2018-06 **EFFICIENT TOOLS** for RESEARCH

Julia: My New Friend FOR Computing & Optimization?

« Julia, my new friend for computing and optimization? »

- Intro to the Julia programming language, for MATLAB users
- *Date:* 14th of June 2018
- Who: Lilian Besson & Pierre Haessig
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Agenda for today [30 min]

- 1. What is Julia? [5 min]
- 2. Comparison with MATLAB [5 min]
- 3. Two examples of problems solved Julia [5 min]
- 4. Longer ex. on optimization with JuMP [13min]
- 5. Links for more information? [2 min]

1. What is Julia?

- Open-source and free programming language (MIT license)
 - Developed since 2012 (creators: MIT researchers)
 - Growing popularity worldwide, in research, data science, finance etc...
 - Multi-platform: Windows, Mac OS X, GNU/Linux...
- Designed for *performance*:
 - Interpreted *and* compiled, very efficient
 - Easy to run your code in parallel (multi-core & cluster)
- Designed to be *simple to learn and use*:
 - Easy syntax, dynamic typing (MATLAB & Python-like)

Ressources

- Website:
 - JuliaLang.org for the language
 - & Pkg.JuliaLang.org for packages
- Documentation: docs.JuliaLang.org



Comparison with MATLAB (1/3)

	Julia 😃	MATLAB 😢	
Cost	Free 🦊	Hundreds of euros / year	
License	Open-source	1 year user license (no longer after your PhD!)	
Comes from	A non-profit foundation, and the community	MathWorks company	
Scope	Mainly numeric	Numeric only	
Performances	Very good performance	Faster than Python, slower than Julia	

Comparison with MATLAB (2/3)

	Julia	MATLAB
Packaging	Pkg manager included. Based on git + GitHub, very easy to use	Toolboxes already included but \$\square\$ have to pay if you wat more!
Editor/IDE	Jupyter is recommended (Juno is also good)	Good IDE already included
Parallel computations	Very easy, low overhead cost	Possible, high overhead

Comparison with MATLAB (3/3)

	Julia	MATLAB
Usage	Generic, worldwide 💲	Research in academia and industry
Fame	Young but starts to be known	Old and known In decline 📉 ?
Support?	Community ¹ : StackOverflow, Forum	By MathWorks
Documentation	OK and growing, inline/online	OK, inline/online

Note¹: Julia Computing, Inc. (founded 2015 by Julia creators) offer paid licenses (JuliaPro Enterprise) with professional support.

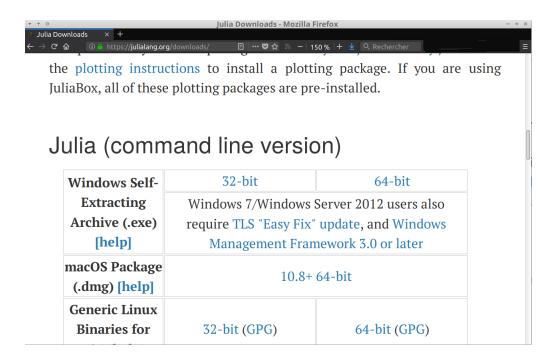
How to install Julia (1/2)

- You can try online for free on JuliaBox.com
- On Linux, Mac OS or Windows:
 - You can use the default installer from the website JuliaLang.org/downloads
- Takes about 4 minutes... and it's free!

You also need Python 3 to use Jupyter 🐎, I suggest to use

Anaconda.com/download if you don't have Python yet.

How to install Julia (2/2)



- 1. Select the binary of your platform •
- 2. Run the binary 🚶!
- 3. Wait 0...
- 4. Done 🤞! Test with julia in a terminal

Different tools to use Julia

• Use julia for the command line for short experiments

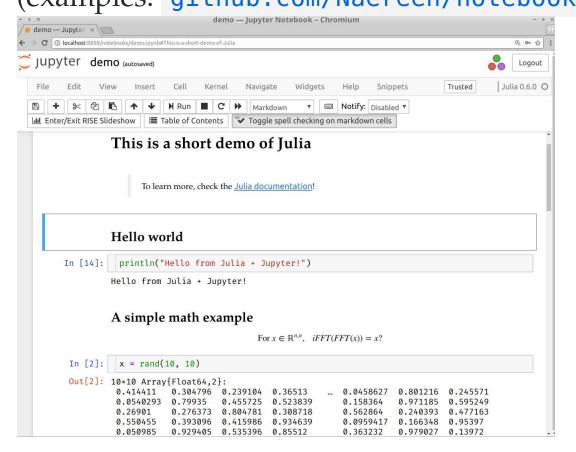
```
(lun. juin 11 -- 03:06:27)lilian@jarvis:[~]> {bashv4.4} — Konsole
$ julia
                             A fresh approach to technical computing
                             Documentation: https://docs.julialang.org
                              Type "?help" for help.
                             Version 0.6.0 (2017-06-19 13:05 UTC)
                             Official http://julialang.org/ release
                             x86_64-pc-linux-gnu
julia> println("Hello world from Julia!")
Hello world from Julia!
julia>
```

• Use the *Juno* IDE to edit large projects

Demo time 💆 !

Different tools to use Julia

• Use **Jupyter** notebooks to write or share your experiments (examples: github.com/Naereen/notebooks)



We How to install modules in Julia?

• Installing is **easy**!

```
julia> Pkd.add("IJulia") # installs IJulia
```

Updating also!

```
julia> Pkg.update()
```

How to find the module you need?

- First... ask your colleagues 😂!
- Complete list on Pkg.JuliaLang.org

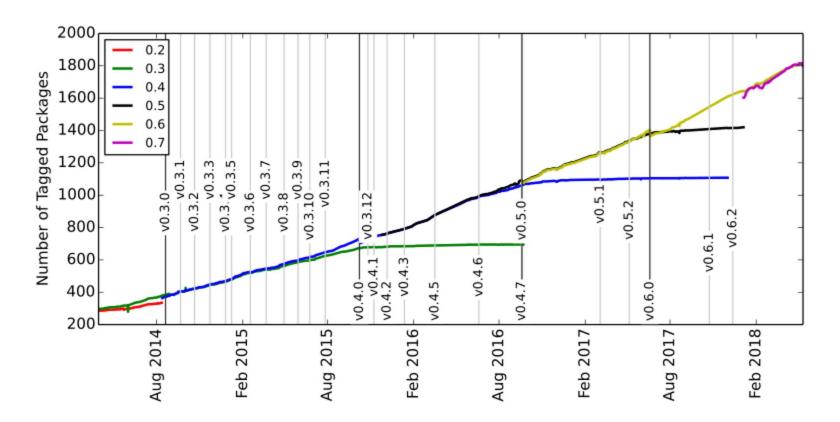


Overview of famous Julia modules

- Plotting:
 - Winston.jl for easy plotting like MATLAB
 - PyPlot.jl interface to Matplotlib (Python)
- The JuliaDiffEq collection for **differential equations**
- The JuliaOpt collection for **optimization**
- The JuliaStats collection for **statistics**
- And many more!

Find more specific packages on GitHub.com/svaksha/Julia.jl

Many packages, and a quickly growing community



Julia is still in development, in version v0.6 but version 1.0 is planned soon!

2. Main differences in syntax between Julia and **MATLAB**

Ref: CheatSheets.QuanteCon.org

2. Main differences in syntax between Julia and MATLAB

Ref: CheatSheets.QuanteCon.org

	Julia	MATLAB	
File ext.	.jl	. m	
Comment	# blabla	% blabla	
Indexing	a[1] to a[end]	a(1) to a(end)	
Slicing	a[1:100] (view)	a(1:100) (! copy)	
Operations	Linear algebra by default	Linear algebra by default	
Block	Use end to close all blocks	Use endif endfor etc	

	Julia	MATLAB
Help	?func	help func
And	a & b	a && b
Or	a b	a b
Datatype	Array of any type	multi-dim doubles array
Array	[1 2; 3 4]	[1 2; 3 4]
Size	size(a)	size(a)
Nb Dim	ndims(a)	ndims(a)
Last	a[end]	a(end)

	Julia	MATLAB
Tranpose	a.'	a.'
Conj. transpose	a '	a'
Matrix x	a * b	a * b
Element-wise x	a .* b	a .* b
Element-wise /	a ./ b	a ./ b
Element-wise ^	a ^ 3	a .^ 3
Zeros	zeros(2, 3, 5)	zeros(2, 3, 5)
Ones	ones(2, 3, 5)	ones(2, 3, 5)
Identity	eye(10)	eye(10)
Range	range(0, 100, 2) or 1:2:100	1:2:100

	Julia	MATLAB
Maximum	max(a)	max(max(a)) ?
Random matrix	rand(3, 4)	rand(3, 4)
L^2 Norm	norm(v)	norm(v)
Inverse	inv(a)	inv(a)
Solve syst.	a \ b	a \ b
Eigen vals	V, $D = eig(a)$	[V,D]=eig(a)
FFT/IFFT	fft(a), ifft(a)	fft(a), ifft(a)

Very close to MATLAB for linear algebra!

3. Scientific problems solved with Julia

Just to give examples of syntax and modules

- 1. 1D numerical integration and plot
- 2. Solving a 2^{nd} order Ordinary Differential Equation

3.1. 1D numerical integration and plot

Exercise: evaluate and plot this function on [-1, 1]:

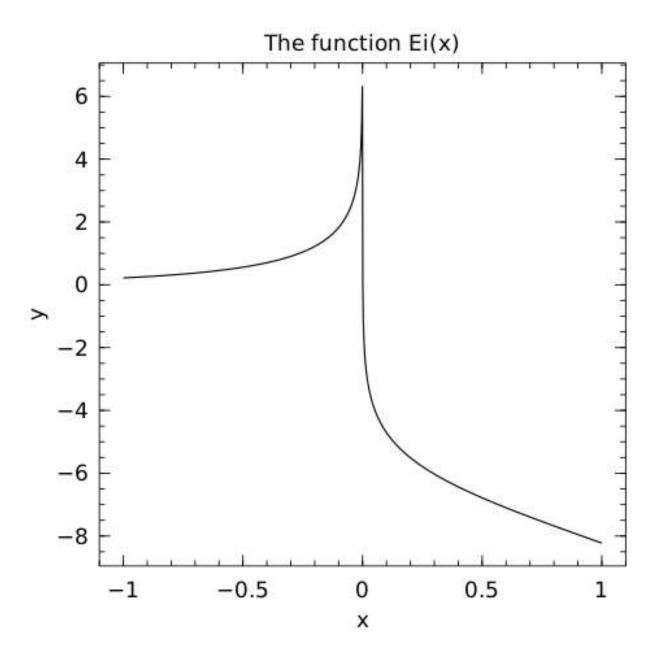
$$\mathrm{Ei}(x) := \int_{-x}^{\infty} rac{\mathrm{e}^u}{u} \; \mathrm{d}u$$

How to?

Use packages and everything is easy!

- QuadGK.jl for integration
- Winston.jl for 2D plotting

```
using QuadGK
function Ei(x, minfloat=1e-3, maxfloat=100)
    f = t -> exp(-t) / t # inline function
    if x > 0
        return quadgk(f, -x, -minfloat)[1]
             + quadgk(f, minfloat, maxfloat)[1]
    else
        return quadgk(f, -x, maxfloat)[1]
    end
end
X = linspace(-1, 1, 1000) # 1000 points
Y = [Ei(x) for x in X] # Python-like syntax!
using Winston
plot(X, Y)
title("The function Ei(x)")
xlabel("x"); ylabel("y")
savefig("figures/Ei integral.png")
```



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3.2. Solving a 2^{nd} order ODE

Goal: solve and plot the differential equation of a pendulum:

$$\theta''(t) + b\theta'(t) + c\sin(\theta(t)) = 0$$

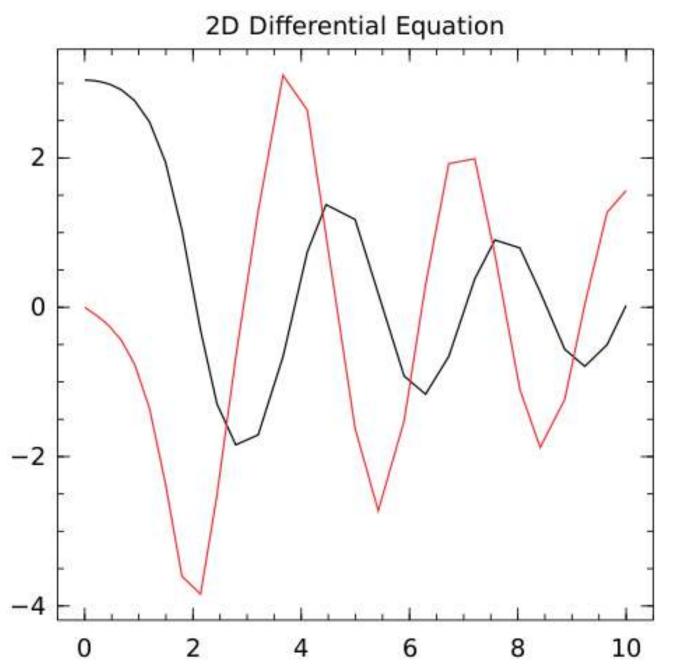
For
$$b=1/4$$
, $c=5$, $\theta(0)=\pi-0.1$, $\theta'(0)=0$, $t\in[0,10]$

How to?

Use packages!

- Differential Equations.jl function for ODE integration
- Winston.jl for 2D plotting

```
using DifferentialEquations
b, c = 0.25, 5.0
y0 = [pi - 0.1, 0]
# macro magic!
pend2 = @ode def Pendulum begin
  d\theta = \omega \# \leftarrow yes, this is UTF8, \theta and \omega in text
  d\omega = (-b * \omega) - (c * \sin(\theta))
end
prob = ODEProblem(pend, y0, (0.0, 10.0))
sol = solve(prob) # \(\preceq solve on interval [0,10]\)
t, y = sol.t, hcat(sol.u...)'
using Winston
plot(t, y[:, 1], t, y[:, 2])
title("2D Differential Equation")
savefig("figures/Pendulum solution.png")
```



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Examples

- 1. **Iterative computation**: signal filtering
- 2. Optimization: robust regression on RADAR data

Ex. 1: Iterative computation

Objective:

- show the efficiency of Julia's Just-in-Time (JIT) compilation
- but also its fragility...

Note: you can find companion notebooks on GitHub

Iterative computation: signal filtering

The classical saying:

« Vectorized code often runs much faster than the corresponding code containing loops. » (cf. MATLAB doc)

does not hold for Julia, because of its **Just-in-Time compiler**.

Example of a computation that cannot be vectorized

Smoothing of a signal $\{u_k\}_{k\in\mathbb{N}}$:

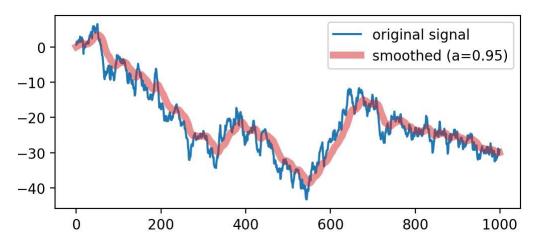
$$y_k = ay_{k-1} + (1-a)u_k, \quad k \in \mathbb{N}^+$$

Parameter a tunes the smoothing (none: a=0, strong $a \to 1^-$).

Iteration (for loop) cannot be avoided.

Signal filtering in Julia 🥠

```
function smooth(u, a)
    y = zeros(u)
    y[1] = (1-a)*u[1]
    for k=2:length(u) # this loop is NOT slow!
        y[k] = a*y[k-1] + (1-a)*u[k]
    end
    return y
end
```



Performance of the signal filter

Implementation	Time for $10\mathrm{Mpts}$	Notes
Julia 🔆	$50-70\mathrm{ms}$	Fast! Easy!
Matlab 2017b*	$90-100\mathrm{ms}$	\$
Octave 4.2	$88000\mathrm{ms}$	slow!! 6 6
Scilab	$7800\mathrm{ms}$	slow!! 🍖 🍖
Python native	$4400\mathrm{ms}$	slow! 🉋
SciPy's lfilter	$70\mathrm{ms}$	many lines of C
Python + @numba.jit	$50\mathrm{ms}$	since 2012

^{*}on a VM which adds an overhead of 20% to 40%, (so that 70 ms \rightarrow 100 ms)

(Matlab and Python implementations)

```
function y = smooth(u, a)
    y = zeros(length(u), 1);
    y(1) = (1-a)*u(1);
    for k=2:length(u)
        y(k) = a*y(k-1) + (1-a)*u(k);
    end
end
```

Python (optionally with Numba's jit decorator)

```
@numba.jit # <- factor ×100 speed-up!</pre>
def smooth jit(u, a):
    y = np.zeros_like(u)
    y[0] = (1-a)*u[0]
    for k in range(1, len(u)):
        y[k] = a*y[k-1] + (1-a)*u[k]
    return y
```

Conclusion on the performance

For this simple iterative computation:

- Julia performs very well, much better than native Python
- but it's possible to get the same with fresh Python tools (Numba)
- more realistic examples are needed

Fragility of Julia's JIT Compilation



The efficiency of the compiled code relies on **type inference**.

```
function smooth1(u, a)
    \vee = 0
    for k=1:length(u)
        y = a*y + (1-a)*u[k]
    end
    return y
end
```

```
function smooth2(u, a)
    y = 0.0 # <- difference is here!
    for k=1:length(u)
        y = a*y + (1-a)*u[k]
    end
    return y
end
```

An order of magnitude difference wvs A

```
julia> @time smooth1(u, 0.9);
  0.212018 seconds (30.00 M allocations: 457.764 MiB ...)
julia> @time smooth2(u, 0.9);
  0.024883 seconds (5 allocations: 176 bytes)
```

Fortunately, Julia gives a good diagnosis tool X

```
julia> @code warntype smooth1(u, 0.9);
... # ↓ we spot a detail
y::Union{Float64, Int64}
```

y is either Float64 or Int64 when it should be just Float64.

Cause: initialization y=0 vs. y=0.0!

Ex. 2: Optimization in Julia

Objective: demonstrate JuMP, a Modeling Language for Optimization in Julia.

- Some researchers migrate to Julia just for this!
- I use JuMP for **my research** (energy management)

Note: you can find companion notebooks on GitHub

Optimization problem example

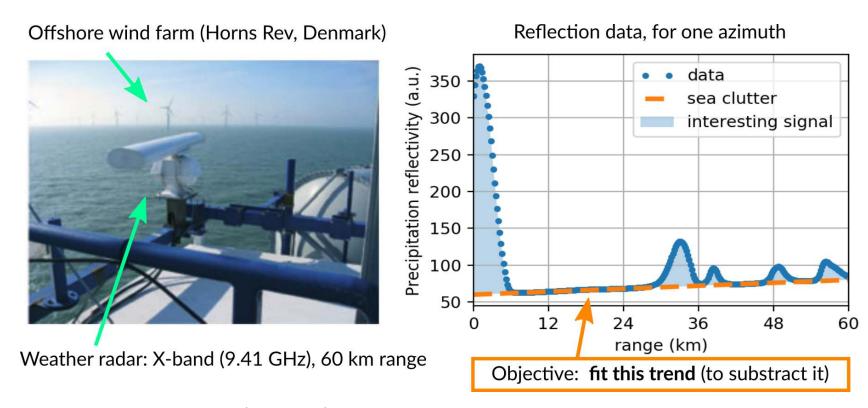
Example problem: identifying the sea clutter in Weather Radar data.

- is a **robust regression** problem
 - $\circ \hookrightarrow$ is an optimization problem!

An « IETR-colored » example, inspired by:

- Radar data+photo: P.-J. Trombe et al., « Weather radars the new eyes for offshore wind farms?,» Wind Energy, 2014.
- Regression methods: S. Boyd and L. Vandenberghe, Convex Optimization. Cambridge University Press, 2004. (Example 6.2).

Weather radar: the problem of sea clutter



Given n data points (x_i, y_i) , fit a linear trend:

$$\hat{y} = a.x + b$$

An **optimization problem** with two parameters: a (slope), b (intercept)

Regression as an optimization problem

The parameters for the trend (a,b) should minimize a criterion Jwhich penalizes the residuals $r_i = y_i - \hat{y} = y_i - a.x + b$:

$$J(a,b) = \sum_i \phi(r_i)$$

where ϕ is the *penaly function*, to be chosen:

- $\phi(r) = r^2$: quadratic deviation \rightarrow least squares regression
- $\phi(r) = |r|$: absolute value deviation
- $\phi(r) = h(r)$: Huber loss

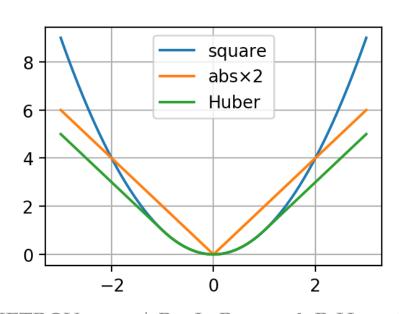


The choice of the loss function influences:

- the optimization result (fit quality)
 - *e.g.*, in the presence of outliers
- the properties of optimization problem: convexity, smoothness

Properties of each function

- quadratic: convex, smooth, heavy weight for strong deviations
- absolute value: convex, not smooth
- Huber: a mix of the two



X How to solve the regression problem?

Option 1: a big bag of tools

A specific package for each type of regression:

- « least square toolbox » (\rightarrow MultivariateStats.jl)
- « least absolute value toolbox » (\rightarrow quantile regression)
- « Huber toolbox » (*i.e.*, robust regression \rightarrow ??)

Option 2: the « One Tool »



- ⇒ a **Modeling Language for Optimization**
 - more **freedom to explore variants** of the problem

Modeling Languages for Optimization

Purpose: make it easy to **specify** and **solve** optimization problems without expert knowledge.

JuMP: optimization modeling in Julia

• The JuMP package offers a domain-specific modeling language for mathematical optimization.

JuMP interfaces with many optimization solvers: open-source (Ipopt, GLPK, Clp, ECOS...) and commercial (CPLEX, Gurobi, MOSEK...).

- Other Modeling Languages for Optimization:
 - Standalone software: AMPL, GAMS
 - Matlab: YALMIP (previous seminar), CVX
 - Python: Pyomo, PuLP, CVXPy

Claim: JuMP is **fast**, thanks to Julia's metaprogramming capabilities (generation of Julia code within Julia code).



Regression with JuMP — common part

• Given x and y the 300 data points:

```
m = Model(solver = ECOSSolver())
@variable(m, a)
@variable(m, b)
res = a*x .- y + b
```

res (« residuals ») is an Array of 300 elements of type JuMP.GenericAffExpr{Float64, JuMP.Variable}, i.e., a semi-symbolic affine expression.

Now, we need to specify the penalty on those residuals.

Regression choice: least squares regression

$$\min \sum_i r_i^2$$

Reformulated as a Second-Order Cone Program (SOCP):

min j, such that $||r||_2 \leq j$

```
@variable(m, j)
@constraint(m, norm(res) <= j)</pre>
@objective(m, Min, j)
```

 $(SOCP problem \Longrightarrow ECOS solver)$

Regression choice: least absolute deviation

$$\min \sum_i |r_i|$$

Reformulated as a Linear Program (LP)

$$\min \sum_i t_i, \quad ext{such that } -t_i \leq r_i \leq t_i$$

```
@variable(m, t[1:n])
@constraint(m, res .<= t)</pre>
@constraint(m, res .>= -t)
@objective(m, Min, sum(t))
```

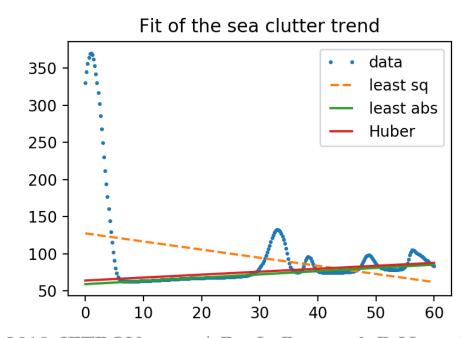
Solve!

```
julia> solve(m)
:Optimal # hopefully
```

```
julia> getvalue(a), getvalue(b)
(-1.094, 127.52) # for least squares
```

Observations:

- least abs. val., Huber
- least squares X



JuMP: summary

A modeling language for optimization, within Julia:

- gives access to all classical optimization solvers
- very fast (claim)
- gives freedom to explore many variations of an optimization problem (fast prototyping)
- More on optimization with Julia:
 - JuliaOpt: host organization of JuMP
 - Optim.jl: implementation of classics in Julia (*e.g.*, Nelder-Mead)
 - JuliaDiff: Automatic Differentiation to compute gradients, thanks to Julia's strong capability for code introspection

Conclusion (1/2)

Sum-up

- I hope you got a good introduction to Julia
- It's not hard to migrate from MATLAB to Julia
- Good start:
 docs.JuliaLang.org/en/stable/manual/getting-started
- Julia is fast!
- Free and open source!
- Can be very efficient for some applications!

Conclusion (2/2)

Thanks for joining 👏!

Your mission, if you accept it... 🛪

- 1. Padawan level: Train yourself a little bit on Julia
 - → JuliaBox.com ? Or install it on your laptop!

And read introduction in the Julia manual!

- 2. **I** *Jedi level:* Try to solve a numerical system, from your research or teaching, in Julia instead of MATLAB
- 3. *Master level:* From now on, try to use open-source & free tools for your research (Julia, Python and others)... 😽

Thank you!!