https://github.com/physicell-training/ws2023

# Setting up PhysiCell on Linux



Elmar Bucher

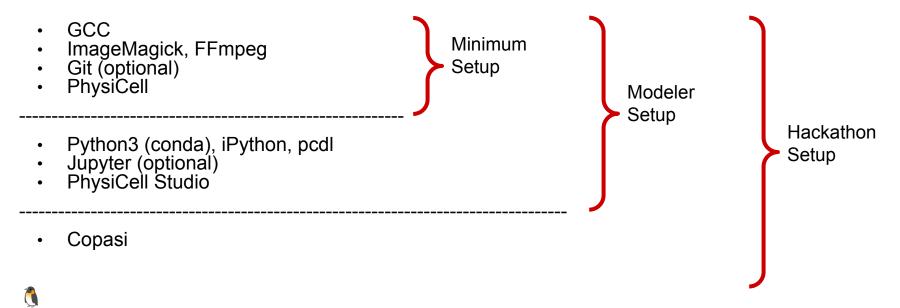


## PhysiCell Project

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## GCC (Minimum Setup)

Check if GCC (the gnu compiler collection) is already installed.
 q++ --version

• If not:
 sudo apt install build-essential

 OpenMP (open multi processing) is a feature, used by PhysiCell, that is implemented in GCC.

## ImageMagick (Minimum Setup)

ImageMagick is used for making jpeg and gif images from PhysiCell svg image output.

- Check if ImageMagick is already installed.
   magick --version
  - If ok: you have >= version 7 installed. You are all set! You can move to the next page.
  - If you receive: Command 'magick' not found, try:
     convert --version
     if ok: you have most probably a version 6 installed (like the most of us)!
- If both of these commands not worked: sudo apt install imagemagick

The PhysiCell Makefile is written for ImageMagick >= version 7, which requires a magick command in front of each ImageMagick command (e.g. magick convert instead of convert).

Iff you have <= version 6 installed, you can follow the instruction below to generate a magick command that simply passes everything to the next command. This will make the PhysiCell Makefiles work for you too.

```
cd to the folder where you have your manual installed binaries. e.g. ~/.local/bin/
echo '$*' > magick
chmod 775
which magick
```

## FFmpeg (Minimum Setup)

FFmpeg is used for making mp4 movies out of jpeg images.

- Check if FFmpeg is already installed. ffmpeg -version
- If not: sudo apt install ffmpeg

## Git (optional, Minimum Setup)

git is an alternative way to install the PhysiCell and the Studio source code. The common way is to use wget.

- Check if git is already installed qit --version
- If not: sudo apt install git

#### wget & unzip

Check if you have wget and unzip installed.

```
• wget --version
if not:
  sudo apt install wget
```

unzip if not: sudo apt install unzip

## PhysiCell (Minimum Setup)

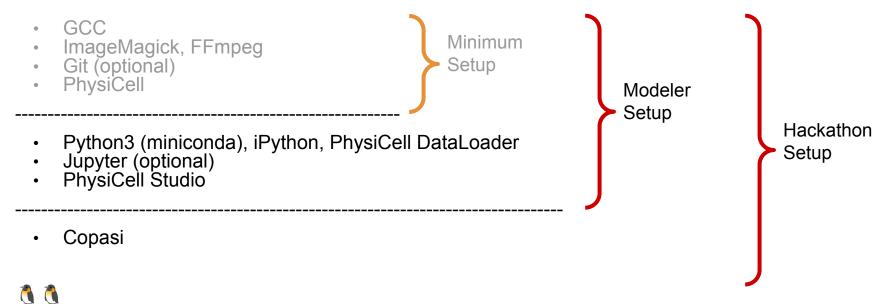
Download PhysiCell and place it where you want to work with this source code.

```
• Git: git clone <u>git@github.com</u>:MathCancer/PhysiCell.git
```

Wget:
 wget
 https://github.com/MathCancer/PhysiCell/releases/download/1.13.1/PhysiCell\_V.1.13.1.zip
 unzip PhysiCell V.n.n.n.zip

Test the installation with the biorobots sample project.

```
cd PhysiCell
make biorobots-sample
make
./biorobots
make jpeg
make movie
```





## Python3 part I (Modeler Setup)

It is up to you to use the python3 that ships with the distribution. The mamba python3 distribution comes in handy, when you want to run somewhere python3 where you have no root rights. <a href="https://mamba.readthedocs.io/en/latest/user\_guide/mamba.html">https://mamba.readthedocs.io/en/latest/user\_guide/mamba.html</a>

- cd to the folder where you have your manual installed programs.
   e.g. ~/.local/lib/
- Adjust the download according to your CPU architecture (here x86\_64)! https://github.com/conda-forge/miniforge
- wget <a href="https://qithub.com/conda-forqe/miniforqe/releases/latest/download/Miniforqe3-Linux-x86\_64.sh">https://qithub.com/conda-forqe/miniforqe/releases/latest/download/Miniforqe3-Linux-x86\_64.sh</a>
   chmod 775 Miniforge3-Linux-x86\_64.sh
   ./Miniforge3-Linux-x86\_64.sh
- Adjust the installation location to where your manual installed programs are.
   e.g. home/<user>/.local/lib/miniforge3
- You wish the installer to initialize mamba!
  yes
  source ~/.bashrc (or log out and in again).
- You can now generate virtual python environment with the command below.
   Beware: You have at least to list one package (e.g. ipython) to successfully generate an environment!
   mamba create -n nameofmyenv ipython

## Python3 part II (Modeler Setup)

- The environment should now be activated.
   Check if the python and pip paths point to the installed location:
   which python
   which pip
- Install the iPython shell: pip install ipython
- Install the PhysiCell DataLoader: pip install pcdl
- Optional: install Jupyter: pip install jupyterlab

## PhysiCell Studio (Modeler Setup)

Download the studio and place it where you want to work with this source code.

• Git: git clone git@qithub.com:PhysiCell-Tools/PhysiCell-Studio.git

Wget:

wget <a href="https://qithub.com/PhysiCell-Tools/PhysiCell-Studio/archive/refs/taqs/v2.37.9.zip">https://qithub.com/PhysiCell-Tools/PhysiCell-Studio/archive/refs/taqs/v2.37.9.zip</a> unzip vn.n.n.zip

#### Put the studio under the PATH:

```
cd to the folder where you have your manual installed binaries. e.g. ~/.local/bin/
echo 'python /absolute/path/to/PhysiCell-Studio/bin/studio.py $*' > studio
chmod 775
which studio
```

#### Install the Qt library dependencies:

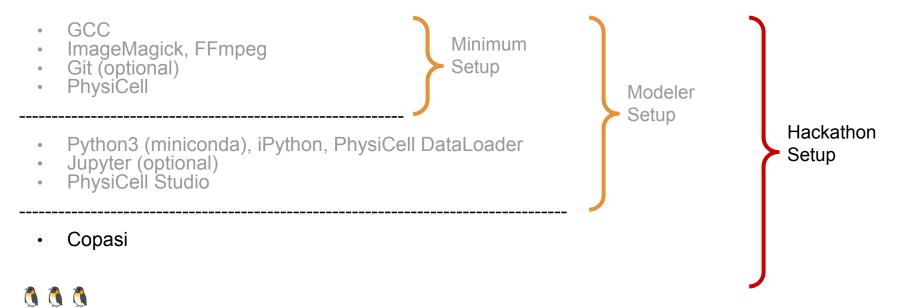
```
sudo apt install qtbase5-dev
pip install PyQt5
```

Test the installation with the biorobots sample project.

cd to wherever you have PhysiCell installed. Inside the PhysiCell folder: studio

PhysiCell Studio should open, loaded with the biorobots settings file.







### Copasi (Hackathon Setup)

- The detailed instructions can be found here: <a href="https://copasi.org/Support/Installation/Linux/">https://copasi.org/Support/Installation/Linux/</a>
- cd to the folder where you have your manual installed programs. e.g. ~/.local/lib/
- download copasi:

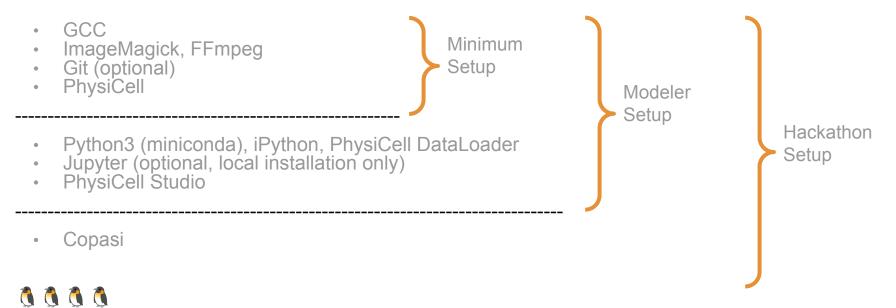
```
wget
```

https://github.com/copasi/COPASI/releases/download/Build-288/COPASI-4.43.288-Linux-64bit.sh

Install copasi:

```
chmod 775 COPASI-n.n.n-Linux-64bit.sh
./COPASI-n.n.n-Linux-64bit.sh
Thereby change the installation directory setting to where you right now are.
```

Put copasi under the PATH
 cd to the folder where you have your manual installed binaries. e.g. ~/.local/bin/
 ln -s /absolute/path/to/installed/CopasiSE
 ln -s /absolute/path/to/installed/CopasiUI





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