Decision Tree and Random Forest

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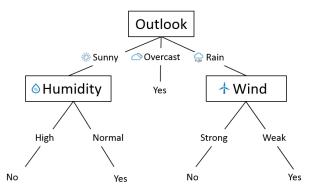
Learning the Play Tennis Decision Tree

4 Attributes

Outlook	Temp	Humidity	Wind	PlayTennis
Sunny	Hot	High	Weak	No
Sunny	Hot	High	Strong	No
Overcast	Hot	High	Weak	Yes
Rain	Mild	High	Weak	Yes
Rain	Cool	Normal	Weak	Yes
Rain	Cool	Normal	Strong	No
Overcast	Cool	Normal	Strong	Yes
Sunny	Mild	High	Weak	No
Sunny	Cool	Normal	Weak	Yes
Rain	Mild	Normal	Weak	Yes
Sunny	Mild	Normal	Strong	Yes
Overcast	Mild	High	Strong	Yes
Overcast	Hot	Normal	Weak	Yes
Rain	Mild	High	Strong	No
	Sunny Sunny Overcast Rain Rain Overcast Sunny Sunny Rain Sunny Overcast Overcast	Sunny Hot Sunny Hot Overcast Hot Rain Mild Rain Cool Overcast Cool Sunny Mild Sunny Cool Rain Mild Sunny Mild Sunny Mild Overcast Mild Overcast Hot	Sunny Hot High Sunny Hot High Overcast Hot High Rain Mild High Rain Cool Normal Rain Cool Normal Overcast Cool Normal Sunny Mild High Sunny Cool Normal Rain Mild Normal Sunny Mild High Overcast Mild High Overcast Mild High	Sunny Hot High Weak Sunny Hot High Strong Overcast Hot High Weak Rain Mild High Weak Rain Cool Normal Weak Rain Cool Normal Strong Overcast Cool Normal Strong Sunny Mild High Weak Sunny Cool Normal Weak Rain Mild Normal Weak Rain Mild Normal Weak Rain Mild Normal Strong Overcast Mild High Strong Overcast Mild High Strong

Play Tennis: Yes or No?

- Learned function is a tree
- Classify instances by sorting them down from the root to the leaf node



6

10

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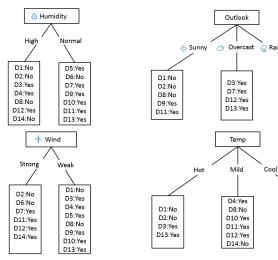
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14 15

Algorithm 1: Decision Tree

```
Input: Training set D = \{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_n, y_n)\}; Attribute set A = \{a_1, a_2, ..., a_d\}.
   Procedure: Function TreeGenerate(D, A)
 1 Generate node:
 2 if all the samples in D belong to class C then
        mark this node as class C leaf node; return
 4 end
   if A = \emptyset OR samples in D have the same value on A then
        mark this node as leaf node, and the class should be the most frequent
          occurrence class; return
   end
   Select the best partition attribute a_* from A;
   for each value a_*^v of attribute a_* do
        D_v is the sample subset of D with a_* = a_*^v;
        if D_v = \emptyset then
             mark this node as the leaf node, and the class should be the most frequent
               occurrence class: return
        else
             generate a branch for this node, TreeGenerate(D_v, A \setminus \{a_*\})
        end
16 end
   Output: A decision tree
```

Which Is The Best Partition Attribute?



D5:Yes

D6:No

D7:Yes

D9:Yes

D4:Yes

D5:Yes

D6:No

D10:Yes

D14:No

Decision Tree Example A Good Attribute

An attribute is good when:

- For one value we get all instances as positive
- For other value we get all instances as negative

Poor Attribute

An attribute is poor when:

- It provides no discrimination
- Attribute is immaterial to the decision
- For each value we have same number of positive and negative instances

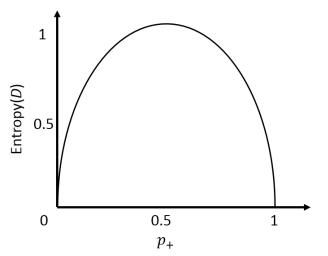
Measure of Homogeneity of Examples

- Entropy: Characterizes the (im)purity of an arbitrary collection of examples.
- Given a collection D of positive and negative examples, entropy of D relative to boolean classification is

$$Entropy(D) \equiv -p_+log_2p_+ - p_-log_2p_-$$

Where p_+ is proportion of positive examples and p_- is proportion of negative examples.

Entropy Function Relative to A Boolean Classification



Entropy

- Illustration:
- D is a collection of 14 examples with 9 positive and 5 negative examples
- Entropy of D relative to the Boolean classification:

$$Entropy(9+,5-) = -\frac{9}{14}log_2\frac{9}{14} - \frac{5}{14}log_2\frac{5}{14} = 0.940$$

ullet Entropy is zero if all members of D belong to the same class

Entropy for Multi-Valued Target function

 If the target attribute can take on c different values, the entropy of D relative to this c-wise classification is

$$Entropy(D) \equiv \sum_{i=1}^{c} -p_i log_2 p_i$$

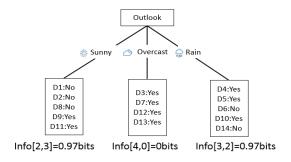
Information Gain Measures the Expected Reduction in Entropy

- Entropy measures the impurity of a collection
- Information gain of attribute A is the reduction in entropy caused by partitioning the set of examples D

$$Gain(D, A) \equiv Entropy(D) - \sum_{v \in Values(A)} \frac{|D_v|}{|D|} Entropy(D_v)$$

• Where Values(A) is the set of all possible values for attribute A and D_v is the subset of D for which attribute A has value v

Measure of Purity: Information (bits)



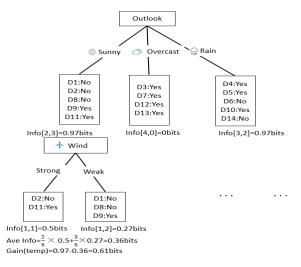
$$Info[2,3] = entropy(2,3)$$

= $-\frac{2}{5}log_2\frac{2}{5} - \frac{3}{5}log_2\frac{3}{5}$
= $0.97bits$

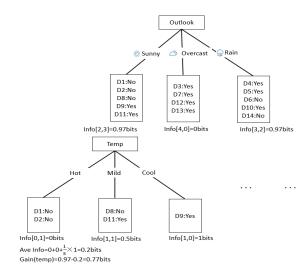
Information Gain for Each Attribute

- Gain(outlook) = 0.94 0.693 = 0.247
- Gain(temperature) = 0.94 0.911 = 0.029
- Gain(humidity) = 0.94 0.788 = 0.152
- Gain(windy) = 0.94 0.892 = 0.048
- $\bullet \ \arg\max_{A}\{0.247, 0.029, 0.152, 0.048\} = \mathsf{outlook}$
- Select outlook as the splitting attribute of tree

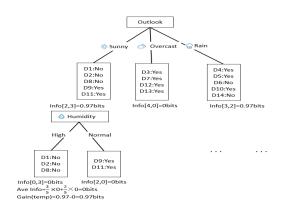
Expanded Tree Stumps for PlayTennis for Outlook=Sunny



Expanded Tree Stumps for PlayTennis for Outlook=Sunny

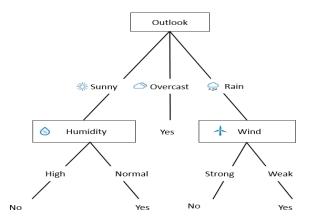


Expanded Tree Stumps for PlayTennis for Outlook=Sunny



- Since Gain(humidity) is highest, select humidity as splitting attribute
- No need to split further

Decision Tree for the Weather Data



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- \bullet Giveing a dataset D with m samples, we take samples to make dataset $D^{'}$
- ullet Select a sample from D to $D^{'}$ and put it back to the data set D each time, so the sample has the probability to be selected next time
- ullet Repeat the procedure m times to get $D^{'}$ with m samples

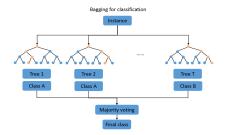
The probablility that a sample will not be selected:

$$\lim_{m \to +\infty} \left(1 - \frac{1}{m} \right)^m \to \frac{1}{e} \approx 0.368$$

- There are approximately $\frac{1}{3}$ samples used for testing which is called out-of-bag estimate
- Bootstrap sampling is useful in the case of small dataset and getting testing samples difficultly

Bagging

- Get T sampling sets through bootstrap sampling
- Train T base learners through the sampling sets respectively



- For classification: The class with the most votes becomes the final class
- For regression: The final output is the average output of every base learner

Random Forest

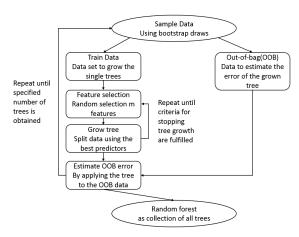
- Random forest is an extension of bagging using decision tree as base learner
- Randomly select m out of p features to get the optimal partition feature

Comparison between bagging and random forest

- The training efficiency of random forest is higher than bagging
- Bagging uses decision tree with definite structure
- Random forest uses decision tree with random structure

Random Forest

An example of the process flow is depicted below



Random Forest

THANK YOU!

Principal Component Analysis

Consider a data matrix, $\mathbf{X} \in \mathbb{R}^{n \times p}$, with **column-wise zero mean**, PCA is to find a direction $\mathbf{w} \in \mathbb{R}^p$ to project the data to the direction to achieve **the largest variance**

- Direction: $||\mathbf{w}|| = 1$
- ullet n observations: $y_i = \mathbf{x}^{ op} \mathbf{w}$, where $\mathbf{x} \in \mathbb{R}^p$ is a sample
- ullet Projected feature: $\mathbf{y} = \mathbf{X}\mathbf{w} \in \mathbb{R}^n$
- w is unknown
- Largest variance?

$$\max_{\mathbf{w}} ||\mathbf{X}\mathbf{w}||^2 = \max_{\mathbf{w}} \mathbf{w}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{w}, s.t., \mathbf{w}^{\top} \mathbf{w} = 1$$
 (1)

Principal Component Analysis

$$\max_{\mathbf{w}} \mathbf{w}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{w}, s.t., \mathbf{w}^{\top} \mathbf{w} = 1$$
 (2)

• Lagrangian multiplier method: $\mathcal{L}(\mathbf{w}, \lambda) = \mathbf{w}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{w} - \lambda (\mathbf{w}^{\top} \mathbf{w} - 1)$

Optimality condition:

$$\frac{\partial \mathcal{L}(\mathbf{w}, \lambda)}{\partial \mathbf{w}} = 0. \Rightarrow \mathbf{X}^{\top} \mathbf{X} \mathbf{w} - \lambda \mathbf{w} = \mathbf{0} \Rightarrow \mathbf{X}^{\top} \mathbf{X} \mathbf{w} = \lambda \mathbf{w}$$

Interpretations and Power Method

Rayleigh quotient:

$$\max_{\mathbf{w}} \frac{\mathbf{w}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{w}}{\mathbf{w}^{\top} \mathbf{w}} \tag{3}$$

- w: Direction or Principal Component or Eigenvector of X^TX.
- λ :
 The objective value or Variance of y or Eigenvalue of $\mathbf{X}^{\top}\mathbf{X}$.

Second Component?

- ullet Compute the residual: $\mathbf{X}_r = \mathbf{X} \mathbf{X} \mathbf{w} \mathbf{w}^{\top}$
- Rayleigh quotient on X_r :

$$\max_{\mathbf{w}} \frac{\mathbf{w}^{\top} \mathbf{X}_r^{\top} \mathbf{X}_r \mathbf{w}}{\mathbf{w}^{\top} \mathbf{w}} \tag{4}$$

Extensions

Consider optimizing $\mathbf{W} \in \mathbb{R}^{p \times r}$ directly:

$$\max_{\mathbf{W} \in \mathbb{R}^{p \times r}} ||\mathbf{X}\mathbf{W}||_F^2 = \mathbf{W}^\top \mathbf{X}^\top \mathbf{X}\mathbf{W}, s.t., \mathbf{W}^\top \mathbf{W} = \mathbf{I}$$
 (5)

- Lagrangian multiplier method: $\mathcal{L}(\mathbf{W}, \lambda) = \mathbf{W}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{W} - \langle \Lambda, \mathbf{W}^{\top} \mathbf{W} - I \rangle$
- Optimality condition: $\frac{\partial \mathcal{L}(\mathbf{W}, \lambda)}{\partial \mathbf{W}} = 0. \Rightarrow \mathbf{X}^{\top} \mathbf{X} \mathbf{W} \lambda \mathbf{W} = 0 \Rightarrow \mathbf{X}^{\top} \mathbf{X} \mathbf{W} = \Lambda \mathbf{W}$
- If r = p, what will happen?