

Separation Logic

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Outline

- 1 Introduction
- 2 Theoretical Foundations
- 3 Reasoning with separation logic
- 4 Tools

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Brief recap: reasoning about code

- Program semantics described by logical conditions satisfied by language constructs
- Classical model, first put forward by Robert W. Floyd and Tony Hoare

$$\{P\}S\{Q\}$$

- P : pre-conditions
- S : statement
- Q : post conditions

Partial correctness: **If the initial state fullfils pre-conditions and the statement terminates**, the final state satisfies the post conditions.

Total correctness: **If the initial state fullfils the pre-conditions** then the statement terminates and the final state satisfies the post-conditions.

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Global view of state becomes a burden when introducing pointers(think of pointer aliasing..)

Motivating example

```
void deletetree(struct node *root){  
    if(root != NULL){  
        struct node *left = root->l;  
        struct node *right = root->r;  
        deletetree(left);  
        deletetree(right);  
        free(root);  
    }  
}
```

How can we prove
memory safety?

First attempt

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The model

$$\text{Ints} \triangleq \{\dots, -1, 0, 1, \dots\}$$

$$\text{Atoms}, \text{Locations} \subseteq \text{Ints}$$

$$\text{Stores} \triangleq \text{Variables} \rightarrow_{fin} \text{Ints}$$

$$\text{Variables} \triangleq \{x, y, \dots\}$$

$$\text{Locations} \cap \text{Atoms} = \{\}, \text{nil} \in \text{Atoms}$$

$$\text{Heaps} \triangleq \text{Locations} \rightarrow_{fin} \text{Ints}$$

$$\text{States} \triangleq \text{Stores} \times \text{Heaps}$$

$$\llbracket E \rrbracket_s \in \text{Ints}, \llbracket B \rrbracket_s \in \{\text{true}, \text{false}\}$$

$$h \in \text{Heaps}, h[E] \in \text{Ints}$$

The language

Expressions:

$$E, F, G := x, y, \dots \mid 0 \mid 1 \mid E + F \mid E \times F \mid E - F$$
$$B := false \mid B \Rightarrow B \mid E = F \mid E < F \mid isatom?(E) \mid isloc?(E)$$

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Assertions:

$$P, Q, R ::= B \mid E \mapsto F \qquad \textit{Atomic Formulae}$$
$$\mid false \mid P \Rightarrow Q \mid \forall x. P \qquad \textit{Classical Logic}$$
$$\mid emp \mid P * Q \mid P - * Q \qquad \textit{Spatial Connectives}$$

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Spatial Connectives

$$\neg P = P \Rightarrow False$$
$$true = \neg(false)$$
$$P \vee Q = \neg(P) \Rightarrow Q$$

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$$\neg P = P \Rightarrow False$$

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$$P \vee Q = \neg(P) \Rightarrow Q$$

$$P \wedge Q = \neg(\neg P \vee \neg Q)$$

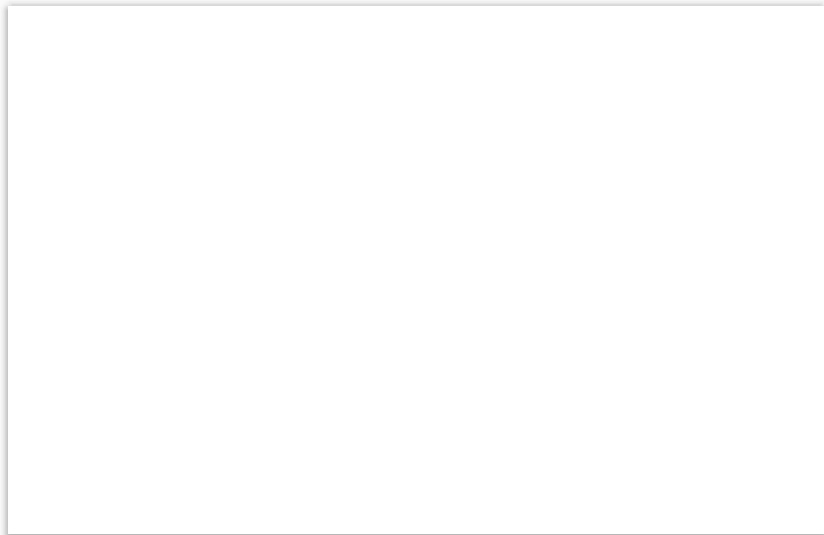
$$\exists x.P = \neg \forall x. \neg P$$

Some notation

- 1 $dom(h)$ and $dom(s)$ denote the domain of definition for $h \in Heaps$ and $s \in Stores$, respectively
- 2 $h \# h' \rightarrow dom(h) \cap dom(h') = \emptyset$
- 3 $h * h'$ is the union of disjoint heaps
- 4 $(f|i \mapsto j)$ represent the partial function that behaves like f except that i goes to j .

Semantics

For store s and heap h



For store s and heap h

$$s, h \models B \text{ iff } \llbracket B \rrbracket_s = \text{true}$$

$$s, h \models E \mapsto F \text{ iff } \{\llbracket E \rrbracket_s\} = \text{dom}(h) \text{ and } h(\llbracket E \rrbracket_s) = \llbracket F \rrbracket_s$$

$$s, h \models \text{false} \quad \text{never}$$

$$s, h \models P \Rightarrow Q \text{ iff if } s, h \models P \text{ then } s, h \models Q$$

$$s, h \models \forall x. P \text{ iff } \forall v \in \text{Ints}. [s \mid x \mapsto v], h \models P$$

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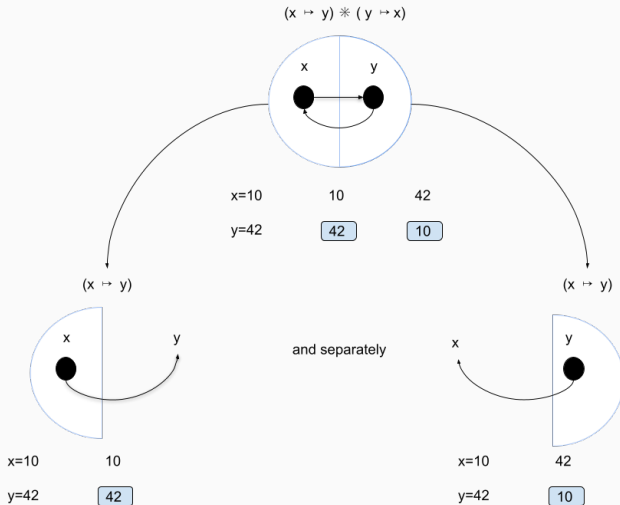
$$s, h \models \forall x. P \text{ iff } \forall v \in \text{Ints}. [s \mid x \mapsto v], h \models P$$

$$s, h \models \text{emp} \text{ iff } h = [] \text{ is the empty heap}$$

$$s, h \models P * Q \text{ iff } \exists h_0, h_1. h_0 \# h_1, h_0 * h_1 = h, s, h_0 \models P \text{ and } s, h_1 \models Q$$

$$s, h \models P - * Q \text{ iff } \forall h'. \text{ if } h' \# h \text{ and } s, h' \models P \text{ then } s, h * h' \models Q$$

Visual example



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