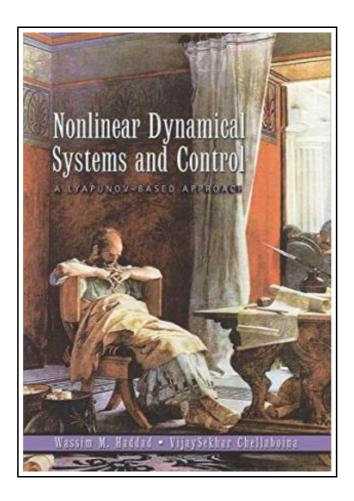
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NONLINEAR DYNAMICAL SYSTEMS AND CONTROL: A LYAPUNOV-BASED APPROACH



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