PROJECT SPECIFICATION

Create a Line Follower Robot

Reference

R = Require Improvements

M = Meeting Expectation

E = Exceed Expectation

Documentations

Specifications	Result		t	Comments
	R	М	Е	
The project report is self- explanatory. Any supplementary materials, charts and graphs should be referenced clearly. The flow of the project should be logical and easy to follow.				
The project report should at least document 1 critical decision/design in both hardware and software parts.				

Sensors and Output Usage

Specifications	Result		t	Comments
	R	М	Е	
The robot should make use of at least 2 sensors. The two sensors could be of same type or different types but they should have different purpose instead of just act as fail-safe purpose.				
The robot should make use of at least 1 output devices. Examples are motor for movements, light or buzzer for debug and testing purpose.				

Software Design

Specifications	Result		t	Comments
	R	М	Е	
The software of the robot should make use of loops, and if-else control flow.				
The algorithm is described clear and understandable. The logic flow can be easily followed. Graphs or flow chart are used when suitable.				
The software should be easy to understand by fresh eyes, including well-defined variable or sensor names.				

Performance Tuning

Specifications	Result		t	Comments
	R	М	Ε	
The program should structure in a way that is easy to be adjusted. For example, when the robot is moved to a dark or sunny position, it can be adjusted conveniently and function properly.				