DAA LAB MANUAL

EXERCISE-1:

Implement Recursive Binary Search Algorithm

```
PROGRAM:
```

```
#include <bits/stdc++.h>
using namespace std;
int binarySearch(vector<int>arr, int I, int r, int x)
{
 while (I \le r)
 {
   int m = I + (r - I) / 2;
   if (arr[m] == x)
   return m;
   else if (arr[m] < x)
   I = m + 1;
   else
   r = m - 1;
  return -1;
}
int main()
{
       int n;
       cout<<"Enter size of Array: "; cin>>n;
       cout<<endl<<"Enter elements: "; vector<int>v;
       for(int i=0;i<n;i++)</pre>
       {
      int k; cin>>k;
     v.push_back(k);
    }
       cout<<endl<<"Enter element to be searched:";
       int x;
```

Enter size of Array: 3 Enter elements: 1 2 3 Enter element to be searched:2 Element is present at index 1

EXERCISE-2:

Implement Recursive Quicksort Algorithm

```
#include <iostream>
using namespace std;
int partition(int arr[], int start, int end)
{
 int pivot = arr[start];
 int count = 0;
 for (int i = start + 1; i <= end; i++)
 {
   if (arr[i] <= pivot)
   count++;
 }
 int pivotIndex = start + count;
 swap(arr[pivotIndex], arr[start]);
 int i = start, j = end;
 while (i < pivotIndex && j > pivotIndex)
 {
   while (arr[i] <= pivot)
   {
     i++;
   }
   while (arr[j] > pivot)
   {
     j--;
   }
   if (i < pivotIndex && j > pivotIndex)
   {
    swap(arr[i++], arr[j--]);
   }
 }
 return pivotIndex;
}
```

```
void quickSort(int arr[], int start, int end)
{
 if (start >= end)
   return;
 int p = partition(arr, start, end);
 quickSort(arr, start, p - 1);
 quickSort(arr, p + 1, end);
}
void printArray(int arr[], int size)
{
 int i;
 for (i = 0; i < size; i++)
   cout<<arr[i]<<" ";
}
int main()
{
 int n;
 cout<<"Enter number of elements: "<<endl;
 cin>>n;
 int arr[n];
 cout<<"Enter elements: "<<endl;
 for(int i=0;i<n;i++)</pre>
 cin>>arr[i];
 cout<<"Given array: "<<endl;
 for(int i=0;i<n;i++)</pre>
 cout<<arr[i]<<" ";
 cout<<endl;
 quickSort(arr, 0, n - 1);
 printf("Sorted array: \n");
 printArray(arr, n);
 return 0;
}
```

```
Enter number of elements:

6
Enter elements:
2 5 10 2 5 1
Given array:
2 5 10 2 5 1
Sorted array:
1 2 2 5 5 10
```

EXERCISE-3:

Implement Recursive Mergesort Algorithm

```
#include <stdio.h>
#include <stdlib.h>
void merge(int arr[], int I, int m, int r)
{
 int i, j, k;
  int n1 = m - l + 1;
  int n2 = r - m;
  int L[n1], R[n2];
  for (i = 0; i < n1; i++)
   L[i] = arr[I + i];
  for (j = 0; j < n2; j++)
   R[j] = arr[m + 1 + j];
  i = 0;
 j = 0;
  k = I;
  while (i < n1 \&\& j < n2)
  {
   if (L[i] \leq R[j])
   {
        arr[k] = L[i];
        i++;
   }
   else
   {
        arr[k] = R[j];
        j++;
   }
   k++;
  }
  while (i < n1)
```

```
{
   arr[k] = L[i];
   i++;
   k++;
  }
  while (j < n2)
 {
   arr[k] = R[j];
   j++;
   k++;
  }
}
void mergeSort(int arr[], int I, int r)
{
 if (I < r)
 {
    int m = I + (r - I) / 2;
    mergeSort(arr, I, m);
    mergeSort(arr, m + 1, r);
    merge(arr, I, m, r);
  }
}
void printArray(int A[], int size)
{
  int i;
  for (i = 0; i < size; i++)
  printf("%d ", A[i]);
  printf("\n");
}
int main()
{
  int n,i;
  printf("enter n value\n");
  scanf("%d",&n);
```

```
int a[n];
printf("enter array to be sorted\n");
for(i=0;i<n;i++)
{
    scanf("%d",&a[i]);
}
printf("Given array is \n");
printArray(a,n);
mergeSort(a, 0,n-1);
printf("\nSorted array is \n");
printArray(a,n);
return 0;
}</pre>
```

```
enter n value
10
enter array to be sorted
1 4 3 2 5 6 8 97 1 2
Given array is
1 4 3 2 5 6 8 97 1 2
Sorted array is
1 1 2 2 3 4 5 6 8 97
```

EXERCISE-4:

Implement Randomized Quicksort Algorithm

```
#include <iostream>
using namespace std;
int partition(int arr[], int low, int high)
{
 int pivot = arr[low];
 int i = low - 1, j = high + 1;
 while (true)
 {
 do
 {
   i++;
 } while (arr[i] < pivot);
 do
 {
  j--;
 } while (arr[j] > pivot);
 if (i \ge j)
 return j;
 swap(arr[i], arr[j]);
 }
}
int partition_r(int arr[], int low, int high)
{
 srand(time(NULL));
 int random = low + rand() % (high - low);
 swap(arr[random], arr[low]);
 return partition(arr, low, high);
}
```

```
void quickSort(int arr[], int low, int high)
{
 if (low < high)
 {
   int pi = partition r(arr, low, high);
   quickSort(arr, low, pi);
   quickSort(arr, pi + 1, high);
 }
}
void printArray(int arr[], int n)
{
  for (int i = 0; i < n; i++)
  printf("%d ", arr[i]);
  printf("\n");
}
int main()
{
  int n;
  cout<<"Enter number of elements: "<<endl;
  cin>>n;
  int arr[n];
  cout<<"Enter elements: "<<endl;</pre>
  for(int i=0;i<n;i++)</pre>
  cin>>arr[i];
  cout<<"Given array: "<<endl;</pre>
  for(int i=0;i<n;i++) cout<<arr[i]<<" ";
  cout<<endl;
  quickSort(arr, 0, n - 1);
  printf("Sorted array: \n");
  printArray(arr, n);
  return 0;
}
```

```
Enter number of elements:
7
Enter elements:
7 8 9 6 5 2 3
Given array:
7 8 9 6 5 2 3
Sorted array:
2 3 5 6 7 8 9
```

EXERCISE-5:

Find an optimal solution for a Knapsack Problem

```
#include <bits/stdc++.h>
using namespace std;
int main()
{
 int n,mx;
 cout<<"Enter number of elements: "<<endl;
 cin>>n;
 cout<<endl<<"Enter the maximum capacity:"<<endl;</pre>
 cin>>mx;
 vector<int>w,p;
 vector<double>d;
 cout<<"Enter weights: "<<endl;
 for(int i=0;i<n;i++)</pre>
 {
   int k;
   cin>>k;
   w.push_back(k);
 }
 cout<<endl<<"Enter profits: "<<endl;</pre>
 for(int i=0;i<n;i++)</pre>
 {
   int k;
   cin>>k;
   p.push_back(k);
 }
 for(int i=0;i<n;i++)
 {
  d.push_back(p[i]/(w[i]*1.0));
 }
```

```
for(int i=0;i<n;i++)</pre>
{
 for(int j=i+1;j<n;j++)
 {
   if(d[i] < d[j])
   {
     double tm=d[i]; d[i]=d[j];
     d[j]=tm;
     int t=w[i];
     w[i]=w[j];
     w[j]=t;
     t=p[i];
     p[i]=p[j];
     p[j]=t;
   }
  }
}
double profit=0;
for(int i=0;i<n;i++)
{
 if(mx<w[i])
 {
   profit+=mx*d[i];
   break;
  }
 else
 {
   profit+=p[i];
   mx-=w[i];
 }
}
```

```
cout<<endl<<"Maximum Profit is "<<pre>return 0;
```

```
Enter number of elements:
3
Enter the maximum capacity:
20
Enter weights:
18 15 10
Enter profits:
25 24 15
Maximum Profit is 31.5
```

EXERCISE-6:

Find the shortest path using Single Source Shortest Path Algorithm

```
#include <bits/stdc++.h>
using namespace std;
int miniDistance(int dist[], bool visited[],int V)
{
 int min = INT_MAX;
 int min_index;
 for (int v = 0; v < V; v++)
   if (visited[v] == false && dist[v] <= min)
    min = dist[v], min_index = v;
       return min_index;
}
void print(int dist[],int V)
{
 printf("Vertex Distance from Source\n");
 for (int i = 0; i < V; i++)
   cout<<i<" "<<dist[i]<<endl;
}
void dijkstra(vector<vector<int>>graph, int src,int V)
{
  int dist[V];
  bool visited[V];
  for (int i = 0; i < V; i++)
  dist[i] = INT_MAX, visited[i] = false;
  dist[src] = 0;
  for (int i = 0; i < V - 1; i++)
  {
```

```
int u = miniDistance(dist, visited,V);
    visited[u] = true;
    for (int v = 0; v < V; v++)
      if (!visited[v] && graph[u][v] && dist[u] != INT_MAX && dist[u] + graph[u][v] < dist[v])
               dist[v] = dist[u] + graph[u][v];
  }
  print(dist, V);
}
int main()
{
 int V;
 cout<<"Enter number of vertices:"<<endl;
 cin>>V;
 cout<<endl<<"Enter adjacency matrix elements:"<<endl;</pre>
 vector<vector<int>>graph;
 for(int i=0;i<V;i++)
 {
   vector<int>v;
   for(int j=0;j<V;j++)
   {
     int k;
     cin>>k;
     v.push_back(k);
   }
   graph.push_back(v);
 }
 dijkstra(graph, 0,V);
 return 0;
}
```

```
Enter number of vertices:

5
Enter adjacency matrix elements:
0 10 5 0 0
0 0 0 1 0
0 3 0 9 2
0 0 0 0 0
2 0 0 6 0
Vertex Distance from Source
0 0
1 8
2 5
3 9
4 7
```

EXERCISE-7:

Implement Huffman Coding Technique

```
#include <bits/stdc++.h> using namespace std;
struct MinHeapNode
{
 char data;
int freq;
 MinHeapNode *left, *right;
 MinHeapNode(char data, int freq)
{
  left = right = NULL;
  this->data = data;
  this->freq = freq;
}
};
struct compare
{
 bool operator()(MinHeapNode* I, MinHeapNode* r)
 {
  return (I->freq > r->freq);
 }
};
void printCodes(struct MinHeapNode* root, string str)
{
 if (!root) return;
 if (root->data != '$')
   cout << root->data << ": " << str << "\n";
 printCodes(root->left, str + "0");
 printCodes(root->right, str + "1");
```

```
void HuffmanCodes(char data[], int freq[], int size)
{
 struct MinHeapNode *left, *right, *top;
 priority_queue<MinHeapNode*, vector<MinHeapNode*>,compare> minHeap;
 for (int i = 0; i < size; ++i)
  minHeap.push(new MinHeapNode(data[i], freq[i]));
 while (minHeap.size() != 1)
 {
   left = minHeap.top();
   minHeap.pop();
   right = minHeap.top();
   minHeap.pop();
   top = new MinHeapNode('$',left->freq + right->freq);
   top->left= left;
   top->right = right;
   minHeap.push(top);
  }
  printCodes(minHeap.top(), "");
}
int main()
{
 int n;
 cout<<"Enter number of characters:"<<endl;
 cin>>n;
 char arr[n];
 int freq[n];
 cout<<endl<<"Enter Characters:"<<endl;
 for(int i=0;i<n;i++)
   cin>>arr[i];
 cout<<endl<<"Enter Frequencies"<<endl;
```

}

```
for(int i=0;i<n;i++)
  cin>>freq[i];
HuffmanCodes(arr, freq, n);
return 0;
}
```

```
Enter number of characters:

5
Enter Characters:
s t u v z
Enter Frequencies
33 12 9 7 22
s: 0
z: 10
t: 110
v: 1110
u: 1111
```

EXERCISE-8:

Implement 0/1 Knapsack Problem

```
PROGRAM:
```

```
#include <stdio.h>
int max(int a, int b)
{
 return (a > b) ? a : b;
}
int knapsack(int weights[], int values[], int n, int capacity)
{
 int i, w;
 int dp[n + 1][capacity + 1];
 for (i = 0; i <= n; i++)
 {
   for (w = 0; w \le capacity; w++)
   {
     if (i == 0 | | w == 0)
       dp[i][w] = 0;
     else if (weights[i - 1] <= w)
     {
       int p=dp[i-1][w-weights[i-1]+values[i-1];
       dp[i][w] = max(dp[i-1][w],p);
     }
     else
        dp[i][w] = dp[i - 1][w];
   }
 }
 printf("Selected items: ");
 i = n;
 w = capacity;
 while (i > 0 \&\& w > 0)
 {
   if (dp[i][w] != dp[i - 1][w])
```

```
{
     printf("%d ", i - 1);
     w -= weights[i - 1];
   }
   i--;
 }
 printf("\n");
 return dp[n][capacity];
}
int main()
{
 int n,i;
 printf("Enter Number of items:");
 scanf("%d",&n);
 int weights[n],profits[n];
 printf("\nEnter Weights:");
 for(i=0;i<n;i++)
 {
  scanf("%d",&weights[i]);
 }
 printf("\nEnter profits:");
 for(i=0;i<n;i++)
 {
   scanf("%d",&profits[i]);
 }
 int capacity;
 printf("\nEnter max capacity:");
 scanf("%d",&capacity);
 int maxValue = knapsack(weights,profits, n, capacity);
 printf("Maximum value: %d\n", maxValue);
 return 0;
}
```

Enter Number of items:7

Enter Weights: 2 3 5 7 1 4 1

Enter profits:10 5 15 7 6 18 3

Enter max capacity:15

Selected items: 5 4 2 1 0

Maximum value: 54

EXERCISE-9:

Find the shortest path using All Pairs Shortest Path Algorithm

```
#include <bits/stdc++.h>
using namespace std;
void printSolution(vector<vector<int>>dist,int V)
{
 cout << "The shortest distances between every pair of vertices \n";</pre>
 for (int i = 0; i < V; i++)
 {
  for (int j = 0; j < V; j++)
  {
        if (dist[i][j] == INT MAX)
          cout << "∞"<< " ";
        else
          cout << dist[i][j] << " ";
  }
   cout << endl;
 }
}
void floydWarshall(vector<vector<int>>dist,int V)
{
 int i, j, k;
 for (k = 0; k < V; k++)
 {
   for (i = 0; i < V; i++)
   {
         for (j = 0; j < V; j++)
         {
           if (dist[i][j] > (dist[i][k] + dist[k][j]) && (dist[k][j] != INT_MAX && dist[i][k] != INT_MAX))
                dist[i][j] = dist[i][k] + dist[k][j];
         }
   }
 }
```

```
printSolution(dist,V);
}
int main()
{
       int V;
       cout<<"Enter number of vertices:";
       cin>>V;
       vector<vector<int>>graph;
       cout<<endl<<"Enter adjacency matrix -1 if no edge exists:";
       for(int i=0;i<V;i++)
       {
         vector<int>v;
         for(int j=0;j<V;j++)
         {
            int k; cin>>k;
            if(k==-1)
            v.push_back(INT_MAX);
            else
            v.push_back(k);
         }
         graph.push_back(v);
       }
       floydWarshall(graph,V);
       return 0;
}
OUTPUT:
```

```
Enter number of vertices:4
Enter adjacency matrix -1 if no edge exists:
0 2 3 -1
-1 0 -1 -1
-1 6 0 4
The shortest distances between every pair of vertices
0 2 3 7
\infty 0 \infty \infty
9 6 0 4
5 7 8 0
```

EXERCISE-10:

Implement Travelling Salesman Problem

```
PROGRAM:
```

```
#include <bits/stdc++.h>
using namespace std;
int travllingSalesmanProblem(vector<vector<int>>graph, int s,int V)
{
 vector<int> vertex;
 for (int i = 0; i < V; i++)
   if (i != s)
        vertex.push_back(i);
 int min_path = INT_MAX;
 do
 {
    int current pathweight = 0;
       int k = s;
       for (int i = 0; i < vertex.size(); i++)
    {
         current_pathweight += graph[k][vertex[i]];
         k = vertex[i];
       }
       current_pathweight += graph[k][s];
       min path = min(min path, current pathweight);
  } while (next permutation(vertex.begin(), vertex.end()));
  return min_path;
}
int main()
{
  vector<vector<int>>graph;
  int V,s;
  cout<<"Enter number of vertices:";
  cin>>V;
  cout<<"Enter adjacency matrix of graph:";
  for(int i=0;i<V;i++)
```

```
{
  vector<int>v;
  for(int j=0;j<V;j++)
  {
    int k; cin>>k;
      v.push_back(k);
  }
  graph.push_back(v);
}

cout<<"Enter Source:";
  cin>>s;
  cout << travllingSalesmanProblem(graph, s,V) << endl;
  return 0;
}</pre>
```

```
Enter number of vertices:4
Enter adjacency matrix of graph:
0 10 15 20
10 0 35 25
15 35 0 30
20 25 30 0
Enter Source:0
```

EXERCISE-11:

Implement Sum of Subsets Problem

```
PROGRAM:
```

```
#include <bits/stdc++.h>
using namespace std;
int found = 0;
void PrintSubsetSum(int i, int n, vector<int>set, int targetSum,vector<int>& subset)
{
if (targetSum == 0)
{
  found = 1;
  cout << "[ ";
  for (int i = 0; i < subset.size(); i++)
  {
       cout << subset[i] << " ";
  }
  cout << "]";
  return;
}
if (i == n)
  return;
 PrintSubsetSum(i + 1, n, set, targetSum, subset);
if (set[i] <= targetSum)</pre>
{
  subset.push_back(set[i]);
  PrintSubsetSum(i + 1, n, set, targetSum - set[i],subset);
  subset.pop_back();
}
}
int main()
{
 int n;
 cout<<"Enter number of elements:";
```

```
cin>>n;
cout<<"Enter elements:";
vector<int> subset,set;
for(int i=0;i<n;i++)
{
    int k; cin>>k;
    subset.push_back(k);
}
cout<<"Enter target sum:";
int targetSum;
cin>>targetSum;
PrintSubsetSum(0,n,subset,targetSum,set);
if(found==0)
    cout<<"No Subset";
return 0;
}</pre>
```

```
Enter number of elements:3
Enter elements:1 2 1
Enter target sum:3
[ 2 1 ][ 1 2 ]
```

EXERCISE-12:

return true;

}

Implement N-Queens Problem

```
PROGRAM:
#include <bits/stdc++.h>
using namespace std;
void printSolution(vector<vector<int>>&board,int N)
{
 for (int i = 0; i < N; i++)
 {
   for (int j = 0; j < N; j++)
       if(board[i][j])
         cout << "Q ";
       else
      cout<<". ";
       printf("\n");
 }
}
bool isSafe(vector<vector<int>>&board, int row, int col,int N)
{
 int i, j;
 for (i = 0; i < col; i++)
       if (board[row][i])
         return false;
 for (i = row, j = col; i >= 0 && j >= 0; i--, j--)
       if (board[i][j])
         return false;
 for (i = row, j = col; j >= 0 && i < N; i++, j--)
       if (board[i][j])
         return false;
```

```
bool solveNQUtil(vector<vector<int>>&board, int col,int N)
{
 if (col >= N)
       return true;
 for (int i = 0; i < N; i++)
 {
   if (isSafe(board, i, col,N))
  {
       board[i][col] = 1;
    if (solveNQUtil(board, col + 1,N))
                return true;
                board[i][col] = 0;
  }
 }
 return false;
}
bool solveNQ()
{
 int n;
 cout<<"Enter size of board(n):";</pre>
 cin>>n;
 vector<vector<int>>board(n,vector<int>(n,0));
 if (solveNQUtil(board, 0,n) == false)
 {
       cout << "Solution does not exist";</pre>
       return false;
  }
  printSolution(board,n);
  return true;
}
int main()
{
       solveNQ();
       return 0;
```

```
}
```

```
Enter size of board(n):4
. . Q .
Q . . .
. . Q
. . Q .
```

Longest Common Subsequence Problem:

```
#include <stdio.h>
#include <string.h>
int lcs(char *X, char *Y, int m, int n) {
  int L[m+1][n+1];
  for (int i = 0; i \le m; i++) {
    for (int j = 0; j \le n; j++) {
       if (i == 0 || j == 0) {
         L[i][j] = 0;
       \} else if (X[i-1] == Y[j-1]) {
         L[i][j] = L[i-1][j-1] + 1;
       } else {
         L[i][j] = (L[i-1][j] > L[i][j-1]) ? L[i-1][j] : L[i][j-1];
       }
    }
  }
  return L[m][n];
}
void printLCS(char *X, char *Y, int m, int n) {
  int L[m+1][n+1];
  for (int i = 0; i \le m; i++) {
    for (int j = 0; j <= n; j++) {
       if (i == 0 || j == 0) {
         L[i][j] = 0;
       else if (X[i-1] == Y[i-1]) {
         L[i][j] = L[i-1][j-1] + 1;
       } else {
         L[i][j] = (L[i-1][j] > L[i][j-1]) ? L[i-1][j] : L[i][j-1];
       }
    }
  }
  int index = L[m][n];
  char lcs[index + 1];
  lcs[index] = '\0';
  int i = m, j = n;
  while (i > 0 \&\& j > 0) {
    if (X[i-1] == Y[j-1]) {
       lcs[index - 1] = X[i - 1];
       i--;
      j--;
       index--;
    ellipsep = \{L[i-1][j] > L[i][j-1]\}
```

```
i--;
    } else {
      j--;
  }
  printf("The Longest Common Subsequence is: %s\n", lcs);
}
int main() {
  char X[] = "ABCDEF";
  char Y[] = "AEBDF";
  int m = strlen(X);
  int n = strlen(Y);
  int length = lcs(X, Y, m, n);
  printf("Length of LCS: %d\n", length);
  printLCS(X, Y, m, n);
  return 0;
}
Output:
Length of LCS: 4
The Longest Common Subsequence is: ABDF
Heap Sort Technique:
#include <stdio.h>
void heapify(int arr[], int n, int i)
  int temp, maximum, left_index, right_index;
  maximum = i;
  right_index = 2 * i + 2;
  left_index = 2 * i + 1;
  if (left_index < n && arr[left_index] > arr[maximum])
    maximum = left_index;
  if (right_index < n && arr[right_index] > arr[maximum])
    maximum = right_index;
  if (maximum != i) {
    temp = arr[i];
    arr[i] = arr[maximum];
```

```
arr[maximum] = temp;
    heapify(arr, n, maximum);
  }
}
void heapsort(int arr[], int n)
  int i, temp;
  for (i = n / 2 - 1; i \ge 0; i--) {
    heapify(arr, n, i);
  }
  for (i = n - 1; i > 0; i--) {
    temp = arr[0];
    arr[0] = arr[i];
    arr[i] = temp;
    heapify(arr, i, 0);
  }
}
int main()
  int arr[] = { 20, 18, 5, 15, 3, 2 };
  int n = 6;
  printf("Original Array:");
  for (int i = 0; i < n; i++) {
    printf("%d", arr[i]);
  }
  printf("\n");
  heapsort(arr, n);
  printf("Array after performing heap sort: ");
  for (int i = 0; i < n; i++) {
    printf("%d ", arr[i]);
  }
  return 0;
}
Output:
Original Array: 20 18 5 15 3 2
Array after performing heap sort: 2 3 5 15 18 20
```

B- Tree and its operations:

```
#include <stdio.h>
#include <stdlib.h>
```

```
#define M 4
```

```
struct BTreeNode {
 int num_keys;
 int keys[M-1];
 struct BTreeNode *children[M];
 int is_leaf;
};
struct BTreeNode *createNode(int is_leaf) {
  struct BTreeNode *newNode = (struct BTreeNode *)malloc(sizeof(struct
BTreeNode));
 if (newNode == NULL) {
    perror("Memory allocation failed");
    exit(EXIT_FAILURE);
 newNode->num_keys = 0;
 newNode->is_leaf = is_leaf;
 for (int i = 0; i < M; i++) {
    newNode->children[i] = NULL;
 return newNode;
}
void splitChild(struct BTreeNode *parent, int index) {
  struct BTreeNode *child = parent->children[index];
 struct BTreeNode *newNode = createNode(child->is_leaf);
 newNode->num_keys = M/2 - 1;
 for (int i = 0; i < M/2 - 1; i++) {
    newNode->keys[i] = child->keys[i + M/2];
 }
 if (!child->is_leaf) {
    for (int i = 0; i < M/2; i++) {
      newNode->children[i] = child->children[i + M/2];
 }
 child->num_keys = M/2 - 1;
 for (int i = parent->num_keys; i > index; i--) {
    parent->children[i + 1] = parent->children[i];
 parent->children[index + 1] = newNode;
```

```
for (int i = parent - num_keys - 1; i > = index; i - ) {
    parent->keys[i + 1] = parent->keys[i];
 parent->keys[index] = child->keys[M/2 - 1];
 parent->num_keys++;
}
void insertNonFull(struct BTreeNode *node, int key) {
  int i = node->num_keys - 1;
 if (node->is_leaf) {
    while (i \ge 0 \&\& node \ge keys[i] > key) {
      node->keys[i + 1] = node->keys[i];
      i--;
    }
    node->keys[i+1] = key;
    node->num_keys++;
 } else {
    while (i \ge 0 \&\& node \ge keys[i] > key) \{
      i--;
    }
    i++;
    if (node->children[i]->num_keys == M - 1) {
      splitChild(node, i);
      if (node->keys[i] < key) {</pre>
        i++;
      }
    }
    insertNonFull(node->children[i], key);
 }
}
void insert(struct BTreeNode **root, int key) {
  struct BTreeNode *node = *root;
 if (node == NULL) {
    *root = createNode(1);
    (*root)->keys[0] = key;
    (*root)->num_keys = 1;
 } else {
    if (node -> num_keys == M - 1) {
      struct BTreeNode *new_root = createNode(0);
      new_root->children[0] = node;
      splitChild(new_root, 0);
      *root = new_root;
    }
```

```
insertNonFull(*root, key);
  }
}
void traverse(struct BTreeNode *root) {
  if (root != NULL) {
    int i;
    for (i = 0; i < root > num_keys; i++) {
      traverse(root->children[i]);
      printf("%d ", root->keys[i]);
   traverse(root->children[i]);
  }
}
int main() {
  struct BTreeNode *root = NULL;
  insert(&root, 10);
  insert(&root, 20);
  insert(&root, 5);
  insert(&root, 6);
  insert(&root, 12);
  insert(&root, 30);
  printf("In-order traversal of the B-tree: ");
  traverse(root);
  printf("\n");
  return 0;
}
output:
In-order traversal of the B-tree: 5 6 10 12 20 30
AVL Trees and Operations:
AVL Tree Program in C
*/
#include<stdio.h>
#include<stdlib.h>
// structure of the tree node
struct node
  int data;
```

```
struct node* left;
 struct node* right;
 int ht:
};
// global initialization of root node
struct node* root = NULL;
// function prototyping
struct node* create(int);
struct node* insert(struct node*, int);
struct node* delete(struct node*, int);
struct node* search(struct node*, int);
struct node* rotate_left(struct node*);
struct node* rotate_right(struct node*);
int balance_factor(struct node*);
int height(struct node*);
void inorder(struct node*);
void preorder(struct node*);
void postorder(struct node*);
int main()
{
 int user_choice, data;
  char user_continue = 'y';
 struct node* result = NULL;
 while (user_continue == 'y' || user_continue == 'Y')
    printf("\n\n----- AVL TREE ----\n");
    printf("\n1. Insert");
    printf("\n2. Delete");
    printf("\n3. Search");
    printf("\n4. Inorder");
    printf("\n5. Preorder");
    printf("\n6. Postorder");
    printf("\n7. EXIT");
    printf("\n\nEnter Your Choice: ");
    scanf("%d", &user_choice);
    switch(user_choice)
      case 1:
        printf("\nEnter data: ");
        scanf("%d", &data);
        root = insert(root, data);
        break;
```

```
case 2:
        printf("\nEnter data: ");
        scanf("%d", &data);
        root = delete(root, data);
        break;
      case 3:
        printf("\nEnter data: ");
        scanf("%d", &data);
        result = search(root, data);
        if (result == NULL)
          printf("\nNode not found!");
        }
        else
          printf("\n Node found");
        break;
      case 4:
        inorder(root);
        break;
      case 5:
        preorder(root);
        break;
      case 6:
        postorder(root);
        break;
      case 7:
        printf("\n\tProgram Terminated\n");
        return 1;
      default:
        printf("\n\tInvalid Choice\n");
    printf("\n\nDo you want to continue? ");
    scanf(" %c", &user_continue);
  return 0;
// creates a new tree node
struct node* create(int data)
```

}

}

```
struct node* new_node = (struct node*) malloc (sizeof(struct node));
  // if a memory error has occurred
 if (new_node == NULL)
    printf("\nMemory can't be allocated\n");
    return NULL;
 new_node->data = data;
 new_node->left = NULL;
 new_node->right = NULL;
 return new_node;
}
// rotates to the left
struct node* rotate_left(struct node* root)
  struct node* right_child = root->right;
  root->right = right_child->left;
  right_child->left = root;
  // update the heights of the nodes
  root->ht = height(root);
  right_child->ht = height(right_child);
  // return the new node after rotation
 return right_child;
}
// rotates to the right
struct node* rotate_right(struct node* root)
 struct node* left_child = root->left;
  root->left = left_child->right;
 left_child->right = root;
  // update the heights of the nodes
  root->ht = height(root);
 left_child->ht = height(left_child);
  // return the new node after rotation
 return left_child;
}
// calculates the balance factor of a node
int balance_factor(struct node* root)
  int lh, rh;
 if (root == NULL)
```

```
return 0;
  if (root->left == NULL)
    lh = 0;
  else
    lh = 1 + root -> left -> ht;
  if (root->right == NULL)
    rh = 0;
  else
    rh = 1 + root->right->ht;
  return lh - rh;
// calculate the height of the node
int height(struct node* root)
{
  int lh, rh;
  if (root == NULL)
    return 0;
  if (root->left == NULL)
    lh = 0;
  else
    lh = 1 + root -> left -> ht;
  if (root->right == NULL)
    rh = 0;
  else
    rh = 1 + root->right->ht;
  if (lh > rh)
    return (lh);
  return (rh);
}
// inserts a new node in the AVL tree
struct node* insert(struct node* root, int data)
  if (root == NULL)
    struct node* new_node = create(data);
    if (new_node == NULL)
      return NULL;
    root = new_node;
  else if (data > root->data)
    // insert the new node to the right
```

```
root->right = insert(root->right, data);
    // tree is unbalanced, then rotate it
    if (balance_factor(root) == -2)
      if (data > root->right->data)
        root = rotate_left(root);
      else
        root->right = rotate_right(root->right);
        root = rotate_left(root);
    }
  }
  else
    // insert the new node to the left
    root->left = insert(root->left, data);
    // tree is unbalanced, then rotate it
    if (balance_factor(root) == 2)
      if (data < root->left->data)
        root = rotate_right(root);
      else
        root->left = rotate_left(root->left);
        root = rotate_right(root);
      }
    }
  // update the heights of the nodes
  root->ht = height(root);
  return root;
// deletes a node from the AVL tree
struct node * delete(struct node *root, int x)
  struct node * temp = NULL;
  if (root == NULL)
    return NULL;
```

}

```
if (x > root -> data)
  root->right = delete(root->right, x);
  if (balance_factor(root) == 2)
    if (balance_factor(root->left) >= 0)
      root = rotate_right(root);
    else
      root->left = rotate_left(root->left);
      root = rotate_right(root);
  }
}
else if (x < root->data)
  root->left = delete(root->left, x);
  if (balance_factor(root) == -2)
    if (balance_factor(root->right) <= 0)</pre>
      root = rotate_left(root);
    else
      root->right = rotate_right(root->right);
      root = rotate_left(root);
}
else
  if (root->right != NULL)
    temp = root->right;
    while (temp->left != NULL)
      temp = temp->left;
    root->data = temp->data;
    root->right = delete(root->right, temp->data);
    if (balance_factor(root) == 2)
      if (balance_factor(root->left) >= 0)
        root = rotate_right(root);
```

```
else
          root->left = rotate_left(root->left);
          root = rotate_right(root);
        }
      }
    else
      return (root->left);
  root->ht = height(root);
  return (root);
}
// search a node in the AVL tree
struct node* search(struct node* root, int key)
  if (root == NULL)
    return NULL;
  if(root->data == key)
  {
    return root;
  if(key > root->data)
    search(root->right, key);
  }
  else
    search(root->left, key);
}
// inorder traversal of the tree
void inorder(struct node* root)
  if (root == NULL)
    return;
  inorder(root->left);
  printf("%d ", root->data);
```

```
inorder(root->right);
}
// preorder traversal of the tree
void preorder(struct node* root)
  if (root == NULL)
    return;
 printf("%d ", root->data);
  preorder(root->left);
  preorder(root->right);
}
// postorder traversal of the tree
void postorder(struct node* root)
  if (root == NULL)
  {
    return;
  postorder(root->left);
  postorder(root->right);
  printf("%d ", root->data);
}
output:
----- AVL TREE -----
1. Insert
2. Delete
3. Search
4. Inorder
5. Preorder
6. Postorder
7. EXIT
Enter Your Choice: 1
Enter data: 2
Do you want to continue? y
```