



Numerical approximation of spatially varying blur operators.

P. Weiss and P. Escande
S. Anthoine, C. Chaux, C. Mélot

CNRS - ITAV - IMT

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Disclaimer

- ✗ We are newcomers to the field of computational harmonic analysis and we are still living in the previous millenium!
- ✓ Do not hesitate to ask further questions to the pillars of time-frequency analysis present in the room.
- ✓ A rich and open topic!

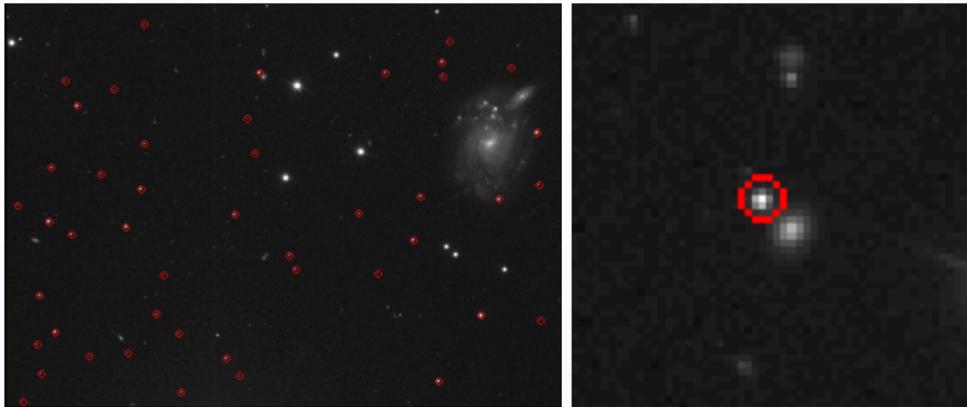
Main references for this presentation

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-  Escande, P. and P. Weiss (2014). "Numerical Computation of Spatially Varying Blur Operators A Review of Existing Approaches with a New One". In: *arXiv preprint arXiv:1404.1023*.
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- **Part I:** Spatially varying blur operators.
 - ① Examples and definitions.
 - ② Challenges.
 - ③ Existing computational methods.
- **Part II:** Sparse representations in wavelet bases.
 - ① Meyer's and Beylkin-Coifman-Rokhlin's results.
 - ② Finding good sparsity patterns.
 - ③ Numerical results.
- **Part III:** Estimation/interpolation.
 - ① An inverse problem on operators.
 - ② A tractable numerical scheme using wavelets.
 - ③ Numerical results.

Part I: Spatially varying blur operators.

Motivating examples - Astronomy (2D)



STARS IN ASTRONOMY. HOW TO IMPROVE THE RESOLUTION OF GALAXIES?
SLOAN DIGITAL SKY SURVEY [HTTP://WWW.SDSS.ORG/](http://www.sdss.org/).

Motivating examples - Imaging under turbulence (2D)



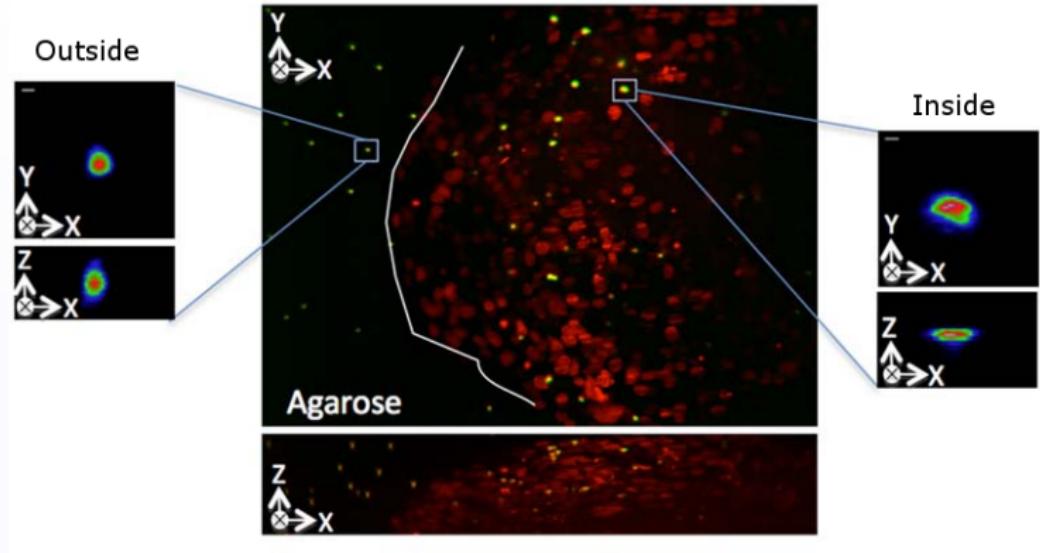
VARIATIONS OF REFRACTIVE INDICES DUE TO AIR HEAT VARIABILITY.

Motivating examples - Computer vision (2D)



A REAL CAMERA SHAKE. HOW TO REMOVE BLUR?
(BY COURTESY OF M. HIRSCH, ICCV 2011)

Motivating examples - Microscopy (3D)



FLUORESCENCE MICROSCOPY. MICRO-BEADS ARE INSERTED IN THE SAMPLE.
(BIOLOGICAL IMAGES WE ARE WORKING WITH).

Other potential applications

- ODFM (orthogonal frequency-division multiplexing) systems (see Hans Feichtinger).
- Geophysics and seismic data analysis (see Caroline Chaux).
- Solutions of PDE's $\operatorname{div}(c\nabla u) = f$ (see Philipp Grohs).
- ...

A standard inverse problem?

In all the imaging examples, we observe:

$$u_0 = Hu + b$$

where H is a blur operator, b is some noise and u is a clean image.

What makes it more difficult?

- ❶ Few studies for such operators (compared to the huge amount dedicated to convolutions).
- ❷ Images are large vectors. How to store an operator?
- ❸ How to numerically evaluate products Hu and $H^T u$?
- ❹ In practice, H is partially or completely unknown. How to retrieve the operator H ?

Notation

- We work on $\Omega = [0, 1]^d$, $d \in \mathbb{N}$ is the space dimension.
- A grayscale image $u : \Omega \rightarrow \mathbb{R}$ is viewed as an element of $L^2(\Omega)$.
- Operators are in capital letters (e.g. H), functions in lower-case (e.g. u), bold is used for matrices (e.g. \mathbf{H}).

Spatially varying blur operators

In this talk, we model the spatially varying blur operator H as a linear integral operator:

$$Hu(x) = \int_{\Omega} K(x, y)u(y) dy$$

The function $K : \Omega \times \Omega \rightarrow \mathbb{R}$ is called kernel.

Important note

By the Schwartz (Laurent) kernel theorem, H can be *any* linear operator if K is a generalized function.

Definition of the PSF

The point spread function or impulse response at point $y \in \Omega$ is defined by

$$H\delta_y = K(\cdot, y), \quad (\text{if } K \text{ is continuous})$$

where δ_y denotes the Dirac at $y \in \Omega$.

An example

Assume that $K(x, y) = k(x - y)$.

Then H is a convolution operator.

The PSF at y is the function $k(\cdot - y)$.

Some PSF examples - Synthetic (2D)



EXAMPLES OF 2D PSF FIELDS (H APPLIED TO THE DIRAC COMB).
LEFT: CONVOLUTION OPERATOR (STATIONARY). RIGHT: SPATIALLY VARYING
OPERATOR (UNSTATIONARY).

What is specific to blurring operators?

Properties of blurring operators

- **Boundedness of the operator:**

$$H : L^2(\Omega) \rightarrow L^2(\Omega)$$

is a bounded operator (the energy stays finite).

- **Spatial decay:** In most systems, PSFs satisfy:

$$|K(x, y)| \leq \frac{C}{\|x - y\|_2^\alpha}$$

for a certain $\alpha > 0$.

Examples: Motion blurs, Gaussian blurs, Airy patterns.

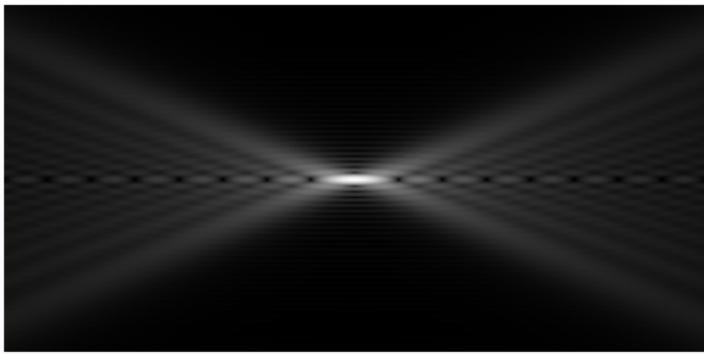
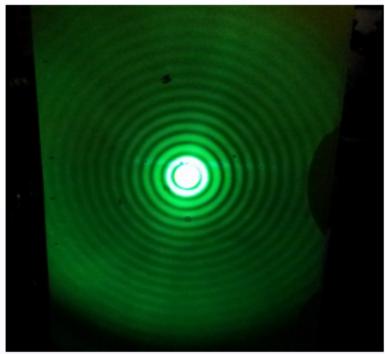
The Airy pattern

The most “standard” PSF is the Airy pattern (diffraction of light in a circular pinhole):

$$k(x) \simeq I_0 \left(\frac{2J_1(\|x\|_2)}{\|x\|_2} \right)^2,$$

where J_1 is the Bessel function of the first kind.

What is specific to blurring operators?



AXIAL AND LONGITUDINAL VIEWS OF AN AIRY PATTERN.

Some PSF examples - Real life microscopy (3D)



3D RENDERING OF MICROBEADS.

Motivating examples - Microscopy (3D)



3D RENDERING OF MICROBEADS.

What is specific to blurring operators?

More properties of blurring operators

- **PSF smoothness:** $\forall y \in \Omega$, $x \mapsto K(x, y)$ is C^M and

$$|\partial_x^m K(x, y)| \leq \frac{C}{\|x - y\|_2^\beta}, \quad \forall m \leq M.$$

for some $\beta > 0$.

- **PSF varies smoothly:**

$\forall x \in \Omega$, $y \mapsto K(x, y)$ is C^M and

$$|\partial_y^m K(x, y)| \leq \frac{C}{\|x - y\|_2^\gamma}, \quad \forall m \leq M.$$

for some $\gamma > 0$.

Other potential hypotheses (not assumed in this talk)

- Positivity: $K(x, y) \geq 0, \forall x, y$ (not necessarily true, e.g. echography).
- Mass conservation: $\forall y \in \Omega$, $\int_{\Omega} K(x, y) dx = 1$ (not necessarily true when attenuation occurs, e.g. microscopy).

The naive numerical approach

Discretization

Let $\Omega = \{k/N\}_{1 \leq k \leq N}^d$ denote a Euclidean discretization of Ω . We can define a **discretized** operator \mathbf{H} by:

$$\mathbf{H}(i, j) = \frac{1}{N^d} K(x_i, y_j)$$

where $(x_i, y_j) \in \Omega^2$. By the **rectangle rule** $\forall x_i \in \Omega$:

$$Hu(x_i) \approx (\mathbf{H}\mathbf{u})(i).$$

Typical sizes

For an image of size 1000×1000 , \mathbf{H} contains $10^6 \times 10^6 = 8$ TeraBytes.

For an image of size $1000 \times 1000 \times 1000$, \mathbf{H} contains $10^9 \times 10^9 = 8$ ExaBytes.

The total amount of data of Google is estimated at 10 ExaBytes in 2013.

\mathbf{H} can be viewed either as a $N^d \times N^d$ matrix, or as a
 $\underbrace{N \times N \times \dots \times N}_{d \text{ times}} \times \underbrace{N \times N \times \dots \times N}_{d \text{ times}}$ array.

Complexity of a matrix vector product

A matrix-vector multiplication is an $O(N^{2d})$ algorithm.

With a 1GHz computer (if the matrix was storables in RAM), a matrix-vector product would take:

- ✗ 18 minutes for a 1000×1000 image.
- ✗ 33 years for a $1000 \times 1000 \times 1000$ image.

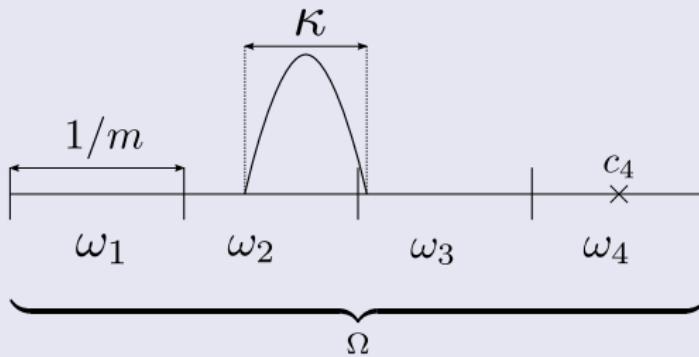
Bounded supports of PSFs help?

- ✓ Might work for very specific applications (astronomy).
- ✓ 0.4 seconds 20×20 PSF and 1000×1000 images.
- ✗ 2 hours for $20 \times 20 \times 20$ PSFs and $1000 \times 1000 \times 1000$ images.
- ✗ If the diameter of the largest PSF is $\kappa \in (0, 1]$, matrix \mathbf{H} contains $O(\kappa^d N^{2d})$ non-zero elements.
- ✗ Whenever super-resolution is targeted, this approach is doomed.

The mainstream approach: piecewise convolutions

Main idea: approximate H by an operator H_m defined by the following process:

- ① Partition Ω in squares $\omega_1, \dots, \omega_m$.
- ② On each subdomain ω_k , approximate the blur by a spatially invariant operator.



Theorem (A complexity result (1D)) Escande and Weiss 2014)

Let K denote a *Lipschitz* kernel that is *not a convolution*. Then:

- The complexity of an evaluation $\mathbf{H}_m \mathbf{u}$ using FFTs is

$$(N + \kappa N m) \log(N/m + \kappa N).$$

- For $1 \ll m < N$, there exists constants $0 < c_1 \leq c_2$ s.t.

$$\|\mathbf{H} - \mathbf{H}_m\|_{2 \rightarrow 2} \leq \frac{c_2}{m}$$

$$\|\mathbf{H} - \mathbf{H}_m\|_{2 \rightarrow 2} \geq \frac{c_1}{m}$$

- For sufficiently large N and sufficiently small $\epsilon > 0$ the number of operations necessary to obtain $\|\mathbf{H} - \mathbf{H}_m\|_{2 \rightarrow 2} \leq \epsilon$ is proportional to

$$\frac{L\kappa N \log(\kappa N)}{\epsilon}.$$

Definition of the spectral norm $\|\mathbf{H}\|_{2 \rightarrow 2} := \sup_{\|\mathbf{u}\|_2 \leq 1} \|\mathbf{H}\mathbf{u}\|_2$.

Pros and cons

- ✓ Very simple conceptually.
- ✓ Simple to implement with FFTs.
- ✓ More than 100 papers using this technique (or slightly modified).
- ✗ The method is insensitive to higher degrees of regularity of the kernel.
- ✗ The dependency in ϵ is not appealing.

Part II: Sparse representations in wavelets bases.

Notation (1D)

We work on the interval $\Omega = [0, 1]$.

The Sobolev space $W^{M,p}(\Omega)$ is defined by

$$W^{M,p}(\Omega) = \{f^{(m)} \in L^p(\Omega), \forall 0 \leq m \leq M\}.$$

We define the semi-norm $|f|_{W^{M,p}} = \|f^{(M)}\|_{L^p}$.

Let ϕ and ψ denote the scaling function and mother wavelet.

We assume that $\psi \in W^{M,\infty}$ has M vanishing moments:

$$\forall 0 \leq m \leq M, \int_{[0,1]} t^m \psi(t) dt = 0.$$

Every $u \in L^2(\Omega)$ can be decomposed as

$$u = \sum_{j \geq 0} \sum_{0 \leq m < 2^j} \langle u, \psi_{j,m} \rangle \psi_{j,m} + \langle u, \phi \rangle \phi.$$

where (apart from the boundaries of $[0, 1]$)

$$\psi_{j,m} = 2^{j/2} \psi(2^j \cdot - m).$$

Shorthand notation

$$u = \sum_{\lambda} \langle u, \psi_{\lambda} \rangle \psi_{\lambda}.$$

with $\lambda = (j, m)$, $j \geq 0$, $0 \leq m < 2^j$ and $|\lambda| = j$. The scalar product with ϕ is included in the sum.

Decomposition/Reconstruction operators

We let $\Psi : \ell^2 \rightarrow L^2([0, 1])$ and $\Psi^* : L^2([0, 1]) \rightarrow \ell^2$ denote the reconstruction/decomposition transforms:

Given a sequence in $\alpha \in \ell^2$,

$$\Psi u = \sum_{\lambda} \alpha_{\lambda} \psi_{\lambda}$$

Given a function $u \in L^2([0, 1])$,

$$\Psi^* u = (u_{\lambda})_{\lambda}$$

with

$$u_{\lambda} = \langle u, \psi_{\lambda} \rangle.$$

Decomposition of the operator on a wavelet basis

Let $u \in L^2(\Omega)$ and $v = Hu$.

$$\begin{aligned} v &= \sum_{\lambda} \langle Hu, \psi_{\lambda} \rangle \psi_{\lambda} \\ &= \sum_{\lambda} \left\langle H \left(\sum_{\lambda'} \langle u, \psi_{\lambda'} \rangle \psi_{\lambda'} \right), \psi_{\lambda} \right\rangle \psi_{\lambda} \\ &= \sum_{\lambda} \sum_{\lambda'} \langle u, \psi_{\lambda'} \rangle \langle H\psi_{\lambda'}, \psi_{\lambda} \rangle \psi_{\lambda}. \end{aligned}$$

The action of H is completely described by the (infinite) matrix

$$\Theta = (\theta_{\lambda, \lambda'})_{\lambda, \lambda'} = (\langle H\psi_{\lambda'}, \psi_{\lambda} \rangle)_{\lambda, \lambda'}.$$

With these notation

$$H = \Psi \Theta \Psi^*.$$

Definition - (Nonsingular) Calderón-Zygmund operators

An integral operator $H : L^2(\Omega) \rightarrow L^2(\Omega)$ with a kernel $K \in W^{M,\infty}(\Omega \times \Omega)$ is a Calderón-Zygmund operator of regularity $M \geq 1$ if

$$|K(x, y)| \leq \frac{C}{\|x - y\|_2^d}$$

and

$$|\partial_x^m K(x, y)| + |\partial_y^m K(x, y)| \leq \frac{C}{\|x - y\|_2^{d+m}}, \quad \forall m \leq M.$$

Important notes

The above definition is simplified.

Calderón-Zygmund operators may be singular on the diagonal $x = y$.

For instance, the Hilbert transform corresponds to $K(x, y) = \frac{1}{x-y}$.

Take home message

Our blurring operators are simple Calderón-Zygmund operators.

Theorem (Decrease of $\theta_{\lambda,\lambda'}$ in 1D)

Assume that H belongs to the Calderón-Zygmund class and that the mother wavelet ψ is compactly supported with M vanishing moments. Set $\lambda = (j, m)$ and $\lambda' = (k, n)$. Then

$$|\theta_{\lambda,\lambda'}| \leq C_M 2^{-(M+1/2)|j-k|} \left(\frac{2^{-k} + 2^{-j}}{2^{-k} + 2^{-j} + |2^{-j}m - 2^{-k}n|} \right)^{M+1}$$

where C_M is a constant independent of j, k, n, m .

Take home message

- ✓ The coefficients decrease exponentially with scales differences $2^{-(M+1/2)|j-k|}$.
- ✓ The coefficients decrease polynomially with shift differences $\left(\frac{2^{-k} + 2^{-j}}{2^{-k} + 2^{-j} + |2^{-j}m - 2^{-k}n|} \right)^{M+1}$.
- ✓ The kernel regularity M plays a key role.

A key upper-bound - Elements of proof

Polynomial approximation - Annales de l'institut Fourier, Deny-Lions 1954

Let $f \in W^{M,p}([0, 1])$. For $1 \leq p \leq +\infty$, $M \in \mathbb{N}^*$ and $I_h \subset [0, 1]$ an interval of length h :

$$\inf_{g \in \Pi_{M-1}} \|f - g\|_{L^p(I_h)} \leq Ch^M |f|_{W^{M,p}(I_h)}, \quad (1)$$

where C is a constant that depends on M and p only.

Let $I_{j,m} = \text{supp}(\psi_{j,m}) = [2^{-j}(m-1), 2^{-j}(m+1)]$. Assume that $j \leq k$:

$$|\langle H\psi_{j,m}, \psi_{k,n} \rangle|$$

$$= \left| \int_{I_{k,n}} \int_{I_{j,m}} K(x, y) \psi_{j,m}(y) \psi_{k,n}(x) dy dx \right|$$

$$= \left| \int_{I_{j,m}} \int_{I_{k,n}} K(x, y) \psi_{j,m}(y) \psi_{k,n}(x) dx dy \right| \quad (\text{Fubini})$$

$$= \left| \int_{I_{j,m}} \inf_{g \in \Pi_{M-1}} \int_{I_{k,n}} (K(x, y) - g(x)) \psi_{j,m}(y) \psi_{k,n}(x) dx dy \right| \quad (\text{Vanishing moments})$$

$$\leq \int_{I_{j,m}} \inf_{g \in \Pi_{M-1}} \|K(\cdot, y) - g\|_{L^\infty(I_{k,n})} \|\psi_{k,n}\|_{L^1(I_{k,n})} |\psi_{j,m}(y)| dy \quad (\text{H\"older})$$

Therefore:

$$\begin{aligned}
 & |\langle H\psi_{j,m}, \psi_{k,n} \rangle| \\
 & \lesssim 2^{-kM} \|\psi_{k,n}\|_{L^1(I_{k,n})} \|\psi_{j,m}\|_{L^1(I_{j,m})} \operatorname{esssup}_{y \in I_{j,m}} |K(\cdot, y)|_{W^{M,\infty}(I_{k,n})} \quad (\text{H\"older again}) \\
 & \lesssim 2^{-kM} 2^{-\frac{j}{2}} 2^{-\frac{k}{2}} \operatorname{esssup}_{y \in I_{j,m}} |K(\cdot, y)|_{W^{M,\infty}(I_{k,n})}.
 \end{aligned}$$

Controlling $\operatorname{esssup}_{y \in I_{j,m}} |K(\cdot, y)|_{W^{M,\infty}(I_{k,n})}$ can be achieved using the fact that derivatives of Calder\'on-Zygmund operator decay polynomially away from the diagonal. We obtain (not direct):

$$\operatorname{esssup}_{y \in I_{j,m}} |K(\cdot, y)|_{W^{M,\infty}(I_{k,n})} \lesssim \left(\frac{1 + 2^{j-k}}{2^{-j} + 2^{-k} + |2^{-j}m - 2^{-k}n|} \right)^{M+1} \quad \square$$

Theorem (Decrease of $\theta_{\lambda,\lambda'}$ in d-dimensions)

Assume that H belongs to the Calderón-Zygmund class and that the mother wavelet ψ is compactly supported with M vanishing moments. Set $\lambda = (j, m)$ and $\lambda' = (k, n)$. Then

$$|\theta_{\lambda,\lambda'}| \leq C_M 2^{-(M+\textcolor{red}{d}/2)|j-k|} \left(\frac{2^{-k} + 2^{-j}}{2^{-k} + 2^{-j} + |2^{-j}m - 2^{-k}n|} \right)^{M+\textcolor{red}{d}}$$

where C_M is a constant independent of j, k, n, m .

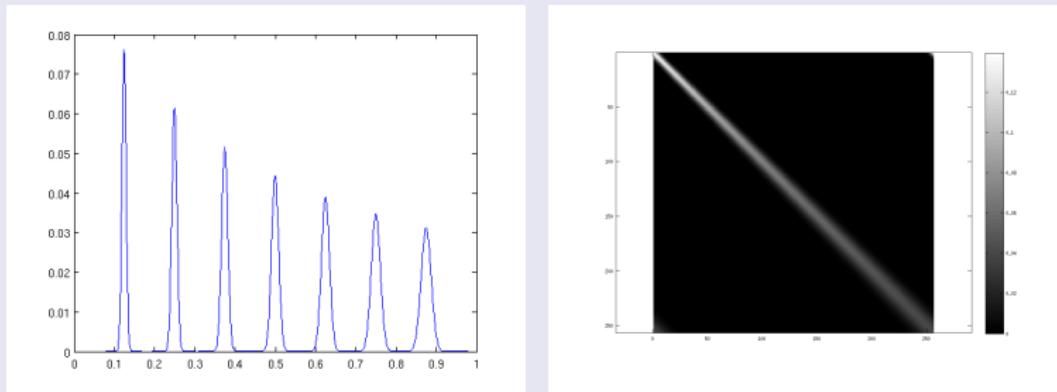
A practical example (1D)

We set:

$$K(x, y) = \frac{1}{\sigma(y)\sqrt{2\pi}} \exp\left(-\frac{(x-y)^2}{2\sigma(y)^2}\right)$$

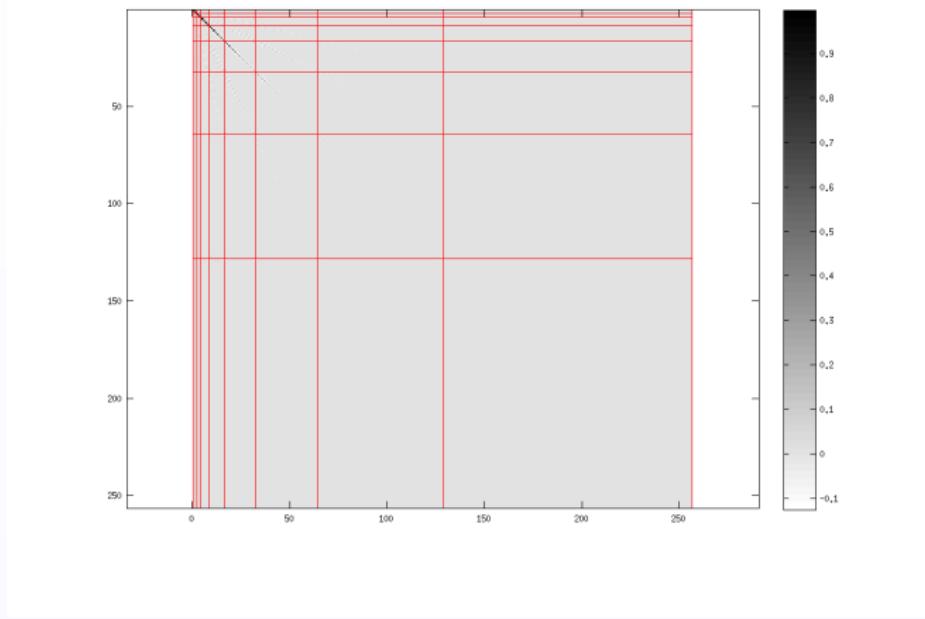
with

$$\sigma(y) = 4 + 10y.$$



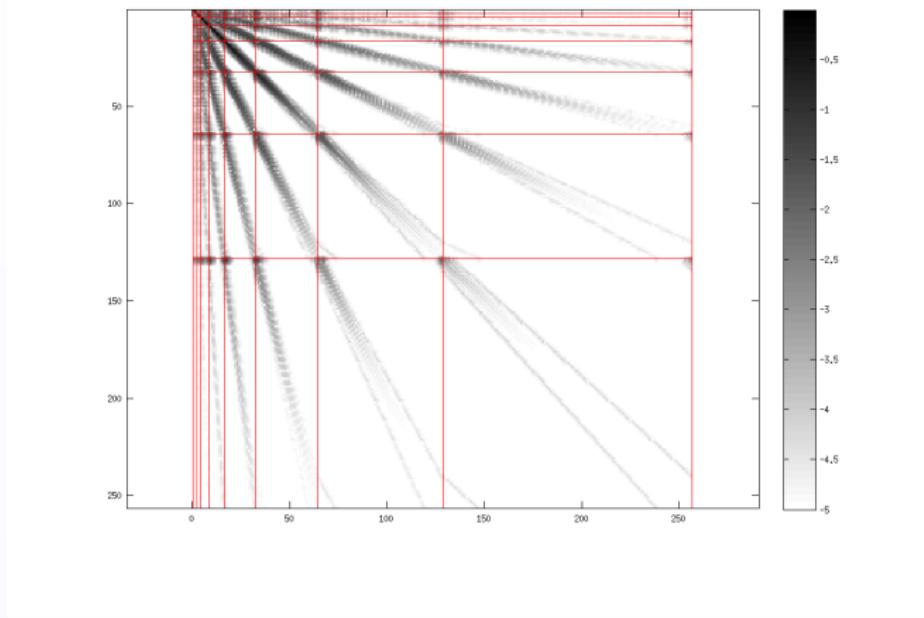
A FIELD OF PSFs AND THE DISCRETIZED MATRIX \mathbf{H} WITH $N = 256$.

Compression of Caderón-Zygmund operators



THE MATRIX Θ (USUAL SCALE).

Compression of Calderón-Zygmund operators



THE MATRIX Θ (\log_{10} -SCALE).

Summary

Calderón-Zygmund operators are compressible in the wavelet domain !

Question

Can these results be used for fast computations?

A word on Galerkin approximations

Numerically, it is impossible to use infinite dimensional matrices.

We can therefore **truncate** the matrix Θ by setting a **maximum scale** J :

$$\Theta = (\theta_{\lambda, \lambda'})_{0 \leq \lambda, \lambda' \leq J}$$

Let

$$\begin{aligned}\Psi_J : & \left\{ \begin{array}{ccc} \mathbb{R}^{2^{J+1}} & \rightarrow L^2(\Omega) \\ \alpha & \mapsto \sum_{|\lambda| \leq J} \alpha_\lambda \psi_\lambda \end{array} \right. \\ \Psi_J^* : & \left\{ \begin{array}{ccc} L^2(\Omega) & \rightarrow \mathbb{R}^{2^{J+1}} \\ u & \mapsto (\langle u, \psi_\lambda \rangle)_{|\lambda| \leq J} \end{array} \right.\end{aligned}$$

We obtain an approximation H_J of H defined by:

$$H_J = \Psi_J \Theta \Psi_J^* = \Pi_J H \Pi_J,$$

where the operator $\Pi_J = \Psi_J \Psi_J^*$ is a projector on $\text{span}(\{\psi_\lambda, |\lambda| \leq J\})$.

A word on Galerkin approximation

Standard results in approximation theory state that if u belong to some Banach space \mathcal{B}

$$\|u - \Pi_J(u)\|_2 = O(N^{-\alpha}), \quad (2)$$

where α depends on \mathcal{B} and $N = 2^{J+1}$.

If we assume that H is **regularizing**, meaning that for any u satisfying (2)

$$\|Hu - \Pi_J(Hu)\|_2 = O(N^{-\beta}), \quad \text{with } \beta \geq \alpha.$$

Then:

$$\begin{aligned} \|Hu - H_J u\|_2 &= \|Hu - \Pi_J H(u - \Pi_J u - u)\|_2 \\ &\leq \|Hu - \Pi_J Hu\|_2 + \|\Pi_J H(\Pi_J u - u)\|_2 = O(N^{-\alpha}). \end{aligned}$$

Examples

- For $u \in H^1([0, 1])$, $\alpha = 2$.
- For $u \in W^{1,1}([0, 1])$ or $u \in BV([0, 1])$, $\alpha = 1$.
- For $u \in W^{1,1}([0, 1]^2)$ or $u \in BV([0, 1]^2)$, $\alpha = 1/2$.

The main idea

Most coefficients in Θ are small.

One can “threshold” it to obtain a sparse approximation Θ_P , where P denotes the number of nonzero coefficients.

We get an approximation $\mathbf{H}_P = \Psi \Theta_P \Psi^*$.

Numerical complexity

A product $\mathbf{H}_P \mathbf{u}$ costs:

- 2 wavelet transforms of complexity $O(N)$.
- A matrix-vector product with Θ_P of complexity $O(P)$.

The overall complexity for is $O(\max(P, N))$.

This is to be compared to the usual $O(N^2)$ complexity.

The consequences for numerical analysis

Theorem (theoretical foundations Beylkin, Coifman, and Rokhlin 1991)

Let Θ_η be the matrix obtained by zeroing all coefficients in Θ such that

$$\left(\frac{2^{-j} + 2^{-k}}{2^{-j} + 2^{-k} + |2^{-j}m - 2^{-k}n|} \right)^{M+1} \leq \eta.$$

Let $\mathbf{H}_\eta = \Psi \Theta_\eta \Psi^*$ denote the resulting operator. Then:

- i) The number of non zero coefficients in Θ_η is bounded above by

$$C'_M N \log_2(N) \eta^{-\frac{1}{M+1}}.$$

- ii) The approximation \mathbf{H}_η satisfies $\|\mathbf{H} - \mathbf{H}_\eta\|_{2 \rightarrow 2} \lesssim \eta^{\frac{M}{M+1}}$.
- iii) The complexity to obtain an ϵ -approximation $\|\mathbf{H} - \mathbf{H}_\eta\|_{2 \rightarrow 2} \leq \epsilon$ is bounded above by $C''_M N \log_2(N) \epsilon^{-\frac{1}{M}}$.

Proof outline

- ① Since Ψ is orthogonal,

$$\|\mathbf{H}_\eta - \mathbf{H}\|_{2 \rightarrow 2} = \|\Theta - \Theta_\eta\|_{2 \rightarrow 2}.$$

- ② Let $\Delta_\eta = \Theta - \Theta_\eta$. Use the Schur test

$$\|\Delta_\eta\|_{2 \rightarrow 2}^2 \leq \|\Delta_\eta\|_{1 \rightarrow 1} \|\Delta_\eta\|_{\infty \rightarrow \infty}.$$

- ③ Majorize $\|\Delta_\eta\|_{1 \rightarrow 1}$ using Meyer's upper-bound.

Note : the 1-norm has a simple explicit expression contrarily to the 2-norm.

The consequences for numerical analysis

Piecewise convolutions VS wavelet sparsity

	Piecewise convolutions	Wavelet sparsity
Simple theory	Yes	No
Simple implementation	Yes	No
Complexity	$O(N \log_2(N) \epsilon^{-1})$	$O\left(N \log_2(N) \epsilon^{-\frac{1}{M}}\right)$
Adaptivity/universality	No	Yes

Link with the SVD

Let $\Psi = (\psi_1, \dots, \psi_N) \in \mathbb{R}^{N \times N}$ denote a discrete wavelet transform.
The change of basis $\mathbf{H} = \Psi \Theta \Psi^*$ can be rewritten as:

$$\mathbf{H} = \sum_{\lambda, \lambda'} \theta_{\lambda, \lambda'} \psi_\lambda \psi_{\lambda'}^T.$$

The $N \times N$ matrix $\psi_\lambda \psi_{\lambda'}^T$ is rank-1.

Matrix \mathbf{H} is therefore decomposed as the sum of N^2 rank-1 matrices.

By “thresholding” Θ one can obtain an ϵ -approximation with
 $O(N \log_2(N) \epsilon^{-\frac{1}{M}})$ rank-1 matrices.

The SVD is a sum of N rank-1 matrices (which can also be compressed for compact operators).

Take home message

Tensor products of wavelets can be used to produce approximations of regularizing operators by sums of rank-1 matrices.

Geometrical intuition of the method



ILLUSTRATION OF THE SPACE DECOMPOSITION WITH A NAIVE THRESHOLDING.

How to choose the sparsity patterns?

First reflex - Hard thresholding

Construct Θ_P by keeping the P largest coefficients of Θ .

This choice is optimal in the sense that it minimizes

$$\min_{\Theta_P \in \mathbb{S}_P} \|\Theta - \Theta_P\|_F^2 = \|\mathbf{H} - \mathbf{H}_P\|_F^2$$

where \mathbb{S}_P is the set of $N \times N$ matrices with at most P nonzero coefficients.

Problem: the Frobenius norm is not an operator norm.

Second reflex - Optimizing the $\|\cdot\|_{2 \rightarrow 2}$ -norm

In most (if not all) publications on wavelet compression of operators:

$$\min_{\Theta_P \in \mathbb{S}_P} \|\Theta - \Theta_P\|_{2 \rightarrow 2}.$$

This problem has no easily computable solution.

Approximate solutions lead to unsatisfactory approximation results.

How to choose the sparsity patterns?

A (much) better strategy Escande and Weiss 2014

Main idea: minimize an operator norm adapted to images.

Most signals/images are in $BV(\Omega)$ (or $B_1^{1,1}(\Omega)$), therefore (in 1D)
Cohen et al. 2003:

$$\sum_{j \geq 0} \sum_{m=0}^{2^j - 1} 2^j |\langle u, \psi_{j,m} \rangle| < +\infty.$$

This motivates to define a norm $\|\cdot\|_X$ on vectors:

$$\|\mathbf{u}\|_X = \|\boldsymbol{\Sigma} \boldsymbol{\Psi}^* \mathbf{u}\|_1$$

where $\boldsymbol{\Sigma} = \text{diag}(\sigma_1, \dots, \sigma_N)$ and $\sigma_i = 2^{j(i)}$ where $j(i)$ is the scale of the i -th wavelet.

It leads to the following variational problem:

$$\min_{\mathbf{S}_P \in \mathbb{S}_P} \sup_{\|\mathbf{u}\|_X \leq 1} \|(\mathbf{H} - \mathbf{H}_P)\mathbf{u}\|_2 = \|\mathbf{H} - \mathbf{H}_P\|_{X \rightarrow 2}.$$

How to choose the sparsity patterns?

Optimization algorithm

Main trick : use the fact that signals and operators are sparse in the same wavelet basis. Let $\Delta_P = \Theta - \Theta_P$. Then

$$\begin{aligned}\max_{\|\mathbf{u}\|_X \leq 1} \|(\mathbf{H} - \mathbf{H}_P)\mathbf{u}\|_2 &= \max_{\|\mathbf{u}\|_X \leq 1} \|(\Psi(\Theta - \Theta_P)\Psi^*)\mathbf{u}\|_2 \\ &= \max_{\|\Sigma\mathbf{z}\|_1 \leq 1} \|\Delta_P \mathbf{z}\|_2 \\ &= \max_{\|\mathbf{z}\|_1 \leq 1} \|\Delta_P \Sigma^{-1} \mathbf{z}\|_2 \\ &= \max_{1 \leq i \leq N} \frac{1}{\sigma_i} \|\Delta_P^{(i)}\|_2.\end{aligned}$$

This problem can be solved exactly using a greedy algorithm with quicksort.

Complexity

- If Θ is known: $O(N^2 \log(N))$.
- If only Meyer's bound is known: $O(N \log(N))$.

Geometrical intuition of the method



OPTIMAL SPACE DECOMPOSITION MINIMIZING $\|\mathbf{H} - \mathbf{H}_P\|_{X \rightarrow 2}$.

Geometrical intuition of the method

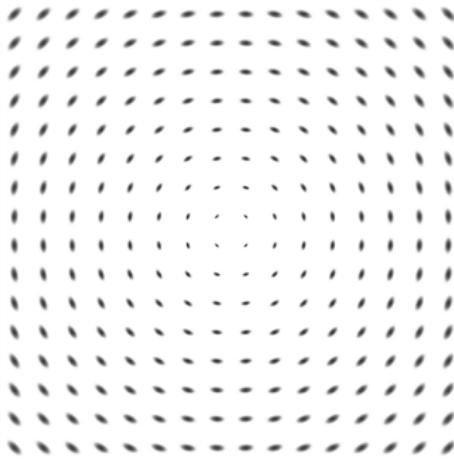


OPTIMAL SPACE DECOMPOSITION MINIMIZING $\|\mathbf{H} - \mathbf{H}_P\|_{X \rightarrow 2}$ WHEN ONLY AN
UPPER-BOUND ON Θ IS KNOWN.

Experimental validation



TEST CASE IMAGE



ROTATIONAL BLUR

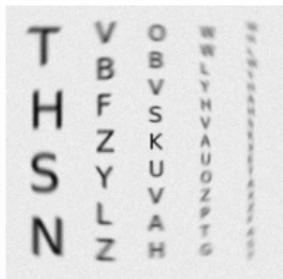
Experimental validation

	Piece. Conv.	Difference	Algorithm	Difference	$l =$
4×4	38.49 dB				30
0.17 s					0.040s
8×8	44.51 dB				50
0.36 s					0.048s

BLURRED IMAGES USING APPROXIMATING OPERATORS AND DIFFERENCES WITH THE EXACT BLURRED IMAGE. WE SET THE SPARSITY $P = lN^2$.

Deblurring results

TV-L2 based deblurring



DEGRADED IMAGE



EXACT OPERATOR
28.97dB – 2 HOURS



WAVELET
28.02dB – 8 SECONDS



PIECE. CONV.
27.12dB – 35 SECONDS

- ✓ Calderón-Zygmund operators are **highly compressible** in the wavelet domain.
- ✓ Evaluation of Calderón-Zygmund operators can be handled efficiently **numerically** in the wavelet domain.
- ✓ Wavelet compression outperforms piecewise convolution both theoretically and experimentally.

- ✓ Calderón-Zygmund operators are **highly compressible** in the wavelet domain.
- ✓ Evaluation of Calderón-Zygmund operators can be handled efficiently **numerically** in the wavelet domain.
- ✓ Wavelet compression outperforms piecewise convolution both theoretically and experimentally.

The devil was hidden!

Until now, we assumed that Θ was known.

In 1D, the change of basis $\Theta = \Psi^* \mathbf{H} \Psi$ has complexity $O(N^3)$!

We had to use **12 cores and 8 hours** to compute Θ and obtain the previous 2D results.

A dead end?

Part III: Operator reconstruction (ongoing work).

The setting

Assume we **only** know a few PSFs at points $(y_i)_{1 \leq i \leq n} \in \Omega^n$.

The “inverse problem” we want to solve is:

Reconstruct K knowing $k_i = K(\cdot, y_i) + \eta_i$, where η_i is **noise**.

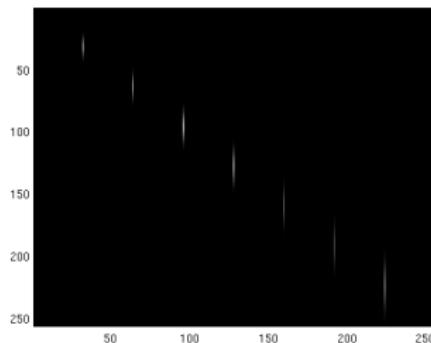
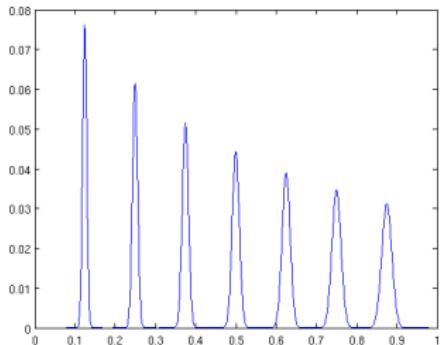
Severely ill-posed!

A variational formulation:

$$\inf_{K \in \mathcal{K}} \frac{1}{2} \sum_{i=1}^n \|k_i - K(\cdot, y_i)\|_2^2 + \lambda R(K).$$

How can we choose the regularization functional R and the space \mathcal{K} ?

Examples



PROBLEM ILLUSTRATION: SOME KNOWN PSFs AND THE ASSOCIATED MATRIX.

The first regularizer

From the first part of the talk, we know that blur operators can be approximated by matrices of type:

$$\mathbf{H}_P = \mathbf{\Psi} \mathbf{\Theta}_P \mathbf{\Psi} \quad (3)$$

where $\mathbf{\Theta}_P$ is a P sparse matrix with a known sparsity pattern \mathbb{P} .

We let \mathbb{H} denote the space of matrices of type (3).

This is a first natural regularizer.

- ✓ Reduces the number of degrees of freedom.
- ✓ Compresses the matrix.
- ✓ Allow fast matrix-vector multiplication.
- ✗ Not sufficient to regularize the problem: we still have to find $O(N \log(N))$ coefficients.

Main features of spatially varying blurs

Assumption: two neighboring PSFs are similar

From a formal point of view:

$$K(\cdot, y) \approx \tau_{-h} K(\cdot, y + h),$$

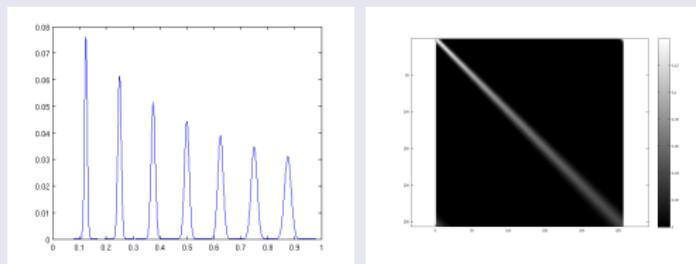
for sufficiently small h , where τ_{-h} denotes the translation operator.

Alternative formulation: the mappings

$$y \mapsto K(x + y, y)$$

should be **smooth** for all $x \in \Omega$.

Interpolation/approximation of scattered data



SOME KNOWN PSFs AND THE ASSOCIATED MATRIX.

A variational formulation in 1D

Spline-based approximation of functions $\Omega = [0, 1]$

Let $f : [0, 1] \rightarrow \mathbb{R}$ denote a function such that $f(y_i) = \gamma_i + \eta_i$, $1 \leq i \leq n$.
A variational formulation to obtain piecewise linear approximations:

$$\inf_{g \in H^1([0,1])} \frac{1}{2} \sum_{i=1}^n \|g(y_i) - \gamma_i\|_2^2 + \frac{\lambda}{2} \int_{[0,1]} (g'(x))^2 dx.$$

From functions to operators $\Omega = [0, 1]$

This motivates us to consider the problem

$$\inf_{K \in \mathcal{K}} \frac{1}{2} \sum_{i=1}^n \|k_i - K(\cdot, y_i)\|_2^2 + \underbrace{\frac{\lambda}{2} \int_{\Omega} \int_{\Omega} \langle \nabla K(x, y), (1; 1) \rangle^2 dy dx}_{R(K)}$$

Discretization

Let $\mathbf{k}_i \in \mathbb{R}^N$ denote the discretization of $K(\cdot, y_i)$. The discretized variational problem can be rewritten:

$$\inf_{\mathbf{H} \in \mathbb{H}} \frac{1}{2} \sum_{i=1}^n \|\mathbf{k}_i - \mathbf{H}(\cdot, y_i)\|_2^2 + \frac{\lambda}{2} \sum_{i=1}^N \sum_{j=1}^N (\mathbf{H}(i+1, j+1) - \mathbf{H}(i, j))^2.$$

The devil is still there!

This is an optimization problem over the **space of $N \times N$ matrices!**

Bad news...

We are now working with **HUGE** operators:

- A matrix $\mathbf{H} \in \mathbb{R}^{N \times N}$ can be thought of as a vector of size N^2 .
- We need the translation operator $\mathbf{T}_{1,1} : \mathbb{R}^{N \times N} \rightarrow \mathbb{R}^{N \times N}$ that maps $\mathbf{H}(i,j)$ to $\mathbf{H}(i+1,j+1)$.
- This way

$$\begin{aligned} R(\mathbf{H}) &= \sum_{i=1}^N \sum_{j=1}^N (\mathbf{H}(i+1,j+1) - \mathbf{H}(i,j))^2 \\ &= \left\| (\mathbf{T}_{1,1} - \mathbf{I})(\mathbf{H}) \right\|_F^2. \end{aligned}$$

A first trick

Main observation: the shift operator $\mathbf{T}_{1,1} = \mathbf{T}_{1,0} \circ \mathbf{T}_{0,1}$.

- the shift in the vertical direction can be encoded by an $N \times N$ matrix:

$$\mathbf{T}_{1,0}(\mathbf{H}) = \mathbf{T}_1 \cdot \mathbf{H}$$

where $\mathbf{T}_1 \in \mathbb{R}^{N \times N}$ is N -sparse.

- Similarly:

$$\mathbf{T}_{0,1}(\mathbf{H}) = (\mathbf{T}_1 \cdot \mathbf{H}^T)^T = \mathbf{H} \cdot \mathbf{T}_{-1}.$$

Note that \mathbf{T}_1 is orthogonal, therefore $\mathbf{T}_1^T = \mathbf{T}_1^{-1} = \mathbf{T}_{-1}$.

- Overall $\mathbf{T}_{1,1}(\mathbf{H}) = \mathbf{T}_1 \cdot \mathbf{H} \cdot \mathbf{T}_{-1}$.

Theorem Beylkin 1992

The shift matrix $\mathbf{S}_1 = \Psi^* \mathbf{T}_1 \Psi$ contains $O(N \log N)$ non-zero coefficients. Moreover, \mathbf{S}_1 can be computed efficiently with an $O(N \log N)$ algorithm.

Consequences for numerical analysis

The regularization term can be computed efficiently in the wavelet domain:

$$\begin{aligned} R(\mathbf{H}) &= \|\mathbf{T}_1 \mathbf{H} \mathbf{T}_{-1} - \mathbf{H}\|_F^2 \\ &= \|\Psi \mathbf{S}_1 \Psi^* \mathbf{H} \Psi \mathbf{S}_{-1} \Psi^* - \mathbf{H}\|_F^2 \\ &= \|\mathbf{S}_1 \Theta \mathbf{S}_{-1} - \Theta\|_F^2. \end{aligned}$$

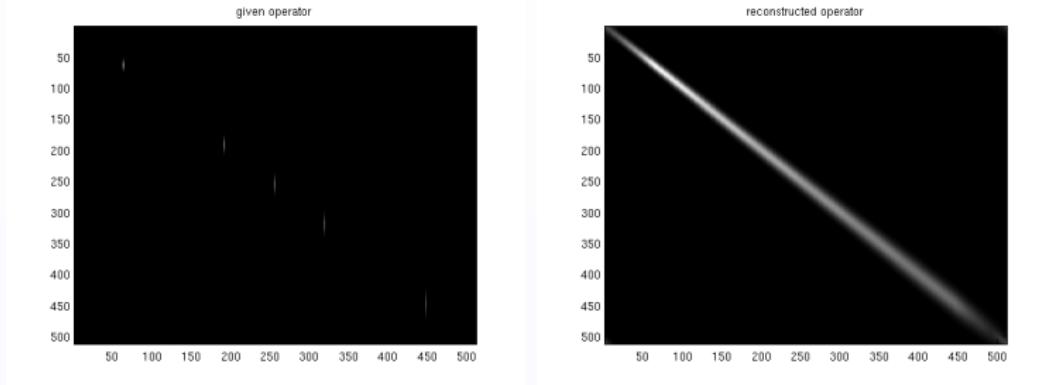
The overall problem is now formulated only in the wonderful sparse world:

$$\min_{\Theta_P \in \Xi} \frac{1}{2} \sum_{i=1}^n \|\mathbf{k}_i - \Psi \Theta_P \Psi^* \delta_{y_i}\|_2^2 + \frac{\lambda}{2} \|\mathbf{S}_1 \Theta_P \mathbf{S}_{-1} - \Theta_P\|_F^2.$$

where Ξ is the space of $N \times N$ matrices with fixed sparsity pattern \mathbb{P} .

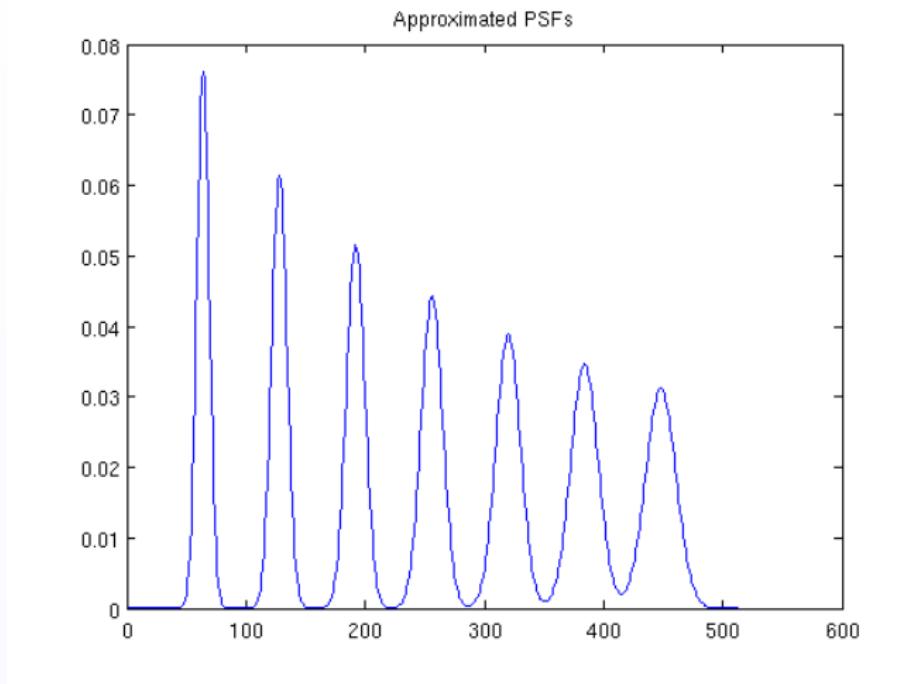
Can be solved using a projected conjugate gradient descent.

Examples



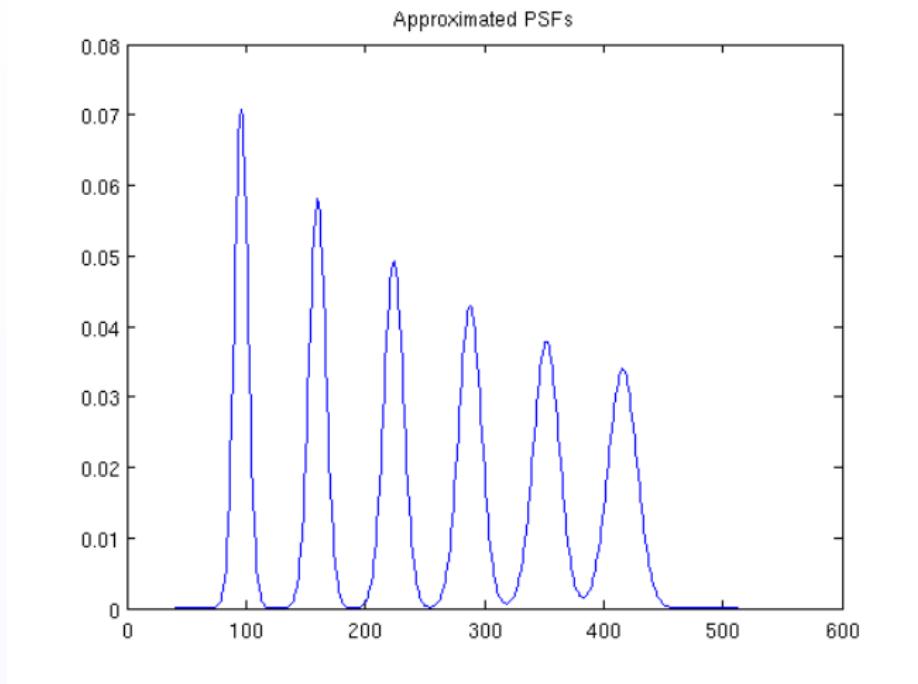
LEFT: KNOWN MATRIX. RIGHT: RECONSTRUCTED MATRIX.

Examples



APPROXIMATED PSF FIELD AT KNOWN LOCATIONS.

Examples



APPROXIMATED PSF FIELD AT SHIFTED KNOWN LOCATIONS.

Spline approximation in higher dimensions

Scattered data in \mathbb{R}^d can be interpolated or approximated using higher-order variational problems.

For instance one can use **biharmonic splines**:

$$\inf_{g \in H^2([0,1]^2)} \frac{1}{2} \sum_{i=1}^n \|g(y_i) - \gamma_i\|_2^2 + \frac{\lambda}{2} \int_{[0,1]^2} (\Delta g(y))^2 dx.$$

A basic reference: Wahba 1990.

A word on the interpolation of scattered data

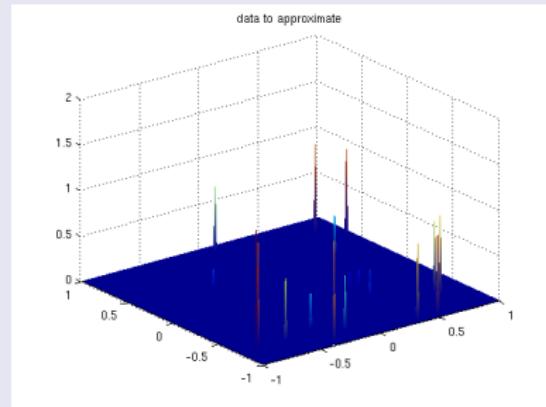
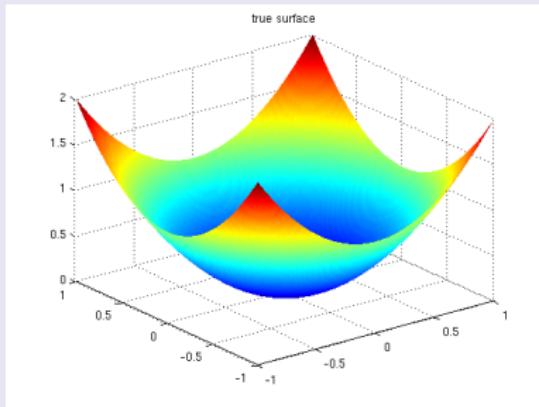
Why use higher orders?

Let $B = \{(x, y) \in \mathbb{R}^2, x^2 + y^2 \leq 1\}$. The function

$$u(x, y) = \log(|\log(\sqrt{x^2 + y^2})|)$$

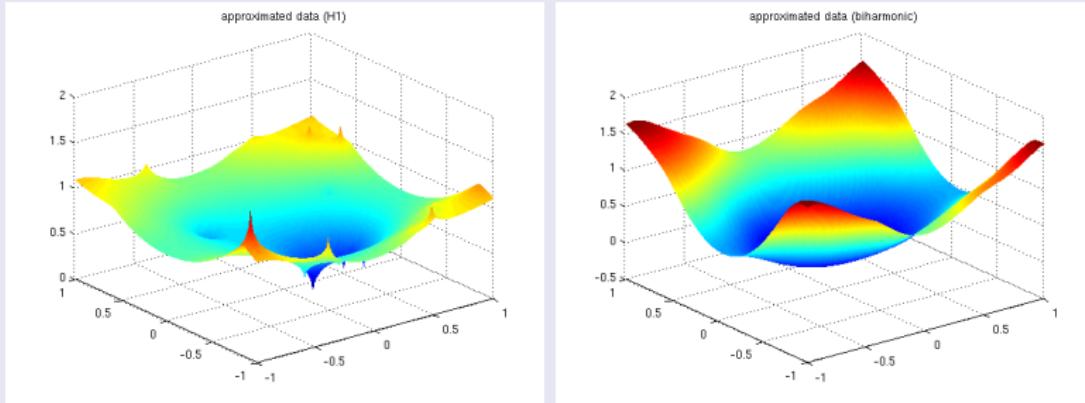
belongs to $H^1(B) = W^{1,2}(B)$ and is unbounded at 0.

Illustration



LEFT: KNOW SURFACE $(x, y) \mapsto x^2 + y^2$. RIGHT: KNOW VALUES.

Illustration



LEFT: H_1 RECONSTRUCTION. RIGHT: BIHARMONIC RECONSTRUCTION.

The case $\Omega = [0, 1]^2$

In 2D, one can solve the following variational problem:

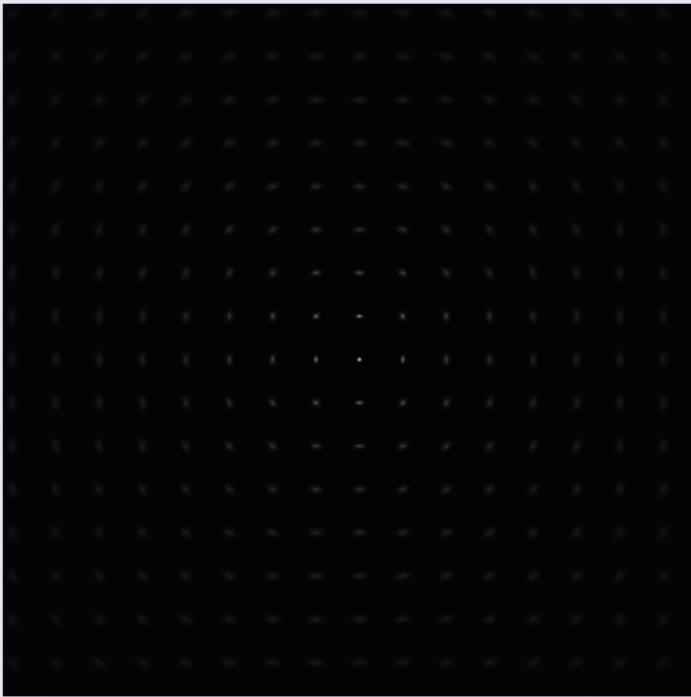
$$\inf_{K \in H^1(\Omega \times \Omega)} \frac{1}{2} \sum_{i=1}^n \|k_i - K(\cdot, y_i)\|_2^2 + \frac{\lambda}{2} \underbrace{\int_{\Omega} \int_{\Omega} \Delta_y(L)^2(x, y) dy dx}_{R(K)}$$

where $L(x, y) := R(x + y, y)$.

Using similar tricks as in the previous part, this problem can be entirely reformulated in the **space of sparse matrices**.

A complete deconvolution example

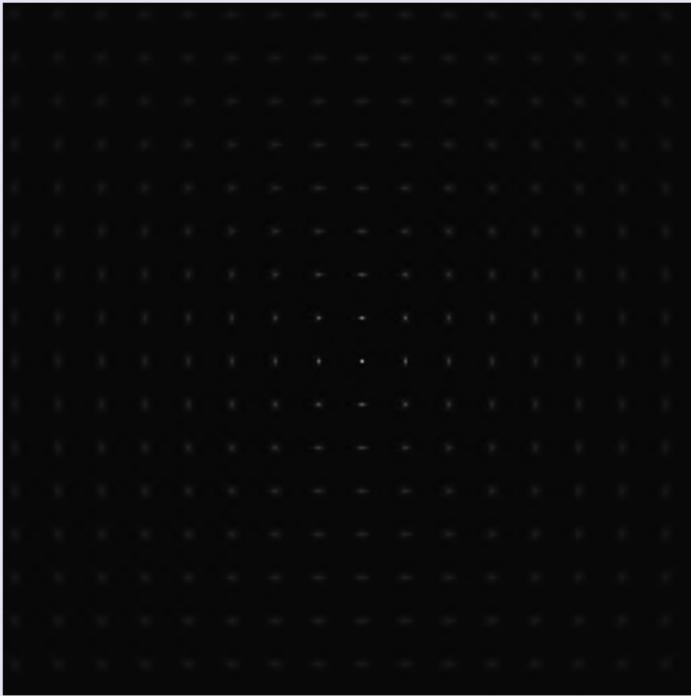
Reconstruction of an operator



TRUE OPERATOR (APPLIED TO THE DIRAC COMB).

A complete deconvolution example

Reconstruction of an operator



OPERATOR RECONSTRUCTION.

Examples

A complete deconvolution example



ORIGINAL IMAGE.

Examples

A complete deconvolution example



BLURRY AND NOISY IMAGE (WITH THE EXACT OPERATOR).

Examples

A complete deconvolution example



RESTORED IMAGE (WITH THE RECONSTRUCTED OPERATOR). OPERATOR
RECONSTRUCTION = 40 MINUTES. IMAGE RECONSTRUCTION = 3 SECONDS (100
ITERATIONS OF A DESCENT ALGORITHM).

Main facts

- ✓ Operators are highly compressible in wavelet domain.
- ✓ Operators can be computed efficiently in the wavelet domain.
- ✓ Possibility to formulate inverse problems on operator spaces.
- ✓ Regarding spatially varying deblurring:
 - ✓ numerical results are promising.
 - ✓ versatile method allowing to handle PSFs on non cartesian grids.
- ✗ Results are preliminary. Operator reconstruction takes too long.

A nice research topic

- ✓ Not much has been done.
- ✓ Plenty of work in theory.
- ✓ Plenty of work in implementation.
- ✓ Plenty of potential applications.

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