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1 Generally Useful Maths

Trig Properties

$$\sin^2 x + \cos^2 x = 1 \qquad \frac{d}{dx} \sin x = \cos x$$

$$\tan x = \frac{\sin x}{\cos x} \qquad \frac{d}{dx} \cos x = -\sin x$$

$$\frac{d}{dx} \tan x = \sec^2 x \qquad \frac{d}{dx} \cot x = -\csc^2 x$$

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1 - x^2}} \qquad \frac{d}{dx} \arccos x = \frac{-1}{\sqrt{1 - x^2}}$$

$$\frac{d}{dx} \arctan x = \frac{1}{1 + x^2}$$

Log & Exp Properties

$$\frac{x}{dx}b^x = b^x \ln x \qquad \log(\frac{1}{x}) = -\log x$$

$$\log_a x = \frac{\log_b x}{\log_a x} \qquad \frac{d}{dx}e^{ax} = ae^{ax}$$

$$\frac{d}{dx}a^x = a^x \ln a \qquad \frac{d}{dx}\ln x = \frac{1}{x}$$

$$x^0 = 1 \qquad x^n \cdot x^m = x^{n+m} \qquad x^{-n} = \frac{1}{x^n}$$

$$\log_a x^n = n\log_a x \qquad \frac{e^{-nx}}{e^x} = e^{-(n+1)x}$$

$$\log_a(\frac{x}{y}) = \log_a x - \log_a y$$

$$\log_a(xy) = \log_a x + \log_a y$$

Useful Series

$$r^0 + r^1 + r^2 + r^3 = \frac{r^n - 1}{r - 1}$$
 for an alternating series the following will work to start: $\sum_{n=0}^{\infty} (-1)^n$ or $\sum_{n=0}^{\infty} (-1)^{n+1}$

In Class Terminology

the relative error formula: $\frac{|x-\hat{x}|}{x}$ these were represed strangely in class: x' = f(t, x) $x(2) = 1 \rightarrow t = 2, x = 1$ If x'' = xx' then x''' = xx'' + x'x'2 Base Conversion

Decimal to Binary

For this simply find the place of the largest binary number that (of the form 2^n) that is within the number. Successivley subtract these numbers while keeping track of their place to generate the binary number.

Binary to Decimal

mal number has a corresponding power of 2. If the decimal number has a floating point then the power is negative counting from zero. This generates a sum of the form: $2^n + \dots + 2^2 + 2^1 + 2^{-1} + 2^{-2} + \dots + 2^{-m}$ Where n is the most significant digit and m is the least. The 2^{-1} term is the begin-

ning of the floating point numbers.

For this notice that each place in the deci-

Binary to Octal

Simply follow the table:
$$000 \rightarrow 0001 \rightarrow 1002 \rightarrow 2003 \rightarrow 3004 \rightarrow 4005 \rightarrow 5006 \rightarrow 6007 \rightarrow 7$$

Binary to Hex

This identical to the Octal method, the Hex symbols range from 0 to F and binary from 0000 to 1111. Simply count up un binary and there is a simple conversi-

One & Two's Complement

3 IEEE Floating Points

Definitions

s =signed bit, c =based exponent, F =fraction. The general form for this is $(-1)^{s} \cdot 2^{c-127} \cdot 1.F$, for both |s| = 1For single precision: |c| = 8, |F| = 23For double precision: |c| = 11, |F| = 52

Converting to IEEE Format

A number will have the form D_n ... $D_1D_0.F_0F_1$... F_m , to start we need to shift the values left (normalize) so that the number is now of the form: $D_n.F_0F_1...F_{m+(n-1)} \cdot 10^{n-1}$.

Example

Converting the number -42.125 to binary floating point with single precision: $0.125 \cdot 2 = [0].25 \rightarrow 0.25 \cdot 2 = [0].5 \rightarrow$ $0.5 \cdot 2 = [1].0$ Thus the fractional part is: 0.001, the nonfractional part is: $\frac{1}{32} \frac{0}{16} \frac{1}{8} \frac{0}{4} \frac{1}{2} \frac{0}{1} \rightarrow 101010$

The full value, 101010.001, when normaized is: $1.01010001 \cdot 10^5$. We find the *c* term with $2^{c-127} = 2^5 \rightarrow c = 132$ and we already have F = .01010001 This gives us the following number with single precision:

$[1][10000100][01010001...b_{23}]$

4 Loss of Significance

Loss of Precision Theorem

The general form of the theorem is as follows:

x and y are floating point numbers such that x > y > 0, the theorem states that given: $2^{-p} \le 1 - \frac{y}{x} \le 2^{-q}$

there are at most p and at least q digits lost in the subtraction x - y.

practically speaking, we view the equation as: E(x) = f(x) - g(x). If we notice this approaches 0 we have a concern of loss of precision at that point, to find that point we typically view the max loss acceptable as 1, so we set the euqation to

 $\frac{g(x)}{f(x)} = \frac{1}{2}$. We find the x = z values that

cause the $\frac{1}{2}$ flip and use a Taylor method there and use the normal formula elsewhere. We're just avoiding the loss of precision as $x \to z$.

Rationalizing Numerators

In some cases we want to rationalize a numerator to avoid a loss of significance. This is the 4th order (RK4) Runge-Kutta The general form for radicals in a

demonitor is:

$$\sqrt[k]{x^n + r} + c \cdot \sqrt[k]{\frac{\sqrt[k]{x^n + r} - c}{\sqrt[k]{x^n + r} - c}} = \frac{x^n + r - 2c}{\sqrt[k]{x^n + r} - c}$$

5 Taylor, Maclaurin, & Euler **Taylor Series**

The Taylor series is a sum of derivatives of increasing order that equate to a function. The formula for the Taylor series of f(x) evaluated at a is:

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n = f(a) +$$
 cession. They the K_n value the first formula above. $f'(a)(x-a) + \frac{f''(a)}{2!} (x-a)^2 + \frac{f'''(a)}{3!} (x-a)^3$

Taylor's Method for ODEs

This method takes advantage of the previously mentioned series. here this is some step size h that we take from some f(x) value. This is the Initial Value Problem (IVP).

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2!}f''(x)h^2 + \frac{1}{3!}f'''(x)h^3 + \dots$$

Maclaurin Series

The Maclaurin series is just the Taylor series at the special case where x = 0. This gives the following:

$$f(x) = f(0) + f'(0) + \frac{x^2}{2!}f'''(0) + \frac{x^3}{3!}f'''(0) + \frac{x^4}{4!}f''''(0) + \dots = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!}x^n$$

Euler's Method for ODEs

This method is just a Taylor series of order 1 with the same step term h, though many steps can be taken: f(x+h) = f(x) + f'(x)h

Error Terms

We note that Taylor's theorem in terms

$$f(x+h) = \sum_{k=0}^{n} \frac{f^{k}(x)}{k!} h^{k} + E_{n+1}$$

Thus, error terms are of the form:

$$E_{n+1} = \frac{f^{n+1}(\xi)}{(n+1)!} h^{n+1}$$

It pays off to look at the term more specifically for the problem. A lot of times the

error term takes the form $\frac{n^2}{n!}$ or $\frac{n^2}{n!}$.

It is important to note that we only care about the $0.5 \cdot 10^n$ if our desired accuracy is to the nth decimal. Thus we set $E_{n+1} < 0.5 \cdot 10^n$

Accuracy to Postition Example

Imagine that we have an error term it will be of the following form:

$$E_{n+1} = \frac{f^{n+1}(\xi)}{(n+1)!} h^{n+1} \text{ Let } E_{n+1} = \frac{x^{n+1}}{n!}$$

6 Runge-Kutta Methods

method for the Initial Value Problem

(IVP):

 $K_3 = h f(t + \frac{1}{2}h, x + \frac{1}{2}K_2)$

$$x(t+h) = x(t)\frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

where the following are values of K_n :
 $K_1 = hf(t,x)$
 $K_2 = hf(t + \frac{1}{2}h, x + \frac{1}{2}K_1)$

 $K_4 = h f(t + \bar{h}, x + K_3)$ first, the K_n values are calculated in succession. They the K_n values are filled into