three ways to test for nearby cells
 - `std::vector<Cell*> Cell::cells_in_my_container(void);`
 - ♦ This returns a vector of the memory addresses of cells in the same mechanics voxel.
 - ♦ It's very fast and very cheap, but it may miss some nearby cells.
 - ♦ **Note:** This also includes your cell in the list! Make sure to test against `pCell` when using!
 - `std::vector<Cell*> Cell::nearby_cells(void);`
 - ♦ This returns a vector of the memory addresses of all cells nearby.
 - ♦ It returns all the cells in neighboring mechanics voxels.
 - ♦ It's more robust and complete, but it has a higher computational cost.
 - ♦ **Note:** This also includes your cell in the list! Make sure to test against `pCell` when using!
 - `std::vector<Cell*> Cell::nearby_interacting_cells(void);`
 - ♦ This returns a vector of the memory addresses of all cells nearby **except** the cell.
 - ♦ It returns all the cells in the neighboring voxels within interaction distance. (same as default potential functions)
 - ♦ It's more robust and complete, but it has a higher computational cost. But it returns fewer cells!

Testing for contact (backup methods 2)

- You can also test for nearby cells for any cell *pCell*
 - `std::vector<Cell*> Cell::nearby_cells(Cell* pCell);`
 - ♦ This returns a vector of the memory addresses of all cells nearby.
 - ♦ It returns all the cells in neighboring mechanics voxels.
 - ♦ It's more robust and complete, but it has a higher computational cost.
 - ♦ **Note:** This also includes your cell in the list! Make sure to test against `pCell` when using!
 - `std::vector<Cell*> Cell::nearby_interacting_cells(Cell* pCell);`
 - ♦ This returns a vector of the memory addresses of all cells nearby **except** `pCell`.
 - ♦ It returns all the cells in the neighboring voxels within interaction distance.
(same as default potential functions)
 - ♦ It's more robust and complete, but it has a higher computational cost. It returns fewer cells!
 - ♦ If you are using the default mechanics model, it returns the same list as `pCell->state.neighbors`.

Ingestion

- A cell (predator) can "eat" another cell (prey)
 - The prey cell solid volume is added to the cytoplasmic solid
 - The prey cell fluid volume is added to the fluid volume
 - The prey cell's volumes are set to zero
 - The prey cell is inactivated (all functions NULL), secretion/uptake set to zero, and any attachments set to zero.
 - The predator's volume will actively shrink back towards its target volume
- This is useful for predation, such as by macrophages.
- `void Cell::ingest_cell(Cell* pCell_to_eat)`

Example: Predator rule

```
// Use this in the "custom" rule to evaluate on the mechanics time scale.
// Test for contact with prey cells and eat them.

void custom_predator_function( Cell* pCell, Phenotype& phenotype , double dt )
{
    static Cell_Definition* pPrey = find_cell_definition( "prey" );

    Cell* pC;
    for( int n = 0; n < pCell->state.neighbors.size() ; n++ )
    {
        pC = pCell->state.neighbors[n];
        if( pC->type == pPrey->type )
        { pCell->ingest_cell( pC ); }
    }

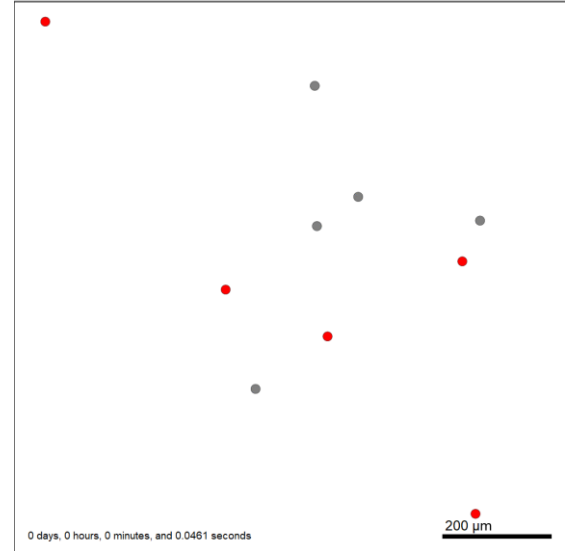
    return;
}
```

Sample result

```
## set the max run time to 3600 minutes  
## set SVG output to every 20 minutes
```

```
make  
./project  
make gif
```

Current time: 0 days, 0 hours, and 0.00 minutes, $z = 0.00 \mu\text{m}$
11 agents



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