Separation Logic

Niccolò Piazzesi January 4, 2022

Outline

- 1 Introduction
- 2 Theoretical Foundations
- 3 Reasoning with separation logic
- 4 Tools

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Brief recap: reasoning about code

- Program semantics described by logical conditions satisfied by language constructs
- Classical model, first put forward by Robert W. Floyd and Tony Hoare

Floyd-Hoare Logic in 1 slide

$\{P\}S\{Q\}$

P : pre-conditions

S : statement

Q : post conditions

Partial correctness: If the inital state fullfils pre-conditions and the statement terminates, the final state satisfies the post conditions.

Total correctness: If the initial state fullfils the pre-conditions then the statement terminates and the final state satisfies the post-conditions.

Limitations

Does not work for non terminating programs

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Global view of state becomes a burden when introducing pointers(think of pointer aliasing..)

Motivating example

```
void deletetree(struct node *root){
   if(root != NULL){
    struct node *left = root->l;
    struct node *right = root->r;
   deletetree(left);
   deletetree(right);
   free(root);
  }
}
```

How can we prove memory safety?

First attempt

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The model

Ints
$$\triangleq \{\cdots, -1, 0, 1, \cdots\}$$

Atoms, Locations
$$\subseteq Ints$$

Stores
$$\triangleq$$
 Variables \rightharpoonup_{fin} Ints

Variables
$$\triangleq \{x, y, \cdots\}$$

$$Locations \cap Atoms = \{\}, \ nil \in \\ Atoms$$

$$\mathsf{Heaps} \triangleq \mathsf{Locations} \rightharpoonup_{fin} \mathsf{Ints}$$

$$\mathsf{States} \triangleq \mathsf{Stores} \times \mathsf{Heaps}$$

$$[\![E]\!]_s \in Ints, \ [\![B]\!]_s \in \{\mathsf{true}, \ \mathsf{false}\}$$

$$h \in Heaps, h[E] \in Ints$$

Expressions:

$$E, F, G := x, y, \dots \mid 0 \mid 1 \mid E + F \mid E \times F \mid E - F$$
$$B := false \mid B \Rightarrow B \mid E = F \mid E < F \mid isatom?(E) \mid isloc?(E)$$

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Assertions:

$$P,Q,R ::= B \mid E \mapsto F$$
 Atomic Formulae $\mid false \mid P \Rightarrow Q \mid \forall x.P$ Classical Logic $\mid emp \mid P * Q \mid P - * Q$ Spatial Connectives

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$$\neg P = P \Rightarrow False
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$$P \land Q = \neg(\neg P \lor \neg Q)
\exists x.P = \neg \forall x. \neg P$$

Some notation

- **1** dom(h) and dom(s) denote the domain of definition for $h \in Heaps$ and $s \in Stores$, respectively
- $2 h \# h' \to dom(h) \cap dom(h') = \emptyset$
- 3 h * h' is the union of disjoint heaps
- **4** $(f|i\mapsto j)$ represent the partial function that behaves like f except that i goes to j.

$$E \mapsto F_0, \dots, F_n \triangleq (E \mapsto F_0) * \dots * (E + n \mapsto F_n)$$

 $E \doteq F \triangleq (E = F) \land emp$
 $E \mapsto - \triangleq \exists y.E \mapsto y$

Semantics

For store s and heap h			

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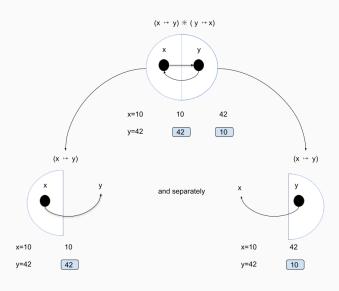
$$\begin{split} s,h &\models B \; iff \; [\![B]\!]_s = true \\ s,h &\models E \mapsto F \; iff \; \{ [\![E]\!]_s \} = dom(h) \; and \; h([\![E]\!]_s) = [\![F]\!]_s \\ s,h &\models false \quad never \\ s,h &\models P \Rightarrow Q \; iff \; if \; s,h \models P \; then \; s,h \models Q \\ s,h &\models \forall x.P \; iff \; \forall v \in Ints.[s \mid x \mapsto v],h \models P \end{split}$$

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Visual example



Core system

Proof rules in seapartion logic are divide in:

- **1** Axioms for basic mutation commands \rightarrow *Small axioms*
- 2 Inference rules for modular reasoing \rightarrow Structural rules

$$\{E\mapsto -\}[\mathbf{E}]:=\mathbf{F}\{E\mapsto F\} \; \big(\text{"Store"}\big)$$

$$\begin{split} \{E \mapsto -\} [\mathbf{E}] &:= \mathbf{F} \{E \mapsto F\} \text{ ("Store")} \\ \{E \mapsto -\} \mathbf{free}(\mathbf{E}) \{emp\} \text{ ("Reclaim memory")} \end{split}$$

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$$\{E \mapsto -\}[\mathbf{E}] := \mathbf{F}\{E \mapsto F\} \text{ ("Store")}$$

$$\{E \mapsto -\}\mathbf{free}(\mathbf{E})\{emp\} \text{ ("Reclaim memory")}$$

$$\{x \doteq m\}\mathbf{x} := \mathbf{cons}(\mathbf{E_1}, \cdots, \mathbf{E_k})\{x \mapsto E_1[m/x], \cdots, E_k[m/x]\}$$
("Allocate memory")
$$\{x \doteq n\}\mathbf{x} := \mathbf{E}\{x \doteq (E[n/x])\}$$

$$\{E \mapsto n \land x = m\}\mathbf{x} := [\mathbf{E}]\{x = n \land E[m/x] \mapsto n\} \text{ ("Load")}$$

Frame Rule

$$\frac{\{P\}C\{Q\}}{\{P*frame\}C\{Q*frame\}}\ Mod(C)\cap Free(frame)=\emptyset$$

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Auxiliary variable elimination

$$\frac{\{P\}C\{Q\}}{\{\exists x.P\}C\{\exists x.Q\}} \ x \notin Free(C)$$

Variable substitution

$$\frac{\{P\}C\{Q\}}{(\{P\}C\{Q\})[E_1/x_1,\cdots E_k/x_k]}$$

 x_i free and if $x_i \in Mod(C)$ then E_i is not free in any E_j

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 x_i free and if $x_i \in Mod(C)$ then E_i is not free in any E_j

Rule of consequence

$$\frac{P\Rightarrow P' \quad \{P\}C\{Q\} \quad Q\Rightarrow Q'}{\{P\}C\{Q'\}}$$

Derived laws

The structural rules can be used to obtain more convenient derived laws.

As an example, we can simplify the rule for memory allocation by assuming $x \notin Free(E_1, \cdots, E_k)$.

$$\{emp\}x := cons(E_1, \cdots, E_k)\{x \mapsto E_1, \cdots, E_k\}$$

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The structural rules can be used to obtain more convenient derived laws.

As an example, we can simplify the rule for memory allocation by assuming $x \notin Free(E_1, \cdots, E_k)$.

$$\{emp\}x := cons(E_1, \cdots, E_k)\{x \mapsto E_1, \cdots, E_k\}$$

The core system can also be extended with the usual Hoare rules

$$\frac{\{P \land B\}C\{Q\} \quad \{P \land \neg B\}C\{Q\}}{\{P\}if \ B \ then \ C \ else \ C'\{Q\}}$$

Revisiting the tree example

```
void deletetree(struct node *root){
   if(root != NULL){
    struct node *left = root->1;
    struct node *right = root->r;
   deletetree(left);
   deletetree(right);
   free(root);
  }
}
```

Revisiting the tree example

```
void deletetree(struct node *root){
    if(root != NULL){
     struct node *left = root->1;
     struct node *right = root->r;
     deletetree(left);
     deletetree (right);
    free (root);
}
Specification:
{tree(root)} deletetree(root) {emp}
tree(root) = if root == 0 then emp
           else \exists xy.root \mapsto [l:x,r:y] * tree(x) * tree(y)
```

 $\{root \mapsto [l: left, r: right] * tree(left) * tree(red)\}$

```
\{root \mapsto [l: left, r: right] * tree(left) * tree(red)\}
deletetree(left);
```

```
\{root \mapsto [l: left, r: right] * tree(left) * tree(red)\}
deletetree(left);
\{root \mapsto [l: left, r: right] * emp * tree(red)\}
```

```
 \{ root \mapsto [l: left, r: right] * tree(left) * tree(red) \}   deletetree(left);   \{ root \mapsto [l: left, r: right] * emp * tree(red) \}   deletetree(right);
```

```
\{root \mapsto [l: left, r: right] * tree(left) * tree(red)\}
deletetree(left);
\{root \mapsto [l: left, r: right] * emp * tree(red)\}
deletetree(right);
\{root \mapsto [l: left, r: right] * emp * emp\}
```

```
\begin{aligned} & \textbf{Proof:} \\ & \{ root \mapsto [l:left,r:right]*tree(left)*tree(red) \} \\ & deletetree(left); \\ & \{ root \mapsto [l:left,r:right]*emp*tree(red) \} \end{aligned}
```

 $\{root \mapsto [l: left, r: right] * emp * emp\}$

deletetree(right);

free(root);

```
Proof:
\{root \mapsto [l: left, r: right] * tree(left) * tree(red)\}
deletetree(left);
\{root \mapsto [l: left, r: right] * emp * tree(red)\}
deletetree(right);
\{root \mapsto [l: left, r: right] * emp * emp\}
free(root);
\{emp * emp * emp\}
\{emp\}
```

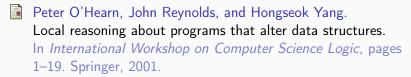
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